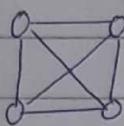


Tenew Baum

Whenever 2 or more autonomous systems are connected together - network

how the systems are connected - topology

ex: Mesh Topology



high reliability

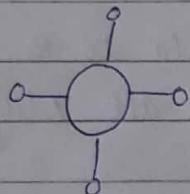
in case of failure of any link but more cost

Bus Topology

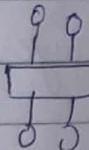


all systems are connected using single link

Ring topology



Star topology



entire communication depends on central switch
if it fails, the entire system fails.

Methods to classify network

- wired or wireless network
- Infrastructure or
- Based on channel - like bluetooth
- Based on various parameters

Here we discuss based on channel

2 Models to define network

- ISO-OSI model
- TCP-IP model

In transferring data, we perform several operations of similar type in single layer known as layered model.
→ open system interaction

ISO-OSI layered model has 7 layers

1. Application layer

2. Presentation

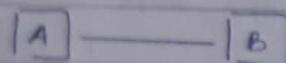
3. Session

4. Transport

5. Network

6. Data ~~link~~ link

7. Physical layer - Digital & analog communication



A has to transmit data to B.

Both machines have all 7 layers.

→ Lower layer is responsible to provide service to its upper layer. User connected to application layer.

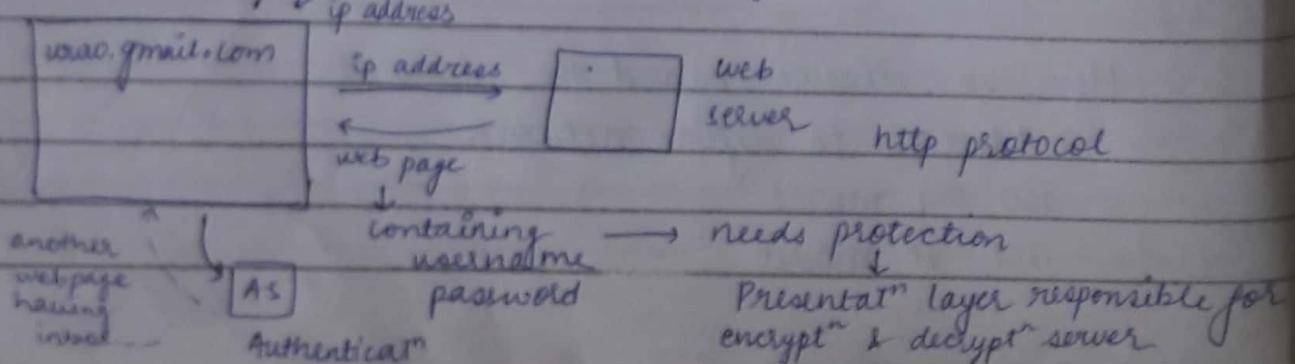
A has to send mail to B

abc@gmail.com

xyz@gmail.com

A first switches on computer and press (types) www.gmail.com
calling applicatⁿ

A table contains data which contains domain & ip address
we have a server (centralised entity)



Presentation layer is also responsible for data conversion so that unicode is obtained.

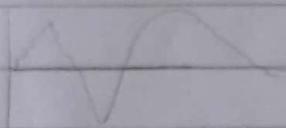
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Conversion

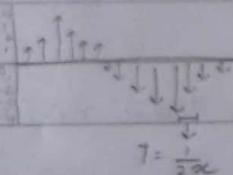
Analog to Digital

analog \rightarrow sample \rightarrow quantizatⁿ \rightarrow binarification

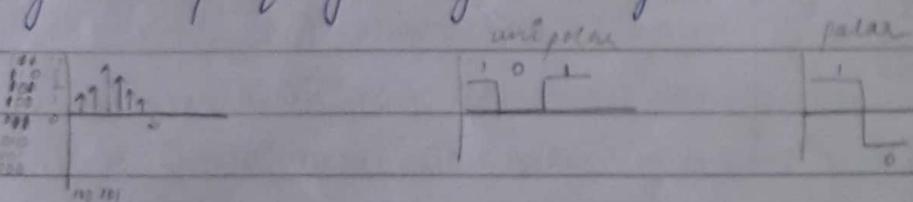
sampling : measuring the amplitude at equal interval of time



convert this signal from time domain to frequency domain using fourier series



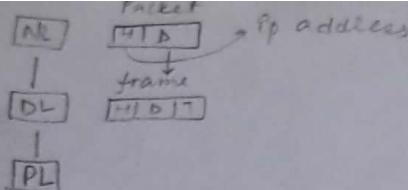
quantization - it is a method of assigning integral values in a specific range to sampled instances. According to to ensure the accurate reproduction of original signal using pulse modulation the sampling rate must be at least twice the highest freq of original signal.



Digital to Analog

If you want to differentiate b/w 1 and 0 using phase than it is PSK

using amplitude - ASK
frequency - FSK



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for analog to analog : AM, PM, FM
unipolar, polar

} 1st assignment

Data link layer (logic link control)

$$\begin{aligned} F \text{ bits} &= H + \text{Data} + T \\ &= H + \text{Data} \end{aligned}$$

3 types of functionality

- flow control
-
-

Flow control

If the no. of intermediate router is K , then no. of link is $K+1$



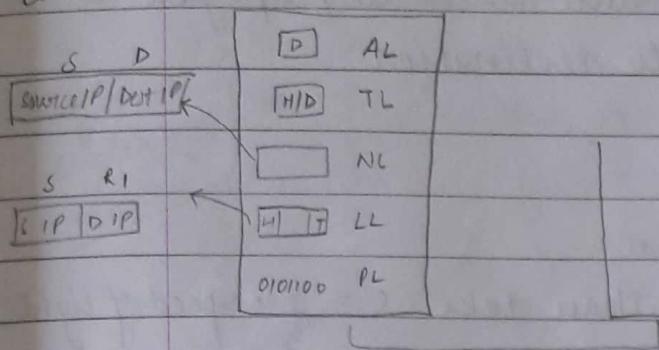
S

case 1

<input checked="" type="checkbox"/>	AL	
<input checked="" type="checkbox"/>	TL	
<input checked="" type="checkbox"/>	NL	
<input checked="" type="checkbox"/>	LL	
<input checked="" type="checkbox"/>	PL	

S uses all the layers

case 2



R uses only 3 layers

The communication b/w S and RI is point to point
S and D is end to end.

S → D 4 times Data link layer is

Flow control (stop and wait protocol)

~~fast~~ flow control means how much amount of data that can be transmitted by the ~~transmitter~~ transmitter without receiving any acknowledgement. Data is transferred in the form of frame which contains overhead and data. $H \boxed{\text{Data IT}}$

$S \quad D$ $F \text{ bits} = H + \text{Data}$

at time, $t=0$ S starts transmission

I - propagation delay

$C \text{ bit/sec}$ - channel capacity

eg $C = 100 \text{ mbps}$, it means you can transmit 100×10^6 bits per sec

$$\text{time taken to transmit one bit} = \frac{1}{C} = \frac{1}{100} \mu\text{sec}$$

$$\text{time taken to transmit } f \text{ bits or frame} = \frac{f}{C}$$

all the communication's are serial mode

$$\text{propagation delay} = \left(\frac{2}{3} \times \text{speed of light}\right)^{-1} \times \text{distance}$$

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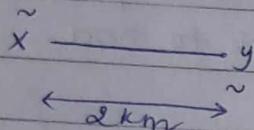
Propagation delay is the time taken to propagate a signal from source to destination

$$I = \frac{\text{distance}}{\text{speed of signal}}$$

If speed is not given than take $s = \frac{2}{3} \times \text{speed of light}$

B - bit length of line

ex: x is 5 bit away from y



$$c = 1 \times 10^6 \text{ bits/sec}$$

Time taken to transmit 1 bit = $1 \mu\text{sec}$

$$\text{Speed of signal} = 2 \times 10^8 \text{ m/sec}$$

Distance covered by signal in $1 \mu\text{sec}$ = 200 m

or
1 bit

$$\text{No. of bits b/w x and y} = \frac{2 \times 10^3}{200}$$

$$\frac{d \times c}{s}$$

$$= 10^3$$

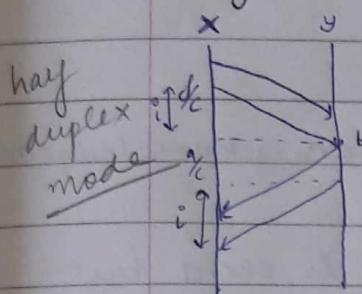
$$I \times c$$

$$B = c * I$$

Flow control means how much amount of data that can be transmitted by the transmitter without receiving any acknowledgement.

- Stop and wait \rightarrow one frame
- Sliding window \rightarrow more than one frame

Performance of stop and wait protocol without error



at time $t=0$, X starts transmission

" $t = \frac{1}{c}$, X transmits First bit

" $t = \frac{2}{c}$, " second bit

" $t = \frac{f}{c}$, " last bit

" $t = \frac{f+i}{c}$, Y receives last bit of data frame

tp is the time taken to process the frame and tp is negligible

at time $t = \frac{f}{c} + i + \frac{1}{c}$, Y transmit first bit of ACK

" $t = \frac{f}{c} + i + \frac{A}{c}$, " last bit "

" $t = \frac{f}{c} + i + \frac{A}{c} + \frac{1}{c}$, X receives last bit of ACK

in terms of bits

$$\begin{aligned} \text{efficiency of } X &= \frac{f/c}{\frac{f}{c} + 2i + \frac{A}{c}} = \frac{F}{F + 2CI + A} \\ \text{in terms of time} &= \frac{1}{1 + \frac{2CI + A}{F}} \end{aligned}$$

larger the waiting time, lesser the efficiency

If we are considering header also then

$$\begin{aligned} \eta &= \frac{D/c}{\frac{f}{c} + 2I + \frac{A}{c}} = \frac{D}{F + 2CI + A} \\ &= \left(\frac{D}{D+H} \right) \left(\frac{1}{1 + \frac{2CI+A}{F}} \right) \\ &\quad \downarrow \text{header} \qquad \downarrow \text{waiting time} \end{aligned}$$

Loss of efficiency is bcz of header and waiting time.

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expected.

$$N = 8 + 1$$

no frame or for the
1st frame 1 round
trip for 8 bits
 $N = \frac{1+9}{2} = 5$

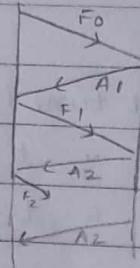
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Performance of stop and wait protocol with error

3 mechanisms of acknowledgement

- ACK - whenever you get a frame send an acknowledgement otherwise do nothing
- NACK - when you get a frame no ack. is send but when frame is lost then ack is send. It is used when system is reliable
- - when you get a frame, you send what you are expecting next.



- Retransmission happens bcz of the following 3 reason-
1. frame is lost so no acknowledgement is received.
 2. frame is send but acknowledgement is lost.
 3. acknowledgement is received after $F_c + 2I + A_c$

Let us assume that P_0 is the prob of data frame being lost.

P_1 is the prob. of ack. frame being lost.

$(1 - P_1)$ is the prob of getting the ack. frame.

$$\text{prob of success } s = (1 - P_0)(1 - P_1)$$

$$\text{"failure } l = 1 - s$$



$$\eta = \frac{D_c}{C}$$

$$\left(\frac{F_c + 2I + A_c}{C}\right) + \left(\frac{F_c + 2I + A_c}{C}\right)$$

$$\eta = \frac{D/C}{(F/C + 2I/C + A/C)} * \frac{1}{N}$$

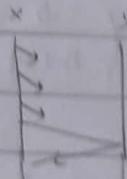
where N is the expected no. of retransmission attempts

$$N = \sum_{k=1}^{\infty} k P_k$$

where P_k is the prob. that exactly k attempts are needed for successfully transmitting a frame.

$$P_1 = L(L_1 - L)$$

$$P_k = L^{k-1} (1-L)$$



$$N = \sum_{k=1}^{\infty} k L^{k-1} (1-L) = (1-L) \sum_{k=1}^{\infty} k L^k$$

$$N = (1-L) [1 \cdot L^0 + 2 \cdot L^1 + 3 \cdot L^2 + \dots + \infty] \quad \text{--- (1)}$$

$$NL = (1-L) [1 \cdot L^1 + 2 \cdot L^2 + 3 \cdot L^3 + \dots + \infty] \quad \text{--- (2)}$$

$$(1) - (2)$$

$$N - NL = (1-L) [1 \cdot L^0 + 1 \cdot L^1 + L^2 + \dots + \infty]$$

$$(1-L)N = (1-L) \frac{1}{1-L}$$

$$N = \frac{1}{1-L} = \frac{1}{S}$$

$$\eta = \frac{D/C}{F/C + 2I/C + A/C} * \frac{1}{N} \nearrow R+1$$

$$\eta = \left(\frac{D}{D+H} \right) * \frac{1}{1 + \frac{2CI+A}{F}} * \left(\frac{1}{1-L} \right)^{-1}$$

$$\eta = \left(\frac{D}{D+H} \right) * \left(\frac{1}{1 + \frac{2CI+A}{F}} \right) * (1-P_0)(1-P_1)$$

Bit error rate

let E be the bit lost rate

$$\begin{array}{ccc} x & & y \\ \bullet & \xrightarrow{\quad} & \circ (1-E) \\ \circ\circ & \xrightarrow{\quad} & \circ\circ (1-E)(1-E) \end{array}$$

$$(1-p_0) = (1-E)^F$$

$$(1-p_1) = (1-E)^A$$

$$\eta = \left(\frac{D}{D+H} \right) * \left(\frac{1}{1 + \frac{2(I+A)}{F}} \right) * (1-E)^F (1-E)^A$$

DT bit error rate ↑
D ↓ H ↑

diff. both side with respect to D

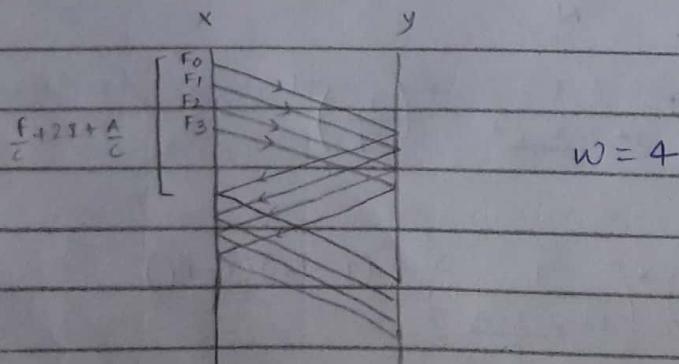
$$\frac{d\eta}{dD} = 0$$

$$D = \sqrt{\frac{H+C T}{E}} \quad \text{where } T = \frac{2I+A}{C}$$

$$F_{opt} = D_{opt} + H.$$

Sliding Window Protocol

- to minimise the waiting time
- more than one frame is send.
- full duplex mode of communication.



$$\frac{(D+H) - D(1)}{(D+H)^2} \left(\frac{1}{1 + \frac{2(I+A)}{D+H}} \right) * (1-E)^{H+D} (1-F)^A$$

$$+ \left(\frac{D}{D+H} \right) \frac{2(I+A)}{(D+H)^2} \frac{(1-E)^{H+D} (1-F)^A}{F}$$

$$+ \left(\frac{D}{D+H} \right) \left(\frac{1}{1 + \frac{2(I+A)}{D+H}} \right) (1-E)^{H+D} (1-F)^A$$

$$\eta = \left(\frac{D}{D+H} \right) * \left(\frac{W}{1 + \frac{2(I+A)}{F}} \right) * (1-E)^{H+D} (1-F)^A$$

waiting time = 0

$$\text{when } W \cdot \frac{f}{c} \geq \frac{f}{c} + 2I + \frac{A}{c}$$

$$W \geq 1 + \frac{2(I+A)}{F}$$

when W is large

$$\eta = \left(\frac{D}{D+H} \right) (1-P_0)(1-P_1)$$

$$\text{when } W \cdot \frac{f}{c} < \frac{f}{c} + 2I + \frac{A}{c}$$

then waiting time > 0

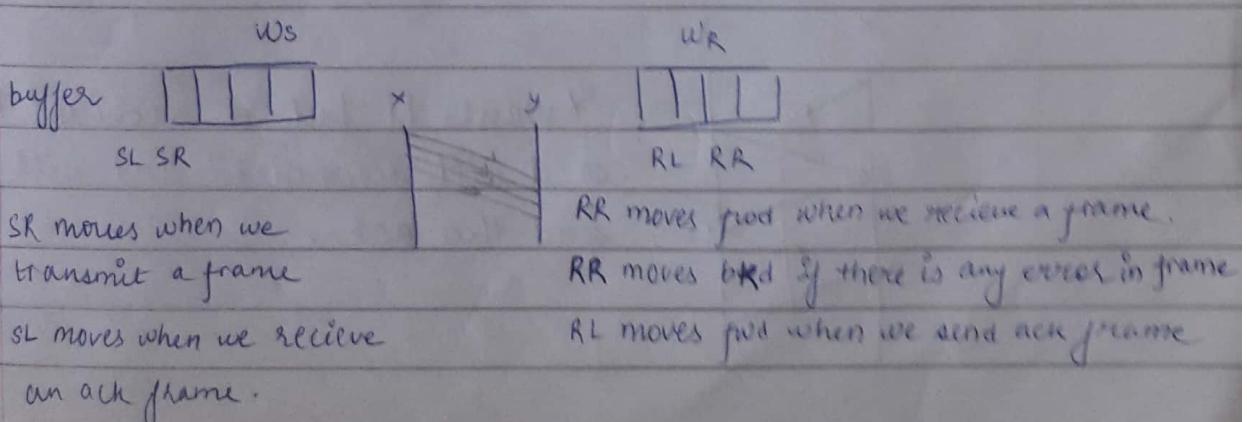
i.e. when W is small

$$\eta = \left(\frac{D}{D+H} \right) \left(\frac{W}{1 + \frac{2(I+A)}{F}} \right) (1-P_0)(1-P_1)$$

$$\frac{f}{c} = 1, \quad \frac{A}{c} = 1 \quad I = 4 \quad W = 15$$

$$W \cdot \frac{f}{c} > 1 + 8 + 1$$

$$15 > 10 \Rightarrow \text{waiting time} = 0$$



max. difference b/w SL and SR is window size.

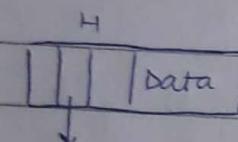
The left side of the window contains those frame which are transmitted as well as acknowledged.

Within window we have frames which are waiting for acknowledgment.

Error Recovery in Flow Control

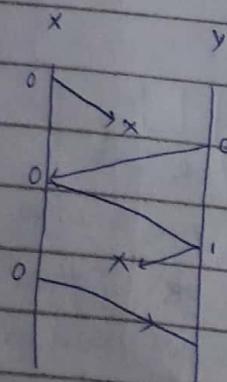
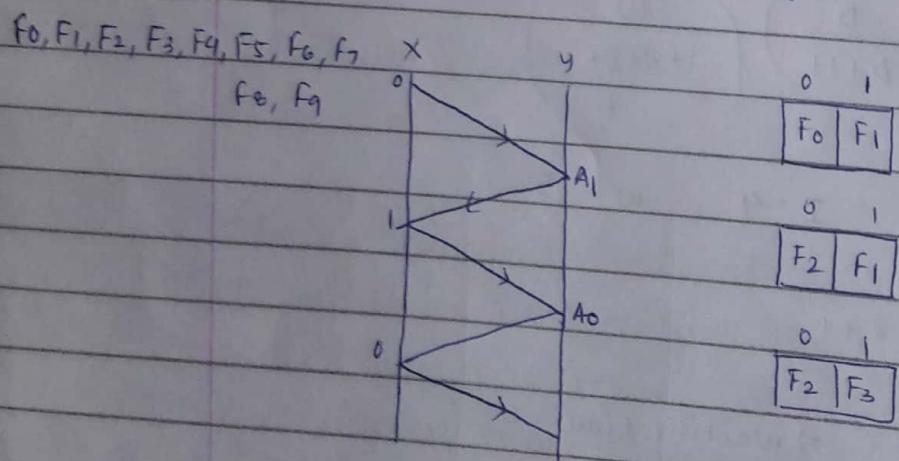
- Go back N ARG
 - Selective Repeat ARG

Flow control protocol specification and verification

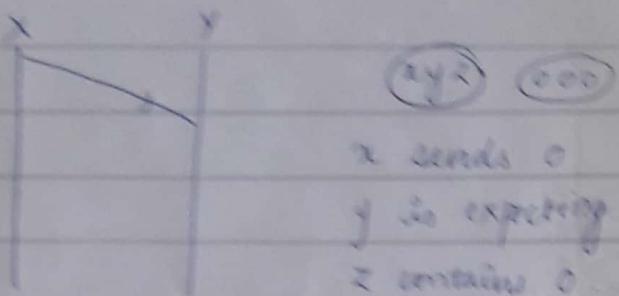
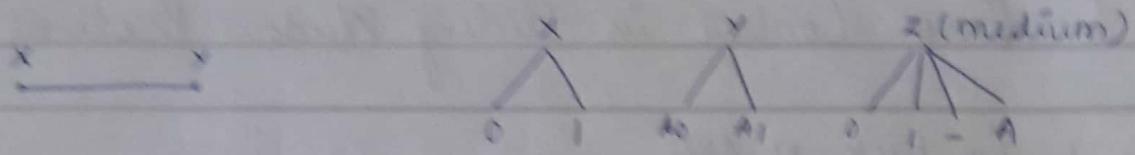


Sequence no.

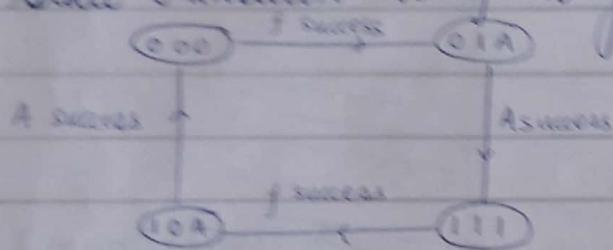
Larger the sequence no. Larger the header.



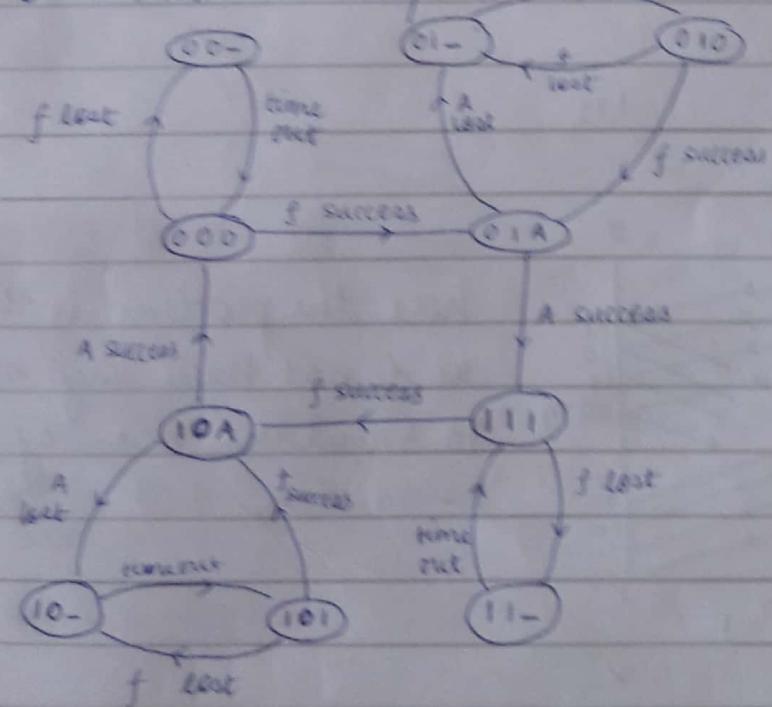
Y wants F1 but it receives F0 so it will discard F0 and will again send the ack.



State Transition Diagram for 1 bit sliding window protocol

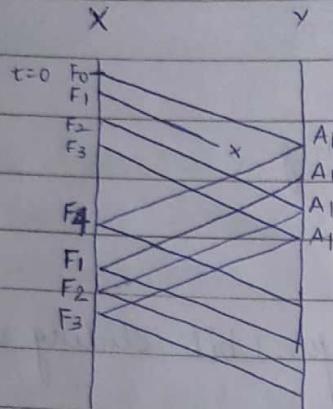


State Transition Diagram time out (in case of error)



Error Control in Sliding Window Protocol

1. Go back N ARQ

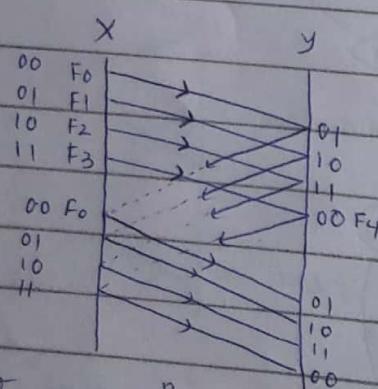


without error

$$\begin{array}{c} n = 2 \\ \downarrow \\ \text{no. of bits} \end{array}$$

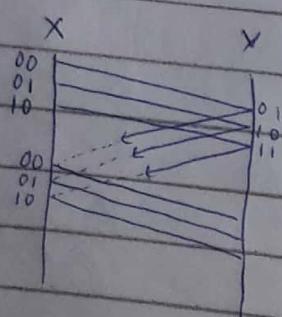
$$\begin{array}{c} w = 2^n \text{ (maximum)} \\ \downarrow \\ \text{window size} \end{array}$$

$00\ 01\ 10\ 11\ 00\dots$
 $F_0\ F_1\ F_2\ F_3\ F_4\dots\ F_{99}$



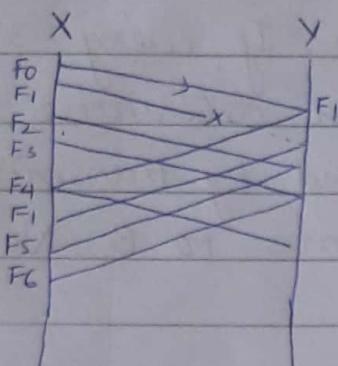
Now let $w = 2^n - 1$

here the problem is that we do not have any mechanism to know the ack. of the send ack.



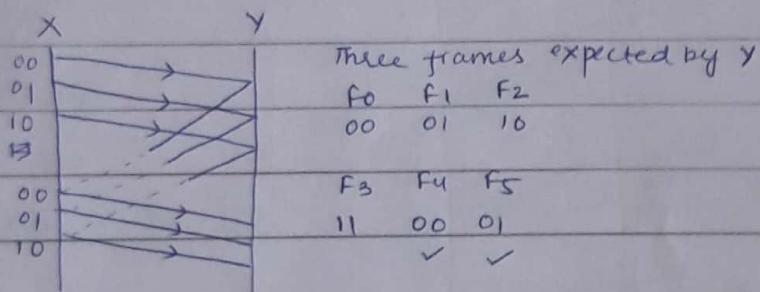
here the problem is solved
max. size of receiver window = 1

2. Selective Repeat ARQ

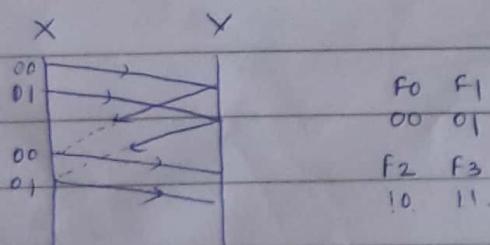


size of receiver window should be more

$$n=2 \quad W = 2^n - 1$$

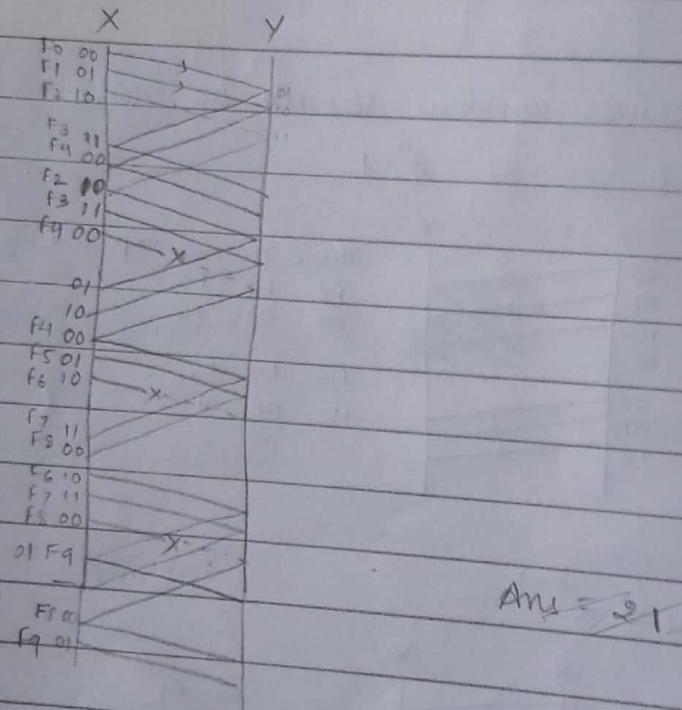


$$\text{Let } W = 2^{n-1}$$

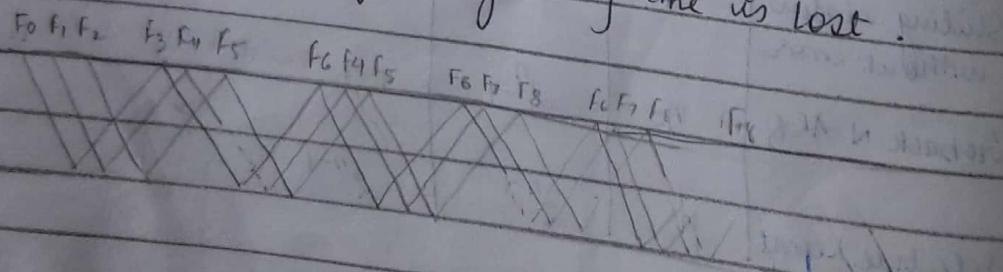


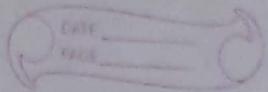
	Seq No. fill	W _{max S}	W _{max R}
Sliding window without error	n	2^n	1
Go-back N ARQ	n	$2^n - 1$	1
Selective Repeat ARQ	n	2^{n-1}	2^{n-1}

Q. A and B are two stations, both station uses go back N sliding window protocol with $w = 3$. A wish to transmit 9 frames to B. If every 3^{rd} frame that A transmit get lost then determine the total no. of frames transmitted by transmitter in order to deliver entire 9 frames to B. No ack. frame ever get lost.



Q. Repeat above ques if every 5^{th} frame is lost.





Q.1 A 25 kbps satellite link has a propagation delay of 400ms. The transmitter implied go back ARQ protocol which is set to 10. Assuming that each frame is 100B long. What is the max data rate possible.

Q.2 Suppose user A uses 32B packet to transfer msg to station B using sliding window protocol. The round trip delay b/w A & B is 80 ms. and the bandwidth of the line is 128 kbps. What is the optimal window size used by station A.

Ans 1

$$C = 25 \text{ kbps}$$

$$I = 400 \text{ ms}$$

$$f = 100B = 800 \text{ bits}$$

$$n = 10$$

$$w = 2^10 - 1 = 1023$$

$$\eta = \left(\frac{D}{D+H} \right) * \left(\frac{w}{\frac{1+2I+A}{F}} \right) * (1-p_0)(1-p_1)$$

$$\text{window size} = 2^{10} - 1 = 1023$$

$$\text{one frame size} = 100B$$

$$\text{window size} = 1023 \times 100B$$

$$\underline{\text{Ans 2}}. f + 2I + A = 80 \text{ ms}$$

$$\begin{aligned} \text{data} &= 80 \times 10^{-3} \times 128 \times 10^3 \\ &= 80 \times 25 \times 10^{-2} \end{aligned}$$

header size is not given so we will assume its size to be negligible
no error given

$\eta = \frac{A}{C}$ is also negligible

$$\begin{aligned} \text{time taken to transmit one frame} &= \frac{800}{25 \times 10^3} \\ &= 0.032 \text{ sec} \end{aligned}$$

$$\frac{w \times f}{c} ? \quad \frac{f + 2I + A}{c}$$

$$1023 \times 0.032 ? \quad 0.032 + 2 \times 400 \times 10^{-3}$$

$$32.736 \geq 0.83$$

so there is no loss bcz of waiting time.

Ans 2 $F = 32B = 32 \times 8 \text{ bits}$
 $= 256 \text{ bits}$

$$2I = 80 \text{ ms}$$

$$I = 40 \text{ ms}$$

$$C = 128 \text{ Kbps.}$$

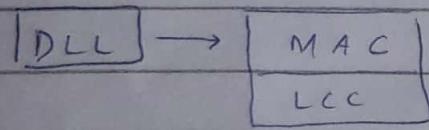
$$W * \frac{f}{C} = \frac{f}{C} + 2I + \frac{A}{C}$$

$$W * \frac{256}{128 \times 10^3} = \frac{256}{128 \times 10^3} + 80 \times 10^{-3}$$

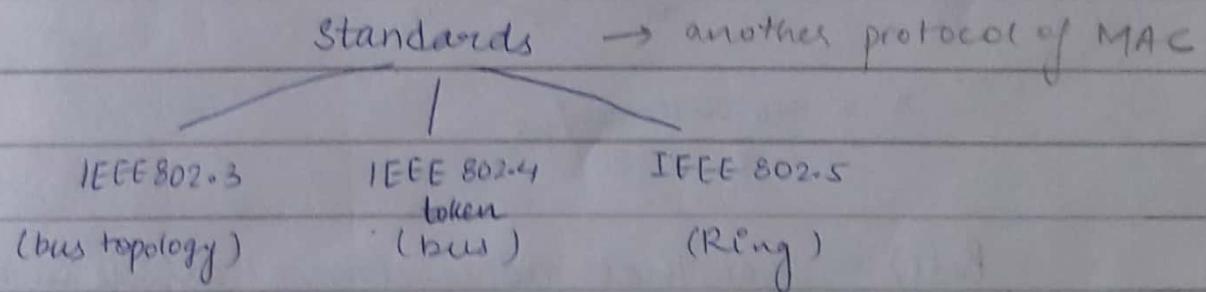
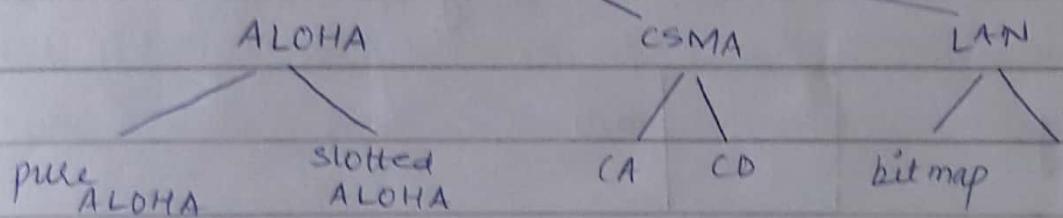
$$W = \frac{82 \times 10^{-3}}{2 \times 10^{-3}}$$

$$W = 41$$

$$n = 6 .$$



Dynamic Channel Allocation



Pure ALOHA

Assumption - Infinite no. of users are there in the zone of a satellite. Each user wish to transmit a fixed size frame. The time taken to transmit such a frame is called 1 frame time i.e $\frac{1}{C}$

- when more than one user transmit the frame then there exist a collision. In case of collision user wait for random period of time and again trying to transmit

the frame.

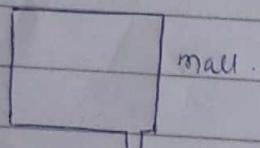
- Data is transmitted successfully if and only if one user transmits the frame.

According to Poisson dist. prob of n arrivals during time t is

$$P_n(t) = \frac{e^{-\lambda t} (\lambda t)^n}{n!}$$

where λ is the mean arrival rate
 t is the time duration
 n is the no. of arrival

e.g.



1 99 50 10

$$\lambda = 40 \text{ customer/hr}$$

$P_0(1)$ = prob that no customer arrive in next one hour.

Now in pure ALOHA.

Let us assume that G_1 is the mean no. of frames generated by all the users per frame time.
 S is the mean no. of success per frame time.

$$0 \leq S \leq 1$$

$$0 \leq G_1 \leq 10$$

relation b/w G_1 & S

$$S = P_0 G_1$$

$$G_1 = 2 \text{ when } t = 1$$

$$S = e^{-G_1 t} \cdot G_1$$

where t is the vulnerable time

P_0 is the prob that no one arrives in time t .

In pure ALOHA protocol user can start transmitting the frame at any time without waiting for an event.

$$1 \text{ sec} = 1000 \text{ ms}$$

$$1 \text{ bit} = 1 \text{ ms.}$$

vulnerable period = 2 frame time

$$S = e^{-2G_1} \cdot G_1$$

$$\frac{ds}{dG_1} = 0$$

$$-2e^{-2G_1} \cdot G_1 + e^{-2G_1} = 0.$$

$$e^{-2G_1} (1 - 2G_1) = 0.$$

$$e^{-2G_1} = 0 \quad \text{and} \quad 1 - 2G_1 = 0.$$

$$G_1 = \infty$$

$G_1 = \frac{1}{2} \rightarrow \text{max success}$

\downarrow
min success

$$S_{\text{max}} = e^{-2 \times \frac{1}{2}} \cdot \frac{1}{2}$$

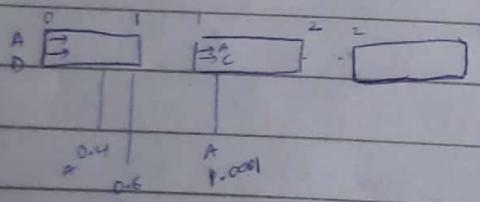
$$S_{\text{max}} = \frac{1}{2e}$$

$$= 18.4 \%$$

Slotted ALOHA Protocol.

1 slot = 1 frame time

In case of slotted ALOHA protocol user can start transmitting the frame only during the beginning of slot.



Vulnerable time = 1 sec.

$$P_0 = \cdot e^{-\lambda t} (\lambda t)^0 \cdot \frac{0!}{0!}$$

$$P_0 = e^{-G_1}$$

$$\lambda = G_1 \\ t = 1$$

$$S = e^{-G_1} \cdot G_1$$

$$\frac{dS}{dG_1} = 0$$

$$dG_1$$

$$-e^{-G_1}G_1 + e^{-G_1} = 0$$

$$e^{-G_1}(1 - G_1) = 0$$

$$e^{-G_1} = 0 \quad , \quad 1 - G_1 = 0$$

$$G_1 = \infty \quad G_1 = 1$$

$$S_{max} = e^{-1} \times 1$$

$$= 36.8\%$$

Pure ALOHA

1. User can start transmitting the frame at any time without waiting for an event.
2. vulnerable time = 2 frame time
3. $P_0 = e^{-2G_1} \cdot G_1$
4. When $G_1 = 1$ then S is S_{max}

$$S_{max} = 18.4\%$$

Slotted ALOHA

- User can only transmit the frame at the beginning of the slot.
- vulnerable period = 1 frame time
 - $P_0 = e^{G_1} \cdot G_1$
 - When $G_1 = 1$ then S is S_{max} .

$$S_{max} = 36.8\%$$

Finite population slotted ALOHA protocol

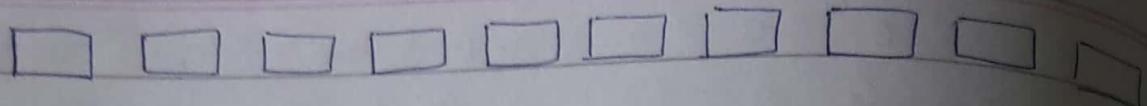
Let us assume that G_i^o is the mean no. of frames generated by user i per frame time.

S_i^o is the mean no. of success of user i per frame time
or

G_i^o is the prob. that user i transmits the frame

S_i^o is the prob. of success

G_i is the mean no. of frames generated by all the users per frame time. S is the mean no. of success of all the users per frame time.



$$G_A = \frac{0.4}{10}$$

$$G_B = \frac{2}{10}$$

Q. 4 users are trying to acquire a medium using finite population slotted aloha protocol (A, B, C, D) The prob that a user transmit the frame per frame time is as follow:

$$G_A = 0.4 \quad 0.2016$$

$$G_C = 0.2 \quad 0.0756$$

$$G_B = 0.3 \quad 0.1296$$

$$G_D = 0.1 \quad 0.0336$$

Determine the prob of success of individual user. Also determine the total success.

$$\begin{aligned} S_A &= G_A (1 - G_B) (1 - G_C) (1 - G_D) \\ &= 0.4 \times 0.7 \times 0.8 \times 0.9 = 0.2016 \end{aligned}$$

$$\begin{aligned} S_B &= G_B (1 - G_A) (1 - G_C) (1 - G_D) \\ &= 0.3 \times 0.6 \times 0.8 \times 0.9 = 0.1296 \end{aligned}$$

$$\begin{aligned} S_C &= 0.2 \times 0.6 \times 0.7 \times 0.9 \\ &= 0.0756 \end{aligned}$$

$$S_D = 0.0336$$

Q. Let us assume that the mean no. of frames generated by all the user is same.

$$\text{i.e } G_A = G_B = G_C = G_D = 0.25$$

$$S_A = G_A (1 - G_A)^3$$

$$= 0.25 (1 - 0.25)^3$$

$$\frac{1}{4} \times \left(\frac{3}{4}\right)^3$$

$$\frac{1}{4} \times \frac{27}{64}$$

$$\begin{matrix} S_B \\ S_C \\ S_D \\ \hline S_F \end{matrix}$$

$$S = "G A (1 - G_A)^3"$$

Finite population slotted ALOHA protocol.

n users are there. Each user generates same no. of frame

$$G_1 = G_2 = G_3 = \dots = G_N$$

$$G = G_1 + G_2 + \dots + G_N$$

$$N G_i = G$$

$$G_i = \frac{G}{N}$$

$$S = S_1 + S_2 + S_3 + \dots + S_N$$

$$NS_i = S$$

$$S_i = \frac{S}{N}$$

$$S_i = G_i (1 - G_j)^{N-1} \quad \text{where } i \neq j \\ 1 \leq j \leq N \quad \text{except } i$$

$$\text{if } G_i = G_j$$

$$S_i = G_i (1 - G_i)^{N-1}$$

$$S = \frac{G}{N} \left(1 - \frac{G}{N}\right)^{N-1}$$

When $N \rightarrow \infty$

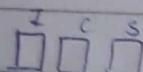
$$\lim_{N \rightarrow \infty} \left(1 + \frac{-G_1}{N}\right)^{N-1} = e^{-G_1}$$

$$S = G_1 e^{-G_1}$$

Q. Measurement of an infinite user slotted ALOHA channel shows that 10% of slots are idle. What is total channel load i.e. G_1 .

(b) What is the throughput i.e. S .

(c) Is the channel overloaded or underloaded.



P_0 = prob that no one will arrive

$$0.1 = e^{-G_1}$$

$$\log(0.1) = -G_1$$

$$G_1 = 2.3$$

$$S = e^{-G_1} \cdot G_1$$

$$= 0.1 \times 2.3$$

$$= 0.23$$

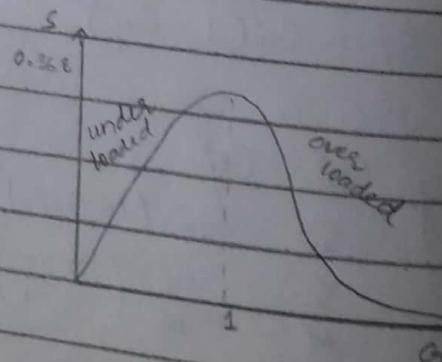
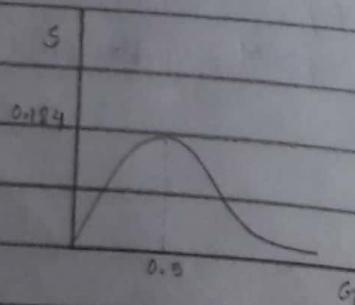
(c) $G_1 > 1$ so overloaded.

Pure ALOHA

$$S = e^{-2G_1} \cdot G_1$$

Slotted ALOHA

$$S = e^{-G_1} \cdot G_1$$



Q.1 10,000 airline reservation stations are competing for the use of a single slotted ALOHA channel. The avg station makes 18 request per hour. A slot is of 10^{-5} msec. What is the approx. channel load i.e. G_1 .

$$1 \text{ hour} \rightarrow 18 \text{ req}$$

- Q2 A large populatⁿ of ALOHA user manages to generate 50 request per second including both original and retransmission. Time is slotted in units of 40 msec.
- (a) What is the chance of success on the first attempt
 - (b) What is the prob of exactly k collision and then success.
 - (c) What is the expected no. of retransmission.

- Q3 A group of n stations share a 56 kbps pure ALOHA channel. Each station output a 1000 bits frame on an avg. of once every 100 sec. What is the max value of n .

Ans 1 $1 \text{ hour} \rightarrow 18 \text{ req.}$

$$1 \text{ sec} \rightarrow \frac{18}{60 \times 60} \text{ req.}$$

$$1 \mu\text{sec} \rightarrow \frac{18 \times 10^{-6}}{60 \times 60} \text{ req.}$$

$$1 \text{ slot} \rightarrow \frac{18 \times 125 \times 10^{-6}}{60 \times 60} \text{ req.}$$

$$\begin{aligned} & 1 \text{ slot} \rightarrow 1 \text{ sec} \\ & 100 \text{ slots} \rightarrow 100 \text{ sec} \\ & n \times 100 = 56 \times 10^3 \text{ bits/sec} \\ & n = \frac{56 \times 10^3}{100} = 560 \text{ slots} \end{aligned}$$

G_1 = mean req of all the user

$$= \frac{18 \times 125 \times 10^{-6}}{60 \times 60} \times 10^4$$

$$= 6.25 \times 10^{-3}$$

Ans 2.

$$1 \text{ sec} \rightarrow 50 \text{ req.}$$

$$40 \text{ msec} \rightarrow 50 \times 40 \times 10^{-3} \text{ req}$$

$$G_1 = 2$$

$$\text{(i) prob of success in 1st attempt} = e^{-G_1} \cancel{\times G_1}$$

$$= e^{-2} \cancel{\times 2} =$$

$$\text{(ii) prob of exactly } k \text{ collision & then success}$$

$$= (1 - e^{-G_1})^k e^{-G_1} \cancel{\times G_1}$$

$$\text{(iii) expected no. of retransmission} = \sum_{k=1}^{\infty} k P_k$$

$$= 1 \cdot e^{-2} + 2 \cdot (1 - e^{-2})e^{-2} + 3 \cdot (1 - e^{-2})^2 e^{-2} + \dots$$

$$= e^2$$

Ans 3

$$n^* \frac{1000}{100} = 56 \times 10^3 \times 0.18$$

$$n = 1008$$

C.S.M.A

Before transmitting the frame, first sense the medium.
If medium is busy then wait.

- Non persistant CSMA
- persistant CSMA
 - 1 persistant
 - ~~P~~ persistant

In this user sense the medium after discrete interval of time i.e non continuous sensing of medium.

In this user sense the medium continuously.

fiber, cable \rightarrow passive component
switch, router \rightarrow active component

19

In 1-persistent CSMA user continuously sense the medium and whenever user get medium is idle then transmit the frame with the probability of 1.

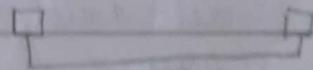
In case of P-persistent CSMA user transmit the frame with the probability of P.

- Determine the min. size of the frame to detect the collision in CSMA protocol or determine how long a user can transmit the frame to detect the collision.

Let us assume that τ is the end-to-end delay b/w two furthest station.

cable length = d m.

$$\tau = \frac{d}{s}$$



τ

at $t=0$ A and B sense the medium.

at $t=\tau$ A & B will detect the collision.

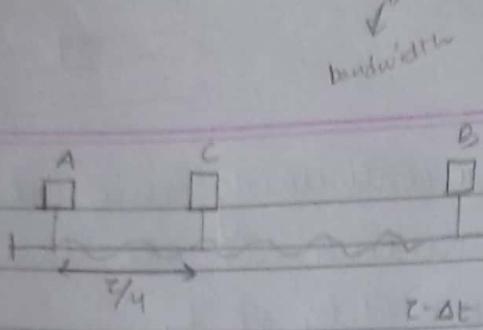
If $\frac{t}{c} < \tau$, then A will go to waiting state. Now if A gets to know about collision, it can't do anything. It has to wait till time out.

If $\frac{t}{c} > \tau$, then A will stop the transmission at τ and wait for some time.

Whenever there is a collision user will stop the transmission and will send a jam signal.

$$\text{time taken to detect a collision} = \sigma \tau + \frac{s_i}{c}$$

If upto this time no jam signal is received then the channel is allocated.



$$\frac{F}{c} \geq \vartheta \tau + \frac{F_j}{c}$$

$$\frac{F_{\min}}{c} = \vartheta \tau + \frac{F_j}{c}$$

$$F_{\min} = \vartheta \tau c + F_j$$

If F_j is negligible, then time taken to detect a collision is $\vartheta \tau$.

Let 1 slot = $\vartheta \tau$

CSMA is also called 1 slot LAN protocol.

Performance of IEEE 802.3 under the condition of constant and heavy load.

K stations suddenly become ready for transmission. Instead of taking binary back off exponential algo use constant retransmission prob in each slot.

Let p is the prob that a user transmit the frame. A is the prob of success. $(1-A)$ is the prob that no channel is allocated.

$$A = c_1 \cdot p(1-p)^{K-1}$$

$$\frac{dA}{dp} = 0$$

c_1

$$p = \frac{1}{K}$$

$$A_{\max} = \frac{K-1}{K} \left(1 - \frac{1}{k}\right)^{k-1}$$

$$A_{\max} = \left(1 - \frac{1}{k}\right)^{k-1}$$

$\Rightarrow k$ is very large

$$A = e^{-1}$$

$$\approx 0.368$$

$$\eta = \frac{\text{useful time}}{\text{total time}}$$

there are three types of slot

- (i) collision slot
- (ii) ideal slot
- (iii) successful slot



$$CT = \bar{r}r \times N$$

N: expected no. of con slot

$$\eta = \frac{r/c}{CT + r/c}$$

$$N = \sum_{j=1}^{\infty} j p_j$$

p_j : prob that contention interval requires exactly j slot

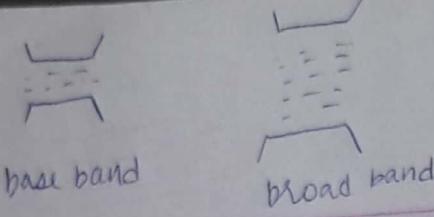
$$p_j = (1-A)^{j-1} A$$

$$N = \sum_{j=1}^{\infty} j (1-A)^{j-1} A$$

$$1-A=L$$

$$N = \sum_{j=1}^{\infty} j (L)^{j-1} (1-L)$$

$$N = \frac{1}{1-L} \approx \frac{1}{A}$$



$$\eta = \frac{f/c}{\alpha \tau \cdot \frac{1}{A} + \frac{f}{c}} = \frac{1}{1 + \alpha \tau \cdot \frac{1}{f} \cdot \frac{1}{A}}$$

$$\eta = \frac{1}{1 + \alpha \cdot \frac{L}{s} \cdot \frac{C}{f} \cdot \frac{1}{A}}$$

$$C = L \\ s$$

When A is A_{max} .

$$\eta = \frac{1}{1 + 5.4 \cdot \frac{L}{s} \cdot \frac{C}{f}}$$

s and C are constant

so η of LAN depends on L and f .

min frame size = $\alpha \tau$

so min size of frame also depends on length of cable
so we can say that η also depends on L .

There are some standard

i. Cable standard

(i) 10 Base 2 → length

↳ data rate → technology
10 Mbps
200m

(ii) 10 Base 5

(iii) 100 Base T ↳ twisted pair

(iv) 100 Base F ↳ fibre

standard length = 100m
length upto 2km

there are 2 types of fibre

(i) single mode: used for long range
(ii) multi mode: used for short range

(v) 10 Broad 36

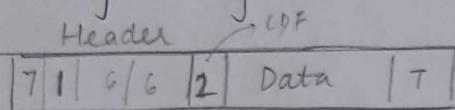
length = 36000 m

logical address - IP
physical " - MAC



	Basic ethernet	fast ethernet	gigabit ethernet
data rate	10Mbps	100Mbps	1Gbps
cable length	2500 m	250 m	250 m
min size of packet	72 Byte	72 B	72 B

IEEE 802.3 frame format



header contains first seven byte of preamble
delimiter is of 1B.

Source address is of 6B

Destination " " 6B

Length of data field is 464B (min) and 1500B (max)
tail is of 4B, contains CRC

Preamble is used for synchronization purpose. It transmit alternate 0,1 upto 7B.

There are two mode of transmission

- Synchronous
- Asynchronous

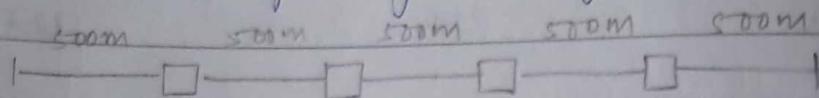
In asynchronous mode we add start and stop bit.

SFD is responsible for this.

48 bit MAC address i.e source address.

LDF - indicate actual length of data frame

Consider 10 Base 5 technology. After every 500ms, a repeater is required. Repeater is used to retransmit the same signal after strengthening it.



$$\frac{F}{c} = \frac{d}{c}$$

$$F/c = 2 (\text{propagation delay} + 4 * \text{processing delay at repeater})$$

$$F_{\min} = \frac{57.6}{10 \times 10^6} \mu\text{sec}$$

$$F_{\min} = \frac{57.6}{10 \times 10^6} \text{ bit}$$

$$= 72 \text{ B}$$

Binary backoff exponential algorithm.

This algo gives waiting time for the stations that are involved in collision.

$$\text{waiting time} = K \times \frac{51.2 \mu\text{sec}}{2^n} \quad \begin{array}{l} \text{assuming min frame size} \\ \text{ignoring 7B preamble} \\ \text{and 1 byte} \end{array}$$

where K is randomly vary from 0 to $2^n - 1$

n : collision no.

A and B are two station and both want to send a frame. They both sense the medium and it is ideal so both of them start transmission.

$n=0$ i.e both will not wait

prob of transmission = 1

prob of collision = 1

Now $n=1$ so $k=0 \text{ to } 1$

prob of transmission of A = $\frac{1}{2}$.

prob of success of A = $\frac{1}{4}$.

prob of collision = $\frac{1}{2}$.

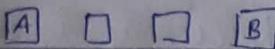
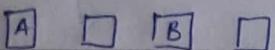
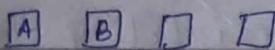
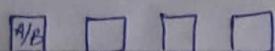
~~Collision effect~~

A and B are only two users over an ethernet. A's frame no. will be $A_1, A_2 \dots$. B's frame no. will be $B_1, B_2 \dots$. A and B transmit the frame and collision happens. After the 1st collision A select $k=0$ and transmits A_1 while B wait for their turn. Now A wish to transmit A_2 and B wish to transmit B_1 . Now determine what is the prob that A gets 2nd back off race
ii) What is the prob that B wins the 2nd back off race.

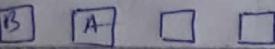
A_2 & B_1 will collide

$$\begin{array}{ll} A_2 & B_1 \\ n=1 & m=2 \\ k=0,1 & k=0,1,2,3 \dots \end{array}$$

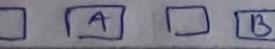
$$\begin{array}{ccc} P & 1/2 & 1/2 \\ P & 1/2 & [A_1 \quad 1/2] \\ P & 1 & 1/2 \\ P & 1/2 & 1/4 \end{array}$$



$$(i) P(A) = \frac{5}{8}$$



$$(ii) P(B) = \frac{1}{8}$$



Token Ring

It uses ring topology.

Important properties of token ring

1. It offers connectionless communication.
2. Priority can be assigned whereas in the case of CSMA priorities cannot be assigned.
3. No restriction on minimum and max. size of packet whereas in ethernet there is restriction on size.
4. It offers deterministic services i.e. it is suitable for real time application whereas ethernet is not suitable for real time app.

Token Reinsertion Strategies

There are two type of token reinsertion

Early Token release

1. Token is transmitted immediately after transmitting the last bit of data frame i.e. as soon as data is transmitted token is released.

2. Reliability is low

3. Efficiency is high

4. used when system is heavily loaded.

5. Cycle time = $a + c + d$

$$a = F/c$$

$b = I$ (propagation delay in ring)

Token is transmitted after receiving the last bit of the data frame i.e. after getting entire data packet back token is released.

Reliability is high

Efficiency is comparatively low

used when system is lightly loaded.

Cycle time = $a + b + c + d$

$$c = \frac{F}{I}$$

$$d = I_{AB}$$

$$6. \eta = \frac{a}{a+c+d}$$

$$\eta = \frac{a}{a+b+c+d}$$

Problem related to token ring

1. Problem related to token

- (i) lost token problem or damaged/corrupted token problem
- #

2. Problem related to source

- (i) monopoly problem
- (ii) orphan packet problem
- (iii) Stray Packet

Once a packet is produced by the source if source is down before packet is received then such generated packet is known as orphan packet. Hence it is circulating around the ring upto its circulating time.

While producing the packet if source is down then partial packet is released to the ring and nobody could understand the packet. Hence it is circulating around the ring.

3. Problem related to destination

destination may present in one of the following 3 mode

- (i) busy destination
- (ii) down/crash destination
- (iii) safe operation

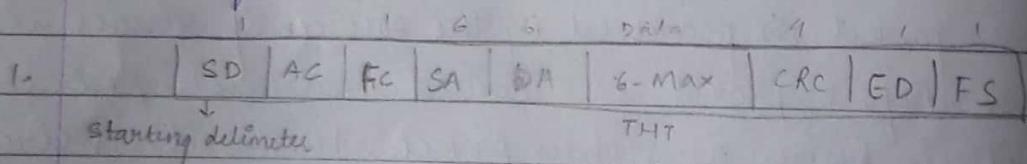
4. Problem related to ring

(i) major cut in the ring or unhealthy part in the ring

In order to solve the above problems either we can deploy a monitor station who is monitoring the ring (or act as a ring admin) or use various types of timer like token holding timer value, ring token rotation timer value, token holder timer value.

Types of frames in token ring

1. Data frame
 2. Token frame
 3. Abort frame

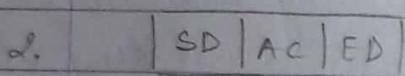


AC: access control

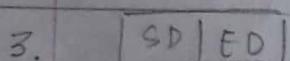
FC: frame control

ED : ending delimiter

FS: frame status



size of token = 24 bit (default size)



SD: it contains $10JK10JK$

ED : it contain IIJKIIIIE

I: information bit
E: error bit

SD and ED are used to indicate starting and ending of frames. They are using invalid differential manifolds.

encoding signal. JK positions are used as bits in such a way to violate DME principles.

AC: In this first 3 bit is for priority, next one bit for token, next one bit for monitor and remaining 3 bit for reservation.



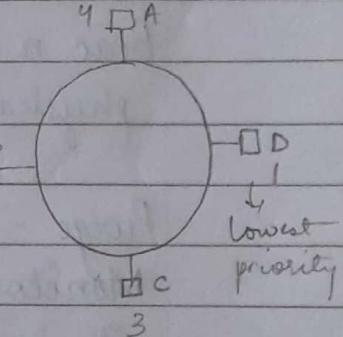
if $T=0$ means it is data frame
 $T=1$ " " token "

$M=0$ before crossing monitor station
 $M=1$ after " "

A transmit the data frame and it reaches

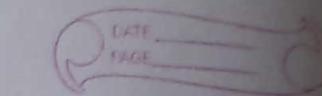
B. If B also wants to transmit the data it will set the P and R_{bits} to 2. Now the

data frame reaches C. C also wants to transmit the data its priority is higher than 2 so it will overwrite P and R bit to 3. Frame will reach D and it will forward it to A. Now A will see the P and R bit and will send the token to C. Now C will start transmission.



No meaning of priority field for data frame, only reservation can be done whereas token frame have priority field as well as reservation field. User can get the token when the priority of the user is equal to the priority of the token. This mech is called access control mech or token passing mech.

with the help of virtualized duplicate address (MAC) can be created.



Fc

If the value of 1st two bit is -

00 : data frame

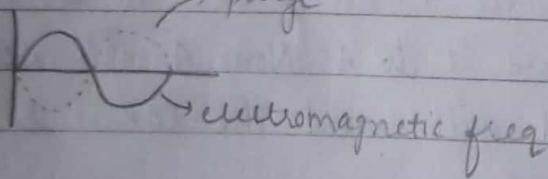
11 : control frame

If it is a control frame then only the other 6 bits are used
claim token - use for election purpose of monitor

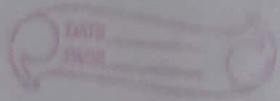
AMP (active monitor present) - it is released by monitor station in equal interval of time to indicate that monitor is available for service.

Beacon frame - This frame is used to identify the physical cut in the ring.

Purge - use to remove unwanted bits from the ring.
Monitor station measures the freq. of the signal, if it is found to be invalid then it produce opposite freq pattern and nullify the invalid freq.



DAT (duplicate address test) - when new station wants to enter and join the network then it sends a DAT frame indicating its address. If any other station is having the same physical address then it sends a refusal packet to the new station then new station changes its address and again sends DAT frame.



SMP (Standby monitor present) - this bit is used to get knowledge about upstream neighbour. Every station have upstream and downstream station. It is necessary to have knowledge of upstream station.

→ Data size depend on token timer value.

FS (frame status)

It contain 2 important field.

A	C	X	X	A	C	X	X
---	---	---	---	---	---	---	---

A : available

C : copy

if initially A = 0 then C = 0

success | |

busy 0 0

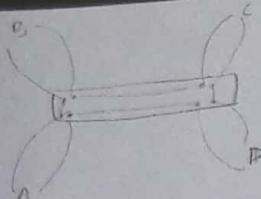
invalid 0 1

Q.1 Why FS is not included in CRC.

Ans CRC is calculated by the source station whereas FS is field by destination station. Therefore while calculating CRC it is not possible for source to predict FS value.

Q2 Why FS is having two set of A,C field.

Ans Since FS is not included in CRC calculation, to have its own error calculation it uses two sets of AC bits. If both sets are same then it is assumed to be correct. otherwise it is treated as error.



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Implementation of Token Ring

There are 4 modes of operation for token ring

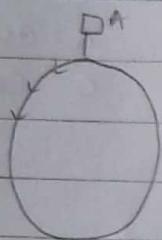
1. Transmission mode

2. Receiving mode

3. Listening mode (waiting for either data or tokens)

4. Bypass mode (in this mode station is disconnected from the ring for maintenance purpose)

Calculate the min size of token ring.



$$C = 1 \times 10^6 \text{ bits/sec}$$

$$\text{speed} = 2 \times 10^8 \text{ m/s}$$

$$\text{distance covered by 1 bit} = \frac{2 \times 10^8}{10^6}$$

$$= 200 \text{ m}$$

$$\text{token frame} = 24 \text{ bit}$$

$$\begin{aligned} \text{min size of ring} &= 24 \times 200 \\ &= 4800 \text{ m} \end{aligned}$$

length of ring $> 4800 \text{ m}$ \rightarrow no overlapping
 $T_p > T_x$

if propagation delay is greater than transmission time of token frame then there is no overlapping

If length of ring is less than min size then there are 2 solⁿ

- add more cable length not good

• add artificial delay in the ring. Artificial delay is needed only when total time of propagation is less than transmission time. This causes overlapping. Therefore to avoid overlapping in the ring artificial

delay is introduced.

$$1 \text{ bit delay} = 200 \text{ ns}$$

$$9 \text{ bit delay} = 1800 \text{ ns} \quad (\text{stopping bit for } 9 \mu\text{s})$$

so a 3000m ring size should have 9 bit delay to avoid overlapping.

Token Rotation Timer Value (TRT)

$$\text{TRT} = \text{propagation delay of ring} + \text{no. of active stations} \times \text{delay at each station}$$

Min TRT - time taken to rotate the token when no station is using the token.

Max TRT - time taken to receive token back when every station is using the token.

Switching

Deciding the path - routing for transferring the data using the path - switching

Routing Table



Routing Mechanism



Routing Principles

Deciding path at run time → adaptive or dynamic routing algo
(on basis of current network traffic)

Before transferring data deciding the path

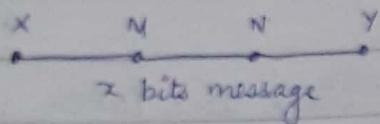
→ static or non-adaptive routing algo

Switching types

- circuit switching
- message "
- packet "

Assumption

x bits is the size of the message
 C is the channel capacity in bits/second

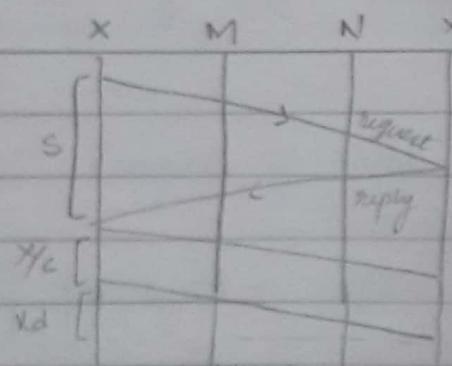


k is the hop path length

No. of intermediate stations = $k-1$

d is per hop path delay

(i) Circuit Switch Network



X sends request for a connect
X gets a reply

s → circuit set up time
(time taken to create connection)

Once connection is created path is dedicated to X & Y
Intermediate stations do not perform any operation over this path.

does not retransmit frame
does not do error correction.

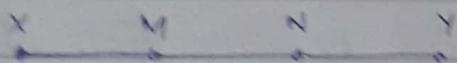
Q Determine total delay experienced by circuit switch network.

$$T_{CSN} = s + \frac{x}{c} + kd + tp$$

↓ ↓ ↓ ↓
negligible total delay
transmit the last bit

(ii) Message Switch Network

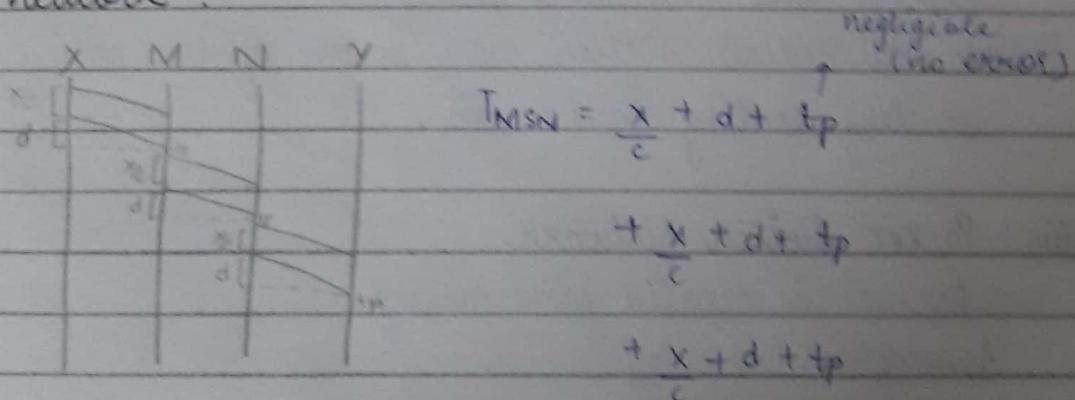
also known as store & forward switching



$X \rightarrow M$ (entire msg delivered to M)
no error msg in msg so it transmits message to N.

Intermediate station performs error detection & transmission process.

Q. Determine total delay experienced by message switch network?



$$T_{MSN} = \frac{x}{c} + (k-1) \frac{x}{c} + (k-1)tp + kd + tp$$

↓

time taken to
retransmit entire
message by $(k-1)$ intermediate
stations

$$T_{MCN} = \frac{x}{c} + (k-1) \frac{x}{c} + kd$$

In CSN, there is an overhead of creating connection
But in MCN, message retransmission is required for intermediate stations.

- Q. Compare the delay of message switch network & CSN under what condⁿ, MSN offers lower delay ?
- CSN → connection creation
MSN → retransmission by intermediate stations

$$T_{MCN} < T_{CSN}$$

$$\frac{x}{c} + (k-1) \frac{x}{c} + kd < s + \frac{x}{c} + kd$$

$$(k-1) \frac{x}{c} < s$$

then MCN offers lower delay.

This is also a routing policy.
No intermediate stations may be one of the policy for selecting routing mechanism.

(iii) Packet Switch Network

Packets is created from message
Assumption

P is size of packet

$$P = h + p$$

$h \rightarrow$ header

$p \rightarrow$ pay load or data portion of message

e.g. size of msg = 4500 bytes

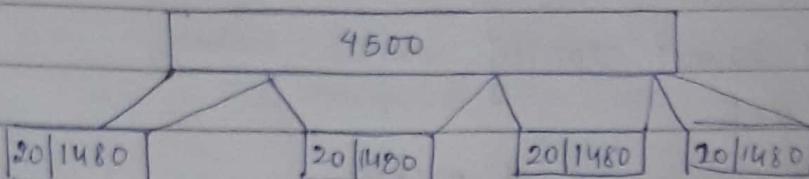
A IP packet size = 1500 bytes.

Determine the no of packets required?

If packet header = 20 bytes

no. of packets required = 4

$$P = 20 + 1480 \text{ bytes}$$



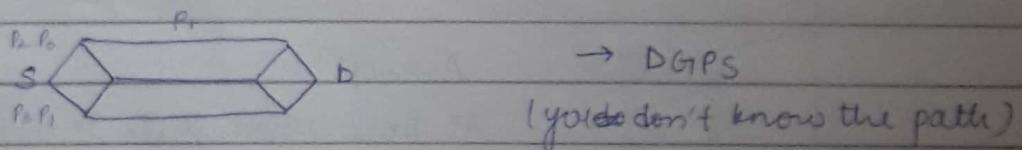
Thus 4 packets required.

There are 2 types of packet switching

- (i) Data gram packet switching
- (ii) Virtual circuit " "

DGPS → connection less

VCPS → virtual connection oriented PS



- DGPS

In data gram packet switching each & every packet route independently. It means each & every packet contain entire routing information.

- Virtual Circuit Packet Switching

Every packet follow the path of the first packet. First packet contain entire path information.

Drops is used when system is heavily loaded
 Voips " lightly "

Q. Determine the delay experienced by lightly loaded packets switch network?

x is size of message

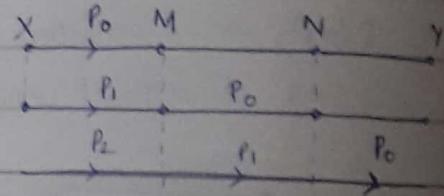
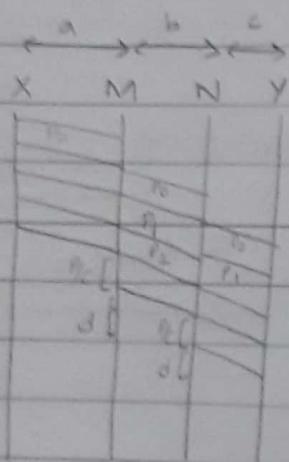
$c \rightarrow$ channel capacity

$$P = p + h$$

$$n = \frac{x}{P} \quad \text{no. of packets}$$

pay load (not packet size)

Data transmitted is in form of packet



Assumptⁿ:

At time when X is transmitting last bit of P_0 , M is transmitting last bit of P_0

Assumption:

Time taken to propagate P_0 packet from M to N
 $=$ time taken to propagate P_1 from X to M .

time taken to transmit last bit of P_2 = $\frac{P}{c}$
 by X

if P_1 by M = $\frac{P}{c}$

But these are performed parallelly.

Even processing is done parallelly.

$$T_{PSN} = \frac{x}{p} + \frac{p+h}{c} + (k-1)tp + tp + kd$$

↑ total delay

↓ ↓ ↓ ↓
 no. of time to (k-1) users destination is
 packets transmit retransmitting processing
 one packet the last the last packet
 packet

only p is variable

Q. What should be the optimum size of the data portion of the packet in lightly loaded PSN.

Opt^m 's size is obtained when delay is min^m .

$$\frac{dJ}{dp} = 0$$

$$P = \sqrt{\frac{h\tau}{(K-1)}} \rightarrow \text{optimum size of data portion of packet.}$$

$$P_{opt} = P_{opt} + h$$

let us assume $\text{tp} \cong \text{neg}$ & $\text{h} \cong \text{neg}$

$$T_{PSN} = \frac{x}{c} + (k-1) \frac{p}{c} + kd$$

Q. Compare the delay of lightly loaded PSN & CSN? Under what condⁿ PSN offers lower delay.

$$T_{PSN}^{UV} < T_{CSN}$$

$$\frac{x + (k-1)p}{c} + kd < s + \frac{x + kd}{c}$$

$$(k-1) \frac{p}{c} < s$$

If time taken to transmit last packet by all intermediate stations is less than connection establishment time, then PSN is better than CSN.

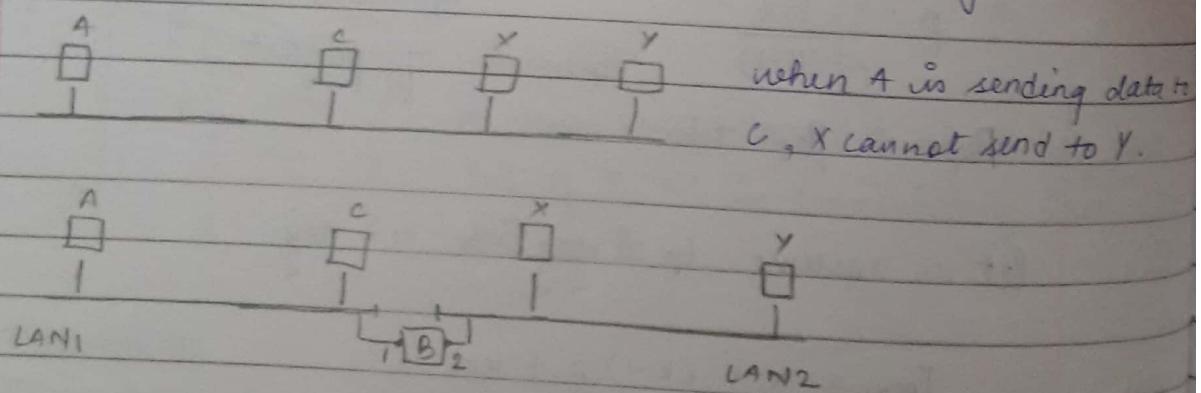
In MSN, whole message was transmitted & in PSN, only a packet is transmitted. Thus, PSN is better than MSN.

- Q. In sliding window protocol, can the sender receive acknowledgement for a packet that falls outside its current window. If so specify scenarios under which this will occur.

19/3/18

BRIDGE

It is a device used to connect at data link layer.



Bridge maintains a table known as forwarding table.

Bridge performs 3 basic functions:

- (i) Forward data from one LAN to another LAN
- (ii) Identify where stations are connected in LAN
- (iii) Prevent loop in the LAN.

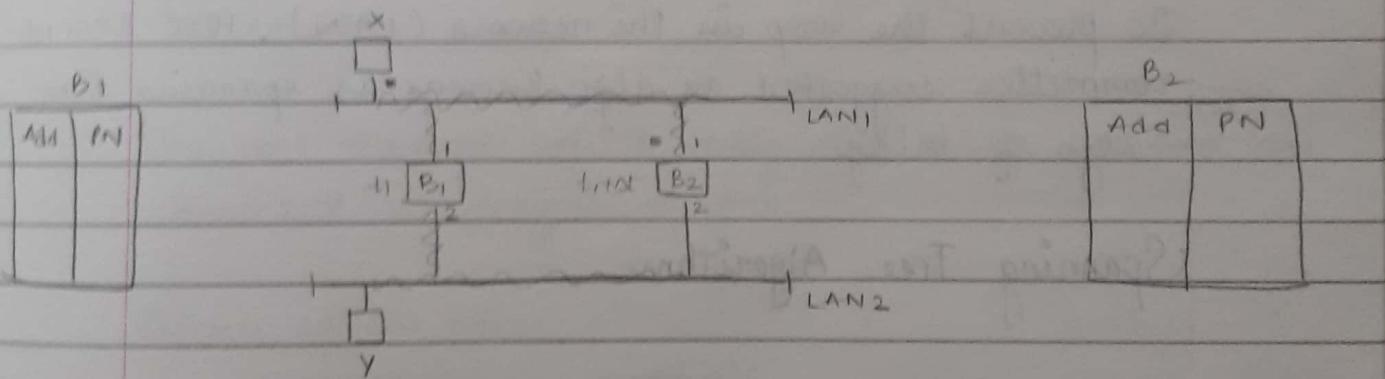
Forwarding table contains two fields i.e address field and port no. field.

Bridge first checks the source address ^{of frame} in forwarding table. If there is an entry then it will update it and if there is no entry then it will insert one.

Now bridge check destination address ^{of frame}. If it is present then it will send it. If not then it will forward the frame to all ports.

Add	Port No.
A	1
C	1
X	2
Y	2

Problem



At time t_1 B_1 receives the data and it checks the entry in FT so it will insert the entry and it will check destination address entry. Since there is no entry it will transmit the data to all the ports.

Same with B_2 .

B_1		B_2	
Add	PN	Add	PN
X	1	X	1

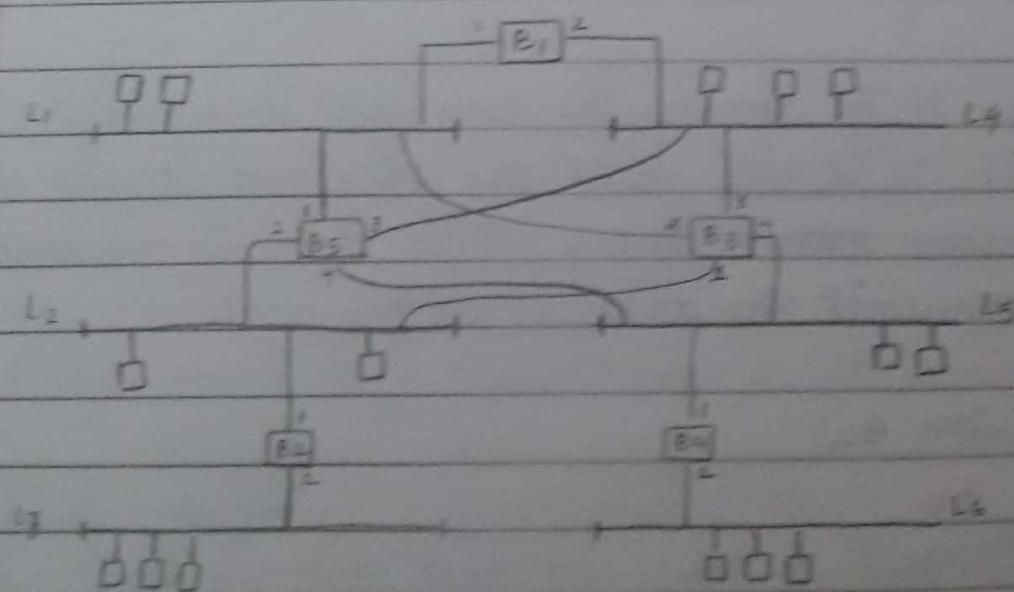
Bridge receives one more frame which is forwarded by it.
 It will check the entry corresponding to source address.
 Since there is entry corresponding to X then it will update it.

B ₂		B ₁	
addr	Port	addr	Port
X	2	X	2

Now when Y will send data, bridge B₁ will check the entry and will insert one entry corresponding to Y now it will check the entry corresponding to destination address since the entry is present and port no. is 2 it will block the data.

To prevent the loop in the network (LAN), IEEE 802.1d committee suggested an algo known as spanning tree algo of bridge.

Spanning Tree Algorithm



Cost b/w bridge and LAN is hop path length

Root bridge

Assume root bridge is a bridge having lowest bridge ID.

Root port

All the ports of root bridge are root port. A root port is a port which will offer least cost path from a bridge to the root bridge. In case of tie, the root port is a port having lowest port id.

Designated bridge is a bridge which offers low cost path from LAN to root bridge. In case of tie, lower ID bridge is selected.

The port through which designated bridge and ^{LAN} port are connected is designated port.

Remove all the other

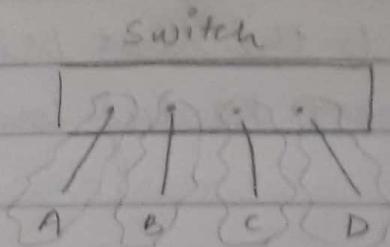
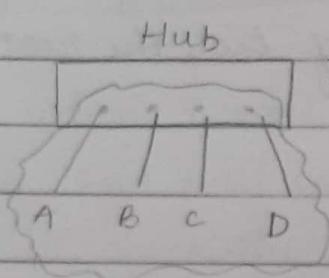
1. Identify the root bridge among all the bridges.
2. Identify root port of all the bridges except root bridge.
3. Identify the designated bridge of each LAN.
4. Only root ports and designated ports are allowed to forward frames. They are only ports that forward the frame and other ports are in blocking state.

HUB

Hub is a physical layer broadcast device. It uses one collision domain.

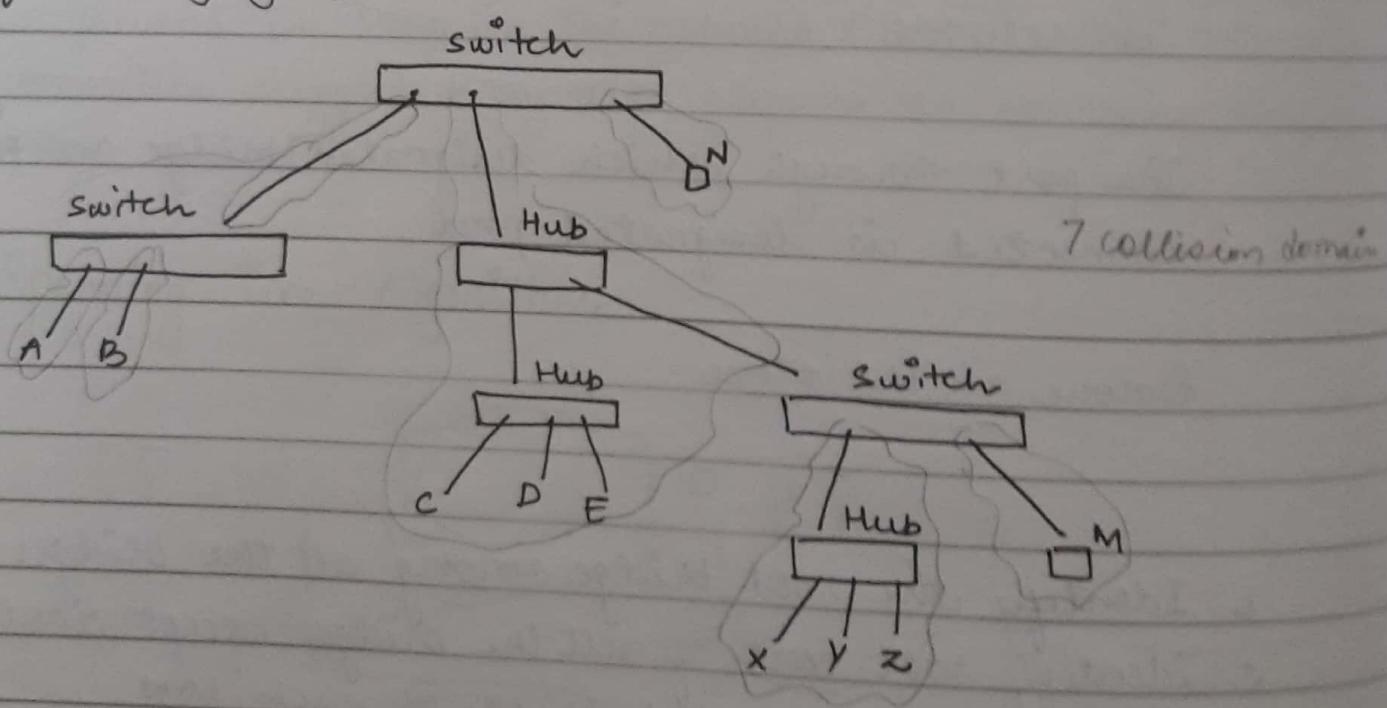


all computers trying to acquire medium at a time then they are all in one collision domain.

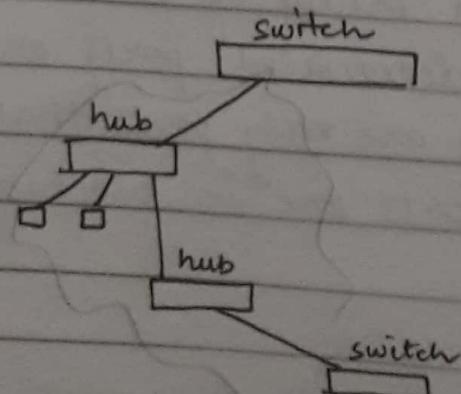


4 collision domain

Identify the no. of collision domains available in the following graph.



Q.2



1 collision domain

internal routing : core to nodes
external : border to outside
base : edge to the network
states / dynamics : sections

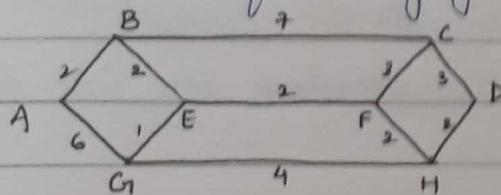
Q. Difference b/w Hub and Switch.

Router

Selecting the path from source to destination

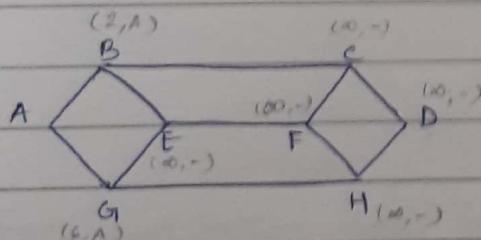
Static Routing - Dijkstra or single source shortest path algo

Consider the following graph

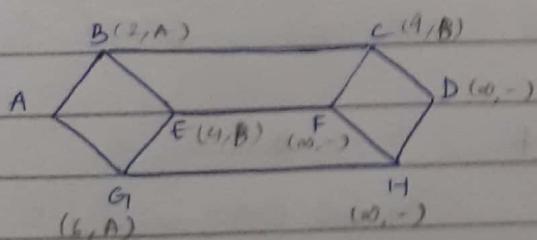


Find shortest path from A.

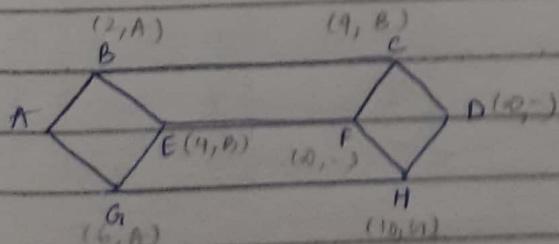
A | B | G



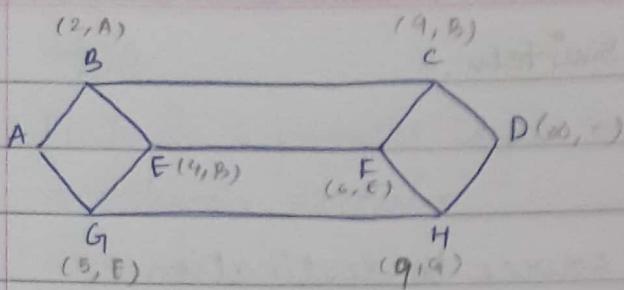
A | B | G | C | D



A | B | G | C | F | D

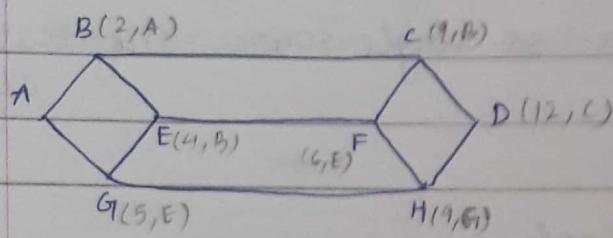


A | B | G | C | F | D

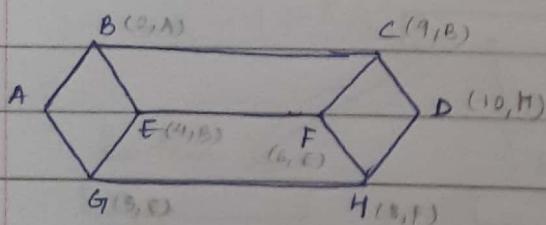
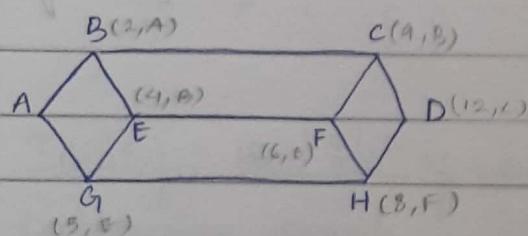


Ques 56

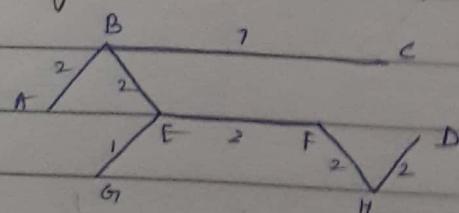
$$\min((10, 4, 13), (11, 5, 11))$$



$$\min((10, 6, 12, 9), (11, 7, 11))$$



No. of lines not used. 4



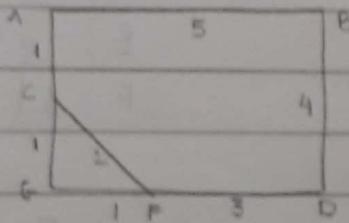
graph for A only

It states that, let us assume that there exist an optimal path from node I to node J and node K belongs to that path then the optimal path from node K to node J also falls along the same path. The routing table constructed by applying optimality principle is called optimality principle routing table.

Dynamic Routing Algorithm

↳ Distance Vector Routing Algo

In this algo, initially path is adaptive



Each and every node have a routing table and initially it contains info about its neighbour only.

	A	B	C	D	E	F
A	0	5	1	-	-	-
B	5	0	-	4	-	-
C	1	-	0	-	1	2
D	-	4	-	0	-	3
E	-	-	1	-	0	1
F	-	-	2	3	1	0

After every regular interval of time, each router

A	0	0	0
B	5	5	5
C	1	1	1
D	-	9	6
E	-	2	2
F	-	3	3

B	5	5	5
B	0	0	0
C	-	6	6
D	4	4	4
E	-	7	7
F	-	7	7

C			
A	1	1	1
B	-	6	6
C	0	0	0
D	-	5	5
E	1	1	1
F	2	2	2

D			
A	-	9	6
B	4	4	4
C	-	5	5
D	0	0	0
E	-	4	4
F	3	3	3

E			
A	-	2	2
B	-	-	7
C	1	1	1
D	-	4	4
E	0	0	0
F	1	1	1

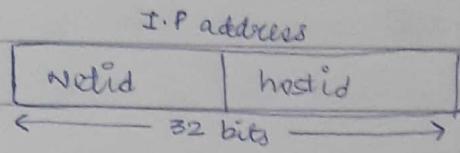
F			
A	-	3	3
B	-	7	7
C	2	2	2
D	3	3	3
E	1	1	1
F	0	0	0

Q After how many rounds the routing table is stabilized.
3

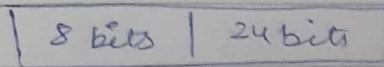
The link from C to E is down.

Provide the routing table of A

Want to a problem



- Note 1. All zeroes in hostid field is reserved for network address
 2. All ones in hostid field is reserved for broadcast address



N₁ 0000 0001 0000 0000 0000 0000 0000

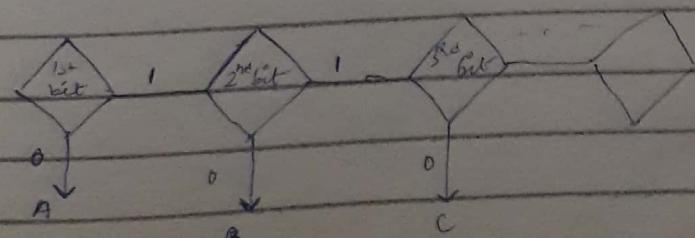
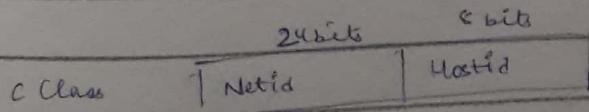
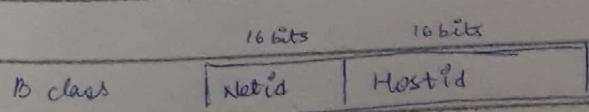
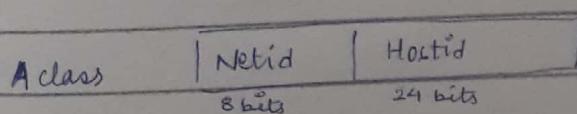
h₁, N₁ 0000 0001 0000 0000 0000 0000 0001

broadcast N₁ 0000 0001 1111 1111 1111 1110

Sche

1.

2.



max no. of networks 2^7
max no. of hosts in each network $2^4 - 2$

B class 2^{16-2} $2^{16} - 2$

C class 2^{24-3} 2^{8-2}

e.g. 192.168.10.230

$\underbrace{1100\ 0000}_{\downarrow \text{C class}}.\ 1010\ 0000.\ 0000\ 1010.\ 1110\ 0110$

net id = 24 bits

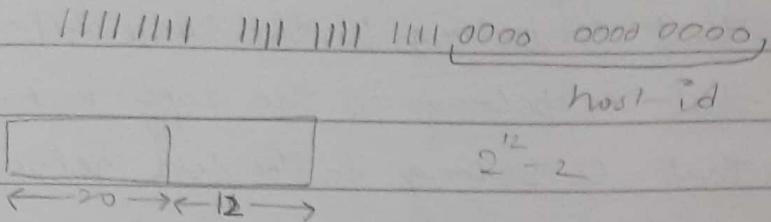
Network address = 192.168.10.0

Masking

It is the concept of identifying the network address of a given host address. In masking IP address is bits wise anded with mask address to determine the network address.

In mask address no. of bits zeroes in host id field indicates no. of bits in host id field, and no. of ones indicate no. of bits in network id.

Q. Determine the max. no. of host possible in a network having mask address 255.255.240.0



Q. Determine the network address of a host having IP address and 255.255.224.0 mask address.

$$\begin{array}{r}
 10010110 01100100 00110010 00011001 \\
 + 11111111 11111111 11100000 00000000 \\
 \hline
 150 \cdot 100 \cdot 32 \cdot 0
 \end{array}$$

Q. Determine the network address.

- (a) 100.200.100.50 Network: 100.0.0.0 Class: A 128 to 191
- (b) 150.250.100.75 Network: 150.250.100.0 Class: C 192 to 223
- (c) 200.100.10.20 Network: 200.100.10.0
- (d) 100.50.10.20 Network: 100.0.0.0

A class 0 to 127

B class 128 to 191

C class 192 to 223

Q4 (a)

(a) 100.200.100.50 Network: 100.100.96.0

IP: 255.255.224.0

$\begin{array}{r} 11100000 \\ 01100100 \end{array}$

(b) 150.150.150.150 Network: 150.150.150.148

IP: 255.255.255.252 Network: $\begin{array}{r} 11111100 \\ 10011000 \end{array}$

A IP: 192.168.10.230 Network: 192.168.10.224

mask: 255.255.255.240 Network: 11100000

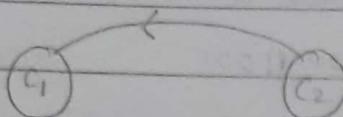
B IP: 192.168.10.180 Network: 192.168.10.176

mask: 255.255.255.240 Network: $\begin{array}{r} 11100000 \\ 10110000 \end{array}$

C_1 and C_2 computers have above IP and mask address resp.

Which of the following statement is true.

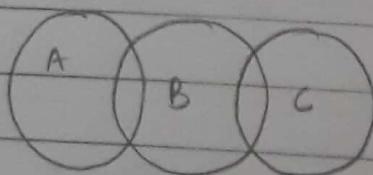
- (i) C_1 assumes that C_2 belongs to the same network but C_2 assumes that C_1 belongs to the diff network.
- (ii) C_1 assumes that C_2 belongs to the diff network but C_2 assumes that C_1 belongs to same network.
- (iii) C_1 and C_2 both assumes that they belong to same network
- (iv) C_1 and C_2 both assumes that they belong to different network



C_2 IP	192.168.10.180	1011 0100
C_1 Mask	255.255.255.224	1110 0000
	<hr/>	<hr/>
	192.168.10.160	1010 0000

C_1 IP	192.168.10.230	1110 0110
C_2 Mask	255.255.255.240	1111 0000
	<hr/>	<hr/>
	192.168.10.224	1110 0000

Adhoc Network



Radio range

Mobile adhoc

Sensor

VANET

adhoc network works on battery
Dynamic Topology
Security - less

Wlan

Q IP address of host 1 of S1

192.168.20.33

IP address of first last host of S1

192.168.20.62

Subnet mask of S1 - 255.255.255.224

Subnet mask of S2 - 255.255.255.224

first host of S2 - 192.168.20.65

last host of S2 - 192.168.20.94

broadcast add. of S2 - 192.168.20.95

Fixed length subnet id - when we have same no. of bits in host id field.

V

Consider an organisation is having C class network address.
Organisation wish to form 5 no. of subnets with following no. of host

S₁ - 60

S₂ - 60

S₃ - 30

S₄ - 30

S₅ - 10

Design the network

192.168.20. xxxx xxxx

to identify 60 hosts we need 6 bits.

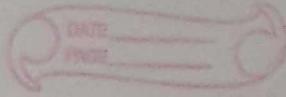
192.168.20. [-] xxxxxx

4 groups possible.

00

✓ 01

✓ 10
11



S₁ : 192.168.20.0100 0000

h₁ of S₁ → 192.168.20.65

broadcast address of S₁ - 192.168.20.127

subnet mask of S₁ - 255.255.255.192

S₂ : 192.168.20.1000 0000

h₁ of S₂

broadcast address of S₂ : 192.168.20.191

subnet mask of S₂ - 255.255.255.192

192.168.20.00xx xxxx } remaining groups
192.168.20.11xx xxxx

192.168.20.000x xxxx } 2 group for 30 hosts
✓ 001x xxxx

S₃ : 192.168.20.0132 .

h₁ of S₃ : 192.168.20.33

broadcast address of S₃ : 192.168.20.63

subnet mask of S₃ : 255.255.255.224

192.168.20.110xxx ✓
1xxx
1110

S₄ : 192.168.20.192

h₁ of S₄ : 192.168.20.193

broadcast address of S₄ : 192.168.20.207

subnet mask : 255.255.255.224

S₅ : 192.168.20.224 .

h₁ of S₅ : 192.168.20.225

broadcast address of S₅ : 192.168.20.239

subnet mask : 255.255.255.240