Extending the Cooperative Dual-Task Space in Conformal Geometric Algebra

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APPENDIX

A. Derivation of the Jacobian of the exponential map

The exponential map is a mapping from bivectors to motors, i.e. $B=\log(M)$. The parameters of the motor and bivector are as follows

$$M = m_1 + m_2 \mathbf{e}_{23} + m_3 \mathbf{e}_{13} + m_4 \mathbf{e}_{12} + m_5 \mathbf{e}_{1\infty} + m_6 \mathbf{e}_{2\infty} + m_7 \mathbf{e}_{3\infty} + m_8 \mathbf{e}_{123\infty},$$

and

$$B = b_1 e_{23} + b_2 e_{13} + b_3 e_{12} + b_4 e_{1\infty} + b_5 e_{2\infty} + b_6 e_{3\infty}.$$

Since a motor is a product of a translator T and a rotor R, we can find the exponential map

$$\begin{split} M &= TR, \\ T &= \left(1 - \frac{1}{2}(b_4\boldsymbol{e}_{1\infty} + b_5\boldsymbol{e}_{2\infty} + b_6\boldsymbol{e}_{3\infty})\right), \\ R &= \frac{1}{\theta}\left(\cos(\frac{1}{2}\theta) - \sin(\frac{1}{2}\theta)\left(b_1\boldsymbol{e}_{23} + b_2\boldsymbol{e}_{13} + b_3\boldsymbol{e}_{12}\right)\right), \end{split}$$

where

$$\theta = \sqrt{b_1^2 + b_2^2 + b_3^2}$$

In terms of parameters the m_i and b_i this becomes

$$m_{1} = \frac{1}{\sqrt{b_{1}^{2} + b_{2}^{2} + b_{3}^{2}}} \cos\left(\frac{1}{2}\sqrt{b_{1}^{2} + b_{2}^{2} + b_{3}^{2}}\right),$$

$$m_{2} = \frac{-b_{1}}{b_{1}^{2} + b_{2}^{2} + b_{3}^{2}} \sin\left(\frac{1}{2}\sqrt{b_{1}^{2} + b_{2}^{2} + b_{3}^{2}}\right),$$

$$m_{3} = \frac{-b_{2}}{b_{1}^{2} + b_{2}^{2} + b_{3}^{2}} \sin\left(\frac{1}{2}\sqrt{b_{1}^{2} + b_{2}^{2} + b_{3}^{2}}\right),$$

$$m_{4} = \frac{-b_{3}}{b_{1}^{2} + b_{2}^{2} + b_{3}^{2}} \sin\left(\frac{1}{2}\sqrt{b_{1}^{2} + b_{2}^{2} + b_{3}^{2}}\right),$$

$$m_{5} = \frac{1}{2} (m_{1}b_{4} + m_{3}b_{6} + m_{4}b_{5}),$$

$$m_{6} = \frac{1}{2} (m_{1}b_{5} + m_{2}b_{6} - m_{4}b_{4}),$$

$$m_{7} = \frac{1}{2} (m_{1}b_{5} - m_{2}b_{5} - m_{3}b_{4}),$$

$$m_{8} = \frac{1}{2} (m_{2}b_{4} - m_{3}b_{5} + m_{4}b_{6}).$$

The non-trivial partial derivatives can then be found as

$$\frac{\partial m_1}{\partial b_1} = -\frac{1}{2} \frac{b_1}{\theta} \sin\left(\frac{1}{2}\theta\right),\,$$

$$\begin{array}{lll} \frac{\partial m_1}{\partial b_2} &=& -\frac{1}{2} \frac{b_2}{\theta} \sin \left(\frac{1}{2}\theta\right), \\ \frac{\partial m_1}{\partial b_3} &=& -\frac{1}{2} \frac{b_3}{\theta} \sin \left(\frac{1}{2}\theta\right), \\ \frac{\partial m_2}{\partial b_1} &=& \sin \left(\frac{1}{2}\theta\right) \left(\frac{b_1^2}{\theta^3} - \frac{1}{\theta}\right) - \frac{1}{2} \frac{b_1^2}{\theta^2} \cos \left(\frac{1}{2}\theta\right), \\ \frac{\partial m_2}{\partial b_2} &=& b_1 \left(\frac{b_2}{\theta^3} \sin \left(\frac{1}{2}\theta\right) - \frac{1}{2} \frac{b_2}{\theta^2} \cos \left(\frac{1}{2}\theta\right), \\ \frac{\partial m_2}{\partial b_3} &=& b_1 \left(\frac{b_3}{\theta^3} \sin \left(\frac{1}{2}\theta\right) - \frac{1}{2} \frac{b_3}{\theta^2} \cos \left(\frac{1}{2}\theta\right)\right), \\ \frac{\partial m_3}{\partial b_1} &=& b_2 \left(\frac{b_1}{\theta^3} \sin \left(\frac{1}{2}\theta\right) - \frac{1}{2} \frac{b_1}{\theta^2} \cos \left(\frac{1}{2}\theta\right)\right), \\ \frac{\partial m_3}{\partial b_2} &=& \sin \left(\frac{1}{2}\theta\right) \left(\frac{b_2^2}{\theta^3} - \frac{1}{\theta}\right) - \frac{1}{2} \frac{b_2^2}{\theta^2} \cos \left(\frac{1}{2}\theta\right), \\ \frac{\partial m_3}{\partial b_3} &=& b_2 \left(\frac{b_3}{\theta^3} \sin \left(\frac{1}{2}\theta\right) - \frac{1}{2} \frac{b_3}{\theta^2} \cos \left(\frac{1}{2}\theta\right)\right), \\ \frac{\partial m_4}{\partial b_1} &=& b_3 \left(\frac{b_1}{\theta^3} \sin \left(\frac{1}{2}\theta\right) - \frac{1}{2} \frac{b_2}{\theta^2} \cos \left(\frac{1}{2}\theta\right)\right), \\ \frac{\partial m_4}{\partial b_2} &=& b_3 \left(\frac{b_2}{\theta^3} \sin \left(\frac{1}{2}\theta\right) - \frac{1}{2} \frac{b_2}{\theta^2} \cos \left(\frac{1}{2}\theta\right)\right), \\ \frac{\partial m_4}{\partial b_3} &=& \sin \left(\frac{1}{2}\theta\right) \left(\frac{b_3^2}{\theta^3} - \frac{1}{\theta}\right) - \frac{1}{2} \frac{b_2^3}{\theta^2} \cos \left(\frac{1}{2}\theta\right), \\ \frac{\partial m_5}{\partial b_1} &=& -\frac{1}{2} \left(b_4 \frac{\partial m_1}{\partial b_1} - b_6 \frac{\partial m_3}{\partial b_1} - b_5 \frac{\partial m_4}{\partial b_1}\right), \\ \frac{\partial m_5}{\partial b_2} &=& -\frac{1}{2} \left(b_4 \frac{\partial m_1}{\partial b_1} - b_6 \frac{\partial m_3}{\partial b_2} - b_5 \frac{\partial m_4}{\partial b_2}\right), \\ \frac{\partial m_6}{\partial b_1} &=& -\frac{1}{2} \left(b_5 \frac{\partial m_1}{\partial b_1} - b_6 \frac{\partial m_2}{\partial b_1} + b_4 \frac{\partial m_4}{\partial b_1}\right), \\ \frac{\partial m_6}{\partial b_3} &=& -\frac{1}{2} \left(b_5 \frac{\partial m_1}{\partial b_1} - b_6 \frac{\partial m_2}{\partial b_1} + b_4 \frac{\partial m_4}{\partial b_1}\right), \\ \frac{\partial m_6}{\partial b_3} &=& -\frac{1}{2} \left(b_5 \frac{\partial m_1}{\partial b_1} - b_6 \frac{\partial m_2}{\partial b_2} + b_4 \frac{\partial m_4}{\partial b_2}\right), \\ \frac{\partial m_7}{\partial b_1} &=& -\frac{1}{2} \left(b_6 \frac{\partial m_1}{\partial b_1} + b_5 \frac{\partial m_2}{\partial b_1} + b_4 \frac{\partial m_3}{\partial b_1}\right), \\ \frac{\partial m_7}{\partial b_2} &=& -\frac{1}{2} \left(b_6 \frac{\partial m_1}{\partial b_1} + b_5 \frac{\partial m_2}{\partial b_2} + b_4 \frac{\partial m_3}{\partial b_2}\right), \\ \frac{\partial m_7}{\partial b_3} &=& -\frac{1}{2} \left(b_6 \frac{\partial m_1}{\partial b_1} + b_5 \frac{\partial m_2}{\partial b_2} + b_4 \frac{\partial m_3}{\partial b_2}\right), \\ \frac{\partial m_8}{\partial b_1} &=& -\frac{1}{2} \left(b_6 \frac{\partial m_1}{\partial b_1} + b_5 \frac{\partial m_2}{\partial b_2} + b_4 \frac{\partial m_3}{\partial b_1}\right), \\ \frac{\partial m_8}{\partial b_1} &=& -\frac{1}{2} \left(b_6 \frac{\partial m_1}{\partial b_1} + b_5 \frac{\partial m_2}{\partial b_1} + b_6 \frac{\partial m_4}{\partial b_1}\right), \\ \frac{\partial m_8}{\partial b_1} &=& -\frac{1}{2} \left(b_6 \frac{\partial m$$

$$\begin{array}{lll} \frac{\partial m_8}{\partial b_2} & = & -\frac{1}{2} \left(b_4 \frac{\partial m_2}{\partial b_2} - b_5 \frac{\partial m_3}{\partial b_2} + b_6 \frac{\partial m_4}{\partial b_2} \right), \\ \frac{\partial m_8}{\partial b_3} & = & -\frac{1}{2} \left(b_4 \frac{\partial m_2}{\partial b_3} - b_5 \frac{\partial m_3}{\partial b_3} + b_6 \frac{\partial m_4}{\partial b_3} \right), \\ \frac{\partial m_5}{\partial b_4} & = & -\frac{1}{2} m_1, \\ \frac{\partial m_5}{\partial b_5} & = & \frac{1}{2} m_4, \\ \frac{\partial m_5}{\partial b_6} & = & \frac{1}{2} m_3, \\ \frac{\partial m_6}{\partial b_4} & = & -\frac{1}{2} m_4, \\ \frac{\partial m_6}{\partial b_5} & = & -\frac{1}{2} m_1, \\ \frac{\partial m_6}{\partial b_6} & = & \frac{1}{2} m_2, \\ \frac{\partial m_7}{\partial b_4} & = & -\frac{1}{2} m_2, \\ \frac{\partial m_7}{\partial b_5} & = & -\frac{1}{2} m_2, \\ \frac{\partial m_7}{\partial b_6} & = & -\frac{1}{2} m_2, \\ \frac{\partial m_8}{\partial b_4} & = & -\frac{1}{2} m_2, \\ \frac{\partial m_8}{\partial b_5} & = & \frac{1}{2} m_3, \\ \frac{\partial m_8}{\partial b_5} & = & \frac{1}{2} m_3, \\ \frac{\partial m_8}{\partial b_6} & = & -\frac{1}{2} m_4. \end{array}$$