

FliK Modul 2020

Autoencoder and VAE

Steffen Seitz, Marvin Arnold & Markus Fritzsche

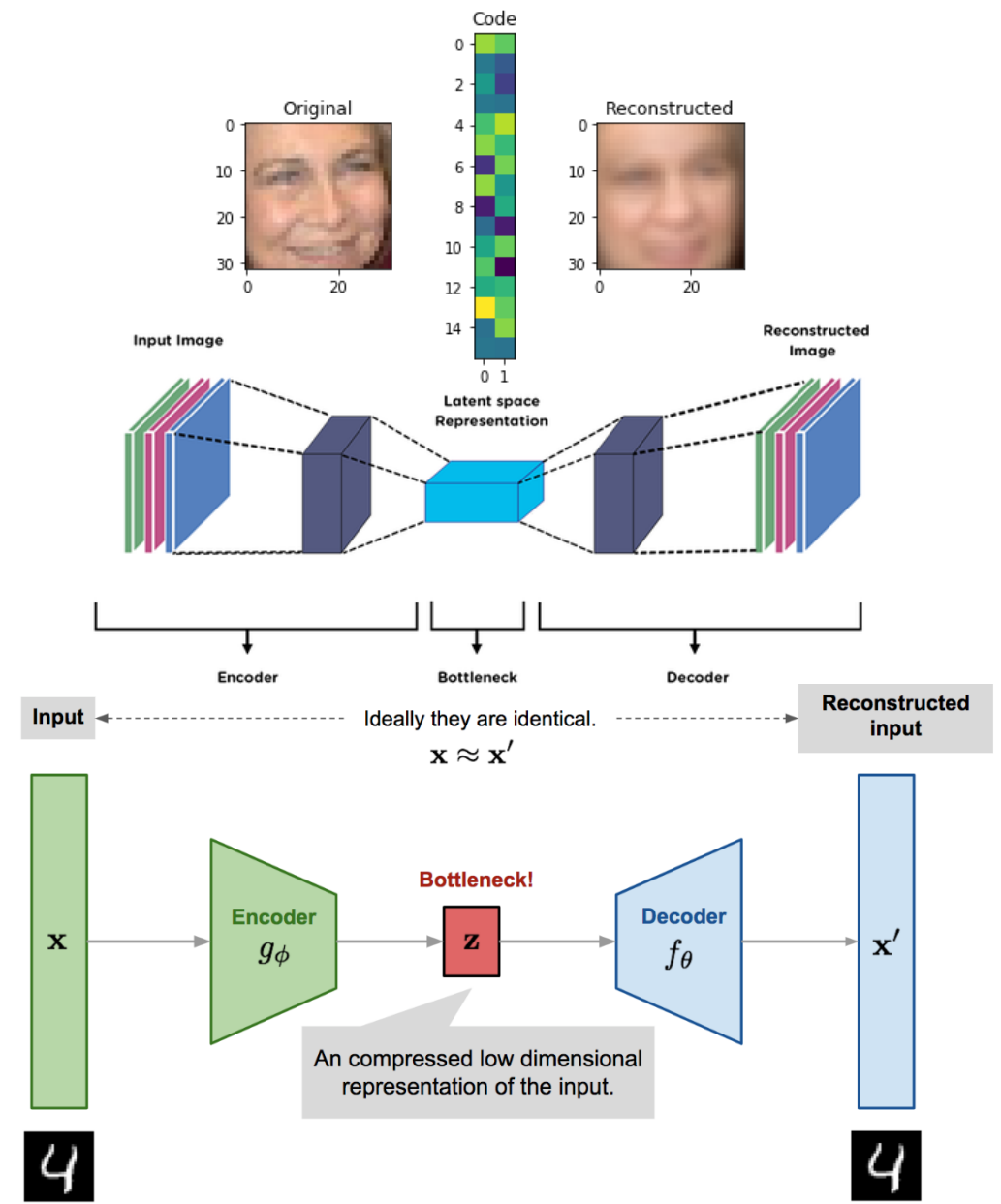
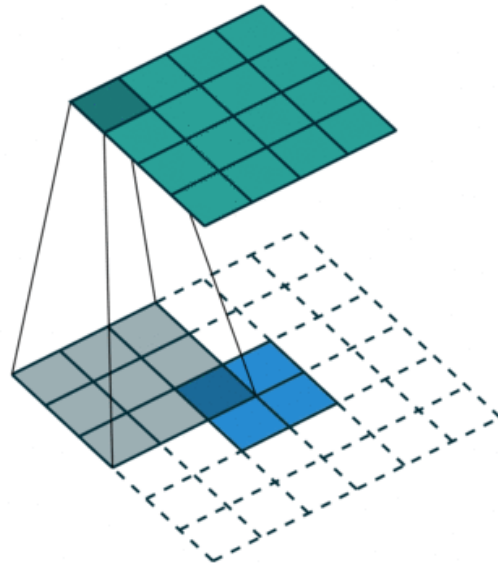
Prof. Ronald Tetzlaff

Dresden, 19-23.10.

Autoencoder

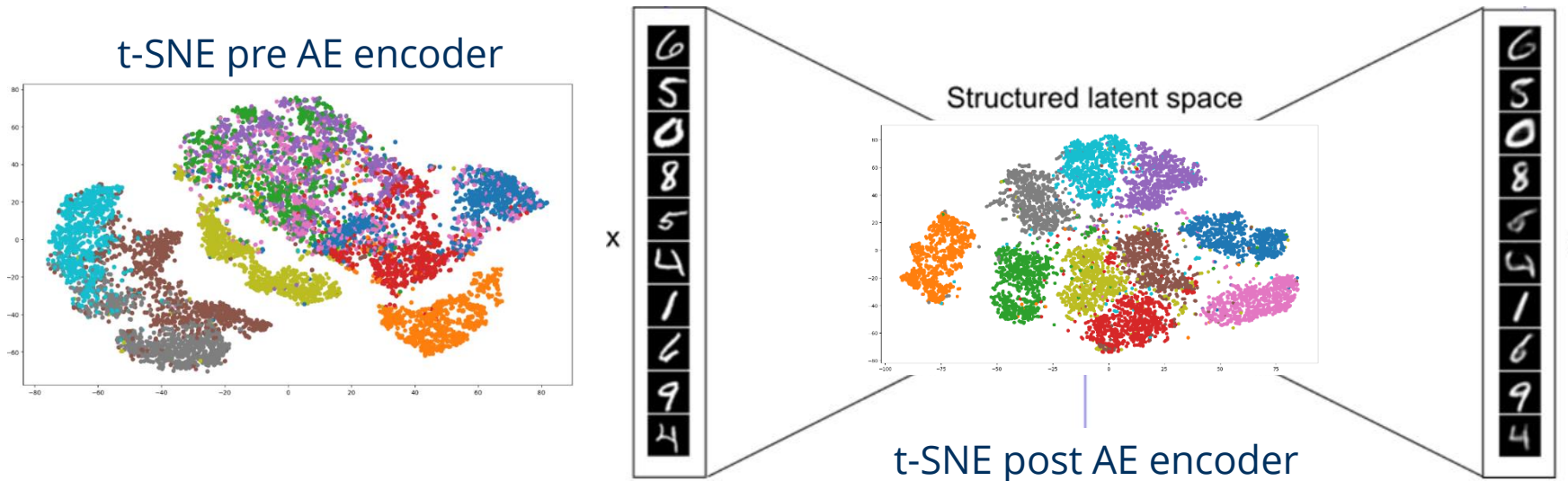
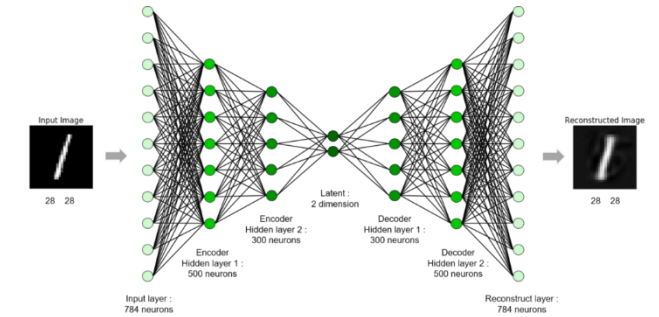
Autoencoder use a different approach to solve neural network tasks. They usually try to **reconstruct** an e.g. an image through a bottleneck in the architecture. In CNN based Autoencoders the bottleneck is achieved by a series of **downsampling** (encoder) and upsampling / **transposed convolutions** (decoder)

transposed
convolutions

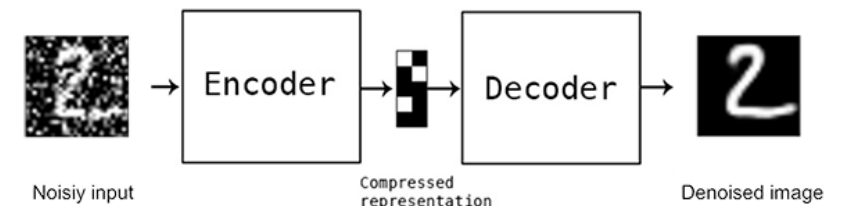


Autoencoder

The goal here is to receive a **latent representation** that best **explains the data**, requiring no supervised training at all! Autoencoder can be built by using **many Neural Network types**. Here we is one build up with standard Feed Forward Layers (e.g. Sigmoid Neurons)



The data prio to the AE doesn't look nice at all! But **after passing** the **encoder** it is **well structured**! We will replicate those plots in the next exercise. A typical **use case** of an Autoencoder is **denoising**!

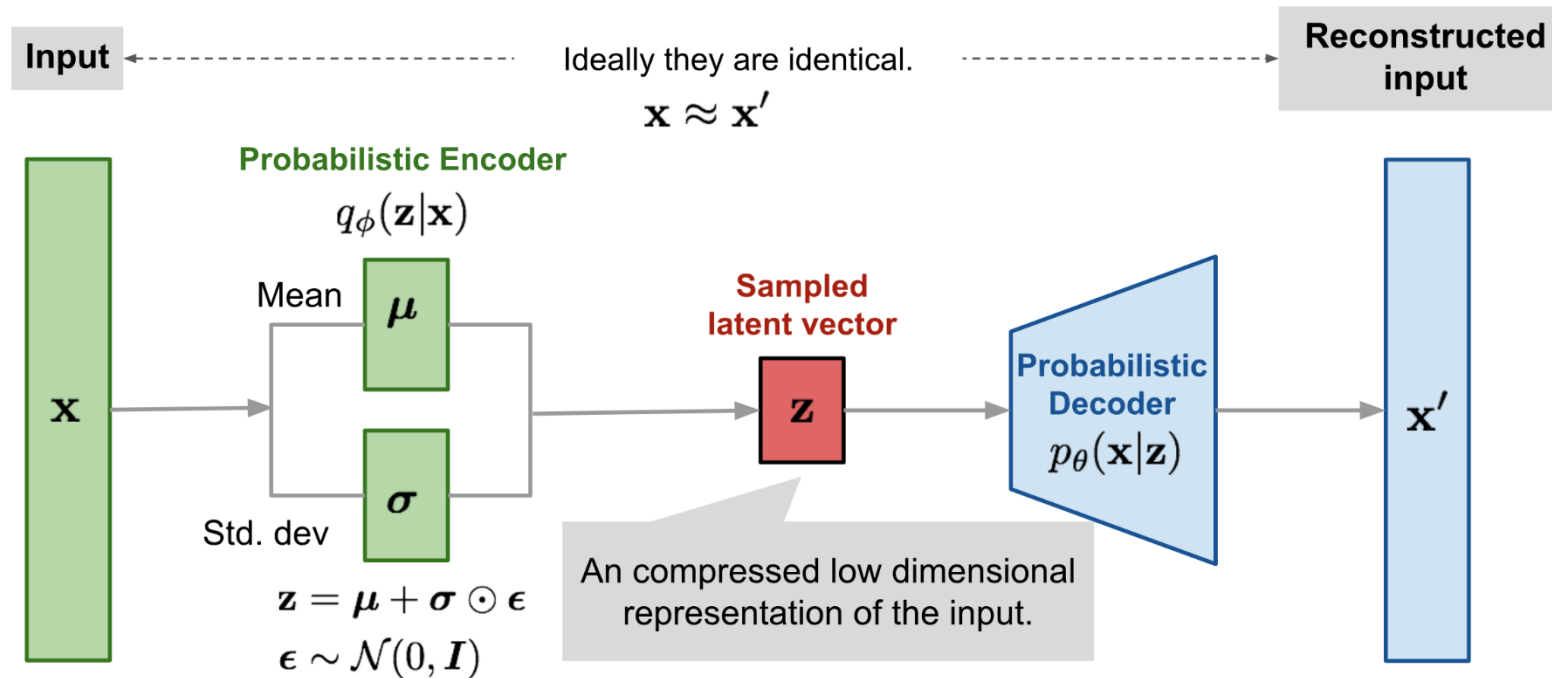


10. Exercise

Let's train our first Autoencoder for MNIST and FashionMNIST!

VariationalAutoencoder

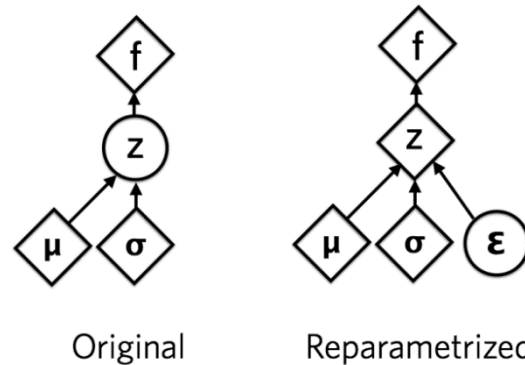
Generative modeling instead of discriminative! Autoencoder is trying to estimate mu and sigma of a distribution!



Variational Autoencoder

Reparametrisation Trick

We can't backpropagate through this network anymore as we pleased in the past. We need to use the **Reparametrisation Trick** by Kingma to so, because we can't backprop over a sampling process.



$$\text{Reparametrization Trick : } z = \mu + \sigma * \epsilon; \quad \epsilon \sim \mathcal{N}(0, 1)$$

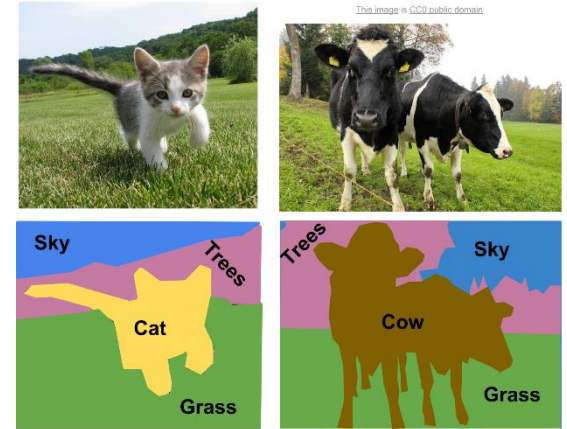
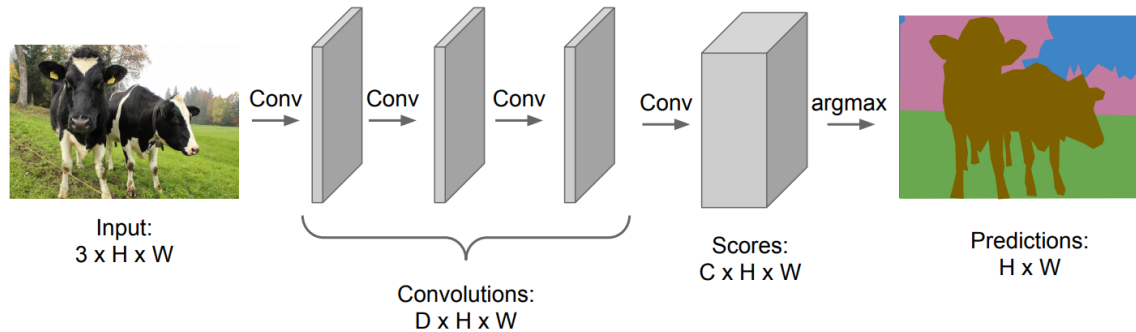
The trick is to **factor out** the sampling. Just multiply μ and σ calculated by the network with a **predefined** (already sampled) image with $\mu = 1$ and $\sigma = 0$. The sampled image stays the same over the whole training process; it is a dummy just **scaled** by the **μ** and **σ calculated** by the **network!** 😊

11. Exercise

Let's train our first Variational Autoencoder!

Image Segmentation

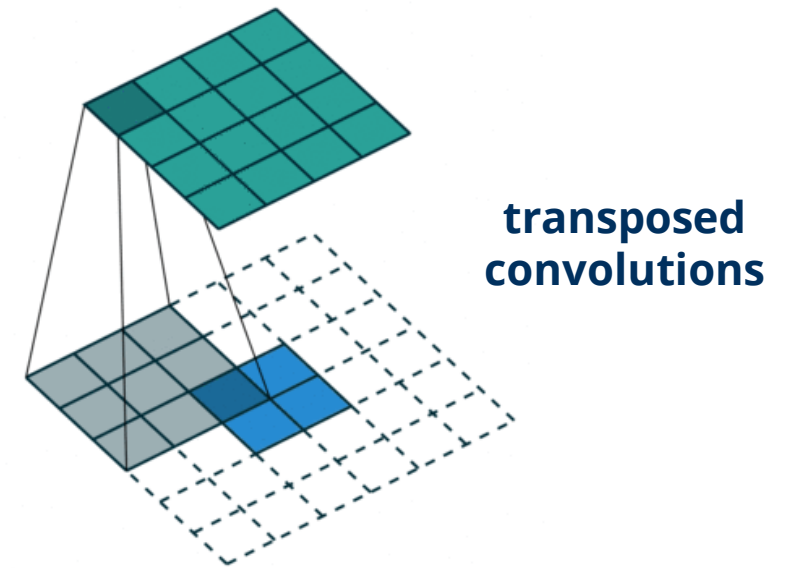
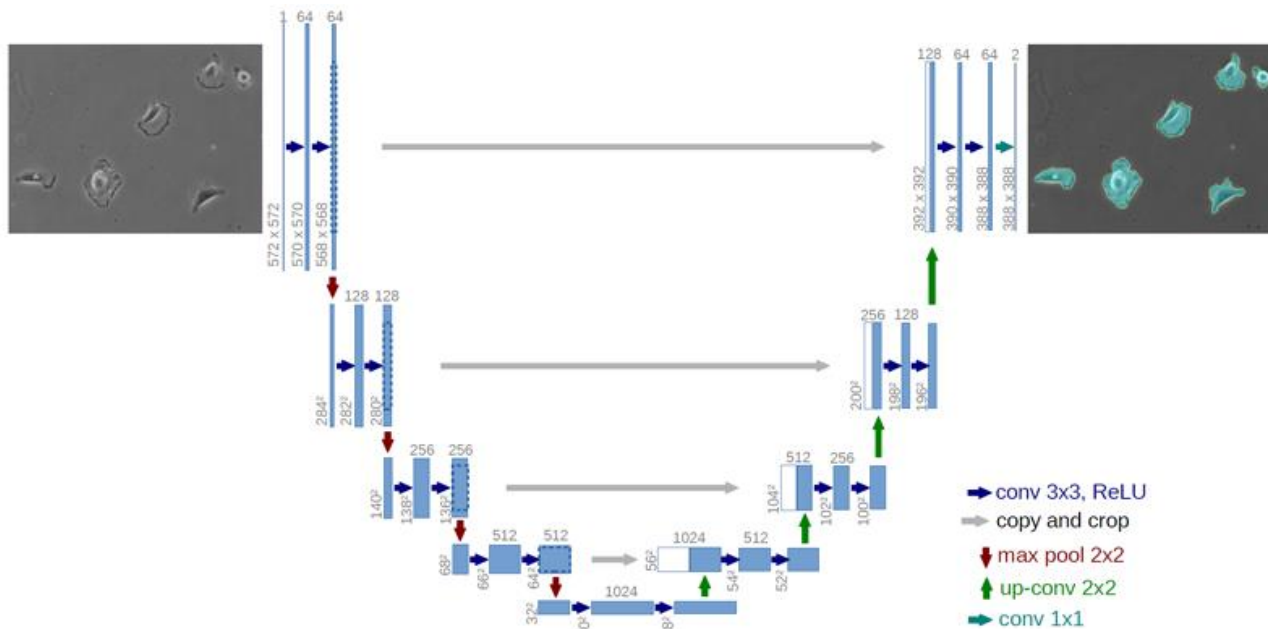
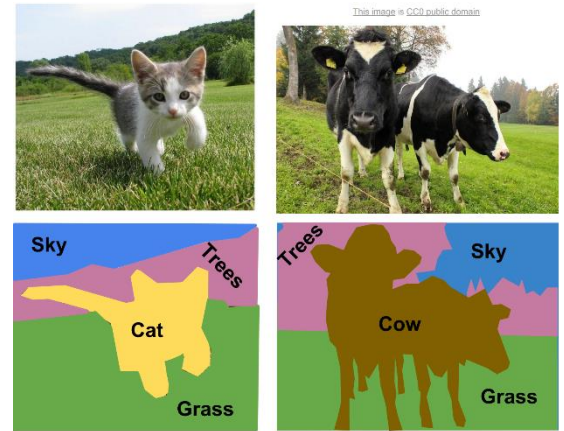
Today, Autoencoders have gained popularity in the task of **Image Segmentation**. For this task, **every pixel** is **labeled** with a class label, e.g. cow, tree, grass sky or cat. Thus we do **not care** about **detecting** any object, only about the label of all the pixels of the image.



How about we **train** a fully convolutional network (=no MLP layer at the end) to make predictions for each pixel **all at once**? The problem with this approach is that (again) convolutions at the original image resolution will be **very expensive** and would take a lot of **memory**.

U-Net

Like an Conv. Autoencoder this architecture consists of a contracting path (**encoder**) to capture context and a symmetric expanding path (**decoder**). There are also **short-cut** paths which allows the network to propagate context information to higher resolution layers. But **in contrast** to the standard AE, **U-Net** uses a **supervised** mapping. The shape gives this network its U-Net name.



Extra

If time, train U-Net for cell segmentation in Uni-Warwick dataset!