

	Model 1	Model 2	Model 3	Model 4	Model 5	Model 6
Intercept	-3.10 ** (-2.76, p = 0.01)	-2.72 ** (-2.58, p = 0.01)	-2.19 * (-2.28, p = 0.02)	-2.13 * (-2.05, p = 0.04)	-2.76 ** (-2.65, p = 0.01)	-1.31, p = 0.18
Partial	1.13 (1.67, p = 0.09)					(-0.62, p = 0.53)
Plot	1.36 * (2.11, p = 0.03)					(-0.58, p = 0.58)
Partial		1.31 ** (2.94, p = 0.00)			0.81 (1.63, p = 0.10)	
Control			0.86 *** (4.22, p = 0.00)		0.20 (0.75, p = 0.45)	
State				0.57 * (2.24, p = 0.03)		(2.39, p = 0.02)
Control:site					0.86 *** (3.31, p = 0.00)	
State:plotPartial						(-2.43, p = 0.02)
State:plotTotal						(-1.83, p = 0.07)
	366	366	366	366	366	
Control(D)	13	13	13	13	13	
Control(h)	12	12	12	12	12	
Control(year)	5	5	5	5	5	
	899.63	895.38	884.76	897.81	875.83	
	926.94	918.80	908.18	921.23	907.06	
Control(l)	0.03	0.04	0.07	0.03	0.09	
Control(l)	0.78	0.78	0.77	0.78	0.79	

Continuous predictors are mean-centered and scaled by 1 standard deviation. *** p < 0.001; ** p < 0.01; * p < 0.05.