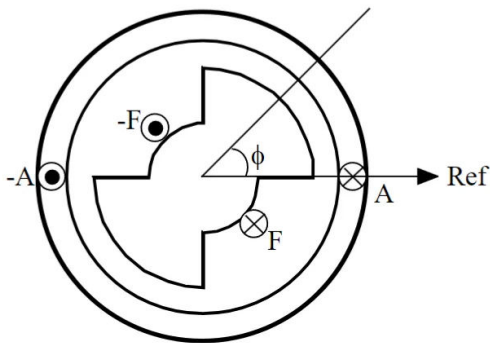


# ECEN 611 Homework 4: Gap Function and Mutual Inductance for Salient Pole Rotor

## Table of Contents

Problem 2.....	1
Inverse Gap Function .....	1
Stator Counting & Winding Function.....	5
Original Stator Counting Function $\phi \in [0 T]$ .....	6
Extended Stator Counting Function $\phi \in [-2T 2T]$ .....	6
Extended Stator Winding Function $\phi \in [-2T 2T]$ .....	8
Rotor Counting & Winding Function .....	9
Original Rotor Counting Function $\phi \in [\theta_r \theta_r+T]$ .....	10
Extended Rotor Counting Function $\phi \in [\theta_r-2T \theta_r+2T]$ .....	11
Extended Rotor Winding Function $\phi \in [\theta_r-2T \theta_r+2T]$ .....	12
(a) Magnetizing inductance of winding A on the stator.....	13
(b) Magnetizing inductance of winding F on the rotor.....	14
(c) Mutual inductance between stator and rotor for the following salient pole synchronous machine.....	15
.....	17

## Problem 2



(pole arc = 90 degree)

```
clearvars
clc
```

## Inverse Gap Function

if you could make Problem 1 a function...

```
syms g_min g_max      positive real
syms alpha             positive real
syms phi               real
syms g_phi(phi)
syms theta_r theta

assume( (alpha > 0) & (alpha <= deg2rad(180)) )
```

```

T = 2*pi;
POLEARC = deg2rad(90);
THETA_R = deg2rad(45);

poleArc = alpha;
midArc = T/2 - poleArc;

rotor_profile_theta = [poleArc/2 midArc poleArc midArc poleArc/2];
rotor_profile_turning_phi = [theta_r, theta_r + cumsum(rotor_profile_theta)];

rotor_profile_turning_phi = subs( ...
    rotor_profile_turning_phi, ...
    poleArc, POLEARC ...
)

```

```

rotor_profile_turning_phi =

$$\left( \theta_r \quad \theta_r + \frac{\pi}{4} \quad \theta_r + \frac{3\pi}{4} \quad \theta_r + \frac{5\pi}{4} \quad \theta_r + \frac{7\pi}{4} \quad \theta_r + 2\pi \right)$$


```

```

% phi_ref = 0;
% rotor_profile_turning_phi = [phi_ref, rotor_profile_turning_phi]

```

```

gap_profile = [g_min, g_max, g_min, g_max, g_min];

firstPhi = rotor_profile_turning_phi(1);
secondPhi = rotor_profile_turning_phi(2);

firstGap = gap_profile(1);

g_phi(phi) = piecewise(firstPhi <= phi < secondPhi, firstGap)

```

$g_{\phi}(\phi) = \begin{cases} g_{\min} & \text{if } \theta_r \leq \phi \wedge 4\phi < 4\theta_r + \pi \end{cases}$

```

for k = 2 : length(rotor_profile_turning_phi) - 1

    thisPhi = rotor_profile_turning_phi(k);
    nextPhi = rotor_profile_turning_phi(k+1);
    thisGap = gap_profile(k);

    g_phi(phi) = piecewise( ...
        thisPhi <= phi < nextPhi, thisGap, ...
        phi <= thisPhi, g_phi(phi) ...
    );
end

g_phi(phi) = simplify(g_phi)

```

```

g_phi(phi) =

```

$$\begin{cases} g_{\min} & \text{if } \phi < \theta_r + 2\pi \wedge \theta_r + \frac{7\pi}{4} \leq \phi \\ g_{\max} & \text{if } \phi < \theta_r + \frac{7\pi}{4} \wedge \theta_r + \frac{5\pi}{4} \leq \phi \\ g_{\min} & \text{if } \phi < \theta_r + \frac{5\pi}{4} \wedge \theta_r + \frac{3\pi}{4} \leq \phi \\ g_{\max} & \text{if } \phi < \theta_r + \frac{3\pi}{4} \wedge \theta_r + \frac{\pi}{4} \leq \phi \\ g_{\min} & \text{if } \theta_r \leq \phi \wedge 4\phi < 4\theta_r + \pi \end{cases}$$

```
g_phi_inv = 1 / g_phi
```

```
g_phi_inv(phi) =
```

$$\begin{cases} \frac{1}{g_{\min}} & \text{if } \phi < \theta_r + 2\pi \wedge \theta_r + \frac{7\pi}{4} \leq \phi \\ \frac{1}{g_{\max}} & \text{if } \phi < \theta_r + \frac{7\pi}{4} \wedge \theta_r + \frac{5\pi}{4} \leq \phi \\ \frac{1}{g_{\min}} & \text{if } \phi < \theta_r + \frac{5\pi}{4} \wedge \theta_r + \frac{3\pi}{4} \leq \phi \\ \frac{1}{g_{\max}} & \text{if } \phi < \theta_r + \frac{3\pi}{4} \wedge \theta_r + \frac{\pi}{4} \leq \phi \\ \frac{1}{g_{\min}} & \text{if } \theta_r \leq \phi \wedge 4\phi < 4\theta_r + \pi \end{cases}$$

```
g_phi_inv_ext(phi) = piecewise( ...
    theta_r - 2*T <= phi < theta_r - T, g_phi_inv(phi+2*T), ...
    theta_r - T <= phi < theta_r,      g_phi_inv(phi+T), ...
    theta_r <= phi < theta_r + T,      g_phi_inv(phi), ...
    theta_r + T <= phi <= theta_r + 2*T, g_phi_inv(phi-T) ...
)
```

```
g_phi_inv_ext(phi) =
```

$$\left\{ \begin{array}{ll} \frac{1}{g_{\min}} & \text{if } \phi + 2\pi < \theta_r \wedge \theta_r \leq \phi + \frac{9\pi}{4} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\max}} & \text{if } \phi + \frac{9\pi}{4} < \theta_r \wedge \theta_r \leq \phi + \frac{11\pi}{4} \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\min}} & \text{if } \phi + \frac{11\pi}{4} < \theta_r \wedge \theta_r \leq \phi + \frac{13\pi}{4} \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\max}} & \text{if } \phi + \frac{13\pi}{4} < \theta_r \wedge \theta_r \leq \phi + \frac{15\pi}{4} \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\min}} & \text{if } (\phi < \theta_r \wedge 4\theta_r \leq 4\phi + \pi) \vee (4\phi + 15\pi < 4\theta_r \wedge \theta_r \leq \phi + 4\pi \wedge \phi \in \mathbb{R}) \\ \frac{1}{g_{\max}} & \text{if } 4\theta_r \leq 4\phi + 3\pi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \wedge 4\phi + \pi < 4\theta_r \\ \frac{1}{g_{\min}} & \text{if } 4\phi + 3\pi < 4\theta_r \wedge 4\theta_r \leq 4\phi + 5\pi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\max}} & \text{if } 4\phi + 5\pi < 4\theta_r \wedge 4\theta_r \leq 4\phi + 7\pi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\min}} & \text{if } (4\phi + 7\pi < 4\theta_r \wedge \theta_r \leq \phi + 2\pi \wedge \phi \in \mathbb{R}) \vee (4\theta_r + 7\pi \leq 4\phi \wedge \phi < \theta_r + 2\pi \wedge \theta_r \in \mathbb{R}) \\ \frac{1}{g_{\max}} & \text{if } 4\phi < 4\theta_r + 7\pi \wedge 4\theta_r + 5\pi \leq 4\phi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\min}} & \text{if } 4\phi < 4\theta_r + 5\pi \wedge 4\theta_r + 3\pi \leq 4\phi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\max}} & \text{if } 4\phi < 4\theta_r + 3\pi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \wedge 4\theta_r + \pi \leq 4\phi \\ \frac{1}{g_{\min}} & \text{if } (\theta_r \leq \phi \wedge 4\phi < 4\theta_r + \pi) \vee (4\theta_r + 15\pi \leq 4\phi \wedge \phi < \theta_r + 4\pi \wedge \theta_r \in \mathbb{R}) \\ \frac{1}{g_{\max}} & \text{if } \phi < \theta_r + \frac{15\pi}{4} \wedge \theta_r + \frac{13\pi}{4} \leq \phi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\min}} & \text{if } \phi < \theta_r + \frac{13\pi}{4} \wedge \theta_r + \frac{11\pi}{4} \leq \phi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\max}} & \text{if } \phi < \theta_r + \frac{11\pi}{4} \wedge \theta_r + \frac{9\pi}{4} \leq \phi \wedge \phi \in \mathbb{R} \wedge \theta_r \in \mathbb{R} \\ \frac{1}{g_{\min}} & \text{if } 4\phi < 4\theta_r + 9\pi \wedge \theta_r + 2\pi \leq \phi \wedge \phi \in \mathbb{R} \end{array} \right.$$

% it was [0 T], now it becomes [theta\_r theta\_r+T]

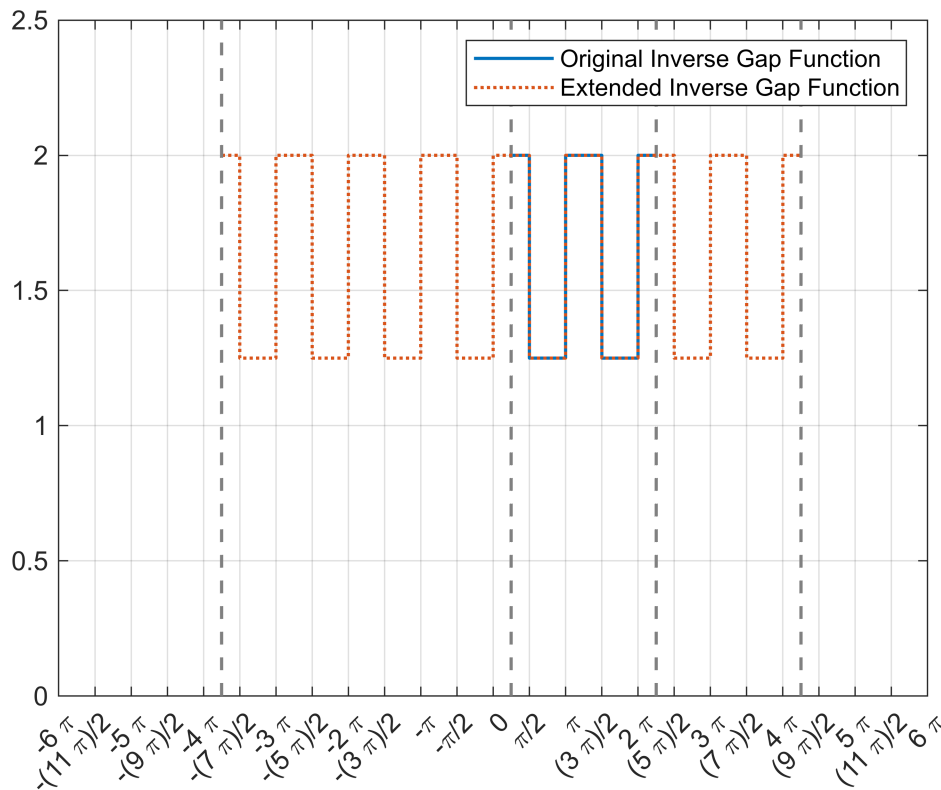
```
vars = [poleArc g_min g_max theta_r];
VALS = [POLEARC 0.5 0.8 THETA_R];
```

```
figure
fplot(subs(g_phi_inv, vars, VALS), [-3*T 3*T], ...
      "DisplayName", "Original Inverse Gap Function", ...
      "LineWidth", 1.2)
hold on
fplot(subs(g_phi_inv_ext, vars, VALS), [-3*T 3*T], ...
```

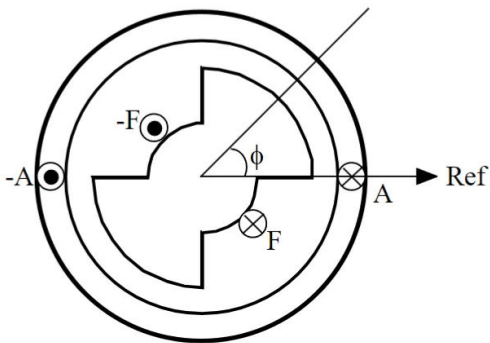
```

    "DisplayName", "Extended Inverse Gap Function", ...
    "LineStyle", ":", ...
    "LineWidth", 1.2 ...
)
hold off
ylim([0 2.5])
grid on
legend
ax = gca;
S = sym(ax.XLim(1):pi/2:ax.XLim(2));
ax.XTick = double(S);
ax.XTickLabel = arrayfun(@texlabel,S,'UniformOutput',false);

```



## Stator Counting & Winding Function



```

numberOfConductors = 2;

```

```

syms I positive real
syms N_s

NS = 1;

% close the "loop": one turn is at phi=0 and the other T/2
% however, closing the "loop" by winding up to T (same as phi=0) makes
% programming easier because that corresponds to a full period
turnsStatorNum = [1 -1 1] * N_s; % number of turns at each location: replace Nt
with 1 for simplicity
turnsStatorPhi = [0 T/2 T]; % angle of each location

% Initialize the piecewise function with the first interval
phiReference = sym(0); % unique and universal "yardstick" for all angles associated
with rotor and stator

turnsStatorNumLevel = cumsum(turnsStatorNum)

```

```

turnsStatorNumLevel = (N_s 0 N_s)

```

```

% Initialize the piecewise function with the first interval
statorCountingFunction(phi) = turnsStatorNumLevel(1);

for k = 1:length(turnsStatorPhi)-1
    thisAngle = turnsStatorPhi(k);
    nextPhi = turnsStatorPhi(k+1);
    statorCountingFunction(phi) = piecewise(thisAngle <= phi < nextPhi,
turnsStatorNumLevel(k), ...
                                phiReference <= phi < thisAngle,
statorCountingFunction);
end

```

### Original Stator Counting Function $\phi \in [0 T]$

```

disp("Original Stator Counting Function  $\phi \in [0 T]$  :")

```

```

Original Stator Counting Function  $\phi \in [0 T]$  :

```

```

disp(statorCountingFunction(phi))

```

$$\begin{cases} 0 & \text{if } \phi \in [\pi, 2\pi) \\ N_s & \text{if } \phi \in [0, \pi) \end{cases}$$

### Extended Stator Counting Function $\phi \in [-2T 2T]$

```

statorCountingFunction_ext(phi) = piecewise( ...
    -2*T <= phi < -T, statorCountingFunction(phi+2*T), ...
    -T <= phi < 0, statorCountingFunction(phi+T), ...
    0 <= phi < T, statorCountingFunction(phi), ...
    T <= phi < 2*T, statorCountingFunction(phi-T) ...
);

```

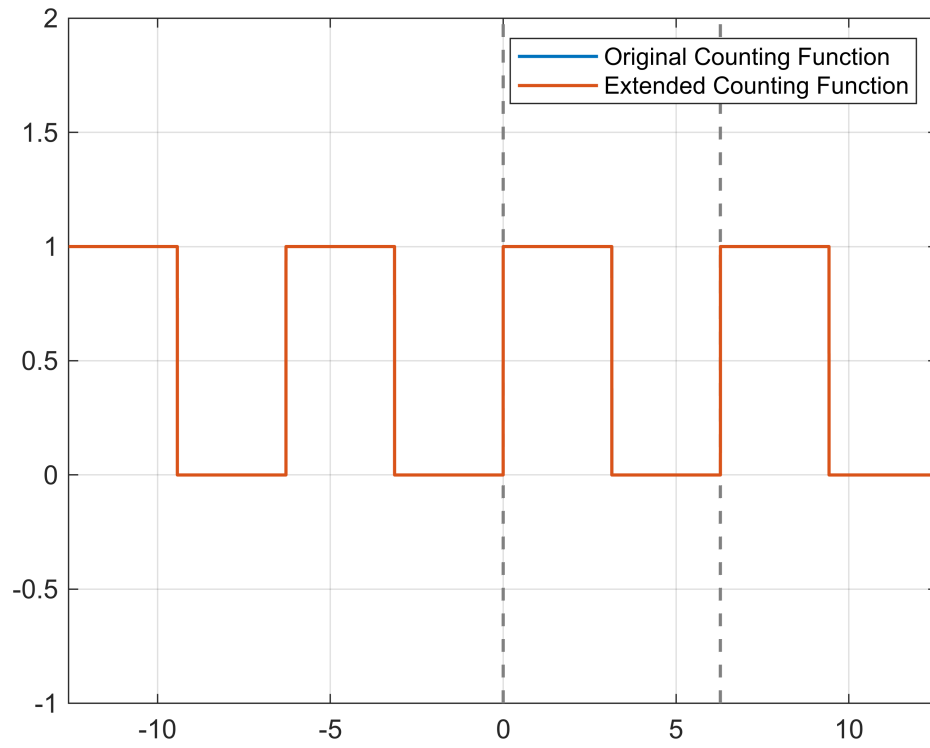
```
disp("Extended Stator Counting Function  $\phi \in [-2T \ 2T]$  :")
```

Extended Stator Counting Function  $\phi \in [-2T \ 2T]$  :

```
disp(statorCountingFunction_ext(phi))
```

$$\begin{cases} 0 & \text{if } \phi \in [-3\pi, -2\pi) \\ N_s & \text{if } \phi \in [-4\pi, -3\pi) \\ 0 & \text{if } \phi \in [-\pi, 0) \\ N_s & \text{if } \phi \in [-2\pi, -\pi) \\ 0 & \text{if } \phi \in [\pi, 2\pi) \\ N_s & \text{if } \phi \in [0, \pi) \\ 0 & \text{if } \phi \in [3\pi, 4\pi) \\ N_s & \text{if } \phi \in [2\pi, 3\pi) \end{cases}$$

```
figure
fplot(subs(statorCountingFunction(phi), N_s, NS), [-2*T 2*T], ...
      "DisplayName", "Original Counting Function", ...
      "LineWidth", 1.2)
hold on
fplot(subs(statorCountingFunction_ext(phi), N_s, NS), [-2*T 2*T], ...
      "DisplayName", "Extended Counting Function", ...
      "LineWidth", 1.2)
hold off
ylim([-1 2])
grid on
legend
```



### Extended Stator Winding Function $\phi \in [-2T \ 2T]$

```
statorCountingFunction_ext_avg = 1/T * int(statorCountingFunction_ext, phi, [0 T]);
statorWindingFunction_ext = statorCountingFunction_ext -
statorCountingFunction_ext_avg
```

statorWindingFunction\_ext(phi) =

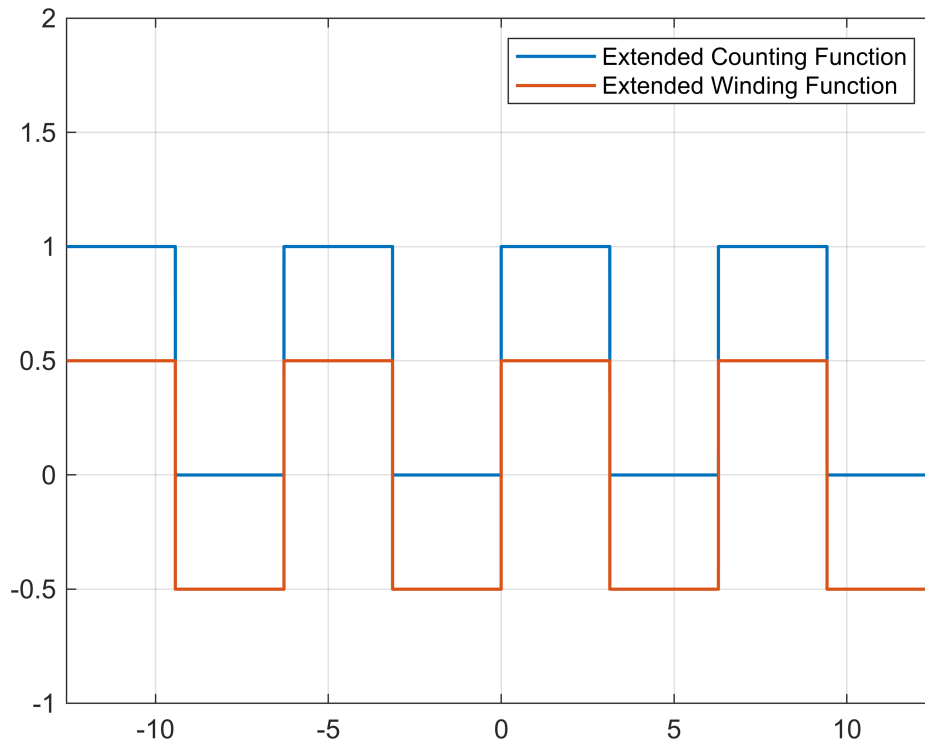
$$\left\{ \begin{array}{ll} -\frac{5734161139222659 \pi N_s}{36028797018963968} & \text{if } \phi \in [-3\pi, -2\pi) \\ N_s - \frac{5734161139222659 \pi N_s}{36028797018963968} & \text{if } \phi \in [-4\pi, -3\pi) \\ -\frac{5734161139222659 \pi N_s}{36028797018963968} & \text{if } \phi \in [-\pi, 0) \\ N_s - \frac{5734161139222659 \pi N_s}{36028797018963968} & \text{if } \phi \in [-2\pi, -\pi) \\ -\frac{5734161139222659 \pi N_s}{36028797018963968} & \text{if } \phi \in [\pi, 2\pi) \\ N_s - \frac{5734161139222659 \pi N_s}{36028797018963968} & \text{if } \phi \in [0, \pi) \\ -\frac{5734161139222659 \pi N_s}{36028797018963968} & \text{if } \phi \in [3\pi, 4\pi) \\ N_s - \frac{5734161139222659 \pi N_s}{36028797018963968} & \text{if } \phi \in [2\pi, 3\pi) \end{array} \right.$$



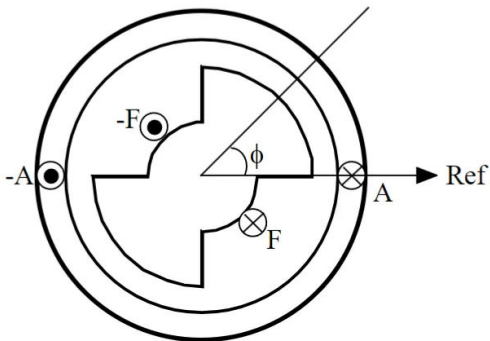
```

figure
fplot(subs(statorCountingFunction_ext(phi), N_s, NS), [-2*T 2*T], ...
      "DisplayName", "Extended Counting Function", ...
      "LineWidth", 1.2)
hold on
fplot(subs(statorWindingFunction_ext(phi), N_s, NS), [-2*T 2*T], ...
      "DisplayName", "Extended Winding Function", ...
      "LineWidth", 1.2)
hold off
ylim([-1 2])
grid on
legend

```



## Rotor Counting & Winding Function



```

% rotor_profile_theta = [poleArc/2 midArc poleArc midArc poleArc/2];
% rotor_profile_turning_phi = [theta_r, theta_r + cumsum(rotor_profile_theta)];
%
% rotor_profile_turning_phi = subs( ...
%     rotor_profile_turning_phi, ...
%     poleArc, POLEARC ...
% )
syms N_r
NR = 1;

turnsRotorNum = [0    -1    1    0 ] * N_r;    % number of turns at each location:
replace Nt with 1 for simplicity
turnsRotorPhi = [0    T/4    T/2    T/4 ];    % angle of each location

turnsRotorNumLevel = cumsum(turnsRotorNum)

```

turnsRotorNumLevel =  $\begin{pmatrix} 0 & -N_r & 0 & 0 \end{pmatrix}$

```
rotor_winding_turning_phi = theta_r + cumsum(turnsRotorPhi)
```

```
rotor_winding_turning_phi =
 $\left( \theta_r \quad \theta_r + \frac{\pi}{2} \quad \theta_r + \frac{3\pi}{2} \quad \theta_r + 2\pi \right)$ 
```

```

% Initialize the piecewise function with the first interval
rotorCountingFunction(phi) = turnsRotorNumLevel(1);

for k = 1:length(rotor_winding_turning_phi)-1

    thisPhi = rotor_winding_turning_phi(k);
    nextPhi = rotor_winding_turning_phi(k+1);

    rotorCountingFunction(phi) = piecewise(thisPhi <= phi < nextPhi,
turnsRotorNumLevel(k), ...
                                         phiReference <= phi < thisPhi,
rotorCountingFunction);
end

```

### Original Rotor Counting Function $\phi \in [\theta_r \theta_r+T]$

```
disp("Original Rotor Counting Function: ");
```

Original Rotor Counting Function:

```
disp(rotorCountingFunction(phi));
```

$$\begin{cases} 0 & \text{if } \phi < \theta_r + 2\pi \wedge \theta_r + \frac{3\pi}{2} \leq \phi \\ -N_r & \text{if } \phi < \theta_r + \frac{3\pi}{2} \wedge \theta_r + \frac{\pi}{2} \leq \phi \wedge 0 \leq \phi \\ 0 & \text{if } \phi < \theta_r + \frac{\pi}{2} \wedge 0 \leq \phi \wedge (\phi < \theta_r \vee (\theta_r \leq \phi \wedge 2\phi < 2\theta_r + \pi)) \end{cases}$$

### Extended Rotor Counting Function $\varphi \in [\theta_r - 2T \ \theta_r + 2T]$

```
rotorCountingFunction_ext(phi) = piecewise( ...
    theta_r - 2*T <= phi < theta_r - T, rotorCountingFunction(phi+2*T), ...
    theta_r - T <= phi < theta_r,      rotorCountingFunction(phi+T), ...
    theta_r <= phi < theta_r + T,      rotorCountingFunction(phi), ...
    theta_r + T <= phi < theta_r + 2*T, rotorCountingFunction(phi-T) ...
)
```

$$\text{rotorCountingFunction\_ext}(\phi) = \begin{cases} 0 & \text{if } \phi + 2\pi < \theta_r \wedge \theta_r \leq \phi + \frac{5\pi}{2} \wedge \theta_r \in \mathbb{R} \\ -N_r & \text{if } 2\phi + 5\pi < 2\theta_r \wedge 2\theta_r \leq 2\phi + 7\pi \wedge \theta_r \in \mathbb{R} \wedge -4\pi \leq \phi \\ 0 & \text{if } (\phi < \theta_r \wedge 2\theta_r \leq 2\phi + \pi) \vee (2\phi + 7\pi < 2\theta_r \wedge \theta_r \leq \phi + 4\pi \wedge (\phi + 4\pi < \theta_r \vee (2\phi + 7\pi < 2 \\ -N_r & \text{if } 2\theta_r \leq 2\phi + 3\pi \wedge \theta_r \in \mathbb{R} \wedge -2\pi \leq \phi \wedge 2\phi + \pi < 2\theta_r \\ 0 & \text{if } (2\theta_r + 3\pi \leq 2\phi \wedge \phi < \theta_r + 2\pi \wedge \theta_r \in \mathbb{R}) \vee (2\phi + 3\pi < 2\theta_r \wedge \theta_r \leq \phi + 2\pi \wedge (\phi + 2\pi < \theta_r \\ -N_r & \text{if } 2\phi < 2\theta_r + 3\pi \wedge \theta_r \in \mathbb{R} \wedge 2\theta_r + \pi \leq 2\phi \wedge 0 \leq \phi \\ 0 & \text{if } (2\theta_r + 7\pi \leq 2\phi \wedge \phi < \theta_r + 4\pi \wedge \theta_r \in \mathbb{R}) \vee (\theta_r \leq \phi \wedge 2\phi < 2\theta_r + \pi \wedge 0 \leq \phi \wedge (\phi < \theta_r \vee (\theta \\ -N_r & \text{if } \phi < \theta_r + \frac{7\pi}{2} \wedge \theta_r + \frac{5\pi}{2} \leq \phi \wedge \theta_r \in \mathbb{R} \wedge 2\pi \leq \phi \\ 0 & \text{if } \phi < \theta_r + \frac{5\pi}{2} \wedge \theta_r + 2\pi \leq \phi \wedge (\phi < \theta_r + 2\pi \vee (2\phi < 2\theta_r + 5\pi \wedge \theta_r + 2\pi \leq \phi)) \wedge 2\pi \leq \phi \end{cases}$$

```
% figure
% fplot(subs(rotorCountingFunction(phi), [theta_r N_r], [0 NR]), [-2*T 2*T], ...
%     "DisplayName", "Original Counting Function", ...
%     "LineWidth", 1.2)
% hold on
% fplot(subs(rotorCountingFunction_ext(phi), [theta_r N_r], [0 NR]), [-2*T 2*T], ...
%     "DisplayName", "Extended Counting Function", ...
%     "LineWidth", 1.2)
% hold off
% ylim([-2 2])
% grid on
%
% ax = gca;
% S = sym(ax.XLim(1):pi/2:ax.XLim(2));
% ax.XTick = double(S);
% ax.XTickLabel = arrayfun(@texlabel,S,'UniformOutput',false);
```

## Extended Rotor Winding Function $\phi \in [\theta_r - 2T \ \theta_r + 2T]$

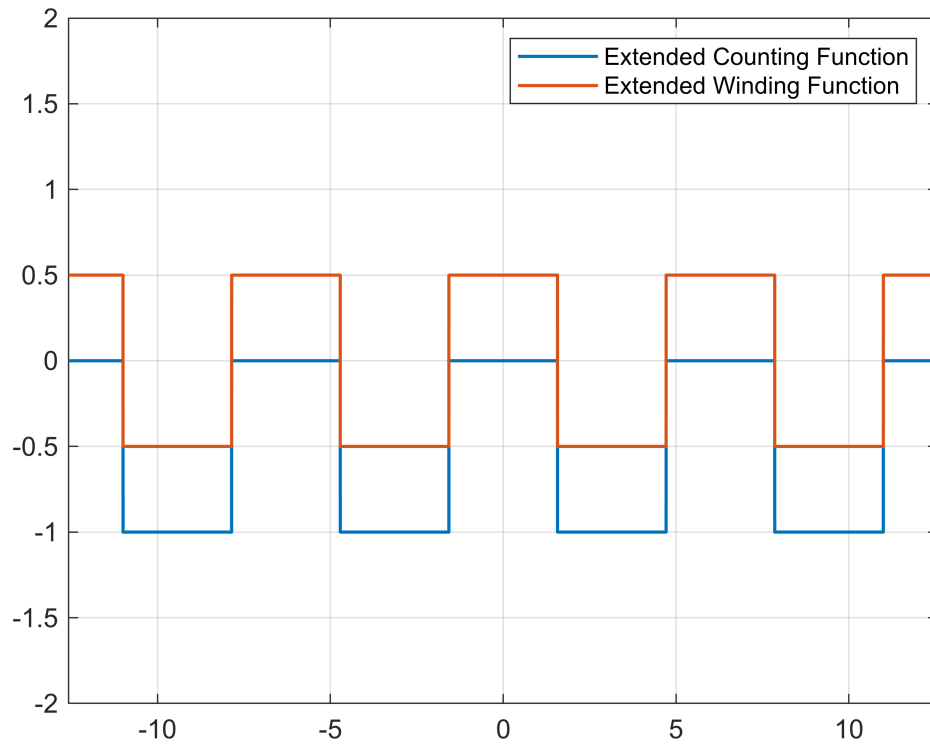
```
% assume( theta < T )
```

```
rotorCountingFunction_ext_avg = 1/T * int( subs(rotorCountingFunction_ext, theta_r,
THETA_R), phi, [0 T]);
rotorWindingFunction_ext = rotorCountingFunction_ext - rotorCountingFunction_ext_avg
```

```
rotorWindingFunction_ext(phi) =
```

$$\left\{ \begin{array}{ll} \frac{5734161139222659 \pi N_r}{36028797018963968} & \text{if } \phi + 2\pi < \theta_r \wedge \theta_r \leq \phi + \frac{5\pi}{2} \wedge \theta_r \in \mathbb{R} \\ \frac{5734161139222659 \pi N_r}{36028797018963968} - N_r & \text{if } 2\phi + 5\pi < 2\theta_r \wedge 2\theta_r \leq 2\phi + 7\pi \wedge \theta_r \in \mathbb{R} \wedge -4\pi \leq \phi \\ \frac{5734161139222659 \pi N_r}{36028797018963968} & \text{if } (\phi < \theta_r \wedge 2\theta_r \leq 2\phi + \pi) \vee (2\phi + 7\pi < 2\theta_r \wedge \theta_r \leq \phi + 4\pi \wedge (\phi + \\ \frac{5734161139222659 \pi N_r}{36028797018963968} - N_r & \text{if } 2\theta_r \leq 2\phi + 3\pi \wedge \theta_r \in \mathbb{R} \wedge -2\pi \leq \phi \wedge 2\phi + \pi < 2\theta_r \\ \frac{5734161139222659 \pi N_r}{36028797018963968} & \text{if } (2\theta_r + 3\pi \leq 2\phi \wedge \phi < \theta_r + 2\pi \wedge \theta_r \in \mathbb{R}) \vee (2\phi + 3\pi < 2\theta_r \wedge \theta_r : \\ \frac{5734161139222659 \pi N_r}{36028797018963968} - N_r & \text{if } 2\phi < 2\theta_r + 3\pi \wedge \theta_r \in \mathbb{R} \wedge 2\theta_r + \pi \leq 2\phi \wedge 0 \leq \phi \\ \frac{5734161139222659 \pi N_r}{36028797018963968} & \text{if } (2\theta_r + 7\pi \leq 2\phi \wedge \phi < \theta_r + 4\pi \wedge \theta_r \in \mathbb{R}) \vee (\theta_r \leq \phi \wedge 2\phi < 2\theta_r + \\ \frac{5734161139222659 \pi N_r}{36028797018963968} - N_r & \text{if } \phi < \theta_r + \frac{7\pi}{2} \wedge \theta_r + \frac{5\pi}{2} \leq \phi \wedge \theta_r \in \mathbb{R} \wedge 2\pi \leq \phi \\ \frac{5734161139222659 \pi N_r}{36028797018963968} & \text{if } \phi < \theta_r + \frac{5\pi}{2} \wedge \theta_r + 2\pi \leq \phi \wedge (\phi < \theta_r + 2\pi \vee (2\phi < 2\theta_r + 5\pi \wedge \phi \end{array} \right.$$

```
figure
fplot(subs(rotorCountingFunction_ext(phi),[theta_r N_r], [0 NR]), [-2*T 2*T], ...
    "DisplayName", "Extended Counting Function", ...
    "LineWidth", 1.2)
hold on
fplot(subs(rotorWindingFunction_ext(phi),[theta_r N_r], [0 NR]), [-2*T 2*T], ...
    "DisplayName", "Extended Winding Function", ...
    "LineWidth", 1.2)
hold off
ylim([-2 2])
grid on
legend
```



### (a) Magnetizing inductance of winding A on the stator

$$L_{AA} = \mu_0 r l \int_0^{2\pi} n_A(\phi) N_A(\phi) g^{-1}(\phi) d\phi \quad (1.167)$$

```
digits(4)
```

```
syms mu_o r l
Lss = mu_o*r*l * int( statorCountingFunction * statorWindingFunction_ext *
subs(g_phi_inv_ext, theta_r, [0 THETA_R T/2]), ...
    phi, [0 T]);
```

```
Lss = simplify( vpa(Lss') )
```

```
Lss =
```

$$\left( \begin{array}{c} \frac{0.7854 \left( \overline{N_s} \right)^2 \overline{l} \overline{\mu_o} \overline{r} (g_{\min} + g_{\max})}{g_{\min} g_{\max}} \\ \frac{0.7854 \left( \overline{N_s} \right)^2 \overline{l} \overline{\mu_o} \overline{r} (g_{\min} + g_{\max})}{g_{\min} g_{\max}} \\ \frac{0.7854 \left( \overline{N_s} \right)^2 \overline{l} \overline{\mu_o} \overline{r} (g_{\min} + g_{\max})}{g_{\min} g_{\max}} \end{array} \right)$$

## (b) Magnetizing inductance of winding F on the rotor

```
THETA_R_ARRAY = 0: T/8 : T;
```

```
rotorIntegrand = subs( ...  
    rotorCountingFunction * rotorWindingFunction_ext * g_phi_inv_ext, ...  
    theta_r, THETA_R_ARRAY);
```

```
Lrr = mu_o*r*l * int( rotorIntegrand, phi, [0 T]);
```

```
Lrr = simplify( vpa(Lrr') )
```

```
Lrr =
```

$$\begin{pmatrix} \frac{0.7854 (\overline{N_r})^2 \overline{l} \overline{\mu_o} \overline{r} (g_{\min} + g_{\max})}{g_{\min} g_{\max}} \\ \frac{0.7854 (\overline{N_r})^2 \overline{l} \overline{\mu_o} \overline{r} (g_{\min} + g_{\max})}{g_{\min} g_{\max}} \\ \frac{0.7854 (\overline{N_r})^2 \overline{l} \overline{\mu_o} \overline{r} (g_{\min} + g_{\max})}{g_{\min} g_{\max}} \\ \frac{0.3927 (\overline{N_r})^2 \overline{l} \overline{\mu_o} \overline{r} (g_{\min} + 2.0 g_{\max})}{g_{\min} g_{\max}} \\ \frac{0.3927 (\overline{N_r})^2 \overline{l} \overline{\mu_o} \overline{r} (g_{\min} + g_{\max})}{g_{\min} g_{\max}} \\ \frac{0.3927 (\overline{N_r})^2 \overline{l} \overline{\mu_o} \overline{r}}{g_{\max}} \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

```
syms K
```

```
Lrr_simplified = double( subs(Lrr, [(N_r^2*l*mu_o*r)' vars], [1 VALS]) )
```

```
Lrr_simplified = 9×1
```

```
2.5526  
2.5526  
2.5526  
2.0617  
1.2763  
0.4909  
0  
0  
0
```

```
figure
```

```
plot(THETA_R_ARRAY, Lrr_simplified, ...  
    "LineWidth", 1.2)
```

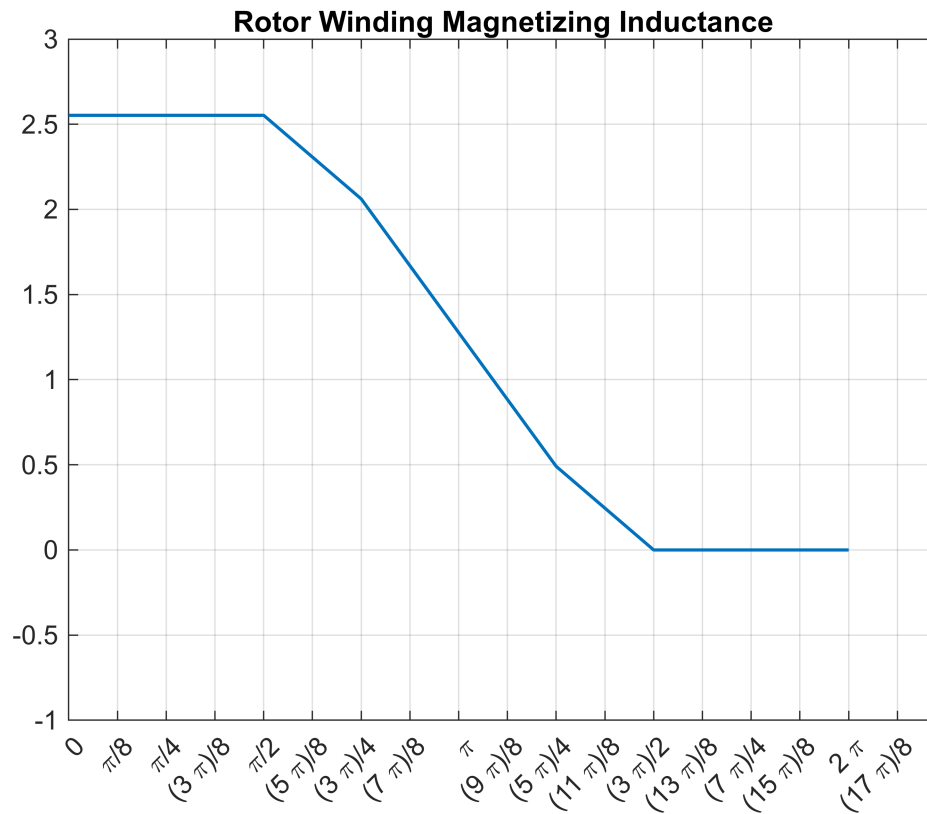
```
ylim([-1 3])
```

```
grid on
```

```

title("Rotor Winding Magnetizing Inductance")
ax = gca;
S = sym(ax.XLim(1):pi/8:ax.XLim(2));
ax.XTick = double(S);
ax.XTickLabel = arrayfun(@texlabel,S,'UniformOutput',false);

```



**(c) Mutual inductance between stator and rotor for the following salient pole synchronous machine**

$$L_{AB} = \mu_0 r l \int_0^{2\pi} n_A(\phi) N_B(\phi) g^{-1}(\phi) d\phi \quad (1.165)$$

```

THETA_R_ARRAY = 0: T/8 : T;

Lsr_integrand = subs( ...
    statorCountingFunction * rotorWindingFunction_ext * g_phi_inv_ext, ...
    theta_r, THETA_R_ARRAY);
Lsr = mu_o*r*l * int( Lsr_integrand, phi, [0 T]);

Lsr = simplify( vpa(Lsr') )

```

Lsr =

$$\left( \begin{array}{c} \frac{90949 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (g_{\min} + g_{\max})}{1000000000000000000 g_{\min} g_{\max}} \\ \frac{1.0\text{e-}17 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (90950.0 g_{\min} + 7.854\text{e+}16 g_{\max})}{g_{\min} g_{\max}} \\ \frac{3927 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (g_{\min} + g_{\max})}{5000 g_{\min} g_{\max}} \\ \frac{1.0\text{e-}17 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (90950.0 g_{\min} + 7.854\text{e+}16 g_{\max})}{g_{\min} g_{\max}} \\ \frac{90949 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (g_{\min} + g_{\max})}{1000000000000000000 g_{\min} g_{\max}} \\ \frac{1.0\text{e-}17 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (90950.0 g_{\min} - 7.854\text{e+}16 g_{\max})}{g_{\min} g_{\max}} \\ - \frac{3927 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (g_{\min} + g_{\max})}{5000 g_{\min} g_{\max}} \\ \frac{1.0\text{e-}17 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (90950.0 g_{\min} - 7.854\text{e+}16 g_{\max})}{g_{\min} g_{\max}} \\ \frac{90949 \bar{N}_r \bar{N}_s \bar{l} \bar{\mu}_o \bar{r} (g_{\min} + g_{\max})}{1000000000000000000 g_{\min} g_{\max}} \end{array} \right)$$

```
Lsr_simplified = double( subs(Lsr, [(N_r*N_s*l*mu_o*r)' vars], [1 VALS]) )
```

```
Lsr_simplified = 9x1
    0.0000
    1.5708
    2.5526
    1.5708
    0.0000
   -1.5708
   -2.5526
   -1.5708
    0.0000
```

```
figure
plot(THETA_R_ARRAY, Lsr_simplified, ...
     "LineWidth", 1.2)
ylim([-3 3])
title("Stator-Rotor Winding Mutual Inductance")
xlabel("\theta_r")
grid on

ax = gca;
S = sym(ax.XLim(1):pi/8:ax.XLim(2));
ax.XTick = double(S);
ax.XTickLabel = arrayfun(@texlabel,S,'UniformOutput',false);
```



