



# Statistical Signal Processing

## *Lecture 4*

chapter 1: parameter estimation

deterministic parameters

- some optimality properties
- Maximum Likelihood estimation
- Fischer Information Matrix
- Cramer-Rao lower bound on the MSE



## Deterministic Parameter Estimation

Two points of view:

- the parameters  $\theta$  are unknown deterministic quantities
- the parameters  $\theta$  are stochastic, but their prior distribution  $f(\theta)$  is unknown

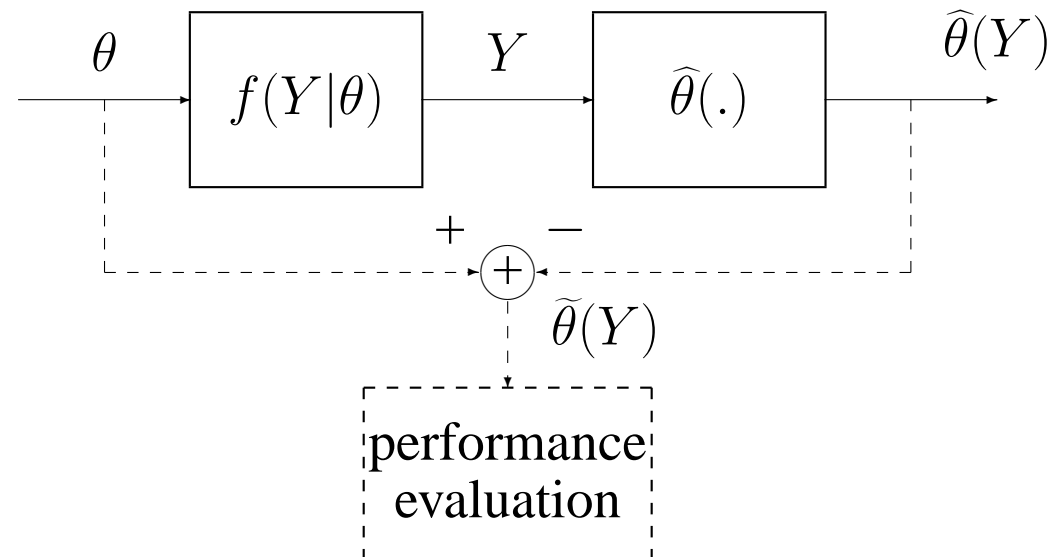
The only stochastic description available is the conditional density  $f(Y|\theta)$  describing the stochastic relation between the unknown parameters  $\theta$  and the observed measurements  $Y$ .

- since  $\theta$  is not necessarily a random vector but just a set of parameters on which the distribution of  $Y$  depends, we often find the notations

$$f(Y|\theta) = f(Y;\theta) = f_{\theta}(Y)$$

but we shall continue to use  $f(Y|\theta)$

- expectation now means  $E = E_{Y|\theta}$





## Deterministic Parameter Estimation (2)

- an estimator  $\hat{\theta}(Y)$  of  $\theta$  is again a function of  $Y$  (a statistic), with estimation error  $\tilde{\theta} = \theta - \hat{\theta}(Y)$
- to evaluate the quality of an estimator, we shall again introduce the *risk* function MSE as the average value of the SE *cost* function

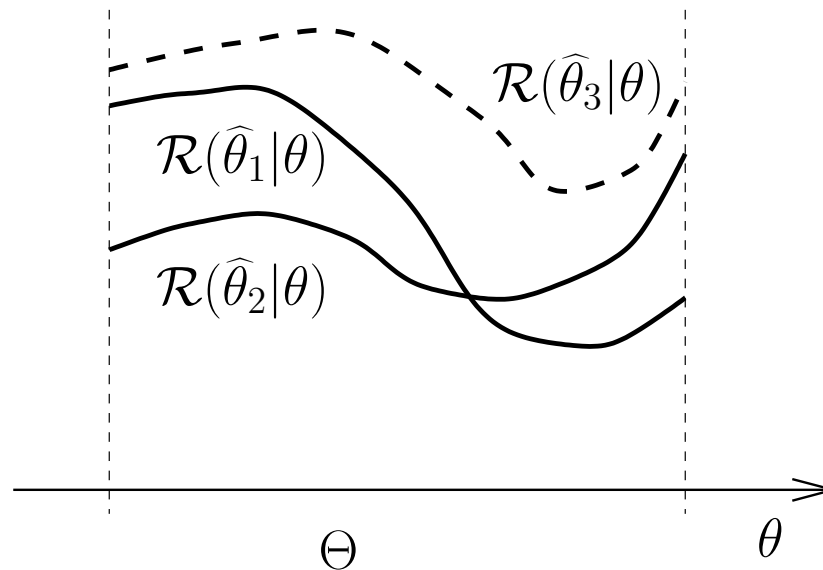
$$\text{MSE} = \mathcal{R}(\hat{\theta}(\cdot)|\theta) = E_{Y|\theta} \|\tilde{\theta}\|^2 = \int f(Y|\theta) \|\theta - \hat{\theta}(Y)\|^2 dY$$

the MSE is a function of  $\theta$  in general

- minimization of the risk function leads to  $\hat{\theta} = \theta$  (and  $\mathcal{R} = 0$ ): not an acceptable strategy since the resulting  $\hat{\theta}$  depends on the unknown  $\theta$
- ideally, would like  $\hat{\theta}(\cdot)$  such that  $\mathcal{R}(\hat{\theta}(\cdot)|\theta)$  is minimized  $\forall \theta \in \Theta$  : impossible!  
Consider  $\hat{\theta}(Y) = \theta_0 \in \Theta$  : ignores the data  $Y$  but  $\mathcal{R}(\hat{\theta}(\cdot)|\theta_0) = 0$
- we shall still evaluate the performance via the MSE, but in the deterministic case, we shall not be able to derive estimators by minimizing the MSE.

## Deterministic Parameter Estimation (3)

- given two estimators  $\hat{\theta}_1(Y)$  and  $\hat{\theta}_2(Y)$ , one is usually not uniformly better than the other one (see figure)
- a uniformly minimum risk estimator does not exist in general
- consider some other desirable properties





## Some Optimality Properties

- estimator *bias* : average deviation from the true parameter

$$b_{\hat{\theta}}(\theta) = -E_{Y|\theta}\tilde{\theta} = E_{Y|\theta}(\hat{\theta}(Y) - \theta) = E_{Y|\theta}\hat{\theta}(Y) - \theta$$

*unbiased* estimator:  $b_{\hat{\theta}}(\theta) = 0, \forall \theta \in \Theta$

Unbiasedness is a weak property: estimator can be correct on the average, but with large deviations. Good estimators exist that are biased.

- Example: mean of Gaussian i.i.d. variables

i.i.d.  $y_i \sim \mathcal{N}(\theta, 1), i = 1, \dots, n$

Consider  $\hat{\theta}(Y) = \bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$ , the sample mean.

$$E_{Y|\theta}\hat{\theta} = E_{Y|\theta}\bar{y} = E_{Y|\theta}\frac{1}{n} \sum_{i=1}^n y_i = \frac{1}{n} \sum_{i=1}^n E_{Y|\theta}y_i = \frac{1}{n} \sum_{i=1}^n \theta = \frac{n\theta}{n} = \theta : \text{unbiased!}$$

- $\hat{\theta}(\cdot)$  is *inadmissible* if another estimator  $\hat{\theta}'(\cdot)$  has uniformly lower risk:

$$\forall \theta \in \Theta : \mathcal{R}(\hat{\theta}'|\theta) \leq \mathcal{R}(\hat{\theta}|\theta), \quad \exists \theta_0 \in \Theta : \mathcal{R}(\hat{\theta}'|\theta_0) < \mathcal{R}(\hat{\theta}|\theta_0)$$

$\hat{\theta}$  is *admissible* if no such  $\hat{\theta}'$  exists. Example:  $\hat{\theta}_3$  in figure above.



## Some Optimality Properties (2)

- $\text{MSE} = E_{Y|\theta} \|\tilde{\theta}\|^2 = E_{Y|\theta} \tilde{\theta}^T \tilde{\theta} = \text{tr} \{ E_{Y|\theta} \tilde{\theta} \tilde{\theta}^T \} = \text{tr} \{ R_{\tilde{\theta}\tilde{\theta}} \},$

$$R_{\tilde{\theta}\tilde{\theta}} = E_{Y|\theta} \tilde{\theta} \tilde{\theta}^T = \text{estimation error correlation matrix}$$

$$\begin{aligned} R_{\tilde{\theta}\tilde{\theta}} &= E_{Y|\theta} (\hat{\theta} - \theta) (\hat{\theta} - \theta)^T = E_{Y|\theta} [\hat{\theta} (-E_{Y|\theta} \hat{\theta} + E_{Y|\theta} \hat{\theta}) - \theta] [\hat{\theta} (-E_{Y|\theta} \hat{\theta} + E_{Y|\theta} \hat{\theta}) - \theta]^T \\ &= E_{Y|\theta} (\hat{\theta} - E_{Y|\theta} \hat{\theta}) (\hat{\theta} - E_{Y|\theta} \hat{\theta})^T + (E_{Y|\theta} \hat{\theta} - \theta) (E_{Y|\theta} \hat{\theta} - \theta)^T \\ &= C_{\hat{\theta}\hat{\theta}} + b_{\hat{\theta}}(\theta) b_{\hat{\theta}}^T(\theta) = C_{\tilde{\theta}\tilde{\theta}} + (E_{Y|\theta} \tilde{\theta}) (E_{Y|\theta} \tilde{\theta})^T \end{aligned}$$

where we used:  $C_{\hat{\theta}\hat{\theta}} = C_{\tilde{\theta}\tilde{\theta}}$



## Some Optimality Properties (3)

- $\hat{\theta}(Y)$  is said to be *minimax* if it satisfies

$$\sup_{\theta \in \Theta} \mathcal{R}(\hat{\theta}|\theta) = \inf_{\hat{\theta}'} \sup_{\theta \in \Theta} \mathcal{R}(\hat{\theta}'|\theta)$$

( $\inf \approx \min$ ,  $\sup \approx \max$ ).

A minimax estimator minimizes the maximum risk over  $\Theta$ .

A minimax  $\hat{\theta}$  is difficult to obtain in general.

Uniformly minimum risk estimators may be found if we restrict the class of estimators.

- $\hat{\theta}$  is a *uniformly minimum variance unbiased estimator* (UMVUE) if it is unbiased and if for any other unbiased estimator  $\hat{\theta}'$  :  $R_{\hat{\theta}\hat{\theta}} \leq R_{\hat{\theta}'\hat{\theta}'}$ ,  $\forall \theta \in \Theta$ ,  
or

$$E_{Y|\theta}(\hat{\theta}(Y) - \theta)(\hat{\theta}(Y) - \theta)^T \leq E_{Y|\theta}(\hat{\theta}'(Y) - \theta)(\hat{\theta}'(Y) - \theta)^T$$

note: variance =  $\text{tr}\{\text{covariance matrix}\}$ ,  $\text{MSE}_{\hat{\theta}} = \text{tr}\{R_{\hat{\theta}\hat{\theta}}\}$

- UMVUE are highly desirable but they may not exist or be difficult to compute. They can be computed if a *complete sufficient statistic* can be found.



## Maximum Likelihood Estimation

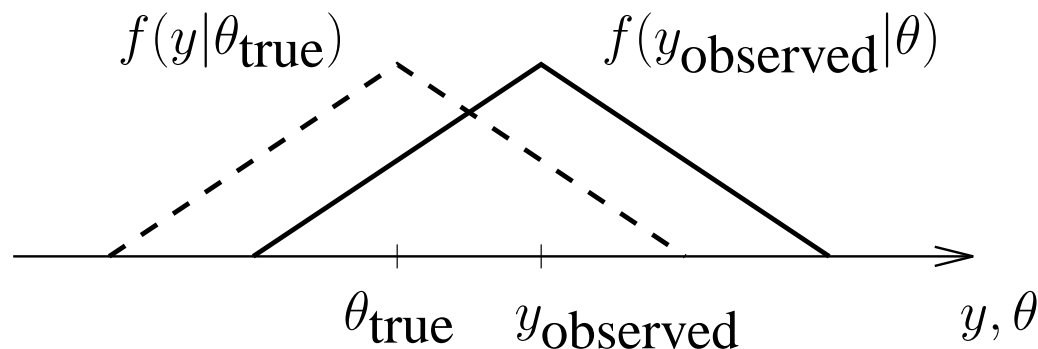
- the maximum likelihood (ML) estimation philosophy is to choose that value of the parameters that renders the observations most likely:

$$\hat{\theta}_{ML}(Y) = \arg \max_{\theta \in \Theta} f(Y|\theta)$$

example:

- $y = \theta + v$ ,  $f_v(v) = \begin{cases} 1 - |v| & , |v| \leq 1 \\ 0 & , |v| > 1 \end{cases}$   $f(y|\theta) = f_v(y - \theta)$

$$\hat{\theta}_{ML}(y) = y$$







## ML Estimation: Remarks

- $f(Y|\theta)$  is called the *likelihood function*. In order to emphasize the dependence on  $\theta$  and the fact that the observation  $Y$  is fixed, it is often denoted as

$$l(\theta; Y) = f(Y|\theta) \qquad L(\theta; Y) = \ln f(Y|\theta)$$

- since the logarithmic function is strictly monotone, the maximum point of  $f(Y|\theta)$  corresponds with the maximum point of  $\ln f(Y|\theta)$ , called the *log likelihood function*
- Often  $f(Y|\theta)$  satisfies certain regularity conditions so that  $\hat{\theta}_{ML}$  is a solution of

$$\frac{\partial}{\partial \theta} \ln f(Y|\theta) = 0 .$$

The conditions for a maximum (rather than another form of extremum) need to be verified of course.

- The ML estimator is given by the *global* maximum of  $f(Y|\theta)$ . If there are several local maxima, all of them need to be examined and compared to find the global maximum.



## ML Estimation: Remarks (2)

- Even if  $f(Y|\theta)$  satisfies regularity conditions, the maximum may occur at the boundary of the parameter space  $\Theta$  (which may not necessarily be  $(-\infty, \infty)$  for every  $\theta_i$ ). In that case, the maximum is not a local extremum.
- The ML estimator can be seen as a limiting case of the MAP estimator when the prior distribution  $f(\theta)$  becomes uninformative (uniform distribution). For those components  $\theta_i$  of  $\theta$  for which the support is unbounded, this means that  $\sigma_{\theta_i}^2 \rightarrow \infty$  (information  $\rightarrow 0$ ). Indeed

$$\begin{aligned}\hat{\theta}_{MAP}(Y) &= \arg \max_{\theta \in \Theta} f(\theta|Y) = \arg \max_{\theta \in \Theta} \frac{f(Y|\theta)f(\theta)}{f(Y)} \\ &= \arg \max_{\theta \in \Theta} f(Y|\theta)f(\theta) \stackrel{f(\theta)=c^t}{=} \arg \max_{\theta \in \Theta} f(Y|\theta) = \hat{\theta}_{ML}(Y)\end{aligned}$$

But in the deterministic case,  $\theta$  is fixed, whereas in the Bayesian case  $\theta$  is random, hence e.g. the MSE is different for both formulations

( $\text{MSE}_{MAP} = \int_{\Theta} \text{MSE}_{ML}(\theta) f(\theta) d\theta$ , averaged with prior distribution for  $\theta$ ).



## ML Estimation: Example 1

- Given:  $y_i = \mu + \sigma v_i$ ,  $v_i \sim \mathcal{N}(0, 1)$  i.i.d. or  $y_i \sim \mathcal{N}(\mu, \sigma^2)$  i.i.d.  $\theta = \begin{bmatrix} \mu \\ \sigma^2 \end{bmatrix}$

$$Y = \mu \mathbf{1} + \sigma V, \quad V \sim \mathcal{N}(0, I_n)$$

- Q:  $\hat{\theta}_1 = \hat{\mu}_{ML}$ ,  $\hat{\theta}_2 = \hat{\sigma}_{ML}^2$

- A:

$$f(Y|\mu, \sigma^2) = \prod_{i=1}^n f(y_i|\mu, \sigma^2) = \prod_{i=1}^n \frac{\exp[-\frac{(y_i - \mu)^2}{2\sigma^2}]}{\sqrt{2\pi\sigma^2}} = (2\pi)^{-\frac{n}{2}} (\sigma^2)^{-\frac{n}{2}} \exp[-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \mu)^2]$$

$$L(\theta; Y) = \ln l(\theta; Y) = -\frac{n}{2} \ln(2\pi) - \frac{n}{2} \ln \sigma^2 - \frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \mu)^2$$

$$\left\{ \begin{array}{l} \frac{\partial}{\partial \mu} L(\theta; Y) = 0 = \frac{1}{\sigma^2} \sum_{i=1}^n (y_i - \mu) \end{array} \right. \quad (1)$$

$$\left\{ \begin{array}{l} \frac{\partial}{\partial \sigma^2} L(\theta; Y) = 0 = -\frac{n}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^n (y_i - \mu)^2 \end{array} \right. \quad (2)$$

$$\left\{ \begin{array}{l} (1) \Rightarrow \hat{\mu}_{ML} = \frac{1}{n} \sum_{i=1}^n y_i = \bar{y} \quad \text{sample mean} \end{array} \right.$$

$$\left\{ \begin{array}{l} (2) \Rightarrow \hat{\sigma}_{ML}^2 = \frac{1}{n} \sum_{i=1}^n (y_i - \bar{y})^2 = \overline{(y - \bar{y})^2} \quad \text{sample variance} \end{array} \right.$$



## ML Estimation: Example 1 (2)

bias calculations

- $E[\hat{\mu}_{ML}|\mu, \sigma^2] = E[\bar{y}|\mu, \sigma^2] = \frac{1}{n} \sum_{i=1}^n E[y_i|\mu, \sigma^2] = \frac{1}{n} \sum_{i=1}^n \mu = \mu$  unbiased!

- note: with  $\bar{y} = \frac{1}{n} \mathbf{1}^T Y$ , we get

$$\begin{aligned} n \hat{\sigma}_{ML}^2 &= \sum_{i=1}^n (y_i - \bar{y})^2 = \left\| \begin{bmatrix} y_1 - \bar{y} \\ \vdots \\ y_n - \bar{y} \end{bmatrix} \right\|^2 = \|Y - \bar{y} \mathbf{1}\|^2 = (Y - \bar{y} \mathbf{1})^T (Y - \bar{y} \mathbf{1}) \\ &= (Y - \mu \mathbf{1} + \mu \mathbf{1} - \bar{y} \mathbf{1})^T (Y - \mu \mathbf{1} + \mu \mathbf{1} - \bar{y} \mathbf{1}) = (Y - \mu \mathbf{1} - (\bar{y} - \mu) \mathbf{1})^T (\dots) = (Y - \mu \mathbf{1})^T (Y - \mu \mathbf{1}) \\ &\quad + (\bar{y} - \mu)^2 \underbrace{\mathbf{1}^T \mathbf{1}}_{=n} - 2(\bar{y} - \mu) \underbrace{\mathbf{1}^T (Y - \mu \mathbf{1})}_{=n(\bar{y} - \mu)} = \underbrace{(Y - \mu \mathbf{1})^T (Y - \mu \mathbf{1})}_{\sum_{i=1}^n (y_i - \mu)^2} - \frac{1}{n} (Y - \mu \mathbf{1})^T \mathbf{1} \mathbf{1}^T (Y - \mu \mathbf{1}) \end{aligned}$$

hence  $\hat{\sigma}_{ML}^2$  is biased:

$$\begin{aligned} E[\hat{\sigma}_{ML}^2|\mu, \sigma^2] &= \frac{1}{n} E_{Y|\mu, \sigma^2} \sum_{i=1}^n (y_i - \mu)^2 - \frac{1}{n^2} \text{tr}\{\mathbf{1} \mathbf{1}^T \overbrace{E_{Y|\mu, \sigma^2} (Y - \mu \mathbf{1})(Y - \mu \mathbf{1})^T}^{=\sigma^2 E_Y V V^T}\} \\ &= \sigma^2 - \frac{1}{n^2} \text{tr}\{\mathbf{1} \mathbf{1}^T \sigma^2 I_n\} = \sigma^2 - \frac{1}{n^2} \sigma^2 \underbrace{\mathbf{1}^T I_n \mathbf{1}}_{=n} = (1 - \frac{1}{n}) \sigma^2 = \frac{n-1}{n} \sigma^2 \neq \sigma^2 \end{aligned}$$

- unbiased variance estimate:  $\hat{\sigma}_{ub}^2 = \frac{n}{n-1} \hat{\sigma}_{ML}^2 = \frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{y})^2$

however, can show:  $\text{Var}\{\hat{\sigma}_{ub}^2\} \geq \text{Var}\{\hat{\sigma}_{ML}^2\}$  (and similarly for MSE).



## ML Estimation: Example 2

- given:  $y_i \sim \mathcal{U}[\theta - \frac{1}{2}, \theta + \frac{1}{2}]$  i.i.d.  $f(y_i|\theta) = \begin{cases} 1 & , y_i \in [\theta - \frac{1}{2}, \theta + \frac{1}{2}] \\ 0 & , \text{elsewhere} \end{cases}$

- Q:  $\hat{\theta}_{ML}$

- A: use the indicator function  $I_A(x) = \begin{cases} 1 & , x \in A \\ 0 & , x \notin A \end{cases}$

$$f(y_i|\theta) = I_{[\theta - \frac{1}{2}, \theta + \frac{1}{2}]}(y_i) = 1 \text{ if } \theta - \frac{1}{2} \leq y_i \leq \theta + \frac{1}{2} \Leftrightarrow y_i - \frac{1}{2} \leq \theta \leq y_i + \frac{1}{2}$$

hence

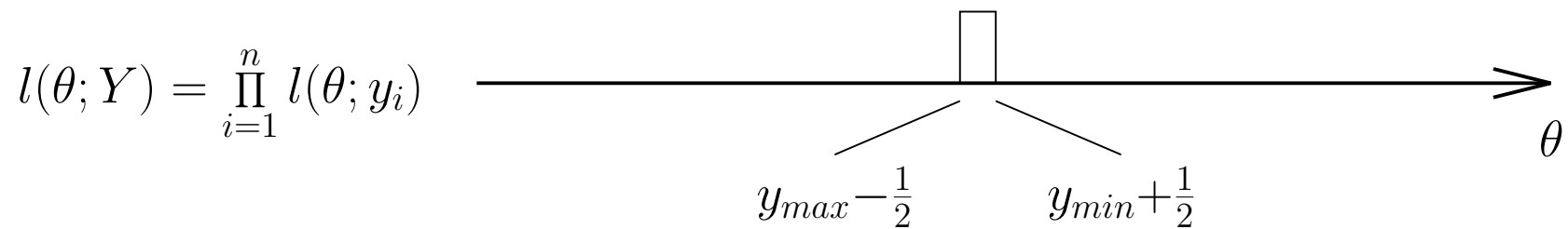
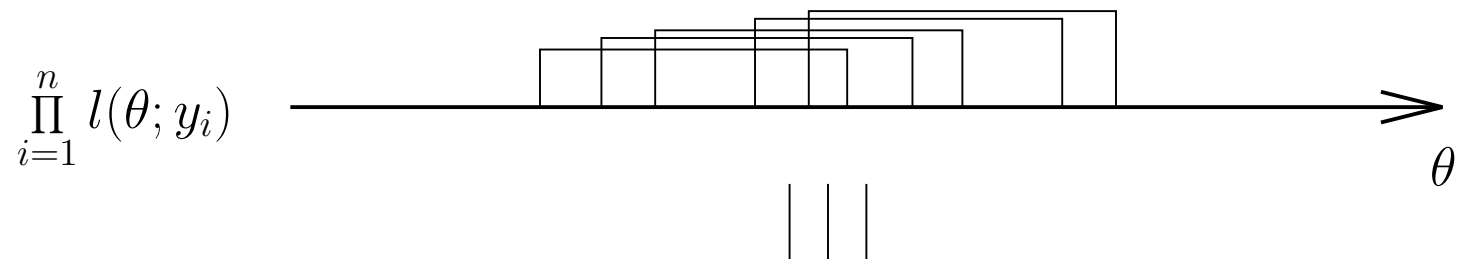
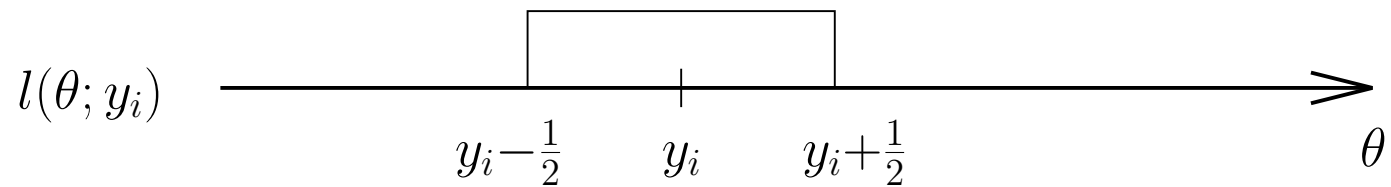
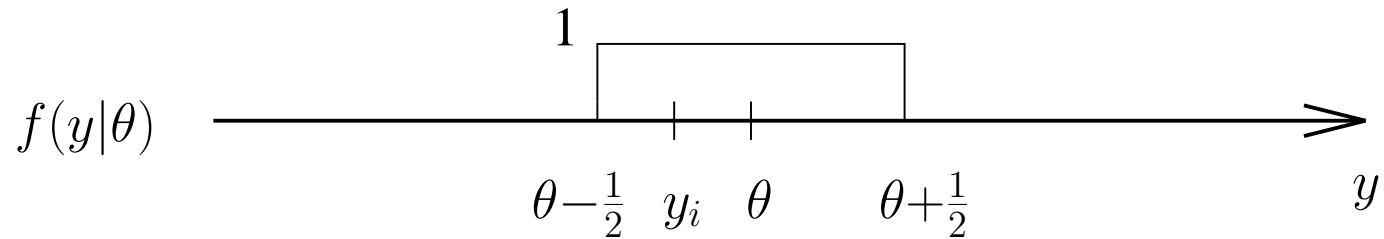
$$\begin{aligned} f(Y|\theta) &= \prod_{i=1}^n f(y_i|\theta) = \prod_{i=1}^n I_{[\theta - \frac{1}{2}, \theta + \frac{1}{2}]}(y_i) = \prod_{i=1}^n I_{[y_i - \frac{1}{2}, y_i + \frac{1}{2}]}(\theta) \\ &= I_{\bigcap_{i=1}^n [y_i - \frac{1}{2}, y_i + \frac{1}{2}]}(\theta) = I_{[y_{\max} - \frac{1}{2}, y_{\min} + \frac{1}{2}]}(\theta) \end{aligned}$$

hence  $\hat{\theta} \in [y_{\max} - \frac{1}{2}, y_{\min} + \frac{1}{2}]$  a whole interval!

- choose  $\hat{\theta}_{ML} = \frac{y_{\min} + y_{\max}}{2}$



## ML Estimation: Example 2 (2)





## Fisher Information Matrix

- The information matrix for deterministic parameters is defined as

$$J(\theta) = R_{\frac{\partial L}{\partial \theta}, \frac{\partial L}{\partial \theta}} = E_{Y|\theta} \left( \frac{\partial \ln f(Y|\theta)}{\partial \theta} \right) \left( \frac{\partial \ln f(Y|\theta)}{\partial \theta} \right)^T = -E_{Y|\theta} \frac{\partial}{\partial \theta} \left( \frac{\partial \ln f(Y|\theta)}{\partial \theta} \right)^T$$

It can again be shown to satisfy all the properties we specified for an information matrix. The second equality can be shown as before. Note that  $J(\theta)$  now depends on the true parameter value  $\theta$ .

- unbiased estimators:  $b_{\hat{\theta}}(\theta) = E_{Y|\theta} \hat{\theta}(Y) - \theta = 0$  ,  $\forall \theta \in \Theta$
- **Lemma 0.1 (Unit Cross Correlation)** *For any unbiased estimator  $\hat{\theta}(Y)$*

$$E_{Y|\theta} \frac{\partial \ln f(Y|\theta)}{\partial \theta} (\hat{\theta} - \theta)^T = I .$$

In words, the cross correlation matrix between  $\frac{\partial \ln f(Y|\theta)}{\partial \theta}$  and the estimation error of any unbiased estimator is the identity matrix.



## Cramer-Rao Bound

- **Theorem (CRB for Deterministic Parameters)** *If the estimator  $\hat{\theta}(Y)$  of  $\theta$  is unbiased, then the covariance matrix of the parameter estimation errors  $\tilde{\theta}$  is bounded below by the inverse of the information matrix:*

$$C_{\tilde{\theta}\tilde{\theta}} = R_{\tilde{\theta}\tilde{\theta}} = E_{Y|\theta} (\hat{\theta} - \theta)(\hat{\theta} - \theta)^T \geq J^{-1}(\theta)$$

*with equality iff*

$$\hat{\theta}(Y) - \theta = J^{-1}(\theta) \frac{\partial \ln f(Y|\theta)}{\partial \theta} \quad a.e. (\theta)$$

An estimator that achieves the lower bound ( $\forall \theta \in \Theta$ ) is called *efficient*.

Remarks:

- when equality holds, we can integrate to get

$$f(Y|\theta) = h(Y) \exp[c_1^T(\theta)\hat{\theta}(Y) - c_0(\theta)]$$

where  $\frac{\partial c_1^T(\theta)}{\partial \theta} = J(\theta)$  and  $\frac{\partial c_0(\theta)}{\partial \theta} = J(\theta)\theta$ . Hence  $\{f(Y|\theta), \theta \in \Theta\}$  forms an exponential family and  $\hat{\theta}(Y)$  is a sufficient statistic.





## Cramer-Rao Bound: Remarks

- the CRB  $J^{-1}(\theta)$  only depends on  $f(Y|\theta)$ , not on  $\hat{\theta}(Y)$
- the (deterministic) CRB has two uses:
  - (i) evaluate unbiased estimators:  $\hat{\theta}$  with  $b_{\hat{\theta}}(\theta) \equiv 0$  : if  $C_{\tilde{\theta}\tilde{\theta}} - J^{-1}(\theta)$  small enough, then  $\hat{\theta}$  good enough
  - (ii) find UMVUE:  $\min_{\hat{\theta}: b_{\hat{\theta}} \equiv 0} C_{\tilde{\theta}\tilde{\theta}} \geq J^{-1}(\theta)$ .

If  $\hat{\theta}$  is efficient ( $\forall \theta \in \Theta$ ),  $C_{\tilde{\theta}\tilde{\theta}} = J^{-1}(\theta)$ , then  $\hat{\theta}$  is UMVUE!

- **Theorem** Suppose  $\hat{\theta}_{ML}$  is obtained by  $\frac{\partial}{\partial \theta} f(Y|\theta)|_{\theta=\hat{\theta}_{ML}} = 0$ . Then if an efficient estimator exists, it is  $\hat{\theta}_{ML}$ .

Proof:  $\hat{\theta}_{eff}$  satisfies

$$\frac{\partial \ln f(Y|\theta)}{\partial \theta} = \underbrace{J(\theta)}_{>0} [\hat{\theta}_{eff} - \theta]$$

For  $\theta = \hat{\theta}_{ML}$ , LHS = 0, hence RHS = 0 :  $\hat{\theta}_{eff} = \hat{\theta}_{ML}$ .

- If  $J(\theta)$  is singular  $\Rightarrow$  (local) *unidentifiability*. E.g. linear model with  $n < m$ .



## Cramer-Rao Bound: Example

- i.i.d.  $y_i \sim \mathcal{N}(\mu, \sigma^2)$ ,  $\sigma^2$  known,  $\theta = \mu$
- $f(Y|\mu) = \prod_{i=1}^n f(y_i|\mu) = (2\pi\sigma^2)^{-n/2} \exp[-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \mu)^2]$
- $\frac{\partial \ln f(Y|\mu)}{\partial \mu} = \frac{1}{\sigma^2} \sum_{i=1}^n (y_i - \mu)$ ,  $\frac{\partial^2 \ln f(Y|\mu)}{\partial \mu^2} = -\frac{n}{\sigma^2}$
- $J = -E_{Y|\mu} \frac{\partial^2 \ln f(Y|\mu)}{\partial \mu^2} = \frac{n}{\sigma^2}$ ,  $C_{\hat{\mu}\hat{\mu}} = E_{Y|\mu}(\hat{\mu} - \mu)^2 \geq J^{-1} = \frac{\sigma^2}{n}$
- $\hat{\mu}_{ML} = \bar{y} = \frac{1}{n} \sum_{i=1}^n y_i$ ,  $E_{Y|\mu} \hat{\mu}_{ML} = \mu$  : unbiased
- $C_{\hat{\mu}\hat{\mu}} = E_{Y|\mu}(\hat{\mu} - \mu)^2 = E_{Y|\mu} \left( \frac{1}{n} \sum_{i=1}^n (y_i - \mu) \right)^2$   
$$= \frac{1}{n^2} \left( \sum_{i=1}^n \underbrace{E(y_i - \mu)^2}_{=\sigma^2} + \sum_{i \neq j} \underbrace{E(y_i - \mu)(y_j - \mu)}_{=(Ey_i - \mu)(Ey_j - \mu) = 0} \right) = \frac{1}{n^2} n \sigma^2 = \frac{\sigma^2}{n} = J^{-1}$$
- efficient:  $\frac{\partial \ln f(Y|\mu)}{\partial \mu} = \frac{1}{\sigma^2} \sum_{i=1}^n (y_i - \mu) = \frac{n}{\sigma^2} (\bar{y} - \mu) = J (\hat{\mu}_{ML} - \mu)$



## The Deterministic Linear Model

- $Y = H\theta + V$  ,  $V \sim \mathcal{N}(0, C_{VV})$
- $f_{Y|\theta}(Y|\theta) = f_V(Y - H\theta) = \frac{1}{\sqrt{(2\pi)^n \det C_{VV}}} e^{-\frac{1}{2}(Y-H\theta)^T C_{VV}^{-1}(Y-H\theta)}$
- $\frac{\partial \ln f_V(Y - H\theta)}{\partial \theta} = H^T C_{VV}^{-1}(Y - H\theta) = 0$   
 $\Rightarrow \hat{\theta}_{ML} = (H^T C_{VV}^{-1} H)^{-1} H^T C_{VV}^{-1} Y$
- $\frac{\partial}{\partial \theta} \left( \frac{\partial \ln f_V(Y - H\theta)}{\partial \theta} \right)^T = - \underbrace{H^T \underbrace{C_{VV}^{-1}}_{>0} H}_{>0} = -J < 0 \Rightarrow \text{maximum!}$   
assuming  $H$  full column rank
- $\tilde{\theta} = \theta - \hat{\theta} = -(H^T C_{VV}^{-1} H)^{-1} H^T C_{VV}^{-1} V$  ,  $E_{Y|\theta} \tilde{\theta} = E_V \tilde{\theta} = 0 \Rightarrow \text{unbiased!}$
- $C_{\tilde{\theta}\tilde{\theta}} = R_{\tilde{\theta}\tilde{\theta}} = E_{Y|\theta} \tilde{\theta} \tilde{\theta}^T = E_V \tilde{\theta} \tilde{\theta}^T = (H^T C_{VV}^{-1} H)^{-1} = J^{-1} : \text{efficient!}$
- $\frac{\partial \ln f_V(Y - H\theta)}{\partial \theta} = H^T C_{VV}^{-1} Y - H^T C_{VV}^{-1} H\theta = J(\hat{\theta} - \theta) : \text{efficient}$