

Problem 1.

Show that $\partial\phi/\partial x^\mu$ is a covariant four-vector (ϕ is a scalar function of x , y , z , and t).

Hint: First determine (from Equation 3.8) how covariant four-vectors transform; then use $\partial\phi / \partial x^{\mu'} = (\partial\phi / \partial x^\nu)(\partial x^\nu / \partial x^{\mu'})$ transforms.

Solution

The four-vectors in x , y , z , t :

$$x^0 = ct, x^1 = x, x^2 = y, x^3 = z. \text{ Equation (3.7)}$$

Equation (3.8)

$$\begin{aligned} x^{0'} &= \gamma(x^0 - \beta x^1) \\ x^{1'} &= \gamma(x^1 - \beta x^0) \\ x^{2'} &= x^2 \\ x^{3'} &= x^3 \\ x^{\mu'} &= \sum_{\nu=0}^3 \Lambda_{\nu}^{\mu'} x^{\nu} \quad (\nu = 0, 1, 2, 3) = \Lambda_{\nu}^{\mu'} x^{\nu} \end{aligned}$$

This is a contravariant tensor.

A contravariant tensor: axes changes \rightarrow the components **inversely** change. And the vector does not change.

This is why it is called contravariant tensor.

A covariant : axes changes \rightarrow the components also changes in the same way : vector \rightarrow scalar.

A covariant vectors' components change the same as coordinates' change.

From Equation 3.8,

$$x^{0'} = \gamma(x^0 - \beta x^1) \rightarrow x'_0 = \gamma(x^0 + \beta x^1)$$

(The details are in Equation 3.1 and 3.3 , 3.3 is the inverse transform of 3.1. using the same inverse transform here.)

$$x^{1'} = \gamma(x^1 - \beta x^0) \rightarrow x'_1 = \gamma(x^1 + \beta x^0)$$

$$x'_2 = x^2$$

$$x'_3 = x^3$$

These are the covariant transform.

Q. What is the scalar function ϕ ?

The quantity I (in Equation 3.13) and $r^2 = x^2 + y^2 + z^2$ can be scalar function.
(not sure)

So, using, $I = (x^{0'})^2 - (x^{1'})^2 - (x^{2'})^2 - (x^{3'})^2$,

Since $I = x_\mu x^\mu$,

$\partial\phi / \partial x^{\mu'} = x_\mu$, covariant tensor.

https://en.wikipedia.org/wiki/covariance_and_contravariance_of_vectors

Problem 2

7.2 Show that Equation 7.17 satisfies Equation 7.15

Solution

Equation 7.15 : $\{\gamma^\mu, \gamma^\nu\} = 2g^{\mu\nu}$

Equation 7.17 : $\gamma^0 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \gamma^i = \begin{pmatrix} 0 & \sigma^i \\ -\sigma^i & 0 \end{pmatrix}$

But, here, 1 denotes the 2×2 unit matrix, and 0 is the 2×2 matrix of zeros.

$$\text{So, } \gamma^0 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}, \gamma^i = \begin{pmatrix} 0 & 0 & \sigma^i & 0 \\ 0 & 0 & 0 & \sigma^i \\ -\sigma^i & 0 & 0 & 0 \\ 0 & -\sigma^i & 0 & 0 \end{pmatrix}$$

Anticommutator $\{A, B\} = AB + BA$

So,

$$\{\gamma^0, \gamma^i\} = \gamma^0 \gamma^i + \gamma^i \gamma^0 =$$

$$\begin{aligned} & \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 0 & \sigma^i & 0 \\ 0 & 0 & 0 & \sigma^i \\ -\sigma^i & 0 & 0 & 0 \\ 0 & -\sigma^i & 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 & \sigma^i & 0 \\ 0 & 0 & 0 & \sigma^i \\ -\sigma^i & 0 & 0 & 0 \\ 0 & -\sigma^i & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \\ &= \begin{pmatrix} 0 & 0 & \sigma^i & 0 \\ 0 & 0 & 0 & \sigma^i \\ \sigma^i & 0 & 0 & 0 \\ 0 & \sigma^i & 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 & -\sigma^i & 0 \\ 0 & 0 & 0 & -\sigma^i \\ -\sigma^i & 0 & 0 & 0 \\ 0 & -\sigma^i & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \end{aligned}$$

So, is this $2g^{0i}$?

Equation (3.14) $g = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$

This is the minkowski metric, $g_{\mu\nu}$.

$g^{\mu\nu}$ is simply g^{-1} , and $g = g^{-1}$ (in a flat space time) (from wiki-minkowski metric)

However except g^{ii} or g^{00} every g is zero.