

Euc. Distance of R2

10

8

6

4

2

0

Signals

Sensor.Object.OB01.Obj.T00.dtct
Traffic.T00.DetectLevel
Sensor.Object.OB01.Obj.T00.RefPnt.ds.x
Sensor.Object.OB01.relvTgt.RefPnt.ds.x
Sensor.Object.OB01.relvTgt.RefPnt.ds_p
Sensor.Object.OB01.relvTgt.RefPnt.r_zyx.y
Car.CFR.tx
VC.Brake
Sensor.Object.OB01.relvTgt.RefPnt.ds.z
Sensor.Object.OB01.relvTgt.RefPnt.theta
Car.CFR.ty
Car.Pitch
Car.ax
Sensor.Object.OB01.Obj.T00.RefPnt.theta
Car.CFR.tz
VC.Gas
Car.Roll
Car.ay
Car.YawRate
VC.Steer.Ang
DM.Steer.Ang
Steer.WhlAng
Car.Yaw
Sensor.Object.OB01.TimeStamp
Time
Time.Global
Car.Road.sRoad
Car.WRL.rot
Car.WRR.rot
Sensor.Object.OB01.relvTgt.RefPnt.dv.z
LatCtrl.DistToLeft
LatCtrl.DistToRight
Traffic.T00.Lane.Act.LaneId
Traffic.T00.LongVel
Sensor.Object.OB01.Obj.T00.RefPnt.dv.y
Sensor.Object.OB01.relvTgt.RefPnt.dv.y
Sensor.Object.OB01.relvTgt.RefPnt.r_zyx.x
Traffic.T00.tRoad
Car.v
Sensor.Object.OB01.Obj.T00.RefPnt.dv.x
Sensor.Object.OB01.relvTgt.RefPnt.dv.x
Sensor.Object.OB01.relvTgt.RefPnt.dv_p
Sensor.Object.OB01.Obj.T00.RefPnt.ds.y
Sensor.Object.OB01.relvTgt.RefPnt.ds.y
Sensor.Object.OB01.Obj.T00.RefPnt.alpha
Sensor.Object.OB01.relvTgt.RefPnt.alpha
Sensor.Object.OB01.relvTgt.RefPnt.r_zyx.z
Sensor.Road.RD00.Path.DevAng