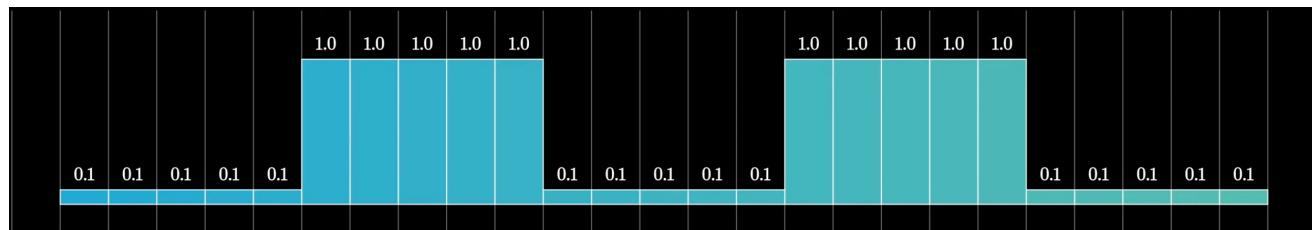


# Deep Learning applied to EEG

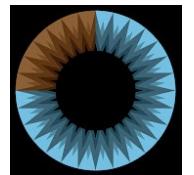
Dung “Young” Truong & Arnaud Delorme



# What kind of operation?



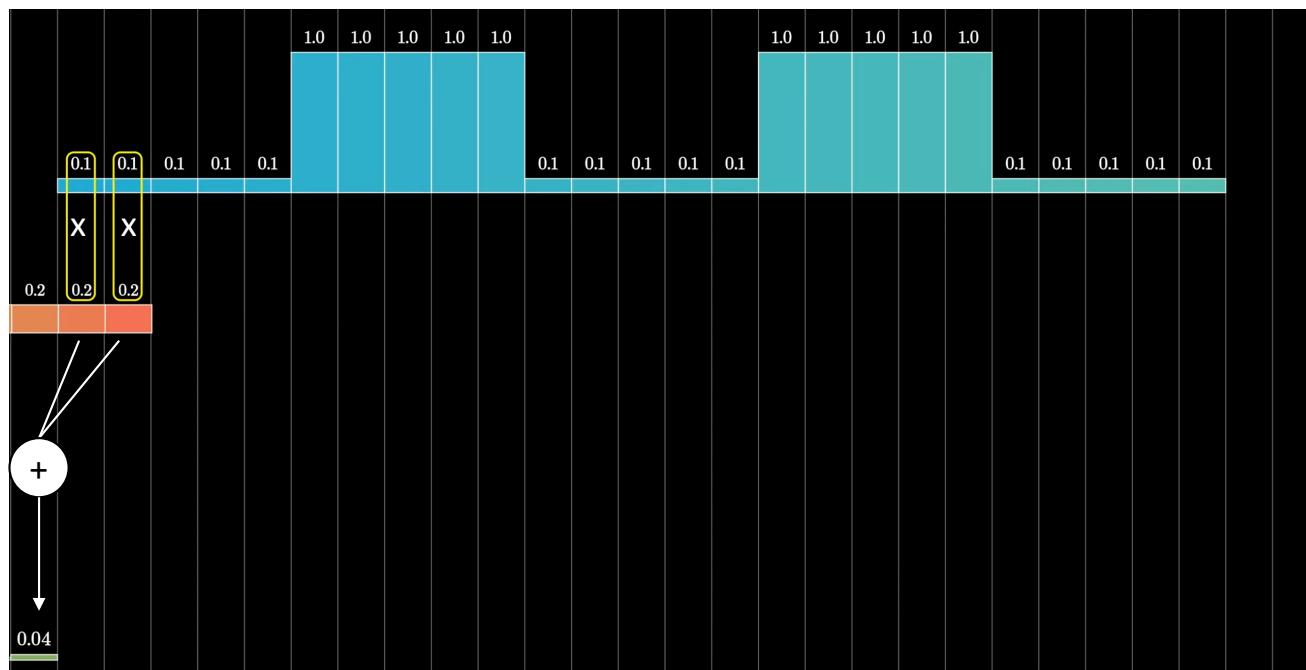
A diagram illustrating a vector operation. It shows a vector with five elements, each labeled "0.2", enclosed in a yellow oval. To the right of the vector is the equation  $\sum_i y_i = 1$ .



3Blue1Brown

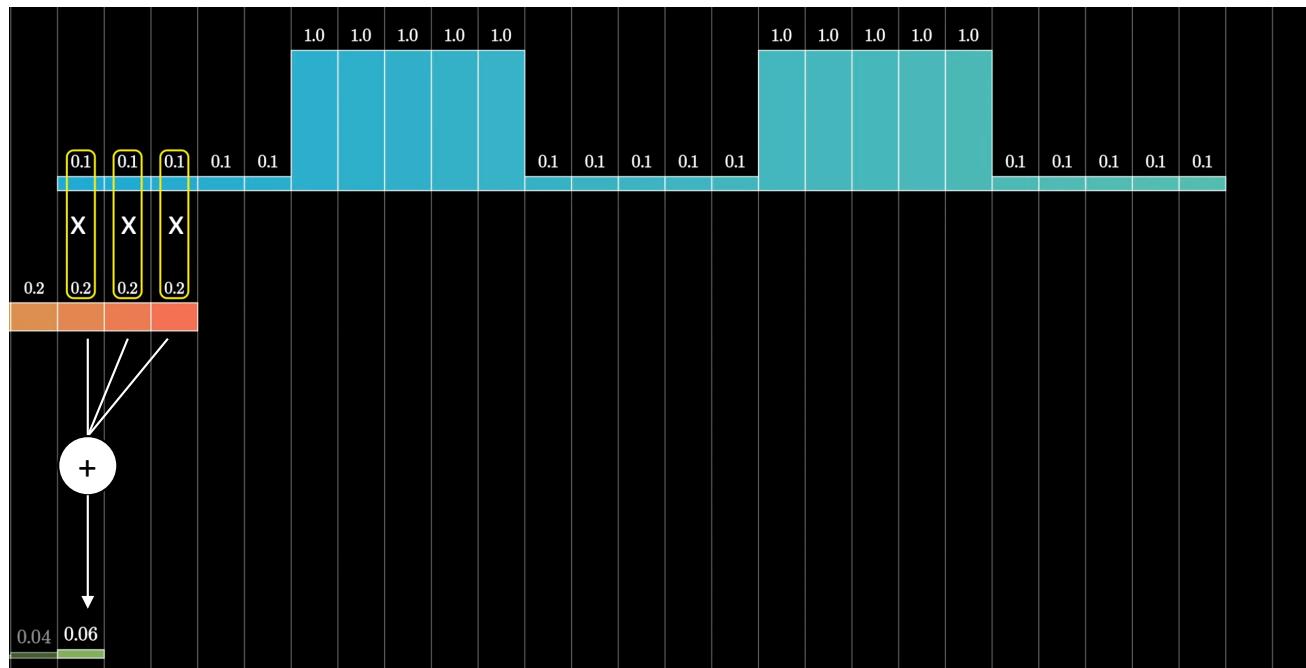
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



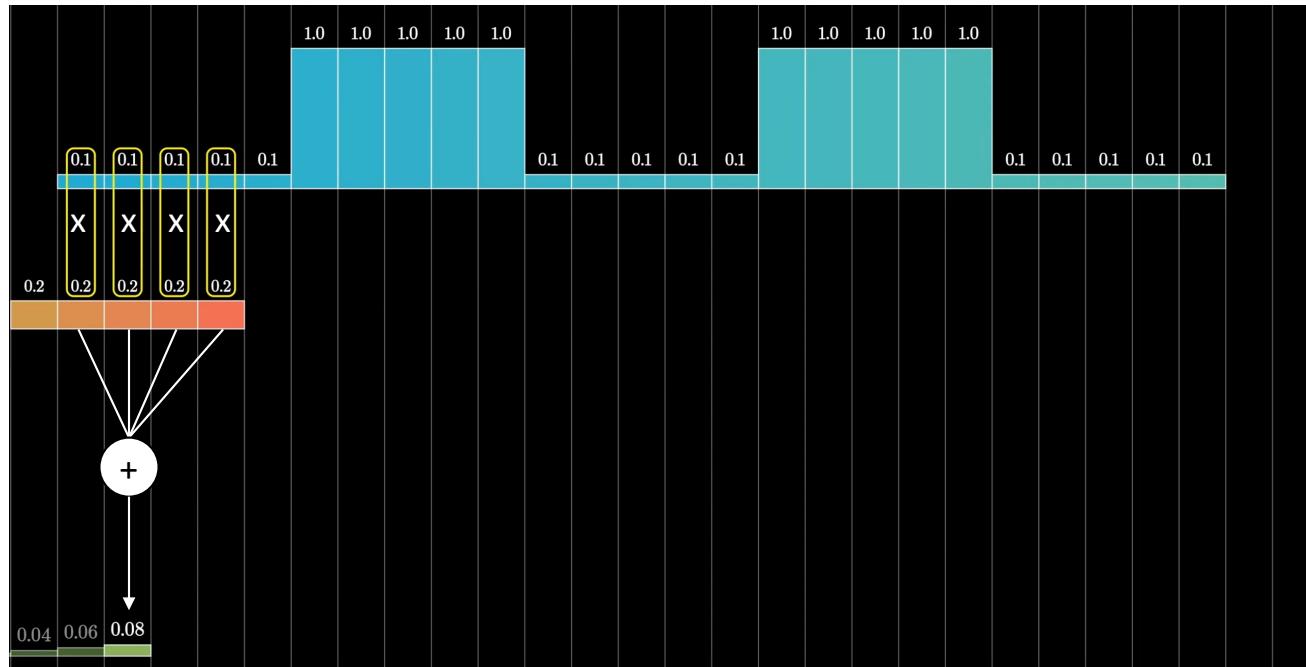
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



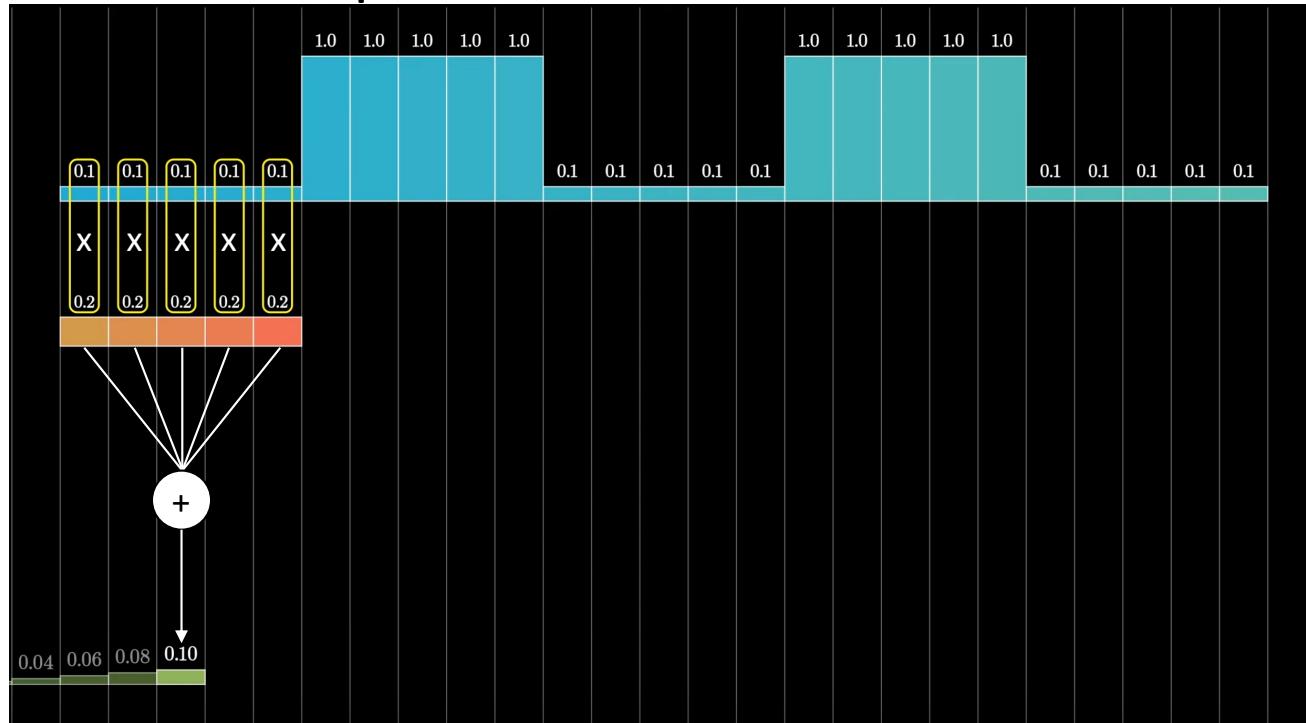
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



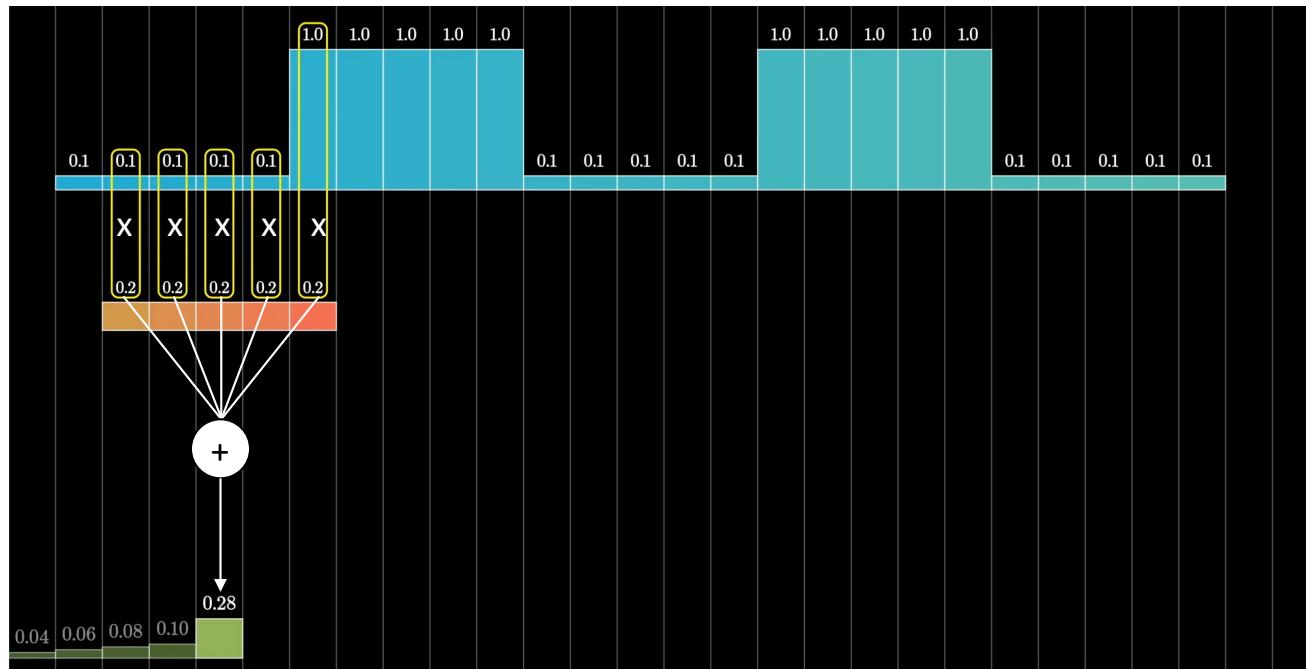
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



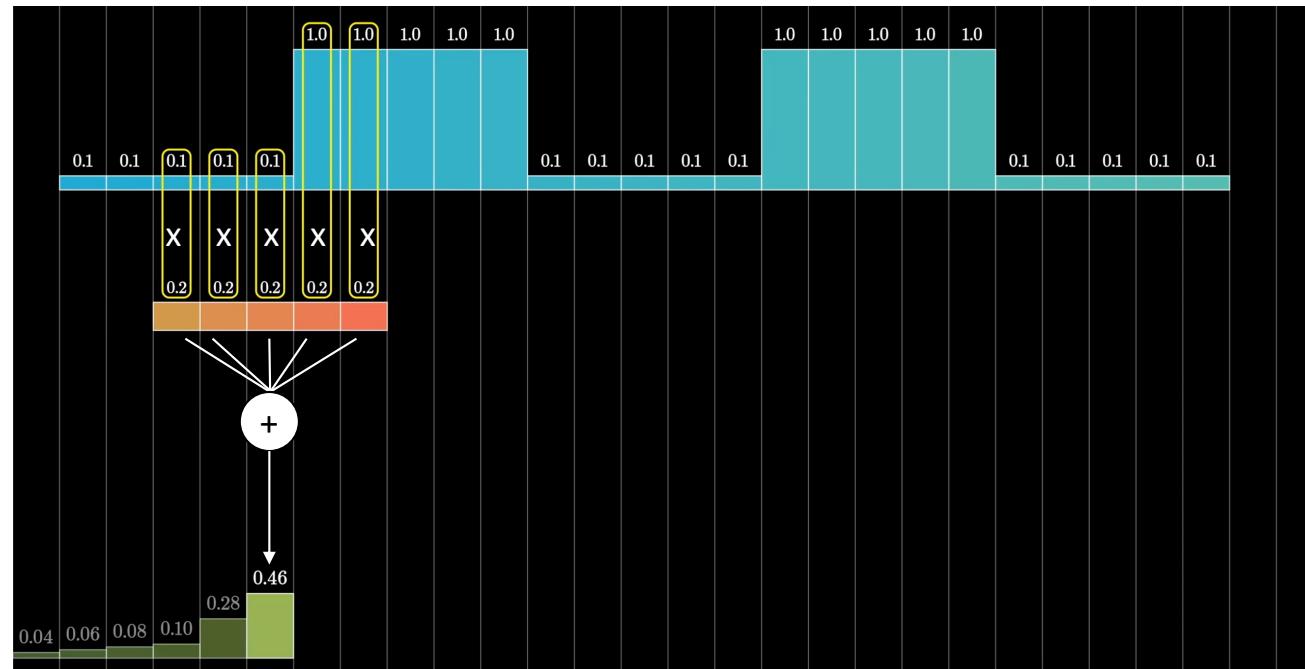
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



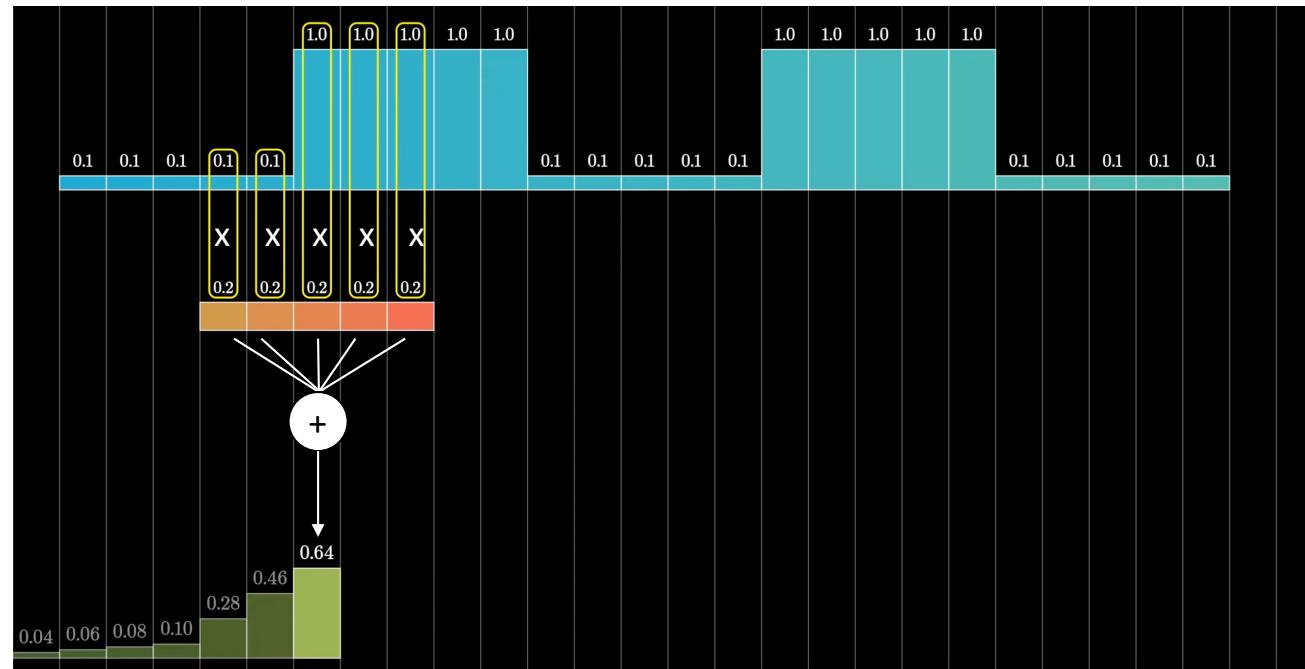
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



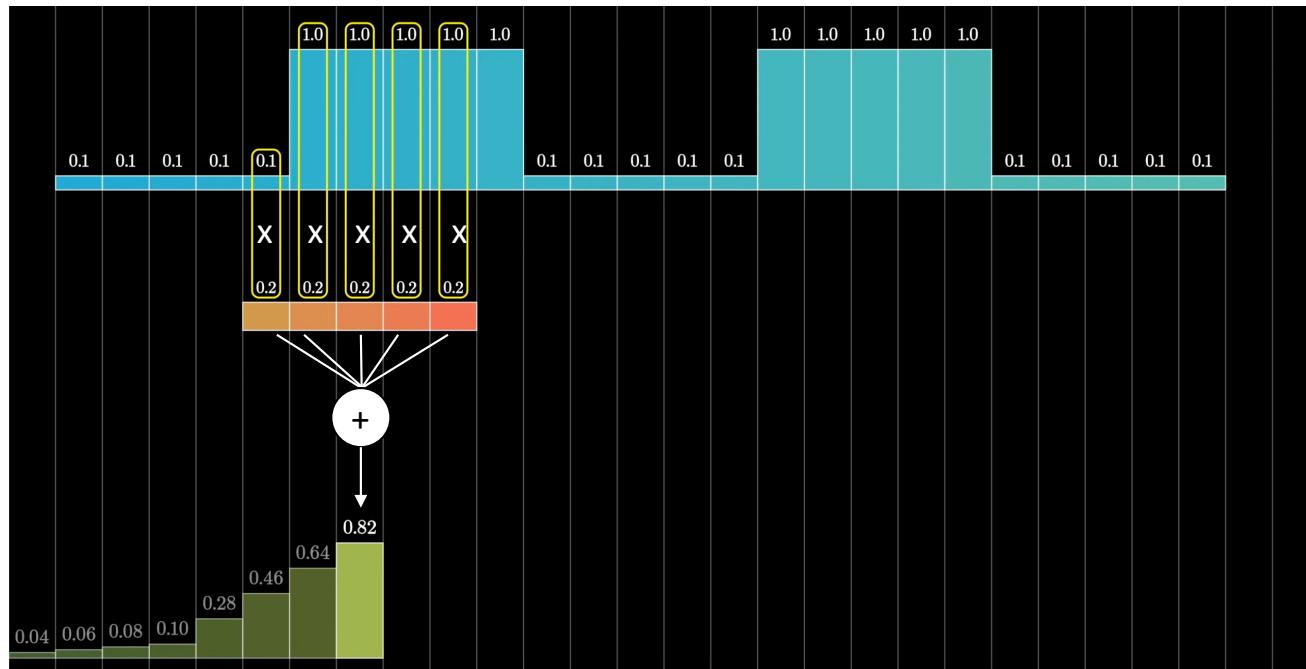
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



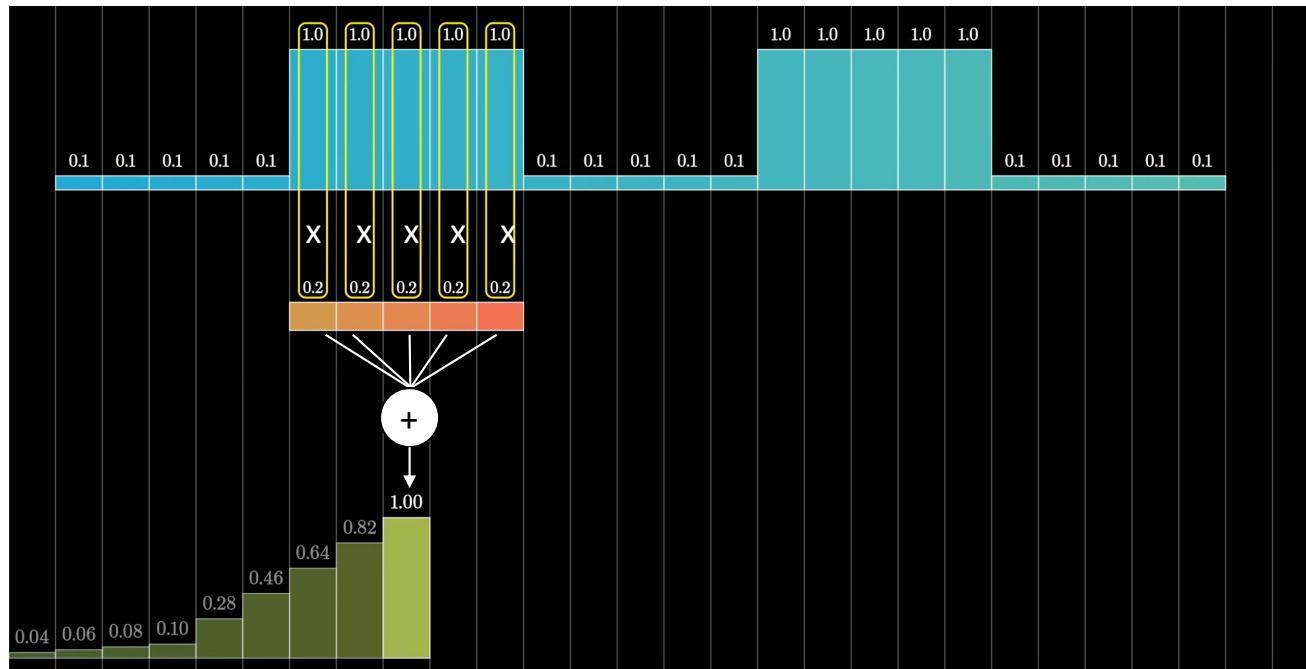
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



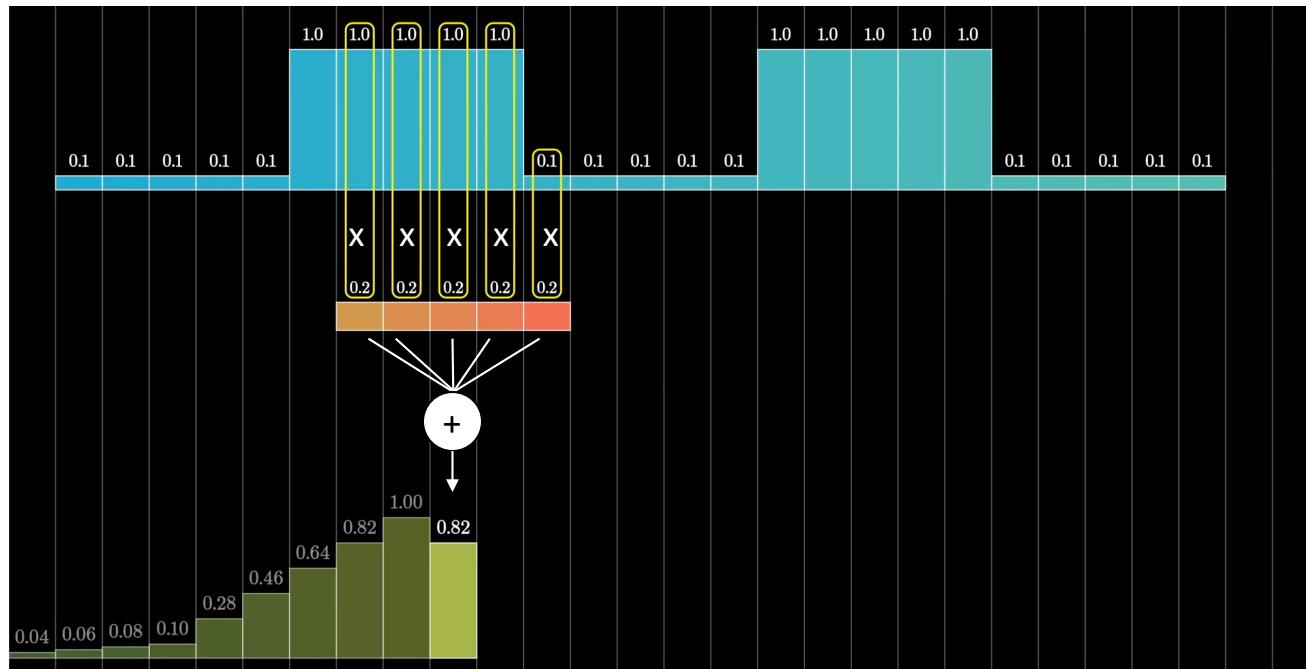
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



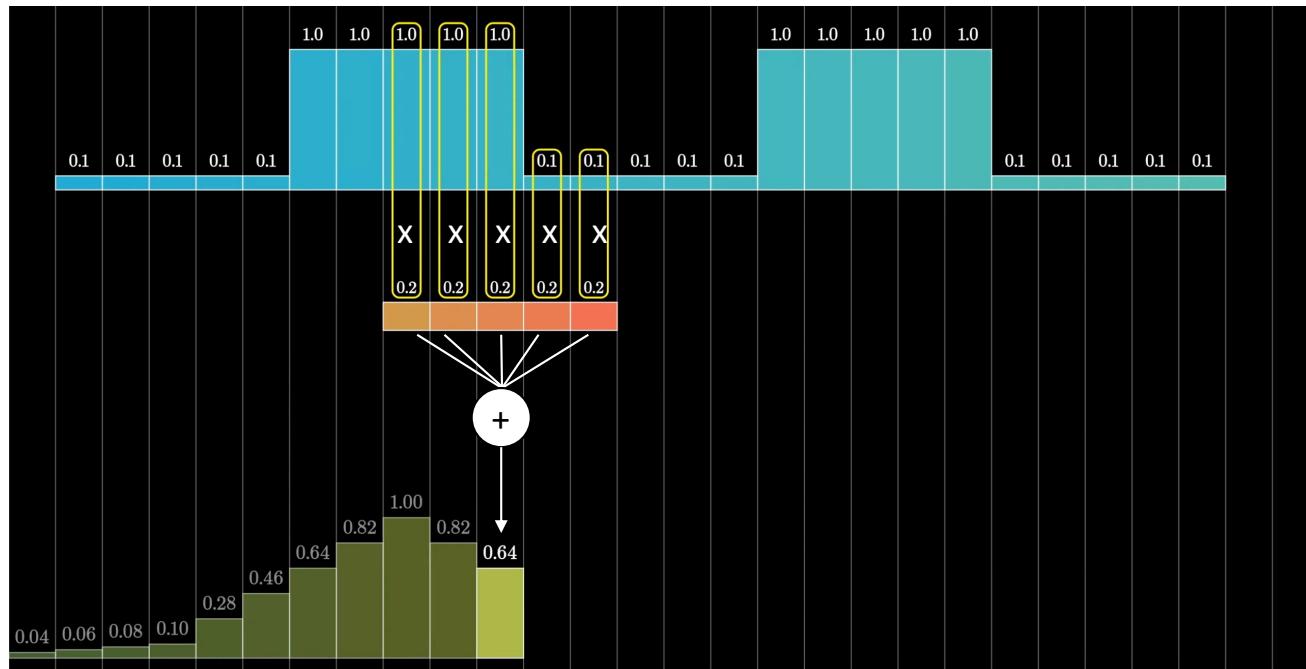
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



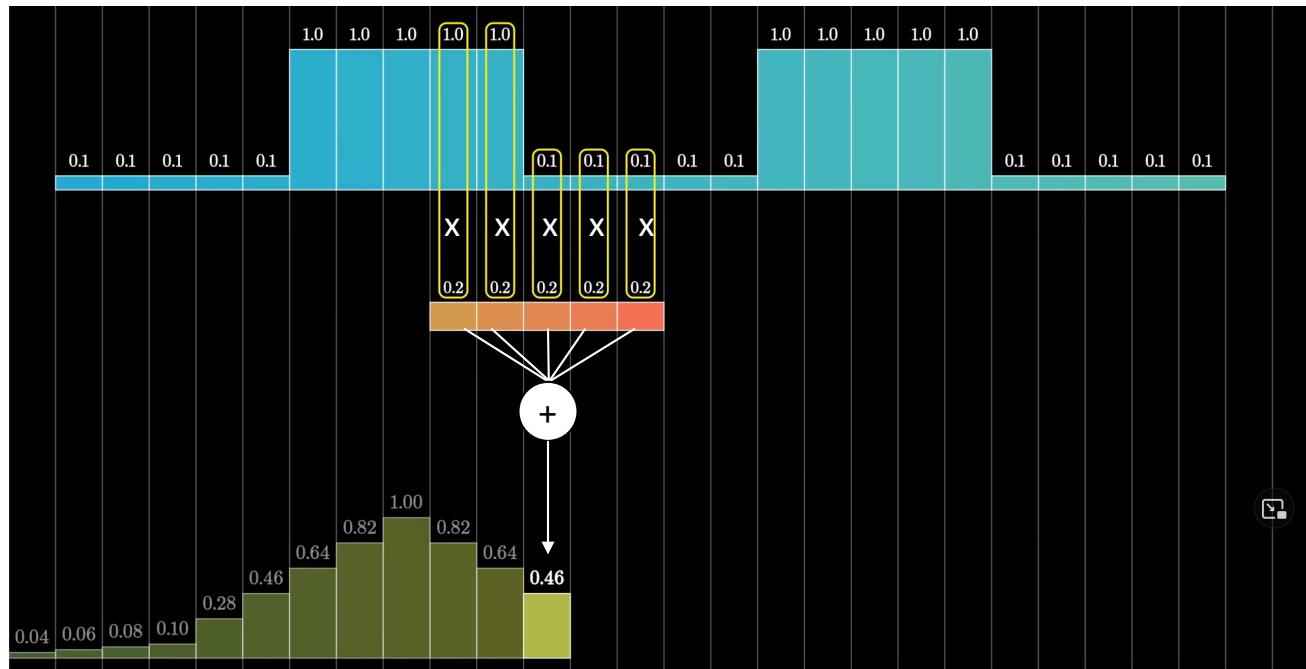
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



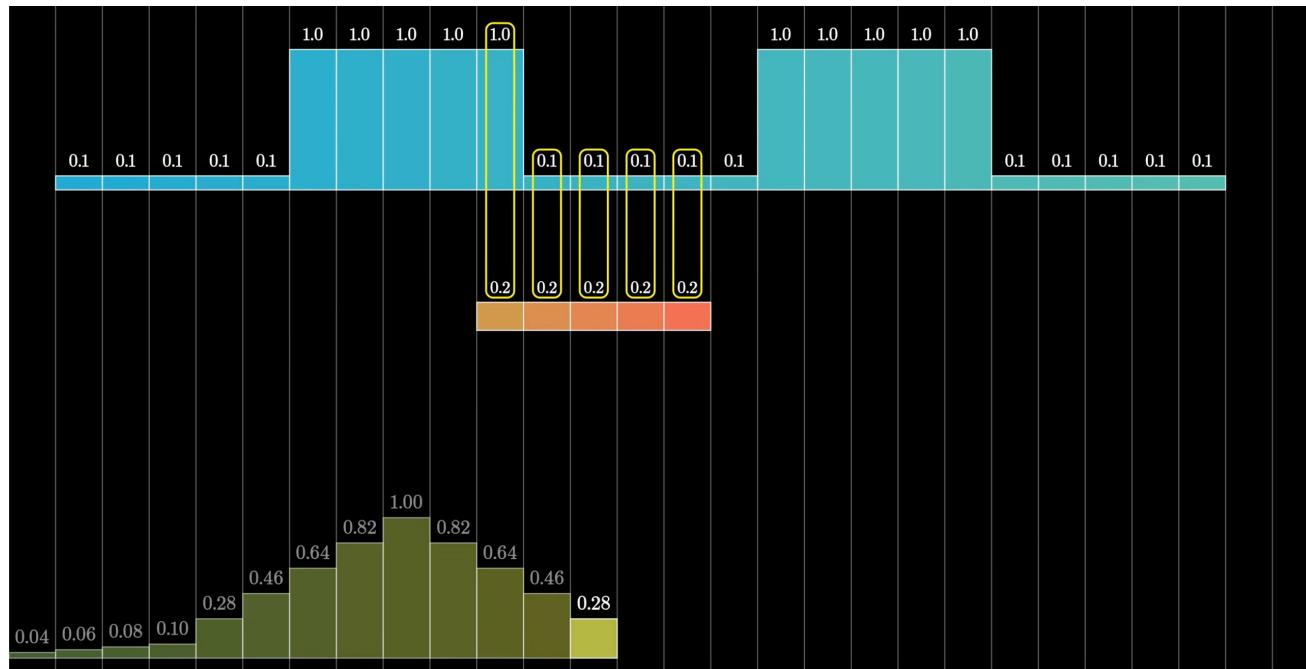
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



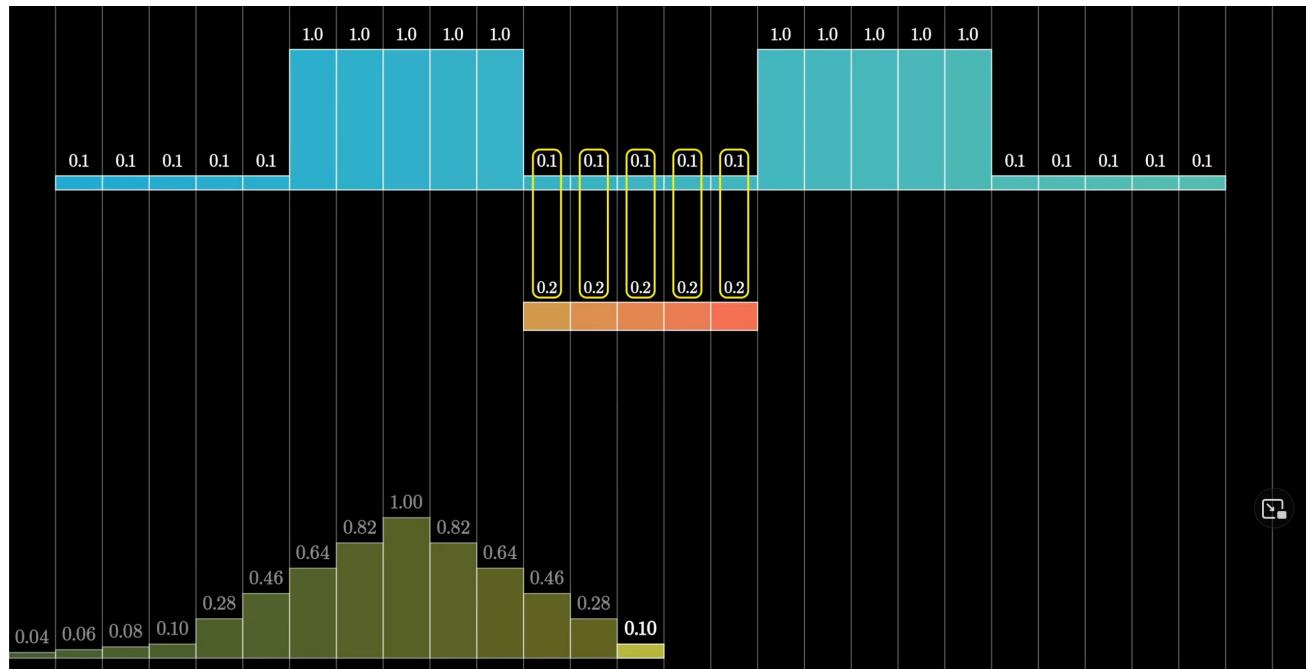
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



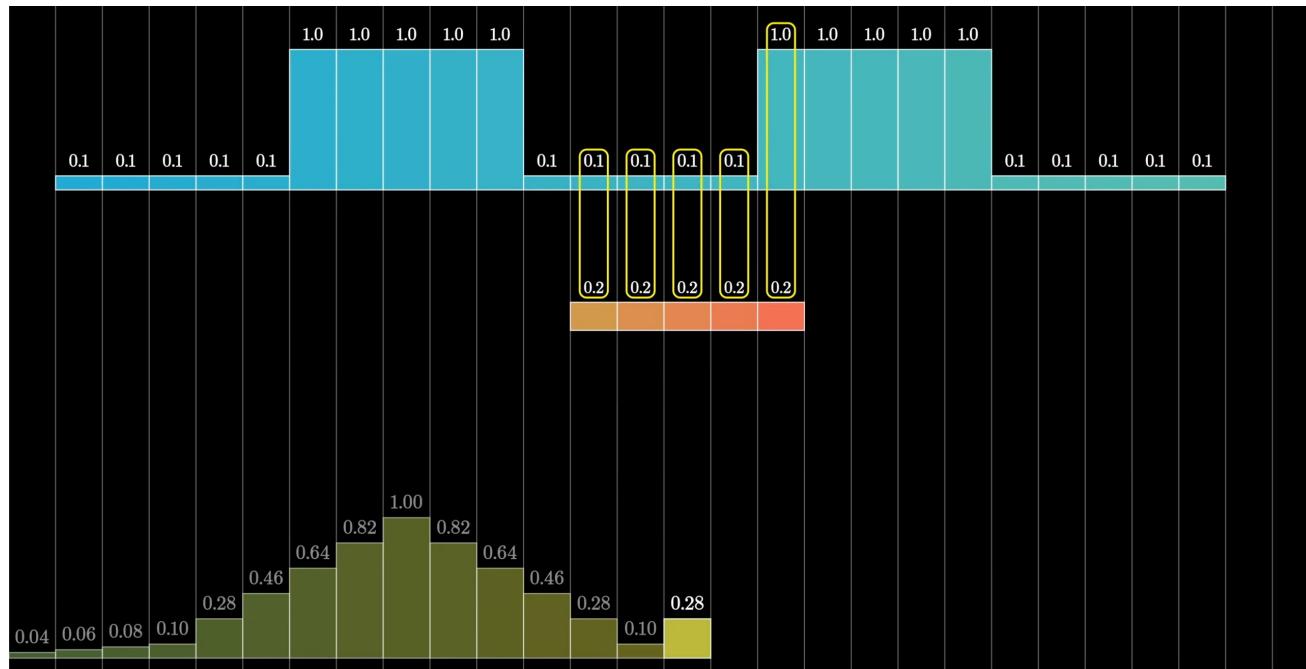
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



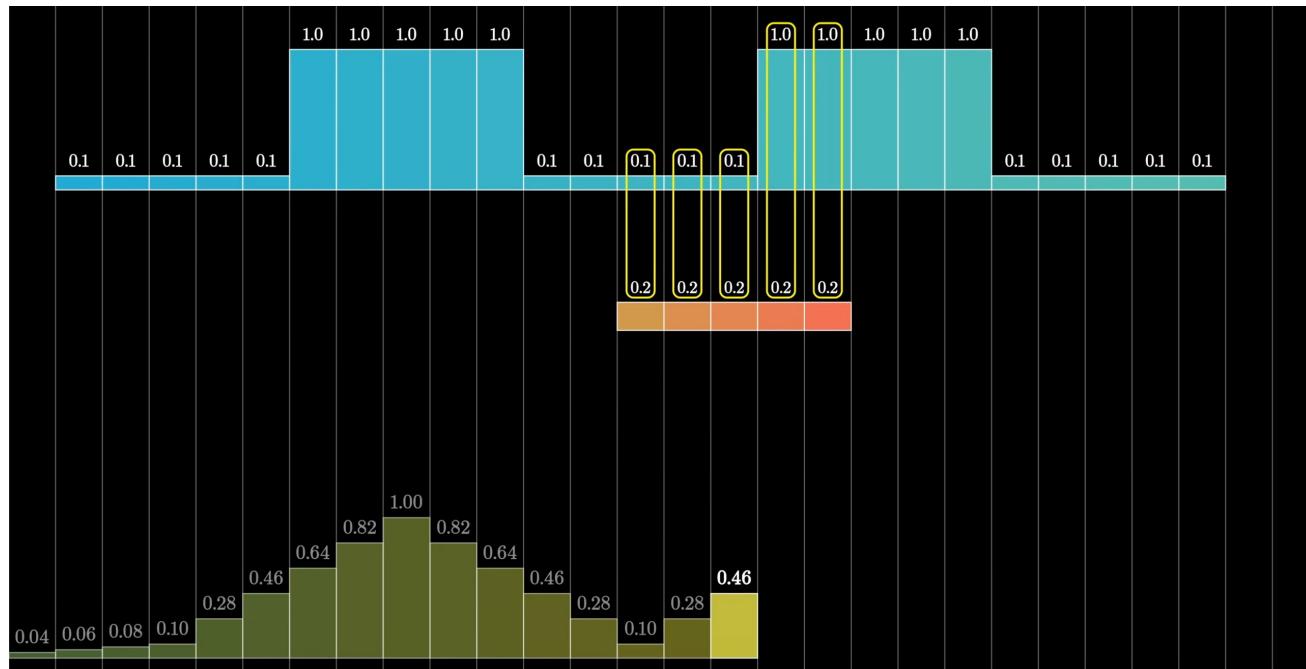
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



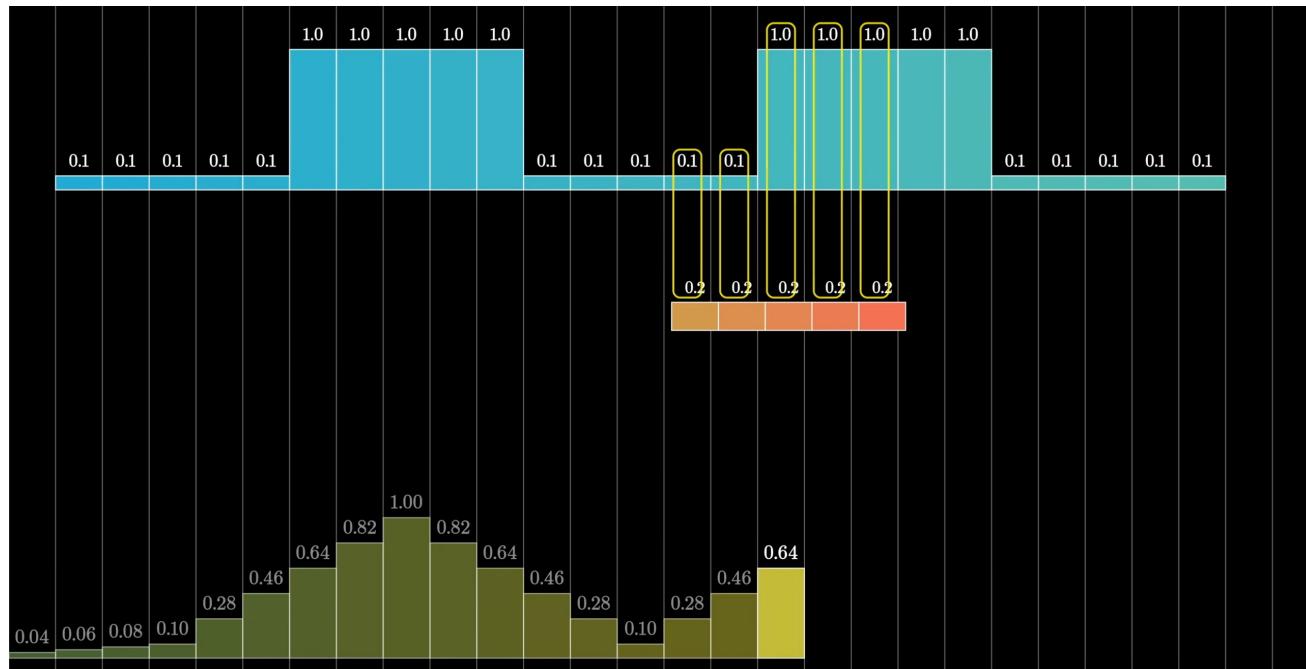
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



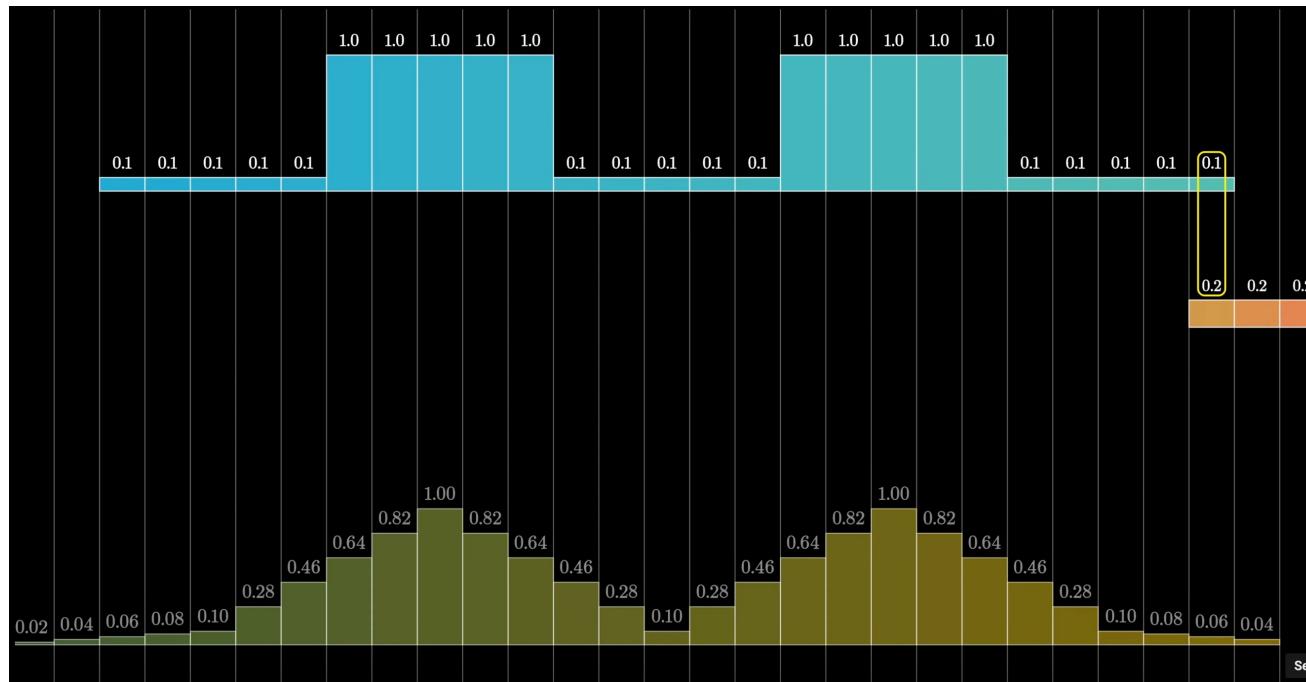
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



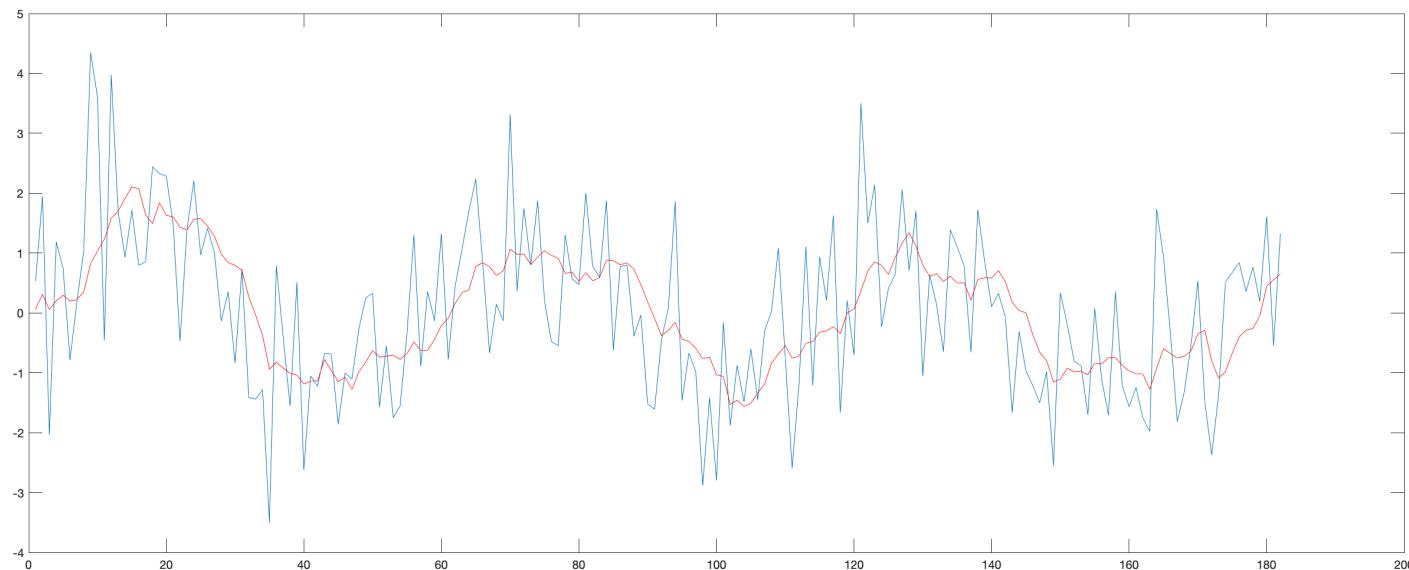
<https://youtu.be/KuXjwB4LzSA>

# What kind of operation?



<https://youtu.be/KuXjwB4LzSA>

# Moving average – 1D Convolution



filter = 1/8 \* [1 1 1 1 1 1 1 1];

# 2D Convolution

Input

|   |   |   |   |   |
|---|---|---|---|---|
| 7 | 2 | 3 | 3 | 8 |
| 4 | 5 | 3 | 8 | 4 |
| 3 | 3 | 2 | 8 | 4 |
| 2 | 8 | 7 | 2 | 7 |
| 5 | 4 | 4 | 5 | 4 |

\*

Kernel/Filter

|   |   |    |
|---|---|----|
| 1 | 0 | -1 |
| 1 | 0 | -1 |
| 1 | 0 | -1 |

=

Feature/Activation map

|   |  |  |
|---|--|--|
| 6 |  |  |
|   |  |  |
|   |  |  |

$$7 \times 1 + 4 \times 1 + 3 \times 1 + \\ 2 \times 0 + 5 \times 0 + 3 \times 0 + \\ 3 \times -1 + 3 \times -1 + 2 \times -1 \\ = 6$$

# Edge detection filter

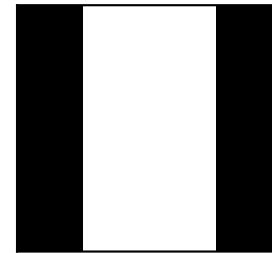
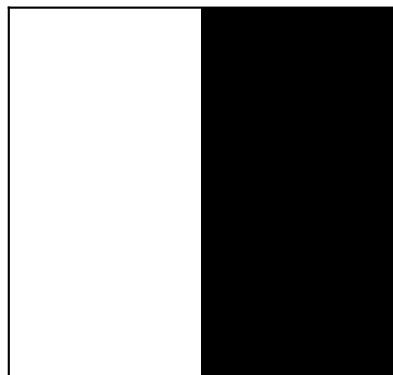
|   |   |   |   |   |   |
|---|---|---|---|---|---|
| 1 | 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | 1 | 0 | 0 | 0 |
| 1 | 1 | 1 | 0 | 0 | 0 |

\*

|   |   |    |
|---|---|----|
| 1 | 0 | -1 |
| 1 | 0 | -1 |
| 1 | 0 | -1 |

=

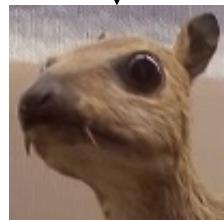
|   |   |   |   |
|---|---|---|---|
| 0 | 3 | 3 | 0 |
| 0 | 3 | 3 | 0 |
| 0 | 3 | 3 | 0 |
| 0 | 3 | 3 | 0 |



# There are many types of filters



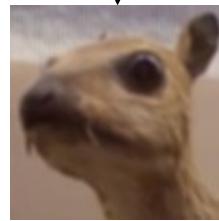
$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$



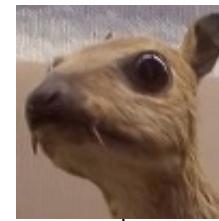
Identity



$$\begin{bmatrix} 1/9 & 1/9 & 1/9 \\ 1/9 & 1/9 & 1/9 \\ 1/9 & 1/9 & 1/9 \end{bmatrix}$$



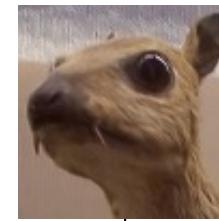
Blur



$$\begin{bmatrix} -1 & -1 & -1 \\ -1 & 8 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$



Edge detection

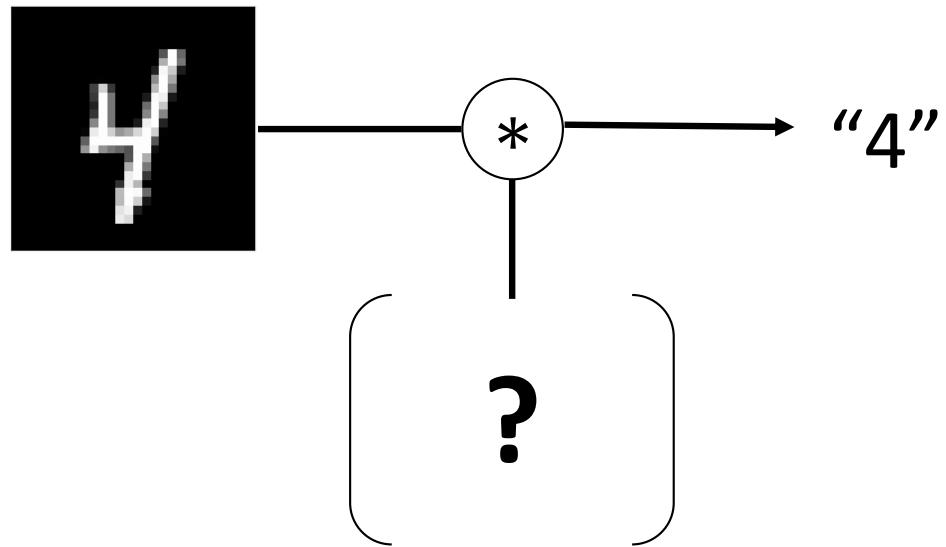


$$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

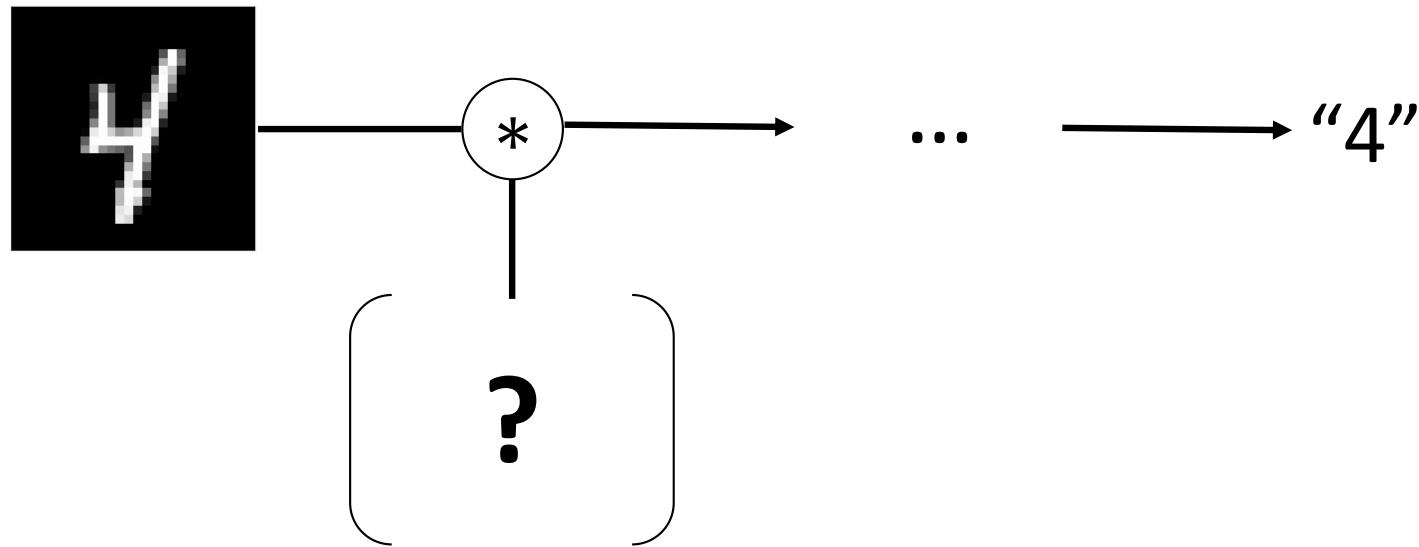


Sharpen

# Filter for digit detection?

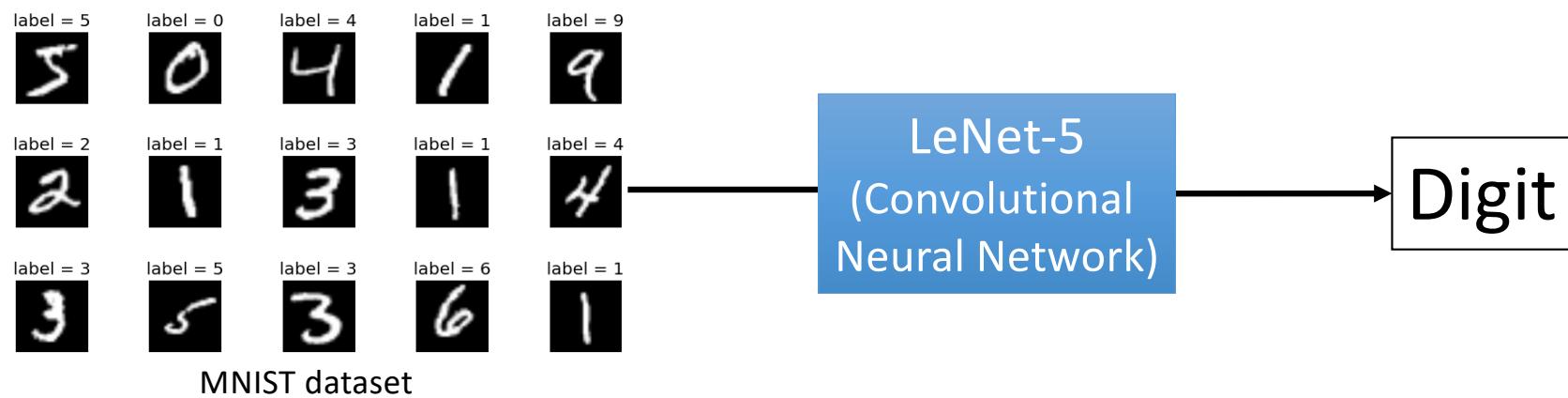


# Filter for digit detection?



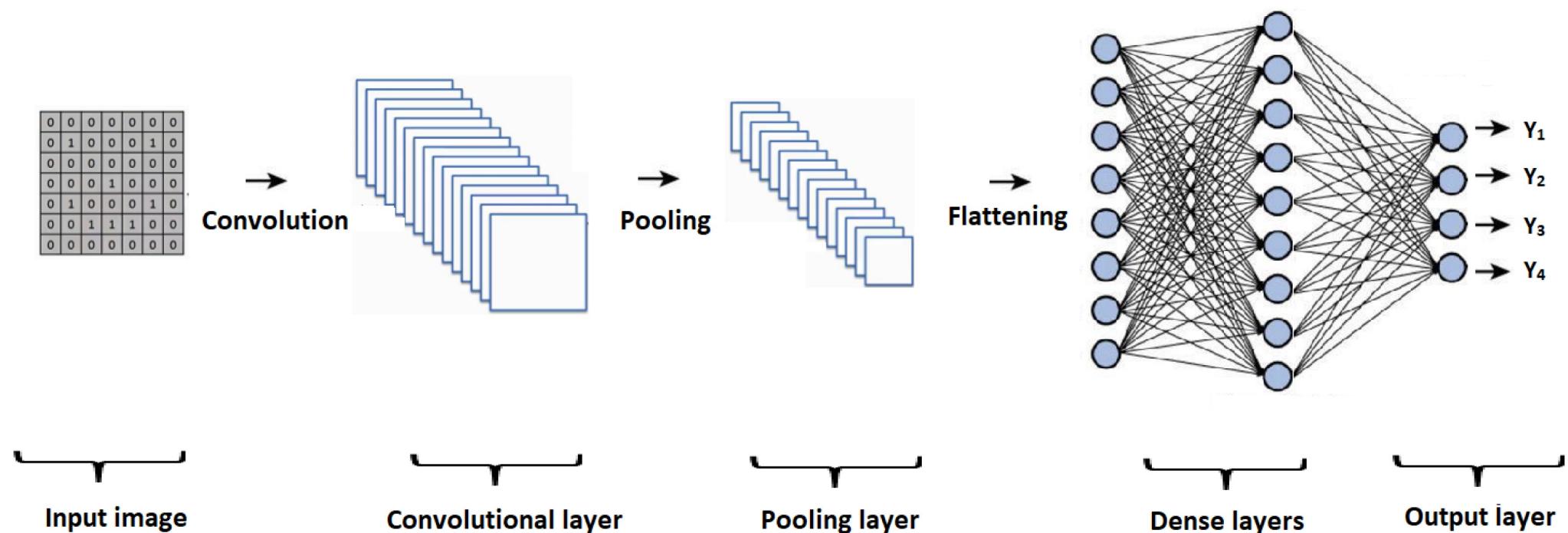
# Let machine learn

# Image processing + Data + Neural network

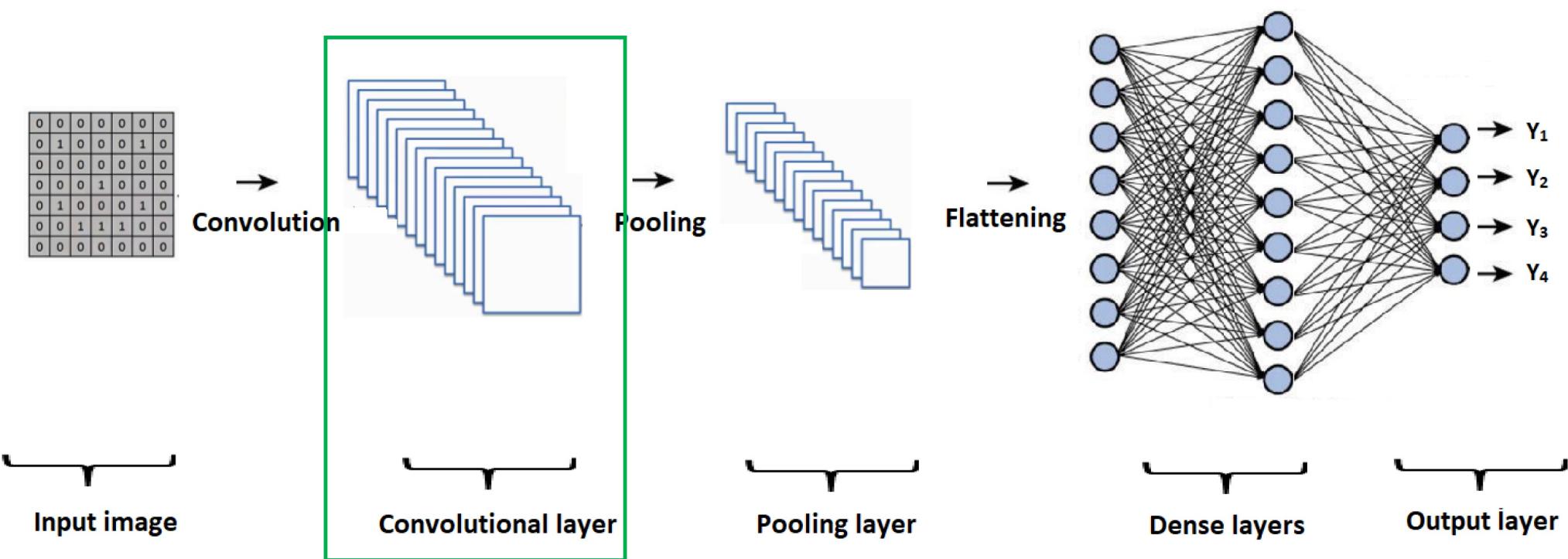


Y. Lecun, L. Bottou, Y. Bengio and P. Haffner, "Gradient-based learning applied to document recognition,"  
in *Proceedings of the IEEE*, vol. 86, no. 11, pp. 2278-2324, Nov. 1998, doi: 10.1109/5.726791.

# Convolutional Neural Network Architecture



# Convolutional Neural Network Architecture



# Convolutional layer

- Convolution operation

Input

|   |   |   |   |   |
|---|---|---|---|---|
| 7 | 2 | 3 | 3 | 8 |
| 4 | 5 | 3 | 8 | 4 |
| 3 | 3 | 2 | 8 | 4 |
| 2 | 8 | 7 | 2 | 7 |
| 5 | 4 | 4 | 5 | 4 |

\*

Kernel/Filter

|   |   |    |
|---|---|----|
| 1 | 0 | -1 |
| 1 | 0 | -1 |
| 1 | 0 | -1 |

=

Feature/Activation map

|   |  |  |
|---|--|--|
| 6 |  |  |
|   |  |  |
|   |  |  |

$$7 \times 1 + 4 \times 1 + 3 \times 1 + \\ 2 \times 0 + 5 \times 0 + 3 \times 0 + \\ 3 \times -1 + 3 \times -1 + 2 \times -1 \\ = 6$$

# Convolutional layer

- Padding

|   |     |     |     |     |     |   |
|---|-----|-----|-----|-----|-----|---|
| 0 | 0   | 0   | 0   | 0   | 0   | 0 |
| 0 | 60  | 113 | 56  | 139 | 85  | 0 |
| 0 | 73  | 121 | 54  | 84  | 128 | 0 |
| 0 | 131 | 99  | 70  | 129 | 127 | 0 |
| 0 | 80  | 57  | 115 | 69  | 134 | 0 |
| 0 | 104 | 126 | 123 | 95  | 130 | 0 |
| 0 | 0   | 0   | 0   | 0   | 0   | 0 |

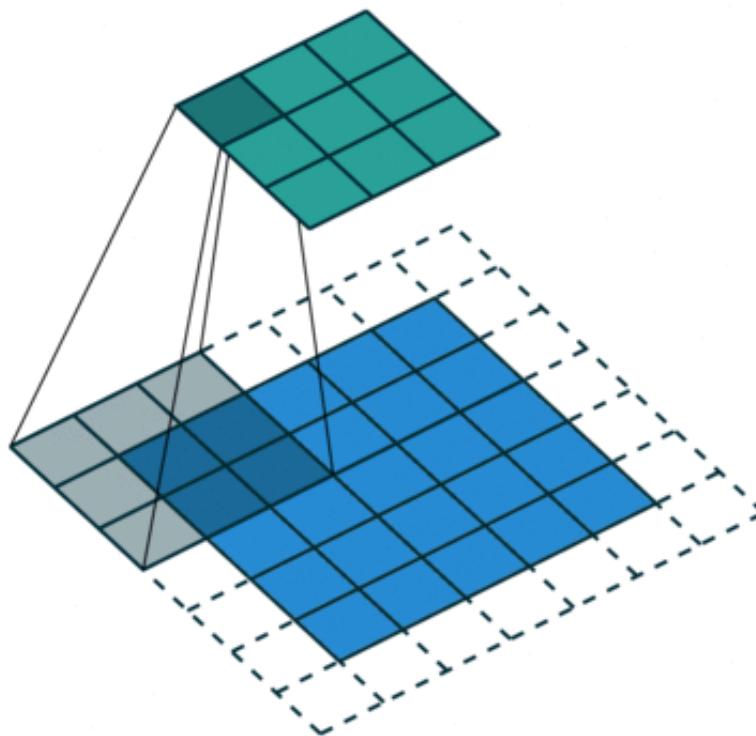
Kernel

|    |    |    |
|----|----|----|
| 0  | -1 | 0  |
| -1 | 5  | -1 |
| 0  | -1 | 0  |

|     |  |  |  |  |
|-----|--|--|--|--|
| 114 |  |  |  |  |
|     |  |  |  |  |
|     |  |  |  |  |
|     |  |  |  |  |
|     |  |  |  |  |

# Convolutional layer

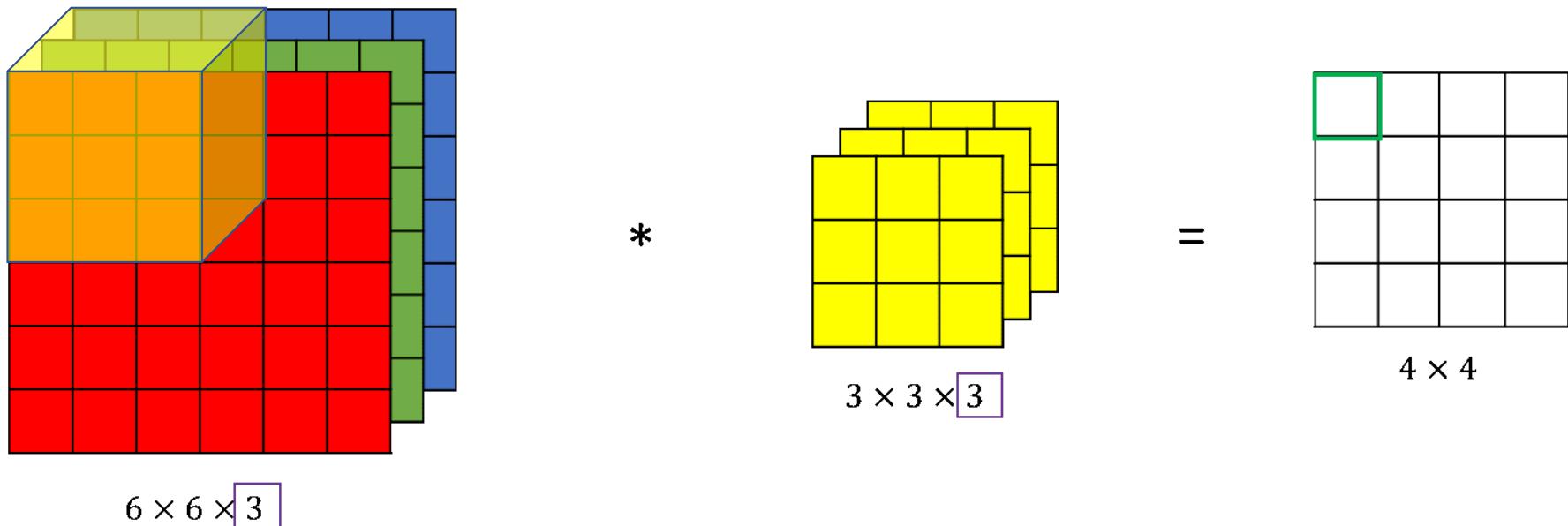
- Stride



Example: Padding = 1, Stride = 2

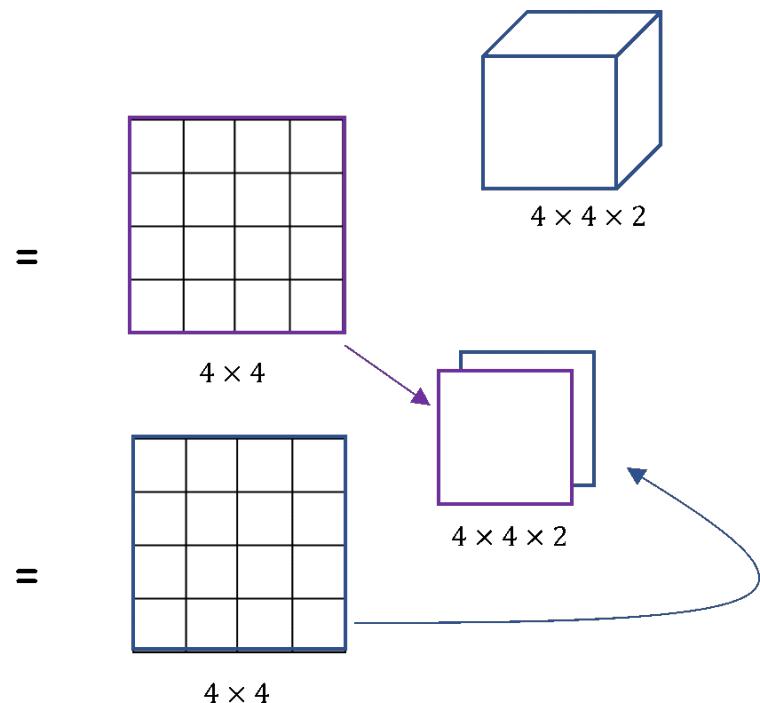
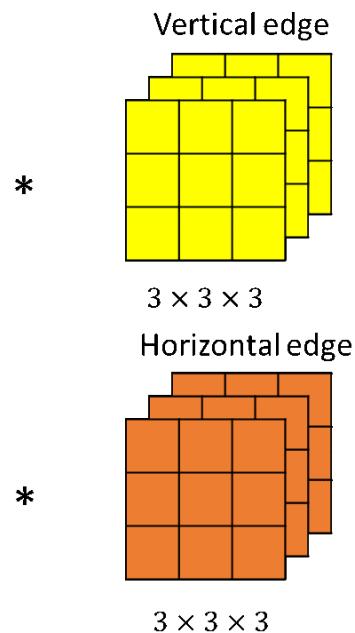
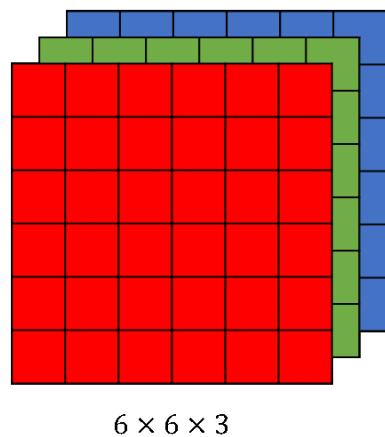
# Convolutional layer

- Convolution over volume



# Convolutional layer

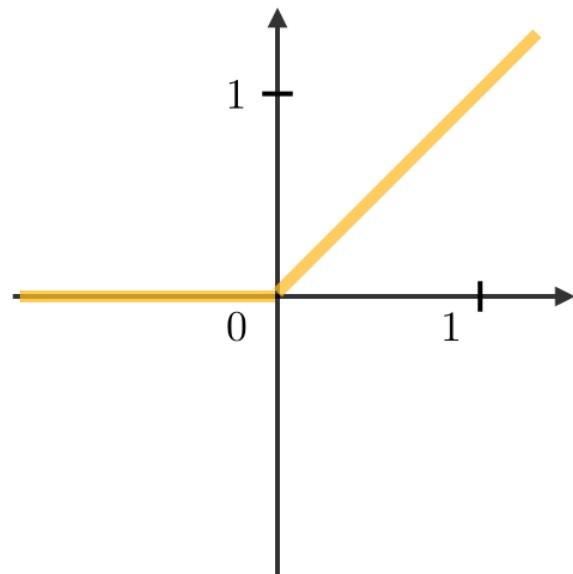
- Stacking activation maps



# Activation functions

- Rectified Linear Unit (ReLU)

$$g(z) = \max(0, z)$$



Filter 1 Feature Map

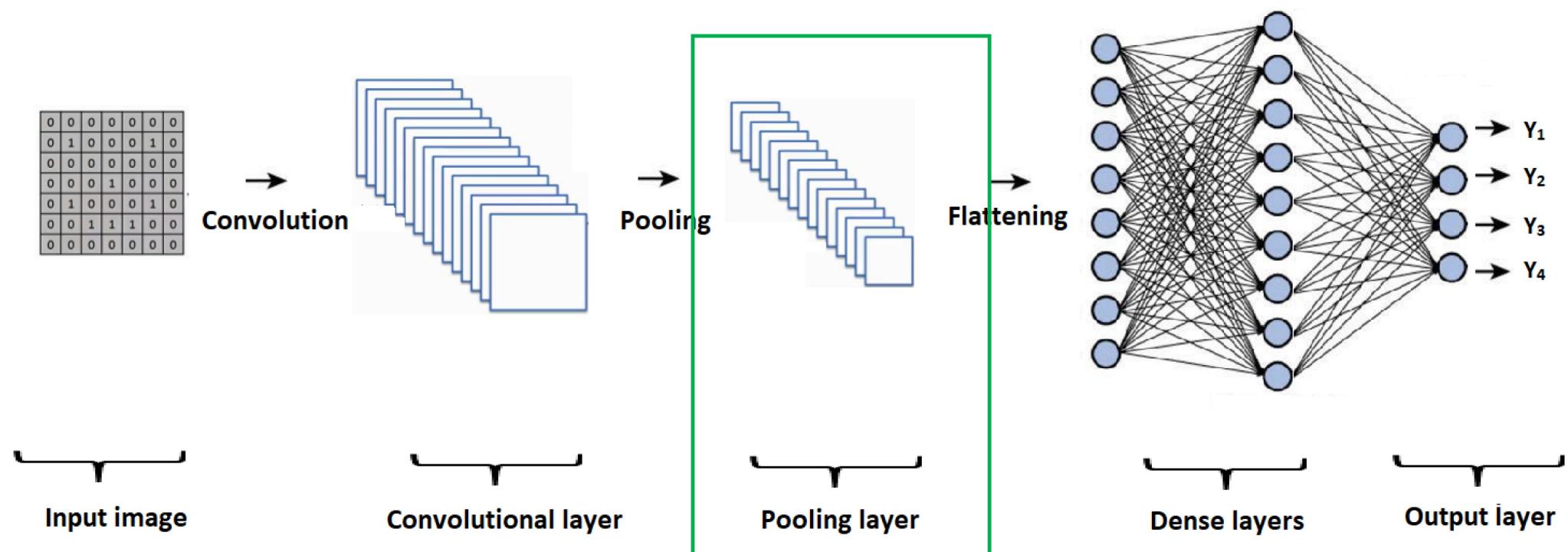
|    |    |    |    |
|----|----|----|----|
| 9  | 3  | 5  | -8 |
| -6 | 2  | -3 | 1  |
| 1  | 3  | 4  | 1  |
| 3  | -4 | 5  | 1  |

ReLU Layer

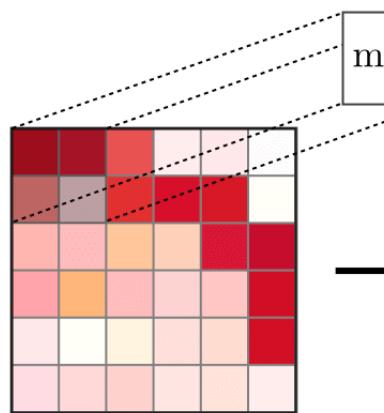


|   |   |   |   |
|---|---|---|---|
| 9 | 3 | 5 | 0 |
| 0 | 2 | 0 | 1 |
| 1 | 3 | 4 | 1 |
| 3 | 0 | 5 | 1 |

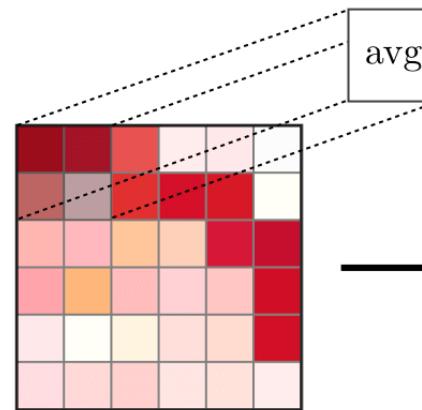
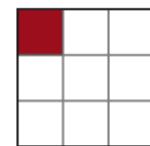
# Convolutional Neural Network Architecture



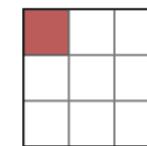
# Pooling layer



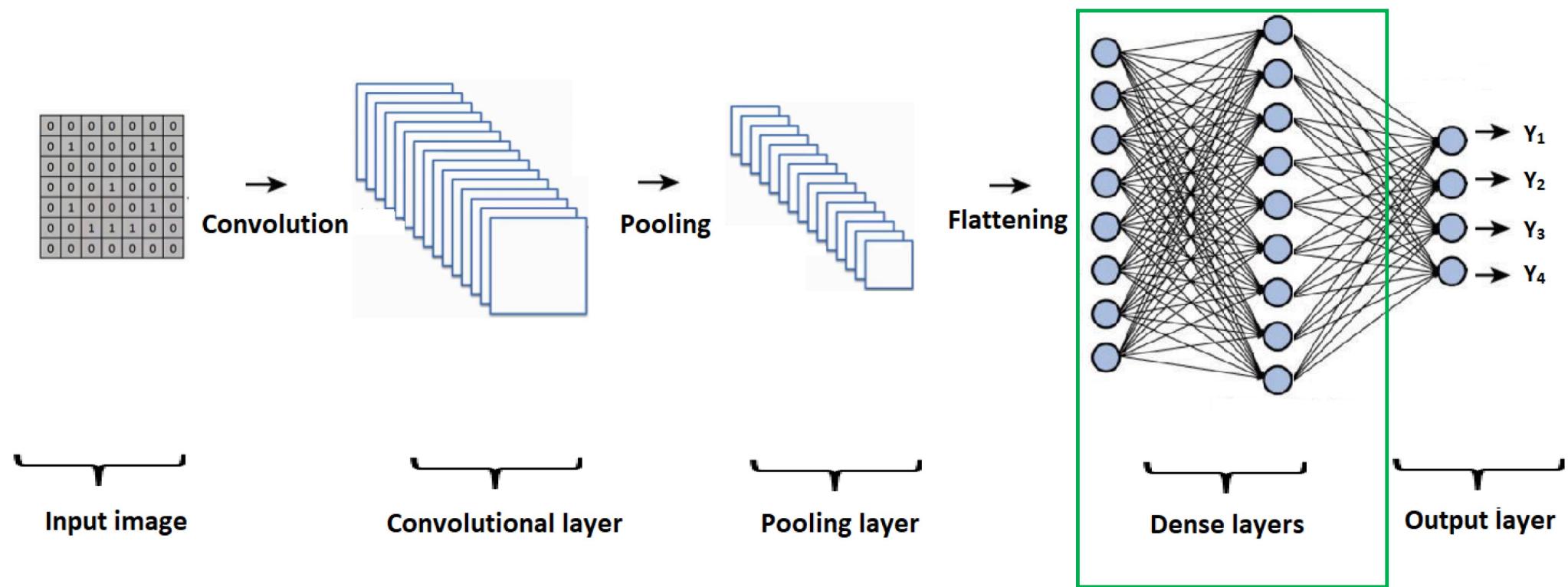
max



avg



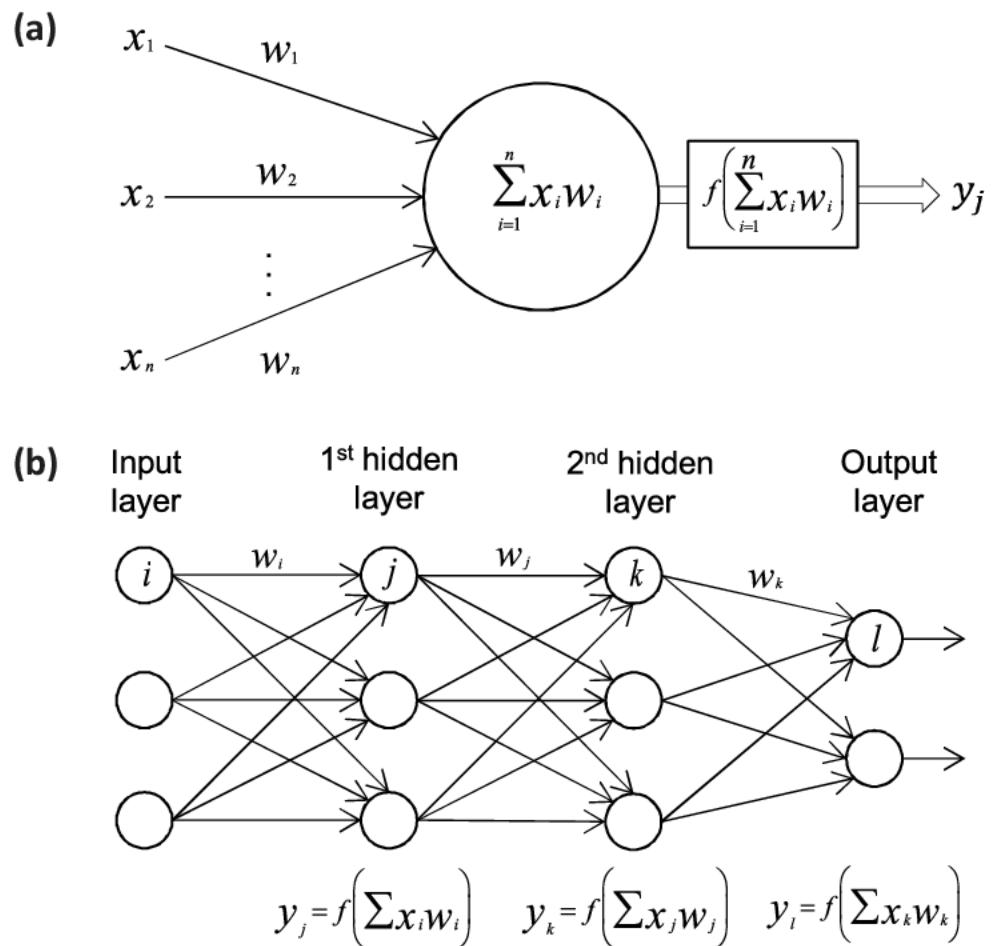
# Convolutional Neural Network Architecture



<https://www.mdpi.com/2076-3417/10/4/1245/htm>

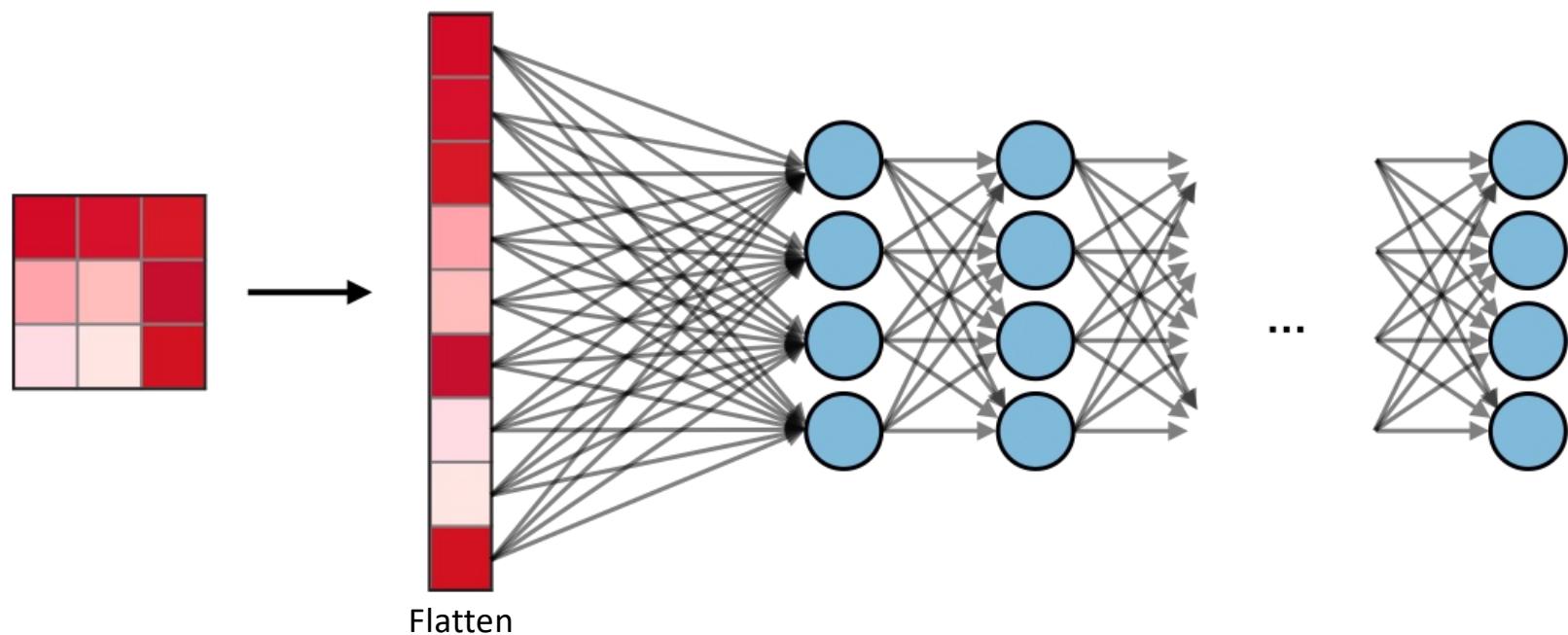
# Fully connected layer

- Also known as dense layer
- Each input is connected to all hidden units



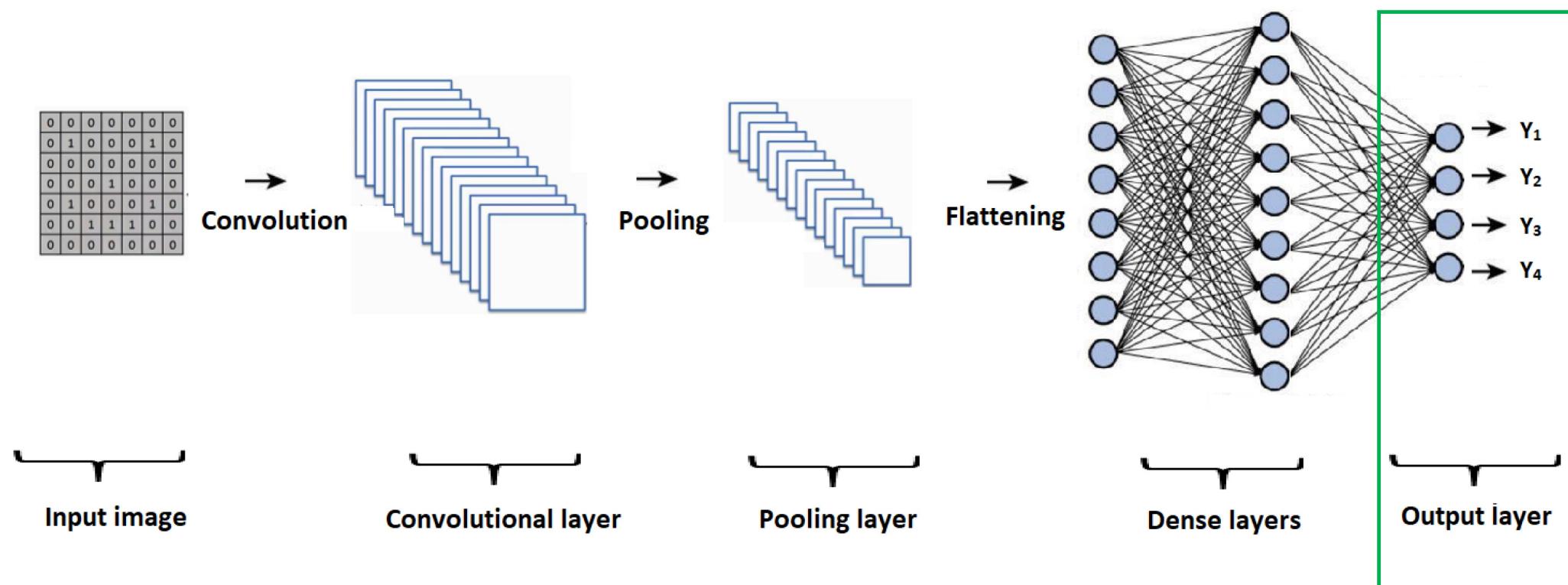
# Fully connected layer

- Flattening



<https://stanford.edu/~shervine/teaching/cs-230/cheatsheet-convolutional-neural-networks#layer>

# Convolutional Neural Network Architecture



<https://www.mdpi.com/2076-3417/10/4/1245/htm>

# Activation function for classification

- Softmax

$$p = \begin{pmatrix} p_1 \\ \vdots \\ p_n \end{pmatrix} \quad \text{where} \quad p_i = \frac{e^{x_i}}{\sum_{j=1}^n e^{x_j}}$$

# Loss function

- Cross-entropy loss

$$L = -\frac{1}{m} \sum_{i=1}^m y_i \cdot \log(\hat{y}_i)$$

$y$  is a one-hot vector ( $[0,0,1,\dots,0]$ )

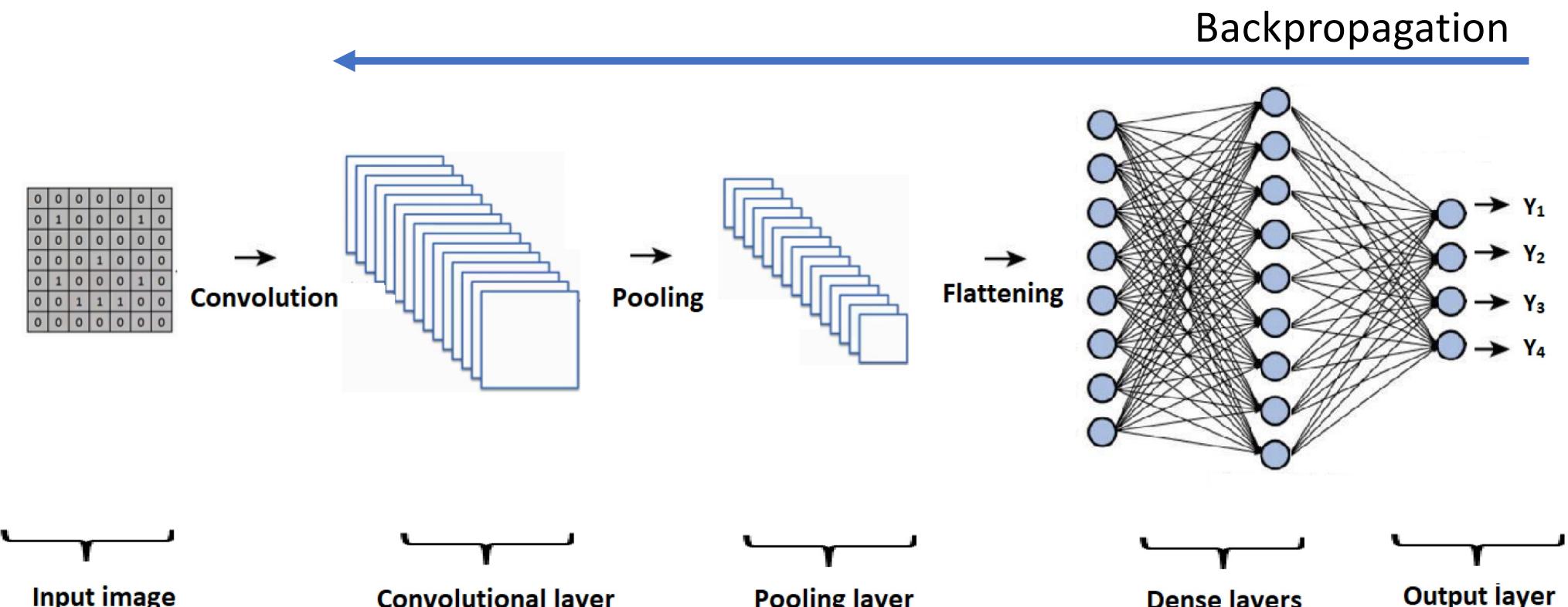
# Gradient descent

$$\theta_j = \theta_j - \alpha \frac{\partial}{\partial \theta_j} L$$

↑  
Parameters

↑  
Learning rate

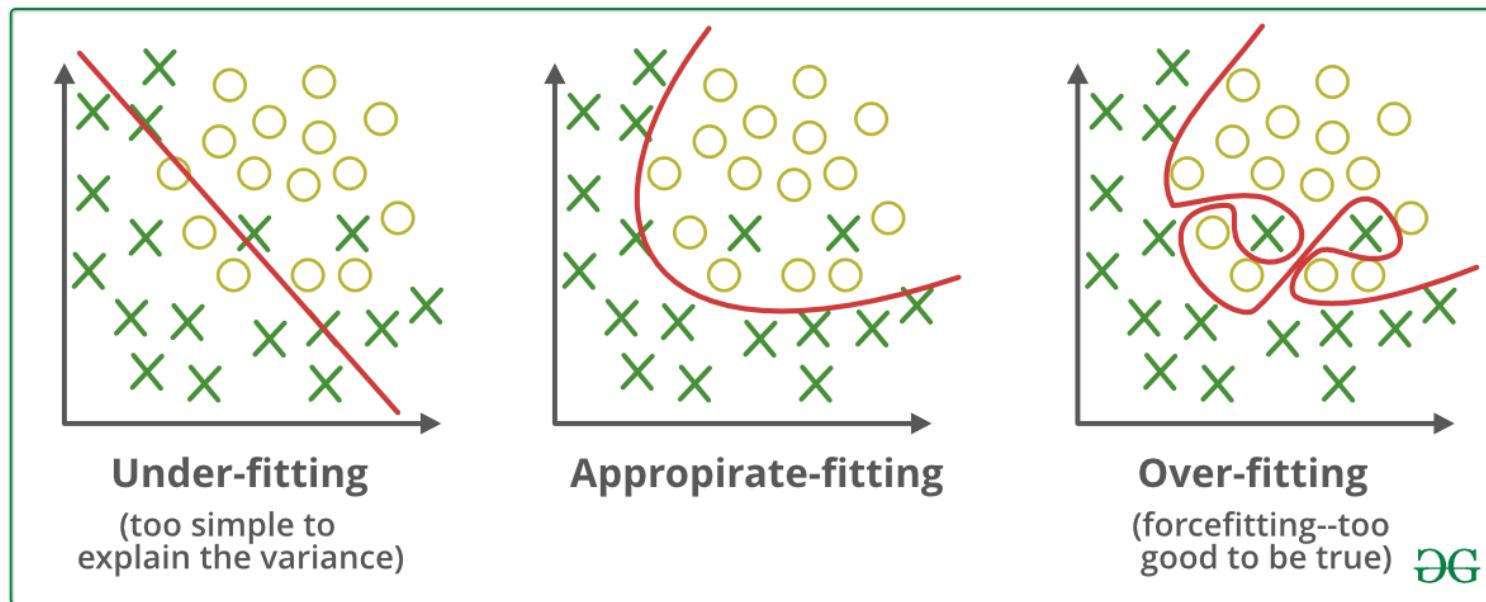
# Training the network



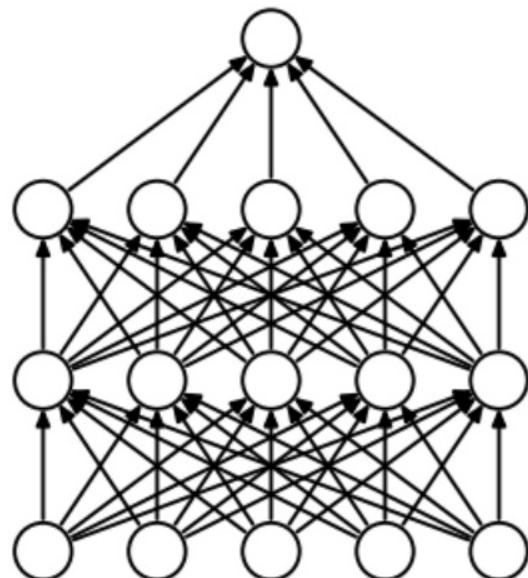
<https://www.mdpi.com/2076-3417/10/4/1245/htm>

# Dropout

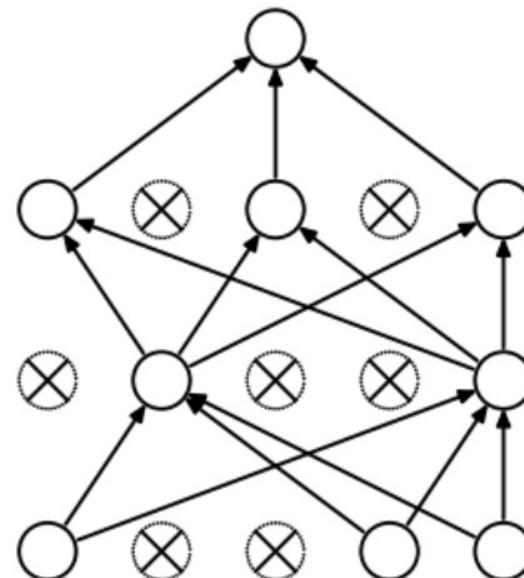
- Overfitting



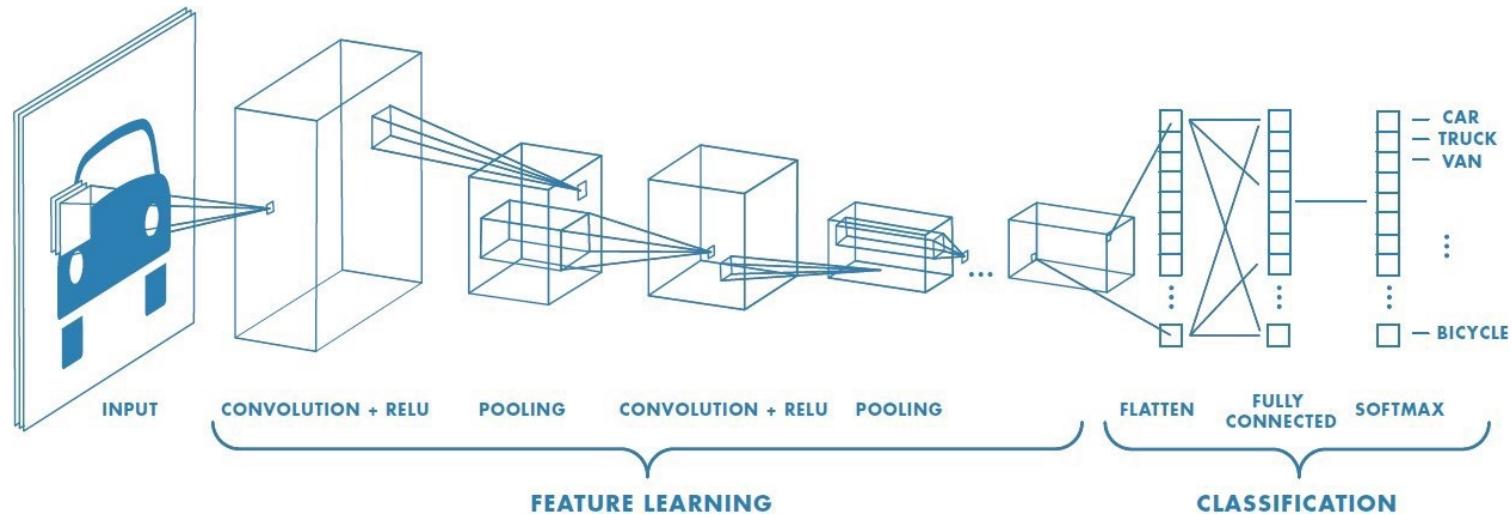
# Dropout



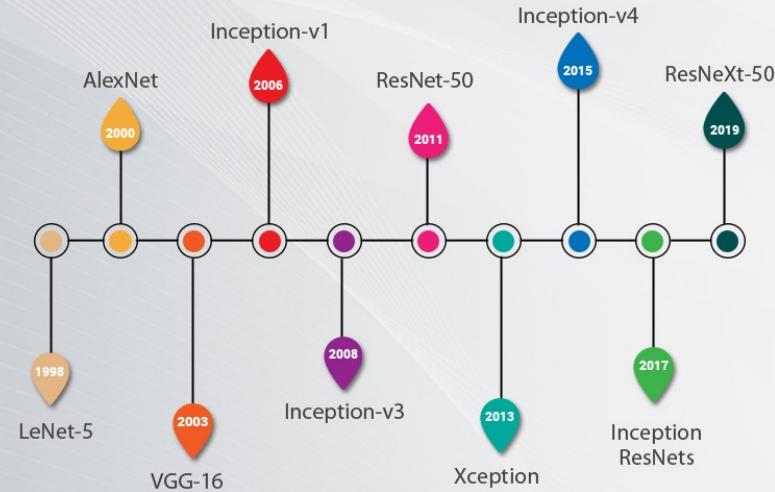
(a) Standard Neural Net



(b) After applying dropout.



## CNN architectures over a timeline(1998-2019)



COCO 2020 Panoptic Segmentation Task



IMDb



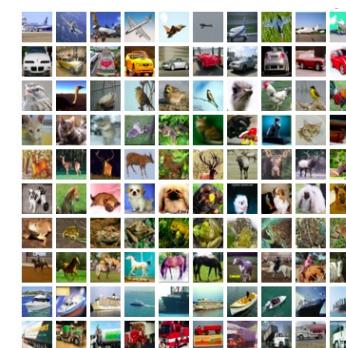
460,723 images

Wikipedia

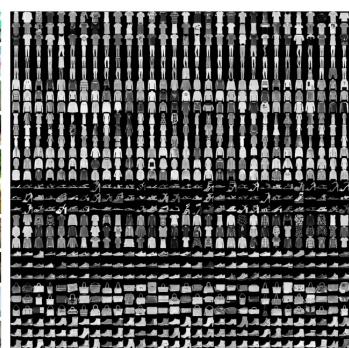


62,328 images

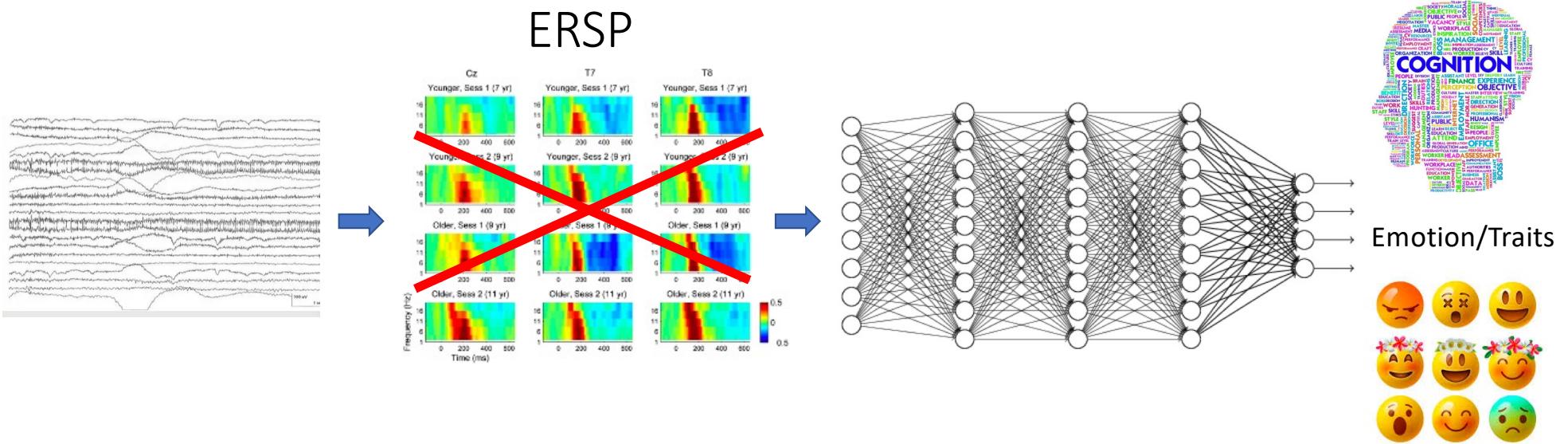
CIFAR-10



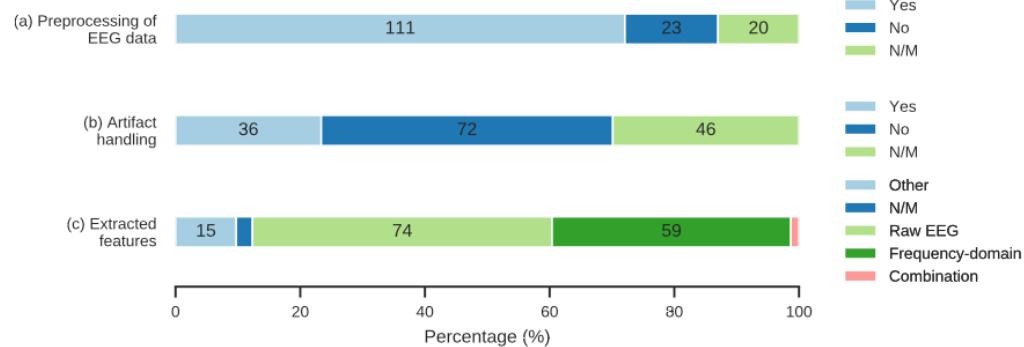
Fashion MNIST



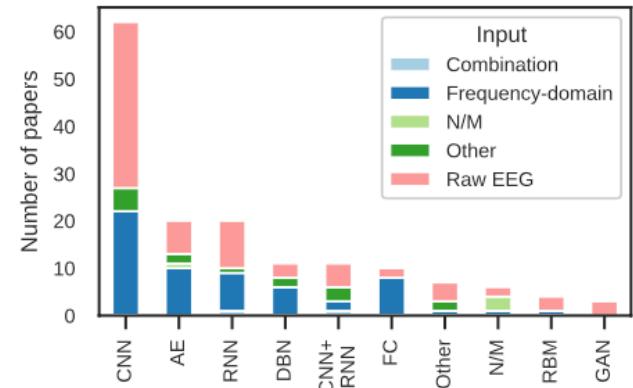
# Applying to EEG



# Raw EEG vs. Frequency-domain

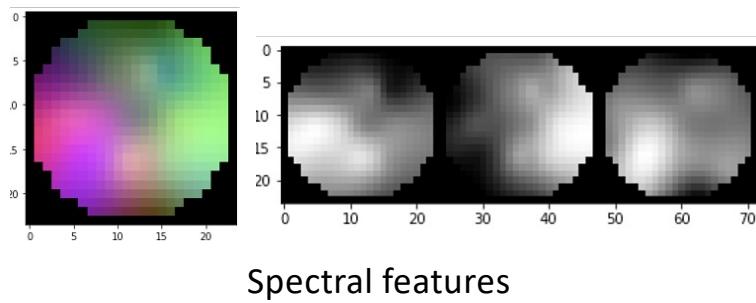


**Figure 9.** EEG processing choices. (a) Number of studies that used preprocessing steps, such as filtering, (b) number of studies that included, rejected or corrected artifacts in their data and (c) types of features that were used as input to the proposed models.

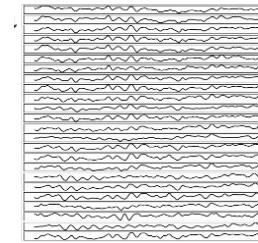


Distribution of input type according to the architecture category.

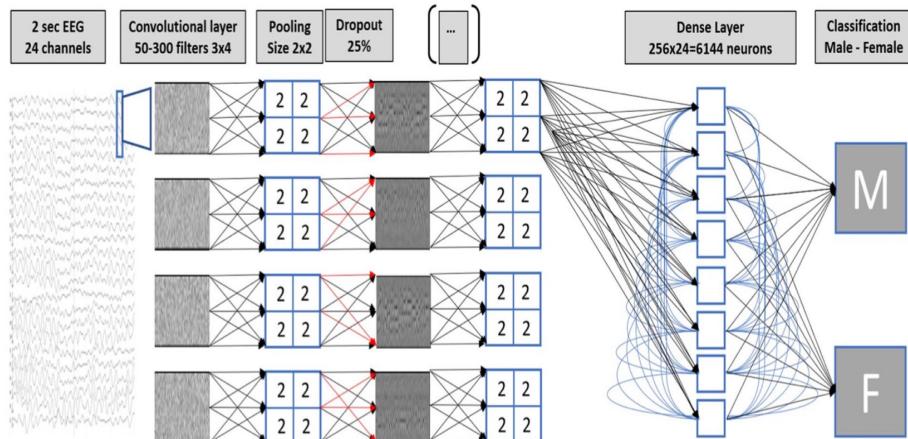
# Our approach



VS.

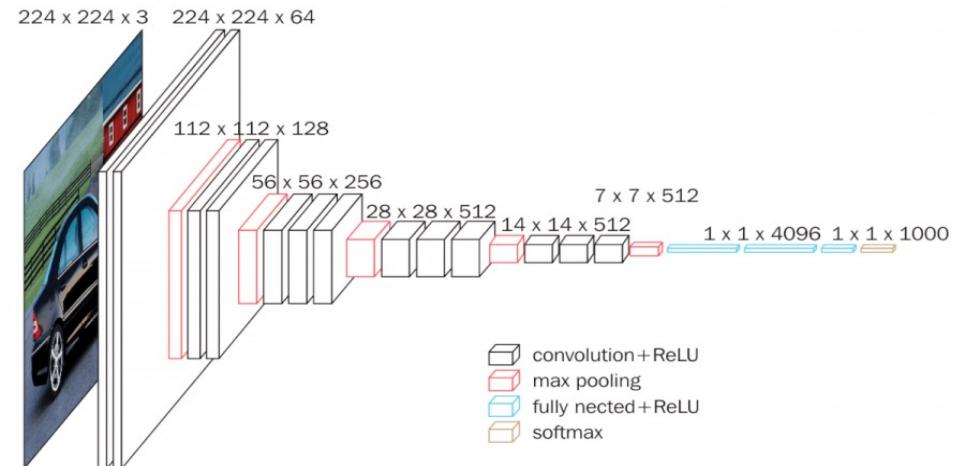


Raw EEG



van Putten et al. (2018)

VS.



Simonyan, K. and Zisserman A. (2014)

# Data Data Data Data Data Data Data



**Michael Milham, PI**

- 128 channels EEG
- ~3,000 EEG datasets (planed 10,000)
- Tasks involving emotions (The Gift movie)
- Rest (eyes open and eyes closed)



# Data

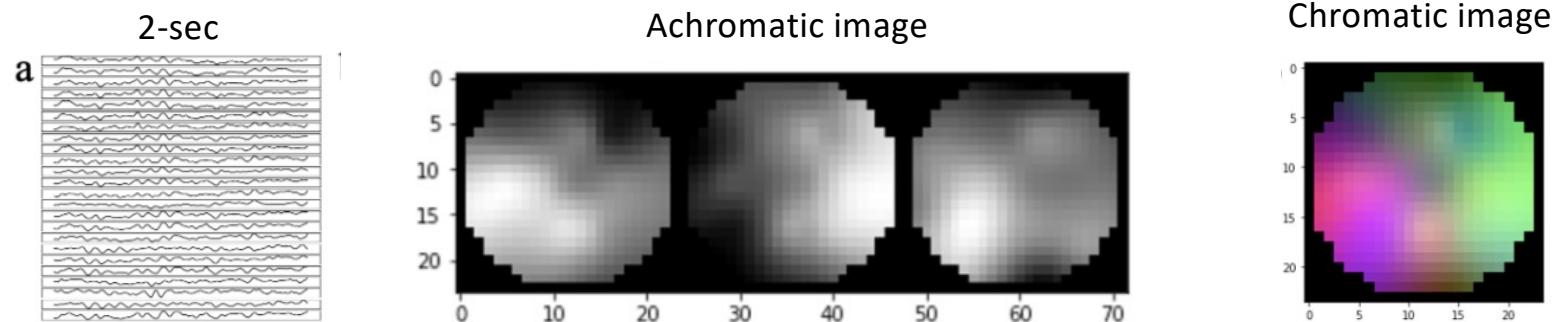
- 2224 subjects:
  - 787 female (35%)
  - Ages: min 5, max 22, mean 10
- Pre-processing following the paper:
  - Remove baseline
  - Filter 0.25-25Hz
  - Resample 128Hz
  - Re-reference to average mastoids
  - Epoching: eye-closed, 3 40-second blocks. Ignored first and last 3 seconds of each block
  - clean\_rawdata – ASR (our)
  - Sub-select 24 channels
    - Fp1, Fp2, F7, F3, Fz, F4, F8, FC3, FCz, FC4, T3, C3, C4, T4, CP3, CPz, CP4, T5, P3, Pz, P4, T6, O1, Cz
  - Segment 2-second non-overlapping windows
    - → ~ 81 samples per subject

# Data

- Sub-select 1574 participants (50% female) 24-channels
  - 2-second extracted epochs eyes open and eyes closed
  - 5 predictors: **sex**, **handedness**, **eyes open/closed**, **age**, **segment count**

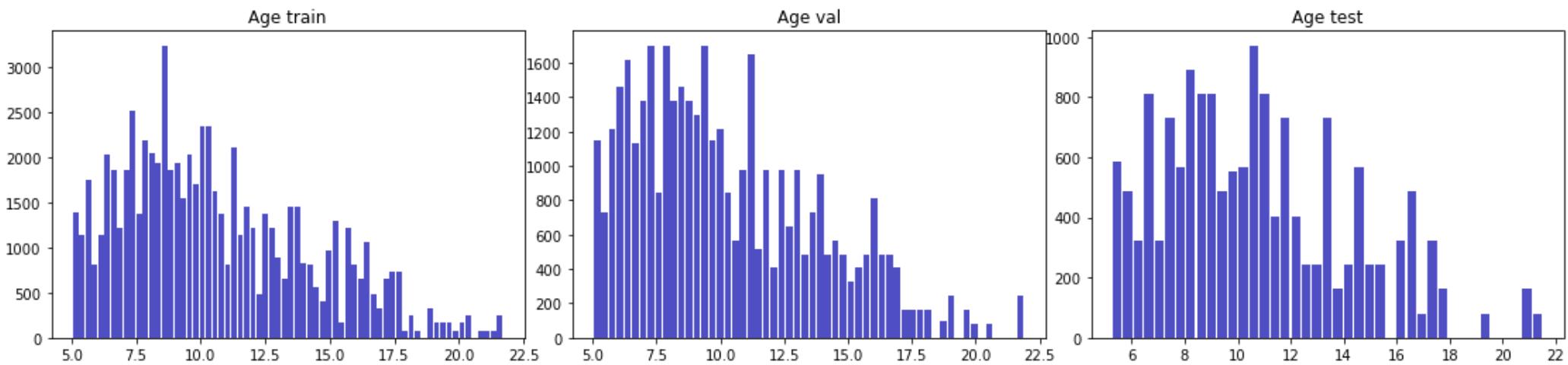
Categorical

# Continuous

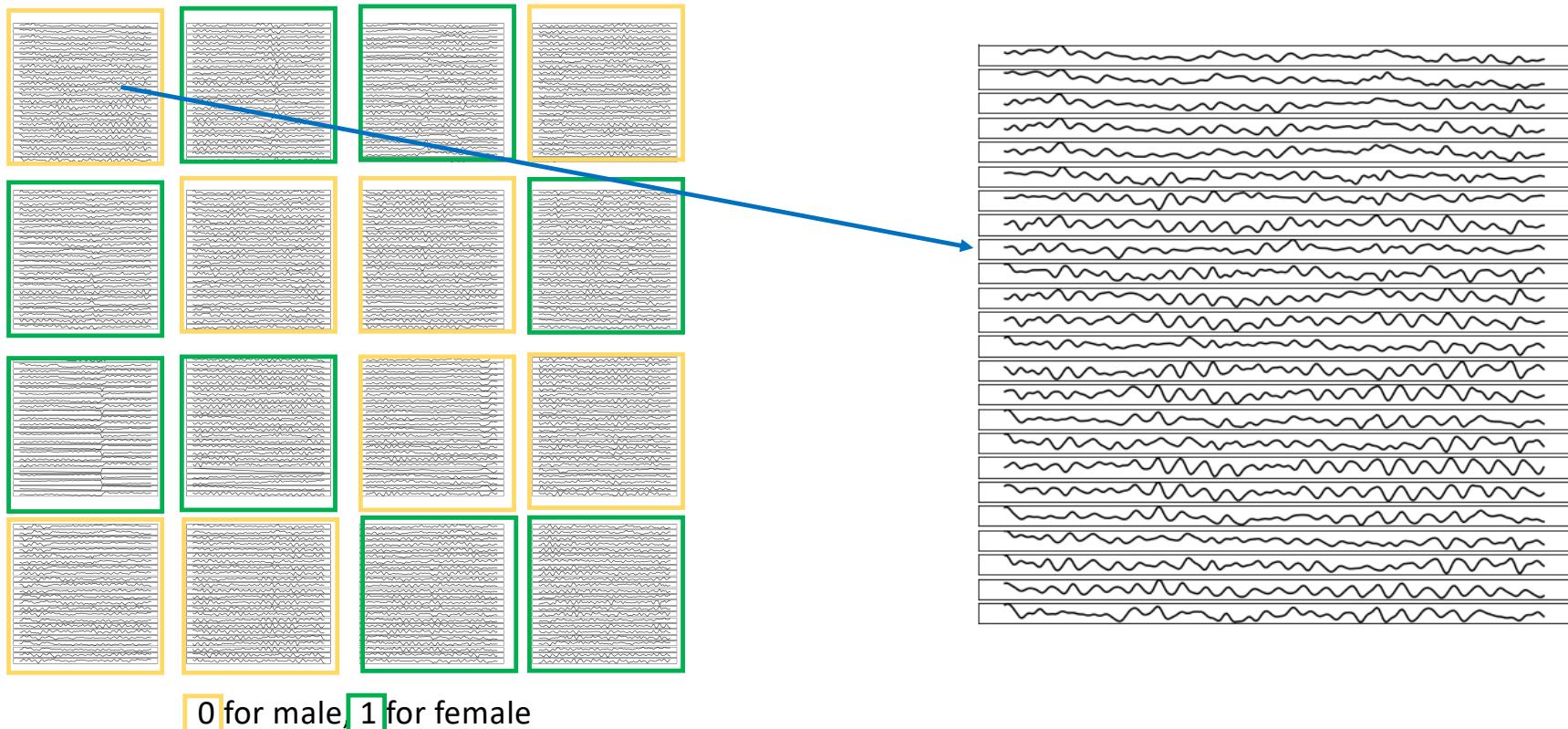


# Data

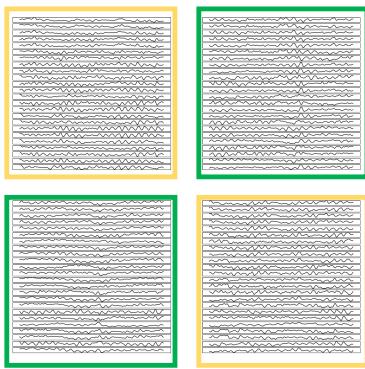
- 10-30-60 split
  - 885 subjects for training → 71,381 samples
  - 492 subjects for validation → 39,868 samples
  - 197 subjects for testing → 15,925 samples



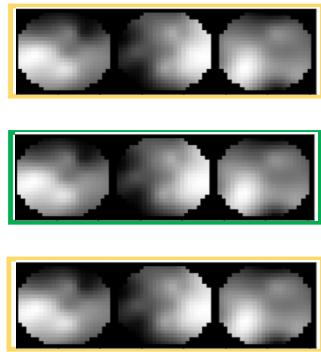
**Input data  $24 \times 256 \times n$**



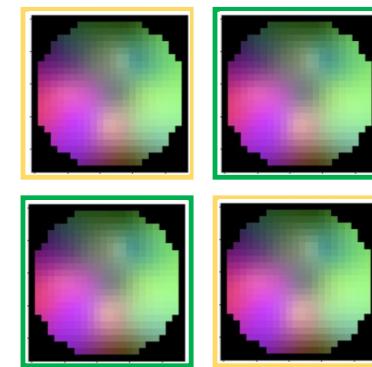
**Raw input data**  
 **$24 \times 256 \times n$**



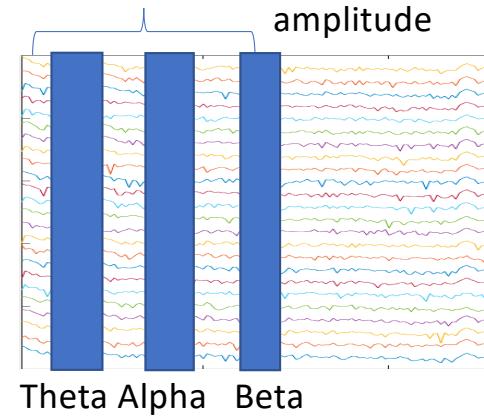
**Spectral data**  
 **$24 \times 72 \times n$**



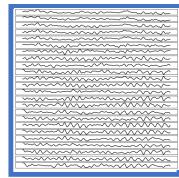
**Spectral data**  
 **$24 \times 24 \times n$**



Tapered FFT  
 $24 \times 256$  complex

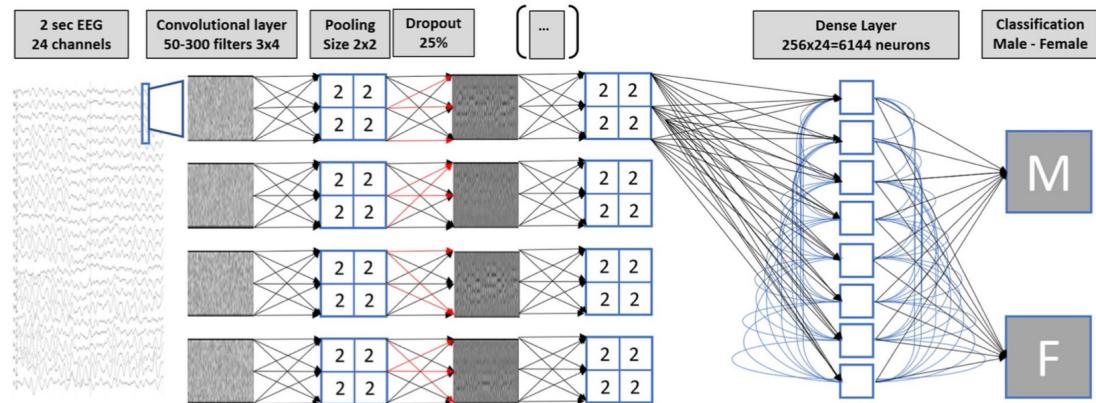
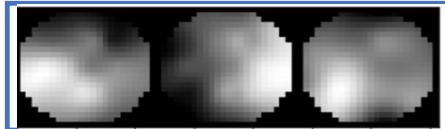


R-SCNN



Or

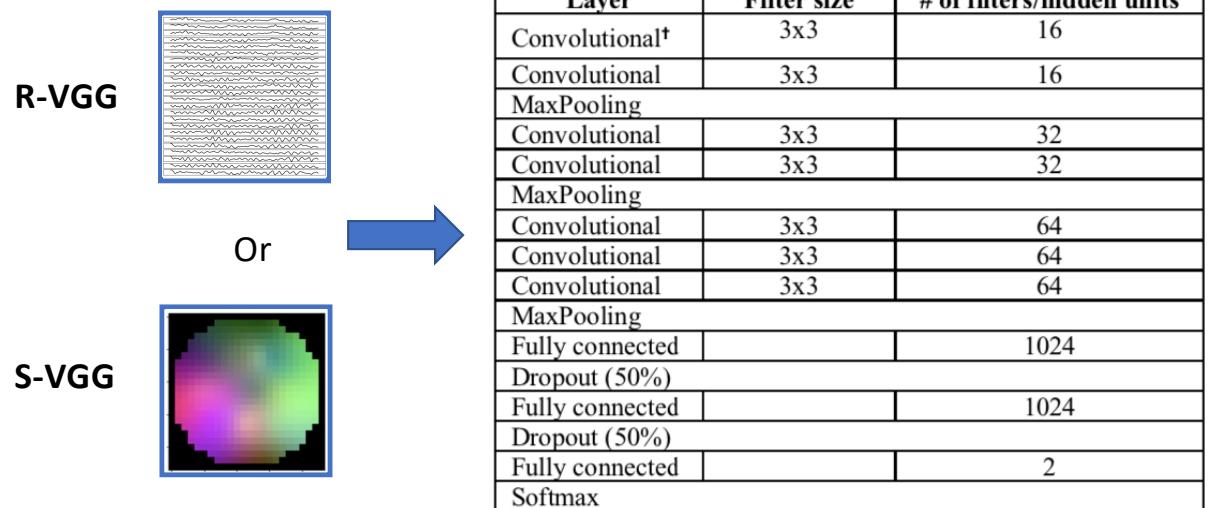
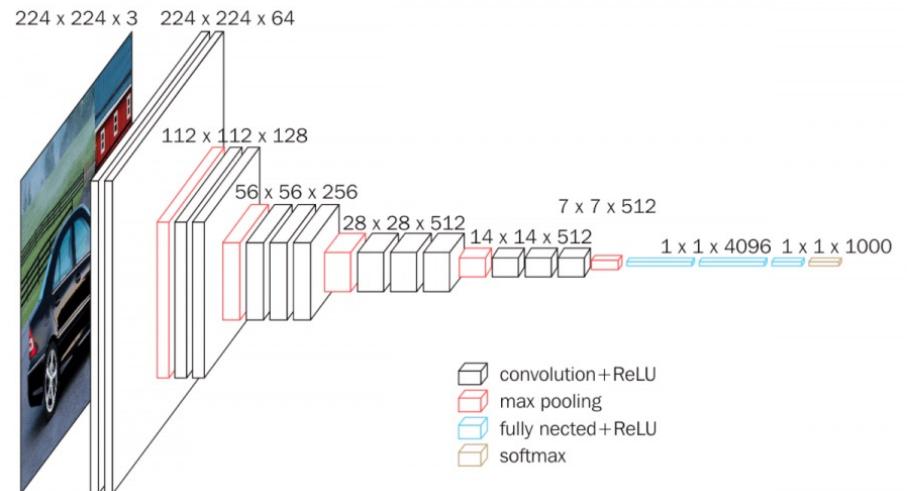
S-SCNN



| Layer           | Filter size | # of filters/hidden units |
|-----------------|-------------|---------------------------|
| Convolutional   | 3x3         | 100                       |
| MaxPooling      |             |                           |
| Dropout (25%)   |             |                           |
| Convolutional   | 3x3         | 100                       |
| MaxPooling      |             |                           |
| Dropout (25%)   |             |                           |
| Convolutional   | 2x3         | 300                       |
| MaxPooling      |             |                           |
| Dropout (25%)   |             |                           |
| Convolutional†  | 1x7         | 300                       |
| MaxPooling*     |             |                           |
| Dropout (25%)   |             |                           |
| Convolutional†  | 1x3         | 100                       |
| Convolutional†  | 1x3         | 100                       |
| Fully connected |             | 6144                      |
| Fully connected |             | 2                         |
| Softmax         |             |                           |

# Modified VGG16

- Changed input size
- Keep the same scaling between layers
- Number of convolutions divided by 8 for each layer
- Dropped layers 19 to 32
- Change number of output classes to 2
- Retrain the whole network



# Training the network

- Computing environment



# Training the network

- Programming environment



v3.7.10



The screenshot shows a Jupyter Notebook interface with the title "jupyter SexPrediction-Final Last Checkpoint: Last Monday at 5:40 PM (unsaved changes)". The notebook has tabs for File, Edit, View, Insert, Cell, Kernel, Widgets, Help, Trusted, and Python (ML) O. The Python (ML) tab is selected. A code cell (In [41]) contains Python code for training a PyTorch model. The code defines a `train` function that iterates over epochs, moves the model to the device, trains it, and performs backpropagation and optimization steps. It also prints epoch and iteration details and checks accuracy. Another code cell (In [82]) shows the definition of a complex PyTorch neural network model with multiple layers of Conv2d, MaxPool2d, Dropout, and Linear layers, along with ReLU and ReLU1 activation functions. The final output cell (Out[82]) shows a message indicating all keys matched successfully.

```
In [41]: def train(model, optimizer, epochs=1):
    """
    Inputs:
    - model: A PyTorch Module giving the model to train.
    - optimizer: An Optimizer object we will use to train the model
    - epochs: (Optional) A Python integer giving the number of epochs to train for
    Returns: Nothing, but prints model accuracies during training.
    """
    model = model.to(device=device) # move the model parameters to CPU/GPU
    for e in range(epochs):
        for t, (x, y) in enumerate(loader_train):
            model.train() # put model to training mode
            x = x.to(device=device, dtype=dtype) # move to device, e.g. GPU
            y = y.to(device=device, dtype=torch.long)

            scores = model(x)
            loss = F.cross_entropy(scores, y)

            # Zero out all of the gradients for the variables which the optimizer
            # will update.
            optimizer.zero_grad()

            # This is the backwards pass: compute the gradient of the loss with
            # respect to each parameter of the model.
            loss.backward()

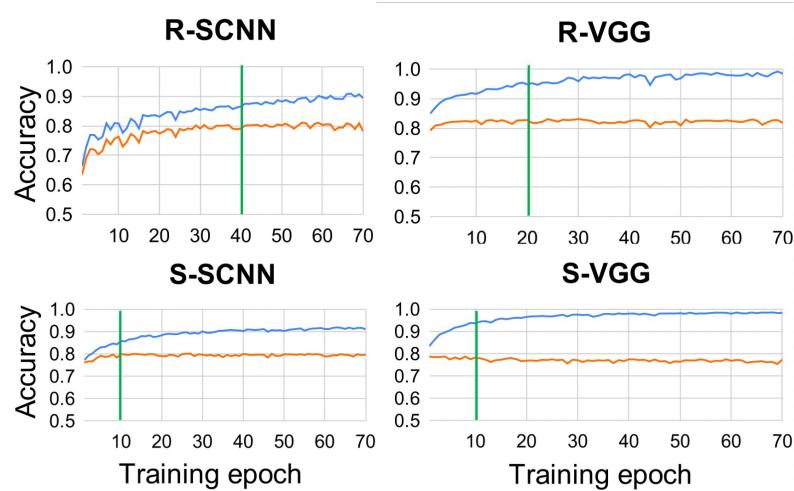
            # Actually update the parameters of the model using the gradients
            # computed by the backwards pass.
            optimizer.step()

            if t % print_every == 0:
                print('Epoch %d, Iteration %d, loss = %.4f' % (e, t, loss.item()))
                check_accuracy(loader_val, model)
                print()

In [82]: lr = 0.002
batch_size = 70
loader_train = DataLoader(train_data, batch_size=batch_size, shuffle=True)
loader_val = DataLoader(val_data, batch_size=batch_size)
model = nn.Sequential(
    nn.Conv2d(1,100,3),
    nn.ReLU(),
    nn.MaxPool2d(2, 2),
    nn.Dropout(0.25),
    nn.Conv2d(100,100,3),
    nn.ReLU(),
    nn.MaxPool2d(2, 2),
    nn.Dropout(0.25),
    nn.Conv2d(100,300,(2,3)),
    nn.ReLU(),
    nn.MaxPool2d(2, 2),
    nn.Dropout(0.25),
    nn.Conv2d(300,300,(1,7)),
    nn.ReLU(),
    nn.MaxPool2d(1,2, stride=1),
    nn.Conv2d(300,100,(1,1)),
    nn.Conv2d(100,100,(1,1)),
    nn.Flatten(),
    nn.Linear(1900,6144),
    nn.Linear(6144,2),
)
optimizer = torch.optim.Adamax(model.parameters(), lr=lr)
train(model, optimizer, epochs=70)
# model.load_state_dict(torch.load('logs/model_saved'))
```

Out[82]: <All keys matched successfully>

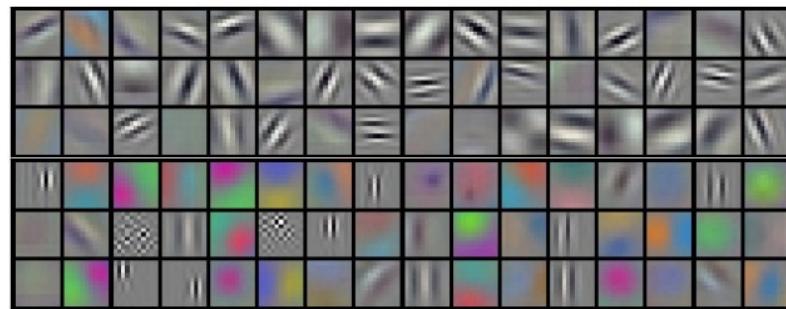
# Results



| 2-sec  |                     |
|--------|---------------------|
| Model  | Per-sample          |
| R-SCNN | 80.6 (79.7 to 81.5) |
| R-VGG  | 83.1 (82.7 to 83.4) |
| S-SCNN | 79.0 (78.7 to 79.3) |
| S-VGG  | 77.1 (76.8 to 77.4) |

Truong, D., Milham, M., Makeig, S., and Delorme, A. Deep Convolutional Neural Network Applied to Electroencephalography: Raw Data vs Spectral Feature. Annu Int Conf IEEE Eng Med Biol Soc, 2021, pp. 1039-1042, doi: 10.1109/EMBC46164.2021.9630708.

# Assessing features learned by the network



Krizhevsky et al., 2012

3/2/add\_5

Type: Add  
Channels: 1,280  
Convolution: [1,1]

Technique

- Feature Visualization
- DeepDream
- Dataset Samples
- Caricature
- Text Feature Visualization

An artificial, optimized image that maximizes activations of the given unit. [Read more](#).

Params

Optimization Objective

- channel
- neuron

View

Image Size

Resize Behavior

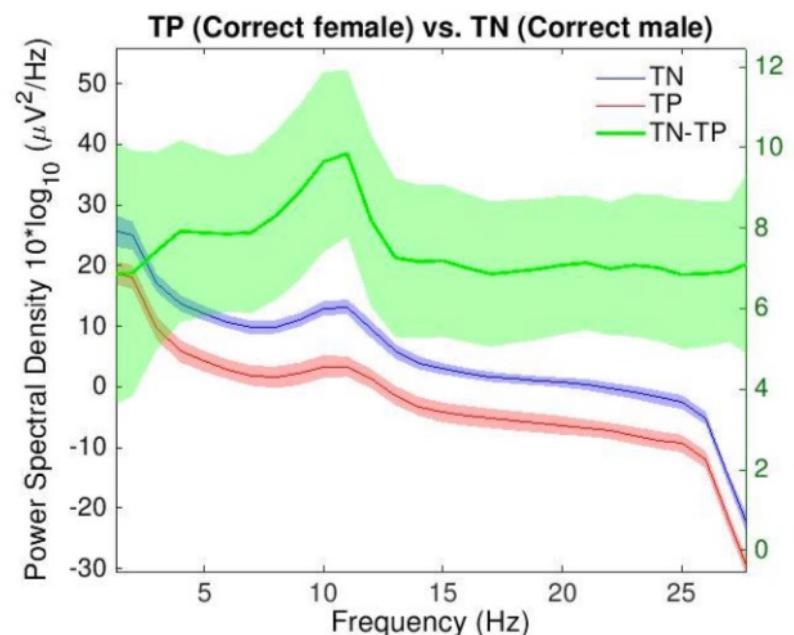
- Crop image
- Scale image

| Unit 0 | Unit 1 | Unit 2 |
|--------|--------|--------|
|        |        |        |
|        |        |        |
|        |        |        |
|        |        |        |

# Best samples

- “Best” = gives highest activation in classification neurons
- Get samples of the top 20 subjects in validation set
- Best male samples show higher spectral power across frequencies, most notably the alpha band near 10Hz

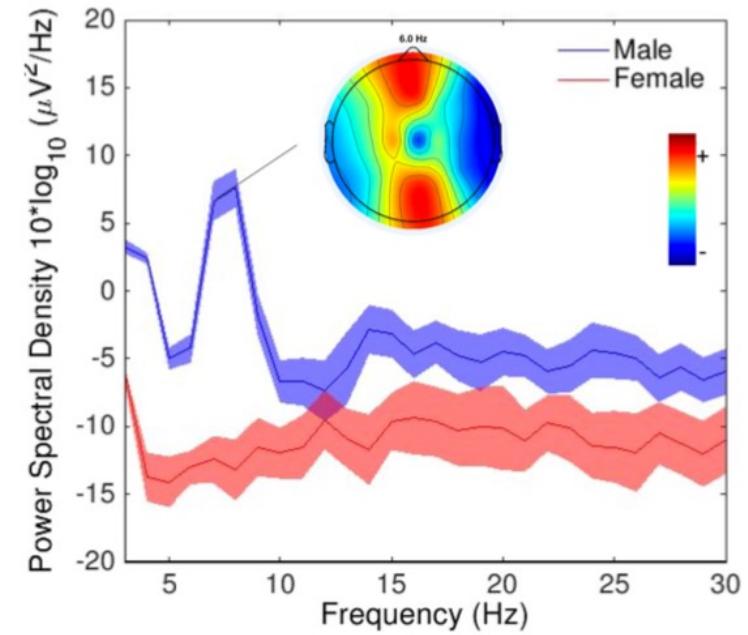
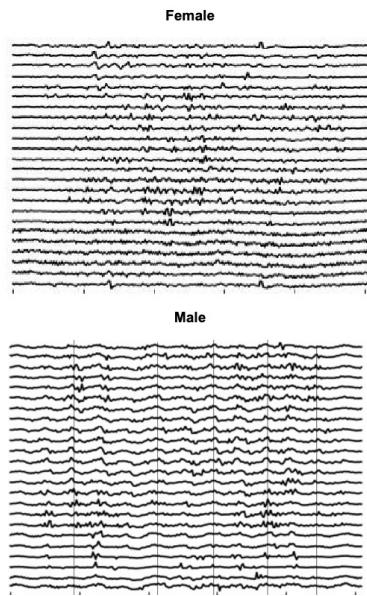
|               | Classified as female      | Classified as male        |
|---------------|---------------------------|---------------------------|
| Female sample | <b>True Positive (TP)</b> | False Negative (FN)       |
| Male sample   | False Positive (FP)       | <b>True Negative (TN)</b> |



Truong, D., Makeig, S., & Delorme, A. (2021). Assessing learned features of Deep Learning applied to EEG. *arXiv preprint arXiv:2111.04309*.

# Activation Maximization

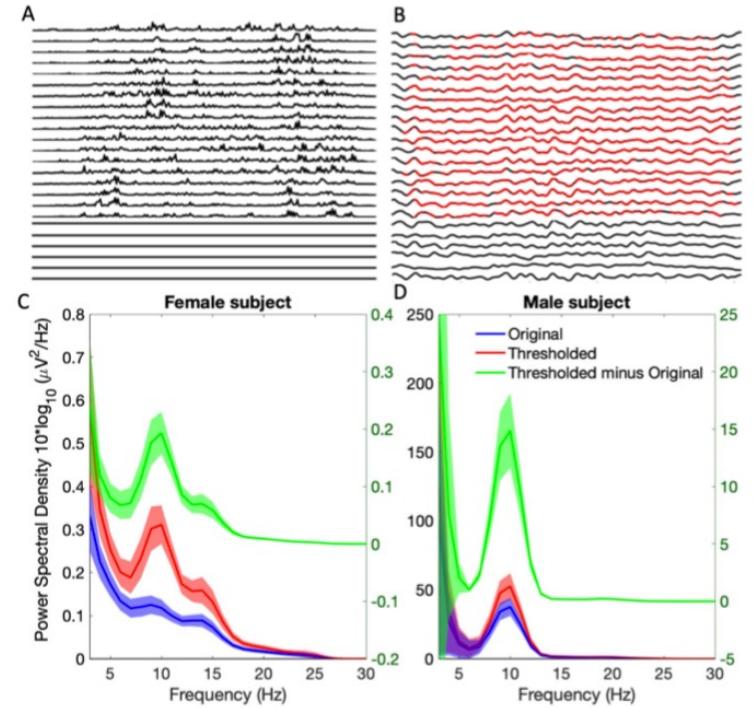
- Synthesize the input that maximize the activation of the classification neurons
- Get 20 samples for each sex
- Best male samples show distinctly higher high theta power for male samples (6-8 Hz)



Truong, D., Makeig, S., & Delorme, A. (2021). Assessing learned features of Deep Learning applied to EEG. *arXiv preprint arXiv:2111.04309*.

# Saliency map

- Back-project the gradient of the classification neuron to the input
- Magnitude of the gradients for each input value indicate the importance of that value to the neuron's activation
- Raw EEG samples contributing the least to the classification (gradients fell below the 30% quantile threshold) were removed then linearly interpolated using the remaining samples
- Thresholded samples showed higher alpha power, most notably near 10Hz



Truong, D., Makeig, S., & Delorme, A. (2021). Assessing learned features of Deep Learning applied to EEG. *arXiv preprint arXiv:2111.04309*.

# Discussion

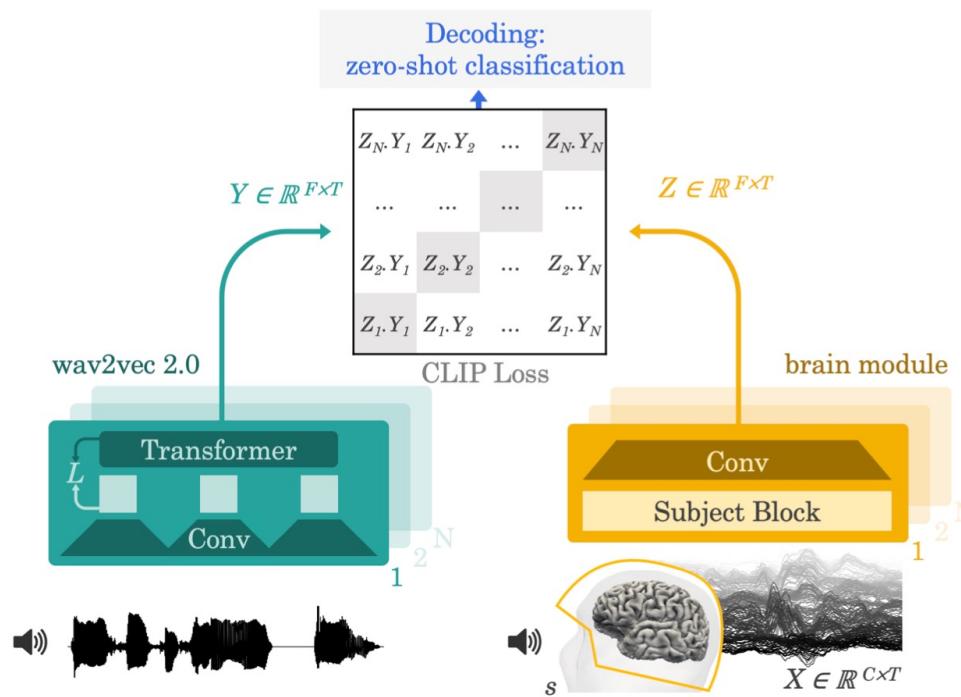
- Architecture design is not physiologically driven
- Not generalizable for different number of channels and sampling rate
- Could be a simple problem: boys move more → Train on normalized data

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# Decoding speech from non-invasive brain recordings

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Alexandre Défossez<sup>1,\*</sup>, Charlotte Caucheteux<sup>1,2</sup>, Jérémie Rapin<sup>1</sup>, Ori Kabeli<sup>1</sup>, and Jean-Rémi King<sup>1,\*</sup>



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# Locating and Editing Factual Associations in GPT

---

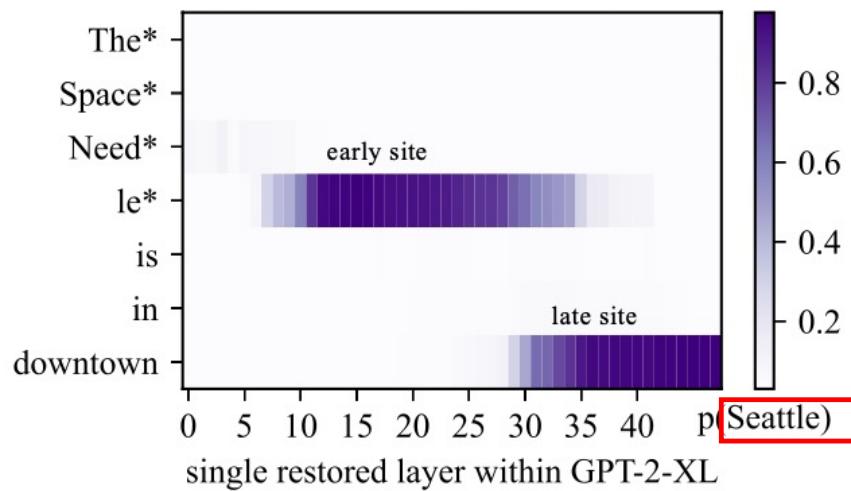
**Kevin Meng\***  
MIT CSAIL

**David Bau\***  
Northeastern University

**Alex Andonian**  
MIT CSAIL

**Yonatan Belinkov<sup>†</sup>**  
Technion – IIT

36th Conference on Neural Information Processing Systems (NeurIPS 2022).



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# Locating and Editing Factual Associations in GPT

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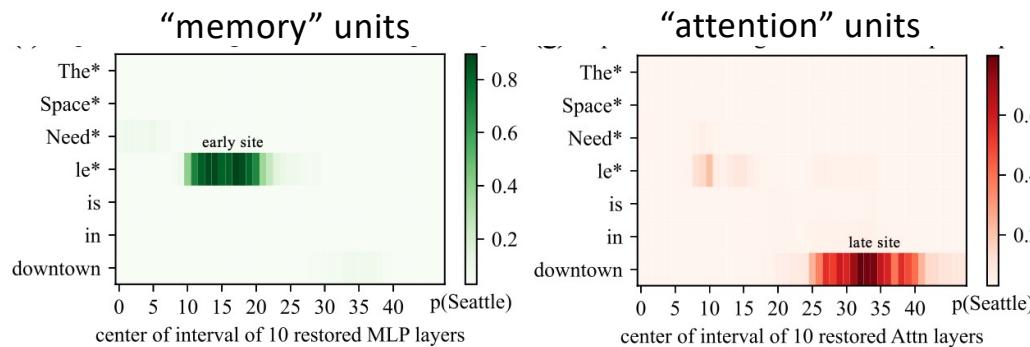
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MIT CSAIL

**Yonatan Belinkov<sup>†</sup>**  
Technion – IIT

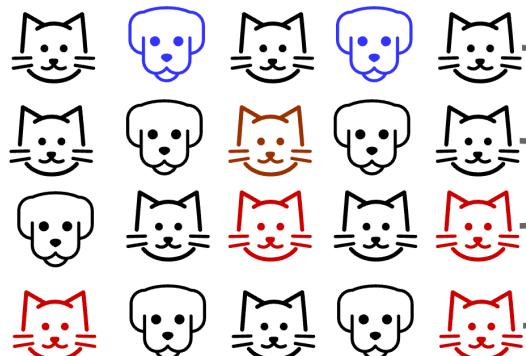
36th Conference on Neural Information Processing Systems (NeurIPS 2022).



# Future work: representation learning

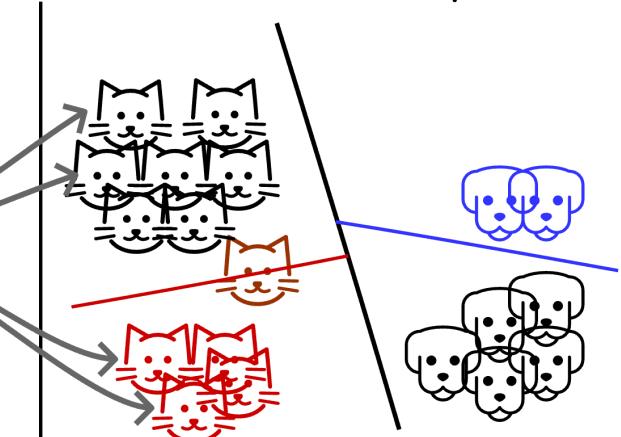
- DL models take data from the original space and map it to a “meaningful” representation

Default Representation



Deep Neural Network

"Good" Semantic Representation

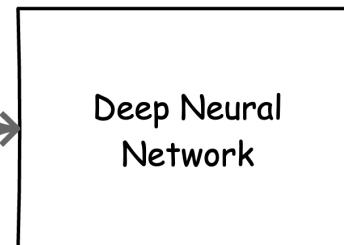
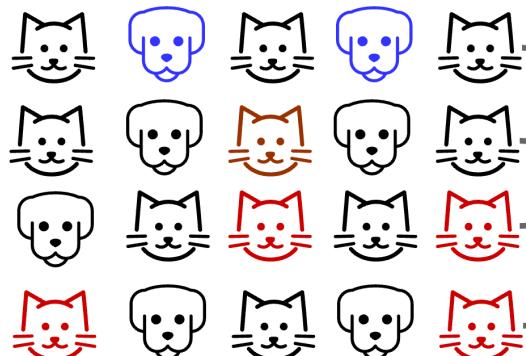


Cat by Martin LEBRETON, Dog by Serhii Smirnov from the Noun Project

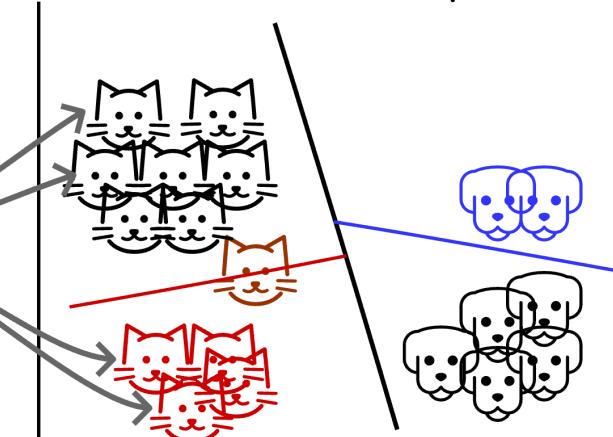
# Future work: representation learning

- DL models take data from the original space and map it to a “meaningful” representation
- Can we learn meaningful embeddings that are also generalizable?

Default Representation



"Good" Semantic Representation



Cat by Martin LEBRETON, Dog by Serhii Smirnov from the Noun Project

# BIDS-DL plug-in

- Automated pipeline to convert HED-identified data segments from BIDS datasets to DL-ready dataset
- Host data on the cloud and make it streamable so that no data download/upload required

Truong, D., Sinha, M., Venkataraju, K. U., Milham, M., & Delorme, A. (2022) A streamable large-scale clinical EEG dataset for Deep Learning. The 44th International Conference of the IEEE Engineering in Medicine & Biology Society (EMBC); July 11-15, 2022.

Thank you