

goal: characterize stability of LTI system using eigenvalues

ref: Hespanha Ch 8.3

• consider LTI DE  $\dot{x}/x^+ = Ax$

set of eigenvalues of  $A$   
 $\{s \in \mathbb{C} \mid \det(sI - A) = 0\}$   
 $\uparrow$

facts: (LTI DE) is:

0°. unstable if any eigenvalue of  $A$ :  $\exists \lambda \in \text{spec } A$

(CT) has positive real part (DT) has magnitude larger than 1  
 $\text{Re } \lambda > 0$   $|\lambda| > 1$

1°. marginally stable if all eigenvalues of  $A$ :  $\forall \lambda \in \text{spec } A$

(CT) have non-positive real part (DT) have magnitudes no larger than 1  
 $\text{Re } \lambda \leq 0$   $|\lambda| \leq 1$

$\text{Re } \lambda \leq 0$ 
than 1  $|\lambda| \leq 1$   
 $\rightarrow$  \* actually need additional condition for repeated eigenvalues  
 (need concept of Jordan normal form)

2: exponentially (hence asymptotically) stable if  
 all eigenvalues of  $A$ :  $\forall \lambda \in \text{spec } A$

(CT) have negative real part  $\text{Re } \lambda < 0$ 
(DT) have magnitude smaller than 1  $|\lambda| < 1$

\* why should you believe these "facts"?

$\rightarrow$  if  $v \neq 0$ ,  $\lambda \in \mathbb{C}$  are s.t.  $Av = \lambda v$ , i.e.  $\lambda$  is eigenval of  $A$   
 w/ eigenvector  $v$

show that  $v$  is eigenvector of  $e^{At}$   
 (what is the eigenvalue?)

\*  $Av = \lambda v \Rightarrow A^k v = \lambda^k v$

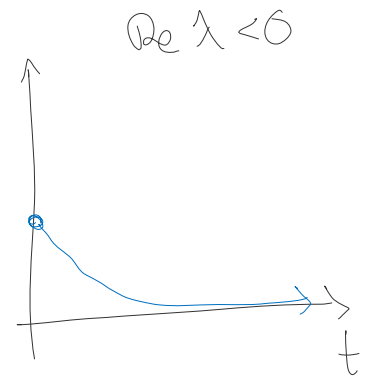
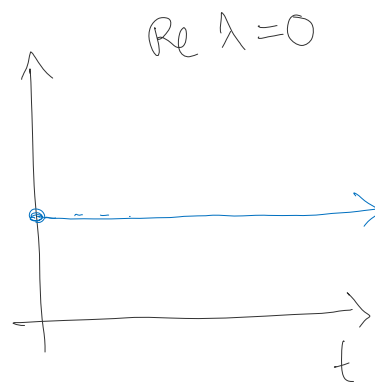
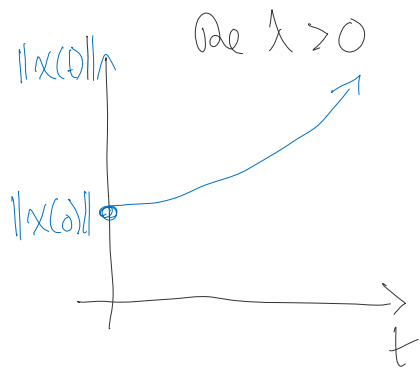
$$\Rightarrow e^{At} v = \left[ \sum_{k=0}^{\infty} \frac{t^k}{k!} A^k \right] v = \sum_{k=0}^{\infty} \left[ \frac{t^k}{k!} A^k v \right] = \left[ \sum_{k=0}^{\infty} \frac{(\lambda t)^k}{k!} \right] v = e^{\lambda t} v$$

so  $e^{\lambda t}$  is eigenval of  $e^{At}$  w/ eigenvector  $v$

• so given  $\underbrace{Av = \lambda v}_{v \neq 0}$  we know  $x(0) = v \Rightarrow x(t) = e^{At} x(0)$   
 $= e^{\lambda t} x(0)$

$\rightarrow$  it's clear that  $\lambda \in \mathbb{C}$ , in particular  $\text{Re } \lambda$ .

↳ it's clear that  $\lambda \in \mathbb{C}$ , in particular  $\operatorname{Re} \lambda$ , determines stability of  $x(t)$ :



\* WARNING! these eigenvalue tests for stability do not apply to LTV systems