

# ECS 170: Homework 2

January 19, 2017

**Your answers should be succinct - our solutions for each problem are no more than a couple sentences.**

**Your submission should be a PDF. We make no guarantees we will grade submissions in other formats.**

1. (R&N 3.18) Describe a search space in which iterative deepening search performs much worse than depth-first search. You do not need to give a specific example of such a space - just a short description is what we want.
2. (R&N 3.28) Show that if a heuristic  $h$  never overestimates by more than some constant  $c$ ,  $A^*$  using  $h$  returns a solution whose cost exceeds that of the optimal solution by no more than  $c$ .
3. For a graph  $G = (V, E)$  where  $V$  is the set of nodes and  $E$  is the set of edges, a vertex cover is some set  $S \subset V$  such that for all nodes  $n \in V$  either  $n \in S$  or there is an edge in  $E$  between  $n$  and some node  $s \in S$ . Let the  $k$ -vertex set cover problem be to find a vertex cover  $S$  for  $G$  such that  $|S| \leq k$ . This can be modeled as a graph search problem as follows: the states describe which nodes are in the partially constructed set cover; the actions are adding a node (not currently in the partial set cover) to the set cover; and the goal test checks if the set  $S$  is a vertex cover of size no more than  $k$ .
  - (a) The number of nodes that are not currently “covered” (i.e. not in the set or having an edge to a node in the set) is not an admissible heuristic. Why?
  - (b)  $k - |S|$  (i.e. the maximum number of nodes we can still add to the set) is not an admissible heuristic. Why?
  - (c) Construct a non-trivial admissible heuristic for this problem description. Why is it admissible?
4. Given a set of admissible heuristics  $h_1, h_2, \dots, h_n$  one can define a new heuristic  $h_{max}$  such that for any node  $n$ :

$$h_{max}(n) = \max_i h_i(n)$$

- (a) Show that  $h_{max}$  is an admissible heuristic.
  - (b) Show that  $h_{max}$  dominates all other  $h_i$ .
  - (c) What are the practical benefits of knowing that a heuristic  $h_1$  dominates another heuristic  $h_2$  (assume we know both are admissible)?
5. Recall the “number of misplaced tiles” heuristic for the 8-puzzle problem. Ian showed this heuristic is admissible in class. Consider a modified 9-puzzle problem where the blank space is replaced with a 9 tile and now the legal moves are swapping the location of pairs of adjacent tiles.
- (a) Show this heuristic is no longer admissible.
  - (b) Give a nontrivial admissible heuristic for this problem. You will likely need to relax the game rules (you may also give a lower bound on the cost of the relaxed version).
6. (R&N 3.30) The traveling salesperson problem (TSP) looks for a tour of all the nodes in a connected graph such that the tour starts and ends at the same node and each node is visited *exactly* once (except start/end node). A minimum-spanning-tree (MST) of a connected graph is a subset of the edges which connect all the nodes with the minimum possible total edge costs. TSP can be posed as a search problem (from a given start node) and can be solved using MST as a heuristic, which estimates the cost of completing a tour, given that a partial tour has already been constructed.
- (a) Show this MST heuristic is admissible (Think about what condition is being relaxed by MST than TSP).
  - (b) Show that the MST heuristic dominates straight-line distance (assume these nodes are the cities in a geographical region).
7. Suppose you have already computed an optimal path  $P$  using A\* on a graph  $G$  with edge weights  $w_{ij} \geq 0$  (where  $i$  and  $j$  are nodes in  $G$ ). You learn that the weights of the edges have changed to  $\hat{w}_{ij} = w_{ij} + \epsilon_{ij} \geq 0$
- (a) If  $\epsilon_{ij} = \epsilon > 0$  for all  $i, j$ , can we guarantee  $P$  will still be an optimal path? Explain.
  - (b) If  $\epsilon_{ij} = \epsilon < 0$  for all  $i, j$ , can we guarantee  $P$  will still be an optimal path? Explain.
  - (c) If  $\epsilon_{ij} = w_{ij}$  for all  $i, j$ , can we guarantee  $P$  will still be an optimal path? Explain.