House Mate Controller Service Design Document

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Introduction

This document describes the high-level design approach and implementation of the House Mate Controller Service(HMCS) and the problems that it solves. This is accomplished using class diagrams, sequence diagrams, use cases, class descriptions etc. to provide a UML view of the HMCS.

Overview

The House Mate Controller Service(HMCS) augments the House Mate Model Service(HMMS). The HMMS creates digital representations of Houses and their occupants. By default, Houses (comprising appliances, sensors, rooms) and occupants created by HMMS simulate a "basic" living space. By basic, the buildings do not implement IoT. IoTs define smart homes as they can accomplish the following,

- Improve the occupants' safety
- Improve the occupants' comfort
- Monitors occupant status and location
- Restock home resources
- Execute real time commands from occupants etc.

HMCS is the central mind that attaches the IoT intelligence and features to the Houses and elements created by the HMMS.

Requirements

This section defines the requirements for the House Mate Controller Service. The House Mate Controller Service should support the following functions:

- Monitor Sensor and Appliances for status updates.
- Apply rules that respond to the status updates from sensors and appliances and generate actions.
- Sensor input includes voice commands received via the Ava devices. Note that Ava devices are now considered appliances since they can provide voice feedback to occupants.
- In response to actions, generate and send control messages to Appliances.

The House Mate Controller Service should use the interface of the House Mate Model Service to monitor the status of each of the IOT devices installed within the houses. In response to inputs, the Controller Service will use rules to invoke actions. The actions will be executed through the appliance controls.

All rule execution and resulting actions should be logged.

Additional requirements

- The HMCS should implement command and observer pattern between the HMMS and HMCS
- Use the HMMS knowledge graph to track the location and status of occupants
- All rules execution and resulting actions should be logged

Sensor, Stimulus, Rule, Action

The following Stimulus table defines the behavior for the HMCS. The HMCS will monitor all sensors and appliances for each of the houses and rooms. For each stimulus, apply the appropriate rule and action.

Stimulus Table

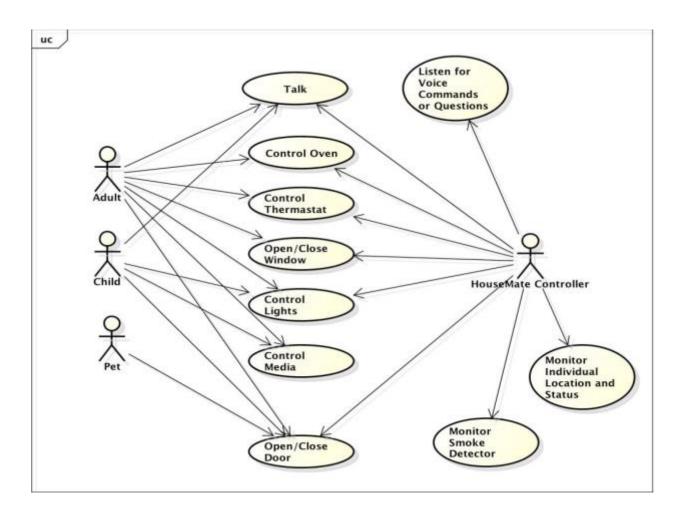
Sensor/Appliance	Stimulus	Rule	Action
Ava	Command: "open	open the door to the	set door status to
	door"	room	open.
Ava	Command: "close	close the door to the	set door status to
	door	room	closed
Ava	Command: "lights	turn off all the lights	
	off"	in the room	set light status to off
Ava	Generic Command:	send the command	forward command to
	"appliance_type	to appliance with	appliance and echo
(light color change)	status_name value"	matching type in the	command via Ava.
		current room.	
Ava	Question: "where is	use the Knowledge	send response to
	<occupant_name>?"</occupant_name>	Graph to determine	Ava. "Rover
	For example, "where	location of occupant.	is_located_in
	is Rover?"		kitchen"
Camera	Occupant detected.	turn on the lights in	send command to
		the room, and	turn lights on,
		increase the	increase the
		thermostat	temperature of the
			thermostat, update
			location of occupant
			in the KG

Camera	Occupant leaving	if no more occupants are in the room, then turn the lights off, and lower the thermostat	turn off lights, decrease the temperature of the thermostat, Update the location of occupant in the KG.
Camera	Occupant is inactive	if the only occupant, dim the lights and update the status of the occupant to resting.	update occupant status in KG to resting.
Camera	Occupant is active	update occupant status to active	update occupant status in KG to be active.
Smoke Detector	Mode Fire	if occupants are in the house, turn on all lights in the house and ask occupants to leave the house. If room has a window and is on the first floor, recommend exiting through the window. Call 911 to let them know there is a fire.	send command to turn on lights send AVA text to speech: "Fire in the Kitchen, please leave the house immediately". Call 911
Oven	TimeToCook goes to 0	if oven is on, turn oven off and alert occupants that food is ready.	Turn oven off. send Ava text to speech. "Food is ready"
Refrigerator	Beer count changes.	If beer count is less than 4, ask Occupant if they would like to order more beer. If occupant says yes, order more beer.	Send email to store requesting more beer

Use Cases

The HMCS supports two primary use cases:

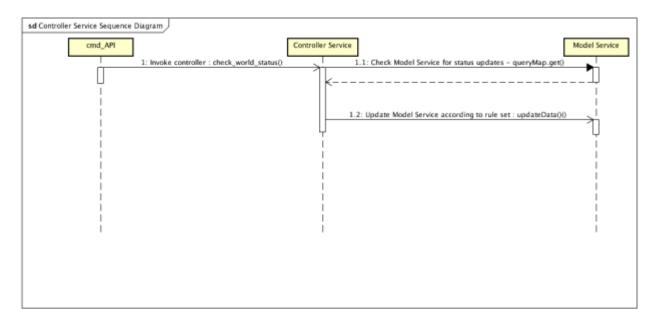
- 1. The HMCS constantly monitors the HMMS knowledge graph for new commands, occupant location or potential safety indicator
- 2. The HMCS executes the commands and updates the KG accordingly



As shown by the diagram above, The HMCS constantly identifies commands and updates that it executes to implement IoT within the HMMS defined home. Simply put, HMCS adds "user defined" intelligence to the HMMS elements.

Sequence Diagram

The Diagram below



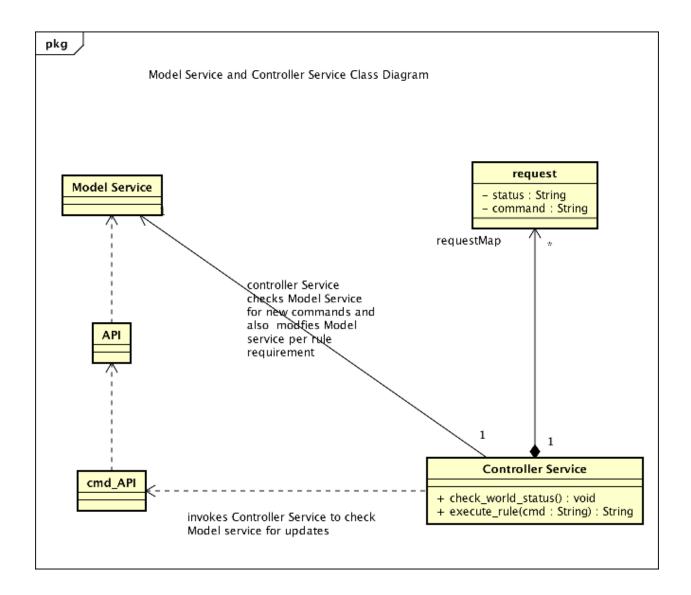
As shown by the sequence Diagram above, for every HMMS specification line read by cmd API

- cmd_API invokes Controller Service to check for new commands/updates with check_world_status().
- Controller service uses queryMap.get() to check for new commands from sensors and appliances. queryMap.get executes as automatic response by either returning all commands.
- Controller service identifies any new commands by the command pool returned by queryMap.get()
- Controller Service saves the new command
- Controller Services executes the new commands according to in-built rules
- If demanded by rule per any command, the Controller Service uses updateData() to update the HMMS

Implementation

Class Diagram

The following diagram defines the House Mate Controller Service Classes contained with the package "cscie97.asn3.housemate.controller".



Class Dictionary

This section specifies the class dictionary for the House Mate Controller service. The classes should be defined within "cscie97.asn3.housemate.controller".

Request Class

As its name implies, the request class stores all commands issued by appliances and sensors. This is a command pattern implementation where an instance is created per request and also saved. It comprises two attributes,

Properties

Method Name	Туре	Description
command	String	Public member that stores
		the sensor or appliance
		command. For example,
		"AVA1 input close_door".
status	String	Public member that stores
		the status of the command
		which can either be "open"
		or "closed".

Controller Service Class

The Controller Service is a singleton design Class which uses command pattern to store new commands, executes the command applies observer pattern to update the knowledge graph/ HMMS elements. The HMCS is invoked by cmd_API. The relationship between the Controller Service (HMCS), cmd_API and Model Service (HMMS) is described in the sequence diagram on page 5.

Methods

Method Name	Signature	Description
Check_world_status	():void	Public member that does the
		following
		- Checks for new
		commands
		- Stores new command
		 Sends command to
		execute_rule() for
		further processing
		 Updates stored
		command status as
		closed if command

		was correctly
		executed
execute_rule	(cmd:String):String	Public member that executes
		the command and uses
		obkect pattern to update the
		KG or HMMS element(s)

Association

Association Name	Туре	Description
requestMap	Map <integer, request=""></integer,>	Public associations that
		stores all new commands,
		whether valid or invalid. The
		request is mapped by a
		hashcode() generated from
		its command

Implementation details

The above described design implementation for the House Mate Controller Service meets the requirements as follows

- 1) With every HMMS update, the HMCS checks the Knowledge graph/HMMS for any new commands and updates
- 2) The execute_rule() method takes a command argument and executes it according to preset rules as described in the stimulus table
- 3) "AVA" type devices are classified as appliances.
- 4) All commands are logged and status indicated
- 5) All resulting actions from commands are printed to standard output. This approach simplifies viewing all commands and respective resulting actions in context
- 6) Control messages are sent to appliances as indicated by rule.
- 7) A request instance is created for every new command satisfying the command pattern requirement
- 8) The execute_rule() method is able to send several control messages to appliances per rule requirement. This satisfies the observer pattern.

Exception Handling

The HMMS handles majority of any errors or exceptions. However, the HMCS throws one exception which is described below

ControllerCommandException: This exception is thrown in either of the following events

- The specified command is generated by the wrong appliance or sensor
- The command cannot be matched to any specific rule or stimuli in the stimulus table

Testing

- 1) Functional testing The Controller Service will successfully identify and execute all valid commands with the accurate syntax and matching stimuli
- 2) Performance testing The Controller service performance is dependent on the processing speed, memory speed and available memory of the host computer. Its speed is also dependent on the number of HMMS elements that need to be updated after a request is processed
- 3) Exception handling: The Controller service is case sensitive but it always identifies undocumented commands or documented commands generated by the wrong devices.

Risks

Because of the in-memory implementation, the number of house, room, occupant, sensor and appliance instances are limited by the memory allocated to the JVM.