

AA/ECE/ME 548 Linear Multivariable Control Sp22 Prof Borden

- today:
- ☑ course logistics, Canvas, etc
 - ☑ HW0 self-assessment - due next Monday
 - ☑ HW1 - due this Friday
 - ☐ week 2 lectures
 - ☐ questions / office hours

todo: ☐ post notes

consider $\dot{x} = Ax$, $A \in \mathbb{R}^{n \times n}$

fact: if A has n distinct eigenvalues $\lambda_1, \dots, \lambda_n \in \mathbb{C}$
with corresponding eigenvectors $v_1, \dots, v_n \in \mathbb{C}^n$

then $D = VAV^{-1} = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} \Rightarrow A = V^{-1}DV$

where $V = [v_1, \dots, v_n]$

so $e^{At} = e^{V^{-1}DVt} = V^{-1}e^{Dt}V$

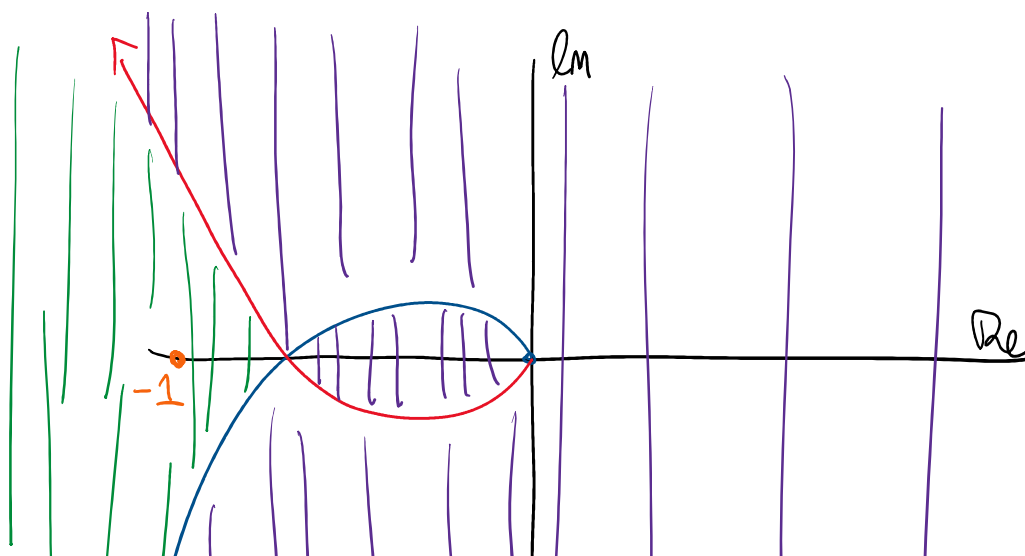
} A is diagonalizable

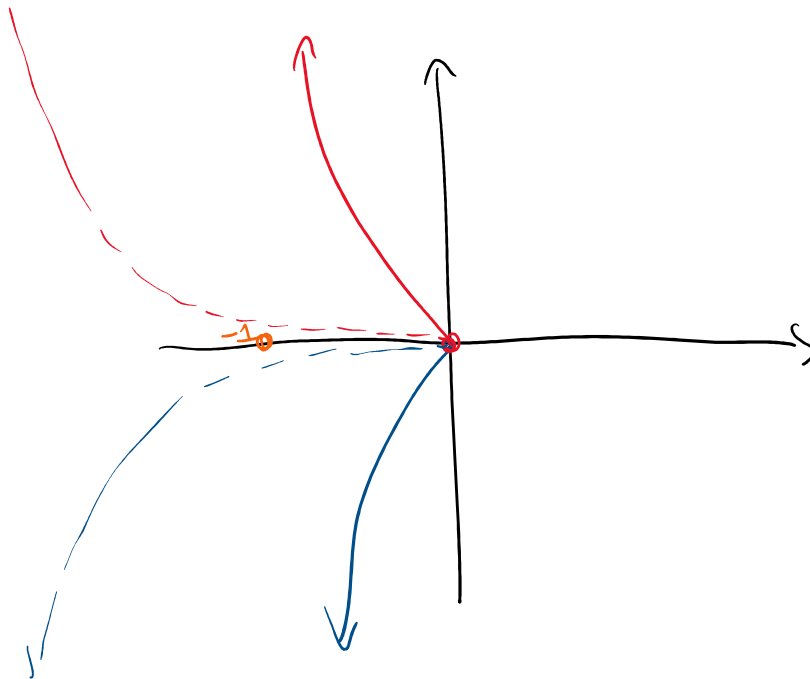
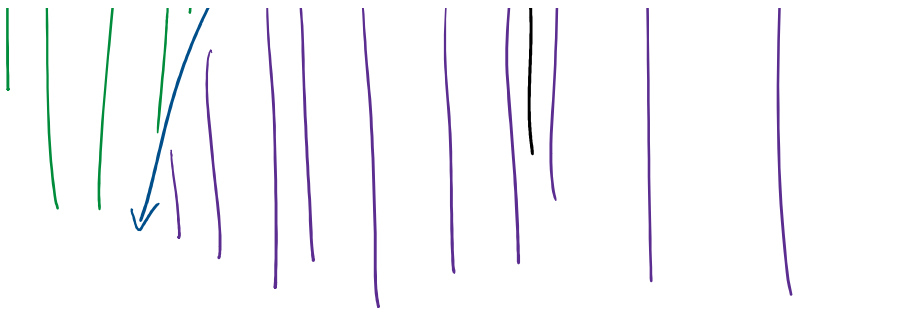
$$\text{so } e^{At} = e^{V^{-1}DVt} = V \underset{\parallel}{e^{Dt}} V$$

$$\begin{bmatrix} e^{\lambda_1 t} & & 0 \\ & \ddots & \\ 0 & & e^{\lambda_n t} \end{bmatrix}$$

more generally, for any A there exists T^{-1} s.t.

$$J = T A T^{-1} = \begin{bmatrix} \Lambda_1 & & 0 \\ & \ddots & \\ 0 & & \Lambda_n \end{bmatrix}, \quad \Lambda_i = \begin{bmatrix} \lambda_i & 1 & & 0 \\ & \ddots & \ddots & \\ 0 & & \ddots & 1 \\ & & & \lambda_i \end{bmatrix}$$





$$\xi = x_i$$

$$\phi = \text{phi}$$

$$D_2 \phi(s+1, \xi) = D_\xi [f(\phi(s, \xi))]$$

$$= Df(\phi(s, \xi)) \cdot D_2 \phi(s, \xi)$$

$$\phi: \mathbb{R} \times \mathbb{R}^d \rightarrow \mathbb{R}^d$$

$$:(t, x_0) \mapsto x_t$$

$$f: \mathbb{R}^d \rightarrow \mathbb{R}^d$$

$$: x \mapsto x^+$$

$$\phi(0, x) \quad \phi(1, x) \quad \phi(2, x)$$

$$\begin{matrix} \parallel & \parallel & \parallel \\ x \mapsto & f(x) \mapsto & f(f(x)) \mapsto \end{matrix}$$

$$\leadsto Df(x): \mathbb{R}^d \rightarrow \mathbb{R}^d \text{ linear}$$

$$\in \mathbb{R}^{d \times d}$$

$$\phi(s+1, x) = f(\phi(s, x))$$

$$D_x [\phi(s+1, x)] = D_x [f(\phi(s, x))]$$

$$\begin{aligned}
 D_x[\phi(s+1, x)] &= D_x[f(\phi(s, x))] \\
 &= Df \cdot D_2 \phi \\
 &= Df(\phi(s, x)) \cdot D_2 \phi(s, x)
 \end{aligned}$$