

# Gaussian Processes

STA5090Z: Advanced Topics in Regression

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## What is a Gaussian Process?

stochastic process which generates functions like this

$$f \sim \mathcal{GP}(m, k)$$

mean function  $m$

covariance function  $k$

... sets of correlated data points

## Example 1 (Rasmussen)

$$\{ \sim \mathcal{GP}(m, k)$$

$$m(x) = \frac{1}{4}x^2, \quad k(x, x') = \exp(-\frac{1}{2}(x - x')^2)$$

$x, x'$  two different  $x$ -values

vector  $\mathbf{f} \sim N(\mu, \Sigma)$

$$\mu_i = m(x_i), \quad \Sigma_{ij} = k(x_i, x_j)$$

# Example 1

```
library(mvtnorm)
set.seed(1)

x <- seq(-5, 5, length = 100)
d = abs(outer(x, x, "-")) # compute distance matrix,  $d_{ij} = |x_i - x_j|$ 

mx <- x^2 / 4
Sigma_SE = exp(-d^2 / 2) # squared exponential kernel

y = mvtnorm::rmvnorm(1, mean = mx, sigma = Sigma_SE)

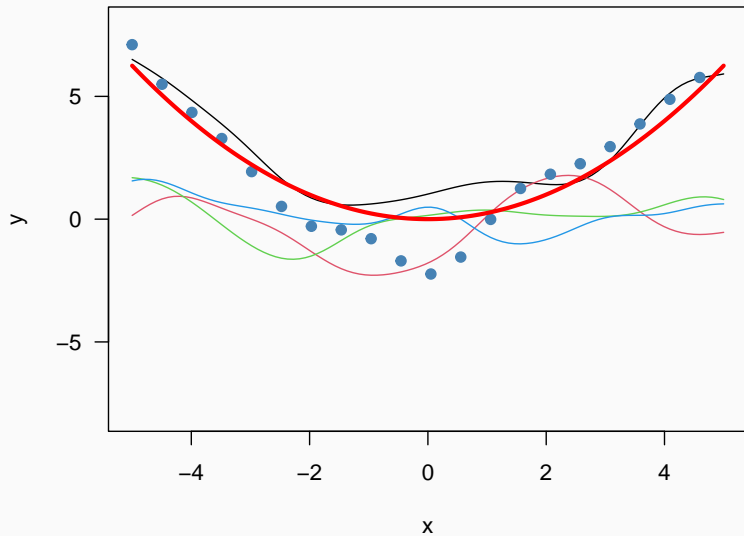
plot(x, y, type = "l", las = 1, ylim = c(-8, 8))

for (i in 1:3) {
  y = mvtnorm::rmvnorm(1, sigma = Sigma_SE)
  lines(x, y, col = i + 1)
}

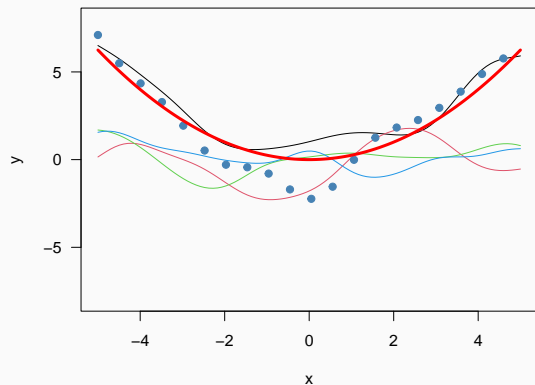
xsel <- seq(1, 100, by = 5)

y = mvtnorm::rmvnorm(1, mean = mx, sigma = Sigma_SE)
points(x[xsel], y[xsel], col = "steelblue", pch = 19)
lines(x, mx, col = "red", lwd = 3)
```

## Example 1



# Distribution



$$f(x) \sim N(m(x), k(x, x))$$

$$y(x) = f(x) + \epsilon, \quad \epsilon \sim N(0, \sigma_n^2)$$

$$f \sim GP(m, k), \quad y \sim GP(m, k + \sigma_n^2 \delta_i)$$

# $k(x, x')$

- \textcolor{blue}{Covariance function} = Kernel
- describes covariance between  $x$  and  $x'$

for example: **squared exponential**

$$k(x, x') = \exp\left(-\frac{1}{2}(x - x')^2\right)$$

more general form:

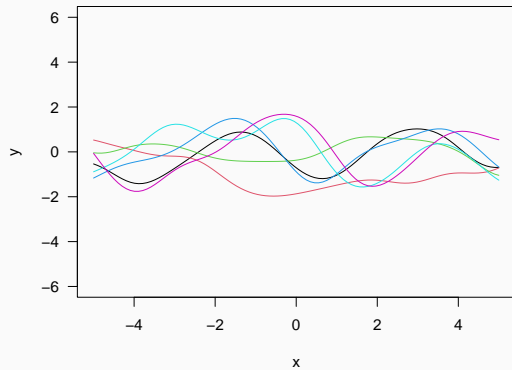
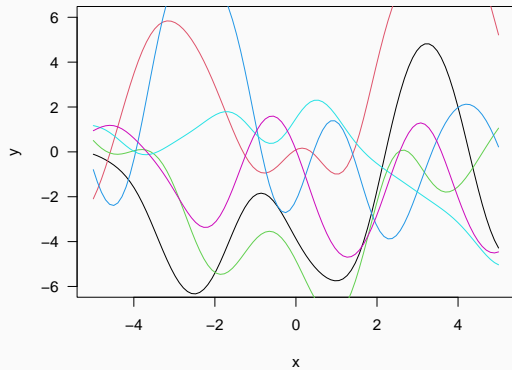
$$k(x, x') = \sigma_y^2 \exp\left(-\frac{(x - x')^2}{2\ell^2}\right) + \sigma_n^2 \delta_{ii'}$$

$\sigma_y = \sigma_f$  = marginal variability of  $f$  ( $d = 0$ )

$\ell$  = length scale (how fast correlation decays)  $\rho = \ell^2$

$\sigma_n$  = observation process noise

$\delta_{ii'}$  = Kronecker delta, = 1 iff  $i = i'$ , else 0

$\sigma_f = 1$  $\sigma_f = 3$ 

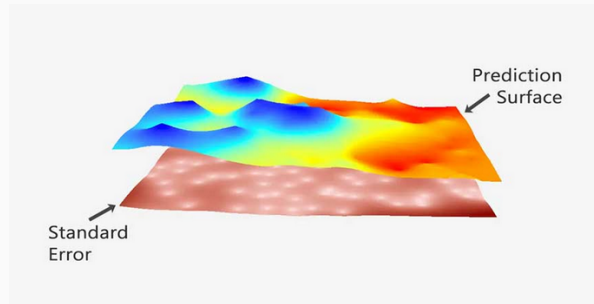
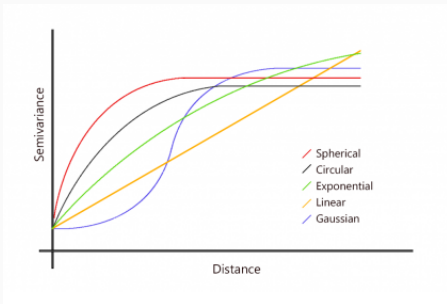


$$y_i = \beta_0 + \beta_1 x_i + e_i, \quad e_i \sim N(0, \sigma^2)$$

$$\mathbf{y} \sim MVN(\boldsymbol{\mu}, \sigma^2 \mathbf{I})$$

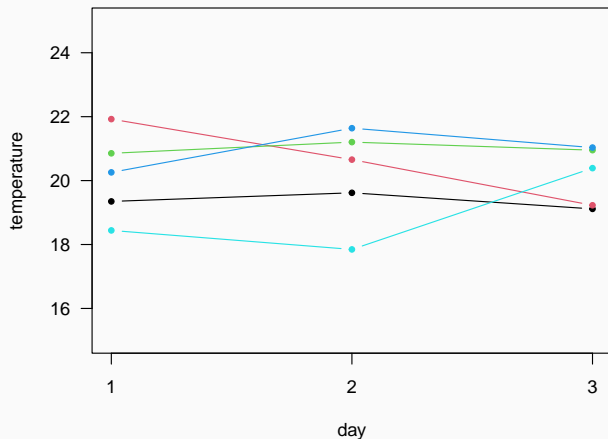
# Kriging

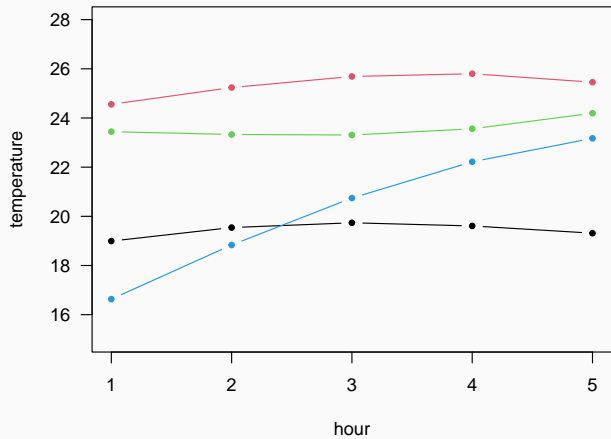
- two-dimensional Gaussian Process
- a random function where any  $k$  values on the function follow a MVN distribution



# Time Series

- Example: temperature reading correlated in time (temperature on day 1, 2, 3)





## Where would use

- autocorrelated error term in time series regression, longitudinal model
- spatial random effect = kriging
- nonlinear regression
- computer simulations – predict outcome at intermediate points

## Limitations

- very expensive (computationally): ( $O(N^3)$ )
- because of matrix inversion
- Cholesky decomposition of  $K$  matrix
- and some other tricks

## Why useful?

- uncertainty estimates for predictions
- many dimensions?
- can construct new covariance functions as products of components

## How are we going to use them?

- autocorrelated random effects / error terms  $y = X\beta + f(t) + e$
- nonlinear regression  $y = f(x) + e$ , or  $y = X\beta + f(z) + e$
- Stan (Bayesian)

<https://mc-stan.org/docs/stan-users-guide/gaussian-processes.html>



# Stan Covariance Functions

[https://mc-stan.org/docs/functions-reference/matrix\\_operations.html#gaussian-process-covariance-functions](https://mc-stan.org/docs/functions-reference/matrix_operations.html#gaussian-process-covariance-functions)

squared exponential = exponentiated quadratic kernel

$$k(\mathbf{x}_i, \mathbf{x}_j) = \sigma^2 \exp \left( -\frac{|\mathbf{x}_i - \mathbf{x}_j|^2}{2l^2} \right)$$

```
matrix gp_exp_quad_cov(array[] real x, real sigma, real length_scale)
```

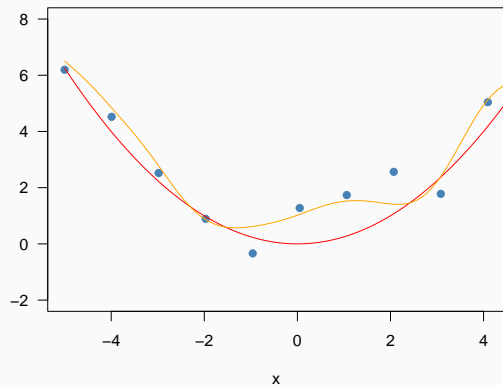
```
matrix[N, N] cov =    cov_exp_quad(x, alpha, rho)
                      + diag_matrix(rep_vector(1e-10, N));
```

add jitter to diagonal elements to stabilize numeral linear algebra

## What are the parameters that we need to estimate?

- length scale  $l$
- noise in observation process  $\sigma_n$
- marginal function variance  $\sigma_f$
- Bayesian, priors for parameters

## Example 1: Rasmussen



$$m(x) = \frac{1}{4}x^2$$

$$k(x, x') = \exp\left(-\frac{1}{2}(x - x')^2\right)$$

$$\sigma_n = 0.5$$

## Fit model (Hamiltonian Monte Carlo)

```
library(cmdstanr)

x2 = x[-xsel]      # test set
data_list <- list(y_obs = y[xsel], x_obs = x[xsel],
                  N_obs = length(xsel),
                  x2 = x2, N2 = length(x2))

m1 <- cmdstan_model(stan_file = "./stan/gp1.stan")

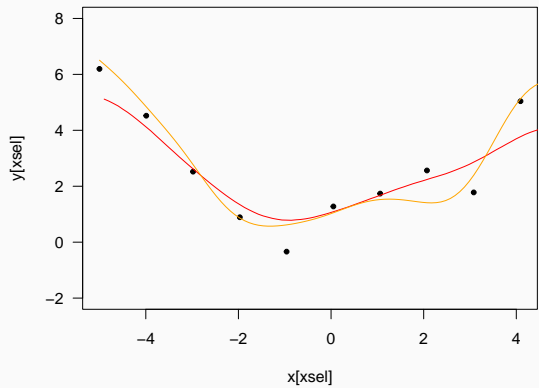
m1.fit <- m1$sample(
  data = data_list,
  seed = 123,
  chains = 4,
  parallel_chains = 2,
```

```
m1.fit$summary()
```

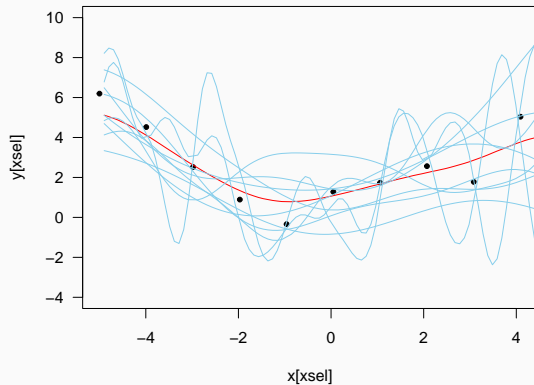
```
# A tibble: 95 x 10
```

	variable	mean	median	sd	mad	q5	q95	rhat	ess_bulk	ess_tail
	<chr>	<dbl>	<dbl>	<dbl>	<dbl>	<dbl>	<dbl>	<dbl>	<dbl>	<dbl>
1	lp__	-16.8	-16.4	1.49	1.19	-19.7	-15.2	1.00	1042.	878.
2	rho	0.820	0.760	0.364	0.297	0.340	1.48	1.00	1649.	963.
3	alpha	2.25	2.25	0.583	0.559	1.29	3.20	1.00	1902.	1102.
4	sigma	1.16	1.08	0.490	0.418	0.522	2.11	1.00	1582.	1084.
5	f[1]	5.12	5.26	1.81	1.68	1.98	7.77	1.00	2987.	3204.
6	f[2]	5.04	5.18	1.77	1.65	1.94	7.62	1.00	2904.	2980.
7	f[3]	4.96	5.11	1.75	1.59	1.93	7.49	1.00	2884.	2957.
8	f[4]	4.87	5.00	1.70	1.54	1.90	7.39	1.00	3021.	3155.
9	f[5]	4.75	4.87	1.66	1.51	1.88	7.24	1.00	2824.	3251.
10	f[6]	4.64	4.75	1.63	1.48	1.87	7.08	1.00	2952.	3411.

```
# i 85 more rows
```



## Example 1: Posterior Sample



## Theory: Predictive Distribution

$$\begin{bmatrix} f \\ f_* \end{bmatrix} \sim N \left( \begin{bmatrix} \mu \\ \mu_* \end{bmatrix}, \begin{bmatrix} \Sigma & \Sigma_* \\ \Sigma_*^T & \Sigma_{**} \end{bmatrix} \right)$$

$\Sigma_*$ :  $n \times n_*$  matrix

$$f_* | X_*, X, f \sim N \left( \mu_* + \Sigma_*^T \Sigma^{-1} (f - \mu), \Sigma_{**} - \Sigma_*^T \Sigma^{-1} \Sigma_* \right)$$

$$\begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \sim N \left( \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}, \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix} \right) \quad \text{then } X_1 | X_2 \sim N(\mu_1 + \Sigma_{12} \Sigma_{22}^{-1} (x_2 - \mu_2), \Sigma_{11} - \Sigma_{12} \Sigma_{22}^{-1} \Sigma_{21}).$$



# Marginal Likelihood

$$\ell = \log p(y|x, \theta) = -\frac{1}{2} \log |\Sigma| - \frac{1}{2} (y - \mu)^T \Sigma^{-1} (y - \mu) - \frac{n}{2} \log(2\pi)$$

(log) marginal likelihood

$$p(y|X) = \int p(y|X, w) p(w) dw$$

- maximise to estimate parameters  $w$

## References

- Rasmussen & Williams. Gaussian Processes for Machine Learning. MIT. <https://direct.mit.edu/books/book/2320/Gaussian-Processes-for-Machine-Learning>
- Rasmussen 2006. Gaussian Processes in Machine Learning.
- Roberts et al. Gaussian processes for time-series modelling. Philosophical Transactions of the Royal Society
- [https://betanalpha.github.io/assets/case\\_studies/gaussian\\_processes.html](https://betanalpha.github.io/assets/case_studies/gaussian_processes.html)
- Ebden 2008. Gaussian Processes for Regression: A Quick Introduction.
- Neal, R.M. (1997) 'Monte Carlo Implementation of Gaussian Process Models for Bayesian Regression and Classification'. arXiv. <https://doi.org/10.48550/arXiv.physics/9701026>.
- Neal, R.M. (1998) 'Regression and Classification Using Gaussian Process Priors', in 26 J.M. Bernardo et al. (eds) Bayesian Statistics 6. Oxford University Press Oxford.

## Example 1: Simulated GP

<https://michael-franke.github.io/Bayesian-Regression/practice-sheets/10c-Gaussian-processes.html>

### Conditional Predict

$$f_* | X_*, X, f \sim N(K(X_*, X)K(X, X)^{-1}f, K(X_*, X_*) - K(X_*, X)K(X, X)^{-1}K(X, X_*))$$

### Marginal Likelihood

<https://mc-stan.org/cmdstanr/reference/model-method-optimize.html>

### HMC

## Example 2: mcycle