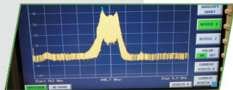


# Radio Engineering

## *Lecture 2: Antennas and Propagation*

Florian Kaltenberger



- History of wireless communications
- Types of services and their requirements
- Technical challenges
  - Multipath propagation
  - Spectrum limitations
  - Limited Energy
  - User Mobility
- Link budgets
  - Decibel notation
  - Noise modeling
  - Antenna gain and EIRP
  - Path loss and fading margin
- Interference limited networks

Consider a mobile radio system with the following characteristics:

- Carrier frequency  $f_c = 950\text{MHz}$ ,
- Bandwidth  $B = 200\text{kHz}$ ,
- Operating temperature  $T = 300\text{ K}$ ,
- Transmit power:  $P = 30\text{ W}$ ,
- Antenna gains  $G_{\text{TX}} = 10\text{ dB}$  and  $G_{\text{RX}} = 0\text{ dB}$ ,
- Cable losses at TX  $L_{\text{TX}} = 5\text{ dB}$ ,
- Receiver noise figure  $F = 7\text{ dB}$ .
- The required operating SNR is 15 dB

**Compute**

- **the EIRP**
- **the RX sensitivity**

Assume the following propagation characteristics

- Path loss model<sup>1</sup>

$$PL(d) = \left( \frac{4\pi d}{\lambda} \right)^2 \quad 0 \leq d \leq d_{\text{break}}$$

$$PL(d) = PL(d_{\text{break}}) \left( \frac{d}{d_{\text{break}}} \right)^n \quad d > d_{\text{break}}$$

with  $d_{\text{break}} = 100\text{m}$ .

- the fading margin is 12 dB.

**What distance can be covered in for  $n = 4$ ?**

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<sup>1</sup>Recall that  $P_{\text{RX}}(d) = \frac{P_{\text{TX}}}{PL(d)}$  or  $P_{\text{RX}}(d)|_{\text{dB}} = P_{\text{TX}}|_{\text{dB}} - PL(d)|_{\text{dB}}$

- ④ Antennas and Propagation
  - Maxwell equations
  - Plane waves
  - Linear and circular polarization
  - Free space loss
  - Reflection and transmission
  - Diffraction
  - Scattering

- Maxwell's Equations fully describe the nature of electromagnetic waves
- They describe the relationship between variations of the electric field **E** and the vector magnetic field **H** in time and space within a medium
- All radio propagation mechanisms could be described, but in practice much too complicated

## Theorem (Maxwell's Equations)

- *An electric field is produced by a time-varying magnetic field*
- *A magnetic field is produced by a time-varying electric field or by a current*
- *Electric field lines may either start and end on charges, or are continuous*
- *Magnetic field lines are continuous*

- Many solutions to Maxwell's Equations exist
- They can all be described as a sum of plane waves

$$\mathbf{E} = E_0 \cos(\omega t - kz) \mathbf{x}$$

$$\mathbf{H} = H_0 \cos(\omega t - kz) \mathbf{y}$$

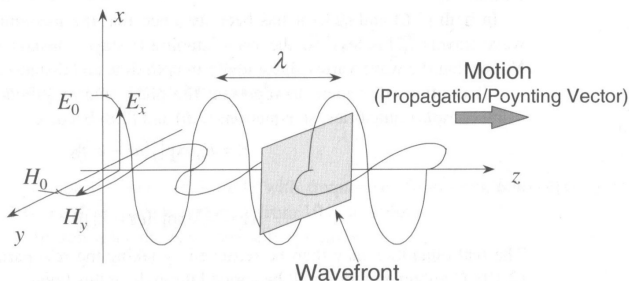


Figure 2.1: A plane wave

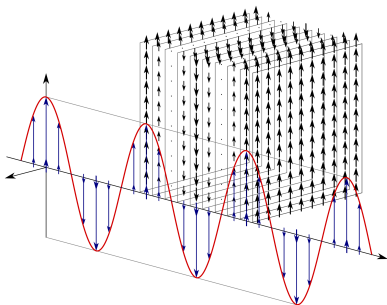


- Alignment of the electric field vector relative to Poynting vector defines the polarization

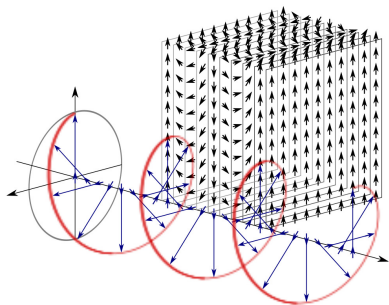
$$\mathbf{E} = E_x \mathbf{x} + E_y \mathbf{y}$$

- *Linearly polarized waves*: Electric field is parallel to x or y-axis
  - *vertical polarization*:  $E_x = 0, E_y = E_0/\sqrt{2}$
  - *horizontal polarization*:  $E_x = E_0/\sqrt{2}, E_y = 0$
- *Circularly polarized waves*: Horizontal and vertical polarization combined with a  $90^\circ$  phase difference
  - *right-hand circular polarization*:  $E_x = -E_0/\sqrt{2}, E_y = jE_0/\sqrt{2}$
  - *left-hand circular polarization*:  $E_x = E_0/\sqrt{2}, E_y = jE_0/\sqrt{2}$

# Linear and circular polarized plane waves (2)



Linearly polarized plane wave



Circularly polarized plane wave

# Chapter 4

## Propagation effects

# Why channel modelling?

- The performance of a radio system is ultimately determined by the radio channel
- The channel models basis for
  - system design
  - algorithm design
  - antenna design etc.
- Trend towards more interaction system-channel
  - MIMO
  - UWB

Without reliable channel models, it is hard to design radio systems that work well in *real* environments.

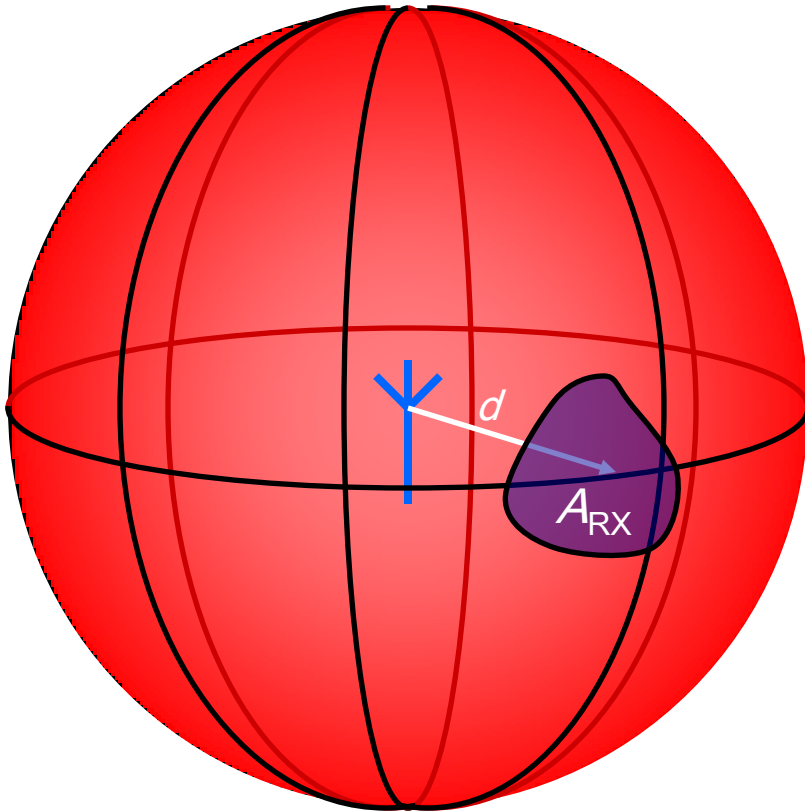
# THE RADIO CHANNEL

## It is more than just a loss

- Some examples:
  - behavior in time/place?
  - behavior in frequency?
  - directional properties?
  - bandwidth dependency?
  - behavior in delay?

# BASIC PROPAGATION MECHANISMS

# Free-space loss



If we assume RX antenna to be isotropic:

$$P_{RX} = \left( \frac{\lambda}{4\pi d} \right)^2 P_{TX}$$

Attenuation between two isotropic antennas in free space is (free-space loss):

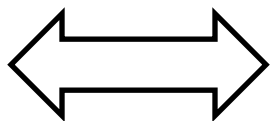
$$L_{free}(d) = \left( \frac{4\pi d}{\lambda} \right)^2$$

# Free-space loss

## Friis' law

Received power, with antenna gains  $G_{TX}$  and  $G_{RX}$ :

$$P_{RX}(d) = \frac{G_{RX} G_{TX}}{L_{free}(d)} P_{TX} = P_{TX} \left( \frac{\lambda}{4\pi d} \right)^2 G_{RX} G_{TX}$$



Valid in the far field only

$$\begin{aligned} P_{RX|dB}(d) &= P_{TX|dB} + G_{TX|dB} - L_{free|dB}(d) + G_{RX|dB} \\ &= P_{TX|dB} + G_{TX|dB} - 10 \log_{10} \left( \frac{4\pi d}{\lambda} \right)^2 + G_{RX|dB} \end{aligned}$$



# Free-space loss

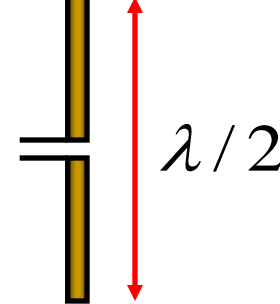
## What is far field?

Rayleigh distance:

$$d_R = \frac{2L_a^2}{\lambda}$$

where  $L_a$  is the largest dimension of the antenna.

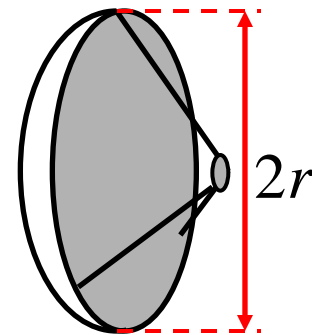
$\lambda/2$ -dipole



$$L_a = \lambda/2$$

$$d_R = \lambda/2$$

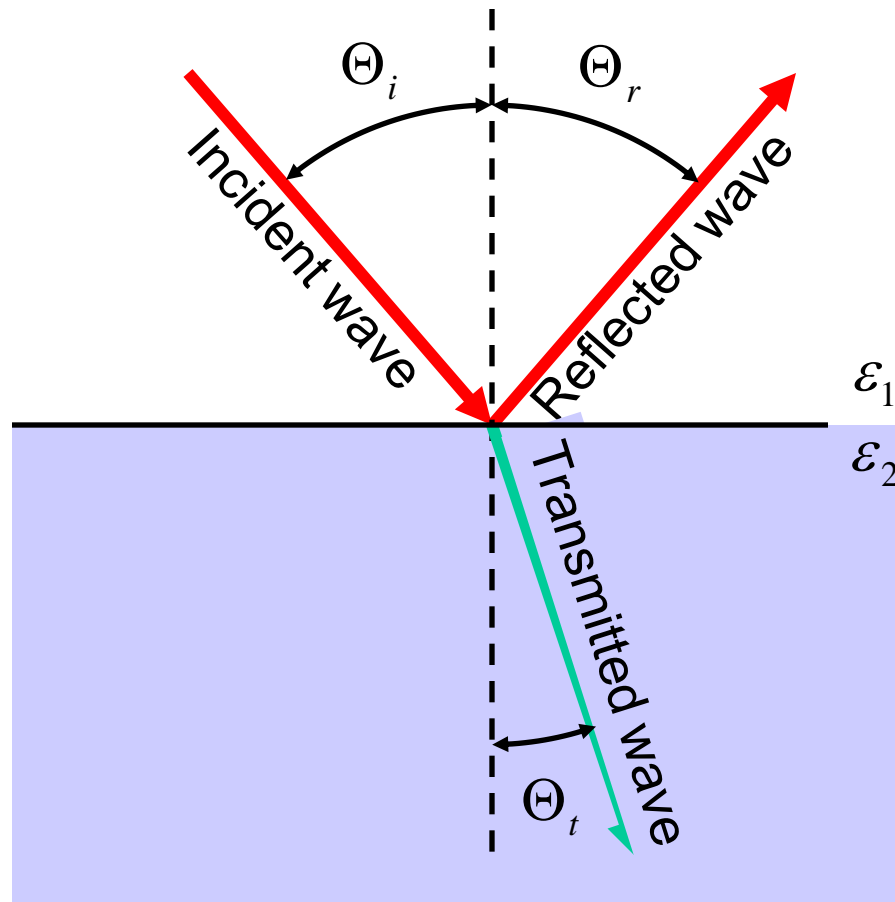
Parabolic



$$L_a = 2r$$

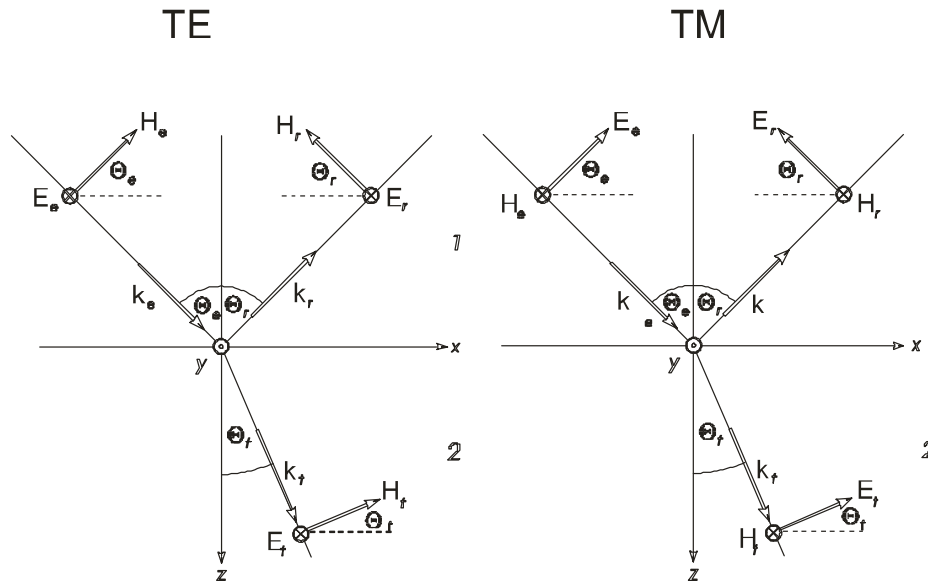
$$d_R = \frac{8r^2}{\lambda}$$

# Reflection and transmission (1)



# Reflection and transmission (2)

- Snell's law
  - Reflection angle  $\Theta_r = \Theta_e$
  - Transmission angle  $\frac{\sin \Theta_t}{\sin \Theta_e} = \frac{\sqrt{\epsilon_1}}{\sqrt{\epsilon_2}}$
- Transmission and reflection: distinguish TE and TM waves



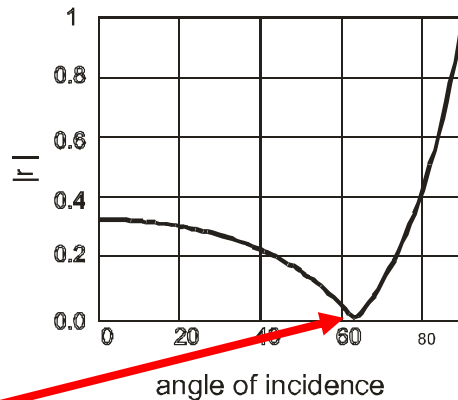
# Reflection and transmission (3)

$$\rho_{\text{TM}} = \frac{\sqrt{\epsilon_2} \cos \Theta_e - \sqrt{\epsilon_1} \cos(\Theta_t)}{\sqrt{\epsilon_2} \cos \Theta_e + \sqrt{\epsilon_1} \cos(\Theta_t)}$$

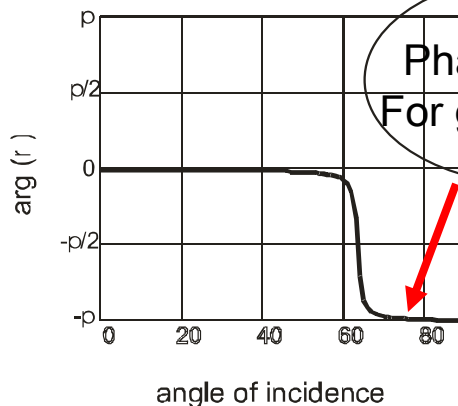
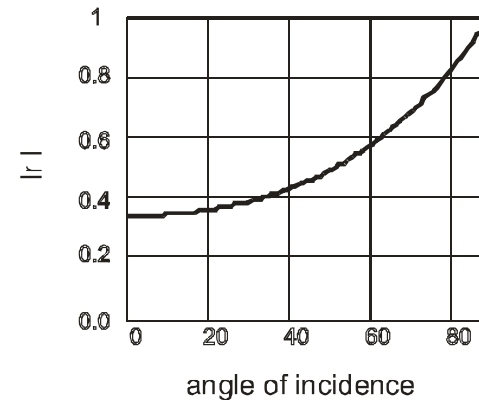
TM-waves

$$\rho_{\text{TE}} = \frac{\sqrt{\epsilon_1} \cos(\Theta_e) - \sqrt{\epsilon_2} \cos(\Theta_t)}{\sqrt{\epsilon_1} \cos(\Theta_e) + \sqrt{\epsilon_2} \cos(\Theta_t)}$$

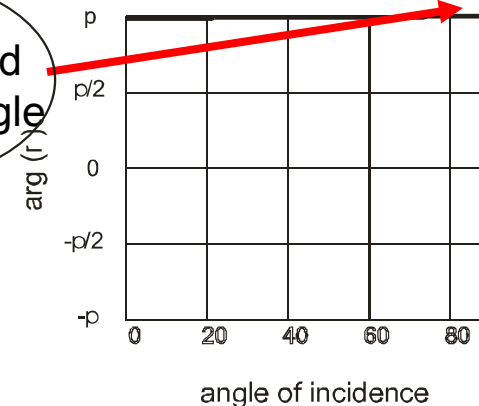
TE-waves



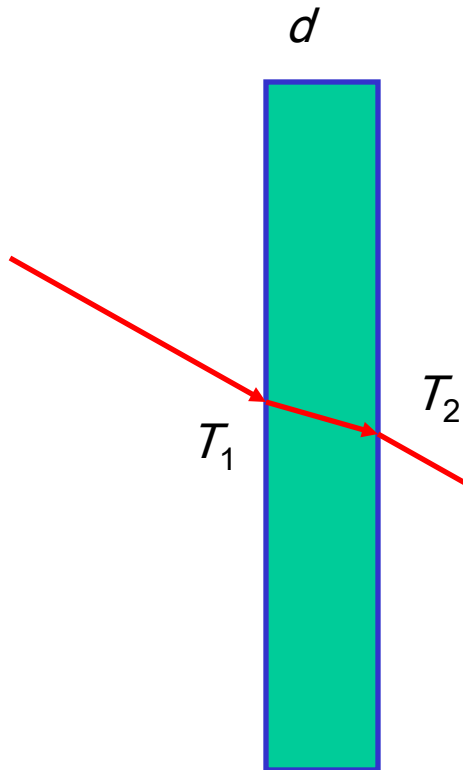
Brewster angle



Phase inverted  
For grazing angle



# Transmission through a wall – layered structures



Total transmission coefficient

$$T = \frac{T_1 T_2 e^{-j\alpha}}{1 + R_1 R_2 e^{-2j\alpha}}$$

total reflection coefficient

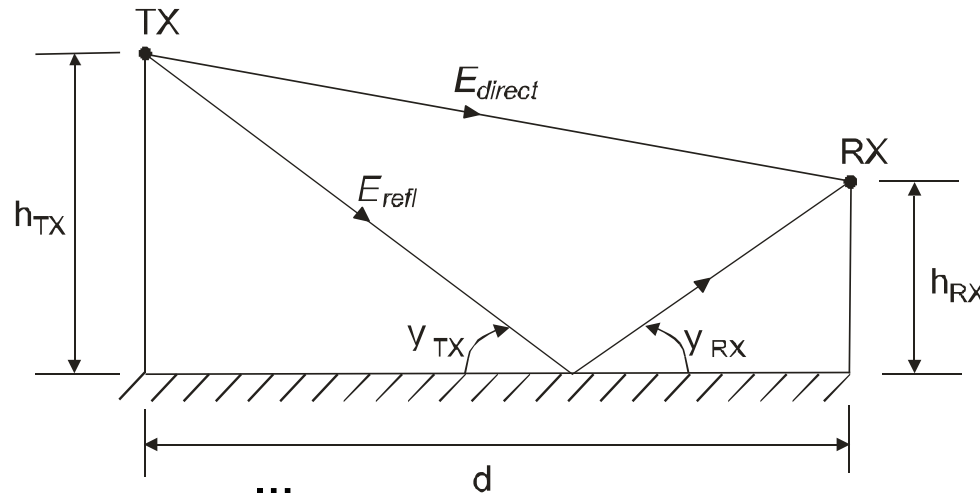
$$\rho = \frac{\rho_1 + \rho_2 e^{-j2\alpha}}{1 + \rho_1 \rho_2 e^{-2j\alpha}}$$

with the electrical length in the wall

$$\alpha = \frac{2\pi}{\lambda} \sqrt{\epsilon_1} d_{\text{layer}} \cos(\Theta_t)$$

# The d<sup>-4</sup> law (1)

- For the following scenario



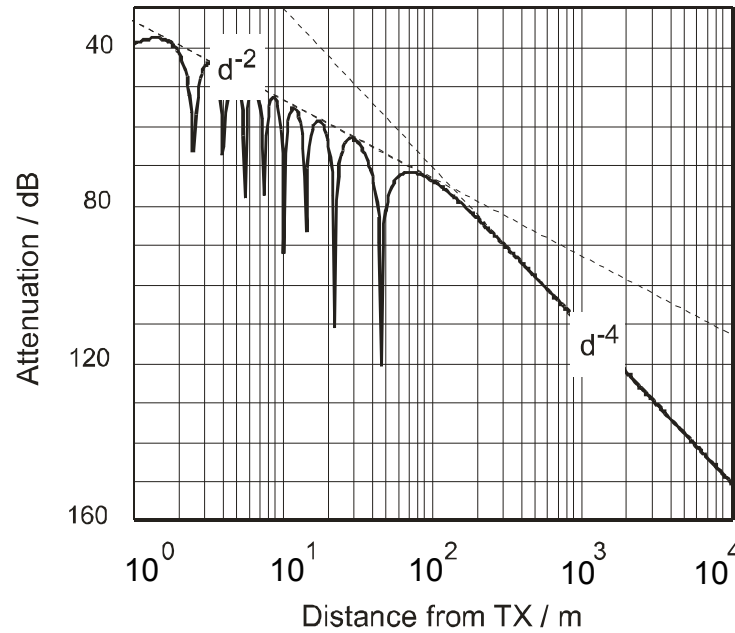
- the power goes like

$$P_{RX}(d) \approx P_{TX} G_{TX} G_{RX} \left( \frac{h_{TX} h_{RX}}{d^2} \right)^2.$$

- for distances greater than

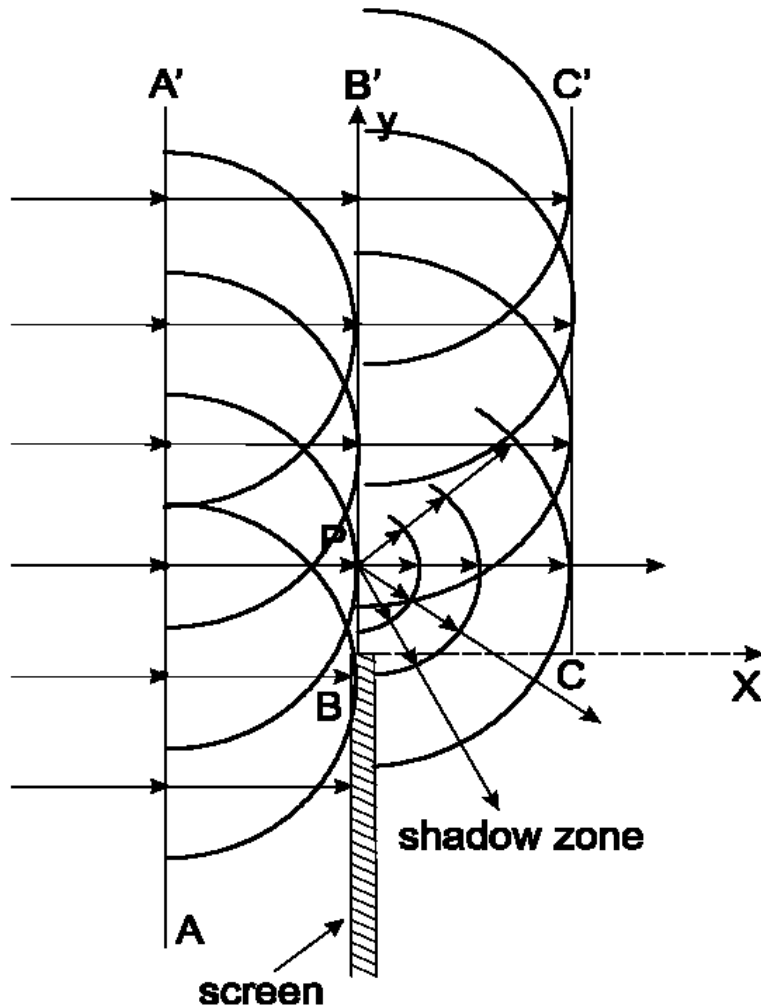
$$d_{break} \gtrsim 4h_{TX}h_{RX}/\lambda$$

# The $d^{-4}$ law (2)



$h_{tx} = 5\text{m}$   
 $h_{rx} = 1.5\text{m}$   
 $f_c = 900\text{MHz}$

# Diffraction, Huygen's principle



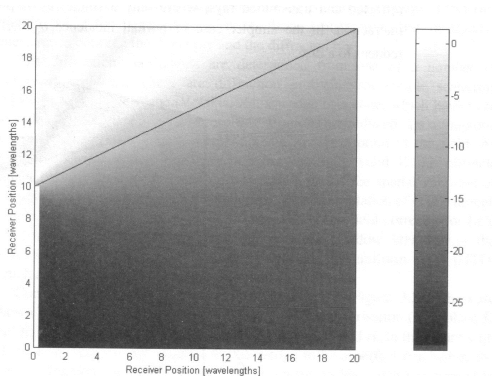
- \* Semi-infinite screen
- \* Each point of the wavefront can be considered as a source of a spherical wave
- \* Screen eliminates parts of the waves
- \* Constructive and destructive interference



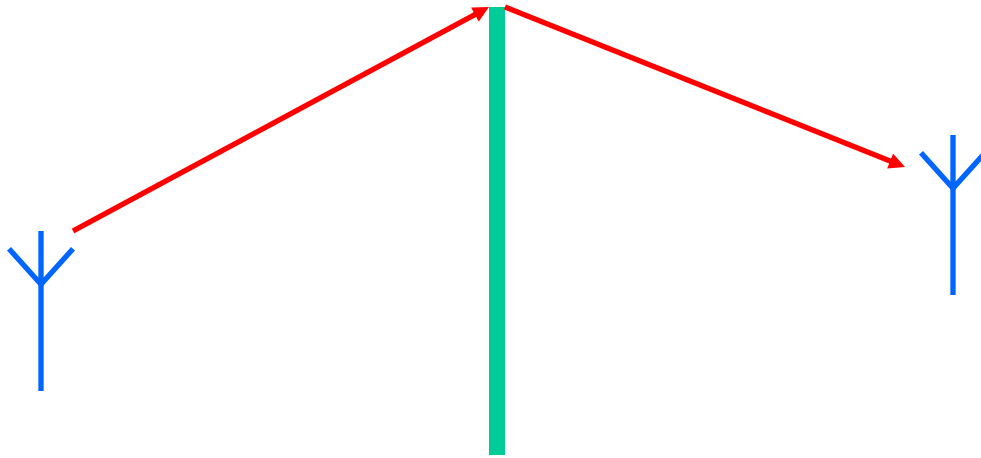
- The electric field (for  $x \geq 0$ ) can be expressed as

$$E_{total} = \exp(-jk_0 x) F(\nu_F)$$

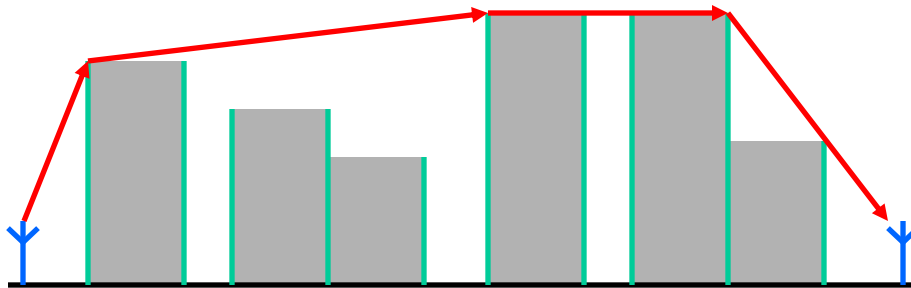
where  $\nu_F = -2y/\sqrt{\lambda x}$  and  $F(\nu_F)$  is the Fresnel integral



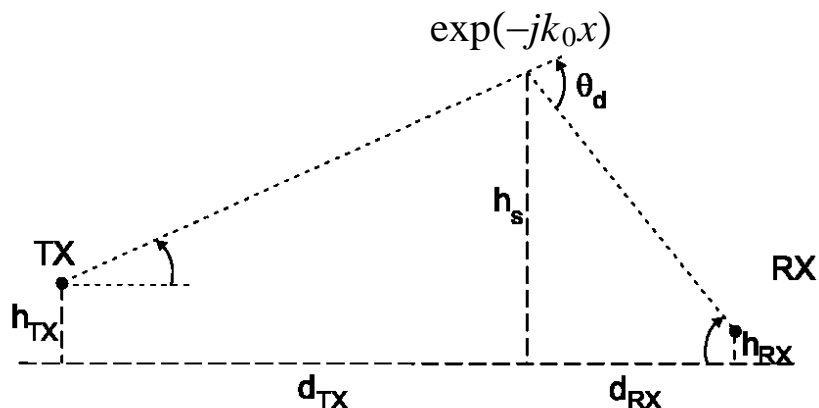
# Diffraction



- Single or multiple edges
- makes it possible to go behind corners
- less pronounced when the wavelength is small compared to objects



# Diffraction coefficient



Total field

$$E_{\text{total}} = \exp(-jk_0 x) \left( \frac{1}{2} - \frac{\exp(-j\pi/4)}{\sqrt{2}} F(v_F) \right)$$

Fresnel integral

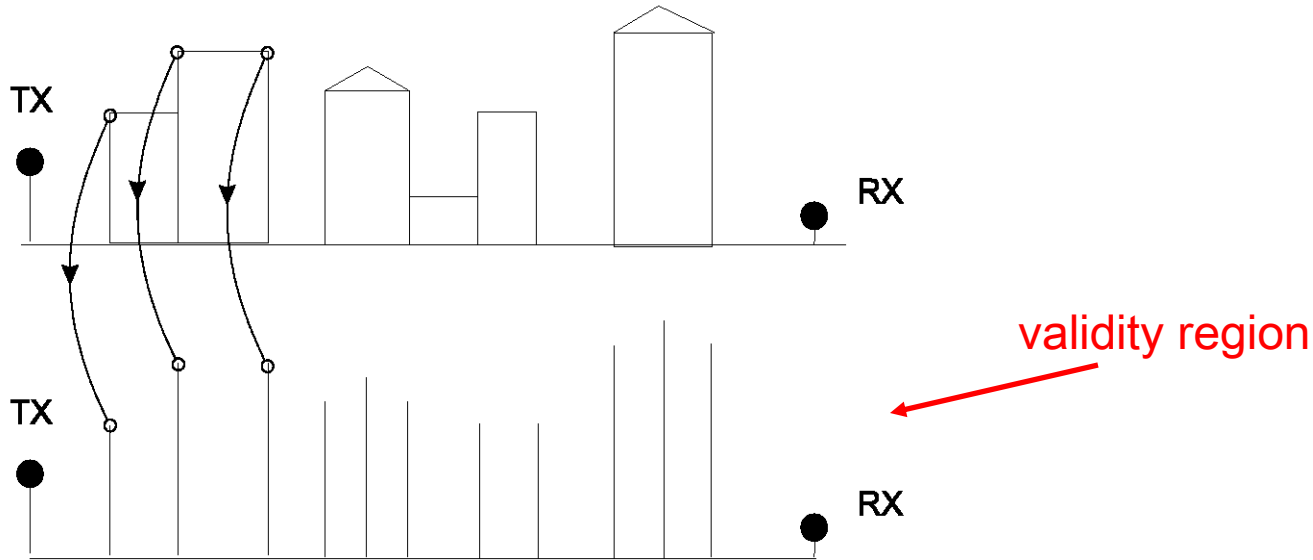
The Fresnel integral is defined

$$F(v_F) = \int_0^{v_F} \exp\left(-j\pi \frac{t^2}{2}\right) dt.$$

with the Fresnel parameter

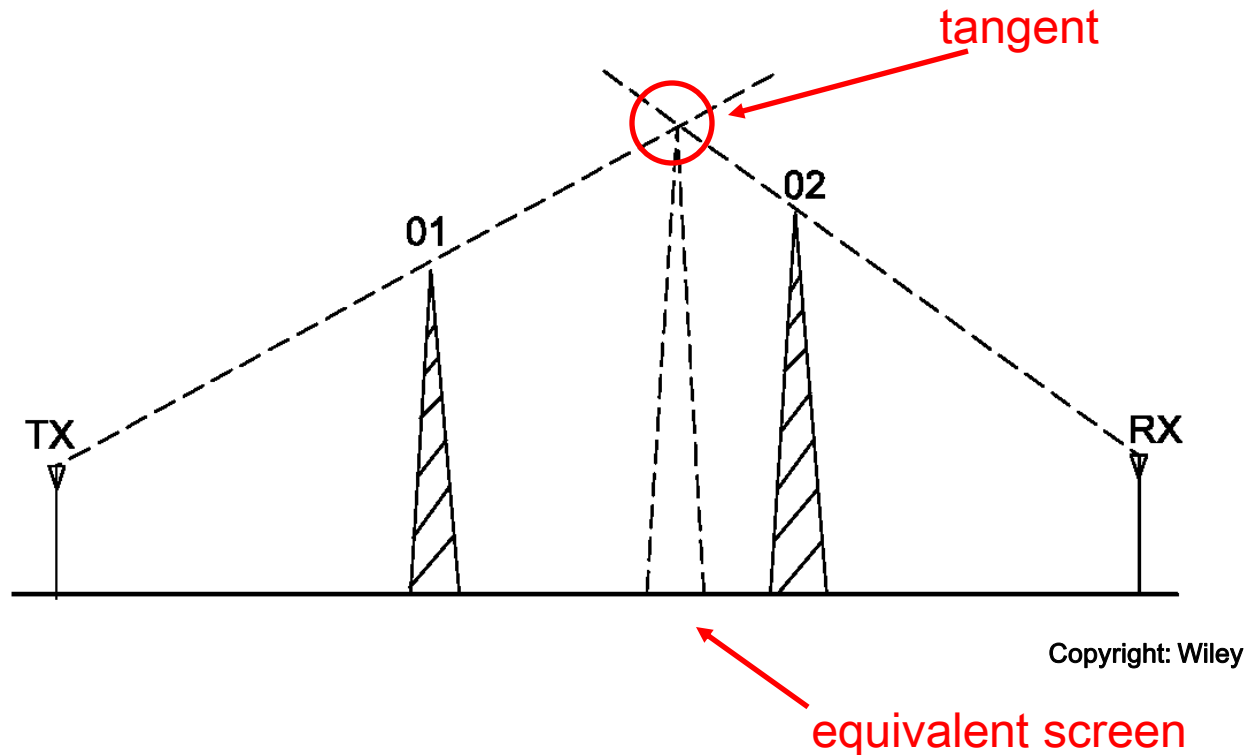
$$v_F = \alpha_k \sqrt{\frac{2d_1 d_2}{\lambda(d_1 + d_2)}}$$

# Diffraction in real environments



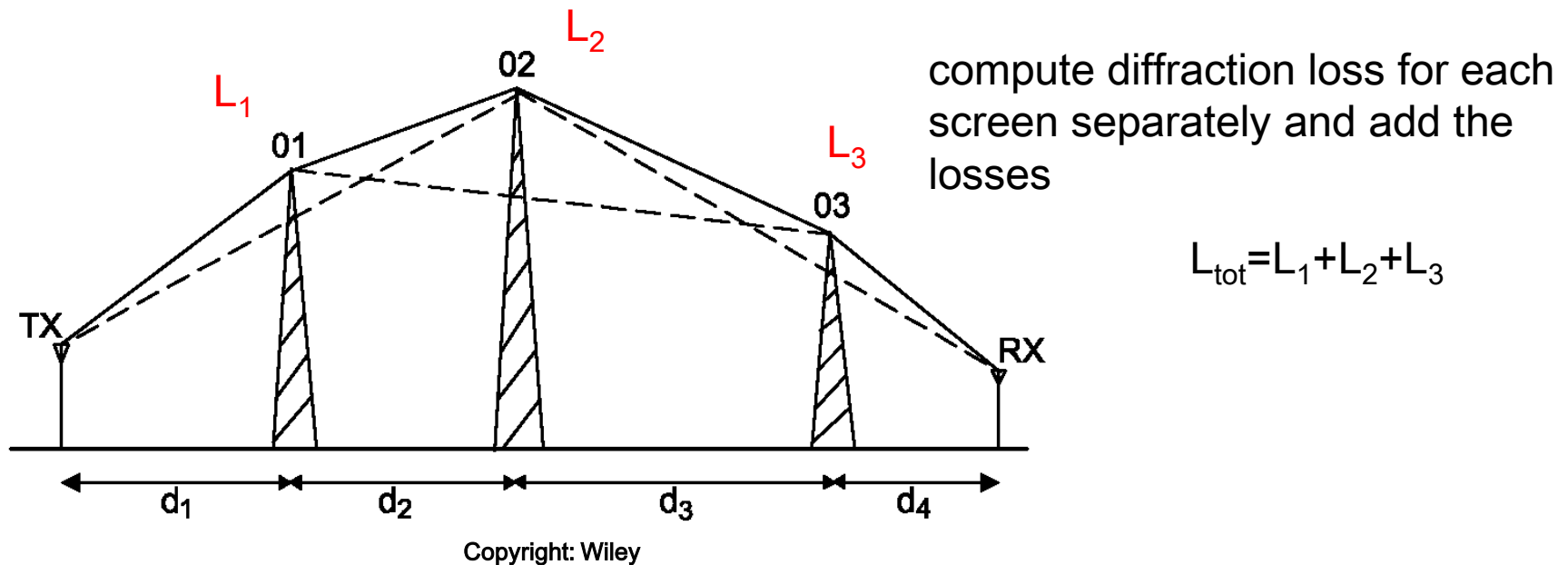
Approximation of multiple buildings by a series of screens

# Diffraction – Bullington's method

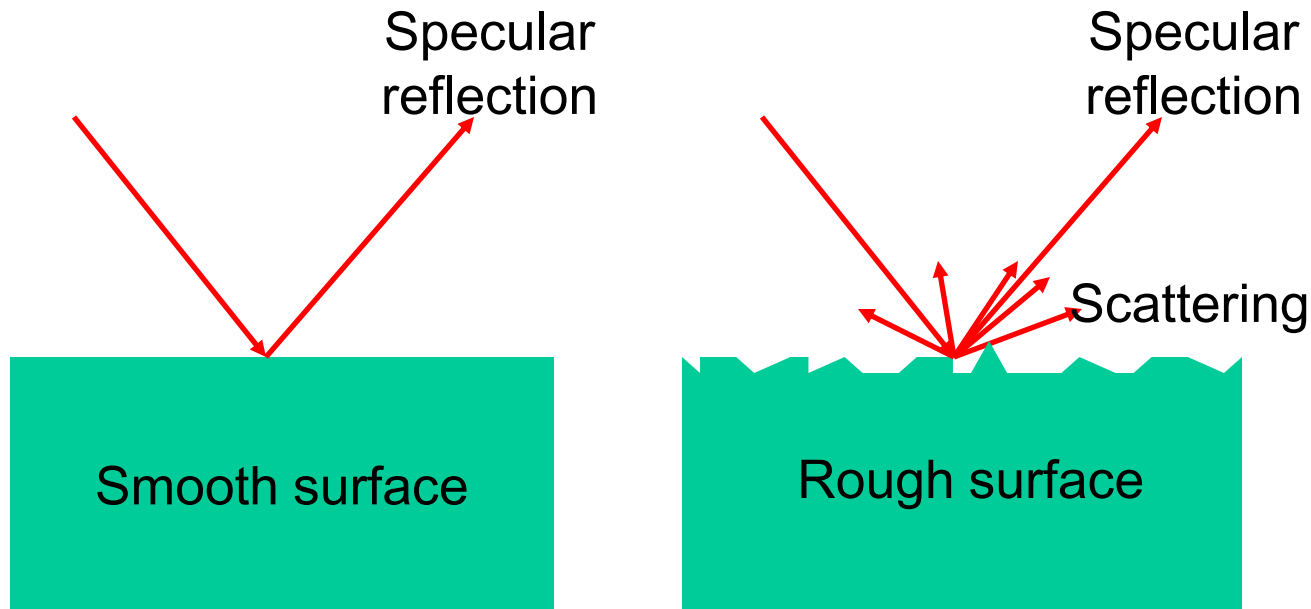


$$E_{\text{total}} = \exp(-jk_0x) \left( \frac{1}{2} - \frac{\exp(-j\pi/4)}{\sqrt{2}} F(v_F) \right) \quad v_F = \alpha_k \sqrt{\frac{2d_1d_2}{\lambda(d_1+d_2)}}$$

# Diffraction – Epstein-Petersen Method

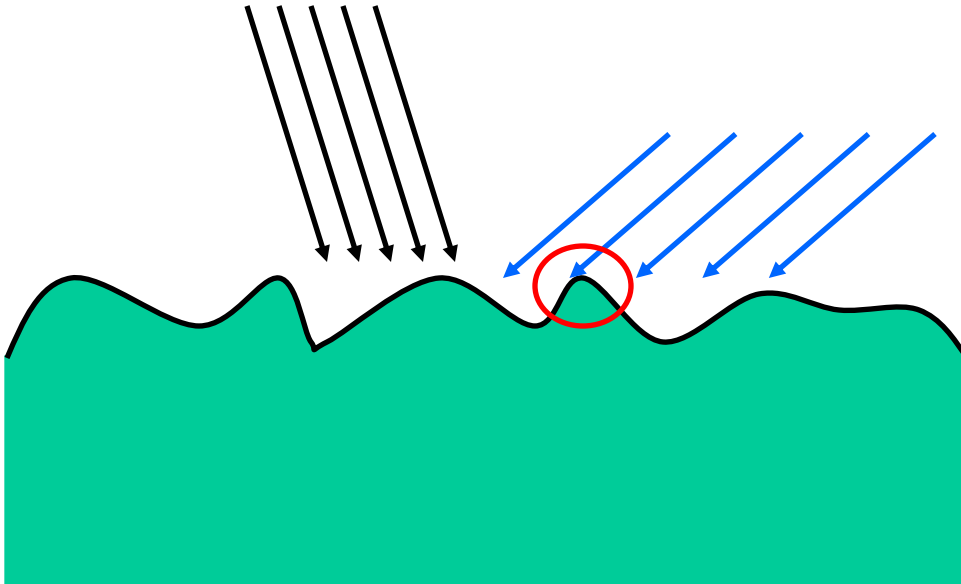


# Scattering



A surface is smooth, when the average height is smaller than the wavelength

# Kirchhoff theory – scattering by rough surfaces



for Gaussian surface distribution

$$\rho_{\text{rough}} = \rho_{\text{smooth}} \exp \left[ -2 \left( k_0 \sigma_h \sin \psi \right)^2 \right]$$

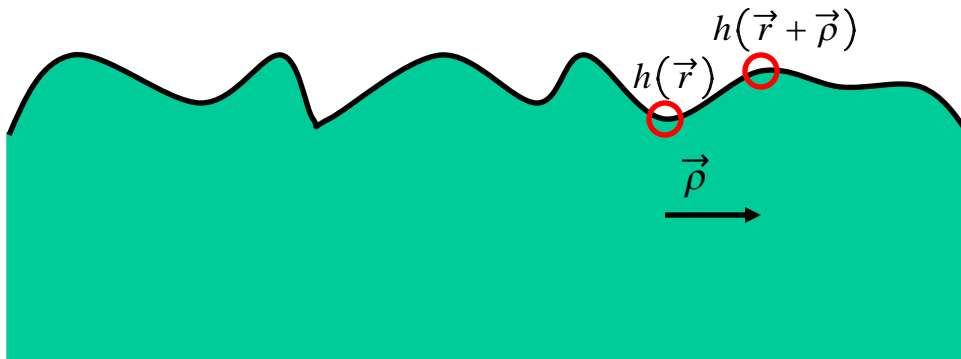
angle of incidence

standard deviation of height



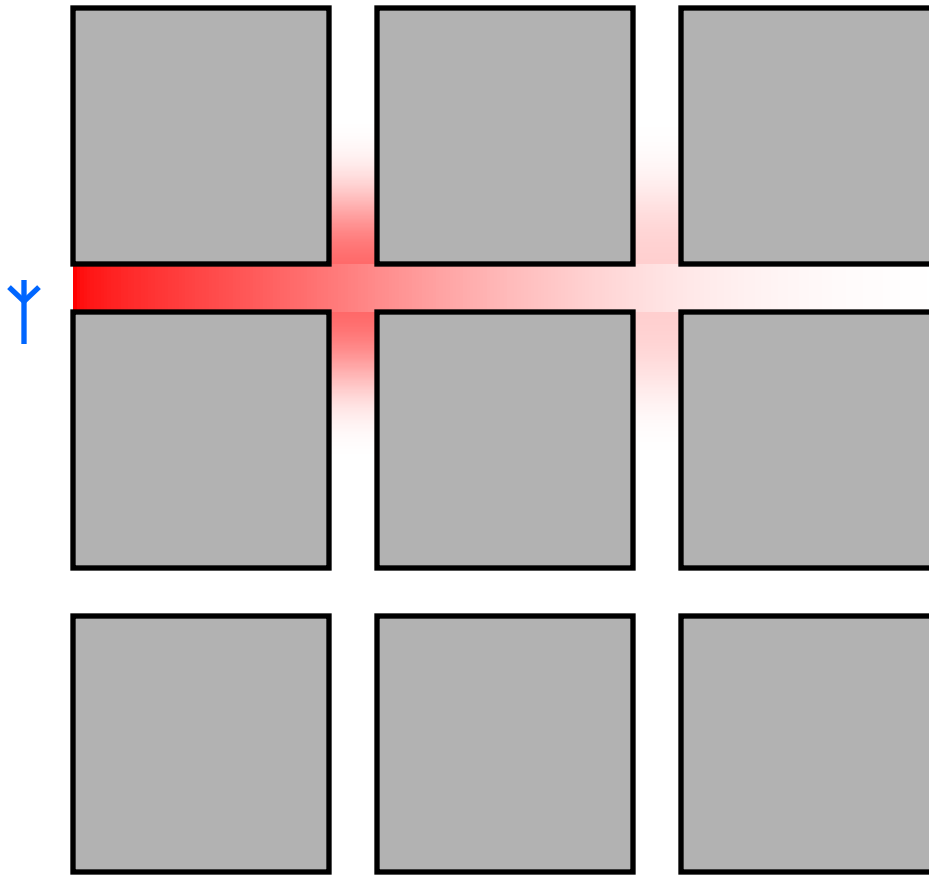
# Perturbation theory – scattering by rough surfaces

$$\sigma_h^2 W(\vec{\rho}) = E_{\vec{r}} \{ h(\vec{r}) h(\vec{r} + \vec{\rho}) \}$$



More accurate than Krichhoff theory, especially for large angles of incidence and “rougher” surfaces

# Waveguiding



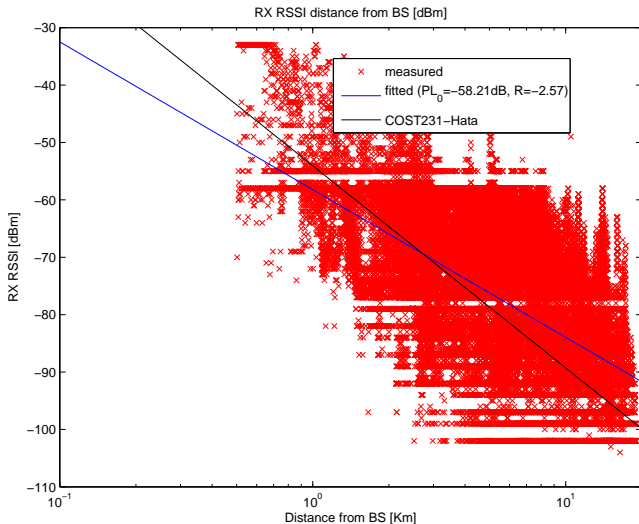
Waveguiding effects  
often result in lower  
propagation exponents

$$n=1.5-5$$

This means lower path  
loss along certain  
street corridors

- Analytical path loss models: free space,  $d^{-4}$  law
- They require exact knowledge of environment, and are not always exact
- Alternative: empirical models based on measurements

# Empirical path loss models: Example



- Plot received signal level  $P$  vs. distance  $d$  on a log-log scale
- Use linear regression to fit a linear function (use  $P_0 = PL(d_{ref})$  as reference point)

$$r_i = P_0|_{\text{dB}} + n * \log(d_i/d_{ref}), \quad i = 0, \dots, N - 1$$

- “Standardized” empirical models
  - Okumura-Hata
  - Walfish-Ikegami
  - Motley-Keenan (indoor)