

Boosting From Different Perspectives

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Outline

1 Statistical Learning Framework

- Notation
- Chernoff Bound as an Preamble to Concentration Inequalities
- Weak V.S. PAC Learning

2 Boosting

- PAC and Weak Learning Equivalence
- Schapire's Boosting Algorithm

3 Adaboost

- Introduction to Adaboost
- Resistance to Overfitting

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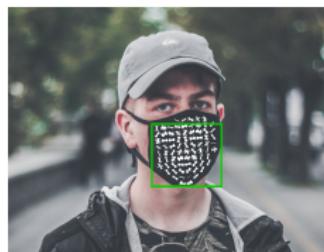
- Introduction to Adaboost
- Resistance to Overfitting

Review

Setting Up some Notation:

Data $\mathcal{S} = \{(X_i, Y_i) \in \mathcal{X} \times \{\pm 1\} : 1 \leq i \leq n\}$ represents learner's observed data where X is generated from an unknown distribution \mathcal{D} and $Y = f(X)$ for some mapping $f : \mathcal{X} \mapsto \{\pm 1\}$.

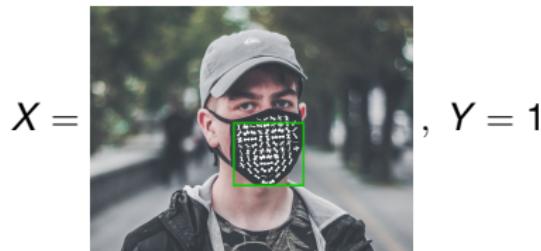
$$X = \text{[Image of a person wearing a mask]} , Y = 1$$



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Output Prediction rule from hypothesis class \mathcal{H} which contains certain mappings from \mathcal{X} into $\{\pm 1\}$. For instance, truncated linear functions $\{x \mapsto \text{sign}(\langle a, x \rangle)\}$ for $a \in \mathbb{R}^d\}$

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- Accuracy can be measured by $L_{\mathcal{D}}(h) = \mathbb{P}[h(X) \neq Y]$ which is the true error rate of a hypothesis $h \in \mathcal{H}$. **Goal** of the learner is try to minimize this.

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 - Instead, estimates it in the most natural way and minimizes that (considering it's computationally feasible). This is called expected risk minimization (ERM):

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Intuition Law of Large Numbers ensures that the estimate is close to the true rate for large enough number of samples.

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Is LLN Enough?

- Suppose $\hat{h} \in \arg \min_{h \in \mathcal{H}} L_S(h)$. We want $L_{\mathcal{D}}(\hat{h})$ to be small and close to optimum. It is enough to control $\sup_{h \in \mathcal{H}} |L_S(h) - L_{\mathcal{D}}(h)|$:

$$\begin{aligned} L_{\mathcal{D}}(\hat{h}) &\leq L_S(\hat{h}) + \sup_{h \in \mathcal{H}} |L_S(h) - L_{\mathcal{D}}(h)| \\ &\leq L_S(h^*) + \sup_{h \in \mathcal{H}} |L_S(h) - L_{\mathcal{D}}(h)| \\ &\leq L_{\mathcal{D}}(h^*) + 2 \sup_{h \in \mathcal{H}} |L_S(h) - L_{\mathcal{D}}(h)| \end{aligned}$$

- Note that $L_S(h) - L_{\mathcal{D}}(h) = \frac{1}{n} \sum_{i=1}^n \mathbf{1}_{\{h(X_i) \neq Y_i\}} - \mathbb{P}_{\mathcal{D}}[h(X) \neq Y]$

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- Chernoff's Inequality controls argument this difference but we have a sup. This is where Empirical Process Theory kicks in!
- Some sort of Uniform Law of Large Number is required...

Chernoff-Hoeffding Bound

Theorem

Let $(Z_i)_{1 \leq i \leq n} \in \{0, 1\}^n$ be the result of n trials of random coin tossing. Then we have the following concentration inequality:

$$\mathbb{P}\left[\left|\frac{1}{n} \sum_{i=1}^n Z_i - \mathbb{E}[Z_1]\right| \geq \epsilon\right] \leq 2e^{-2n\epsilon^2}$$

Remark

The tail bound is asymptotically sharp due to *Central Limit Theorem* since tail of a gaussian decays exponentially quadratic.

Proof

Let $p = \mathbb{E}[Z_1]$. Using Markov's Inequality $\mathbb{P}[X \geq \alpha] \leq \alpha^{-1}\mathbb{E}[X]$ for a positive random variable X :

$$\mathbb{P}\left[\frac{1}{n} \sum_{i=1}^n Z_i - \mathbb{E}[Z_1] \geq \epsilon\right] = \mathbb{P}[e^{\lambda(\sum_{i=1}^n Z_i - n\mathbb{E}[Z_1])} \geq e^{n\lambda\epsilon}]$$

$$(\text{Markov's Inequality}) \leq e^{-n\lambda\epsilon} \mathbb{E}[e^{\lambda(\sum_{i=1}^n Z_i - n\mathbb{E}[Z_1])}]$$

$$\begin{aligned} & (\text{By Independence}) = e^{-n\lambda\epsilon} (\mathbb{E}[e^{\lambda(Z_1 - \mathbb{E}[Z_1])}])^n \\ & = e^{-n\lambda\epsilon} (pe^{\lambda(1-p)} + (1-p)e^{-\lambda p})^n \\ & = e^{-n\lambda\epsilon - n\lambda p + n \log(1-p+pe^\lambda)} \end{aligned}$$

$$(\text{Hoeffding's Lemma}) \leq e^{-n\lambda\epsilon + n\frac{\lambda^2}{8}}$$

$$(\text{Optimize over } \lambda \geq 0) = e^{-2n\epsilon^2}$$

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Notions of Learnability

Probably Approximately Correct (PAC) Learnability

A hypothesis class \mathcal{H} is called PAC learnable if for every $\epsilon, \delta, \mathcal{D}$, and f which satisfies realizability assumption provided with enough number of samples (polynomial function of $1/\epsilon, 1/\delta$) learner can return hypothesis $h \in \mathcal{H}$ such that $L_{\mathcal{D}}(h) \leq \epsilon$ holds with probability at least $1 - \delta$.

Notions of Learnability

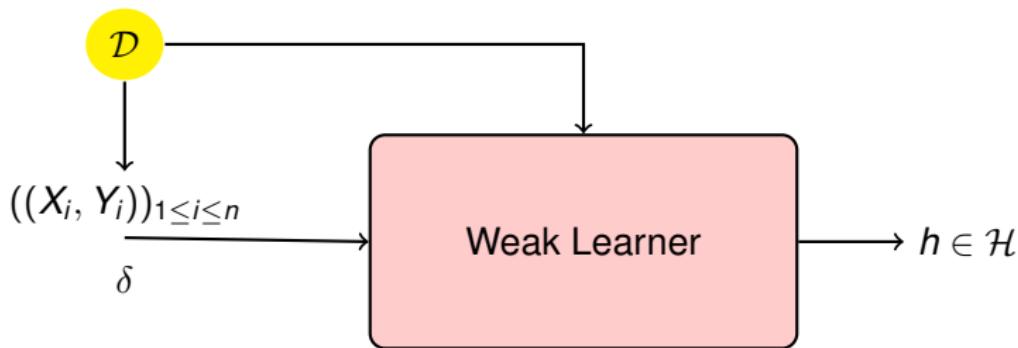
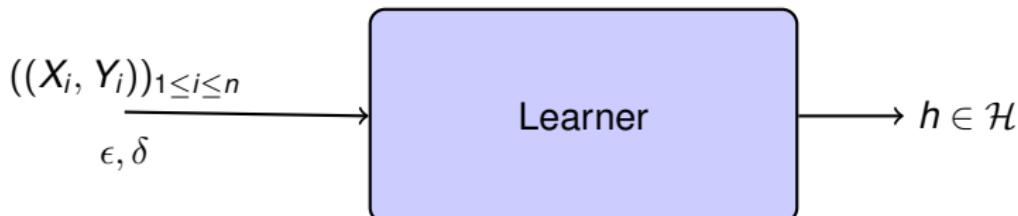
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γ -Weak-Learnability

A hypothesis class \mathcal{H} is called γ -Weak-learnable if for every δ, \mathcal{D} , and f which satisfies realizability assumption provided with enough number of samples (polynomial function of $1/\delta$) learner can return hypothesis $h \in \mathcal{H}$ such that $L_{\mathcal{D}}(h) \leq 1/2 - \gamma$ holds with probability at least $1 - \delta$.

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Is PAC Learning Stronger Than Weak Learning?

- Suppose hypothesis class \mathcal{H} is γ Weak learnable. Denote, $A = [Y_i h(X_i)]_{i,h}$ then for every $p \in \Delta([n])$ there exists $h \in \mathcal{H}$ such that:

$$\sum_{i=1}^n p_i \mathbf{1}_{\{h(X_i) \neq Y_i\}} \leq \frac{1}{2} - \gamma$$

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$$\boxed{\min_{p \in \Delta([n])} \max_{h \in \mathcal{H}} p^\top A e_h \geq 2\gamma}$$

Existence of an Ideal Booster

If we assume \mathcal{H} is finite then this can be considered as a zero-sum game between learner and booster. By Von Neumann's Minimax Theorem:

- **Booster's Strategy**

$$\min_{p \in \Delta([n])} \max_{h \in \mathcal{H}} p^\top A e_h = \max_{w \in \Delta(\mathcal{H})} \min_{i \in [n]} e_i^\top A w$$

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The diagram illustrates the minimax theorem for a zero-sum game. It features three colored circles: a red circle labeled p^\top , a blue circle labeled A , and a yellow circle labeled w . Arrows point from the text "Booster's Strategy" to the red circle and from the text "(Learner's) Payoff Matrix" to the blue circle. The equation $\min_{p \in \Delta([n])} \max_{h \in \mathcal{H}} p^\top A e_h = \max_{w \in \Delta(\mathcal{H})} \min_{i \in [n]} e_i^\top A w$ is positioned between the red and blue circles.

- (Learner's) Payoff Matrix

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- (Learner's) Payoff Matrix
- Learner's Strategy

Existence Continued

Preceeding argument implies existence of a weighted majority vote classifier which has zero training error.

$$\max_{w \in \Delta(\mathcal{H})} \min_{i \in [n]} e_i^\top Aw \geq 2\gamma > 0$$

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$$\forall i \in [n] \quad Y_i \left(\sum_{h \in \mathcal{H}} w_h^* h(X_i) \right) > 0$$

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Is it computationally tractable to find $g(X) = \text{sign} \left(\sum_{h \in \mathcal{H}} w_h^* h(X) \right)$,
though? How should we find the weights?

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Roadmap

- It is promising to learn about Booster's Minimax strategy by playing the game multiple times and learn from your mistakes.

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- The idea is to change the effective distribution $p \in \Delta([n])$ (Booster's strategy) at each round so that we can trick the learner into spreading out the error.

Roadmap

- It is promising to learn about Booster's Minimax strategy by playing the game multiple times and learn from your mistakes.
- The idea is to change the effective distribution $p \in \Delta([n])$ (Booster's strategy) at each round so that we can trick the learner into spreading out the error.
- Now by taking a majority vote over the hypotheses produced by Weak learner we can make training error zero!

Boosting Repeated Game

- Initialize: $s_0 = 0 \in \mathbb{R}^n$
- For $t = 1, \dots, T$:
 - 1- Booster picks a strategy $p_t \in \Delta([n])$.
 - 2- Weak learner picks $z_t \in \{\pm 1\}^n$ where $z_{t,i} = Y_i h_t(X_i)$ which satisfies $p_t^\top z_t \geq 2\gamma$.
 - 3- Update state $s_t = s_{t-1} + z_t$.
- Final majority vote rule is $g(X) = \text{sign}(\sum_{t=1}^T h_t(X))$.
- **Loss** for Booster is RHS and his **Goal** is to minimize training error (make it zero):

$$\sum_{i=1}^n \mathbf{1}_{\{g(X_i) \neq Y_i\}} = \sum_{i=1}^n \mathbf{1}_{\{s_{T,i} \leq 0\}} \leq \sum_{i=1}^n e^{-\eta s_{T,i}}$$

Analysis

Suppose s is the state after first $T - 1$ rounds. How should the Booster choose p_T in round T ?

- Denote, $\Lambda_T(s) := \sum_{i=1}^n \phi_T(s_i)$ where $\phi_T(s_i) = e^{-\eta s_i}$. He should pick p which attains the min below:

$$\Lambda_{T-1}(s) := \min_{p \in \Delta([n])} \max_{\substack{z \in \{\pm 1\}^n \\ p^\top z \geq 2\gamma}} \Lambda_T(s + z)$$

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- By the same argument if we assume s is the state after $t - 1$ rounds of play we can define total incurred loss of the booster as:

$$\Lambda_{t-1}(s) := \min_{p \in \Delta([n])} \max_{\substack{z \in \{\pm 1\}^n \\ p^\top z \geq 2\gamma}} \Lambda_t(s + z)$$

Value of the Game

- The minimum possible total loss achievable by Booster against an optimal Learner becomes:

$$\min_{p_1 \in \Delta([n])} \max_{\substack{z_1 \in \{\pm\}^n \\ p_1^\top z_1 \geq 2\gamma}} \min_{p_2 \in \Delta([n])} \max_{\substack{z_2 \in \{\pm\}^n \\ p_2^\top z_2 \geq 2\gamma}} \cdots \min_{p_T \in \Delta([n])} \max_{\substack{z_T \in \{\pm\}^n \\ p_T^\top z_T \geq 2\gamma}} \Lambda_T \left(\sum_{t=1}^T z_t \right)$$

- Booster tries to make this value less than one in order to obtain zero training error.
- Unfortunately this expression is unwieldy and it's not clear there exists an efficient algorithm to compute the best strategy.
- Instead, we work with a **tractable** upper bound.

Toward Decomposition on States

- The trick is to somehow rid of intertwined coordinates.

$$\begin{aligned}\Lambda_{t-1}(s) &= \min_{p \in \Delta([n])} \max_{\substack{z \in \{\pm 1\}^n \\ p^\top z \geq 2\gamma}} \Lambda_t(s + z) \\ &= \min_{p \in \Delta([n])} \max_{z \in \{\pm 1\}^n} \min_{\lambda \geq 0} \Lambda_t(s + z) + \lambda(p^\top z - 2\gamma) \\ &\leq \min_{p \in \Delta([n])} \min_{\lambda \geq 0} \max_{z \in \{\pm 1\}^n} \Lambda_t(s + z) + \lambda(p^\top z - 2\gamma) \\ &= \min_{q \in \mathbb{R}_+^n} \max_{z \in \{\pm 1\}^n} \Lambda_t(s + z) + q^\top(z - 2\gamma)\end{aligned}$$

- Define recursively:

$$\phi_{t-1}(s_i) := \min_{q_i > 0} \max_{z_i \in \{\pm 1\}} \phi_t(s_i + z_i) + q_i(z_i - 2\gamma)$$

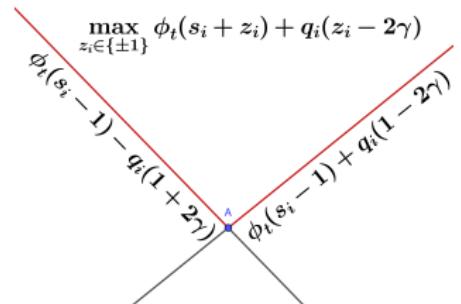
Claim. $\forall t \quad \Lambda_t(s) \leq \sum_{i=1}^n \phi_t(s_i)$

Proof. Backward induction on t :

$$\begin{aligned}\Lambda_{t-1}(s) &\leq \min_{q \in \mathbb{R}_+^n} \max_{z \in \{\pm 1\}^n} \Lambda_t(s + z) + q^\top(z - 2\gamma) \\ &\leq \min_{q \in \mathbb{R}_+^n} \max_{z \in \{\pm 1\}^n} \sum_{i=1}^n \phi_t(s_i + z_i) + q_i(z_i - 2\gamma) \\ &= \sum_{i=1}^n \min_{q_i \geq 0} \max_{z_i \in \{\pm 1\}} \phi_t(s_i + z_i) + q_i(z_i - 2\gamma) \\ &= \sum_{i=1}^n \phi_{t-1}(s_i)\end{aligned}$$

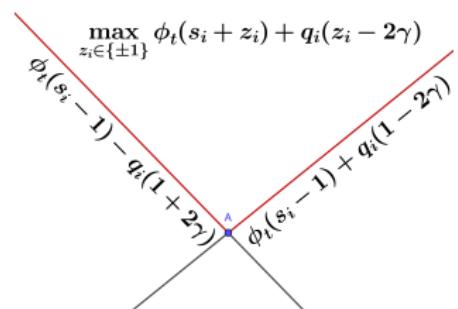
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- $\phi_t(s_i + z_i) + q_i(z_i - 2\gamma)$ is linear in q_i



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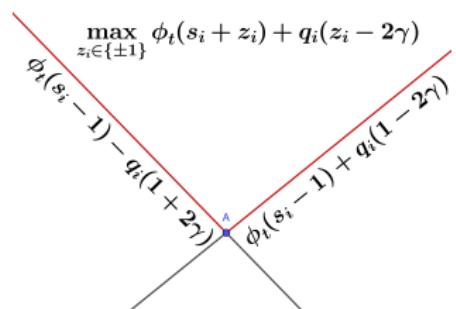
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$$q_i = \frac{\phi_t(s_i + 1) - \phi_t(s_i - 1)}{2}$$

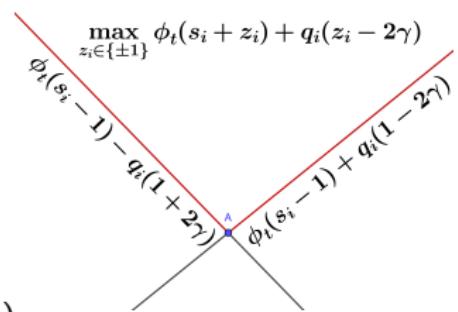


Achieving The Bound

- $\phi_t(s_i + z_i) + q_i(z_i - 2\gamma)$ is linear in q_i
- **Intersection point achieves the Minimax.**

$$q_i = \frac{\phi_t(s_i + 1) - \phi_t(s_i - 1)}{2}$$

$$\phi_{t-1}(s_i) = \left(\frac{1}{2} + \gamma\right)\phi_t(s_i + 1) + \left(\frac{1}{2} - \gamma\right)\phi_t(s_i - 1)$$



Booster's Strategy

- Solution to the recursion formula becomes:

$$\phi_t(s_i) = \left(\left(\frac{1}{2} + \gamma \right) e^{-\eta} + \left(\frac{1}{2} - \gamma \right) e^{+\eta} \right)^{T-t} e^{-\eta s_i}$$

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$$p_{t,i} \propto q_i \propto e^{-\eta s_{t-1,i}}$$

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Intuition Booster tries to weigh more on **hard** samples to force the Weak learner to learn that sample...

Suppose Booster plays the proposed strategy and encounters states s_0, s_1, \dots, s_T .

Claim.

$$\sum_{i=1}^n \phi_T(s_{T,i}) \leq \sum_{i=1}^n \phi_{T-1}(s_{T-1,i}) \leq \dots \leq \sum_{i=1}^n \phi_0(s_{0,i})$$

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Proof.

$$\begin{aligned}\sum_{i=1}^n \phi_{t-1}(s_{t,i}) &= \sum_{i=1}^n \min_{q_i \geq 0} \max_{z_i \in \{\pm 1\}} \phi_t(s_{t,i} + z_i) + q_i(z_i - 2\gamma) \\ &= \sum_{i=1}^n \max_{z_i \in \{\pm 1\}} \phi_t(s_{t,i} + z_i) + q_{t,i}(z_i - 2\gamma) \\ &\geq \sum_{i=1}^n \phi_t(s_{t,i} + z_{t,i}) + \underbrace{\sum_{i=1}^n q_{t,i}(z_{t,i} - 2\gamma)}_{\geq 0}\end{aligned}$$

Suppose Booster plays the proposed strategy and encounters states s_0, s_1, \dots, s_T .

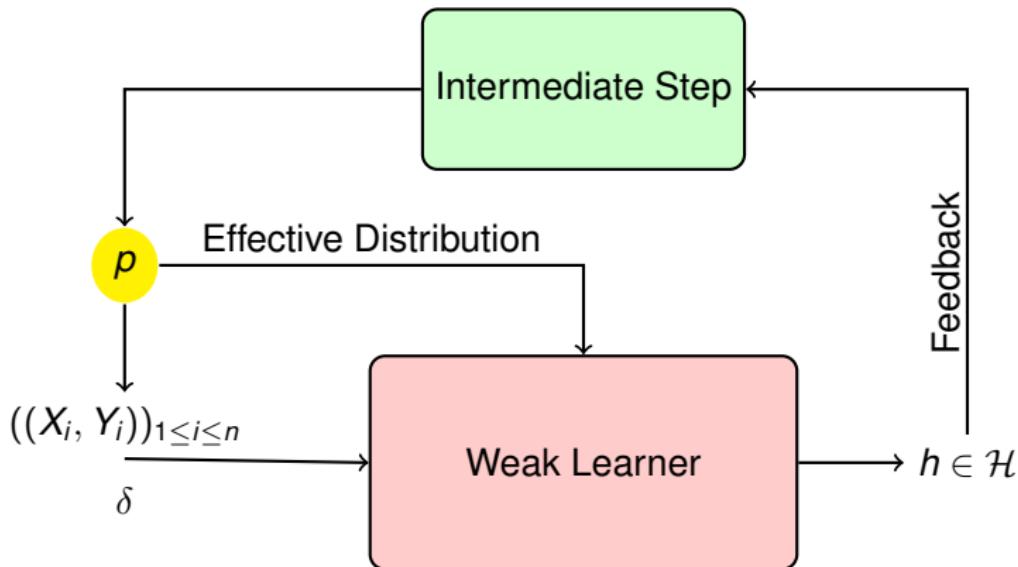
Claim. $\sum_{i=1}^n \phi_T(s_{T,i}) \leq \sum_{i=1}^n \phi_{T-1}(s_{T-1,i}) \leq \dots \leq \sum_{i=1}^n \phi_0(s_{0,i})$

$$\begin{aligned}\text{Training Error} &= \sum_{i=1}^n \mathbf{1}_{\{s_{T,i} \leq 0\}} \leq \sum_{i=1}^n e^{-\eta s_{T,i}} = \sum_{i=1}^n \phi_T(s_{T,i}) \\ &\leq \sum_{i=1}^n \phi_0(s_{0,i}) = n\phi_0(0)\end{aligned}$$

$$(\text{Optimize over } \eta) = n\left(\frac{1}{2} + \gamma\right)e^{-\eta} + \left(\frac{1}{2} - \gamma\right)e^{+\eta})^T$$

$$(\text{Setting } \eta = \frac{1}{2} \log(\frac{1/2 + \gamma}{1/2 - \gamma})) = n(1 - 4\gamma^2)^{\frac{T}{2}} \xrightarrow{T \rightarrow \infty} 0$$

Boosting Algorithm Flowchart



Outline

1 Statistical Learning Framework

- Notation
- Chernoff Bound as an Preamble to Concentration Inequalities
- Weak V.S. PAC Learning

2 Boosting

- PAC and Weak Learning Equivalence
- Schapire's Boosting Algorithm

3 Adaboost

- **Introduction to Adaboost**
- Resistance to Overfitting

AdaBoost

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- Final majority vote becomes $g(X) = \text{sign}\left(\sum_{t=1}^T \eta_t h_t(X)\right)$

AdaBoost

Theorem

Suppose the weak learning algorithm, when called by AdaBoost, generates hypotheses with advantages $\gamma_1, \dots, \gamma_T$. Then the final bound on number of misclassified examples by the majority vote becomes:

$$n \prod_{t=1}^T \sqrt{1 - 4\gamma_t^2}$$

Remark

γ_t does not require to be positive which corresponds to a classifier better than random guessing and the bound still holds.

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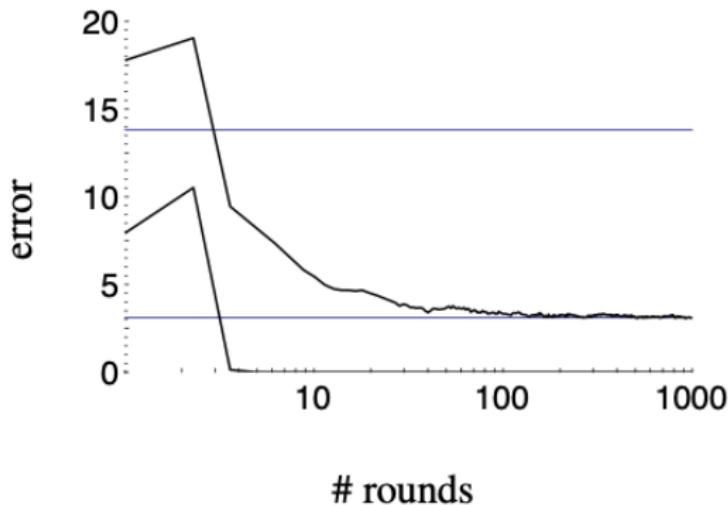
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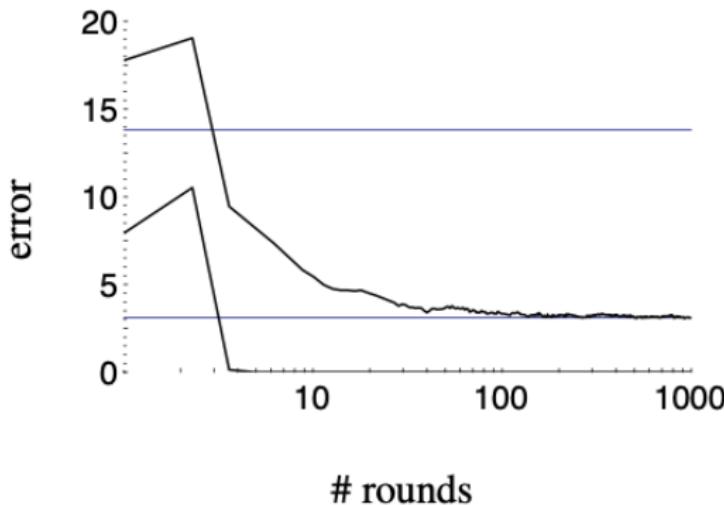
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Paradox

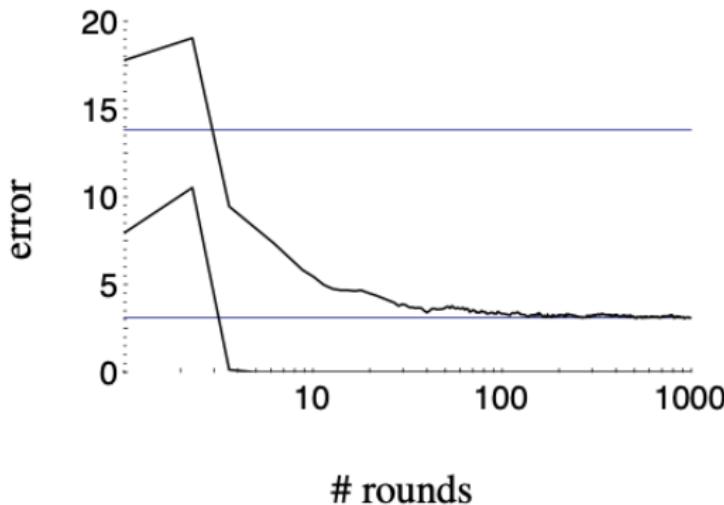


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- A How can it be that **complex** combined classifiers are performing well? Why test error flattens?

Paradox



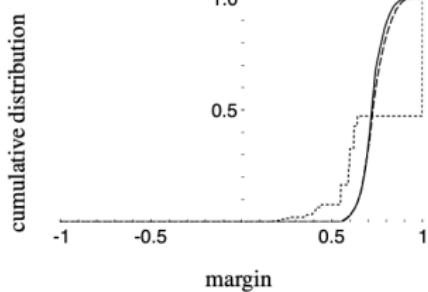
- A How can it be that **complex** combined classifiers are performing well? Why test error flattens?!
- B How come training error is zero but **test error** is still reducing?

Is a simpler classifier a better one?

- One might say η_t are rapidly converging to zero so the number of classifiers combined is effectively bounded.
 - This is **not true** since if $\eta_t = \frac{1}{2} \log(\frac{1/2 + \gamma_t}{1/2 - \gamma_t})$ goes to zero then γ_t must go to zero but it stays around 44-45% in this dataset.
 - This indicates **resistance** to overfitting! Don't get me wrong, though, there are cases which AdaBoost overfits. This happens when we use very weak base classifiers...

Margin Theory

- Additional information lies in the confidence of our prediction, i.e., $|g(X)|$ which is the margin corresponding to that sample.
- The confidence in our predictions increases significantly with additional rounds of AdaBoost
- There is a Generalization theorem by Schapire and other peers which relates true error with empirical distribution of the margin...



Conclusion

- We showed boosting had its roots in a purely theoretical question.
- Proved existence of an ideal Majority Vote Booster and then attempted to give an algorithm to find such classifiers.
- We proved training error can be very small (even zero) after enough number of iterations.
- We Introduced AdaBoost which was basically an adaptation from the boosting algorithm stated.
- We gave some intuition on how Boosting resist to overfit.

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