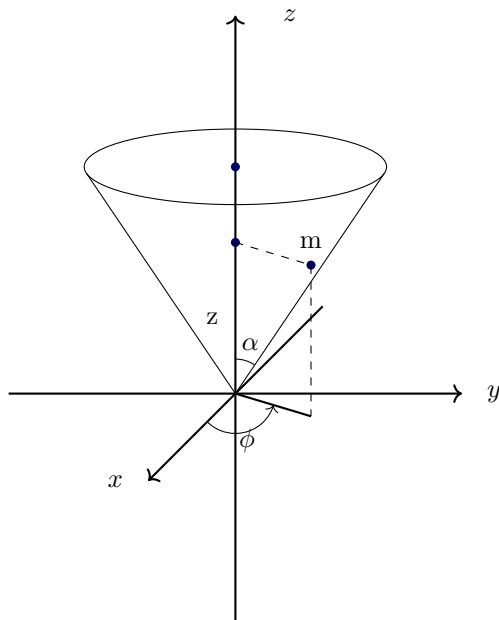


Problem 1.

One advantage of the Lagrangian formulation is that it does not commit us to any particular coordinate system - the  $q$ 's in Equation 10.6 could be Cartesian coordinates, or polar coordinates, or any other variables we might use to designate the particle's position. Suppose, for example, we want to analyze the motion of a particle that slides frictionlessly on the inside surface of a cone mounted with its axis pointing upward, as shown.



- Express  $T$  and  $U$  in terms of the variables  $z$  and  $\phi$  and the constants  $\alpha$  (the opening angle of the cone),  $m$  (the mass of the particle), and  $g$  (the acceleration of gravity).
- Construct the Lagrangian, and apply the Euler-Lagrangian equation to obtain differential equations for  $z(t)$  and  $\phi(t)$ .
- Show that  $L = (m \tan^2 \alpha) z^2 \dot{\phi}$  is a constant of the motion. What is this quantity, physically?
- Use the result in (c) to eliminate  $\phi$  from the  $z$  equation. (You are left with a second-order differential equation for  $z(t)$ ; if you want to pursue the problem further, it is easiest to invoke conservation of energy, which yields a first-order equation for  $z$ .)

Solution

(a)

Q. How can I get the equation of motion?

A. Need the velocity.

$$\mathbf{v} = \dot{r} \hat{\mathbf{r}} + r \dot{\phi} \hat{\boldsymbol{\phi}}$$

$$r = z \tan \alpha,$$

so,

$$v = z \tan \alpha \dot{\phi} + \dot{z} \tan \alpha \phi + \cancel{z \sec^2 \alpha \dot{\alpha}}$$

so,

$$T = \frac{1}{2} m (\tan \alpha)^2 (z^2 \dot{\phi}^2 + \dot{z}^2 \phi^2)$$

$$V = mgz$$

$$(b) L = T - V$$

And Euler-Lagrangian equation is,

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \left( \frac{\partial L}{\partial \dot{q}} \right) = 0$$

$$\left( \frac{m \tan^2 \alpha}{2} \right) \left( \frac{\partial(z^2 \dot{\phi}^2 + \dot{z}^2 \phi^2)}{\partial z} + \frac{\partial(z^2 \dot{\phi}^2 + \dot{z}^2 \phi^2)}{\partial \phi} - \frac{d}{dt} \left( \frac{\partial(z^2 \dot{\phi}^2 + \dot{z}^2 \phi^2)}{\partial \dot{z}} \right) - \frac{d}{dt} \left( \frac{\partial(z^2 \dot{\phi}^2 + \dot{z}^2 \phi^2)}{\partial \dot{\phi}} \right) \right) -$$

$$\frac{\partial(mgz)}{\partial z} + \frac{d}{dt} \left( \frac{\partial(mgz)}{\partial \dot{z}} \right) = 0$$

$$\text{for } z, \left( \frac{m \tan^2 \alpha}{2} \right) (2z\dot{\phi}^2 - 2\ddot{z}\phi^2 - 2\dot{z}2\phi\dot{\phi}) - mg = 0$$

$$\text{for } \phi, \left( \frac{m \tan^2 \alpha}{2} \right) (2\phi\dot{z}^2 - 2\ddot{\phi}z^2 - 2z\dot{z}2\dot{\phi}) = 0$$

Problem 2.

Derive Equation 10.17

Solution

Equation 10.17

$$\frac{\partial L}{\partial A_\nu} = \frac{1}{4\pi} \left( \frac{mc}{\hbar} \right)^2 A^\nu$$

The Proca Lagrangian for a Vector (Spin-1) Field ( $A^\mu$ ).

$$L = \frac{-1}{16\pi} (\partial^\mu A^\nu - \partial^\nu A^\mu) (\partial_\mu A_\nu - \partial_\nu A_\mu) + \frac{1}{8\pi} \left( \frac{mc}{\hbar} \right)^2 A^\nu A_\mu \quad (10.16)$$

Note for myself

From (7.71)

$$F^{\mu\nu} = \begin{bmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{bmatrix}$$

From wiki - electromagnetic tensor

$F = dA$ . where  $F$  is the electromagnetic tensor, defined as exterior derivative of the electromagnetic four-potential,  $A$ , a differential 1-form.

$F$  is an antisymmetric rank-2 tensor field.

$$F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu.$$

where  $\partial$  is the four-gradient and  $A$  is the four-potential.

This is the contravariant matrix form.

$$F^{\mu\nu} = \begin{bmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -B_z & B_y \\ E_y & B_z & 0 & -B_x \\ E_z & -B_y & B_x & 0 \end{bmatrix}$$

This is the covariant matrix form.

$$F_{\mu\nu} = \eta_{\alpha\nu} F^{\beta\alpha} \eta_{\mu\beta} = \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -B_z & B_y \\ -E_y & B_z & 0 & -B_x \\ -E_z & -B_y & B_x & 0 \end{bmatrix}$$

Q. The matrix notation for the contravariant or covariant tensors?

A. convention :

A contravariant vector :

$$v^\alpha = \begin{bmatrix} v^0 \\ v^1 \\ v^2 \end{bmatrix}$$

A covariant vector :

$$u_\alpha = [v_0, v_1, v_2]$$

ref: <https://bjlkeng.io/posts/tensors-tensors-tensors/>

$$\mathbf{u} \cdot \mathbf{v} = \sum_{i=1}^n u_i v_i$$

$$\mathbf{u} \cdot \mathbf{v} = g(\mathbf{u}, \mathbf{v}) = g_{ij} u^i v^j = [u^0, u^1] \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} v^0 \\ v^1 \end{bmatrix}$$

Q. Why  $F^{\mu\nu}$  is a square matrix? if  $F^i$  means a column matrix?

A.  $F^{ii} = F^{11} g_{11} + F^{12} g_{12}$ ? contraction is needed? not sure.

ref: <https://dasublogbyprashanth.blogspot.com/2023/11/contravariant-and-covariant-objects-in.html?m=1>