

A HIGH-ORDER LOW-ORDER ALGORITHM WITH EXPONENTIALLY-CONVERGENT MONTE CARLO FOR THERMAL RADIATIVE TRANSFER

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ABSTRACT

We have implemented a new high-order low-order (HOLO) algorithm for solving thermal radiative transfer problems. The low-order (LO) system is based on spatial and angular moments of the transport equation and a linear-discontinuous finite-element spatial representation, producing equations similar to the standard S_2 equations. The LO solver is fully implicit in time and efficiently resolves the non-linear temperature dependence at each time step. The HO solver utilizes exponentially-convergent Monte Carlo (ECMC) to give a globally accurate solution for the angular intensity to a fixed-source, pure absorber transport problem. This global solution is used to compute consistency terms, which require the HO and LO solutions to converge towards the same solution. The use of ECMC allows for the efficient reduction of statistical noise in the MC solution, reducing inaccuracies introduced through the LO consistency terms. We compare results with an implicit Monte Carlo (IMC) code for one-dimensional, gray test problems and demonstrate the efficiency of ECMC over standard Monte Carlo in this HOLO algorithm.

Key Words: hybrid Monte Carlo, residual Monte Carlo, thermal radiative transfer

I. INTRODUCTION

We have implemented a high-order low-order (HOLO) algorithm for the case of 1D gray thermal radiative transfer (TRT) problems. The governing equations are the radiation and material energy balance equations, i.e.,

$$\frac{1}{c} \frac{\partial I}{\partial t} + \mu \frac{\partial I}{\partial x} + \sigma_t I = \frac{\sigma_s}{2} \phi + \frac{1}{2} \sigma_a a c T^4 \quad (1)$$

$$\rho c_v \frac{\partial T}{\partial t} = \sigma_a \phi - \sigma_a a c T^4. \quad (2)$$

In the above equations x is the position, t is the time, μ is the x -direction cosine of the angular intensity $I(x, \mu, t)$, and a , c , ρ , and c_v are the radiation constant, speed of light, mass density, and specific heat; σ_a , σ_s , and σ_t are the absorption, scattering, and total cross sections (cm^{-1}), respectively. The desired unknowns are the material temperature $T(x, t)$ and the scalar radiation intensity $\phi(x, t) = \int_{-1}^1 I(x, \mu, t) d\mu$. The scalar intensity is related to the radiation energy density as $E = \phi/c$. The equations are strongly coupled through the gray Planckian emission source $\sigma_a a c T^4$, which is a nonlinear function of temperature, and the absorption term $\sigma_a \phi$. In general, the material properties are a function of

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T. The temperature dependent material properties and absorption- reemission physics lead to systems that require solution in a mix of streaming and optically-thick, diffusive regions.

Monte Carlo (MC) solution to the TRT equations is typically achieved by the implicit Monte Carlo (IMC) method [1]. This method linearizes Eq. (1) & Eq. (2) over a discrete time step. The linearization of the system produces a transport equation that contains an approximate emission source and an effective scattering cross section representing absorption and reemission of photons over a time step. This transport equation is solved using MC. The MC simulation tallies energy absorption over a discretized spatial mesh. The energy absorption in each mesh cell is used to directly estimate a new end of time step temperature in that cell. In optically thick regions, or for large time steps, the effective scattering dominates interactions. In these diffusive regions IMC becomes computationally expensive. Acceleration methods typically attempt to improve efficiency by allowing particles to take discrete steps through optically thick regions based on a discretized diffusion approximation [2,3]. In IMC the approximate linearization of the emission source is not iterated on within a time step due to the large computational cost of the MC transport each time step; this imposes a limit on the time step size to produce physically accurate results [4].

In IMC the material and radiation energy fields are discretized spatially to solve for cell-averaged values. Inaccurate spatial representation of the emission source over a cell can result in energy propagating through the domain artificially fast, yielding non-physical results referred to as “teleportation error” [15]. The IMC method uses a fixup known as source tilting to mitigate this problem. Source tilting reconstructs a more accurate linear-discontinuous representation of the emission source within a cell based on the cell-averaged material temperatures in adjacent cells.

Moment-based hybrid Monte Carlo (MC) methods provide an alternative solution method. Recent work has focused on so-called high-order low-order (HOLO) approaches [5–8]. Such methods utilize a low-order (LO) operator based on angular moments of the transport equation, formulated over a fixed spatial mesh. Physics operators that are time consuming for MC to resolve, e.g., absorption-reemission and scattering events, are moved to the LO system. Newton methods allow for non-linearities in the LO equations to be fully resolved efficiently [5]. The high-order (HO) transport equation is defined by Eq. (1), with sources that are truly implicit in time estimated from the LO solution. The HO equation is solved via MC to produce a high-fidelity solution for the angular intensity. The MC estimate of the angular intensity is used to estimate consistency terms, present in the LO equations, that require the LO system to preserve the angular accuracy of the MC solution. The HO system does not directly estimate a new material temperature, eliminating stability issues that require linearization of the emission source.

Sufficient MC histories must be performed to eliminate statistical noise in the consistency terms that can contaminate the LO solution. Exponentially-convergent Monte Carlo (ECMC)[?] provides an algorithm that can efficiently reduce statistical noise to the same order as the HOLO iteration error with significantly less particle histories than standard MC. In particular, ECMC is exceptionally efficient in time-dependent TRT problems because information about the intensity from the previous time step can be used as an accurate initial guess for the end of time step intensity. Additionally, no particle histories are required in regions of the problem where the problem is in equilibrium, similar to [7]. However, implementation of ECMC is non-trivial, requiring a finite-element representation of the solution in all phase-space variables. The fundamental transport of particles is the same as standard Monte Carlo transport codes, but the source will now contain positive and negative weight particles.

Our ECMC solver contains similarities to the residual Monte Carlo (RMC) HO solver in [7], with some key differences. The RMC algorithm uses a particular, fixed estimate of the solution to significantly reduce the statistical noise in the simulation compared to a standard MC simulation. The guess for the solution is

chosen to produce only sources on the faces of cells, reducing the dimension of the phase-space to be sampled [7]. The RMC algorithm uses a piecewise constant trial space representation for the intensity in x and μ . The primary difference between the methods is that ECMC iteratively estimates the solution, in batches, producing a known MC estimate of the error in that estimate. The ECMC algorithm also uses a linear-discontinuous finite-element (LDFE) trial space to represent the intensity, although the RMC algorithm could similarly be formulated with an LDFE representation. The LDFE representation introduces significant implementation complexity. The formulation of the residual in [7] can produce minimal statistical noise in slowly varying problems where the behavior of the system is near equilibrium. The ECMC algorithm has similar statistical efficiency by choosing the old intensity as the initial guess to the algorithm. The ECMC algorithm will generally be more efficient in cases where the solution varies greatly over a time step or when very low statistical noise is desired. Generally, the minimum number of histories per batch to obtain convergence with the LDFE trial space is larger than a piece-wise constant representation because additional histories are needed to sufficiently estimate the first moment in x and μ of the intensity. It is noted that our formulation of the LO equations is in great contrast to the formulation in [7].

In this work, we demonstrate the utility of an S_2 -like LO operator [9] in conjunction with an ECMC method [10] for the HO solver. The ECMC algorithm uses information about the intensity from the previous time step to reduce statistical noise to the same order as the HOLO iteration error with significantly less particle histories than standard MC simulations, with less computational cost than IMC per history. We have derived the LO operator directly from the transport equation, using a linear-discontinuous (LD) finite-element (FE) spatial discretization, such that the HO and LO solutions are converging towards the same solution. Herein we describe the algorithm and present results for one-dimensional test problems.

II. Overview of the HOLO Algorithm

For simplicity, our HOLO method will use a backwards Euler discretization in time, as well as constant specific heats and cell-wise constant cross sections. The time discretized equations are

$$\mu \frac{\partial I^{n+1}}{\partial x} + \left(\sigma_t + \frac{1}{c\Delta t} \right) I^{n+1} = \frac{\sigma_s}{2} \phi^{n+1} + \frac{1}{2} (\sigma_a a c T^4)^{n+1} + \frac{I^n}{c\Delta t} \quad (3)$$

$$\rho c_v \frac{T^{n+1} - T^n}{\Delta t} = \sigma_a \phi^{n+1} - \sigma_a a c (T^4)^{n+1}. \quad (4)$$

where Δt is the time step size and the superscript n is used to indicate the n -th time step. It is noted that in IMC the time derivative in Eq. (1) is typically treated using continuous time-dependent MC over each time step. Our HO transport equation is discrete in time for easy application of ECMC and to avoid difficulties in coupling to the fully-discrete LO solver, but this does introduce some artificial propagation of energy due to the implicit time differencing, in optically thin regions.

In the HOLO context, the LO solver models the physical scattering and resolves the material temperature spatial distribution $T(x)$ at each time step. The LO equations are formed via half-range angular and spatial moments of Eq. (3) and Eq. (4), formed over a spatial finite element mesh. The angular treatment in the LO equations has the same form as those used in the hybrid- S_2 method in [9], with element-averaged consistency parameters that are analogous to a variable Eddington factor. If the angular consistency parameters were estimated exactly, then the LO equations are exact with respect to the chosen spatial discretization. These consistency parameters are lagged in each LO solve, estimated from the previous HO solution for $I^{n+1}(x, \mu)$, as explained below. For the initial LO solve for each time step, the parameters are calculated based on the $I^n(x, \mu)$. The LO equations always conserve total energy, independent of the accuracy of the consistency terms.

The solution to the LO system is used to construct a spatially LDFE representation of the scattering and emission sources on the right hand side of Eq. (3). The LDFE representation of the emission source mitigates teleportation error. This defines a fixed-source, pure absorber transport problem for the HO operator. This HO transport problem represents a characteristic method that uses MC to invert the continuous streaming plus removal operator with an LDFE representation of sources. We will solve this transport problem using ECMC. The output from ECMC is $\tilde{I}(x, \mu)$, a space-angle LDFE projection of the exact solution for $I(x, \mu)$. Once computed, $\tilde{I}(x, \mu)$ is used to directly evaluate the necessary consistency parameters for the next LO solve. Since there is a global, functional representation of the angular intensity, LO parameters are estimated using quadrature and do not require additional tallies. The HO solution is not used to directly estimate a new temperature at the end of the time step; it is only used to estimate the angular consistency parameters for the LO equations, which eliminates typical operator splitting stability issues that require linearization of the emission source.

The process of performing subsequential HO and LO solves, within a single time step, can be repeated to obtain an increasingly accurate solution for $\phi^{n+1}(x)$ and $T^{n+1}(x)$. Thus, the HOLO algorithm, for the n -th time step, is

1. Perform a LO solve to produce an initial guess for $T^{n+1,0}(x)$ and $\phi^{n+1,0}(x)$, based on consistency terms estimated with \tilde{I}^n .
2. Solve the HO system for $\tilde{I}^{n+1,k+1/2}(x, \mu)$ using ECMC, based on the current LO estimate of the emission and scattering sources.
3. Compute LO consistency parameters with $\tilde{I}^{n+1,k+1/2}$.
4. Solve the LO system using HO consistency parameters to produce a new estimate of $\phi^{n+1,k+1}$ and $T^{n+1,k+1}$.
5. Repeat 2 – 4 until convergence is achieved.
6. Store $\tilde{I}^n \leftarrow \tilde{I}^{n+1}$, and move to the next time step.

where the superscript k denotes an outer HOLO iteration. The consistency terms force the HO and LO solutions for $\phi^{n+1}(x)$ to be consistent to the order of the current HOLO iteration error.

III. Forming the Low-Order System

To form the LO system of equations, spatial moments are taken over each spatial cell i : $x \in [x_{i-1/2}, x_{i+1/2}]$, weighted with the standard linear FE interpolatory basis functions. For example, the L moment operator is defined by

$$\langle \cdot \rangle_{L,i} = \frac{2}{h_i} \int_{x_{i-1/2}}^{x_{i+1/2}} b_{L,i}(x)(\cdot) dx, \quad (5)$$

where $h_i = x_{i+1/2} - x_{i-1/2}$ is the width of the spatial element and $b_{L,i}(x) = (x_{i+1/2} - x)/h_i$ is the FE basis function, for cell i , corresponding to position $x_{i-1/2}$. The right moment $\langle \cdot \rangle_R$ is defined with weight function $b_{R,i}(x) = (x - x_{i-1/2})/h_i$. It is noted in this notation $\langle \phi \rangle_{L,i}$ and $\langle \phi \rangle_{R,i}$ represent spatial moments of the intensity over cell i , rather than $\phi_{L,i}$ and $\phi_{R,i}$, which represent the interior value of the linear $\phi(x)$ at $x_{i-1/2}$ and $x_{i+1/2}$. To reduce the angular dimensionality, positive and negative half-range integrals of the angular intensity are taken. The half-range averages of I are defined as $\phi^+(x) = \int_0^1 I(x, \mu) d\mu$ and $\phi^-(x) = \int_{-1}^0 I(x, \mu) d\mu$, respectively. Thus, in terms of half-range quantities, $\phi(x) = \phi^-(x) + \phi^+(x)$.

III.A. Radiation Energy Equations

Pairwise application of the L and R basis moments with the $+$ and $-$ half-range integrals to Eq. (3) ultimately yields four radiation moment equations per cell. As in [9], algebraic manipulation is performed to form intensity-weighted averages of μ , which we denote consistency terms. As an example, the equation resulting from application of the L moment and positive half-range integral is

$$-2\mu_{i-1/2}^{n+1,+} \phi_{i-1/2}^{n+1,+} + \{\mu\}_{L,i}^{n+1,+} \langle \phi \rangle_{L,i}^{n+1,+} + \{\mu\}_{R,i}^{n+1,+} \langle \phi \rangle_{R,i}^{n+1,+} + \left(\sigma_t^{n+1} + \frac{1}{c\Delta t} \right) h_i \langle \phi \rangle_{L,i}^{n+1,+} - \frac{\sigma_s h_i}{2} \left(\langle \phi \rangle_{L,i}^{n+1,+} + \langle \phi \rangle_{L,i}^{n+1,-} \right) = \frac{h_i}{2} \langle \sigma_a^{n+1} ac T^{n+1,4} \rangle_{L,i} + \frac{h_i}{c\Delta t} \langle \phi \rangle_{L,i}^{n,+}, \quad (6)$$

where the $\phi_{i-1/2}^+$ and $\mu_{i-1/2}^+$ terms represent face-averaged quantities at $x_{i-1/2}$. The negative direction and R moment equations are derived analogously. Opacities are assumed constant over each element, evaluated at the average temperature in the element, i.e., $\sigma_a = \sigma_a([T_{L,i} + T_{R,i}]/2)$, $x \in (x_{i-1/2}, x_{i+1/2})$. The element-averaged angular consistency terms are defined in terms of half-range integrals, e.g.,

$$\{\mu\}_{L,i}^{n+1,+} \equiv \frac{\langle \mu I^{n+1} \rangle_{L,i}^+}{\langle I^{n+1} \rangle_{L,i}^+} = \frac{\frac{2}{h_i} \int_0^1 \int_{x_{i-1/2}}^{x_{i+1/2}} \mu b_{L,i}(x) I^{n+1}(x, \mu) dx d\mu}{\frac{2}{h_i} \int_0^1 \int_{x_{i-1/2}}^{x_{i+1/2}} b_{L,i}(x) I^{n+1}(x, \mu) dx d\mu}. \quad (7)$$

The $\mu_{i-1/2}^{n+1,+}$ term is defined analogously and represents an angular average on the face at $x_{i-1/2}$.

III.B. Material Energy Equations

To derive the LO material energy equations, $T(x)$ is represented spatially in the LDFE trial space, i.e., $T(x) \simeq T_{L,i} b_{L,i}(x) + T_{R,i} b_{R,i}(x)$, $x \in (x_{i-1/2}, x_{i+1/2})$. Similarly, the emission term is represented in the material and radiation equations with the LDFE interpolant $T^4(x) \simeq T_{L,i}^4 b_{L,i}(x) + T_{R,i}^4 b_{R,i}(x)$. The L and R spatial moments are taken of the material energy equation, using these definitions for $T(x)$ and $\sigma_a ac T^4(x)$ to simplify moments. For example, the final LO material energy equation resulting from application of the L moment is

$$\frac{\rho_i c_{v,i}}{\Delta t} \left[\left(\frac{2}{3} T_{L,i} + \frac{1}{3} T_{R,i} \right)^{n+1} - \left(\frac{2}{3} T_{L,i} + \frac{1}{3} T_{R,i} \right)^n \right] + \sigma_a^{n+1} \left(\langle \phi \rangle_{L,i}^+ + \langle \phi \rangle_{L,i}^- \right)^{n+1} = \sigma_a^{n+1} ac \left(\frac{2}{3} T_{L,i}^4 + \frac{1}{3} T_{R,i}^4 \right)^{n+1}. \quad (8)$$

Because the material energy balance only contains angularly integrated quantities, there is no need to take angular moments of the above equation.

III.C. Closing the System with Information from the HO solution

The six degrees of freedom (DOF) over each cell i are the four moments $\langle \phi \rangle_{L,i}^+$, $\langle \phi \rangle_{R,i}^+$, $\langle \phi \rangle_{L,i}^-$, and $\langle \phi \rangle_{R,i}^-$ and the two spatial edge values $T_{L,i}$ and $T_{R,i}$. The four radiation and two material energy equations define a system of equations for the six DOF, coupled to other cells via upwinding in the streaming term. The relation between the volume and face averaged quantities and the angular consistency parameters (e.g., Eq. (7)) are not known a priori. A lagged estimate of I^{n+1} from the previous HO solve is used to estimate the angular consistency parameters. In the HOLO algorithm, the equations for LO unknowns at iteration

$k + 1$ use consistency parameters computed (via relations, e.g., Eq. (7)) using the latest HO solution $\tilde{I}^{n+1,k+1/2}$ as an approximation for $I^{n+1}(x, \mu)$. To close the LO system spatially, the usual upwinding approximation is used. For example, for positive flow (e.g., Eq. (6)) the face terms $\mu_{i-1/2}$ and $\phi_{i-1/2}$ are upwinded from the previous cell $i - 1$ or from a boundary condition; the terms at $x_{i+1/2}$ are linearly extrapolated, computed using the L and R basis moments, e.g., $\phi_{i+1/2}^+ = 2\langle\phi\rangle_R^+ - \langle\phi\rangle_L^+$. The HO ECMC solver computes an LDFE representation of the intensity, so the same spatial closure is used to relate volume and face averaged consistency terms. Thus, the spatial closure between the LO and HO solvers are inherently consistent. Because there are no spatial temperature derivatives, there is no need for an additional closure in T .

The LD closure is not strictly positive. In particular, for optically thick cells with a steep intensity gradient, the solution becomes negative. These negativities can also result in adjacent cells in the direction of flow. In thick regions of TRT problems, reasonably fine spatial cells can still be on the order of millions of mean free paths; negativities with a LD representation are unavoidable in practice for such cells and mesh refinement is of minimal use. Typically, for a standard LDFE method, the equations are lumped to produce a strictly positive solution for 1D [11]. However, standard FE lumping procedures would introduce difficulties in computing the consistency terms from the HO solution. Thus, an alternative spatial closure is used that is equivalent to the standard FE lumping procedure. The L and R moments are defined the same as before, preserving the same average within a cell, but the relation between the moments and the outflow is modified. For example, for positive μ , the outflow is now defined as $\phi_{i+1/2}^+ = \langle\phi\rangle_R^+$. Because the basis function $b_{R,i}(x)$ is strictly positive, the outflow is positive. This closure is only used in cells that negativities occur.

III.D. Solving the Non-Linear LO System

We have used Newton's method to solve the global system of coupled LO equations, based on a typical linearization of the Planckian source with cross sections evaluated at the previous iteration temperatures, as described in [11]. Once the system is linearized, a discrete matrix equation is formed. Scattering is included in the system matrix. The system matrix is an asymmetric, banded matrix with a band width of seven and is inverted directly. Newton iterations are repeated until $\phi^{n+1}(x)$ and $T^{n+1}(x)$ are converged to a desired relative tolerance. Convergence is calculated using the spatial L_2 norm of the change in $\phi^{n+1}(x)$ and $T^{n+1}(x)$, relative to the norm of each solution. The lumping-equivalent discretization discussed above is used for cells where the solution for ϕ^{n+1} becomes negative. When negativities are detected, the lumping-equivalent discretization is used within those cells and that Newton step is repeated.

IV. The ECMC High Order Solver

The transport equation to be solved by the HO solver is

$$\mu \frac{\partial I^{n+1,k+1/2}}{\partial x} + \left(\sigma_t^k + \frac{1}{c\Delta t} \right) I^{n+1,k+1/2} = \frac{\sigma_s}{2} \phi^{n+1,k} + \frac{1}{2} \left(\sigma_a^k a c T^4 \right)^{n+1,k} + \frac{\tilde{I}^n}{c\Delta t} \quad (9)$$

where the superscript k represents the outer HOLO iteration index. Material property indices will be suppressed from now on. Here, $k + 1/2$ denotes the ECMC solution within outer HOLO iteration k , whereas k and $k + 1$ represent successive LO solves. The sources at k in Eq. (9) are estimated by the previous LO solution. Cross sections are evaluated at $T^{n+1,k}$. As all sources on the right side of the equation are known, this defines a fixed-source, pure absorber transport problem. We will solve this equation using ECMC. A more detailed description of the ECMC method can be found in [12], but a brief overview is given here.

In operator notation, the previous equation can be written as

$$\mathbf{L}^k I^{n+1,k+1/2} = q^k \quad (10)$$

where $I^{n+1,k+1/2}$ is the transport solution of the angular intensity based on the k -th LO estimate of q^k . The linear operator \mathbf{L}^k is the streaming plus removal operator defined by the left hand side of Eq. (3). The m -th approximate LDFE solution to Eq. (10) (m is the index of inner HO batches) is represented as $\tilde{I}^{n+1,(m)}$. The m -th residual is defined as $r^{(m)} = q - \mathbf{L}\tilde{I}^{n+1,(m)}$. For reference, the residual at iteration m in the HO solve is

$$r^{(m),k+1/2} = \frac{\sigma_s}{2}\phi^{n+1,k} + \frac{1}{2}(\sigma_a a c T^4)^{n+1,k} + \frac{\tilde{I}^n}{c\Delta t} - \left(\mu \frac{\partial \tilde{I}^{n+1,k+1/2}}{\partial x} + \left(\sigma_t + \frac{1}{c\Delta t} \right) \tilde{I}^{n+1,k+1/2} \right)^{(m)} \quad (11)$$

where the k terms are LD in space on the coarsest mesh and are not recalculated at any point during the HO solve. The functional form of \tilde{I}^n is defined from the final HO solution of the previous time step.

To define the ECMC algorithm, the HOLO iteration indices are dropped, as the LO estimated q^k and \mathbf{L}^k remain constant over the entire HO solve. Addition of $\mathbf{L}I^{n+1} - q = 0$ to the residual equation and manipulation of the result yields the error equation

$$\mathbf{L}(I^{n+1} - \tilde{I}^{n+1,(m)}) = \mathbf{L}\epsilon^{(m)} = r^{(m)} \quad (12)$$

where I^{n+1} is the exact solution and $\epsilon^{(m)}$ is the error in $\tilde{I}^{n+1,(m)}$. The \mathbf{L} operator in the above equation is inverted yielding the Monte Carlo LDFE projection of the error in $\tilde{I}^{n+1,(m)}$, i.e.,

$$\tilde{\epsilon}^{(m)} = \mathbf{L}^{-1}r^{(m)} \quad (13)$$

where \mathbf{L}^{-1} is the Monte Carlo inversion of the streaming and removal operator. This inversion is strictly a standard Monte Carlo simulation. The space-angle moments of the error computed in $\tilde{\epsilon}^{(m)}$ can be added to the moments of $\tilde{I}^{n+1,(m)}$ to produce a more accurate solution.

Here, we emphasize the solution $\tilde{I}^{n+1,(m)}$ represents the projection of the exact Monte Carlo solution onto the trial space. This is in general far more accurate than a standard finite element solution. For example, in typical IMC calculations the average energy deposition within a cell is computed using a standard path-length volumetric flux tally; the zeroth moment of the LDFE projection of $\tilde{\epsilon}$ is computed using an equivalent tally. The primary truncation error is in the LD representation of the right hand side source terms. Volumetric flux tallies over each space-angle element are required to represent $\tilde{\epsilon}^{(m)}$. The tallies are given in Appendix A.

The ECMC algorithm is

1. Initialize the guess for $\tilde{I}^{n+1,(0)}$ to \tilde{I}^n or the projection of \tilde{I}^{n+1} from the latest HO solve
2. Compute $r^{(m)}$.
3. Perform a MC simulation to obtain $\tilde{\epsilon}^{(m)} = \mathbf{L}^{-1}r^{(m)}$
4. Compute a new estimate of the intensity $\tilde{I}^{n+1,(m+1)} = \tilde{I}^{n+1,(m)} + \tilde{\epsilon}^{(m)}$
5. Repeat steps 2 – 4 until desired convergence criteria is achieved.

The initial guess for the angular intensity $I^{n+1,(0)}$ is computed based on the previous solution for \tilde{I}^n . This is a critical step in the algorithm; it significantly reduces the required number of particles per time step because the intensity does not change drastically between time steps in optically thick regions. It is noted

that the ECMC batch (steps 1-4 of the algorithm) results in essentially the same estimate of the solution as the residual formulation used in [7]. The primary difference is that our method uses an LDFE trial space, and we are able to use our new estimate of the solution to recompute a residual.

Exponential convergence is obtained because with each batch a better estimate of the solution is being used to compute the new residual, decreasing the magnitude of the Monte Carlo source each iteration m , relative to the solution I^{n+1} . Each Monte Carlo estimate of the moments of ϵ still has a statistical uncertainty that is governed by the standard $1/\sqrt{N}$ convergence rate [13], for a particular source $r^{(m)}$. If the statistical estimate of the projection $\tilde{\epsilon}$ is not sufficiently accurate, then the iterations would diverge. Although the variance in tallies of $\epsilon^{(m)}$ can be estimated with the sample variance of histories, the variance in the moments of $I^{n+1,(m)}$ cannot be easily estimated due to the correlation between $I^{n+1,(m)}$ and the source $r^{(m)}$.

Because the exact angular intensity does not in general lie within the LDFE trial space, the iterative estimate of the error will eventually stagnate once the error cannot be sufficiently represented by a given FE mesh. Although mesh refinement is not performed in the calculations presented here, an adaptive h -refinement algorithm has been implemented that can be used to allow the system to continue converging towards the exact solution [10,8]. In general, for TRT problems, optically thick and slowly varying regions of the problem do not require as refined of a mesh to accurately capture the solution because there is less variation in the angular dependence of the solution. Once error stagnation has occurred, additional histories can be performed with a fixed residual source to estimate the remaining error in the current solution. Although the remaining error will converge statistically at a standard $1/\sqrt{N}$ convergence rate, the remaining error will be much smaller than a standard MC simulation, producing a much more efficient solution method overall.

For the HO solver, in cells near the radiation wave front, the LDFE trial space results in negativities in $\tilde{I}^{n+1}(x, \mu)$, similar to the LO solver. Because the residual formulation in ECMC allows for negative weight particles to occur, currently we do not treat these cells specially. We detect if the consistency terms lie in the appropriate half space at the end of the HO solve, an indication that the intensity was negative within that cell. If the terms are non-physical, then they are replaced with the corresponding S_2 -equivalent value. In general, in such cells where the trial space cannot accurately represent the solution, error stagnation will rapidly occur.

IV.A. Variance Reduction and Source Sampling

As in [6], because we are solving a pure absorber problem with Monte Carlo, we will allow particles to stream without absorption to reduce statistical variance in the tallies. The weight of particles is reduced deterministically along the path as they stream, with no need to sample a path length. Because particles are exponentially attenuated, the normalized weight is adjusted as $w(x, \mu) = w(x_0, \mu) \exp(-\sigma|(x - x_0)/\mu|)$, where x_0 is the starting location of the path. The tallies account for the continuously changing weight, as given in Appendix A. Histories are allowed to stream in this manner for 6 mean free paths before switching to analog path length sampling; this limits the tracking of very small weight histories. The choice of 6 mean free paths allows particles to continuously deposit weight until they reach 0.25% of their original weight.

As another way to improve efficiency, a modified systematic sampling method [13] was used for determining source particle locations. The goal is to effectively distribute particle histories to regions of importance, but to sample a sufficient number of histories in less probable regions to prevent large statistical noise. However, there is no need to sample histories in regions in equilibrium. The residual gives a good indication of where histories are most likely to contribute to the error, particularly in optically thick

cells where particles do not transport long distances. The residual consists of both face and volumetric sources [10]. In the sampling algorithm the number of particle histories sampled in each space-angle cell is predetermined and proportional to the magnitude of the residual, including face and volumetric sources, within that cell. Then, for the predetermined number of histories within a cell, the source location is randomly sampled according to the residual source distribution of that cell. There is a relative probability cutoff such that cells with an insignificant residual will have no histories sampled there. In these regions the problem is remaining in equilibrium and the solution is known exactly. For cells that are significant, but have a predetermined number of histories below some preset minimum N_{min} , the number of histories sampled in that cell is set to N_{min} . This is to limit bad statistics in low probability cells (this would be important for adaptively refined meshes). In the simulations performed for this work $N_{min} = 1$. This choice was made for comparing to IMC to keep the total number of histories per time step constant throughout the entire simulation. The relative probability cutoff was 10^{-4} .

V. Results

We will compare results of the HOLO method to IMC with a source tilting algorithm for two test problems [14]. Also, we briefly compare performance in Section V.C. Finally, we will demonstrate the efficiency advantage of ECMC in our HOLO algorithm by comparing the results to the same HOLO algorithm if the ECMC algorithm is replaced with a standard Monte Carlo (SMC) simulation. Results are also given for the case of a single ECMC batch, which is similar to a RMC method [7].

A measure of variance in cell-averaged scalar intensities was calculated to provide a quantitative measure of the statistical accuracy of different solution methods. To form sample standard deviations, twenty independent simulations for each particular result were performed using different pseudo-random number seeds. The variance of a particular cell-averaged $\phi(x)$ is

$$S_i^2 = \frac{20}{20-1} \sum_{l=1}^{20} \left(\bar{\phi}_i - \phi_i^l \right)^2, \quad (14)$$

where ϕ_i^l is the cell-averaged scalar intensity for cell i from the l -th of 20 independent simulations and $\bar{\phi}_i$ is the corresponding sample mean from the 20 simulations. To provide a normalized, spatially-integrated result, we form a norm over cells as

$$\|s\| = \left(\frac{\sum_{i=1}^{N_c} S_i^2}{\sum_{i=1}^{N_c} \bar{\phi}_i^2} \right)^{1/2}, \quad (15)$$

where N_c is the number of spatial cells.

We will also form a figure of merit (FOM) to demonstrate how statistical accuracy scales with the number of histories performed. Our FOM is defined as

$$\text{FOM} = \frac{1}{N_{\text{tot}} \|s\|^2} \quad (16)$$

where N_{tot} is the total number of histories performed over the simulation. A larger value of the FOM indicates that the method produced less variance in the solution per history performed, for a given problem. This form of the FOM is typically chosen because the variance is expected to reduce inversely proportional to N_{tot} , so for standard MC simulations the FOM becomes, on average, independent of N_{tot} [13]. The FOM is not necessarily expected to be independent of N_{tot} for IMC or our HOLO method due to correlation of the solution between time steps; additionally, ECMC has correlations between batches.

V.A. Marshak Wave

For the first problem, the radiation and material energies are initially in equilibrium at 2.5×10^{-5} keV. An isotropic incident intensity of 0.150 keV is applied at $x = 0$; the incident intensity on the right boundary is 2.5×10^{-5} keV. The material properties are $\rho = 1 \text{ g cm}^{-3}$ and $c_v = 0.013784 \text{ jks/keV-g}$. The absorption cross section varies as $\sigma(T) = 0.001 \rho T^{-3} \text{ (cm}^{-1}\text{)}$. The simulation was advanced until $t = 5 \text{ sh}$ ($1 \text{ sh} \equiv 10^{-8} \text{ s}$) with a fixed time step size of 0.001 sh. For comparison purposes, we have not used adaptive mesh refinement, only performed one HOLO iteration per time step, and use a fixed 3 HO batches with equal number of histories per batch. A relative tolerance of 10^{-6} for the change in $\phi(x)$ and $T(x)$ was used for the LO newton solver. Radiation energy distributions are plotted as an equivalent temperature given by $T_r = (\phi/(ac))^{0.25}$. Cell-averaged quantities are plotted. Although isotropic scattering can be included in the LO solver with this method [8], we have only considered problems with $\sigma_s = 0$ here.

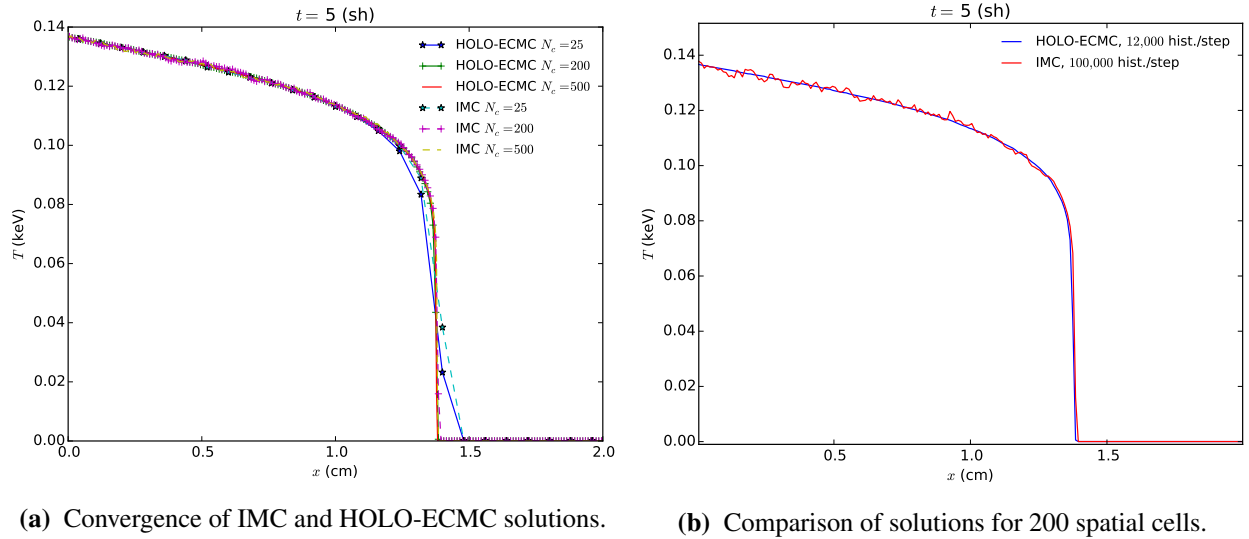


Figure 1: Comparison of solutions for Marshak wave problem at $t = 5 \text{ sh}$.

Fig. 1a compares the cell-averaged radiation temperatures for the IMC and HOLO method with ECMC, for various number of spatial mesh cells N_c ; we have used HOLO-ECMC to denote our algorithm because the results in Section V.D HO solvers. For all IMC calculations, $n = 10^5$ histories per time step were used. For the HOLO method, we have used 4 equal-sized cells in μ for the finite-element angular mesh used by the ECMC solver. The spatial grid is the same for the HO and LO solvers. For the cases of $N_c = 25$ and $N_c = 200$, 4,000 histories per batch ($n = 12,000$ per time step) were used. For $N_c = 500$, 16,000 histories per time step were used due to increased number of space-angle cells that need to be sampled. The IMC and HOLO solutions agree as the mesh is converged. There is similar agreement in the location of the wave front due to the linear shape of the emission source over a cell. The cells nearest the wave front required use of the lumping-equivalent discretization and S_2 equivalent terms during the LO solve, resulting in strictly positive solutions.

Fig. 1b compares solutions for the case of 200 cells. For the IMC solution 10^5 histories per time step were simulated; for the HOLO method only 4,000 histories per batch (12,000 per time step) were simulated. There is significant statistical noise in the IMC solution compared to the HOLO solution. The HOLO solution visually demonstrates no statistical noise. Because the ECMC solve is only determining the change over the time step, the statistical noise in the result is small relative to the magnitude of I^{n+1} . Also, the source sampling only places particles in cells where the residual is large. No particles are sampled in

the equilibrium region out front of the wave.

Table I compares $\|s\|$ and the FOM for IMC and the HOLO method, for different numbers of histories per time step. The FOM results are normalized to the value for IMC with $n = 12,000$. HOLO-ECMC demonstrates less variance for the same numbers of histories. Where as the FOM remains relatively constant for IMC, as n is increased the FOM improves for HOLO-ECMC. This is a result of each batch producing more statistically accurate estimates of the error ϵ , which results in an increased convergence rate of ϵ overall.

Table I: Comparison of sample statistics for the Marshak Wave problem for 200 x cells. Simulation end time is $t = 5$ sh.

hists./step	$\ s\ $		FOM	
	IMC	HOLO-ECMC	IMC	HOLO-ECMC
12,000	3.40%	0.28%	1	145
100,000	1.22%	0.057%	0.93	422

V.B. Two Material Problem

This problem consists of an optically thin (left) and an optically thick (right) material region, with constant cross sections. The material properties are given in Table II. Initially the radiation and material energies are in equilibrium at a temperature of 0.05 keV. An isotropic incident intensity of 0.500 keV is applied at $x = 0$ at $t = 0$; the isotropic incident intensity on the right boundary is 0.05 keV. The simulation is ran for 5 sh. For all HOLO simulations, we have used 8 equal-sized mesh cells in μ . As for the Marshak problem, the cells nearest the wave front required use of the lumping-equivalent discretization and S_2 equivalent terms during the LO solve.

Table II: Material properties for two material problem

	$x \in [0, 0.5)$ cm	$x \in [0.5, 1.0]$ cm
σ_a (cm ⁻¹)	0.2	2000
ρ (g cm ⁻³)	0.01	10.0
c_v (jks/keV-g)	0.1	0.1

Fig. 2a compares the HOLO and IMC radiation temperatures at the end of the simulation. The IMC and HOLO results show good agreement over the finer mesh. On the coarse mesh ($N_c = 20$), the LDFE representation of T^4 in the HOLO method predicts the location of the wave front more accurately than the IMC method with source tilting.

Fig. 2b demonstrates the benefit of ECMC as a HO solver compared to standard MC. The HOLO algorithm with the ECMC HO solver (HOLO-ECMC) results are for running 3 batches of 10,000 histories, per time step. The solution for the HOLO method with a standard MC solver as the HO solver (HOLO-SMC) with standard source sampling uses 10^5 histories per time step. The HOLO-SMC solution demonstrates significant statistical noise. This noise is introduced into the LO solver by bad statistics in computing the consistency terms. Also plotted is an S_2 solution obtained with consistency terms that are equivalent to S_2 and not performing the HO correction step in the algorithm. The S_2 solution results in an artificially fast wave front, as expected, demonstrating the necessity of HO correction in this problem.

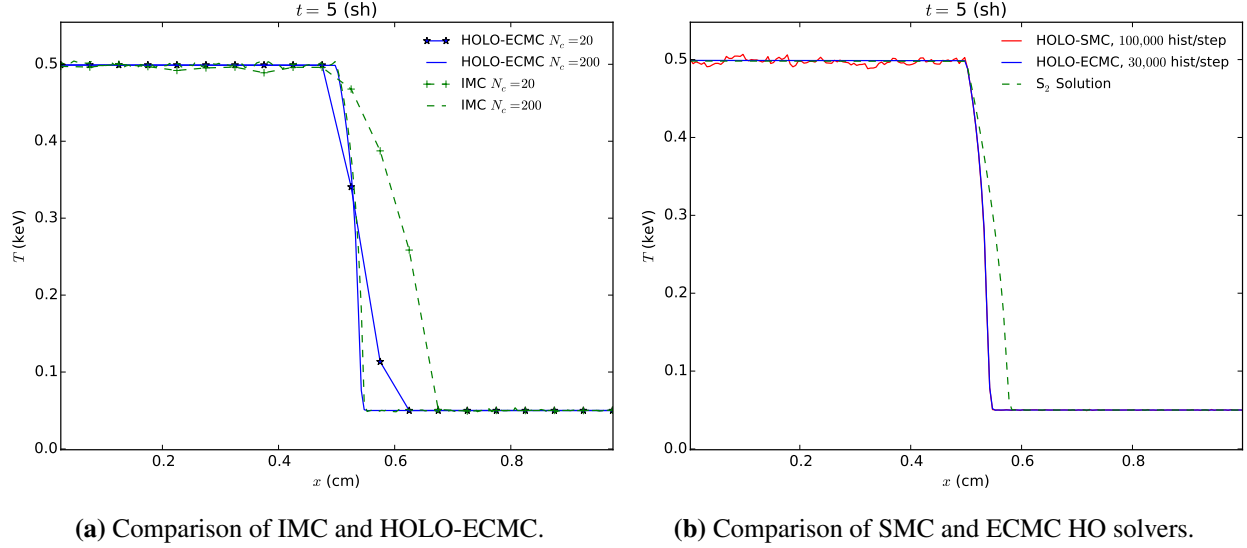


Figure 2: Comparison of radiation temperatures for two material problem.

Table III compares the FOM and $\|s\|$ for IMC and the HOLO-ECMC method. The FOM values are normalized to the value for IMC with $n = 30,000$. The end time was reduced to 2 sh for these results to reduce computational times. The reduction in variance by the HOLO method over IMC is substantial. The improvement of the FOM for the HOLO method compared to IMC is greater than for the Marshak wave problem. This improvement is because the wave moves much slower in this problem, due to the large, constant cross section in the right region. Also, in the optically thin region of the problem the solution quickly comes to equilibrium. Thus, the ECMC algorithm has to estimate a very small change in the solution over a time step. Additionally, difficulties in resolving the solution at the wave front are not as severe compared to the Marshak wave problem, where the cold cells have a much larger cross section.

Table III: Comparison of sample statistics for the two material problem for 200 x cells. Simulation end time is $t = 2$ sh.

hists./step	$\ s\ $		s_{\max}	
	IMC	HOLO-ECMC	IMC	HOLO-ECMC
30,000	3.63%	0.01%	1	104,000
100,000	1.96%	0.003%	1.03	360,000

V.C. Performance comparison of IMC and HOLO-ECMC

We have measured the total CPU time for simulations to provide a crude measure of the computational cost. These results provide a measure of how the methods compare for the two different problems and how they scale with time step size and particle histories. Absolute comparisons in the computational cost of the two methods cannot be made because the methods are implemented in different code infrastructures. Additionally, the HOLO method fully resolves non-linearities at each time step, whereas IMC is using a single linearized step with lagged cross sections. Simulations were performed on the same processor, using a single CPU core. Reported times are the average of 10 runs.

Table IV compares the average simulation time per history performed for the Marshak wave problem. The average time per history is computed by dividing the total simulation time by the total number of histories performed (the time of the LO solves is included for the HOLO method). Results are given for different numbers of histories per time step, as well as a case with an increased time step size. The table also includes the number of LO iterations performed per LO solve for the HOLO method, averaged over all time steps; there are two LO solves per time step. The same results are reported for the two material problem in Table V.

The HOLO method does not scale with the number of histories due to the fixed cost of the LO solver. The cost of the LO solver is more significant at the lower history counts compared to the case of 10^5 histories, for both problems. There is a slight increase in the number of newton iterations as the time step is increased, but the average cost per history is not significantly increased. Similar to the results in [6], as the time step size is increased to 0.005 sh, the IMC method increases in cost per time step, particularly for the two material problem. Because the cross sections in the two material problem do not have a T^{-3} behavior, the cost of the effective scattering cross section in IMC is more apparent, resulting in longer simulation times.

Table IV: Comparison of average CPU times per history and LO iterations counts for the Marshak Wave problem for 200 x cells. Simulation end time is $t = 2$ sh.

hists./step	$\Delta t(sh)$	IMC ($\mu s/hist.$)	HOLO-ECMC ($\mu s/hist$)	Iters./LO solve
10^5	0.001	10	5.3	3.8
1.2×10^4	0.001	9.7	8.1	4.1
1.2×10^4	0.005	19	9.4	6.2

Table V: Average CPU times per history required for the two material problem. Simulation end time is $t = 2$ sh.

hists./step	$\Delta t(sh)$	IMC ($\mu s/hist.$)	HOLO-ECMC ($\mu s/hist$)	Iters./LO Solve
10^5	0.001	17	3.5	4.9
3×10^4	0.001	18	6.9	5.0
3×10^4	0.005	59	7.4	7.6

V.D. Comparison of different HO Solvers

In this section we compare the results of our HOLO algorithm with different HO solvers. We compare standard MC (SMC) as a HO solver to the HOLO algorithm with ECMC using both three batches and a single batch, per time step. The use of a single batch is similar to the approach in [7]. Results are tabulated using the same total number of histories per time step, divided evenly among the batches.

Tables VI and VII compare the results for the Marshak wave and two material problems. The number of batches for each ECMC case is indicated in parenthesis. The FOM values are normalized to the corresponding IMC values from Tables I and III. For HOLO-SMC there is minimal reduction in variance compared to IMC in the Marshak wave problem and the two material problem actually demonstrates worse variance. Sufficient histories are not performed to accurately estimate consistency terms throughout the problem. For ECMC, a single batch produces less variance than the case of three equal batches. This indicates that if the solution cannot be resolved with the trial space (i.e., the intensity is driven negative), a

single large batch may be more accurate. It is noted that these results only account for statistical variance, and do not account for the additional error in the solution ϵ that is being computed each iteration.

Table VI: Comparison of sample statistics for the Marshak Wave problem for 200 x cells. Simulation end time is $t = 5$ sh.

	$\ s\ $			FOM		
hists./step	SMC	ECMC (1 batch)	ECMC (3 batches)	SMC	ECMC (1 batch)	ECMC (3 batches)
12,000	2.77%	0.10%	0.28%	1.50	1280	145
100,000	0.98%	0.03%	0.06%	1.43	1270	422

Table VII: Comparison of sample standard deviations for the two material problem for 200 x cells and $\delta t = 0.001$ sh. Simulation end time is $t = 2$ sh.

	$\ s\ $			FOM		
hists./step	SMC	ECMC (1 batch)	ECMC (3 batches)	SMC	ECMC (1 batch)	ECMC (3 batches)
30,000	5.35%	0.002953%	0.011%	0.46	1.51×10^6	1.04×10^4
100,000	2.85%	0.001474%	0.0033%	0.49	1.80×10^6	3.59×10^4

V.E. Pre-heated Marshak wave problem and adaptive mesh refinement

Finally, to demonstrate the potential of ECMC with adaptive space-angle mesh refinement, we perform results for a modified Marshak wave problem. The problem is modified so that the LDFE trial space can accurately represent the solution (i.e., the intensity is strictly positive). Mesh refinement is of minimal use in the previous problems due to the large cross sections. The modified problem has the same material properties and left boundary source as the Marshak wave problem in Section V.A. However, the initial equilibrium temperature and right boundary condition are raised to 0.03 keV. The higher initial temperature reduces the initial cross section and increases the strength of the emission source within cells. The LDFE mesh can now sufficiently resolve the solution and lumping is not required by the LO solution. The simulation end time is 0.5 sh with a constant time step of $\Delta t = 0.001$ sh.

Fig. 3 compares the result from HOLO-ECMC with three batches and IMC. It was found that 100 x cells was sufficient to resolve the solution spatially. There is slightly more noise in IMC past the wave front due to the increased emission source. Additionally, the opacity is thin enough that some photon energy is able to reach the equilibrium region of the problem past the wave.

Table VIII compares the variances for this problem for the various HO solvers. The final row of the table is for an ECMC simulation with adaptive mesh refinement. The strategy for refinement is described in Appendix B. The adaptive mesh refinement case used a total of nine batches, with a refinement occurring at the end of the third and sixth batches. The initial number of histories was adjusted so that the average number of histories per time step is near 100,000; on average 99,881 histories were used. All ECMC meshes used 4 equally-spaced μ cells initially.

The FOM values are normalized to the case of HOLO-SMC with 12,000 histories per time step. The improvement in variance over SMC is not as significant as for the other problems. This is a result of the reduced opacity leading to intensity changing throughout the problem. The angular solution also varies more. The FOM is highest for the case of ECMC with adaptive refinement. When the solution can be

resolved, the adaptive algorithm allows for a higher convergence rate of statistical variance. It is noted that the consistency terms are still computed over the coarser LO mesh. Additionally, in general, the refined mesh can produce higher accuracy in consistency terms that is not being measured by the FOM.

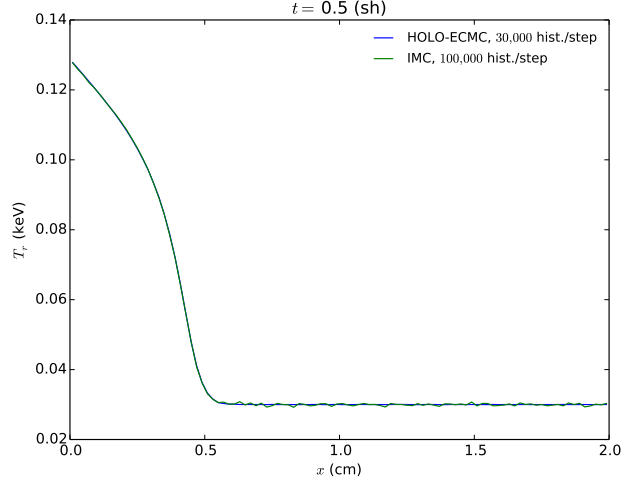


Figure 3

Figure 4: Comparison of solutions for the pre-heated Marshak wave problem for 100 x cells at $t = 0.5$ sh.

Table VIII: Comparison of sample statistics for the pre-heated marshak wave problem for 100 x cells. Simulation end time is $t = 0.5$ sh.

hists./step	$\ s\ $			FOM		
	SMC	ECMC (1 batch)	ECMC (3 batches)	SMC	ECMC (1 batch)	ECMC (3 batches)
12,000	0.86%	0.13%	0.24%	1	41	13
100,000	0.16%	0.042%	0.08%	3.32	52	15
99,881 (AMR)	—	—	0.038%	—	—	61

VI. Conclusions

We have been able to produce solutions for Marshak wave test problems using a new HOLO method that are in agreement with IMC. Unlike IMC, our method requires no effective scattering events to be included in the MC simulation, which limits the run time of particle tracking and adding the relatively steady cost of the LO newton solver. The LDFE spatial representation mitigates issues with teleportation error, similar to source tilting in the IMC algorithm. The ECMC approach, with initial guesses based on the previous radiation intensity, results in efficient reduction of statistical error and allows for particles to be distributed to largely varying regions of the problem. The LO solver resolves the non-linearities in the equations resulting in a fully implicit time discretization. The LO solver can accurately and efficiently resolve the solution in diffusive regions, while the HO transport solver provides the accuracy of a full transport treatment where necessary.

The primary difficulty to overcome in the ECMC algorithm is when the solution cannot be accurately represented by the trial space, e.g., in optically thick cells where the solution is driven negative. We are currently developing an approach to allow the ECMC iterations to continue converging globally when there

are such regions present. It is necessary to ensure the closure in the LO system is consistent with the HO representation for the solution in such regions. The ability to represent the solution accurately in rapidly varying regions of the problem will be key for generalization of this method to higher dimensions. A formulization of the ECMC method that allows for time-continuous MC transport (similar to IMC) is also currently being investigated. This may reduce some of the loss of accuracy in optically thin regions due to the time discretization of the transport equation in the HO solver. However, greater time accuracy is not of primary concern as this method is intended for use in problems dominated by large absorption opacities, where the absorption-reemission physics make the LO acceleration is critical.

Future work will also explore the accuracy of the HOLO method, in particular comparing using more than one batch and the benefit of adaptive refinement. This will likely require the use of manufactured solutions. The sensitivity of the method to mesh sizes and time step sizes will be investigated more thoroughly. Future results will investigate the ability of this method to preserve the maximum principle [4]. Ultimately, we plan to extend this method to multiple spatial dimensions for the case of multigroup TRT equations. For TRT problems, it is important that the LO spatial discretization satisfies the equilibrium diffusion limit. To extend to higher dimensions, our LDFE representation may require the use of a higher-degree spatial representation for the LO system to achieve the diffusion limit. Further asymptotic analysis on the method will be applied before implementation. It may be necessary to use a different LO system (e.g., the non-linear diffusion acceleration approach in [7]), if the S_2 -like equations become too inefficient or difficult to implement in higher dimensions. Alternatively, a variable Eddington Tensor approach may provide more stability in rapidly variable regions of the problem while still being consistent and efficiently solvable.

ACKNOWLEDGEMENTS

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A Implementation of ECMC finite-element space and tallies

The ECMC solver uses a finite element representation in space and angle. On the interior of the cell with the i -th spatial index and j -th angular index, the linear representation is defined as

$$\tilde{I}(x, \mu) = I_{a,ij} + \frac{2}{h_x} I_{x,ij} (x - x_i) + \frac{2}{h_\mu} I_{\mu,ij} (\mu - \mu_j), \quad x_{i-1/2} < x < x_{i+1/2}, \quad \mu_{j-1/2} \leq \mu \leq \mu_{j+1/2}$$

The spatial cell width is h_x , the angular width is h_μ , the center of the cell is (x_i, μ_j) , and

$$I_{a,ij} = \frac{1}{h_x h_\mu} \iint_{\mathcal{D}} I(x, \mu) dx d\mu \quad (17)$$

$$I_{x,ij} = \frac{6}{h_x h_\mu} \iint_{\mathcal{D}} \left(\frac{x - x_i}{h_x} \right) I(x, \mu) dx d\mu \quad (18)$$

$$I_{\mu,ij} = \frac{6}{h_x h_\mu} \iint_{\mathcal{D}} \left(\frac{\mu - \mu_j}{h_\mu} \right) I(x, \mu) dx d\mu, \quad (19)$$

where $\mathcal{D} : x_{i-1/2} \leq x \leq x_{i+1/2} \times \mu_{j-1/2} \leq \mu \leq \mu_{j+1/2}$. Standard upwinding in space is used to define $I(\mu)$ on incoming faces. This representation can directly be plugged into Eq. (11) and evaluated to produce the residual source in the ECMC HO transport problem.

During a MC batch, moments of the error are tallied. The necessary moments of the error are defined analogously to Eq.'s (17)–(19). The tallies are evaluated by weighting the particle density with the appropriate basis function and integrating along the path of the history. For the cell average, the n -th particle makes the contribution

$$\epsilon_{a,ij}^n = \frac{1}{h_x h_\mu} \int_{s_o^n}^{s_f^n} w^n(x, \mu) ds \quad (20)$$

where s_o^n and s_f^n are the beginning and end of the n -th particle track in the cell and $w(x, \mu)$ is the weight of the error particle in the MC simulation. As it is a pure absorber simulation, weight is attenuated exponentially, i.e., $w(x, \mu) \propto \exp(-\sigma_t |x/\mu|)$. Substitution of the exponential attenuation of the weight produces the result

$$\epsilon_{a,ij}^n = \frac{w(x_0, \mu)}{\sigma_t h_x h_\mu} (1 - e^{-\sigma_t s^n}) \quad (21)$$

where $w(x_0, \mu)$ is the particle weight at the start of the path and s^n is the length of the track. The contribution of a particle track to ϵ_x is given by

$$\epsilon_{x,ij}^n = \frac{w(x_0, \mu)}{h_x^2 h_\mu \sigma_t} \left[x_0 - x_f e^{-\sigma_t s^n} + \left(\frac{\mu}{\sigma_t} - x_i \right) (1 - e^{-\sigma_t s^n}) \right], \quad (22)$$

where x_0 and x_f are the beginning and ending x coordinates of the n -th path. The contribution to the first moment in μ is

$$\epsilon_{\mu,ij}^n = \frac{w(x_0, \mu)}{h_\mu^2 h_x \sigma_t} (\mu - \mu_j) (1 - e^{-\sigma_t s^n}) \quad (23)$$

where the particle x -direction cosine μ does not change along the path because it is a pure-absorber simulation. Finally, the moments of the error are simply the average contribution of all particles.

B. Adaptive Mesh Refinement

This section describes the adaptive refinement strategy for the ECMC algorithm. Detailed equations for performing projections and computing the residual source on the refined meshes can be found in [10]. At the end of the ECMC batch, refinement is performed in space-angle cells based on a jump indicator. The jump indicator is the magnitude of the different between solutions in adjacent cells, averaged over an edge. The maximum jump within a cell is used as the indicator for each cell. Based on this indicator, the 20% of cells with the largest jump are refined. The refinement of a cell is symmetric, with each space-angle cell divided into four equal-sized cells. The solution for \tilde{I}^{n+1} of the batch is projected onto the finer mesh for the next batch. At the end of the last HO solve in a time step, \tilde{I}^{n+1} is projected back onto the original, coarsest mesh and stored as \tilde{I}^n for the time step.