01 -- Tue Oct 3

ECE 447: Control Systems

Prof Burden TA Tim

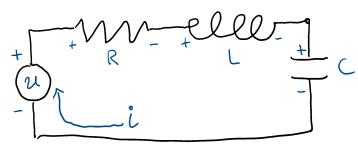
this week: D HWO assigned -> due Fri Oct 6

1 week 1 lecture material

tutorial: apply week 1 lectures to RLC circuit

u-voltage surce L-inductore
R-resistance C-capacitone

(a) mathematical mode (



Kirchoffic voltage law: \(\subseteq Ve = O = - Vu + VR + VL + Vc

ex = "lumped element"

Lumped

 $V_u = u$ $V_L = L \frac{di}{dt} - \text{change in current } \frac{dc}{dt}$ $V_R = iR - \text{current } i$ $V_L = \frac{1}{C}G - \text{charge } G$ $\frac{dG}{dt} = i$

(b) differential equation - how physical quantities change in time in

(b) differential equation - how physical quantities change in time in relation to each other
$$v_R + v_L + v_c = iR + L \frac{di}{dt} + \frac{1}{C}g = u$$

$$= \frac{dg}{dt}R + L \frac{d^2g}{dt^2} + \frac{1}{C}g = u$$

$$= \frac{d}{dt}x = x$$

$$L\ddot{g} + R\ddot{g} + \frac{1}{C}g = u$$
I time domain" model

(c) transfer function - how input signal transforms to output signal o recall that $\mathcal{F}(\dot{x}) = s \cdot \mathcal{F}(x)$

$$(Ls^{2} + Rs + \frac{1}{C})\hat{g} = \hat{u} \iff \hat{g} = \left(\frac{1}{Ls^{2} + Rs + \frac{1}{C}}\right)\hat{u}$$
"frequency domain"
$$= (G(s)\hat{u})$$
mode
"transfer function"

(d) block diagram

(e) feedback control

udisturbonce"



* our job: design C so that feedback interconnection/ behaves the way we want

Q: what about using up as output from circuit?

A: I'm bad at circuit analysis, so I'll think of it from a systems perspective:

$$Q = \left(\frac{1}{Ls^2 + Rs + 1/c}\right)u \qquad V_R = iR \quad i = \frac{dg}{dt} \sim s \cdot g$$

$$= G_{ig}(s) \cdot g$$

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$$\frac{\hat{V}_R}{\hat{u}} = R \cdot Gig \cdot Ggu \cdot u = \left(\frac{Rs}{Ls^2 + Rs + 1/c}\right) \cdot u$$