

CPSC 406, Term I, 2016-17

Assignment 4, due Tuesday, November 8

Answer the **first question** as well as **two out of the last three questions**.

Please show all your work: provide a hardcopy of the entire assignment (including plots and programs); in addition, e-mail your MATLAB programs to `cs406@ugrad.cs.ubc.ca`. When e-mailing your programs, include your name and student ID in the message's title.

Do not e-mail a complete assignment: only the programs.

1. Consider the least squares problem

$$\min_{\mathbf{x}} \|\mathbf{b} - A\mathbf{x}\|_2,$$

where the columns of the $m \times n$ matrix A are linearly dependent or almost so. Consider the *regularization* approach that replaces the normal equations by the modified, better conditioned system

$$(A^T A + \gamma I)\mathbf{x}_\gamma = A^T \mathbf{b},$$

where $\gamma > 0$ is a parameter. This approach “rivals” the truncated SVD (TSVD) method that we saw in Chapter II3.

- (a) Show that $\kappa_2^2(A) \geq \kappa_2(A^T A + \gamma I)$.
- (b) Reformulate the equations for \mathbf{x}_γ as a linear least squares problem.
- (c) Show that $\|\mathbf{x}_\gamma\|_2 \leq \|\mathbf{x}\|_2$.
- (d) Find a bound for the relative error $\frac{\|\mathbf{x} - \mathbf{x}_\gamma\|_2}{\|\mathbf{x}\|_2}$ in terms of either the largest or the smallest singular value of the matrix A .

State a sufficient condition on the value of γ that would guarantee that the relative error is bounded below a given value ε .

- (e) Write a short program to solve the 5×4 problem of the Example on slide 30 of chapII3 regularized as above, using MATLAB's “backslash”. Try $\gamma = 10^{-j}$ for $j = 0, 3, 6$ and 12. For each γ , calculate the ℓ_2 -norms of the residual, $\|A\mathbf{x}_\gamma - \mathbf{b}\|$, and the solution, $\|\mathbf{x}_\gamma\|$. Compare to the results for $\gamma = 0$ and to those using TSVD. What are your conclusions?
- (f) For large ill-conditioned least squares problems, what is a potential advantage of the regularization with γ presented here over minimum norm TSVD?

2. Prove the following **theorem**:

Let A be $m \times n$, $m < n$, with full row rank m . Further, let $B = R^T R$ where R is a nonsingular $n \times n$ matrix.

Then the limit solution of the problem

$$(A^T A + \gamma B) \mathbf{x}_\gamma = A^T \mathbf{b}$$

as $\gamma \downarrow 0$ exists and is unique (even though $A^T A$ is singular). It is given by

$$\mathbf{x}^* = -B^{-1} A^T \mathbf{y} = B^{-1} A^T (AB^{-1} A^T)^{-1} \mathbf{b}.$$

Furthermore, this \mathbf{x}^* is the unique solution of the problem

$$\min_{\mathbf{x}} \frac{1}{2} \mathbf{x}^T B \mathbf{x}, \quad \text{s.t. } A \mathbf{x} = \mathbf{b}.$$

3. (a) Convert the following linear program to standard primal form:

$$\begin{aligned} \min_{\mathbf{z}} \quad & f = z_1 - 5z_2 - 6z_3 \\ \text{s.t.} \quad & 4z_1 - 2z_2 + 6z_3 \geq 5 \\ & 3z_1 + 4z_2 - 9z_3 = 3 \\ & 7z_1 + 3z_2 + 5z_3 \leq 9 \\ & z_1 \geq -2. \end{aligned}$$

- (b) Solve the problem using any means you like (but tell us what you have used). Report the values of the optimal \mathbf{z}^* and $f(\mathbf{z}^*)$.
4. (a) Please read the writeup **sparseI**. (Sorry, no points for this item. Note also that the last part of this writeup is reproduced in Section 9b.4.)
- (b) Consider the problem

$$\begin{aligned} \min_{\mathbf{x}} \quad & \|\mathbf{x}\|_p \\ \text{s.t.} \quad & A \mathbf{x} = \mathbf{b}, \end{aligned}$$

where A is $m \times n$, $m \leq n$.

Describe an instance where solving this with $p = 2$ actually makes more sense than with $p = 1$.

- (c) For $p = 2$ the problem can be solved as described in the writeup **sparseI** using SVD. But it can also be solved using the techniques of constrained optimization:
- Explain why it is justified to replace the objective function by $\frac{1}{2} \|\mathbf{x}\|_2^2$.
 - Form the KKT conditions of the resulting constrained optimization problem, obtaining a linear system of equations.
 - Devise an example and solve it using the method just developed as well as the one using SVD from **sparseI**. Compare and discuss.