

Euc. Distance of R2

10

8

6

4

2

0

Sensor.Object.OB01.Obj.T00.dtct  
Traffic.T00.DetectLevel  
Sensor.Object.OB01.Obj.T00.RefPnt.ds.x  
Sensor.Object.OB01.relvTgt.RefPnt.ds.x  
Sensor.Object.OB01.relvTgt.RefPnt.ds\_p  
Sensor.Object.OB01.Obj.T00.RefPnt.theta  
Car.CFR.tz  
VC.Gas  
VC.Brake  
Car.CFR.tx  
Car.CFR.ty  
Car.Pitch  
Car.ax  
Sensor.Object.OB01.relvTgt.RefPnt.ds.z  
Sensor.Object.OB01.relvTgt.RefPnt.theta  
Sensor.Object.OB01.relvTgt.RefPnt.r\_zyx.y  
Sensor.Object.OB01.Obj.T00.RefPnt.dv.y  
Sensor.Object.OB01.relvTgt.RefPnt.dv.y  
Sensor.Object.OB01.Obj.T00.RefPnt.ds.y  
Sensor.Object.OB01.relvTgt.RefPnt.ds.y  
Sensor.Object.OB01.Obj.T00.RefPnt.alpha  
Sensor.Object.OB01.relvTgt.RefPnt.alpha  
Car.v  
Sensor.Object.OB01.Obj.T00.RefPnt.dv.x  
Sensor.Object.OB01.relvTgt.RefPnt.dv.x  
Sensor.Object.OB01.relvTgt.RefPnt.dv\_p  
Sensor.Road.RD00.Path.DevAng  
Traffic.T00.tRoad  
Sensor.Object.OB01.relvTgt.RefPnt.dv.z  
Sensor.Object.OB01.relvTgt.RefPnt.r\_zyx.x  
LatCtrl.DistToLeft  
LatCtrl.DistToRight  
Sensor.Object.OB01.relvTgt.RefPnt.r\_zyx.z  
Car.Roll  
Car.ay  
Car.YawRate  
VC.Steer.Ang  
DM.Steer.Ang  
Steer.WhlAng  
Sensor.Object.OB01.TimeStamp  
Time  
Time.Global  
Car.Road.sRoad  
Car.WRL.rot  
Car.WRR.rot  
Traffic.T00.LongVel  
Car.Yaw  
Traffic.T00.Lane.Act.Lanelid

Signals

