

## nonlinear programming

goal: derive necessary & sufficient conditions for local optimality in unconstrained nonlinear programs (NLP)

refs: Stengel 1994 pg 29-41

Lewis, Vrabie, Syrmos 2012 ch 1

• we want to minimize a given objective function  $J: \mathbb{R}^m \rightarrow \mathbb{R}$   
:  $u \mapsto J(u)$

i.e. find  $u^* \in \mathbb{R}^m$  s.t.  $\forall u \neq u^*: J(u^*) < J(u)$

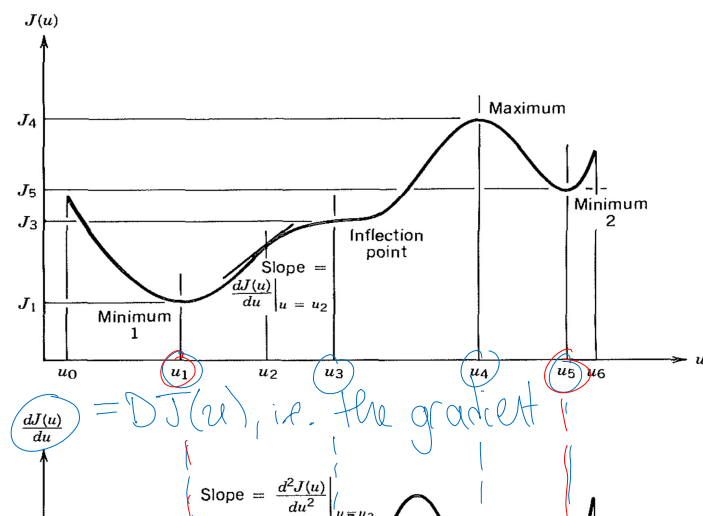
— write  $\min_{u \in \mathbb{R}^m} J(u) \leftarrow$  "nonlinear program" (NLP)

idea: starting from  $u \in \mathbb{R}^m$  where  $DJ(u) \neq 0$  then  
 $u^+ = u - \alpha \cdot DJ(u)$  yields  $J(u^+) < J(u)$  for all  $\alpha > 0$  small

→ so we can use gradients to:

1°. detect that we haven't found the minimum

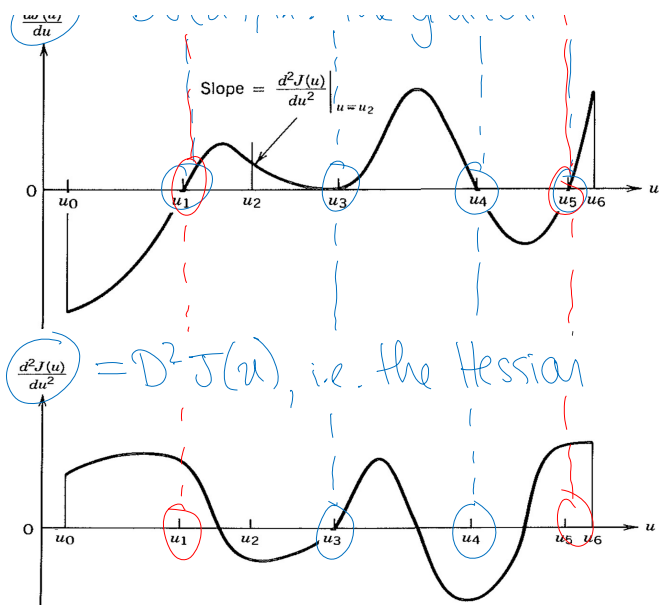
2°. update / iterate to get closer to minimum



def:  $u_0 \in \mathbb{R}^m$  is stationary if  $DJ(u_0) = 0$

ex:  $u_1, u_3, u_4, u_5$

def:  $u^* \in \mathbb{R}^m$  is a local minimum if  
there is an open neighborhood  $\mathcal{U} \subset \mathbb{R}^m$   
s.t.  $\forall u \in \mathcal{U}: J(u^*) \leq J(u)$



s.t.  $\forall u \in \mathcal{U}: J(u^*) \leq J(u)$   
 i.e. a "ball":  $\{u: \|u - u^*\| < r\}$   
 $u^*$  is a strict local min if  $\bigcirc$  strict for  $u \neq u^*$   
ex:  $u_1, u_5$

thm: (sufficient conditions for optimality)

a stationary point  $u_0 \in \mathbb{R}^m$  is a strict local min if  $\overbrace{D^2 J(u_0) > 0}^{\in \mathbb{R}^{m \times m}}$   
 $\Rightarrow DJ(u_0) = 0 \in \mathbb{R}^{1 \times m}$   
 i.e. positive-definite

aside:  $D^2 J(u_0)$  is symmetric if  $J$  is twice continuously differentiable

because  $D^2 J(u_0) = \left[ \frac{\partial}{\partial u_i} \frac{\partial}{\partial u_j} J \Big|_{u=u_0} \right]_{i,j} = \left[ \frac{\partial}{\partial u_j} \frac{\partial}{\partial u_i} J \Big|_{u=u_0} \right]_{i,j}$   
 $\Rightarrow D^2 J(u_0)^T = D^2 J(u_0)$

aside: if  $S = S^T$  then all eigenvalues of  $S$  are real  
 so  $S > 0 \Leftrightarrow$  all eigenvalues of  $S$  are positive

$\rightarrow$  determine  $J$  s.t.  $u_0 = 0$  is a local min but  $D^2 J(u_0) \not> 0$

—  $J(u) = 0$  —  $J(u) = u^4$  —  $J(u) = |u| \leftarrow$  not differentiable

thm: (necessary conditions for optimality):

if  $u_0 \in \mathbb{R}^m$  is a local min, then:

— if  $J$  is continuously differentiable ( $J \in C^1$ ) then  $DJ(u_0) = 0$

- if  $J$  is continuously differentiable ( $J \in C^1$ ) then  $DJ(u_0) = 0$
- if  $J$  is twice continuously diffable ( $J \in C^2$ ) then  $D^2J(u_0) \geq 0$

→ determine necessary conditions on  $b^T \in \mathbb{R}^{1 \times m}$ ,  $C^T = C$   
for  $u_0 \in \mathbb{R}^m$  to be local min of

$$J(u) = J(u_0) + b^T(u - u_0) + \frac{1}{2}(u - u_0)^T C(u - u_0)$$

- $DJ(u) = b^T + (u - u_0)^T C$  so necessary that  $DJ(u_0) = \boxed{b^T = 0}$
- $D^2J(u) = C$ , so necessary  $DJ(u_0) = \boxed{C \geq 0}$

→ if  $u_0$  is a strict local min, solve for  $u_0$

- if  $C > 0$  then  $\exists v_0 \neq 0$  s.t.  $Cv_0 = 0$

so  $J(u) = J(u_0)$  for all  $u - u_0 = \alpha \cdot v_0$ ,  $\alpha \in \mathbb{R}$

- conclude  $C > 0$  for  $u_0$  to be a strict local min

- verify that  $u_0 = \underbrace{u - (D^2J(u))^{-1} DJ(u)^T}_{\text{Newton-Raphson iteration}}$