

Applied Optimization Exercise 1 - Convex Sets

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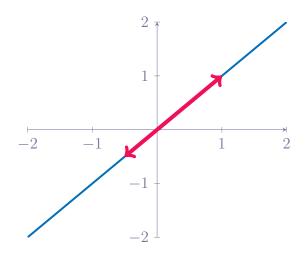
October 5, 2021

1 Convex Sets

1. Example sets

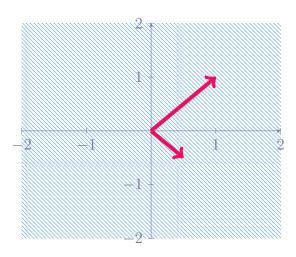
Sketch the following sets in \mathbb{R}^2

1. span
$$\left\{ \begin{pmatrix} 1\\1 \end{pmatrix}, \begin{pmatrix} -0.5\\-0.5 \end{pmatrix} \right\}$$

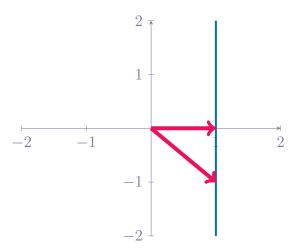




$$2. \operatorname{span}\left\{ \begin{pmatrix} 1\\1 \end{pmatrix}, \begin{pmatrix} 0.5\\-0.5 \end{pmatrix} \right\}$$

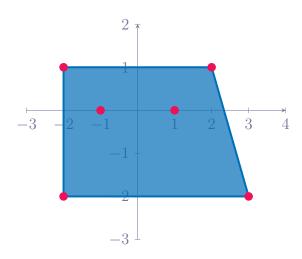


3. aff
$$\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$$





4. conv
$$\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 3 \\ -2 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 1 \end{pmatrix}, \begin{pmatrix} -2 \\ -2 \end{pmatrix} \right\}$$



2. Convexity

Let $C \in \mathbb{R}^n$ be a convex set, with $x_1, ..., x_k \in C$, and let $\theta_1, ..., \theta_k \in \mathbb{R}$ satisfy $\theta_i \geq 0, \theta_1 + ... + \theta_k = 1$. Show that $\theta_1 x_1 + ... + \theta_k x_k \in C$. (The definition of convexity is that this holds for k = 2; you must show it for arbitrary k.) Hint. Use induction on k.

Show. that $\theta_1 + ... + \theta_k \in C$

Proof. Base Case k=2 By definition, it holds for k=2.

Inductive Step Assume it is correct for k = n, then for k = n + 1, we have:

$$x_1, ..., x_{n+1} \in C$$

$$\theta_1, ..., \theta_{n+1} \in C$$

with
$$\theta_i \geq 0$$
 and $\sum_{i=0}^{n+1} \theta_i = 1 \Rightarrow \theta_{n+1} = 1 - \sum_{i=1}^{n} \theta_i$

$$\Rightarrow \sum_{i=1}^{n+1} \theta_i x_i = \sum_{i=1}^n \theta_i x_i + \theta_{n+1} x_{n+1} = \sum_{i=1}^n \theta_i x_i + x_{n+1} = \sum_{i=1}^n \theta_i x_{n+1}$$

$$= \underbrace{x_{n+1}}_{\in C} \underbrace{\sum_{i=1}^n \theta_i (x_i - x_{n+1})}_{\text{because } \sum_{i=1}^n \theta_i \in [0,1]} \Rightarrow \in C$$



3. Linear Equations

Show that the solution set of linear equations $\{x|Ax=b\}$ with $x\in R^n$, $A\in R^{m\times n}$ and $b\in R^m$ is an affine set.

Proof. Let x_0, x_1 be solutions of linear equations, i.e. $Ax_0 = b$ and $Ax_1 = b$

Then

$$A((1-\beta)x_0 + \beta x_1) = (1-\beta)Ax_0 + \beta Ax_1$$
$$= (1-\beta)b + \beta b = b$$

 \Rightarrow The set is affine.

4. Linear Inequations

1. Show that the solution set of linear inequations $\{x|Ax \leq b, Cx = d\}$ with $x \in \mathbb{R}^n$, $A \in \mathbb{R}^{m \times n}$ and $b \in \mathbb{R}^m$, $C \in \mathbb{R}^{k \times n}$ and $d \in \mathbb{R}^k$ is a convex set. Here \leq means componentwise less or equal.

Proof. Let x_0, x_1 be solutions of linear inequations, i.e. $Ax_0 \leq b, Cx_0 = d$ and $Ax_1 \leq b, Cx_1 = d$, for $\beta \in [0, 1]$

Then

$$A((1-\beta)x_0 + \beta x_1) = \underbrace{(1-\beta)}_{>0}\underbrace{Ax_0}_{\prec b} + \underbrace{\beta}_{>0}\underbrace{Ax_1}_{\prec b} \preceq (1-\beta)b + \beta b = b \tag{1}$$

and

$$C((1-\beta)x_0 + \beta x_1) = (1-\beta)Cx_0 + \beta Cx_1 = (1-\beta)d + \beta d = d$$

 \Rightarrow convex set.

2. Is it an affine set?

No, cf Equation 1, if we don't have the $a_i \geq 0$ for $\forall i$ constraint, it removes the constraint on the $\beta \in [0,1]$, which then means we could have $(1-\beta) < 0$. Therefore the step $(1-\beta)Ax_0 \leq b$ is not doable, we might have $(1-\beta)Ax_0 \geq b$



5. Voronoi description of halfspace

Let a and b be distinct points in \mathbb{R}^n . Show that the set of all points that are closer (in Euclidean norm) to a than b, i.e., $\{x | \|x - a\|^2 \le \|x - b\|^2\}$, is a halfspace. Describe it explicitly as an inequality of the form $c^T x \le d$. Draw a picture.

Proof. Be $c \in \mathbb{R}^n$ a vector, c = b - a be $d \in \mathbb{R}$, $d = c^T x_0 = c^T \frac{a+b}{2}$ then we have the halfspace

$$\left\{ x \middle| (b-a)^T x \le \frac{(b-a)^T (b-a)}{2} \right\}$$

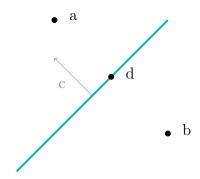
Check.

$$||x - a||^2 \le ||x - b||^2$$

$$\Leftrightarrow (x - a)^T (x - a) \le (x - b)^T (x - b)$$

$$\Leftrightarrow x^T x - 2a^T x + a^T a \le x^T x - 2b^T x + b^T b$$

$$\Leftrightarrow (b - a)^T x \le (b^T b - a^T a) \frac{1}{2}$$





2 Convex Illumination Problem

Show that the solution $p^* = (p_1^*, p_2^*, ..., p_*^n)^T \in \mathbb{R}^n$ of the non-convex illumination problem from the lecture

$$\begin{array}{ll} \text{minimize} & \max_{k=1...m} \big| \log I_k - \log I_{des} \big| \\ \text{subject to} & 0 \leq p_j \leq p_{max}, \quad j = 1...n \end{array}$$

with $I_k = \sum_{j=1}^n a_{kj} p_j$ for geometric constants $a_{jk} \in R$, a constant desired illumination $I_{des} \in R$ and an upper bound $p_{max} \in R$ on the lamp power, is identical to the solution of the following equivalent (convex) problem

minimize
$$\max_{k=1...m} h(I_k/I_{des})$$

subject to $0 \le p_j \le p_{max}, \quad j = 1...n$

with $h(u) = max\{u, \frac{1}{u}\}.$

Proof.

$$\max_{k=1,\dots,m} \left| \log(I_k) - \log(I_{des}) \right| \qquad \left| \log \text{ rules} \right|$$

$$= \max_{k=1,\dots,m} \left| \log \left(\frac{I_k}{I_{des}} \right) \right| \qquad \left| \text{ remove } \right| . \left|$$

$$= \max_{k=1,\dots,m} \max \left\{ \log \left(\frac{I_k}{I_{des}} \right), \log \left(\frac{I_{des}}{I_k} \right) \right\} \qquad \left| \text{ max log = log max} \right|$$

$$= \log \max_{k=1,\dots,m} \max \left\{ \frac{I_k}{I_{des}}, \frac{I_{des}}{I_k} \right\} \qquad \left| \text{ with } h = (u) = \max \left\{ u, \frac{1}{u} \right\} \right\}$$

$$= \log \max_{k=1,\dots,m} h \left(\frac{I_k}{I_{des}} \right)$$

The log is a monotonically increasing function, i.e. $\forall x, y$ with $x \leq y$ we have $\log(x) \leq \log(y)$. So when minimizing, we can remove it without affecting the solution.

$$\Rightarrow = \max_{k=1,\dots,m} h\left(\frac{I_k}{I_{des}}\right) \text{ with } h(u) = \max\left\{u, \frac{1}{u}\right\}.$$