

Channel Coding Theory

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Course Information

Instructor	Laura Cottatellucci Office 333 Phone: 04 93 00 81 37 Any course related e-mail should contain the subject line "Channel Coding Theory" to get a quicker response.
Class Time	Wednesday 13:30–15:00 Wednesday 15:15–16:45
Location	Classroom 102
Important Dates	Exercise session: to be defined Final Exams: to be defined
Course Web Page	http://intranet.eurecom.fr/accademicAffaris/cursus_d/courses_content/techcourses/Coding .

Course Information (2)

Goal

The goal of this course is to introduce channel coding theory and its applications in communication systems. This is done by the design and performance analysis of encoders and decoders in both wireline and wireless communication systems. The course will address classical topics of algebraic coding theory (e.g. block codes and convolutional codes) and modern coding approaches based on soft decision.

Exams

Home-works will be assigned during the course. Homework will be graded. There will be an exercise session (TD) and a final exam. Dates and rules of the exercise session and the exam will be announced in class and by e-mail.

Grading

Just as an indication: Reports of exercise session 40%, Home-works 20%, Final exam 40%.

Course Information (3)

Related Courses

Digital communications (Raymond Knopp)
Information Theory (David Gesbert)

Coursenotes

You can find slides used during lectures in the web page.

Recommended Texts

At the end of each topic detailed references will be provided. Reference copies of the texts are available in the library or in my office. When possible, the referenced documents will be in the web page.

Outlines

- I. Outlines
- II. Communication Problem
 - II-a. Source-Channel Separation
 - II-b. Channel
 - II-c. Coding Problem
 - II-d. BIAWGN Channel
 - II-e. AWGN Channel
 - II-f. Decoders
- III. Channel Code Taxonomy
- IV. Outlines of the Course
- V. Some Notes on the History of Channel Coding
- VI. References

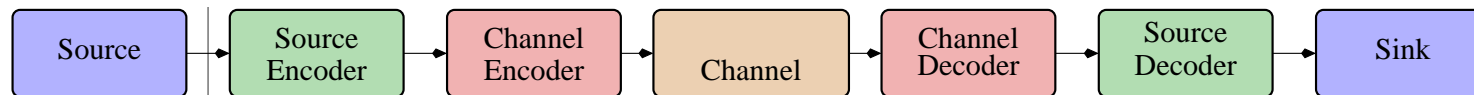
Basic Point-to-point Communication Problem



A **source** transmits via a **noisy** channel to a **sink**

Problem: **Reliable** transmission, i.e. we want to recreate the transmitted information with as little **distortion** as possible at the sink, at high speed.

Comm. Problem and Source-Channel Separation



Source Coding Theorem: For a given source and distortion measure there exists a minimum rate $R = R(d)$ (bit per emitted source symbol) which is necessary and sufficient to describe this source with distortion not exceeding d .

Channel Coding Theorem: Given a **channel** there exists a maximum rate (bits per channel use) at which information can be transmitted reliably, i.e. with vanishing error probability, over the channel.

The maximum rate is called the capacity of the channel and is denoted by C .

Comm. Problem and Source-Channel Separation (2)

Source-Channel Separation Coding Theorem: Given a channel of capacity C , a source can be reconstructed with a distortion at most of d at the receiver if $R(d) < C$, i.e. if the rate required to represent the given source with the allowed distortion is smaller than the channel capacity. Conversely, no scheme can do better.

Under the assumptions of the source-channel separation theorem

The approach of separating source and channel coding is optimum.

Comm. Problem and Source-Channel Separation (3)

Examples of situations where source channel coding separation is not optimum:

- **Delay constraints;**
- **Multi-user scenarios.**

Joint source coding could be substantially better in terms of complexity and delay.

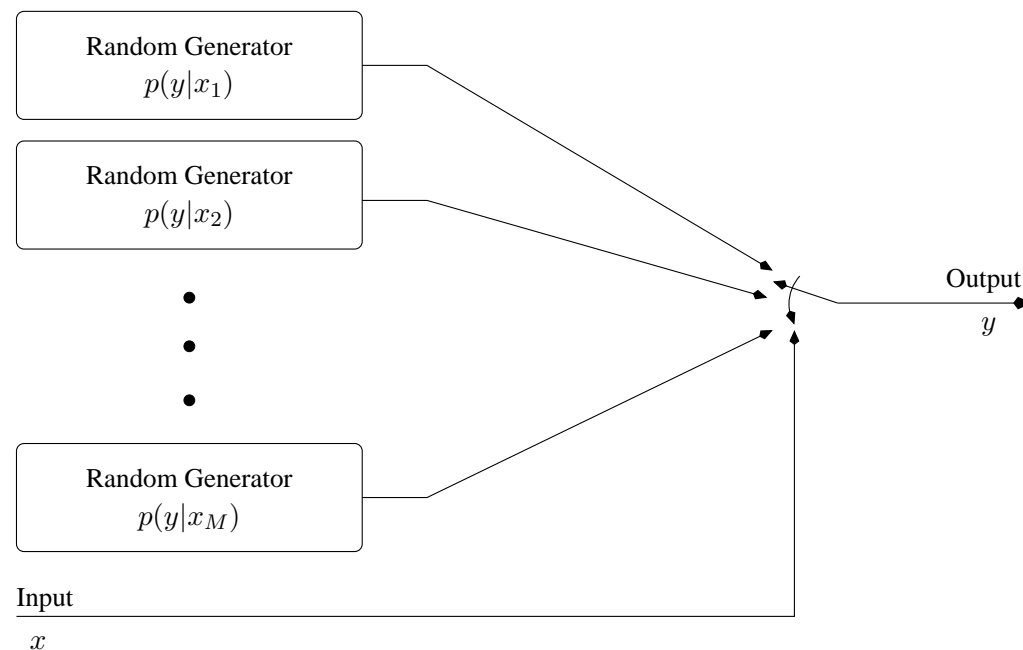
In the following we do not concern about source coding and we assume:

- **Source coding problem optimally solved.**
- **The source emits a sequence of i.i.d. bits.**

The Channel (1)

The channel is modelled as a random mapping from the input x to the output y

It is described by a cumulative distribution function $P(x, y)$ or a probability density(mass) function (p.d.(m.) f.) $p(x, y)$.



Channel: Taxonomy

with feedback

e.g. Automatic Repeat Request (ARQ)

memoryless

e.g. flat fading, additive white noise, etc.

without spatial diversity

e.g. single receive antenna

binary input

discrete output

without feedback

e.g. Forward Error Correction (FEC)

with memory

e.g. frequency selective fading, additive colored noise

with spatial diversity

e.g. multiple transmit, multiple receive antennas

continuous waveform input

continuous output

	Binary input	Continuous waveform input
Discrete output	BEC, BSC	
Continuous output	BIAWGN	AWGN, Fading channel

Discrete Input – Discrete Output Channels

Communication Model



$\mathbf{u} = (u_0, u_1, \dots, u_{k-1})$: binary k -tuple called **message**

$\mathbf{v} = (v_0, v_1, \dots, v_{n-1})$: n -tuple of discrete symbols called **codeword**

$\mathbf{r} = (r_0, r_1, \dots, r_{n-1})$: n -tuple of discrete symbols at the channel output

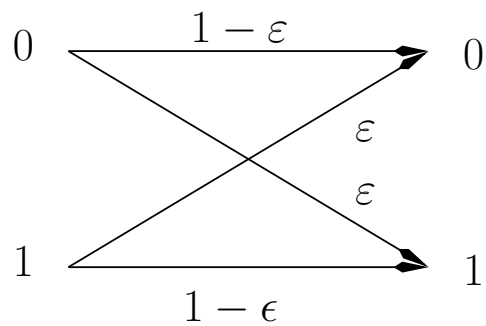
$\hat{\mathbf{u}} = (\hat{u}_0, \hat{u}_1, \dots, \hat{u}_{k-1})$: binary k -tuple called **decoded message**

$R = \frac{k}{n}$ **[bit/symbol] is the code rate**

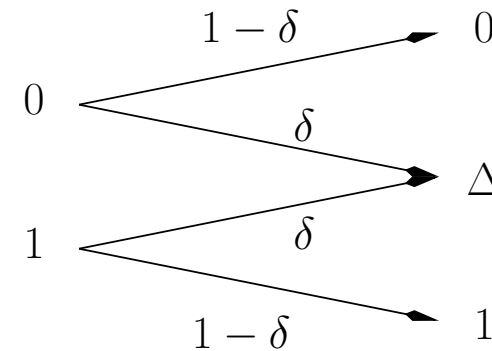
The code rate is the number of bits entering in the encoder per transmitted symbol.

Examples

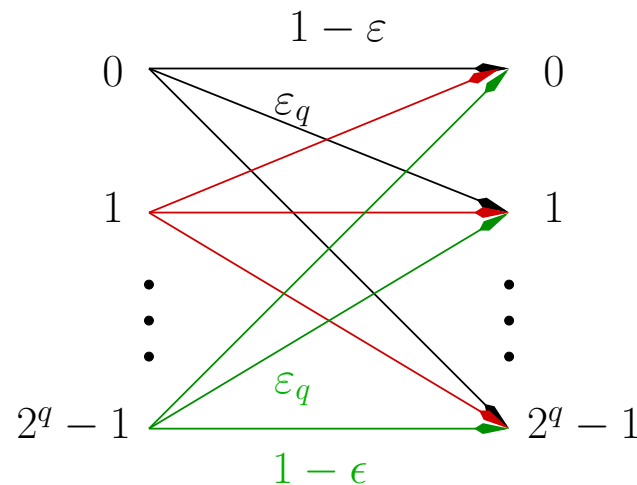
Binary Symmetric Channel (BSC)



Binary Erasure Channel (BEC)



Universal Binary Symmetric Channel (UBSC)



$$\varepsilon_q = \frac{\varepsilon}{2^q - 1}$$

Some Capacities of Discrete Channels

From the general equation for the capacity of a channel $P_{X|Y}(x|y)$

$$C = \max_{P_X(x)} I(X; Y) = \max_{P_X(x)} \sum_y \sum_x P_{X,Y}(x, y) \log_2 \frac{P_{X,Y}(x, y)}{P_X(x) P_Y(y)}$$

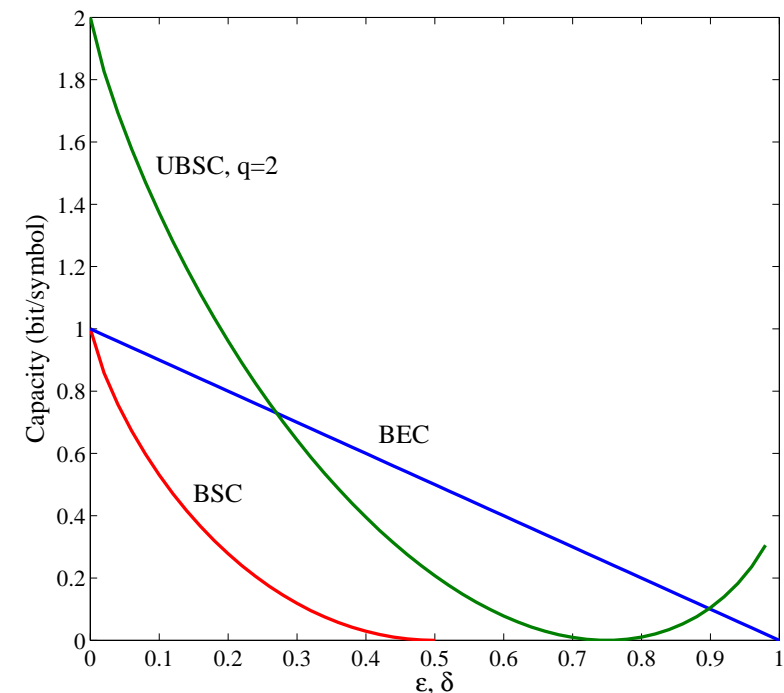
$$C_{\text{BSC}} = 1 - \mathcal{H}(\varepsilon) \text{ with}$$

$$\mathcal{H}(x) = -x \log_2(x) - (1 - x) \log_2(1 - x)$$

being the entropy of a binary source

$$C_{\text{BEC}} = 1 - \delta$$

$$C_{\text{UBSC}} = q + \varepsilon \log_2 \varepsilon_q + (1 - \varepsilon) \log_2(1 - \varepsilon) \leq q$$



The Coding Problem

Capacity is achievable with random codes for messages of infinite length...

...However, the complexity of the decoder is not affordable!

Example of a simple code: Repetition Code

	Decoded bit	Error probability	(rate, error prob.)
First trial:	$\hat{u} = \hat{u}_{\text{MAP}}(r_1) = r_1$	$P_{e,1} = \varepsilon$	$(1, \varepsilon)$
Third trial:	$\hat{u} = \hat{u}_{\text{MAP}}(r_1, r_2, r_3)$ $= \text{majority}(r_1, r_2, r_3)$	$P_{e,3} = \binom{3}{2} \varepsilon^2 (1 - \varepsilon) + \varepsilon^3$	$(\frac{1}{3}, P_{e,3})$
\vdots	\vdots	\vdots	\vdots
k th trial (k odd):	$\hat{u} = \hat{u}_{\text{MAP}}(r_1, \dots, r_k)$ $= \text{majority}(r_1, \dots, r_k)$	$P_{e,k} = \sum_{i > \frac{k}{2}} \binom{k}{i} \varepsilon^i (1 - \varepsilon)^{k-i}$	$(\frac{1}{k}, P_{e,k})$

Low decoding complexity but in order to get $P_e \rightarrow 0$ also the rate vanishes!

Object: Design codes enabling low/affordable encoding and decoding complexity and vanishing error probability with positive rate.

Some Definitions

Definition of Code: A code \mathcal{C} of **length** n and **cardinality** M over a field (set endowed with some specific operation) \mathbb{F} is a subset of \mathbb{F}^n with M elements.

$$\mathcal{C}(n, M) = \{\mathbf{v}^{[1]}, \mathbf{v}^{[2]}, \dots, \mathbf{v}^{[M]}\}, \quad \mathbf{v}^{[m]} \in \mathbb{F}^n, \quad 1 \leq m \leq M.$$

The elements of the code are called **codewords**. The parameter n is called the **blocklength**.

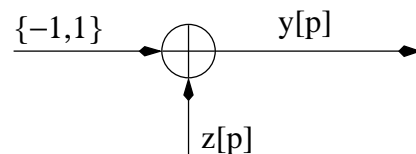
Example: For $\mathbb{F} = \{0, 1\}$, $n = 5$ and $M = 4$

$$\mathcal{C} = \{01001, 11001, 11011, 10101\}$$

Definition of Encoder: An encoder \mathcal{E} is the set of the M pairs (u, v) where u is the message or data word and v is the codeword belonging to a code \mathcal{C} .

Definition of Rate: The rate (measured as information symbol per transmitted symbol) of a code $\mathcal{C}(n, M) = \frac{1}{n} \log_{|\mathbb{F}|} M$.

Binary-Input Additive White Gaussian Channel



$z[p]$ is a random Gaussian sequence with uncorrelated elements (white noise), zero mean, and variance σ^2 .

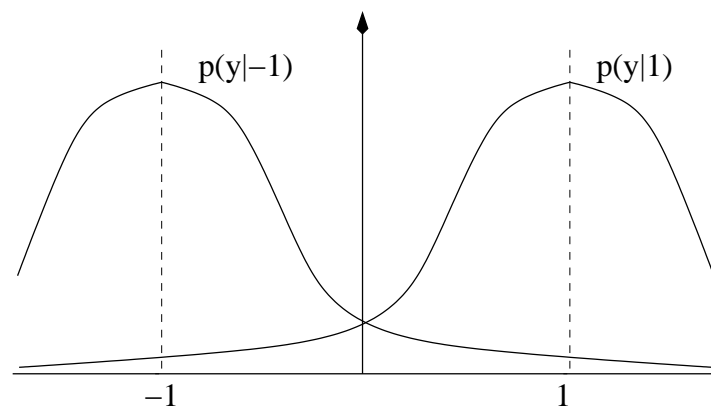
$$p_Z(z) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{z^2}{2\sigma^2}}$$

Then, the conditioned pdf describing the channel are also Gaussian.

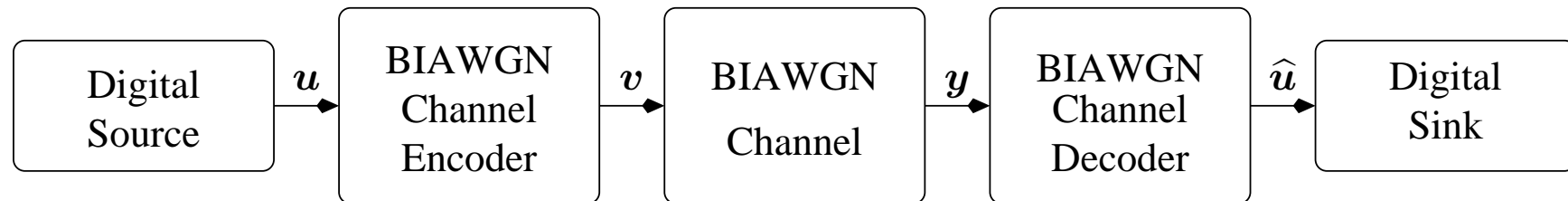
Note that we implicitly assumed that the channel is **symmetric**.

If \mathcal{E}_s is the energy of the transmitted symbol, i.e. we transmit $\pm\sqrt{\mathcal{E}_s}$, then

$$p_{Y|\pm\sqrt{\mathcal{E}_s}}(y|\pm\sqrt{\mathcal{E}_s}) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y\mp\sqrt{\mathcal{E}_s})^2}{2\sigma^2}}$$



Optimum Communication System Model



u , v and \hat{u} are defined as for the discrete-input discrete-output channel.

$\mathbf{y} = (y_0, y_1, \dots, y_{n-1})$: n -tuple of received signals at the channel output with values in \mathbb{R} .

In contrast to a channel decoder for discrete output channels...

...a **BIAWGN** channel decoder processes **analog** sequences.

Such decoders are called **soft decoders**.

Capacity of a BIAWGN Channel (1)

Note that for a BIAWGN channel

$$p_{Y|X}(y|x = -\sqrt{\mathcal{E}}) = p_{Y|X}(-y|x = \sqrt{\mathcal{E}}).$$

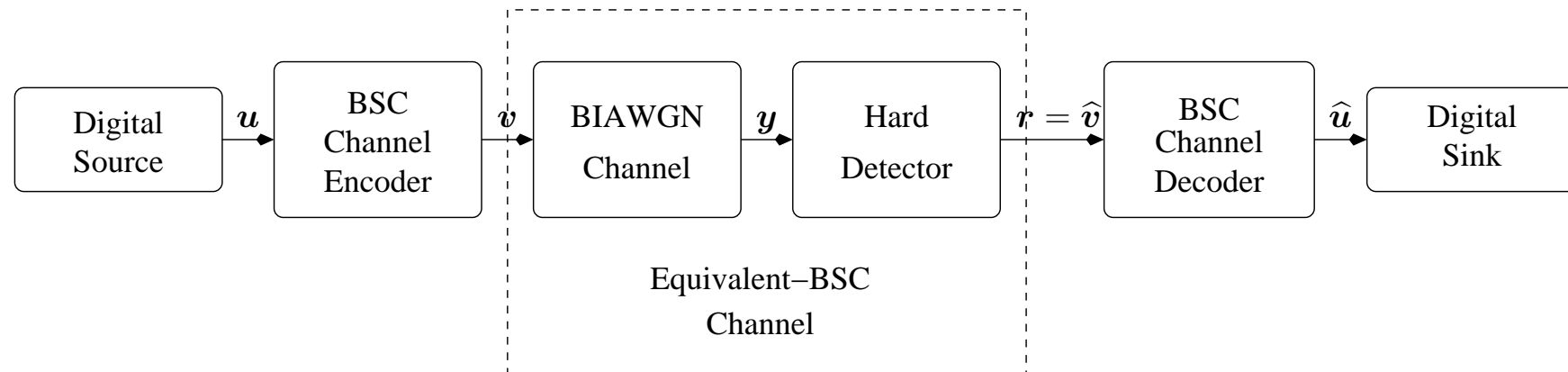
Thanks to the symmetry of the channel, the capacity is obtained for equiprobable inputs.

Capacity of a BIAWGN Channel (2)

$$\begin{aligned}
C_{\text{BIAWGN}} &= \max_{P_X(x)} I(X; Y) \\
&= I(X; Y) \quad \text{for } P_X(x) = \frac{1}{2} \text{ and } x = \pm\sqrt{\mathcal{E}} \\
&= H(X) - H(X|Y) \\
&= 1 - \sum_{x=\pm\sqrt{\mathcal{E}}} \int_{\mathbb{R}} p_{XY}(x, y) \log \frac{1}{p_{X|Y}(x|y)} dy \\
&= 1 - \sum_{x=\pm\sqrt{\mathcal{E}}} \int_{\mathbb{R}} p_{XY}(x, y) \log \frac{p_Y(y)}{p_{Y|X}(y|x)p_X(x)} dy \\
&= 1 - \sum_{x=\pm\sqrt{\mathcal{E}}} \int_{\mathbb{R}} p_{XY}(x, y) \log \frac{\sum_{x=\pm\sqrt{\mathcal{E}}} p_{Y|X}(y|x)p_X(x)}{p_{Y|X}(y|x)p_X(x)} dy \\
&= 1 - \int_{\mathbb{R}} p_{Y|X}(y|x = \pm\sqrt{\mathcal{E}}) \log \frac{2 \sum_{x=\pm\sqrt{\mathcal{E}}} p_{Y|X}(y|x)p_X(x)}{p_{Y|X}(y|x = \pm\sqrt{\mathcal{E}})} dy \quad \text{for } x = -\sqrt{\mathcal{E}} \text{ or } x = \sqrt{\mathcal{E}}
\end{aligned}$$

* $H(X)$ is the entropy of X . In case of binary inputs $H(X) = \mathcal{H}(x)$.

A Suboptimum Approach



u , v , and \hat{u} are defined as for the discrete-input discrete-output channel.

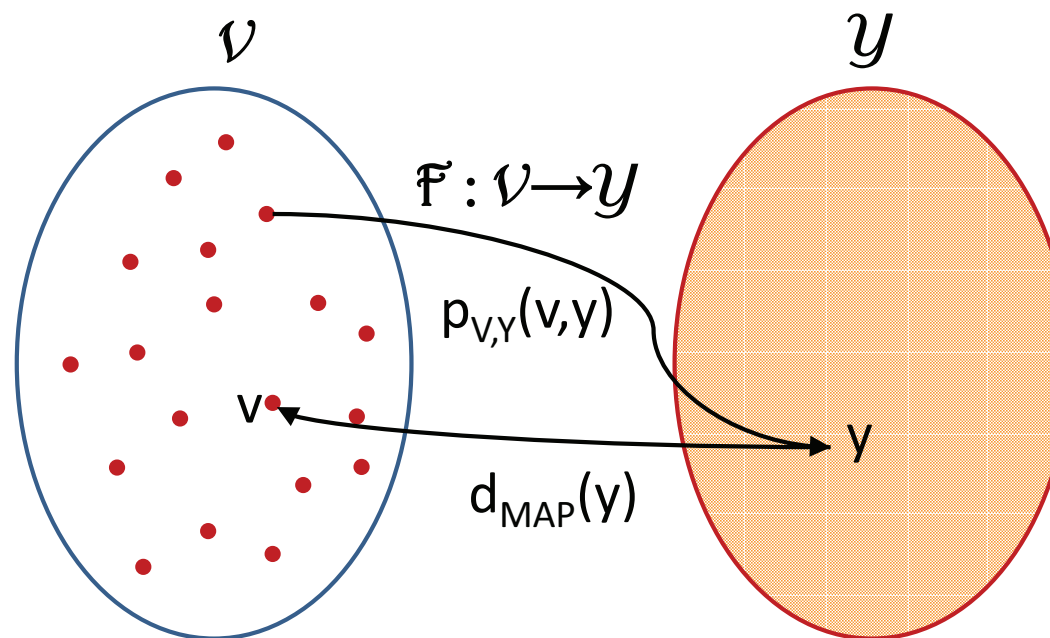
r is defined as in the optimum communication system for BIAWGN channel.

$\hat{v} = (\hat{v}_0, \hat{v}_1, \dots, \hat{v}_{n-1})$: n -tuple of binary symbols corresponding to the detected transmitted signals v .

The hard detector maps each received real element of the vector y onto an element of a binary set.

Maximum A Posteriori (MAP) Probability Detector

Definition of Detector: Given a random mapping from a discrete set \mathcal{V} to a discrete or continuous set \mathcal{Y} a detector $d(y)$ of $v \in \mathcal{V}$ given $y \in \mathcal{Y}$ is a deterministic mapping $d : \mathcal{Y} \rightarrow \mathcal{V}$.



Maximum A Posteriori (MAP) Probability Detector (2)

If the random mapping $\mathcal{F} : \mathcal{V} \rightarrow \mathcal{Y}$ is described by the pdf (pms) $p_{V,Y}(v, y)$, then the MAP detector is given by

$$d_{\text{MAP}}(y) = \underset{v}{\operatorname{argmax}} p_{V|Y}(v|y).$$

Using the Markov rule $p_{V,Y}(v, y) = p_{V|Y}(v|y)p_Y(y) = p_{Y|V}(y|v)p_V(v)$

$$\begin{aligned} d_{\text{MAP}}(y) &= \underset{v}{\operatorname{argmax}} \frac{p_{Y|V}(y|v)p_V(v)}{p_Y(y)} \\ &= \underset{v}{\operatorname{argmax}} p_{Y|V}(y|v)p_V(v) \end{aligned}$$

Maximum A Posteriori Probability Detector (3)

If V is an equiprobable random variable, i.e. $\forall v \in \mathcal{V} \ P_V(v) = \frac{1}{|\mathcal{V}|}$

$$d_{\text{MAP}}(y) = \underset{v}{\operatorname{argmax}} p_{Y|V}(y|v)$$

$d_{\text{MAP}}(y)$ coincides with the definition of the maximum likelihood detector $d_{\text{ML}}(y)$.

If $|\mathcal{V}| = 2$

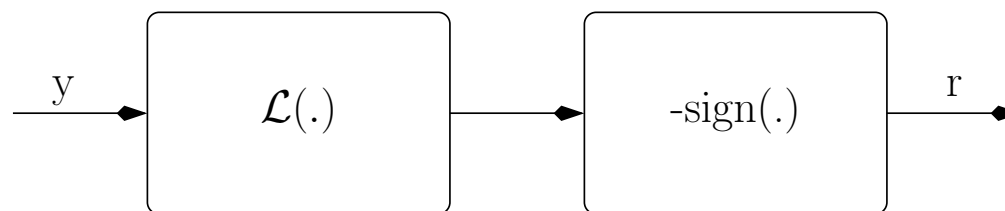
$$\begin{aligned} d_{\text{MAP}}(y) &= \begin{cases} 0 \ (-1) & \text{for } \frac{p_{Y|V}(y|0)}{p_{Y|V}(y|1)} > 1, \\ 1 & \text{otherwise} \end{cases} \\ &= \begin{cases} 0 \ (-1) & \text{for } \log \frac{p_{Y|V}(y|0)}{p_{Y|V}(y|1)} > 0, \\ 1 & \text{otherwise} \end{cases} \end{aligned}$$

Maximum A Posteriori Probability Detector (4)

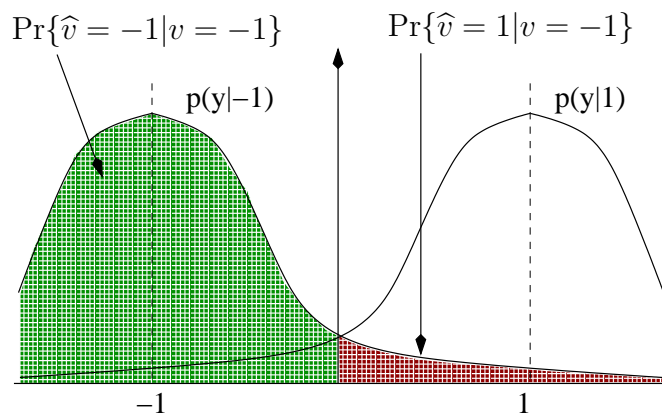
The ratio $\frac{p_{Y|V}(y|0)}{p_{Y|V}(y|1)}$ is called **likelihood ratio**.

$\mathcal{L}(y) = \log \frac{p_{Y|V}(y|0)}{p_{Y|V}(y|1)}$ is the **log-likelihood ratio**.

Hard Detector for a BIAWGN channel



Capacity of the Suboptimum Scheme



\mathcal{E} : average energy of the transmitted signal.

σ^2 : variance of the AWGN.

$$\text{SNR} = \frac{\mathcal{E}}{\sigma^2}$$

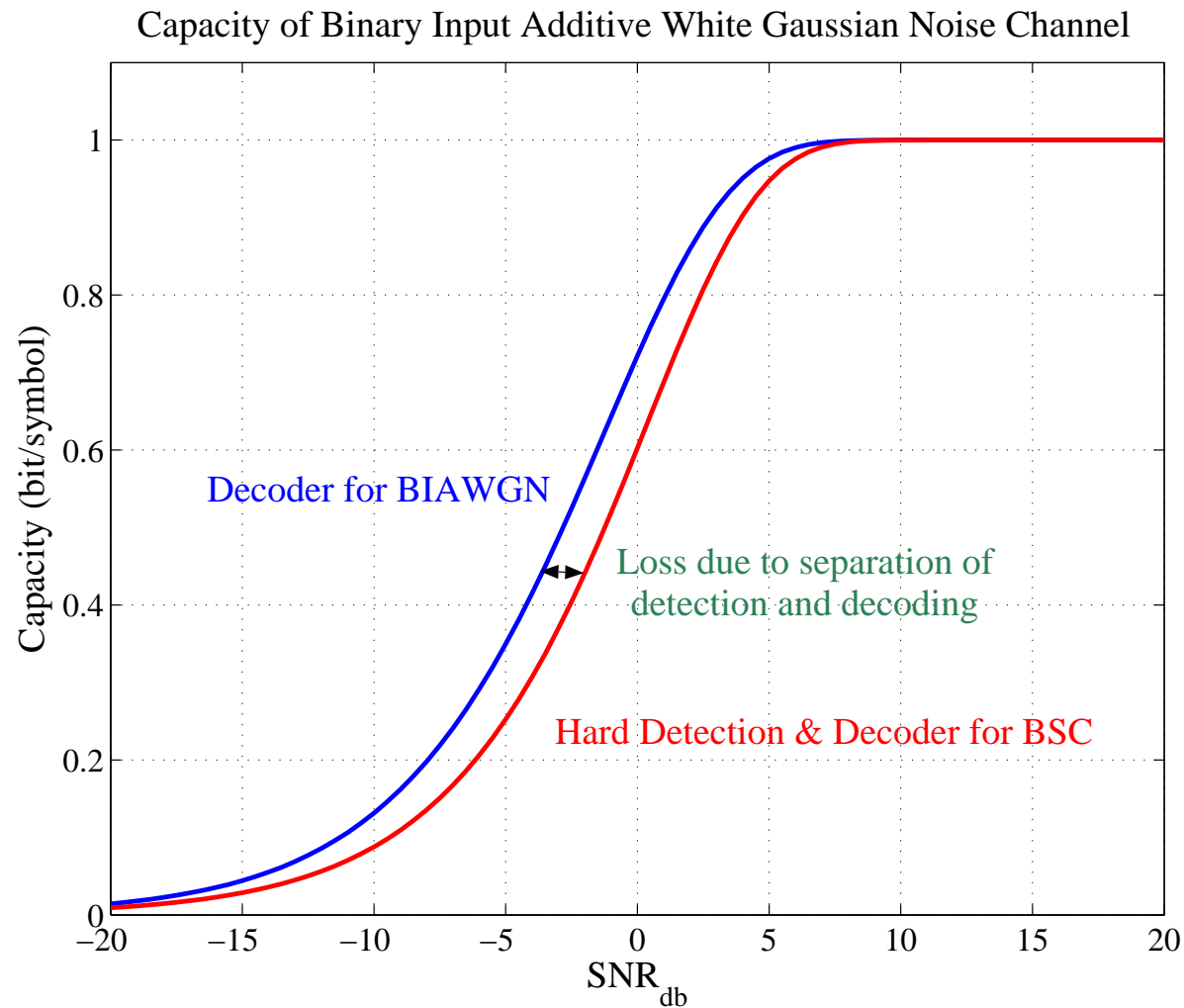
Probability of error of the hard detector

$$\begin{aligned} P_e &= \Pr\{\hat{v} = -1|v = 1\}P_V(v = 1) + \Pr\{\hat{v} = +1|v = -1\}P_V(v = -1) \\ &= \int_0^{+\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y+\sqrt{\mathcal{E}})^2}{2\sigma^2}} dy \\ &= \frac{1}{2} \text{erfc} \left(\sqrt{\frac{\text{SNR}}{2}} \right) \end{aligned}$$

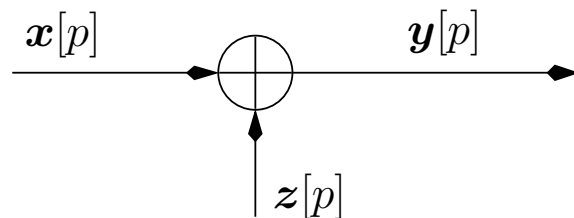
The capacity of the suboptimum scheme is given by the capacity of the equivalent BSC with $\varepsilon = P_e$.

$$C_{\text{eq-BSC}} = 1 - \mathcal{H} \left(\frac{1}{2} \text{erfc} \left(\sqrt{\frac{\text{SNR}}{2}} \right) \right)$$

BIAWGN Channel versus the Equivalent-BSC



Additive White Gaussian Channel (Discrete-Time)



Channel Input: $\{\mathbf{x}[p], p \in \mathcal{Z}\}$, sequence of elements in \mathbb{R}^N , i.e. $\mathbf{x}[p] \in \mathbb{R}^N$.

For $N = 1$, $\{\mathbf{x}[p]\}$ is a sequence of reals. For $N = 2$, $\{\mathbf{x}[p]\}$ is a sequence of complex numbers. For $N > 2$, $\{\mathbf{x}[p]\}$ is a sequence of vectors (typical case: MIMO channels).

$$\mathbf{Y}|\mathbf{X} \sim \mathcal{N}(\mathbf{x}, \mathbf{Q})$$

Additive Noise: $\{\mathbf{z}[p], p \in \mathcal{Z}\}$, is a random process (discrete time) of independent elements in \mathbb{R}^N described by the pdf

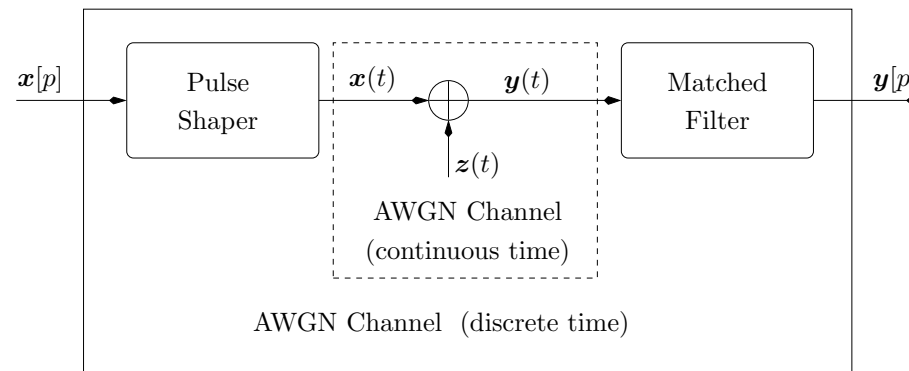
$$P_{\mathbf{Z}}(\mathbf{z}) = \frac{1}{\sqrt{(2\pi)^N \det \mathbf{Q}}} e^{-\frac{\mathbf{z}^H \mathbf{Q}^{-1} \mathbf{z}}{2}} \quad (\mathcal{N}(\mathbf{0}, \mathbf{Q}))$$

being $\mathbf{Q} \in \mathbb{R}^{N \times N}$ a diagonal matrix. We assume $\mathbf{Q} = \sigma^2 \mathbf{I}$ (i.i.d. random variables).

Channel Output: $\{\mathbf{y}[p], p \in \mathbb{Z}\}$ random sequence of elements in \mathbb{R}^N .

Discrete-time versus Continuous-time AWGN Channels

An AWGN channel in the discrete-time domain is typically obtained from a continuous time AWGN channel via a pulse shaper and a matched filter.



Pulse waveforms with unit energy



- \mathcal{E}_p , the energy of continuous waveform transmitted in pT equals the energy of the discrete signal $\mathbf{x}[p]$, i.e. $\mathcal{E}_p = \|\mathbf{x}[p]\|^2$;
- The variance σ^2 of the discrete Gaussian noise per dimension equals $\frac{N_0}{2}$, the power spectral density per dimension of the continuous noise, i.e. $\sigma^2 = \frac{N_0}{2}$.

Capacity of an AWGN Channel (Discrete Time)

Capacity in an AWGN channel can be achieved with Gaussian distributed input.

Under the constraint of average energy \mathcal{E} , $p_{\mathbf{X}}(\mathbf{x}) = \left(\frac{2\pi\mathcal{E}}{N}\right)^{-\frac{N}{2}} e^{-\frac{|\mathbf{x}|^2}{2\mathcal{E}}}$

Let us focus on $N = 1$ and recall that the entropy of a Gaussian random variable X is

$$H(x) = \frac{1}{2} \log 2\pi e E\{x^2\}$$

Since

$$Y \sim \mathcal{N}\left(0, \mathcal{E} + \frac{N_0}{2}\right) \quad Z \sim \mathcal{N}\left(0, \frac{N_0}{2}\right)$$

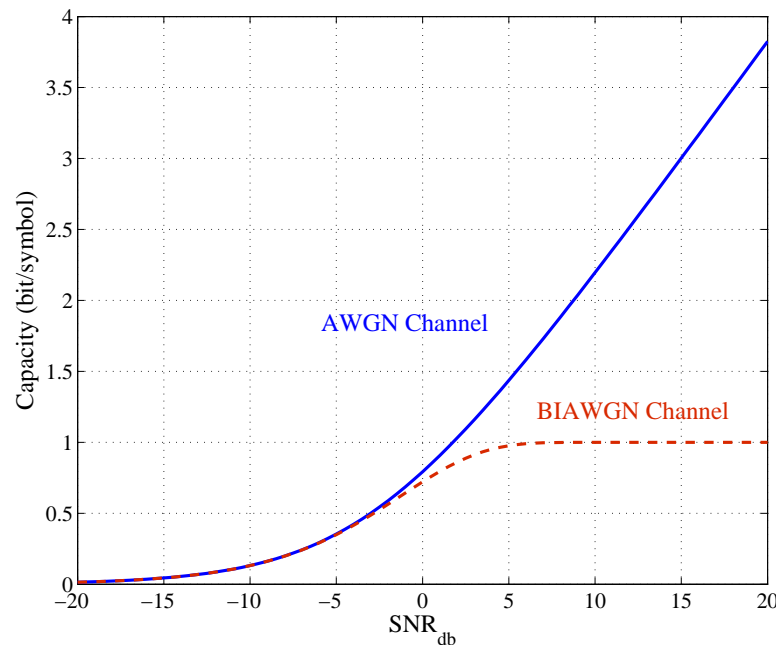


$$\begin{aligned} C &= H(Y) - H(Y|X) = \frac{1}{2} \log \left(2\pi e \left(\mathcal{E} + \frac{N_0}{2} \right) \right) - \frac{1}{2} \log \left(2\pi e \frac{N_0}{2} \right) \\ &= \frac{1}{2} \log \left(1 + \frac{2\mathcal{E}}{N_0} \right) \end{aligned}$$

being $\frac{2\mathcal{E}}{N_0} = \text{SNR}$.

AWGN Channel versus BIAWGN Channel: Capacity

Transmission of antipodal signals in a AWGN channel \Rightarrow BIAWGN channel



Transmission of codewords with antipodal signals (BIAWGN channel) almost optimum only at low SNR.

How to use the channel at high SNR effectively?

Coding in a signal space!

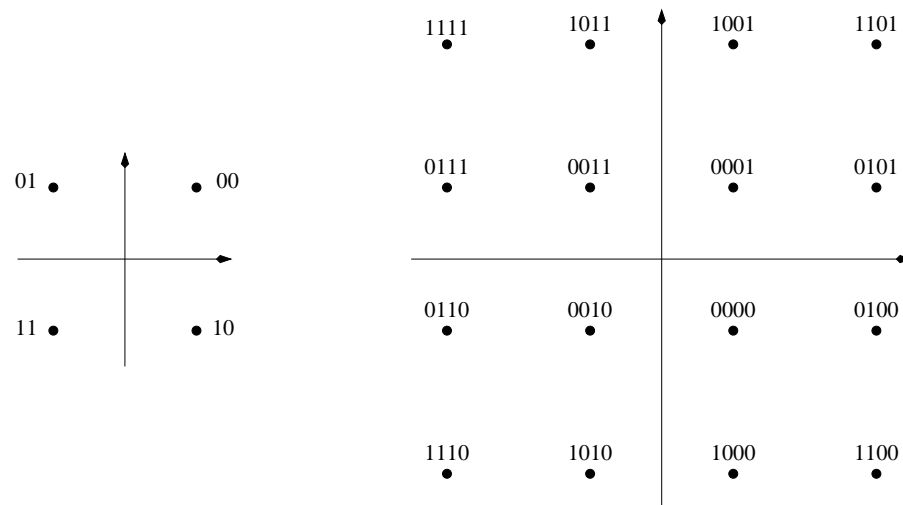
Coding in a Signal Space

Definition: A **finite signal constellation** is a finite set $\mathcal{S} = \{x\}$ of vectors in \mathbb{R}^N having cardinality $M = |\mathcal{S}|$. The vectors x are called points or signals.

For simplicity we assume $M = 2^m$.

Definition: **Labelling** is a one-to-one map, which associates with every element $x \in \mathcal{S}$ an n -tuple of binary digits.

Examples

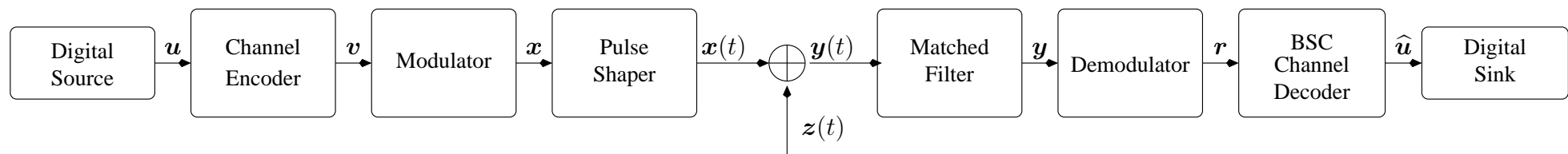


Coding in a Signal Space (2)

Definition: Modulation is the association of a n -tuple of binary digits with the elements of \mathcal{S} , based on labelling.

Definition: The demodulator transforms the received vector y back to a sequence of m binary digits. Note that in general the dimension of y may differ from the dimension of x .

System Model for an AWGN Channel



u , v , y , r , and \hat{u} are as previously defined.

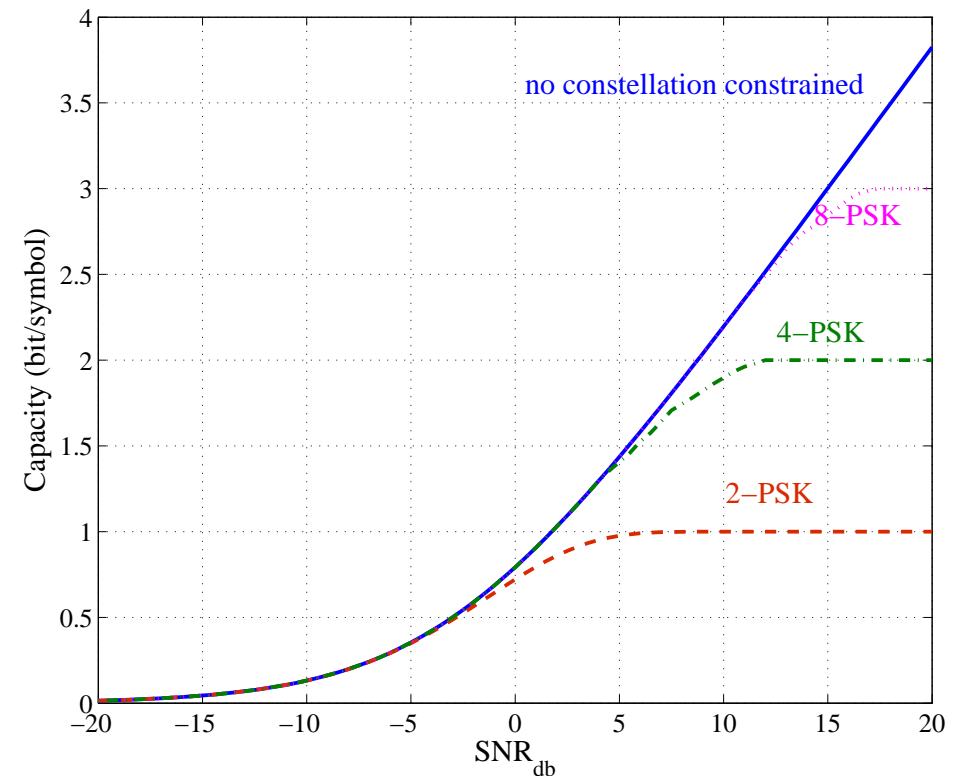
$\{x\}$ is a sequence of elements in the signal space \mathcal{S} .

Capacity of a Constellation-Constrained AWGN Channel

To avoid the maximization of the mutual information over the a priori probability, we make the simplifying assumption that the signals in $|\mathcal{S}|$ are transmitted with equal probabilities.

As for the BIAWGN channel

$$\begin{aligned} I(\mathbf{X}; \mathbf{Y}) &= H(\mathbf{X}) - H(\mathbf{X}|\mathbf{Y}) \\ &= \log |\mathcal{S}| - \mathbb{E} \left\{ \log \frac{1}{p_{\mathbf{X}|\mathbf{Y}}(\mathbf{x}|\mathbf{y})} \right\} \\ &= \log |\mathcal{S}| - \mathbb{E} \left\{ \log \frac{\sum_{\mathbf{x}' \in \mathcal{S}} p_{\mathbf{Y}|\mathbf{X}}(\mathbf{y}|\mathbf{x}')}{p_{\mathbf{Y}|\mathbf{X}}(\mathbf{y}|\mathbf{x})} \right\} \end{aligned}$$



Performance Measures for a Channel Decoder

We are interested mainly in two performance measures:

- Message (symbol) error probability P_e (or SER)

$$P_e = \sum_u \Pr(\mathbf{u} \neq \hat{\mathbf{u}})$$

- Bit error probability P_b (or BER)

$$P_b = \sum_u \sum_{k=1}^K \Pr(u_k \neq \hat{u}_k)$$

Relation between P_e and P_b

$$\frac{P_e}{K} \leq P_b \leq P_e$$

Maximum a Posteriori Decoders

Object: Minimize $P_e = \sum_{\mathbf{u} \in \mathbb{F}^K} \sum_{\mathbf{r} \in \mathcal{S}} \Pr(\mathbf{u} \neq \hat{\mathbf{u}}|\mathbf{r})\Pr(\mathbf{r})$

P_e is minimized if $\Pr(\mathbf{u} \neq \hat{\mathbf{u}}|\mathbf{r})$ is minimized, or, equivalently, if $\Pr(\mathbf{u} = \hat{\mathbf{u}}|\mathbf{r})$ is maximized. Then, the decoder that minimizes the message error probability is

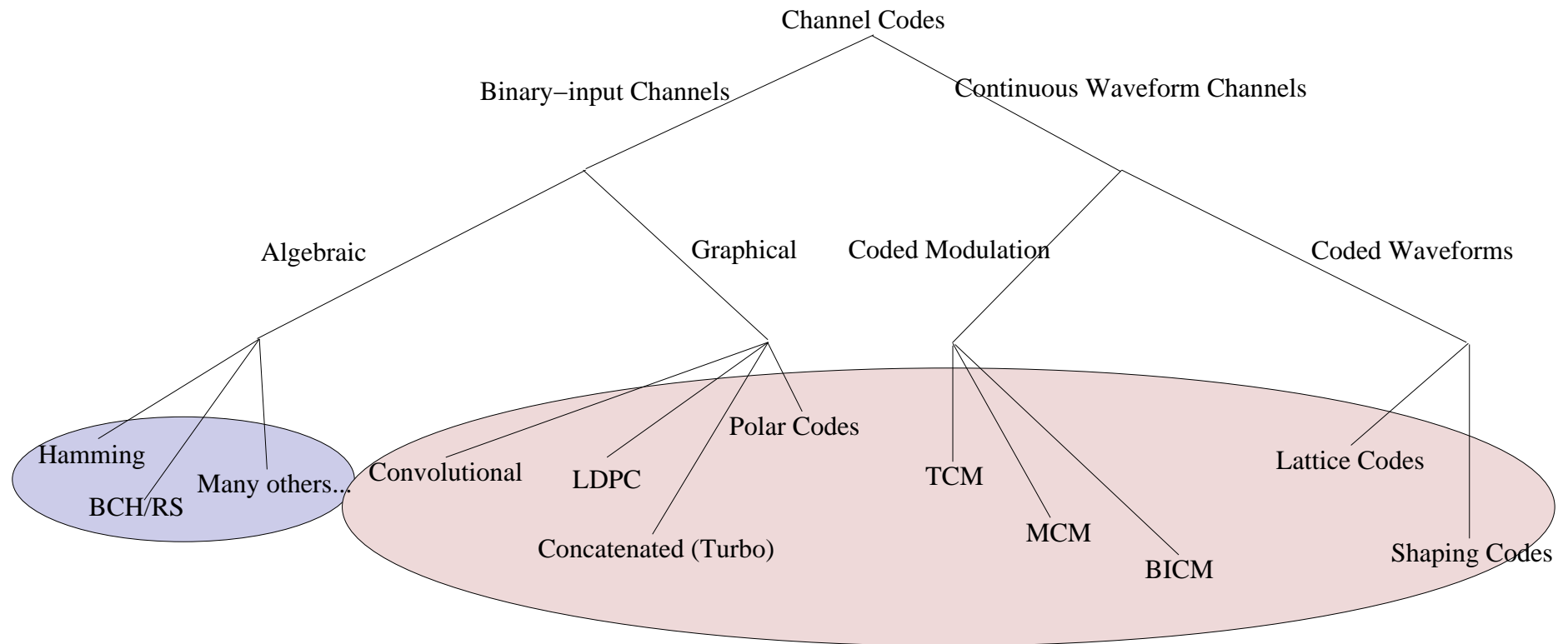
$$\begin{aligned}\hat{\mathbf{u}}_{\text{MAP}} &= \underset{\mathbf{u}}{\operatorname{argmax}} P_{U|R}(\mathbf{u}|\mathbf{r}) \\ &= \underset{\mathbf{u}}{\operatorname{argmax}} \frac{P_{R|U}(\mathbf{r}|\mathbf{u})P_U(\mathbf{u})}{P_R(\mathbf{r})} \\ &= \underset{\mathbf{u}}{\operatorname{argmax}} P_{R|U}(\mathbf{r}|\mathbf{u})P_U(\mathbf{u})\end{aligned}$$

If the transmitted messages are equiprobable

$$\hat{\mathbf{u}}_{\text{MAP}} = \underset{\mathbf{u}}{\operatorname{argmax}} P_{R|U}(\mathbf{r}|\mathbf{u})$$

For equiprobable messages the MAP decoder coincides with the maximum likelihood decoder.

Channel Code Taxonomy



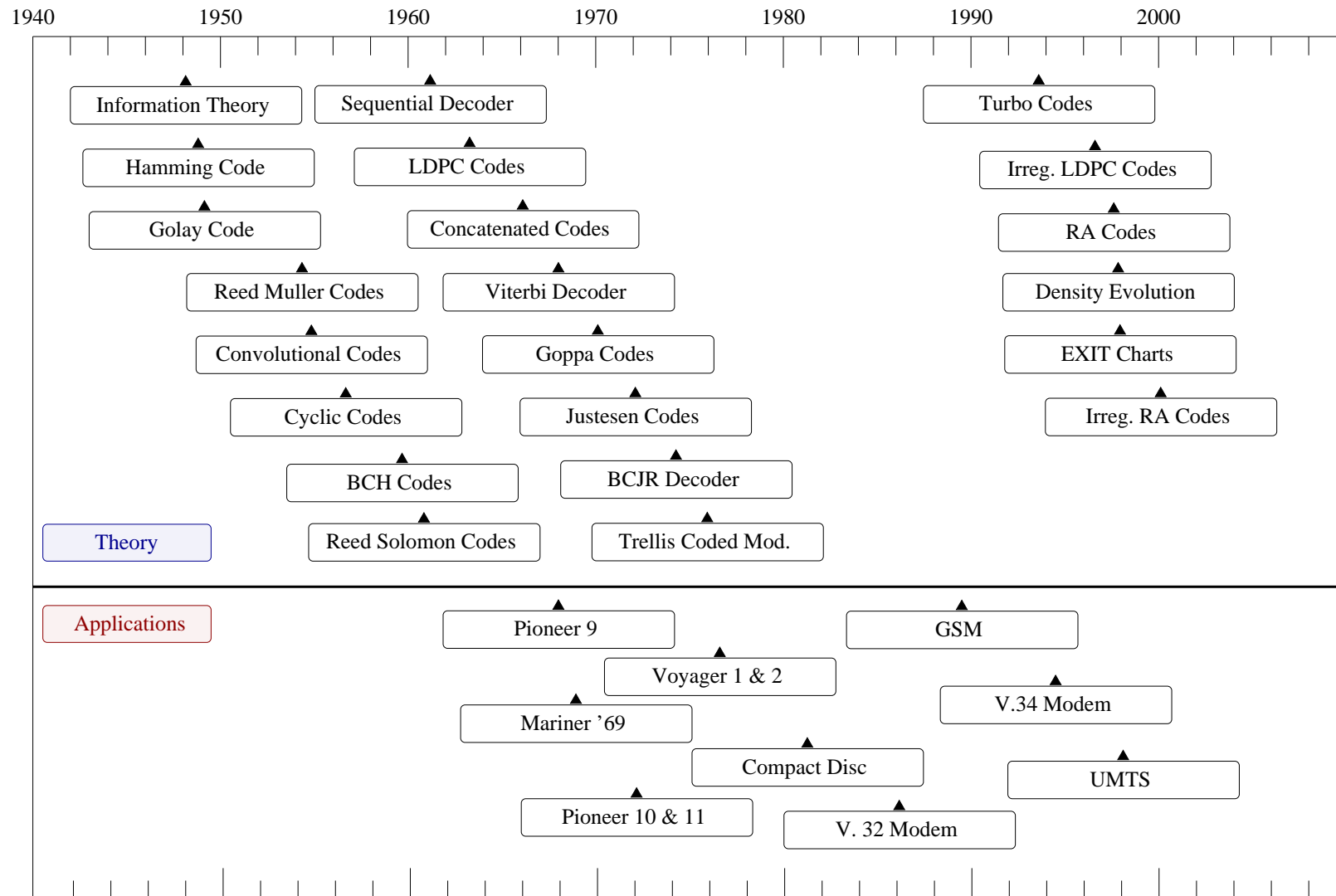
Outlines

- **Block codes**
- **Convolutional codes**
- **Serially and parallel concatenated (turbo) codes**
- **Low density parity check (LDPC) and repeat-accumulate codes**

Two Milestones in the History of Channel Coding

- **C.E. Shannon, A Mathematical Theory of Communication,** *The Bell System Technical Journal*, vol. 27, pp. 379-423, 623-656, July, October, 1948.
- **R.W. Hamming, Error-Detecting and Error-Correcting Codes,** *The Bell System Technical Journal*, vol. 29, pp. 147-160, 1950.

Timeline



Codes Used in Deep-Space Communications

Year	Mission	Code
1968	Pioneer 9	$R = 1/2$ convolutional, memory 20, sequential decoder
1969	Mariner '69	(32,6) Reed-Muller, correlation decoder
1972	Pioneer 10 & 11	(2, 1, 32) convolutional, memory 31, sequential decoder
1977	Voyager 1 & 2	(2, 1, 7) convolutional, Viterbi decoder
1987	CCSDS* Telemetry Standard	concatenation, (255, 223) Reed Solomon and (2, 1, 7) convolutional
1989	Galileo	concatenation, (255, 223) Reed Solomon and (4, 1, 15) convolutional
1999	CCSDS Telemetry Recommendation	adds Turbo code specification

* CCSDS: Consultative Committee for Space Data System, <http://www.ccsds.org>
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