Notes on numerical simultaneous matrix diagonalization

Fabian Schrodi

Suppose we are given a set $\{A_j\}$ of N matrices $A_j \in \mathbb{C}^{MxM}$, where $j \in \{1, ..., N\}$ and $N, M \in \mathbb{N}$. Provided that all matrices in this set pairwise commute with each other it is possible to find a common eigenbasis, which is characterized by $V \in \mathbb{C}^{MxM}$, such that $V^{-1}A_jV = D_j$ is diagonal $\forall j$. The purpose of the program is to numerically solve for the eigenvector matrix V and eigenvalues D_j .

Algorithm: We assume pairwise commutativity for the whole set of matrices, $[A_i, A_j] = A_i A_j - A_j A_i = 0 \ \forall i, j \in \{1, ..., N\}$. Further let all A_j be diagonalizable. We can then write $A_1 = U_1 D_1 U_{-1}$, or equivalently $D_1 = U_1^{-1} A_1 U_1$. With the eigenvector matrix U_1 at hand we define $A_j^{(1)} = U_1^{-1} A_j U_1$ for $j \in \{2, ..., N\}$. In the next stef we find the eigenvalue decomposition $D_2 = U_2^{-1} A_2^{(1)} U_2$ and update $A_j^{(2)} = U_2^{-1} A_j^{(1)} U_2$ accordingly. This procedure is continued until we reach $D_N = U_N A_N^{(N-1)} U_N$. The common eigenbasis is then found as $V = U_1 \cdot ... \cdot U_N = \prod_{j=1}^N U_j$, while the eigenvalues are $D_j = V^{-1} A_j V$.

An example in \mathbb{R}^{2x^2} : We choose the set $\{A_1, A_2\}$, i.e. N=2 with

$$A_1 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 2 \end{pmatrix} , A_2 = \begin{pmatrix} 2 & 4 & 0 \\ 3 & 1 & 0 \\ -1 & -4 & 1 \end{pmatrix} .$$

The diagonalization of A_1 gives $D_1 = U_1^{-1}A_1U_1$ where

$$U_1 = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} = U_1^{-1} .$$

Now we need to renormalize A_2 as

$$A_2^{(1)} = U_1^{-1} A_2 U_1 = \begin{pmatrix} 2 & -4 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

The second diagonalization then gives $D_2 = U_2^{-1} A_2^{(1)} U_2$ with

$$U_2 = \begin{pmatrix} 1 & 0 & -4 \\ 1 & 0 & 3 \\ 0 & 1 & 0 \end{pmatrix} , \ U_2^{-1} = \frac{1}{7} \begin{pmatrix} 3 & 4 & 0 \\ 0 & 0 & 7 \\ -1 & 1 & 0 \end{pmatrix} .$$

The common eigenbasis is then given by

$$V = U_1 U_2 = \begin{pmatrix} -1 & 0 & 4 \\ 1 & 0 & 3 \\ 1 & 1 & -4 \end{pmatrix} , V^{-1} = U_2^{-1} U_1^{-1} = \frac{1}{7} \begin{pmatrix} -3 & 4 & 0 \\ 7 & 0 & 7 \\ 1 & 1 & 0 \end{pmatrix} .$$

From here we can find the eigenvalues from

$$D_1 = V^{-1} A_1 V = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix} , D_2 = V^{-1} A_2 V = \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{pmatrix} ,$$

which concludes our small practical example.

Comments on the implementation Numerically it is important to catch the case of A_i and A_j , $i \neq j$, sharing common eigenvectors. In such a situation, assuming i < j, the matrix $A_j^{(i)}$ has already a diagonal form and it can be numerically unstable to diagonalize it once more (mainly due to rounding errors/numerical inaccuracies). The same holds true for all A_j , j > 1, that are diagonal from the beginning. This problem can be treated by simply skipping the diagonalization of any matrix that is diagonal up to numerical accuracy.

MATLAB code: Created with version R2013b, expected to be compatible with newer versions.