

Particle Collisions

1. Projectile Motion with Euler Method

Simulate a projectile (m = 1 kg) launched from (0,0) with initial velocity $\mathbf{v}_0 = (10 \, m/s, 10 \, m/s)$ under gravitational force $\mathbf{F}_g = -mg\hat{\mathbf{y}}$ (g = 9.81).

Implement the collision between the particle and the ground. Use different values for ε to see the different behaviors.

2. Particle Motion Inside a Cube with Euler Method

Simulate a particle (m = 1 kg) moving inside a cube, starting from the initial position $\mathbf{p}_0 = (1 m, 1 m, 1 m)$ with an initial velocity $\mathbf{v}_0 = (5 m/s, 5 m/s, 5 m/s)$.

The cube is defined by the limits:

$$0 \le x \le 5$$
, $0 \le y \le 5$, $0 \le z \le 5$.

Implement a simulation using the Euler method, updating the particle's position and velocity at each time step $\Delta t = 0.01$.

Collision Handling: - When the particle collides with one of the cube's wall, apply the reflection rule:

$$\mathbf{v} = \mathbf{v} - (1 + \varepsilon)(\mathbf{n} \cdot \mathbf{v})\mathbf{n}.$$

where **n** is the normal vector of the ground. - Use different values for ε : - $\varepsilon = 1$ (Perfectly elastic collision) - $\varepsilon = 0.5$ (Partially inelastic collision) - $\varepsilon = 0$ (Perfectly inelastic collision, the particle stops moving)

Extension:

- Extend the simulation to handle collisions with all six walls of the cube.
- Observe the behavior of the particle as it bounces inside the cube

Extension 2: - For each wall put a different value of ε .

3. Particle Motion Inside a Triangle with Euler Method

Simulate a particle (m = 1 kg) moving freely inside a **triangular** region, starting from the initial position $\mathbf{p}_0 = (1 m, 1 m)$ with an initial velocity $\mathbf{v}_0 = (3 m/s, 4 m/s)$. The particle moves with **constant velocity**, meaning there is no external force acting on it.

The triangular region is defined by the vertices:

$$A = (0,0), \quad B = (5,0), \quad C = (2.5,5).$$

Implement a simulation using the Euler method, updating the particle's position at each time step Δt . Collision Handling: - When the particle collides with one of the triangle's edges, apply the reflection rule:

$$\mathbf{v} = \mathbf{v} - (1 + \varepsilon)(\mathbf{n} \cdot \mathbf{v})\mathbf{n}.$$

where \mathbf{n} is the normal vector of the edge.

- Use different values for ε : - $\varepsilon = 1$ (Perfectly elastic collision) - $\varepsilon = 0.5$ (Partially inelastic collision) - $\varepsilon = 0$ (Perfectly inelastic collision, the particle stops moving)

Extension: - Implement a method to detect which edge the particle collides with. - Observe how the particle's trajectory evolves as it bounces inside the triangle.

4. Verify that in a mechanical system, the following equality is satisfied

$$\Delta U = -W.$$