DEPARTAMENTO DE MATEMÁTICA Y FÍSICA APLICADAS

Introducción a la Programación de Elementos Finitos con FreeFem++ y su Aplicación en Mecánica de Fluidos

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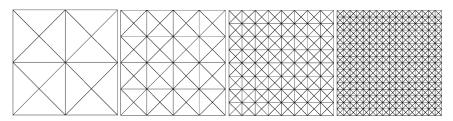
¿Qué entiendes por Método de Elementos Finitos ?

Una respuesta con un poco de historia ...

- El Método de los Elementos Finitos (MEF) es una técnica numérica usada ampliamente en el contexto de ingeniería y aplicaciones varias.
- El MEF es capaz de manejar sistemas complejos para los cuales no puede encontrarse soluciones analíticas explícitas.
- Fue desarrollado por primera vez en 1943 por Richard Courant, quien utilizó el método de Ritz del análisis numérico y la minimización del cálculo variacional para obtener soluciones aproximadas a sistemas vibrantes.
- En un artículo publicado en 1956 por M. J. Turner, R. W. Clough, H. C. Martin, y L. J. Topp, se estableció una definición más amplia del método y análisis numérico. El artículo se focalizaba en la rigidez y la deflexión de estructuras complejas. De aguí se acuñan los términos: Matriz de Rigidez y Vector de carga.

Una respuesta a grandes rasgos ...

- Dada una EDP, por ejemplo: $\begin{cases} -\mathbf{D}^{-1}\Delta\,p = f & \text{en} \quad \Omega\,, \\ p = 0 & \text{en} \quad \partial\Omega\,. \end{cases}$ (Ecuación de Darcy)
- Obtener su formulación variacional a nivel continuo en H y discreto en H_h .
- Particionar/dividir el dominio donde se quiere resolver la EDP, en elementos más pequeños y finitos:



Una respuesta a grandes rasgos ...

- Escoger espacios discretos (polinomiales) H_h contenidos en su contraparte continua H.
- Considerar funciones bases φ_n , con n la cantidad de incógnitas, tales que, cualquier función en dicho espacio de dimensión finita se pueda escribir como una combinación lineal de ellas.
- En particular, $p_h = \sum_{i=1}^{n} \alpha_i \, \varphi_i$, con α_i incógnitas a calcular.
- Mediante cálculos locales (en cada triángulo de la malla) y un proceso de ensamble de la información, generar la matriz A y el vector F globales.
- Así, el problema original se reduce a resolver el sistema de ecuaciones lineales:

$$\mathbf{A} \boldsymbol{\alpha} = \mathbf{F}$$
, con $\boldsymbol{\alpha} = (\alpha_1, \alpha_2, \dots, \alpha_n)$.

Programación del Método de Elementos Finitos con FreeFem++

FreeFem++ es un toolbox para resolver ecuaciones diferenciales parciales. Creado y desarrollado desde 1987. Su sitio oficial es: http://www.freefem.org.





Creador: Frédéric Hecht

FreeFem++: Algunos Datos Importantes

- Los programas creados con FreeFem++ pueden usarse para resolver problemas en multifísica en 2D y 3D.
- FreeFem++ es escrito en C++. Puede ser considerado como un lenguaje de programación en sí mismo.
- Es multiplataforma, se puede instalar en sistemas operativos: MacOS, Windows. y GNU-Linux.
- Para escribir los códigos, podemos utilizar cualquier editor de texto plano: vi, vim, nano, gedit, xed, notepad, etc.
- En linux-mint/ubuntu, lo podemos instalar como: sudo apt-get install FreeFem++.
- En general, lo podemos descargar desde el sitio oficial: http://www.freefem.org
- Alternativamente, podemos descargar un entorno integrado para FreeFem++: FreeFem++-cs

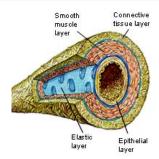
Manos al código ... iniciemos con el cursillo!!!

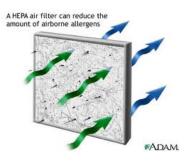
Contenidos del Cursillo

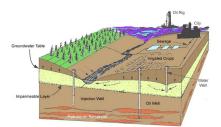
- Motivación
- Ecuación de Darcy: Formulación Primal
- Ecuación de Darcy: Formulación Mixta
- Ecuaciones de Brinkman-Forchheimer

Motivación

Algunos fenómenos físicos en mecánica de fluidos









Notaciones en 2D:
$$\Delta p = \frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2}, \ \nabla p = \left(\frac{\partial p}{\partial x}, \frac{\partial p}{\partial y}\right)^t, \ \mathbf{y} \ \mathrm{div}(\mathbf{u}) = \frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial y}$$

Ecuaciones de Darcy: presión p – velocidad \mathbf{u} y presión p

$$-\mathbf{D}^{-1}\,\Delta\,p = f \quad \text{en} \quad \Omega \Longleftrightarrow \left\{ \begin{array}{ll} \mathbf{D}\,\mathbf{u} + \nabla p = \mathbf{0} & \text{en} \quad \Omega, \\[1ex] \mathrm{div}(\mathbf{u}) = f & \text{en} \quad \Omega, \end{array} \right. , \quad p = 0 \quad \text{en} \quad \Gamma \, .$$

Ecuaciones de Stokes: velocidad u y presión p

$$-\nu \Delta \mathbf{u} + \nabla p = \mathbf{f}$$
 en Ω , $\operatorname{div}(\mathbf{u}) = 0$ en Ω , $\mathbf{u} = \mathbf{0}$ en Γ .

Ecuaciones de Brinkman-Forchheimer: velocidad \mathbf{u} y presión p

$$-\nu \Delta \mathbf{u} + \mathbf{D} \mathbf{u} + \mathbf{F} |\mathbf{u}| \mathbf{u} + \nabla p = \mathbf{f}$$
 en Ω , $\operatorname{div}(\mathbf{u}) = 0$ en Ω , $\mathbf{u} = \mathbf{0}$ en Γ .

Ecuación de Darcy: Formulación Primal

Problema modelo

$$-\mathbf{D}^{-1}\,\Delta p=f\quad\text{en}\quad\Omega\,,\quad p=0\quad\text{en}\quad\partial\Omega\,.$$

p: presión

- $\Omega \subset \mathbb{R}^n$: dominio poligonal/poliedral
- D: número de Darcy (permeabilidad)
- $\partial\Omega$: frontera de Ω

• n=2,3: dimensión del espacio

• $f \in L^2(\Omega)$

Multiplicando por una función test apropiada e integrando por partes, deducimos que

$$-\mathbf{D}^{-1}\int_{\Omega}\Delta p\,q = -\mathbf{D}^{-1}\int_{\partial\Omega}\frac{\partial p}{\partial n}\,\mathbf{q}\,ds + \mathbf{D}^{-1}\int_{\Omega}\nabla p\cdot\nabla q = \mathbf{D}^{-1}\int_{\Omega}\nabla p\cdot\nabla q\,.$$

Formulación variacional: Hallar $p \in H_0^1(\Omega)$ tal que

$$a(p,q) := \mathbf{D}^{-1} \int_{\Omega} \nabla p \cdot \nabla q \, = \, \int_{\Omega} f \, q =: F(q) \qquad \forall \, q \in H^1_0(\Omega) \, .$$

Tiene solución?

Método de Elementos Finitos

Espacio de Elementos Finitos ($H_h \subset H^1(\Omega)$):

$$H_h := \left\{ q_h \in C(\bar{\Omega}) : \quad q_h|_T \in \mathbb{P}_k(T) \quad \forall T \in \mathcal{T}_h, \ k \ge 1 \right\}$$

$$H_{h,0} := H_h \cap H_0^1(\Omega)$$

Problema discreto: Hallar $p_h \in H_{h,0}$ tal que

$$a(p_h, q_h) := \mathbf{D}^{-1} \int_{\Omega} \nabla p_h \cdot \nabla q_h = \int_{\Omega} f \, q_h =: F(q_h) \qquad \forall \, q_h \in H_{h,0} \,.$$

P1: Tiene solución?

P2: Como calcular p_h ?

P3: $||p - p_h||_{1,\Omega} \le C(p) h^k$.

 $h = \max_{T \in \mathcal{T}_h} h_T$ y h_T la mayor longitud entre dos puntos del triángulo T

Fórmula de tasa de convergencia

• Dadas dos particiones/mallas del dominio de estudio Ω , con tamaños de mallas h_{n-1} y h_n , respectivamente, se tienen las estimaciones del error

$$||p - p_{h_{n-1}}||_{1,\Omega} \le C_{n-1}(p) h_{n-1}^k \quad \mathbf{y} \quad ||p - p_{h_n}||_{1,\Omega} \le C_n(p) h_n^k,$$

donde k es el orden de convergencia del método dependiendo de la norma con la que es medida el error y el grado polinomial utilizado para dicha aproximación.

De lo anterior, deducimos que

$$\frac{\|p - p_{h_n}\|_{1,\Omega}}{\|p - p_{h_{n-1}}\|_{1,\Omega}} \approx \left(\frac{h_n}{h_{n-1}}\right)^k.$$

Así, el órden de convergencia del método puede ser calculado como:

$$k \approx \log \left(\frac{\|p - p_{h_n}\|_{1,\Omega}}{\|p - p_{h_{n-1}}\|_{1,\Omega}} \right) / \log \left(\frac{h_n}{h_{n-1}} \right) \,.$$

Llevemos a FreeFem++ nuestro primer ejemplo ...

Ejemplo 2D: Tasa de Convergencia para Formulación Primal

Solución para ilustrar tasa de convergencia teórica

- $\Omega := (0,1) \times (0,1)$
- D = 1
- $p(x,y) = \cos(\pi x)\sin(\pi y)$
- $p_x(x,y) = -\pi \sin(\pi x) \sin(\pi y)$
- $p_y(x,y) = \pi \cos(\pi x) \cos(\pi y)$
- $\bullet f = -D^{-1} (p_{xx}(x,y) + p_{yy}(x,y))$

Código FreeFEM++: Darcy-primal_2D.edp I

```
1 //
2 // This code solves the 2D Darcy problem in primal formulation
3 // with nonhomogeneous Dirichlet boundary condition
4 // - (1/D) * Delta p = f in Omega, p = pD on Gamma.
5 //
6 // Global information
7 load "iovtk"; // for saving data in paraview format
8 load "UMFPACK64": // UMFPACK solver
9 load "Element P3";
10 //----
     Initial parameters
12 //-----
13 //---- Global parameters
14 int nref = 5:
15 real[int] H(nref); // mesh size
16 real[int] DOF(nref); // degrees of freedom
17 real[int] nbT(nref); // degrees of freedom
19 //---- error
20 real[int] H1p(nref);
22 //---- rate of convergence
23 real[int] pH1rate(nref-1);
25 //
26 //----
27 //--- Data RHS
28 func p = cos(pi*x)*sin(pi*v);
29 func px = -pi*sin(pi*x)*sin(pi*y);
30 func py = pi*cos(pi*x)*cos(pi*y);
```

Código FreeFEM++: Darcy-primal_2D.edp II

```
31 func pxx = -(pi^2)*cos(pi*x)*sin(pi*y);
32 func pvy = -(pi^2)*cos(pi*x)*sin(pi*y);
34 \text{ real } D = 1.;
35 func f = -(1./D)*(pxx + pyy);
37 //--- Macros
38 macro gp [px,py] //
39 macro grad(qh) [dx(qh),dy(qh)] //
40 //-----
            Defining The Domain
41 //
42 //----
43 for(int n = 0; n < nref; n++) {
45 int size = 2^(n + 2); // space discretization
46 int Gamma = 11:
47
48 border GammaD1(t=0,1) {x=t; y=0; label = Gamma;};
49 border GammaD2(t=0,1) {x=1; v=t; label = Gamma; };
50 border GammaD3(t=1,0) {x=t; y=1; label = Gamma;};
51 border GammaD4(t=1,0) {x=0; y=t; label = Gamma; };
52
53 mesh Th = buildmesh(GammaD1(size) + GammaD2(size) + GammaD3(size) + GammaD4(size));
54 //plot(Th, wait=true);
56 // Finite element spaces
57 //-----
58 fespace Hhp(Th,P1);
59
```

Código FreeFEM++: Darcy-primal_2D.edp III

```
60 fespace Vh(Th,P1); // discrete space to compute the meshsize
             Defining the bilinear forms and RHS
63 //----
64 Hhp ph;
65 //---- bilinear forms
66 varf a(ph,qh) = int2d(Th)((1./D)*(qrad(ph)'*qrad(qh))) + on(Gamma,ph=p);
68 //---- RHS
69 varf rhs(ph,qh) = int2d(Th)(f*qh) + on(Gamma,ph=p);
71 //
           Building matrices and Load vector
72 //-----
73 matrix A = a(Hhp, Hhp);
74 //
75 real[int] RHS = rhs(0, Hhp);
76 //
77 set (A, solver = sparsesolver);
79 //---- calculating the solution
80 real[int] sol = A^-1*RHS;
81
82 //---- exporting data
83 ph[] = sol;
84
85 //---- calculating the errors
86 H1p[n] = sqrt(int2d(Th)((p - ph)^2 + (qp - qrad(ph))'*(qp - qrad(ph)));
87
88 //---- for the meshsize in Omega
```

Código FreeFEM++: Darcy-primal_2D.edp IV

```
89 Vh h = hTriangle:
90 \, H[n] = h[].max;
91 DOF[n] = Hhp.ndof;
92 \text{ nbT[n]} = \text{Th.nt};
94 //---- exporting to Praraview
95 savevtk("Data_Paraview_2D/Darcy-primal_aprox"+n+".vtk", Th, ph, dataname="ph");
96 savevtk("Data Paraview 2D/Darcy-primal exact"+n+".vtk", Th.p.dataname="p");
97 }
99 //
                         showing the tables
101 cout << " p error in H1 = " << H1p <<endl;
102 for(int n =1; n < nref; n++)
103 pH1rate[n-1] = log(H1p[n]/H1p[n-1]) / log(H[n]/H[n-1]);
104 cout << " convergence rate p in H1 = " << pH1rate <<endl;
106 cout << " mesh size = " << H <<endl:
107 cout << " degrees of freedom = " << DOF <<endl;
108 cout << " number of Triangles = " << nbT <<endl;
```

Observaciones

- El grado polinomial se puede modificar en la opción: fespace Hhp (Th, P2)
- Código simple de migrar a 3D ... hagámoslo!!!

Ejemplo 3D: Tasa de Convergencia para Formulación Primal

Solución para ilustrar tasa de convergencia teórica

- $\Omega := (0,1) \times (0,1) \times (0,1)$
- D = 1
- $p(x, y, z) = \cos(\pi x) \sin(\pi y) \exp(z)$
- $p_x(x, y, z) = -\pi \sin(\pi x) \sin(\pi y) \exp(z)$
- $p_u(x, y, z) = \pi \cos(\pi x) \cos(\pi y) \exp(z)$
- $p_z(x, y, z) = \cos(\pi x) \sin(\pi y) \exp(z)$
- $f = -D^{-1} (p_{xx}(x, y, z) + p_{yy}(x, y, z) + p_{zz}(x, y, z))$

Implementación Numérica en FreeFEM++: Darcy-primal_3D.edp I

```
2 // This code solves the 3D Darcy problem in primal formulation
3 // with nonhomogeneous Dirichlet boundary condition
4 // - (1/D) * Delta p = f in Omega, p = pD on Gamma.
5 //
6 // Global information
7 load "msh3";
8 load "medit";
9 load "iovtk":
10 load "UMFPACK64";
11 include "cube.idp";
12 //-----
13 //
         Initial parameters
14 //-----
15 //---- Global parameters
16 int nref = 5:
17 real[int] H(nref); // mesh size
18 real[int] DOF(nref); // degrees of freedom
19 real[int] nbT(nref); // degrees of freedom
21 //---- error
22 real[int] H1p(nref);
24 //---- rate of convergence
25 real[int] pH1rate(nref-1);
26 //-----
            Global data
27 //
29 //--- Data RHS
```

Implementación Numérica en FreeFEM++: Darcy-primal_3D.edp II

```
30 func p = \cos(pi*x)*\sin(pi*y)*\exp(z);
31 func px = -pi*sin(pi*x)*sin(pi*y)*exp(z);
32 func py = pi*cos(pi*x)*cos(pi*y)*exp(z);
33 func pz = cos(pi*x)*sin(pi*y)*exp(z);
34 func pxx = -(pi^2)*cos(pi*x)*sin(pi*y)*exp(z);
35 func pvv = -(pi^2)*cos(pi*x)*sin(pi*v)*exp(z);
36 func pzz = cos(pi*x)*sin(pi*y)*exp(z);
38 \text{ real } D = 1.:
39 func f = -(1./D)*(pxx + pyy + pzz);
41 //--- Macros
42 macro qp [px,py,pz] //
43 macro grad (gh) [dx (gh), dy (gh), dz (gh)] //
44 //-----
45 //
             Defining The Domain
47 for(int n = 0; n < nref; n++) {
49 int size = n^2 + n + 2.; // space discretization
50 int Gamma = 11;
51
52 int[int] NN = [size.size.size]; // the number of step in each direction
53 real[int,int] BB = [[0,1],[0,1],[0,1]];
54 int[int,int] LL = [[Gamma,Gamma],[Gamma,Gamma],[Gamma,Gamma]]; // left,right,front, back, down
        , top
55 mesh3 Th = Cube(NN, BB, LL);
56
57 //medit("cube", Th);
```

Implementación Numérica en FreeFEM++: Darcy-primal_3D.edp III

```
59 // Finite element spaces
61 fespace Hhp (Th, P13d);
63 fespace Vh(Th,P13d); // discrete space to compute the meshsize
            Defining the bilinear forms and RHS
66 //-----
67 Hhp ph:
68 //---- bilinear forms
69 varf a(ph,qh) = int3d(Th)( (1./D)*(grad(ph)'*grad(qh))) + on(Gamma,ph=p);
71 //---- RHS
72 varf rhs(ph,qh) = int3d(Th)(f*qh) + on(Gamma,ph=p);
74 //
         Building matrices and Load vector
76 matrix A = a(Hhp, Hhp);
77 //
78 real[int] RHS = rhs(0, Hhp);
79 //
80 set(A.solver = sparsesolver);
81
82 //---- calculating the solution
83 real[int] sol = A^-1*RHS:
84
85 //---- exporting data
86 ph[] = sol;
```

Implementación Numérica en FreeFEM++: Darcy-primal_3D.edp IV

```
88 //---- calculating the errors
89 H1p[n] = sqrt(int3d(Th)((p - ph)^2 + (qp - qrad(ph)))'*(qp - qrad(ph)));
91 //---- for the meshsize in Omega
92 Vh h = hTriangle;
93 H[n] = h[].max;
94 DOF[n] = Hhp.ndof;
95 \text{ nbT[n]} = \text{Th.nt};
97 //---- exporting to Praraview
98 savevtk("Data Paraview 3D/Darcy-primal aprox"+n+".vtk", Th, ph, dataname="ph");
99 savevtk("Data Paraview 3D/Darcy-primal exact"+n+".vtk", Th.p.dataname="p");
100 }
101 //----
102 //
                    showing the tables
104 cout << " p error in H1 = " << H1p <<endl;
105 for (int n =1; n < nref; n++)
106 pH1rate[n-1] = log(H1p[n]/H1p[n-1]) / log(H[n]/H[n-1]);
107 cout << " convergence rate p in H1 = " << pH1rate <<endl;
108
109 cout << " mesh size = " << H <<endl:
110 cout << " degrees of freedom = " << DOF <<endl;
111 cout << " number of Tetrahedra = " << nbT <<endl:
```

Ecuación de Darcy:

Formulación Mixta

Formulación Mixta

Problema de Darcy en formulación mixta

$$\mathbf{u} = -\mathbf{D}^{-1}\nabla p$$
 en Ω , $\operatorname{div}(\mathbf{u}) = f$ en Ω , $p = p_D$ en Γ

$$\mathbf{H}(\operatorname{div};\Omega) := \left\{ \mathbf{v} = (v_1, v_2) \in \mathbf{L}^2(\Omega) : \operatorname{div}(\mathbf{v}) \in L^2(\Omega) \right\}, \text{ con } \operatorname{div}(\mathbf{v}) = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y}.$$

Formulación variacional

Hallar $(\mathbf{u}, p) \in \mathbf{H}(\mathrm{div}; \Omega) \times L^2(\Omega)$ tal que:

$$D \int_{\Omega} \mathbf{u} \cdot \mathbf{v} - \int_{\Omega} p \operatorname{div}(\mathbf{v}) = -\langle \mathbf{v} \cdot \mathbf{n}, p_D \rangle_{\Gamma} \quad \forall \mathbf{v} \in \mathbf{H}(\operatorname{div}; \Omega),$$
$$-\int_{\Omega} q \operatorname{div}(\mathbf{u}) = -\int_{\Omega} f q \quad \forall q \in L^{2}(\Omega)$$



G.N. GATICA, A Simple Introduction to the Mixed Finite Element Method. Theory and Applications. Springer Briefs in Mathematics. Springer, Cham, 2014.

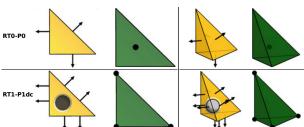
Formulación variacional discreta

Hallar $(\mathbf{u}_h, p_h) \in \mathbf{H}_h^{\mathbf{u}} \times H_h^p$ tal que:

$$\begin{split} & \mathsf{D} \int_{\Omega} \mathbf{u}_h \cdot \mathbf{v}_h - \int_{\Omega} p_h \operatorname{div}(\mathbf{v}_h) &= & - \left\langle \mathbf{v}_h \cdot \mathbf{n}, p_D \right\rangle_{\Gamma} & \forall \, \mathbf{v}_h \in \mathbf{H}_h^{\mathbf{u}} \,, \\ & - \int_{\Omega} q_h \operatorname{div}(\mathbf{u}_h) &= & - \int_{\Omega} f \, q_h & \forall \, q_h \in H_h^p \,. \end{split}$$

$$\mathbf{H}_{h}^{\mathbf{u}} := \left\{ \mathbf{v}_{h} \in \mathbf{H}(\mathrm{div}; \Omega) : \quad \mathbf{v}_{h}|_{T} \in \mathbf{RT}_{k}(T) \quad \forall T \in \mathcal{T}_{h} \right\},$$

$$H_{h}^{p} := \left\{ q_{h} \in L^{2}(\Omega) : \quad q_{h}|_{T} \in \mathbf{P}_{k}(T) \quad \forall T \in \mathcal{T}_{h} \right\}.$$



Tasas de convergencia

P1: Tiene solución?

P2: Como calcular \mathbf{u}_h, p_h ?

P3:
$$\|\mathbf{u} - \mathbf{u}_h\|_{\text{div};\Omega} + \|p - p_h\|_{0,\Omega} \le C(\mathbf{u}, p) h^{k+1}$$
, con $k \ge 0$

Manos al código ... iniciemos con nuestro tercer programa ...

Ejemplo 2D: Tasa de Convergencia para Formulación Mixta

Solución para ilustrar tasa de convergencia teórica

- $\Omega := (0,1) \times (0,1)$
- D = 1
- $p(x,y) = \cos(\pi x)\sin(\pi y)$
- $p_x(x,y) = -\pi \sin(\pi x) \sin(\pi y)$
- $p_y(x,y) = \pi \cos(\pi x) \cos(\pi y)$
- $\mathbf{u}(x,y) = -\mathbf{D}^{-1} (p_x(x,y), p_y(x,y))^{\mathrm{t}}$
- $f = -D^{-1} (p_{xx}(x, y) + p_{yy}(x, y))$

Código FreeFEM++: Darcy-mixto_2D.edp I

```
2 // This code solves the 2D Darcy problem in mixed formulation with
3 // nonhomogeneous Dirichlet boundary conditions
        u = -(1/D) * \nabla p \qin \Omega, div(u) = f in \Omega,
4 //
5 //
                     p = pD on \Gamma.
6 //
7 // Global information
8 load "iovtk"; // for saving data in paraview format
9 load "UMFPACK64"; // UMFPACK solver
10 load "Element Mixte";
          Initial parameters
12 //
13 //-----
14 //---- Global parameters
15 int nref = 5:
16 real[int] H(nref); // mesh size
17 real[int] DOF(nref); // degrees of freedom
18 real[int] nbT(nref); // degrees of freedom
20 //---- errors
21 real[int] uerror(nref);
22 real[int] perror(nref);
24 //---- rate of convergence
25 real[int] urate(nref-1);
26 real[int] prate(nref-1);
27 //-----
28 //
            Global data
```

Código FreeFEM++: Darcy-mixto_2D.edp II

```
30 //--- Data RHS
31 func p = cos(pi*x)*sin(pi*y);
32 func px = -pi*sin(pi*x)*sin(pi*y);
33 func py = pi*cos(pi*x)*cos(pi*y);
34 func pxx = -(pi^2) * cos(pi*x) * sin(pi*y);
35 func pvv = -(pi^2)*cos(pi*x)*sin(pi*v);
36 //
37 real D = 1.;
38 func f = -(1./D)*(pxx + pyy);
39 //
40 //---- Macros
41 macro u [-(1./D)*px,-(1./D)*pv] //
43 macro uh [uh1,uh2] //
44 macro vh [vh1, vh2] //
45
46 macro norm [N.x,N.v] //
47 macro div(vh) ( dx(vh[0]) + dy(vh[1]) ) //
48 //-----
49 //
      Defining The Domain
50 //----
51 for(int n = 0; n < nref; n++) {
52 //
53 int size = 2 (n + 2); // space discretization
54 int Gamma = 11;
55
56 border GammaD1(t=0,1) {x=t; y=0; label = Gamma; };
57 border GammaD2(t=0,1) {x=1; v=t; label = Gamma; };
58 border GammaD3(t=1,0) {x=t; v=1; label = Gamma; };
```

Código FreeFEM++: Darcy-mixto_2D.edp III

```
59 border GammaD4(t=1,0) {x=0; v=t; label = Gamma; };
61 mesh Th = buildmesh(GammaD1(size) + GammaD2(size) + GammaD3(size) + GammaD4(size));
62 //-----
63 // Finite element spaces
64 //-----
65 fespace Hhu (Th, RTO);
66 fespace Hhp(Th,P0);
68 fespace Vh(Th,P1); // discrete space to compute the meshsize
             Defining the bilinear forms
70 //
71 //-----
72 Hhu uh; Hhp ph;
73 //---- bilinear forms
74 varf a(uh, vh) = int2d(Th)(D*(uh'*vh));
75 varf b([ph], vh) = int2d(Th)( -(ph*div(vh)));
77 //---- RHS
78 varf rhs1(uh,vh) = int1d(Th,Gamma)( -p*(vh'*norm));
79 varf rhs2(ph,qh) = int2d(Th)( -(f*qh));
80 //----
81 //
    Building matrices
82 //-----
83 matrix A = a(Hhu, Hhu);
84 matrix B = b(Hhp, Hhu);
85
86 matrix M; {
87 M = [[A, B],
```

Código FreeFEM++: Darcy-mixto_2D.edp IV

```
88 [ B', 0]];}
                          Load vector
 91 //----
 92 real[int] RHS1 = rhs1(0, Hhu);
93 real[int] RHS2 = rhs2(0, Hhp);
 95 real[int] L = [RHS1, RHS2];
97 set (M. solver = sparsesolver);
99 //---- calculating the solution
100 real[int] sol = M^-1*L:
101
102 //---- exporting data
103 uh1[] = sol(0:Hhu.ndof - 1);
104 ph[] = sol(Hhu.ndof:Hhu.ndof + Hhp.ndof - 1);
105
106 //---- calculating the errors
107 uerror[n] = sqrt(int2d(Th)((u - uh)'*(u - uh) + (f - div(uh))^2));
108 perror[n] = sqrt(int2d(Th)((p - ph)^2));
109
110 //---- for the meshsize in Omega
111 Vh h = hTriangle;
112 \, H[n] = h[].max;
113 DOF[n] = Hhu.ndof + Hhp.ndof;
114 \text{ nbT}[n] = \text{Th.nt};
116 //---- exporting to Praraview
```

Código FreeFEM++: Darcy-mixto_2D.edp V

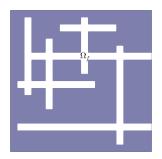
```
117 savevtk("Data_Paraview_2D/Darcy-mixto_aprox"+n+".vtk", Th, [uh1, uh2, 0], ph, dataname="uh ph");
118 savevtk("Data Paraview 2D/Darcy-mixto exact"+n+".vtk", Th, [px,py,0],p,dataname="u p");
119 }
121 //
       showing the tables
123 cout << " u error in Hdiv = " << uerror <<endl;
124 for(int n = 1; n < nref; n++)
125 urate[n-1] = log(uerror[n]/uerror[n-1]) / log(H[n]/H[n-1]);
126 cout << " convergence rate u in Hdiv = " << urate <<endl;
128 cout << " p error in L2 = " << perror <<endl;
129 for(int n =1; n < nref; n++)
130 prate[n-1] = log(perror[n]/perror[n-1]) / log(H[n]/H[n-1]);
131 cout << " convergence rate p in L2 = " << prate <<endl;
132
133 cout << " mesh size = " << H <<endl:
134 cout << " degrees of freedom = " << DOF <<endl;
135 cout << " number of Triangles = " << nbT <<endl;
```

Fluido en un medio poroso 2D con fracturas

Parámetros

•
$$\Omega = (-1,1)^2$$

$$\bullet \ \mathtt{D} = \left\{ \begin{array}{ccc} 10 & \mathsf{en} & \overline{\Omega} \setminus \Omega_{\mathrm{f}} \\ \\ 1 & \mathsf{en} & \Omega_{\mathrm{f}} \end{array} \right.$$



$$p = \left\{ \begin{array}{lll} -0.5 \, (y-1) & \text{en} & \Gamma_{\rm left} \, , \\ \\ -0.5 \, (x-1) & \text{en} & \Gamma_{\rm bottom} \, , \end{array} \right.$$

$$p = 0 & \text{en} & \Gamma_{\rm right} \cup \Gamma_{\rm top} \, , \label{eq:potential}$$

Figure: Izquierda: dominio computacional. Derecha: condiciones de contorno.

Código FreeFEM++: Darcy-mixto-fracture_2D.edp I

```
2 // This code solves the Darcy problem in mixed formulation with
3 // nonhomogeneous Dirichlet boundary conditions in a fracture domain
        u = -(1/D) * \nabla p in \Omega, div(u) = f in \Omega,
4 //
5 //
                         p = pD on \Gamma.
6 //
7 // Global information
8 load "iovtk"; // for saving data in paraview format
9 load "UMFPACK64"; // UMFPACK solver
10 load "Element_Mixte";
               Global data
12 //
13 //-----
14 //---- Global parameters
15 real H. DOF, nbT;
17 //--- Data RHS
18 real D1 = 10:
19 real D2 = 1.;
21 func pLeft = -0.5*(y-1.);
22 func pBottom = -0.5*(x-1.);
23 func f = 0.;
25 //---- Macros
26 macro uh [uh1,uh2] //
27 macro vh [vh1, vh2] //
29 macro norm [N.x, N.y] //
```

Código FreeFEM++: Darcy-mixto-fracture_2D.edp II

```
30 macro div(vh) ( dx(vh[0]) + dy(vh[1]) ) //
32 // Defining The Domain
33 //------
34 mesh Th = readmesh("Fracture network-mesh.msh");
35 // Labels setting:
36 // 33: region outside the fracture
37 // 34: region inside the fracture
38 // 1: bottom boundary
39 // 22: right and top boundaries
40 // 4: left boundary
41 //-----
42 // Finite element spaces
43 //-----
44 fespace Hhu (Th, RT0);
45 fespace Hhp(Th,P0);
46
47 fespace Vh(Th,P1); // discrete space to compute the meshsize
48 //-----
49 // Defining the bilinear forms
50 //----
51 Hhu uh; Hhp ph;
52 //---- bilinear forms
53 varf a(uh,vh) = int2d(Th,33)( D1*(uh'*vh) ) + int2d(Th,34)( D2*(uh'*vh) );
54 varf b([ph], vh) = int2d(Th)( -(ph*div(vh)));
56 //---- RHS
57 varf rhs1(uh,vh) = int1d(Th,1)( -pBottom*(vh'*norm)) + int1d(Th,4)( -pLeft*(vh'*norm));
58 varf rhs2(ph,qh) = int2d(Th)( -(f*qh));
```

Código FreeFEM++: Darcy-mixto-fracture_2D.edp III

```
Building matrices
62 matrix A = a(Hhu, Hhu);
63 matrix B = b(Hhp, Hhu);
65 matrix M: {
66 M = [[A, B],
67 [ B', 011; }
                 Load vector
70 //----
71 real[int] RHS1 = rhs1(0, Hhu);
72 real[int] RHS2 = rhs2(0, Hhp);
74 real[int] L = [RHS1, RHS2];
75
76 set (M, solver = sparsesolver);
78 //---- calculating the solution
79 real[int] sol = M^-1*L;
81 //---- exporting data
82 uh1[] = sol(0:Hhu.ndof - 1);
83 ph[] = sol(Hhu.ndof:Hhu.ndof + Hhp.ndof - 1);
84
85 //---- for the meshsize in Omega
86 Vh h = hTriangle;
87 H = h[].max;
```

Código FreeFEM++: Darcy-mixto-fracture_2D.edp IV

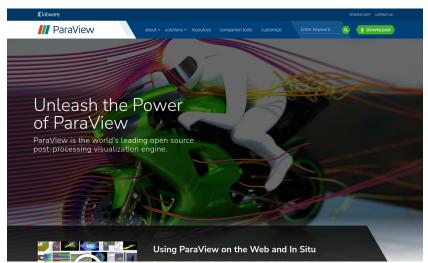
```
88 DOF = Hhu.ndof + Hhp.ndof;
89 nbT = Th.nt;
91 //---- exporting to Praraview
92 savevtk("Data Paraview 2D/Darcy-mixto-fracture aprox.vtk", Th, [uh1, uh2, 0], ph, dataname="uh ph");
                         showing the tables
96 cout << " mesh size = " << H <<endl;
97 cout << " degrees of freedom = " << DOF <<endl;
98 cout << " number of Triangles = " << nbT <<endl;
```

Observaciones

- Podemos cargar mallas creadas con malladores externos, como Gmsh o Triangle, siempre y cuando tengan el formato msh soportado por FreeFEM++
- Como este ejemplo no tiene solución analítica, realizamos un estudio cualitativo de los resultados obtenidos. Usemos ParaView!!!

ParaView como una herramienta para crear imágenes de alta calidad

https://www.paraview.org



Ecuaciones de Brinkman-Forchheimer

Formulación velocidad-presión con $\rho \in [3, 4]$:

$$-\nu\,\Delta\mathbf{u} + \mathsf{D}\,\mathbf{u} + \mathsf{F}\,|\mathbf{u}|^{\rho-2}\mathbf{u} + \nabla p = \mathbf{f} \quad \text{en} \quad \Omega, \quad \mathrm{div}(\mathbf{u}) = 0 \quad \text{en} \quad \Omega,$$

$$\mathbf{u} = \mathbf{u}_\mathrm{D} \quad \text{en} \quad \Gamma, \quad \int_{\Omega} p = 0 \,.$$

$$\boldsymbol{\sigma} := \nu \nabla \mathbf{u} - p \, \mathbf{I} \quad \text{and} \quad \mathrm{div}(\mathbf{u}) = 0 \quad \text{en} \quad \Omega \Longleftrightarrow \mathrm{tr}(\boldsymbol{\sigma}) = -n \, p \quad \text{en} \quad \Omega \, ,$$

de donde

$$p = -\frac{1}{n}\operatorname{tr}(\boldsymbol{\sigma}), \quad \text{and} \quad \boldsymbol{\sigma}^{\operatorname{d}} := \boldsymbol{\sigma} - \frac{1}{n}\operatorname{tr}(\boldsymbol{\sigma})\mathbf{I}.$$

Formulación mixta (Pseudoesfuerzo-velocidad)

$$\begin{split} \frac{1}{\nu}\, \boldsymbol{\sigma}^{\mathrm{d}} &= \nabla \mathbf{u} \quad \text{en} \quad \Omega, \quad \mathtt{D}\, \mathbf{u} + \mathtt{F}\, |\mathbf{u}|^{\rho-2} \mathbf{u} - \mathbf{div}(\boldsymbol{\sigma}) = \mathbf{f} \quad \text{en} \quad \Omega, \\ \mathbf{u} &= \mathbf{u}_{\mathrm{D}} \quad \text{en} \quad \Gamma, \quad \int_{\Omega} \mathrm{tr}(\boldsymbol{\sigma}) = 0 \end{split}$$



S. CAUCAO AND I. YOTOV, A Banach space mixed formulation for the unsteady Brinkman-Forchheimer equations. IMA Journal of Numerical Analysis, vol. 41, 4, pp. 2708-2743. (2021).

Consideremos $\rho \in [4/3, 3/2]$ tal que $1/\rho + 1/\rho = 1$

- $\bullet \ \mathbb{H}(\mathbf{div}_{\varrho};\Omega) := \left\{ \boldsymbol{\tau} \in \mathbf{L}^2(\Omega) : \quad \mathbf{div}(\boldsymbol{\tau}) \in \mathbf{L}^{\varrho}(\Omega) \right\}$
- $\mathbb{H}_0(\mathbf{div}_{\varrho};\Omega) := \left\{ \boldsymbol{\tau} \in \mathbb{H}(\mathbf{div}_{\varrho};\Omega) : \int_{\Omega} tr(\boldsymbol{\tau}) = 0 \right\}$
- Notar que $\sigma \in \mathbb{H}_0(\operatorname{\mathbf{div}}_{\rho}; \Omega)$.

Formulación variacional

Hallar $(\boldsymbol{\sigma}, \mathbf{u}) \in \mathbb{H}_0(\mathbf{div}_{\rho}; \Omega) \times \mathbf{L}^{\rho}(\Omega)$ tal que:

$$rac{1}{
u} \int_{\Omega} oldsymbol{\sigma}^{
m d} : oldsymbol{ au}^{
m d} + \int_{\Omega} oldsymbol{u} \cdot {
m div}(oldsymbol{ au}) \qquad \qquad = \quad \langle oldsymbol{ au} {
m n}, {
m u}_D
angle_{\Gamma} \; ,$$

$$\int_{\Omega} \mathbf{v} \cdot \mathbf{div}(\boldsymbol{\sigma}) - \mathbf{D} \int_{\Omega} \mathbf{u} \cdot \mathbf{v} - \mathbf{F} \int_{\Omega} |\mathbf{u}|^{\rho-2} \mathbf{u} \cdot \mathbf{v} = - \int_{\Omega} \mathbf{f} \cdot \mathbf{v} ,$$

para todo $(\boldsymbol{\tau}, \mathbf{v}) \in \mathbb{H}_0(\mathbf{div}_{\rho}; \Omega) \times \mathbf{L}^{\rho}(\Omega)$.

Formulación variacional discreta

Hallar $(\boldsymbol{\sigma}_h, \mathbf{u}_h) \in \mathbb{H}_{h,0}^{\boldsymbol{\sigma}} \times \mathbf{H}_h^{\mathbf{u}}$ tal que:

$$\begin{split} &\frac{1}{\nu} \int_{\Omega} \boldsymbol{\sigma}_{h}^{\mathrm{d}} : \boldsymbol{\tau}_{h}^{\mathrm{d}} + \int_{\Omega} \mathbf{u}_{h} \cdot \mathbf{div}(\boldsymbol{\tau}_{h}) &= \langle \boldsymbol{\tau}_{h} \mathbf{n}, \mathbf{u}_{D} \rangle_{\Gamma} , \\ &\int_{\Omega} \mathbf{v}_{h} \cdot \mathbf{div}(\boldsymbol{\sigma}_{h}) - D \int_{\Omega} \mathbf{u}_{h} \cdot \mathbf{v}_{h} - F \int_{\Omega} |\mathbf{u}_{h}|^{\rho - 2} \mathbf{u}_{h} \cdot \mathbf{v}_{h} &= - \int_{\Omega} \mathbf{f} \cdot \mathbf{v}_{h} , \end{split}$$

para todo $(\boldsymbol{\tau}_h, \mathbf{v}_h) \in \mathbb{H}_{b,0}^{\boldsymbol{\sigma}} \times \mathbf{H}_h^{\mathbf{u}}$.

$$\begin{split} \mathbb{H}_h^{\boldsymbol{\sigma}} &:= \left\{ \boldsymbol{\tau}_h \in \mathbb{H}(\mathbf{div}_{\varrho}; \Omega) : \quad \mathbf{c}^{\mathrm{t}} \boldsymbol{\tau}_h |_T \in \mathbf{RT}_k(T) \quad \forall \, \mathbf{c} \in \mathbb{R}^n, \quad \forall \, T \in \mathcal{T}_h \right\}, \\ \mathbb{H}_{h,0}^{\boldsymbol{\sigma}} &:= \mathbb{H}_h^{\boldsymbol{\sigma}} \cap \mathbb{H}_0(\mathbf{div}_{\varrho}; \Omega), \\ \mathbf{H}_h^u &:= \left\{ \mathbf{v}_h \in \mathbf{L}^{\rho}(\Omega) : \quad \mathbf{v}_h |_T \in \mathbf{P}_k(T) \quad \forall \, T \in \mathcal{T}_h \right\}. \end{split}$$

Formulación variacional discreta

Hallar $(\sigma_h, \mathbf{u}_h, \lambda_h) \in \mathbb{H}_h^{\sigma} \times \mathbf{H}_h^{\mathbf{u}} \times \mathbf{R}$ tal que:

$$\begin{split} &\frac{1}{\nu} \int_{\Omega} \boldsymbol{\sigma}_h^{\mathrm{d}} : \boldsymbol{\tau}_h^{\mathrm{d}} + \int_{\Omega} \mathbf{u}_h \cdot \mathbf{div}(\boldsymbol{\tau}_h) + \lambda_h \int_{\Omega} \mathrm{tr}(\boldsymbol{\tau}_h) &= \langle \boldsymbol{\tau}_h \mathbf{n}, \mathbf{u}_D \rangle_{\Gamma} \;, \\ &\int_{\Omega} \mathbf{v}_h \cdot \mathbf{div}(\boldsymbol{\sigma}_h) - \mathbf{D} \int_{\Omega} \mathbf{u}_h \cdot \mathbf{v}_h - \mathbf{F} \int_{\Omega} |\mathbf{u}_h|^{\rho-2} \mathbf{u}_h \cdot \mathbf{v}_h &= -\int_{\Omega} \mathbf{f} \cdot \mathbf{v}_h \,, \\ &\eta_h \int_{\Omega} \mathrm{tr}(\boldsymbol{\sigma}_h) &= 0 \,, \end{split}$$

para todo $(\boldsymbol{\tau}_h, \mathbf{v}_h, \eta_h) \in \mathbb{H}_h^{\boldsymbol{\sigma}} \times \mathbf{H}_h^{\mathbf{u}} \times \mathbf{R}$.

Notar que:

$$p = -\frac{1}{n}\operatorname{tr}(\boldsymbol{\sigma}) \quad \mathsf{y} \quad \nabla \mathbf{u} = \frac{1}{\nu}\,\boldsymbol{\sigma}^{\mathrm{d}}\,.$$

Variables postprocesadas

$$p_h = -\frac{1}{n}\operatorname{tr}(\boldsymbol{\sigma}_h) \quad \mathsf{y} \quad \mathbf{G}_h = \frac{1}{\nu}\,\boldsymbol{\sigma}_h^{\mathrm{d}}\,.$$

Estrategia Iterativa de Picard

$$\begin{split} \mathsf{Dado} \ \mathbf{u}_h^0 \in \mathbf{H}_h^{\mathbf{u}}, \, \mathsf{para} \ m \geq 1, \, \mathsf{hallar} \ (\boldsymbol{\sigma}_h^m, \mathbf{u}_h^m, \lambda_h^m) \in \mathbb{H}_h^{\boldsymbol{\sigma}} \times \mathbf{H}_h^{\mathbf{u}} \times \mathbf{R} \, \mathsf{tal} \, \mathsf{que} \colon \\ \frac{1}{\nu} \int_{\Omega} (\boldsymbol{\sigma}_h^m)^{\mathrm{d}} : \boldsymbol{\tau}_h^{\mathrm{d}} + \int_{\Omega} \mathbf{u}_h^m \cdot \mathbf{div}(\boldsymbol{\tau}_h) + \lambda_h^m \int_{\Omega} \mathrm{tr}(\boldsymbol{\tau}_h) = \langle \boldsymbol{\tau}_h \mathbf{n}, \mathbf{u}_D \rangle_{\Gamma} \,\,, \\ \int_{\Omega} \mathbf{v}_h \cdot \mathbf{div}(\boldsymbol{\sigma}_h^m) - \mathbf{D} \int_{\Omega} \mathbf{u}_h^m \cdot \mathbf{v}_h - \mathbf{F} \int_{\Omega} |\mathbf{u}_h^{m-1}|^{\rho-2} \mathbf{u}_h^m \cdot \mathbf{v}_h = - \int_{\Omega} \mathbf{f} \cdot \mathbf{v}_h \,, \\ \eta_h \int_{\Omega} \mathrm{tr}(\boldsymbol{\sigma}_h^m) = 0 \,, \end{split}$$

para todo $(\boldsymbol{\tau}_h, \mathbf{v}_h, \eta_h) \in \mathbb{H}_h^{\boldsymbol{\sigma}} \times \mathbf{H}_h^{\mathbf{u}} \times \mathbf{R}$.

Ejemplo 2D: Tasa de Convergencia para Formulación Mixta

Solución para ilustrar tasa de convergencia teórica

- $\Omega := (0,1) \times (0,1)$
- $\nu = 1$. D = 1. F = 10. V $\rho = 3$
- $p(x,y) = \cos(\pi x) \sin\left(\frac{\pi}{2}y\right)$
- $\mathbf{u}(x,y) = \begin{pmatrix} \sin(\pi x)\cos(\pi y) \\ -\cos(\pi x)\sin(\pi y) \end{pmatrix}$
- $\bullet \mathbf{f} = \mathtt{D} \mathbf{u} + \mathtt{F} |\mathbf{u}| \mathbf{u} \mathbf{div}(\boldsymbol{\sigma})$

Código FreeFEM++: BF-mixto_2D-Picard.edp I

```
2 // This code solves a 2D mixed finite element method
3 // for the Brinkman-Forchheimer equations
4 // sig = nu* \nabla u - p*I \qin \Omega, D*u + F*|u|**(rho-2)*u - div(sig) = f in \Omega,
5 //
                       u = uD on \backslash Gamma, int Omega tr(sig) = 0.
6 //
7 // Global information
8 load "iovtk"; // for saving data in paraview format
9 load "UMFPACK64"; // UMFPACK solver
10 load "Element_Mixte"; // for using RT1
          Initial parameters
12 //
13 //----
14 //---- Global parameters
15 int nref = 4:
16 real tol;
18 real[int] H(nref);
19 real[int] DOF(nref);
20 real[int] nbT(nref);
21 real[int] iterations(nref);
23 //---- errors
24 real[int] sigerror(nref);
25 real[int] uerror(nref);
26 real[int] perror(nref);
27 real[int] Guerror(nref);
29 //---- rate of convergence
```

Código FreeFEM++: BF-mixto_2D-Picard.edp II

```
30 real[int] sigrate(nref-1);
31 real[int] urate(nref-1);
32 real[int] prate(nref-1);
33 real[int] Gurate(nref-1);
34 //-----
35 // Global data
36 //----
37 real nu = 1.;
38 \text{ real pp} = 3.;
39 real qq = pp/(pp-1);
40 real Fc = 10.;
41 real D = 1.;
43 func p = cos(pi*x)*sin((pi/2.)*y);
44 func px = -pi*sin(pi*x)*sin((pi/2.)*y);
45 func py = (pi/2.)*cos(pi*x)*cos((pi/2.)*y);
47 func u1 = sin(pi*x)*cos(pi*y);
48 func u2 = -cos(pi*x)*sin(pi*v);
49 func ulx = pi*cos(pi*x)*cos(pi*y);
50 func uly = -pi*sin(pi*x)*sin(pi*y);
51 func u2x = pi*sin(pi*x)*sin(pi*y);
52 func u2v = -u1x:
53 func ulxx = -(pi^2) * sin(pi*x) * cos(pi*y);
54 func ulvy = -(pi^2)*sin(pi*x)*cos(pi*y);
55 func u2xx = (pi^2) *cos(pi*x) *sin(pi*y);
56 func u2vy = (pi^2) *cos(pi*x) *sin(pi*y);
58 func sig1 = nu*u1x - p;
```

Código FreeFEM++: BF-mixto_2D-Picard.edp III

```
59 func sig2 = nu*u1v;
60 func sig3 = nu*u2x;
61 func sig4 = nu*u2y - p;
62
63 func Divsig1 = nu*(u1xx + u1yy) - px;
64 func Divsig2 = nu*(u2xx + u2vv) - pv;
66 func fbnorm = sgrt(u1^2 + u2^2);
67 func f1 = (D + Fc*pow(fbnorm,pp-2) )*u1 - Divsig1;
68 func f2 = (D + Fc * pow(fbnorm, pp-2)) * u2 - Divsig2;
70 //---- Global macros
71 macro u [u1.u2] //
72 macro Gu [u1x,u1y,u2x,u2y] //
73 macro sig [sig1,sig2,sig3,sig4] //
74 macro Divsig [Divsig1, Divsig2] //
75 macro F [f1,f2] //
76
77 macro sigh [sigh1.sigh2.sigh3.sigh4] //
78 macro tauh [tauh1,tauh2,tauh3,tauh4] //
80 macro uh [uh1,uh2] //
81 macro vh [vh1.vh2] //
82 macro wh [wh1, wh2] //
83
84 macro norm [N.x, N.y] //
85
86 macro fb(vh) ( sgrt(vh[0]^2 + vh[1]^2) ) //
87 macro tr(tauh) (tauh[0] + tauh[3]) //
```

Código FreeFEM++: BF-mixto_2D-Picard.edp IV

```
88 macro dev(tauh) [0.5*(tauh[0] - tauh[3]),tauh[1],tauh[2],0.5*(tauh[3] - tauh[0])] //
89 macro Div(tauh) [dx(tauh[0]) + dy(tauh[1]),dx(tauh[2]) + dy(tauh[3])] //
91 //---- Post-processing formulae
92 macro ph(tauh) ( -0.5*(tauh[0] + tauh[3]) ) //
93 macro Guh(tauh) [1./(2.*nu)*(tauh[0]-tauh[3]),(1./nu)*tauh[1],(1./nu)*tauh[2],1./(2.*nu)*(tauh
        [31-tauh[0])] //
94 //----
95 //
      Defining the domain
96 //----
97 for(int n = 0; n < nref; n++) {
99 int size = 2^{n} (n + 2.);
100
101 int GammaD = 11;
103 border Gamma1(t=0.1) {x=t; v=0; label = GammaD; };
104 border Gamma2(t=0,1) {x=1; y=t; label = GammaD; };
105 border Gamma3(t=1,0) {x=t; v=1; label = GammaD; };
106 border Gamma4(t=1,0) {x=0; v=t; label = GammaD; };
108 mesh Th = buildmesh(Gamma1(size) + Gamma2(size) + Gamma3(size) + Gamma4(size));
109 //----
110 // Finite element spaces
112 fespace Hhsig(Th, [RT0, RT0]);
113 fespace Hhu (Th, [P0, P0]);
114
115 fespace Vh (Th, P1);
```

Código FreeFEM++: BF-mixto_2D-Picard.edp V

```
Defining the bilinear forms
117 //
118 //----
119 Hhsiq sigh;
120 Hhu uh, wh;
121 //---- bilinear forms
122 varf all(sigh,tauh) = int2d(Th)( (1./nu)*(dev(sigh)'*dev(tauh)));
123 varf a12(uh,tauh) = int2d(Th)(uh'*Div(tauh));
124 varf a22 (uh, vh) = int2d(Th) ( -(D + Fc*pow(fb(wh), pp-2))*(uh'*vh) );
126 varf lm(sigh,tauh) = int2d(Th)(tr(tauh));
128 //---- RHS
129 varf rhs1(sigh, tauh) = int1d(Th, GammaD) ( u'*([[tauh[0], tauh[1]], [tauh[2], tauh[3]]]*norm) );
130 varf rhs2(uh,vh) = int2d(Th)(-(F'*vh));
131 //----
132 //
                   Stiff matrix
134 matrix All = all(Hhsig, Hhsig);
135 matrix A12 = a12 (Hhu, Hhsiq);
136 real[int] LM = lm(0, Hhsig);
137
138 //---- RHS
139 real[int] RHS1 = rhs1(0, Hhsig);
140 real[int] RHS2 = rhs2(0, Hhu);
141 real[int] L = [RHS1,RHS2,0];
142 //-----
              Picard iteration
143 //
```

Código FreeFEM++: BF-mixto_2D-Picard.edp VI

```
145 \text{ wh} = [0.,0.];
146
147 int itt = 0.;
148 tol = 10.;
149 real[int] solt(Hhsiq.ndof+Hhu.ndof+1); solt = 0.;
150
151 while ((tol > 1e-6) && (itt < 30)) {
152
       itt = itt + 1.;
154
       matrix A22 = a22(Hhu, Hhu);
155
       matrix M; {
       M = [[A11, A12, LM],
156
          [ A12', A22, 0],
157
158
          [ LM', 0, 0]];}
159
       set (M. solver = sparsesolver);
160
161
       real[int] sol = M^-1*L:
162
       wh1[] = sol(Hhsig.ndof:Hhsig.ndof + Hhu.ndof-1);
163
164
165 //---- computing tol
     real[int] diff = sol - solt;
166
    tol = sqrt(diff'*diff)/sqrt(sol'*sol);
167
168
       cout << " tolerance = " << tol << endl:
169
170 //---- updating data for the next step
     solt = sol;
172 }
173 iterations[n] = itt:
```

Código FreeFEM++: BF-mixto_2D-Picard.edp VII

```
174
175 //---- Approximation of the solution
176 sigh1[] = solt(0:Hhsig.ndof-1);
177 uh1[] = solt(Hhsig.ndof:Hhsig.ndof + Hhu.ndof-1);
178
179 //---- calculating the errors
180 sigerror[n] = sgrt(int2d(Th)( (sig - sigh)'*(sig - sigh))) + pow(int2d(Th)( pow((Divsig - Div
                         (sigh))'*(Divsig - Div(sigh)), qq/2.)), 1./qq);
181 uerror[n] = pow(int2d(Th) ( pow((u - uh)'*(u - uh),pp/2.) ),1./pp);
182
183 perror[n] = sqrt(int2d(Th)( square(p - ph(sigh))));
184 Guerror[n] = sgrt(int2d(Th)((Gu - Guh(sigh))'*(Gu - Guh(sigh)));
185
186 //---- for the meshsize in Omega
187 Vh h = hTriangle;
188 \text{ H[n]} = \text{h[l.max;}
189
190 \text{ nbT}[n] = \text{Th.nt};
191 DOF[n] = Hhsig.ndof + Hhu.ndof;
192 //---- exporting to Praraview
193 savevtk("Data Paraview 2D/BF aprox"+n+".vtk", Th, [sigh1, sigh2, 0], [sigh3, sigh4, 0], [uh1, uh2, 0], ph
                         (sigh), (1./nu)*sgrt((0.5*(sigh[0]-sigh[3]))^2 + sigh[1]^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3])^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3])^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3])^2 + sigh[2]^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3]-sigh[3])^2 + sigh[2]^2 + sigh[2]^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3]-sigh[3]-sigh[3])^2 + sigh[2]^2 + 
                         sigh[0]))^2 ),dataname="sig1h sig2h uh ph mGuh");
194 savevtk("Data Paraview 2D/BF exact"+n+".vtk", Th, [sig1, sig2, 0], [sig3, sig4, 0], [u1, u2, 0], p, sgrt(
                         (u1x)^2 + (u1y)^2 + (u2x)^2 + (u2y)^2), dataname="sig1 sig2 u p mGu");
195 }
                                                         showing the tables
197 //
```

Código FreeFEM++: BF-mixto_2D-Picard.edp VIII

```
199 cout << " sigerror = " << sigerror <<endl;
200 for (int n = 1; n < nref; n++)
201 sigrate[n-1] = \log(\text{sigerror}[n-1]/\text{sigerror}[n]) / \log(H[n-1]/H[n]);
202 cout << " convergence rate sig in Hdiv-g = "<< sigrate <<endl;
203
204 cout << " uerror = " << uerror <<endl;
205 for (int n = 1; n < nref; n++)
206 urate[n-1] = log(uerror[n-1]/uerror[n]) / log(H[n-1]/H[n]);
207 cout << " convergence rate u in Lp = " << urate <<endl;
209 cout << " perror = " << perror <<endl;
210 for (int n = 1; n < nref; n++)
211 prate[n-1] = \log(perror[n-1]/perror[n]) / \log(H[n-1]/H[n]);
212 cout << " convergence rate p in L2 = " << prate <<endl;
214 cout << " Guerror = " << Guerror <<endl;
215 \text{ for (int } n = 1; n < nref; n++)
216 Gurate[n-1] = \log(Guerror[n-1]/Guerror[n]) / \log(H[n-1]/H[n]);
217 cout << " convergence rate velocity gradient in L2 = " << Gurate <<endl;
218
219 cout << " mesh size Omega = " << H <<endl;
220 cout << " DOF Omega = " << DOF <<endl;
221 cout << " Number of triangles = " << nbT <<endl;
222 cout << " Newton iterations = " << iterations <<endl:
```

Estrategia Iterativa de Newton

$$\begin{split} & \mathsf{Dado} \ \mathbf{u}_h^0 \in \mathbf{H}_h^{\mathbf{u}}, \mathsf{para} \ m \geq 1, \, \mathsf{hallar} \ (\boldsymbol{\sigma}_h^m, \mathbf{u}_h^m, \lambda_h^m) \in \mathbb{H}_h^{\boldsymbol{\sigma}} \times \mathbf{H}_h^{\mathbf{u}} \times \mathbf{R} \, \mathsf{tal} \, \mathsf{que} \colon \\ & \frac{1}{\nu} \int_{\Omega} (\boldsymbol{\sigma}_h^m)^{\mathrm{d}} : \boldsymbol{\tau}_h^{\mathrm{d}} + \int_{\Omega} \mathbf{u}_h^m \cdot \mathbf{div}(\boldsymbol{\tau}_h) + \lambda_h^m \int_{\Omega} \mathrm{tr}(\boldsymbol{\tau}_h) = \langle \boldsymbol{\tau}_h \mathbf{n}, \mathbf{u}_D \rangle_{\Gamma} \,\,, \\ & \int_{\Omega} \mathbf{v}_h \cdot \mathbf{div}(\boldsymbol{\sigma}_h^m) - \mathbf{D} \int_{\Omega} \mathbf{u}_h^m \cdot \mathbf{v}_h - \mathbf{F}(\rho - 2) \int_{\Omega} |\mathbf{u}_h^{m-1}|^{\rho - 4} (\mathbf{u}_h^{m-1} \cdot \mathbf{u}_h^m) (\mathbf{u}_h^{m-1} \cdot \mathbf{v}_h) \\ & - \mathbf{F} \int_{\Omega} |\mathbf{u}_h^{m-1}|^{\rho - 2} \mathbf{u}_h^m \cdot \mathbf{v}_h = - \int_{\Omega} \mathbf{f} \cdot \mathbf{v}_h - \mathbf{F}(\rho - 2) \int_{\Omega} |\mathbf{u}_h^{m-1}|^{\rho - 2} \mathbf{u}_h^{m-1} \cdot \mathbf{v}_h \,, \\ & \eta_h \int_{\mathbb{R}} \mathrm{tr}(\boldsymbol{\sigma}_h^m) = 0 \,, \end{split}$$

para todo $(\boldsymbol{\tau}_h, \mathbf{v}_h, \eta_h) \in \mathbb{H}_h^{\boldsymbol{\sigma}} \times \mathbf{H}_h^{\mathbf{u}} \times \mathbf{R}$.

Corramos el ejemplo anterior con nuestra estrategia iterativa de Newton

Código FreeFEM++: BF-mixto_2D-Newton.edp I

```
2 // This code solves a 2D mixed finite element method
3 // for the Brinkman-Forchheimer equations
4 // sig = nu* \nabla u - p*I \qin \Omega, D*u + F*|u|**(rho-2)*u - div(sig) = f in \Omega,
5 //
                       u = uD on \backslash Gamma, int Omega tr(sig) = 0.
6 //
7 // Global information
8 load "iovtk"; // for saving data in paraview format
9 load "UMFPACK64"; // UMFPACK solver
10 load "Element_Mixte"; // for using RT1
          Initial parameters
12 //
13 //-----
14 //---- Global parameters
15 int nref = 4:
16 real tol;
18 real[int] H(nref);
19 real[int] DOF(nref);
20 real[int] nbT(nref);
21 real[int] iterations(nref);
23 //---- errors
24 real[int] sigerror(nref);
25 real[int] uerror(nref);
26 real[int] perror(nref);
27 real[int] Guerror(nref);
29 //---- rate of convergence
```

Código FreeFEM++: BF-mixto_2D-Newton.edp II

```
30 real[int] sigrate(nref-1);
31 real[int] urate(nref-1);
32 real[int] prate(nref-1);
33 real[int] Gurate(nref-1);
34 //-----
35 // Global data
36 //----
37 real nu = 1.;
38 \text{ real pp} = 3.;
39 real qq = pp/(pp-1);
40 real Fc = 10.;
41 real D = 1.;
43 func p = cos(pi*x)*sin((pi/2.)*y);
44 func px = -pi*sin(pi*x)*sin((pi/2.)*y);
45 func py = (pi/2.)*cos(pi*x)*cos((pi/2.)*y);
47 func u1 = sin(pi*x)*cos(pi*y);
48 func u2 = -cos(pi*x)*sin(pi*v);
49 func ulx = pi*cos(pi*x)*cos(pi*y);
50 func uly = -pi*sin(pi*x)*sin(pi*y);
51 func u2x = pi*sin(pi*x)*sin(pi*y);
52 func u2v = -u1x:
53 func ulxx = -(pi^2) * sin(pi*x) * cos(pi*y);
54 func ulvy = -(pi^2)*sin(pi*x)*cos(pi*y);
55 func u2xx = (pi^2) *cos(pi*x) *sin(pi*y);
56 func u2vy = (pi^2) *cos(pi*x) *sin(pi*y);
58 func sig1 = nu*u1x - p;
```

Código FreeFEM++: BF-mixto_2D-Newton.edp III

```
59 func sig2 = nu*u1v;
60 func sig3 = nu*u2x;
61 func sig4 = nu*u2y - p;
62
63 func Divsig1 = nu*(u1xx + u1yy) - px;
64 func Divsig2 = nu*(u2xx + u2vv) - pv;
66 func fbnorm = sgrt(u1^2 + u2^2);
67 func f1 = (D + Fc*pow(fbnorm,pp-2) )*u1 - Divsig1;
68 func f2 = (D + Fc * pow(fbnorm, pp-2)) * u2 - Divsig2;
70 //---- Global macros
71 macro u [u1.u2] //
72 macro Gu [u1x,u1y,u2x,u2y] //
73 macro sig [sig1,sig2,sig3,sig4] //
74 macro Divsig [Divsig1, Divsig2] //
75 macro F [f1,f2] //
76
77 macro sigh [sigh1.sigh2.sigh3.sigh4] //
78 macro tauh [tauh1,tauh2,tauh3,tauh4] //
80 macro uh [uh1,uh2] //
81 macro vh [vh1.vh2] //
82 macro wh [wh1, wh2] //
83
84 macro norm [N.x, N.y] //
85
86 macro fb(vh) ( sgrt(vh[0]^2 + vh[1]^2) ) //
87 macro tr(tauh) (tauh[0] + tauh[3]) //
```

Código FreeFEM++: BF-mixto_2D-Newton.edp IV

```
88 macro dev(tauh) [0.5*(tauh[0] - tauh[3]),tauh[1],tauh[2],0.5*(tauh[3] - tauh[0])] //
89 macro Div(tauh) [dx(tauh[0]) + dy(tauh[1]),dx(tauh[2]) + dy(tauh[3])] //
91 //---- Post-processing formulae
92 macro ph(tauh) ( -0.5*(tauh[0] + tauh[3]) ) //
93 macro Guh(tauh) [1./(2.*nu)*(tauh[0]-tauh[3]),(1./nu)*tauh[1],(1./nu)*tauh[2],1./(2.*nu)*(tauh
        [31-tauh[0])] //
94 //----
95 //
      Defining the domain
96 //----
97 for(int n = 0; n < nref; n++) {
99 int size = 2^{n} (n + 2.);
100
101 int GammaD = 11;
103 border Gamma1(t=0.1) {x=t; v=0; label = GammaD; };
104 border Gamma2(t=0,1) {x=1; y=t; label = GammaD; };
105 border Gamma3(t=1,0) {x=t; v=1; label = GammaD; };
106 border Gamma4(t=1,0) {x=0; v=t; label = GammaD; };
108 mesh Th = buildmesh(Gamma1(size) + Gamma2(size) + Gamma3(size) + Gamma4(size));
109 //----
110 // Finite element spaces
112 fespace Hhsig(Th, [RT0, RT0]);
113 fespace Hhu (Th, [P0, P0]);
114
115 fespace Vh (Th, P1);
```

Código FreeFEM++: BF-mixto_2D-Newton.edp V

```
117 // Defining the bilinear forms
119 Hhsiq sigh;
120 Hhu uh, wh;
121 //---- bilinear forms
122 varf all(sigh,tauh) = int2d(Th)( (1./nu)*(dev(sigh)'*dev(tauh)));
123 varf a12(uh,tauh) = int2d(Th)(uh'*Div(tauh));
124 varf a22 (uh, vh) = int2d(Th) (-(D + Fc*pow(fb(wh), pp-2))*(uh'*vh) - (pp-2)*Fc*pow(fb(wh), pp
      -4) * (wh' *uh) * (wh' *vh) );
125
126 varf lm(sigh,tauh) = int2d(Th)(tr(tauh));
128 //---- RHS
129 varf rhs1(sigh,tauh) = int1d(Th,GammaD) ( u'*([[tauh[0],tauh[1]],[tauh[2],tauh[3]]]*norm) );
130 varf rhs2(uh, vh) = int2d(Th)( -(F'*vh) - (pp-2)*Fc*pow(fb(wh), pp-2)*(wh'*vh));
131 //-----
              Stiff matrix
132 //
133 //-----
134 matrix All = all(Hhsig, Hhsig);
135 matrix A12 = a12(Hhu, Hhsiq);
136 real[int] LM = lm(0, Hhsig);
138 //---- RHS
139 real[int] RHS1 = rhs1(0, Hhsig);
140 //-----
141 //
            Picard iteration
142 //----
143 wh = [0..1e-6];
```

Código FreeFEM++: BF-mixto_2D-Newton.edp VI

```
144
145 int itt = 0.:
146 tol = 10.;
147 real[int] solt(Hhsiq.ndof+Hhu.ndof+1); solt = 0.;
148
149 while ((tol > 1e-6) && (itt < 30)) {
       itt = itt + 1.;
150
151
       real[int] RHS2 = rhs2(0, Hhu);
152
       real[int] L = [RHS1,RHS2,0];
154
155
       matrix A22 = a22(Hhu, Hhu);
       matrix M: {
156
157
       M = [[A11, A12, LM],
158
          [ A12', A22, 0],
          [ LM', 0, 0]];}
159
160
       set (M, solver = sparsesolver);
161
       real[int] sol = M^-1*L;
162
163
164
       wh1[] = sol(Hhsig.ndof:Hhsig.ndof + Hhu.ndof-1);
165
166 //---- computing tol
167
     real[int] diff = sol - solt;
   tol = sgrt(diff'*diff)/sgrt(sol'*sol);
168
       cout << " tolerance = " << tol << endl;
169
171 //---- updating data for the next step
172 solt = sol;
```

Código FreeFEM++: BF-mixto_2D-Newton.edp VII

```
173 }
174 iterations[n] = itt;
175
176 //---- Approximation of the solution
177 sigh1[] = solt(0:Hhsig.ndof-1);
178 uhl[] = solt(Hhsiq.ndof:Hhsiq.ndof + Hhu.ndof-1);
180 //---- calculating the errors
181 sigerror[n] = sqrt(int2d(Th)( (sig - sigh)'*(sig - sigh))) + pow(int2d(Th)( pow((Divsig - Div
                         (sigh))'*(Divsig - Div(sigh)),qq/2.) ),1./qq);
182 uerror[n] = pow(int2d(Th) ( pow((u - uh) '* (u - uh), pp/2.) ),1./pp);
183
184 perror[n] = sqrt(int2d(Th)( square(p - ph(sigh))));
185 Guerror[n] = sgrt(int2d(Th)((Gu - Guh(sigh))'*(Gu - Guh(sigh)));
186
187 //---- for the meshsize in Omega
188 Vh h = hTriangle:
189 \, H[n] = h[].max;
190
191 \text{ nbT[n]} = \text{Th.nt};
192 DOF[n] = Hhsig.ndof + Hhu.ndof;
193 //---- exporting to Praraview
194 savevtk("Data_Paraview_2D/BF_aprox"+n+".vtk", Th, [siqh1, siqh2, 0], [siqh3, siqh4, 0], [uh1, uh2, 0], ph
                         (sigh), (1./nu)*sgrt((0.5*(sigh[0]-sigh[3]))^2 + sigh[1]^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3])^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3])^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3])^2 + sigh[2]^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3]-sigh[3])^2 + sigh[2]^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3]-sigh[3])^2 + sigh[2]^2 + sigh[2]^
                         sigh[0]))^2 ),dataname="sig1h sig2h uh ph mGuh");
195 savevtk("Data_Paraview_2D/BF_exact"+n+".vtk", Th, [sig1, sig2, 0], [sig3, sig4, 0], [u1, u2, 0], p, sqrt(
                         (u1x)^2 + (u1y)^2 + (u2x)^2 + (u2y)^2), dataname="sig1 sig2 u p mGu");
196
```

Código FreeFEM++: BF-mixto_2D-Newton.edp VIII

```
198 //
                           showing the tables
200 cout << " sigerror = " << sigerror <<endl;
201 for(int n = 1; n < nref; n++)
202 sigrate[n-1] = log(sigerror[n-1]/sigerror[n]) / log(H[n-1]/H[n]);
203 cout << " convergence rate sig in Hdiv-q = "<< sigrate <<endl;
204
205 cout << " uerror = " << uerror <<endl;
206 for(int n = 1; n < nref; n++)
207 \operatorname{urate}[n-1] = \log(\operatorname{uerror}[n-1]/\operatorname{uerror}[n]) / \log(H[n-1]/H[n]);
208 cout << " convergence rate u in Lp = " << urate <<endl;
209
210 cout << " perror = " << perror <<endl;
211 for(int n = 1; n < nref; n++)
212 prate[n-1] = log(perror[n-1]/perror[n]) / log(H[n-1]/H[n]);
213 cout << " convergence rate p in L2 = " << prate <<endl;
214
215 cout << " Guerror = " << Guerror <<endl;
216 for(int n = 1; n < nref; n++)
217 Gurate[n-1] = log(Guerror[n-1]/Guerror[n]) / log(H[n-1]/H[n]);
218 cout << " convergence rate velocity gradient in L2 = " << Gurate <<endl;
220 cout << " mesh size Omega = " << H <<endl;
221 cout << " DOF Omega = " << DOF <<endl;
222 cout << " Number of triangles = " << nbT <<endl;
223 cout << " Newton iterations = " << iterations <<endl:
```

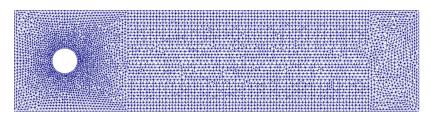
Fluido en un canal rectangular 2D con obstáculos

Parámetros

• $\Omega = (0, 1.6) \times (0, 0.4) \setminus \Omega_c$, where

$$\Omega_c = \left\{ (x, y) : (x - 0.2)^2 + (y - 0.2)^2 < 0.05^2 \right\}$$

• $\nu = 1e - 3$, D = 1, F = 10, $\rho = 4$ y f = 0



$$\mathbf{u} = \Big(-0.5\,y\,(y-0.4),0\Big)^{\mathrm{t}} \text{ en } \Gamma_{\mathrm{left}} \cup \Gamma_{\mathrm{right}}\,, \quad \text{y} \quad \mathbf{u} = \mathbf{0} \text{ en } \Gamma_{\mathrm{top}} \cup \Gamma_{\mathrm{bottom}}$$

Código FreeFEM++: BF-mixto_2D-rectangle-holes.edp I

```
2 // This code solves a 2D mixed finite element method
3 // for the Brinkman-Forchheimer equations
4 // sig = nu* \nabla u - p*I \qin \Omega, D*u + F*|u|**(rho-2)*u - div(sig) = f in \Omega,
5 //
                     u = uD on \backslash Gamma, int Omega tr(sig) = 0.
6 //
7 // Global information
8 load "iovtk"; // for saving data in paraview format
9 load "UMFPACK64"; // UMFPACK solver
10 load "Element_Mixte"; // for using RT1
12 // Initial parameters
13 //----
14 //---- Global parameters
15 real tol, H. DOF, nbT, iterations:
18 // Global data
19 //-----
20 real nu = 1e-3;
21 real pp = 4.;
22 real qq = pp/(pp-1);
23 real Fc = 10.;
24 real D = 1.;
26 func u1 = -0.5*y*(y - 0.4);
27 func u2 = 0.;
29 func fbnorm = sgrt(u1^2 + u2^2);
```

Código FreeFEM++: BF-mixto_2D-rectangle-holes.edp II

```
30 func f1 = 0:
31 func f2 = 0;
33 //---- Global macros
34 macro u [u1,u2] //
35 macro F [f1,f2] //
37 macro sigh [sigh1, sigh2, sigh3, sigh4] //
38 macro tauh [tauh1,tauh2,tauh3,tauh4] //
40 macro uh [uh1,uh2] //
41 macro vh [vh1, vh2] //
42 macro wh [wh1.wh2] //
44 macro norm [N.x, N.y] //
45
46 macro fb(vh) ( sqrt(vh[0]^2 + vh[1]^2) ) //
47 macro tr(tauh) (tauh[0] + tauh[3]) //
48 macro dev(tauh) [0.5*(tauh[0] - tauh[3]),tauh[1],tauh[2],0.5*(tauh[3] - tauh[0])] //
49 macro Div(tauh) [dx(tauh[0]) + dy(tauh[1]), dx(tauh[2]) + dy(tauh[3])] //
50
51 //---- Post-processing formulae
52 macro ph(tauh) ( -0.5*(tauh[0] + tauh[3]) ) //
53 macro Guh(tauh) [1./(2.*nu) * (tauh[0]-tauh[3]), (1./nu) *tauh[1], (1./nu) *tauh[2], 1./(2.*nu) * (tauh
        [3]-tauh[0])] //
55 //
                      Defining the domain
57 int size = 32:
```

Código FreeFEM++: BF-mixto_2D-rectangle-holes.edp III

```
59 border Gamma1(t=0,1.6) {x=t; y=0; label = 1;};
60 border Gamma2(t=0,0.4) {x=1.6; v=t; label = 2;};
61 border Gamma3(t=1.6,0) {x=t; y=0.4; label = 3;};
62 border Gamma4(t=0.4,0) \{x=0; y=t; label = 4; \};
63 border Gamma5(t=0,2*pi) {x=0.05*cos(t)+0.2; y=0.05*sin(t)+0.2; label = 5;};
65 mesh Th = buildmesh(Gamma1(4*size) + Gamma2(size) + Gamma3(4*size) + Gamma4(size) + Gamma5
       (-1.5*size)):
67 // Finite element spaces
68 //-----
69 fespace Hhsig(Th, [RT1, RT1]);
70 fespace Hhu (Th, [P1dc, P1dc]);
72 fespace Vh (Th, P1);
73 //-----
74 // Defining the bilinear forms
76 Hhsig sigh;
77 Hhu uh, wh;
78 //---- bilinear forms
79 varf all(sigh,tauh) = int2d(Th)( (1./nu)*(dev(sigh)'*dev(tauh)));
80 varf al2(uh,tauh) = int2d(Th)(uh'*Div(tauh));
81 varf a22(uh,vh) = int2d(Th)( -(D + Fc*pow(fb(wh),pp-2))*(uh'*vh) - (pp-2)*Fc*pow(fb(wh),pp
       -4) * (wh' * uh) * (wh' * vh) );
82
83 varf lm(sigh, tauh) = int2d(Th)(tr(tauh));
84
```

Código FreeFEM++: BF-mixto_2D-rectangle-holes.edp IV

```
85 //---- RHS
86 varf rhs1(sigh,tauh) = int1d(Th,2,4) ( u'*([[tauh[0],tauh[1]],[tauh[2],tauh[3]]]*norm) );
87 varf rhs2(uh,vh) = int2d(Th)( -(F'*vh) - (pp-2)*Fc*pow(fb(wh),pp-2)*(wh'*vh));
88 //----
89 // Stiff matrix
90 //----
91 matrix Al1 = al1(Hhsig, Hhsig);
92 matrix A12 = a12(Hhu, Hhsig);
93 real[int] LM = lm(0.Hhsig);
95 //---- RHS
96 real[int] RHS1 = rhs1(0, Hhsiq);
97 //----
98 //
              Picard iteration
99 //----
100 \text{ wh} = [0..1e-6];
102 int itt = 0.;
103 \text{ tol} = 10.;
104 real[int] solt(Hhsiq.ndof+Hhu.ndof+1); solt = 0.;
105
106 while ((tol > 1e-6) && (itt < 30)) {
      itt = itt + 1.;
108
    real[int] RHS2 = rhs2(0, Hhu);
109
     real[int] L = [RHS1,RHS2,0];
      matrix A22 = a22(Hhu, Hhu);
   matrix M:{
113
```

Código FreeFEM++: BF-mixto_2D-rectangle-holes.edp V

```
114
       M = [[A11, A12, LM],
         [ A12', A22, 0],
          [ LM', 0, 0]];}
116
       set (M, solver = sparsesolver);
118
       real[int] sol = M^-1*L;
120
       wh1[] = sol(Hhsig.ndof:Hhsig.ndof + Hhu.ndof-1);
123 //---- computing tol
     real[int] diff = sol - solt;
124
     tol = sqrt(diff'*diff)/sqrt(sol'*sol);
125
       cout << " tolerance = " << tol << endl;
126
128 //---- updating data for the next step
     solt = sol:
129
130 }
131 iterations = itt;
132
133 //---- Approximation of the solution
134 sigh1[] = solt(0:Hhsig.ndof-1);
135 uh1[] = solt(Hhsig.ndof:Hhsig.ndof + Hhu.ndof-1);
136
137 //---- for the meshsize in Omega
138 Vh h = hTriangle;
139 H = h[].max;
140
141 \text{ nbT} = \text{Th.nt};
142 DOF = Hhsig.ndof + Hhu.ndof;
```

Código FreeFEM++: BF-mixto_2D-rectangle-holes.edp VI

```
143 //---- exporting to Praraview
144 savevtk("Data_Paraview_2D/BF_aprox.vtk", Th, [sigh1, sigh2, 0], [sigh3, sigh4, 0], [uh1, uh2, 0], ph (sigh
         ), (1./nu)*sqrt((0.5*(sigh[0]-sigh[3]))^2 + sigh[1]^2 + sigh[2]^2 + (0.5*(sigh[3]-sigh[3])
         [0]))^2 ),dataname="sig1h sig2h uh ph mGuh");
146 //
                showing the tables
148 cout << " mesh size Omega = " << H <<endl;
149 cout << " DOF Omega = " << DOF <<endl;
150 cout << " Number of triangles = " << nbT <<endl;
151 cout << " Newton iterations = " << iterations <<endl:
```

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