

Schedule, Support, Adjust, and Fix: Topology Control Revolutions for Data-Aware Networks

Stefan Schmid (University of Vienna, Austria)



Great Time to be An ALGOSENSORS Researcher!



Rhone and Arve Rivers
Switzerland

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Sensor and wireless networks evolving quickly: in terms of **applications**, **technology** (e.g. **SDN**) and **scale** (**#devices** and **data**).



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Actually, Opportunities Have Even More Dimensions!



Passau, Germany

Inn, Donau, Ilz

Actually, Opportunities Have Even More Dimensions!

Example: IoT

- **Converging technologies**
- Traditional fields become “*in*” again:
control systems,
automation



Passau, Germany

Inn, Donau, Ilz

IoT History or: *Finnish for Beginners!*

- **Network of smart devices** discussed already **1982**: Coke machine @ CMU connected to the Internet (reports inventory and whether drinks were cold)

Tavaravirran seuranta osana Internet-pohjaista tuotetiedon hallintaa

Kary Främling, TKT, Teknillinen korkeakoulu, TAI tutkimuslaitos

Johdanto

Tavaravirran seuranta on yleensä helposti hallittavissa niin kauan kuin pysytään yhden yhtiön tai organisaation sisällä, jolloin seurantaan liittyvät tiedot löytyvät sisäisestä tietojärjestelmästä jo ovat aina saatavilla. Käytännössä tavaravirra kulkee kuitenkin yhä suurempien toimitusverkostojen läpi, jolloin tavaravirran hallinta koskee monia eri yrityksiä. Tavaravirran suurimmat riskitekijät liittyvätkin usein juuri yhtiöiden väliseen tavaroiden siirtoon. Tavaravirran seuranta on kuitenkin hankalinta tässä tapauksessa, koska eri yhtiöiden tietojärjestelmät eivät yleensä osaa kommunikoida keskenään.

The first IoT paper



The first IoT device

- **First paper** mentioning the term “IoT” published 2002 in **Finnish** at Helsinki University of Technology

New Types of Sensor Networks

- Sensor networks based on **laptops**
- E.g., early warning of **disasters** such as **earthquakes** (e.g., to stop high-speed trains)
 - Using integrated **accelerometer** (originally to protect harddrive when falling)
 - **Fill the „gaps“** between seismometers already in place in California
 - E.g., Apple laptops since 2005



New Types of Applications: Smart Devices Move...

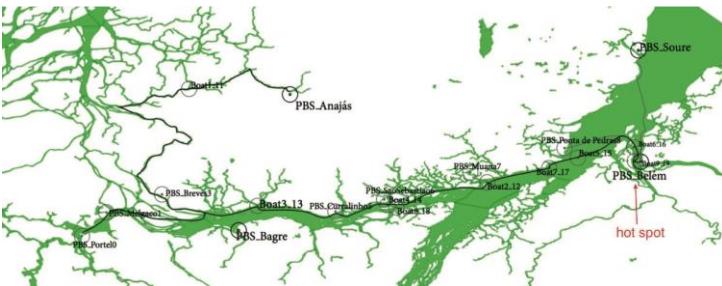
- E.g., smart devices/things move with their owners: (social) **mobile network**
- May have **intermittent** connectivity and must hence be **delay-tolerant**
 - E.g., student (“data mule”) commuting between hotspots



*MULE = Mobile Ubiquitous LAN Extension

Case Study: “Data Mules” in Amazon Riverine

- By **Richa et al.**, with Brazilian collaborators
- Challenge: providing **health care** to the remote communities in the Brazilian Amazon
- Constraint: Lack of modern **communication infrastructure** in these communities
- Solution: **delay-tolerant network**
 - **Local nurses** perform routine clinical examinations, such as **ultrasounds** on pregnant women
 - **Records sent** to the doctors in Belem (city) for evaluation
 - Idea: use of regularly **scheduled boats** as data mules



Source: Liu et al. Robust data mule networks with remote healthcare applications in the Amazon region. HealthCom 2015: 546-551

Enjoy: last river in this presentation!

... Fly ...

- E.g., 1000+ high-tech **drones** at Winter olympics



... Collect Lots of Data While Flying ...: The “Internet of Aircraft Things”

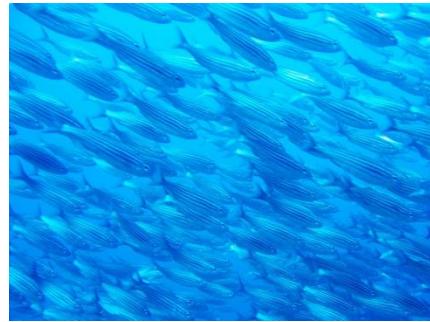
- Geared Turbo Fan (GTF) engines fitted with **5000 sensors** that generate **10 GB** of data per second
 - I.e., twin-engine aircraft with **12 h flight** time: **>800 TB** of data
- Usage, e.g. **AI** for prediction of engine demands to ***adjust thrust levels***



Hey, Robots!

Last Week's Dagstuhl Seminar on Programmable Matter and Swarm Robotics

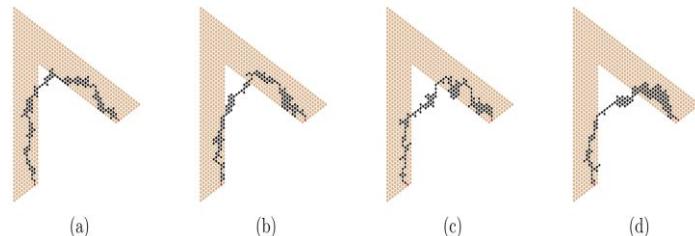
- Emergence of large number **simple and small** robots that, when combined, can perform **complex** tasks
- Often inspired by **nature: What can we learn from natural swarms?**



Dagstuhl Seminar “**Programmable Matter**”

Example: Smart Natural Swarms

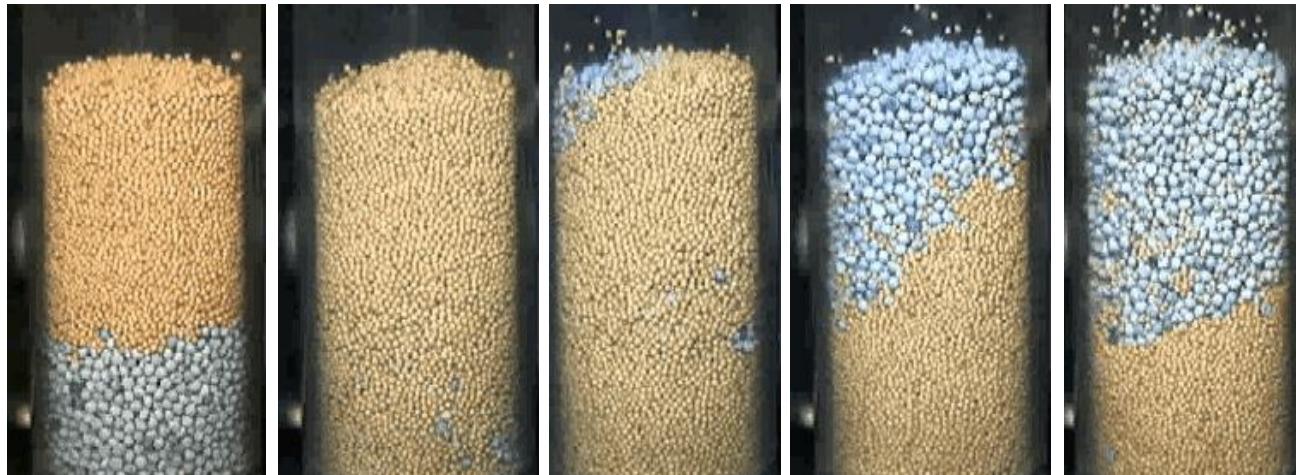
- Army ants (*Eciton*) can solve ***non-trivial optimization*** problems, e.g., build “ant-bridges” as ***shortcut*** along supply chain
- Bridge location ***depends on angle*** of gap
- **Tradeoff: longer bridges** make the total path ***shorter***, but need to ***sacrifice more workers***



[RLPKCG 2015: “Army ants dynamically adjust living bridges...”](#)

Example: Exploit Brazil Nut Effect

- Task: separate different robots
- Inspiration: exploit nuts effect and gravity: shaking / random move of nuts: **big nuts** up, **small nuts** down



From: University of Amsterdam



E-puck

- Solution: robots with **distance sensors**:



Big nut: large
collision radius



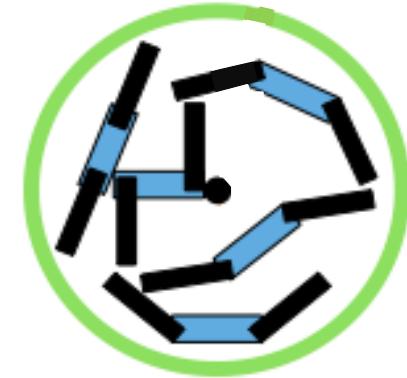
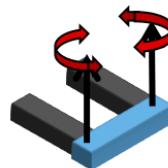
Small nut: small
collision radius

Locomotion by *Combining* Very Simple Robots



A **ring-robot** made of robots

smarticle



supersmarticle

- Very simple things: **smarticle** (alone: “random **flapping**”)
 - One smarticle: **no locomotion**
- But when interaction with **multiple** smarticles confined in a **ring**, with **one inactive** smarticle:
 - **Brownian motion w/ drift** (toward **inactive** smarticle)

Discovered **by accident**:
one smarticle died!

Further Applications

Reconfigurable robots
("transformers")



Flora Robotica: e.g.,
robots to grow houses



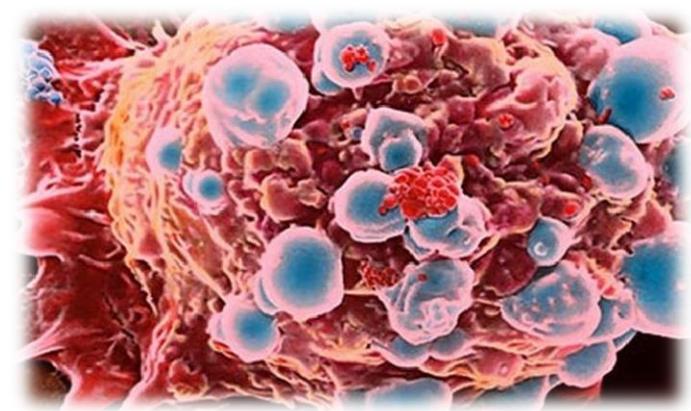
“Helpful” robots ☺

“IoT trend” also for robots: Many becoming smaller in size but larger scale



Kilobots, Harvard

Monitor health and assist
in **surgeries**



We still lack **models** (first attempts such as **Amoeba** model, name *depricated*)!

Common Theme: *Bigger*

In terms of **size**:

E.g., 8.4 billion IoT devices
in 2017, 30 billion devices
expected by 2020

But also in terms of **data**:

„Data generated by
aerospace industry alone
could be in the order of the
consumer Internet.“

AviationWeek.com



New challenges, new solutions required!

“Large scale and big data”: Babyphone Attack (Fall 2016)

- First big IoT device **attack**
- Attackers exploited household devices: IP-cameras, printers, **babyphones**, tv recorders, ...
- DoS attack of more than **500 Gbps!**
- Twitter, Netflix, Spotify, ... unreachable for several hours

Security / #CyberSecurity

SEP 25, 2016 @ 10:00 AM 41,011 VIEWS

How Hacked Cameras Are Helping Launch The Biggest Attacks The Internet Has Ever Seen

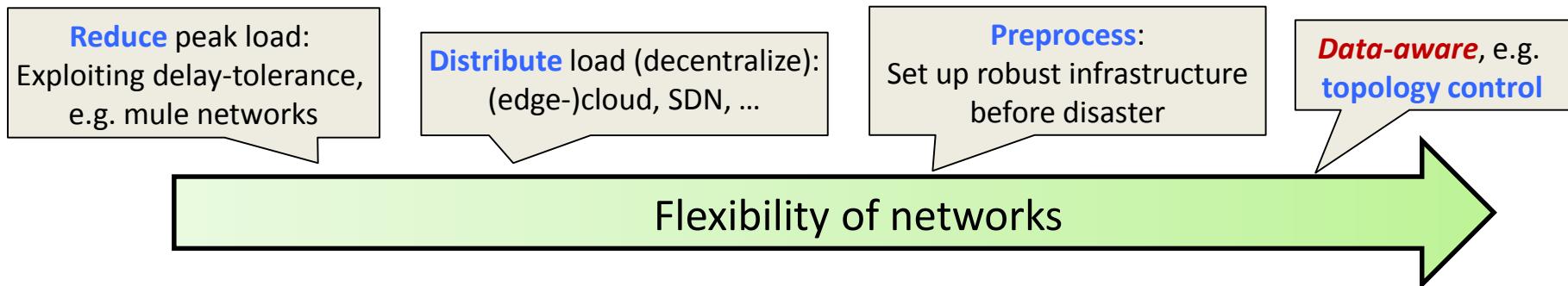


Thomas Fox-Brewster, FORBES STAFF

I cover crime, privacy and security in digital and physical forms. [FULL BIO](#) ▾

“Cyber-attack from the babyphone” – Spiegel, 2016

Dealing With These Challenges: Exploiting Algorithmic Flexibilities



In general: make algorithms „aware“ of network flexibilities and specific properties of the workload!



Emerging applications and large-scale sensor networks
processing big data require ***new models and algorithms!***

Some (early) examples.

General Remark: CS = “The Science of the Machine”

- Technological **enablers** are there, but emerging machines **hardly understood** today!
- **Models**? Practical constraints? Objectives? Etc.
- Algorithmic **opportunities**?



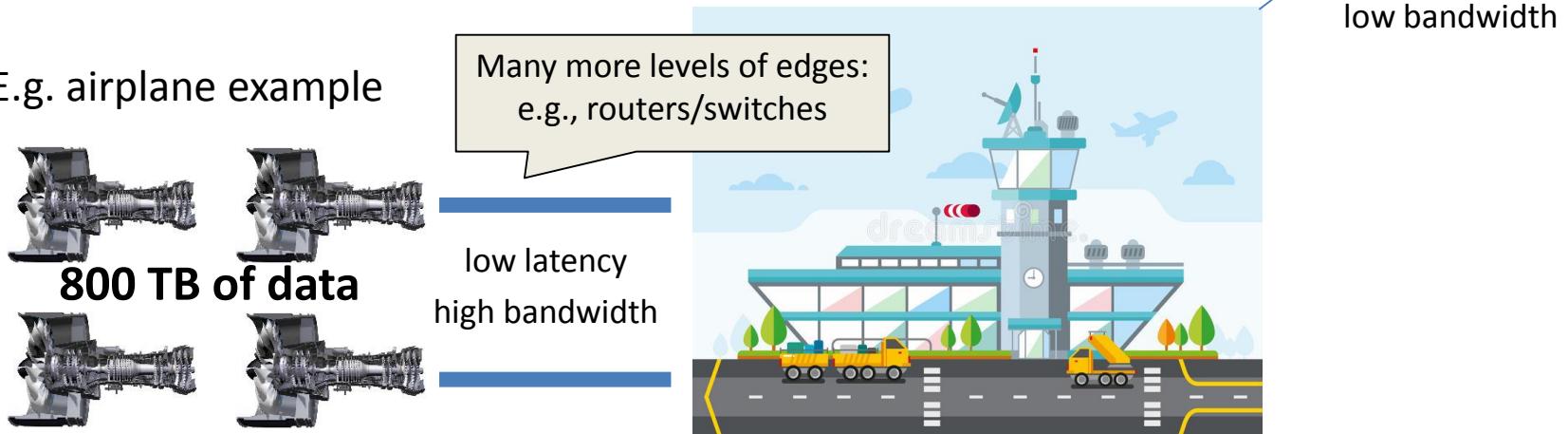
Credits: Marcos K. Aguilera

PODC 2018

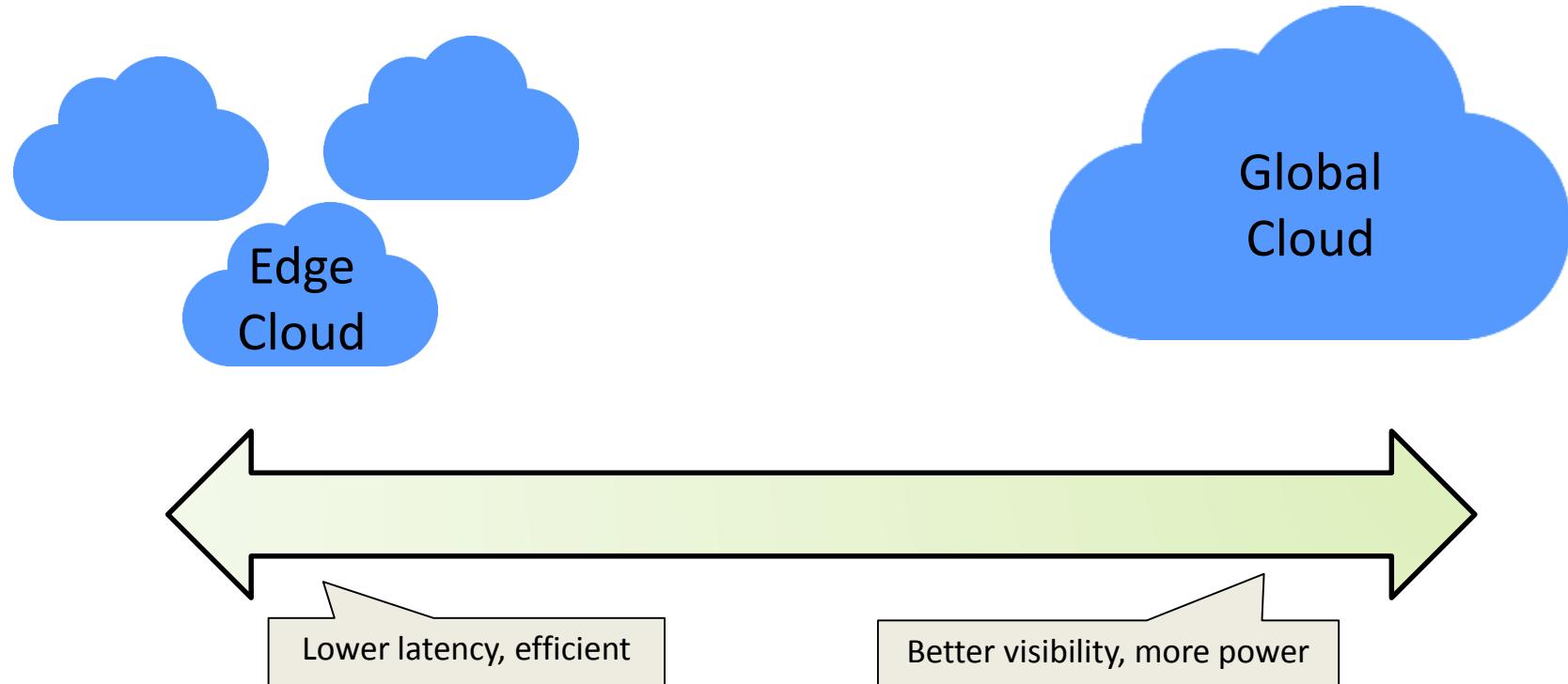
Opportunity: Choose Level of Decentralization

Centralized vs Decentralized: Example “Edge Cloud / Distributed Cloud”

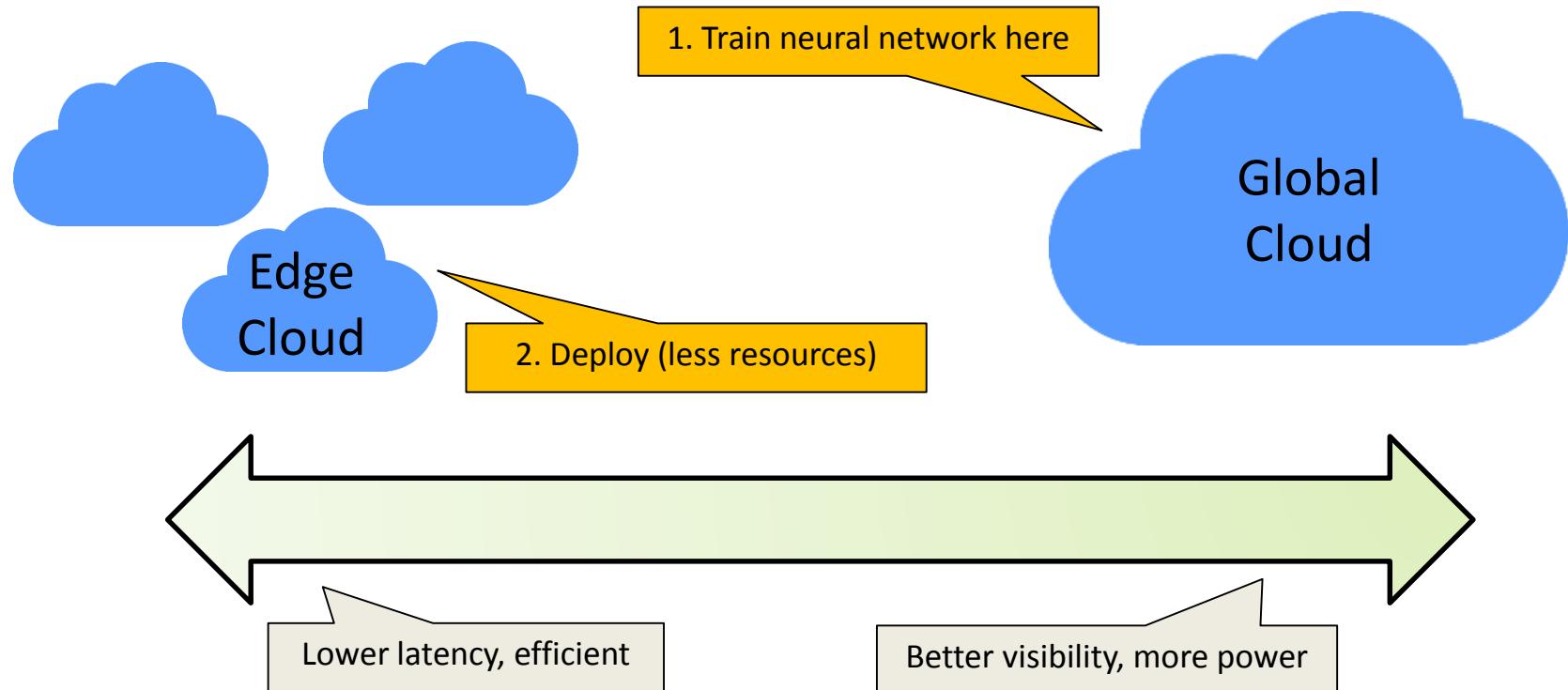
- ***Big scale*** and big data: **central cloud** is not always the best solution
- Motivation for ***applying scale out*** to the datacenter: **distributed cloud**
- Lower latency, less bandwidth
- E.g. airplane example



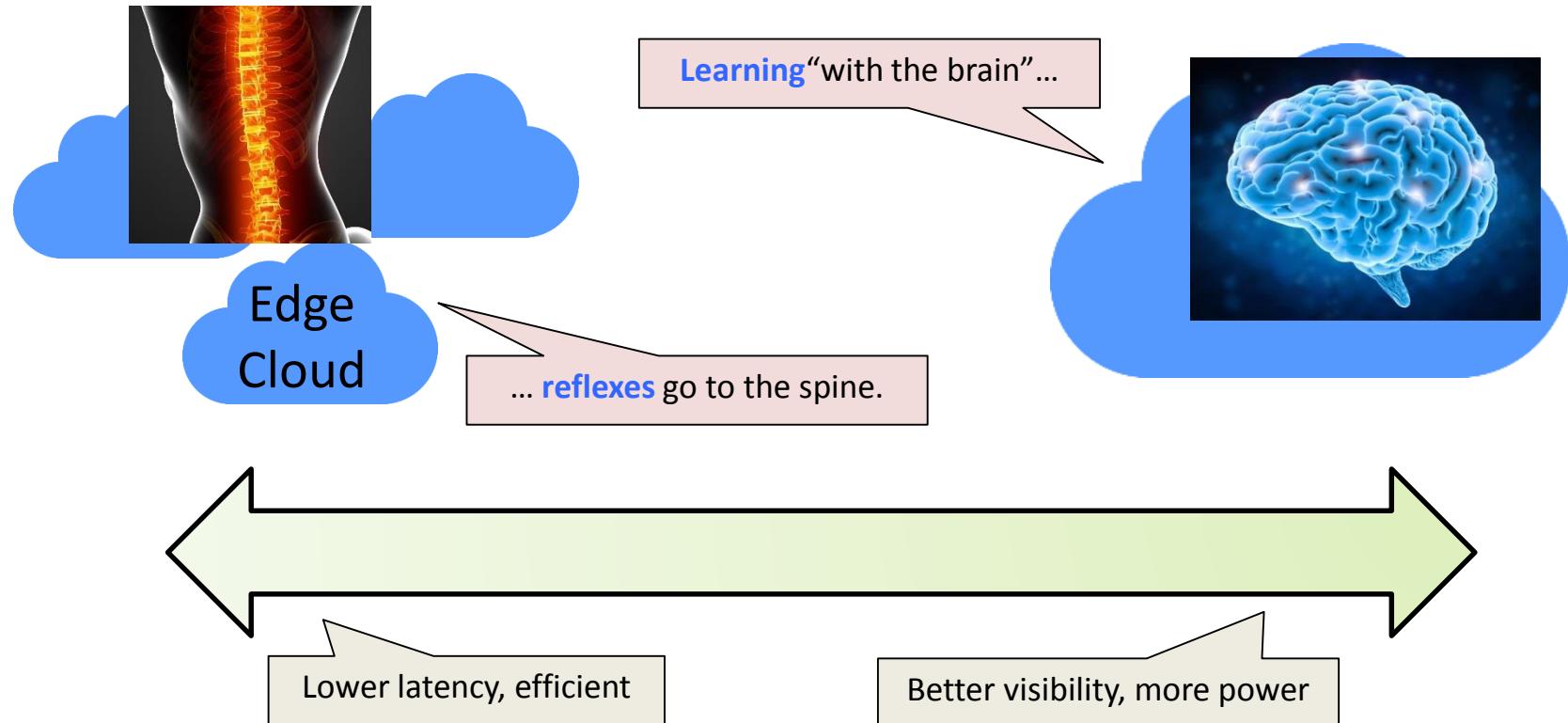
Centralized vs Decentralized: A Tradeoff



Centralized vs Decentralized: A Tradeoff



Centralized vs Decentralized: A Tradeoff

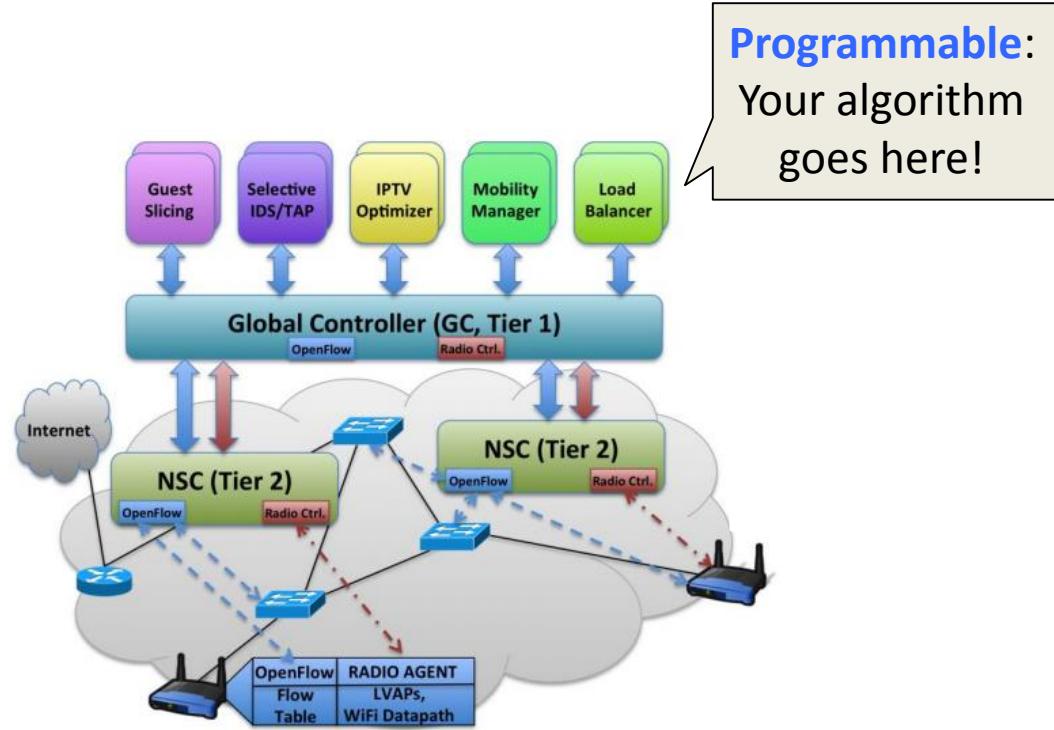


Centralized vs Decentralized: Example “Software-Defined Networks (SDN)”

- Interesting new technology for **Algosensors**:
(Wireless) networks become programmable („**software-defined**“)
- Easy to deploy your own algorithm for:
routing, **rate/power control**, interference/
mobility management, load-balancing, etc. :
 - Opportunity for research & innovation: „the **linux of networking**“

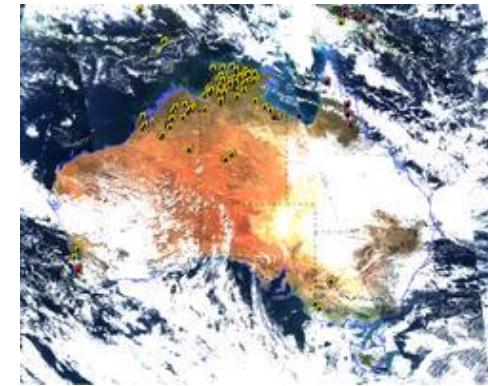
Interesting dimension: distributed control plane

- **Global controller** for coarse-grained control
 - Services that require global visibility (e.g. **spanning tree** or shortest path)
- **Near-sighted controller** for fine grained control
 - **Latency-critical** transmission control **or load-intensive** tasks



Going back to Distaster Detection “Bushfire Monitoring”: Centralized vs Decentralized?

- Example: SENTINEL Australian **bushfire monitoring** system
- Centralized, based on **satellites**
- However, satellites may **miss certain heat** sources, e.g., if there is **smoke**!
- **Distributed** sensor nodes (in addition) can be a good alternative



SENTINEL Disclaimer Agreement

Please note the limitations of the Sentinel Hotspots mapping system:

1. Under ideal conditions, the hotspots shown will have been detected 1-24 hours ago, depending on regional information received from the last satellite overpass.
2. The hotspot location on any map (no matter how detailed) is only accurate to at best 1.5 km.
3. The symbol used for the hotspot on the maps does not indicate the size of the fire.
4. Not all hotspots are detected by the satellites. Some heat sources may be too small, not hot enough, or obscured by thick smoke or cloud.
5. The satellites detect any heat source that is hotter than normal. As well as fires these may include industrial operations such as furnaces.

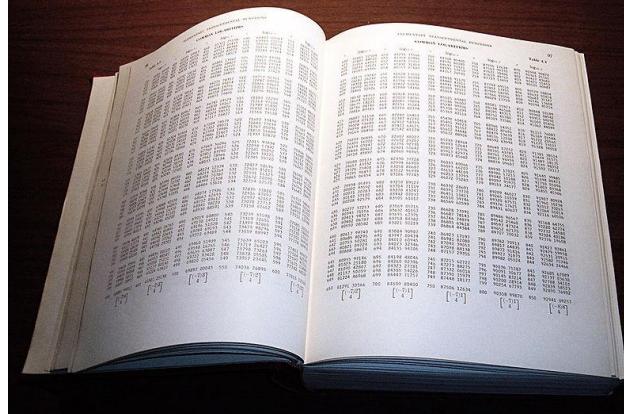
Research Challenges

So what can be computed ***locally***, what should be ***global*** comes in many new flavors:

- E.g., in distributed / edge cloud: Trend of moving away from ***client-server***: How does „**client-edge-server**“ change consistency, fault-tolerance etc. compare to „user-cloud/server“? New ***distributed computing challenges!***
- E.g., in software-defined wireless networks
- Etc.

The **clue**: Unlike classic distributed graph algorithms, there is a ***choice***! Hybrid distributed-centralized networks

Opportunity: Precomputation



Precomputed logarithms
(20th century book)

Example: Classic Distributed Graph Algorithms

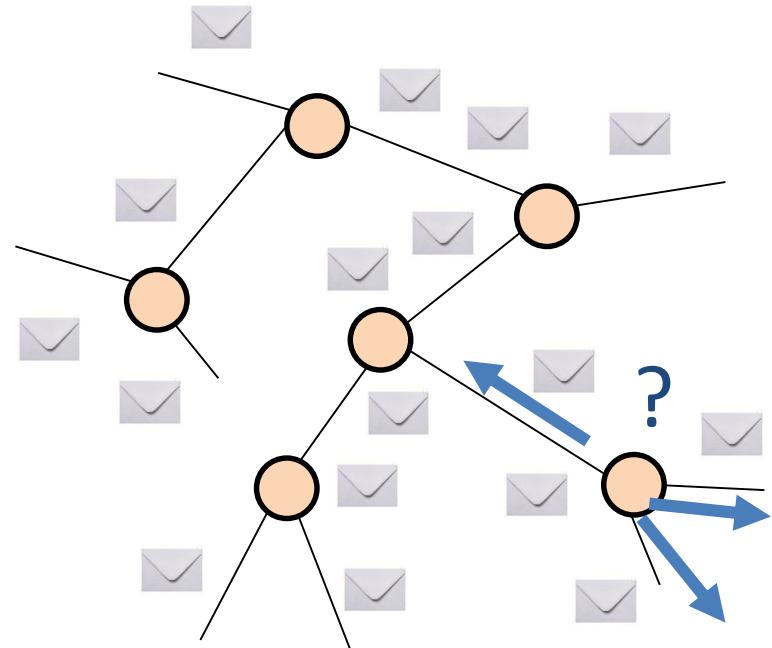


The Power of Precomputation?

- Example: Distributed graph algorithms
- Traditional model (LOCAL and CONGEST):
 - Start **from scratch**
 - Each node first needs to explore its neighborhood, break **symmetries**, etc.

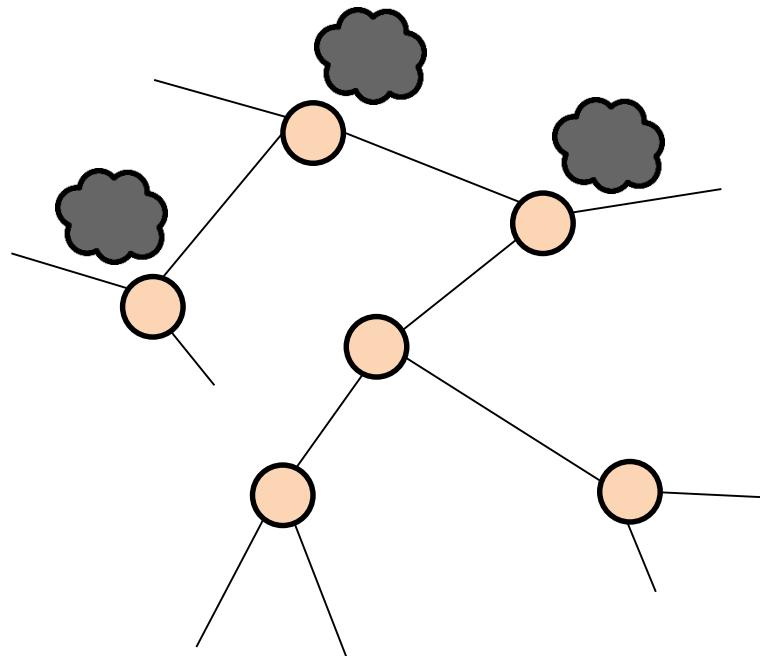
 Sometimes, some **pre-computation** is possible:
E.g., (rough) idea how network looks like (**node locations** or links «**before failures**»)!

- Just don't know, e.g., **failures** or **demand**
- So:
 - Which information is **useful to precompute** so that later distributed algorithms are faster?
 - How to **exploit** it in algorithms?

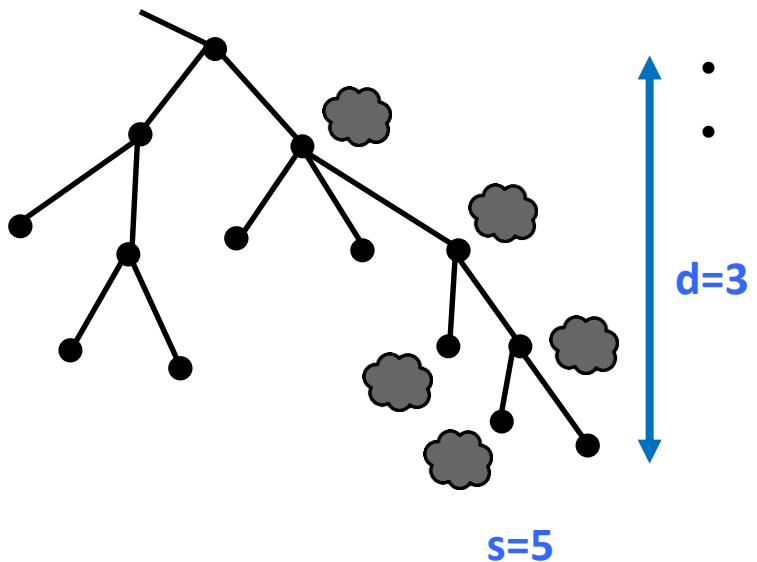


Going Back to Bushfire: Estimate the Disaster Size

- A simple **model**: *bush fire* breaks out, smoke detected by local nodes
- Goal: efficiently detect *size of disaster*, i.e., of connected «**event component**»
 - at least 1 node should know
- Ideally, don't waste energy for *small events*: algorithm should be **output sensitive**. In case of „small disasters“, only a small number of messages is transmitted
- Different model flavors:
 - *On-duty*: non-affected nodes can help too
 - *Off-duty*: they cannot help



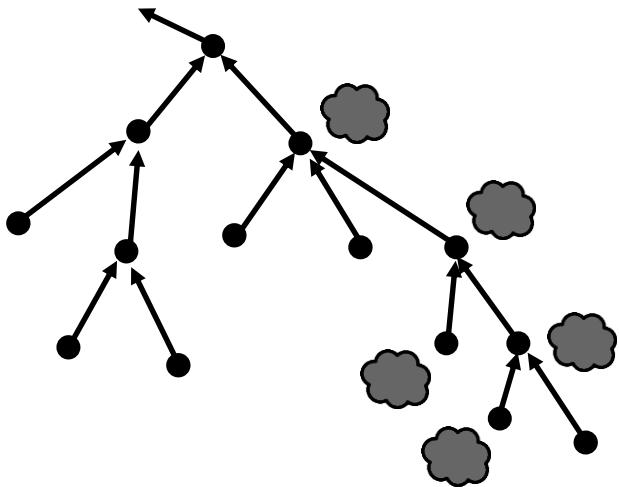
Example: Disaster Estimation on Trees



- Assume: disaster of **size s** of **diameter d**
- Ideally: message complexity **s** , time complexity **d**

How to achieve this?

Example: Disaster Estimation on Trees

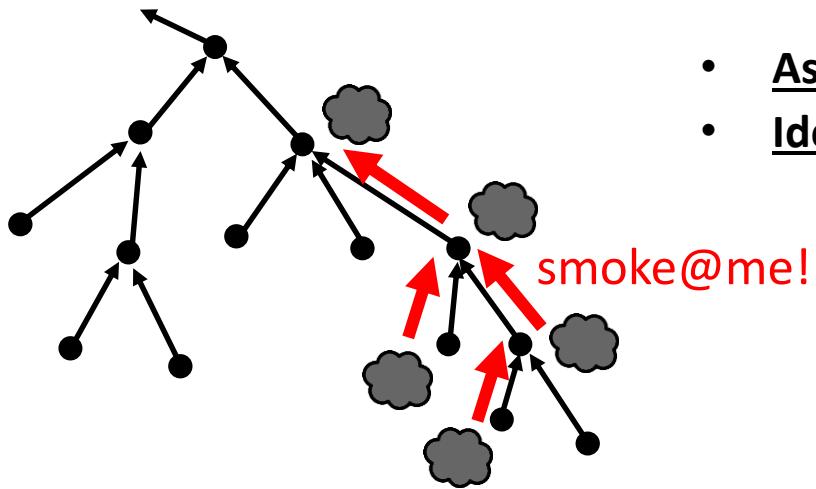


- Assume: disaster of **size s** of **diameter d**
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Preprocess: make tree
rooted and **directed**!

Example: Disaster Estimation on Trees

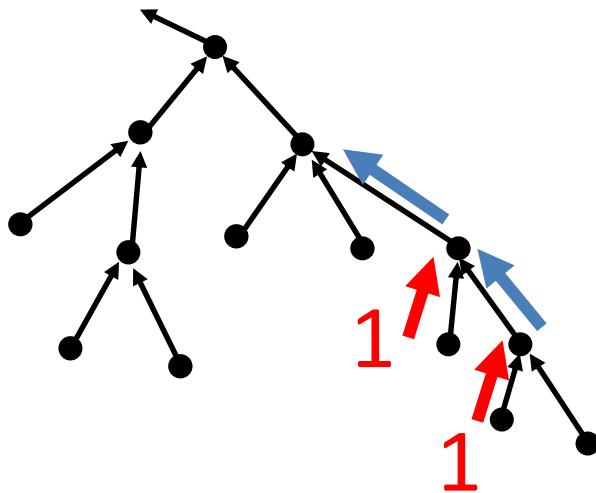


- Assume: disaster of *size s* of *diameter d*
- Ideally: message complexity *s*, time complexity *d*

Round 1

1. each node *v* **immediately informs** its parent in case of an event «sensed»

Example: Disaster Estimation on Trees

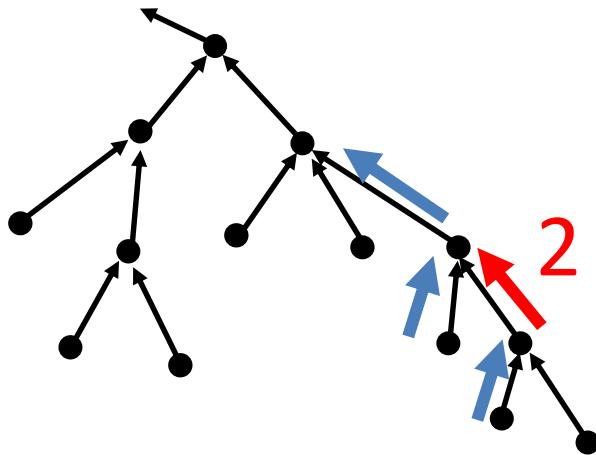


- Assume: disaster of **size s** of **diameter d**
- Ideally: message complexity **s**, time complexity **d**

Round 2

1. each node v immediately informs its parent in case of an event «sensed»
2. wait until all **event-children** counted the total number of event nodes in their subtrees

Example: Disaster Estimation on Trees

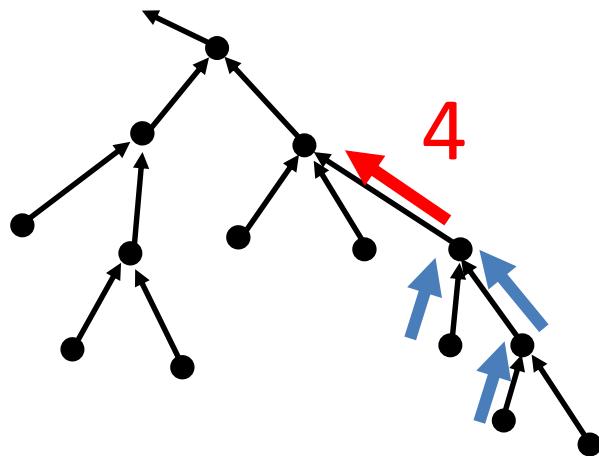


- Assume: disaster of **size s** of **diameter d**
- Ideally: message complexity **s**, time complexity **d**

Round 3

1. each node v immediately informs its parent in case of an event «sensed»
2. wait until all **event-children** counted the total number of event nodes in their subtrees
3. **propagate** up

Example: Disaster Estimation on Trees

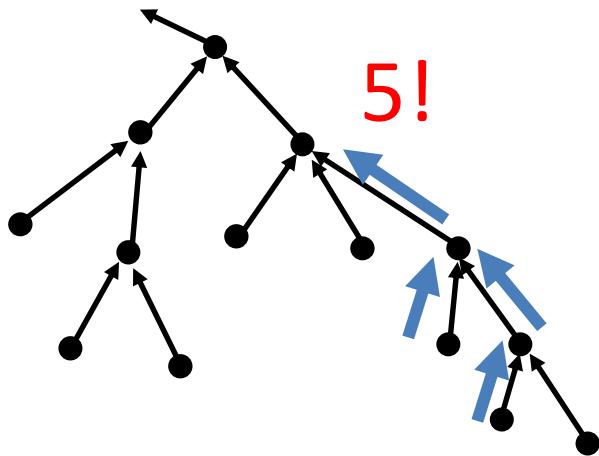


- Assume: disaster of **size s** of **diameter d**
- Ideally: message complexity **s**, time complexity **d**

Round 4

1. each node v immediately informs its parent in case of an event «sensed»
2. wait until all **event-children** counted the total number of event nodes in their subtrees
3. **propagate** up

Example: Disaster Estimation on Trees



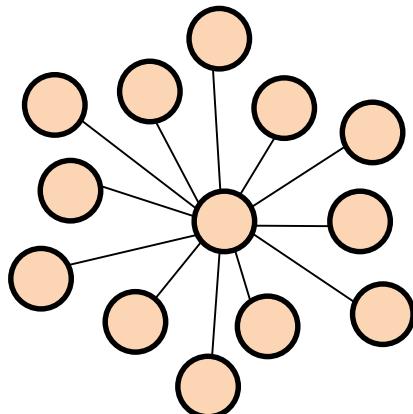
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Preprocessing For Neighborhood Discovery

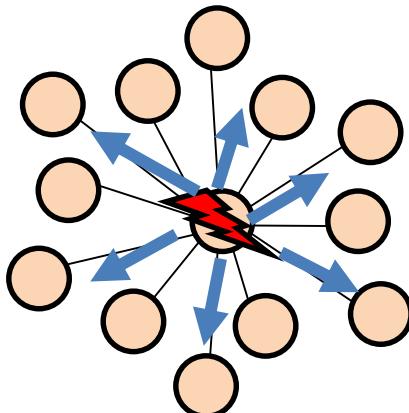
- How to do this on **general graphs**?
- Even more **basic problem**: How to efficiently find out which of my neighbors also sensed an event? **Neighborhood discovery!** Goal again: «**output-sensitive**»
- Idea: «Just inform all neighbors!»



Preprocessing For Neighborhood Discovery

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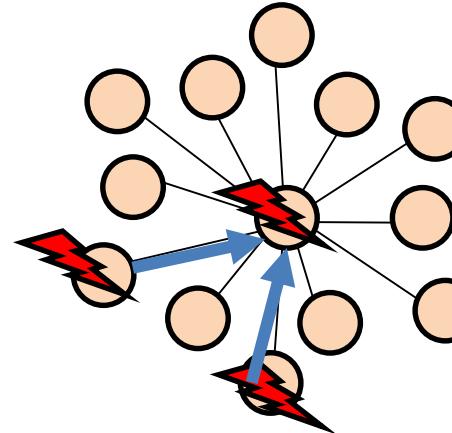
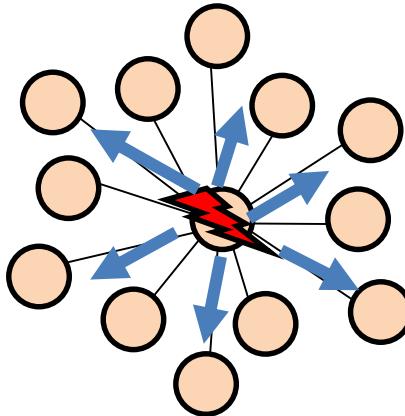
Problem:
**disaster size
1, but cost n**



Preprocessing For Neighborhood Discovery

- How to do this on **general graphs**?
- Even more **basic problem**: How to efficiently find out which of my neighbors also sensed an event? **Neighborhood discovery!** Goal: «**output-sensitive**»!
- Idea: «Just inform all neighbors!»
- Another idea: «Low-degree nodes inform **high-degree neighbors**!»

Problem:
disaster size 1, but cost n



Efficient here!
(Note: on-duty only)

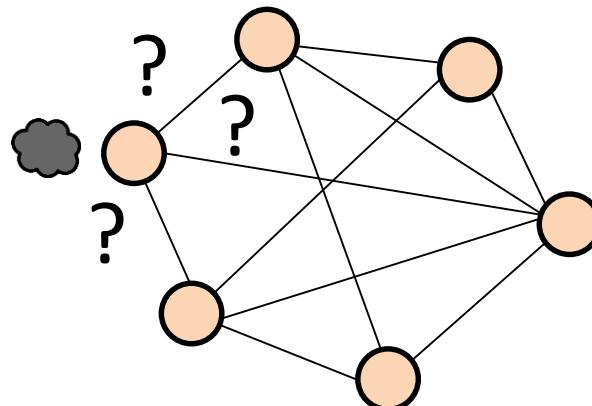


Preprocessing For Neighborhood Discovery

But what about symmetric graphs like **clique**?

Again **neighborhood discovery** only: how to know which neighbors sensed the event with **$O(s)$ messages** in total only?

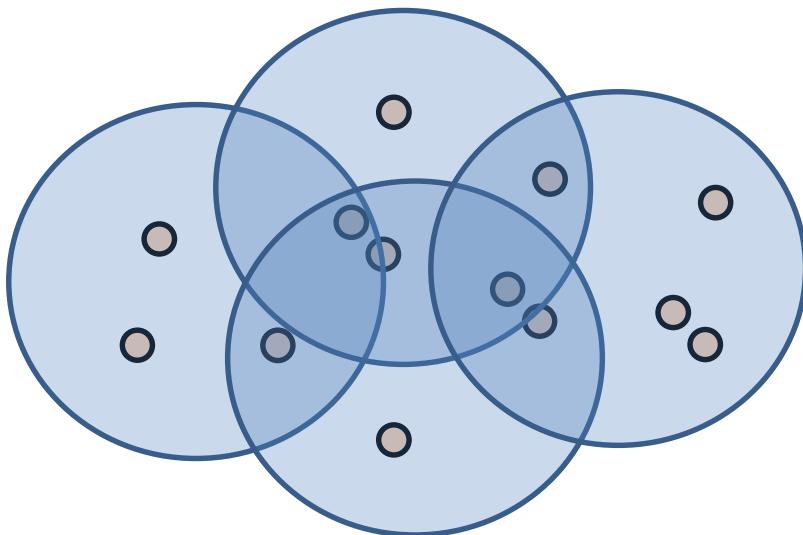
Can we avoid cost n for small components?



Useful Preprocessing For Neighborhood Discovery: Neighborhood Cover



Yes we still can **leverage preprocessing**: graph **decompositions**! (On-duty only.)



E.g., pre-process sparse (k,t) - **neighborhood cover**, clustering ensures that:

- Each **t -neighborhood** included entirely in **at least one cluster**
- Diameter of cluster at most **$O(kt)$**
- Sparse: node part of at most **$kn^{1/k}$** clusters

Idea:

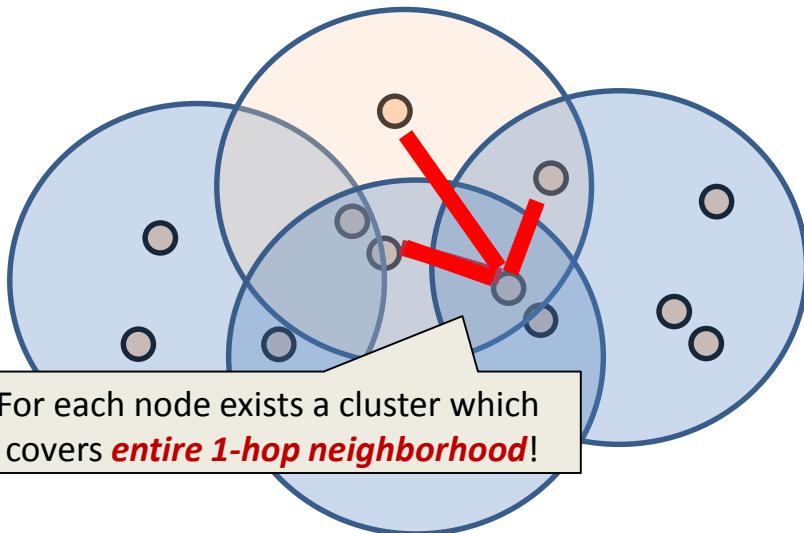
- Preprocess neighborhood cover **$k=\log n$, $t=1$**
- Assign one node per cluster («**cluster head**») collects «**who sensed event**» information
- Since **low diameter**: nodes can send to cluster head in **$\log n$ hops**
- Since **sparse**: Nodes need to send to at most **$\log n$ cluster heads**

Time $O(\log n)$, Message complexity $O(\text{polylog } n)$

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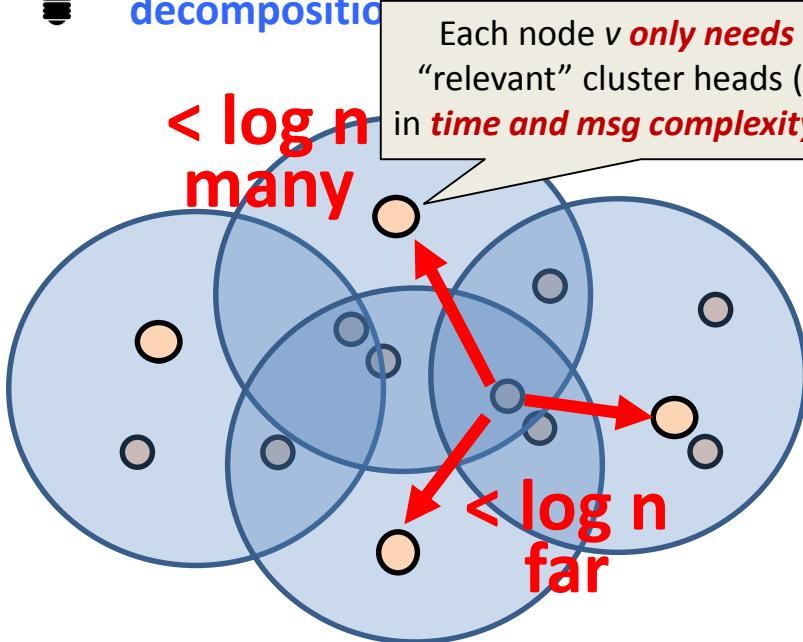
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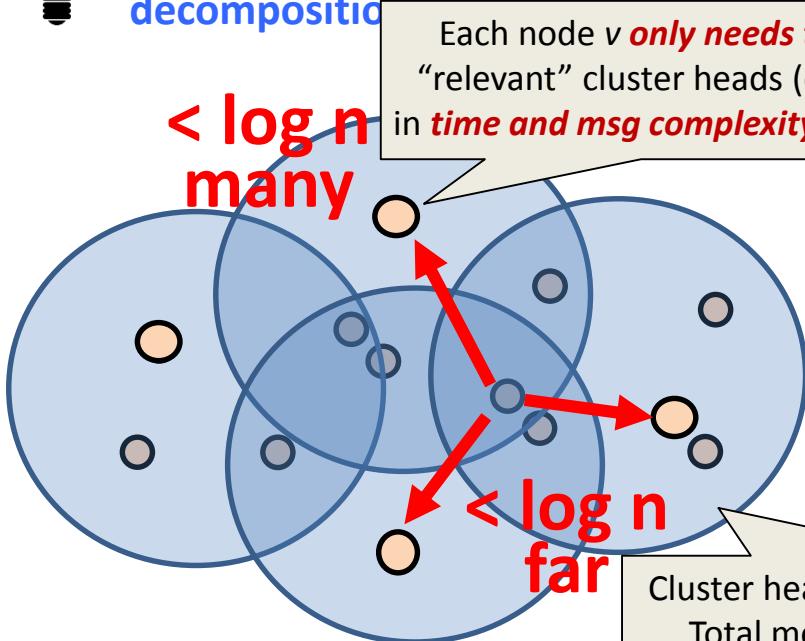
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Useful Preprocessing For Neighborhood Discovery: Neighborhood Cover



Yes we still can **leverage preprocessing**: graph decomposition



Each node v **only needs to inform** “relevant” cluster heads (covering v) in **time and msg complexity $\text{polylog}(n)$** .

E.g., pre-process sparse (k,t) - **neighborhood cover**. clustering ensures that:

Each **t -neighborhood** included entirely in **at least one cluster**

- Diameter of cluster at most $O(kt)$
- Sparse: node part of at most $kn^{1/k}$ clusters

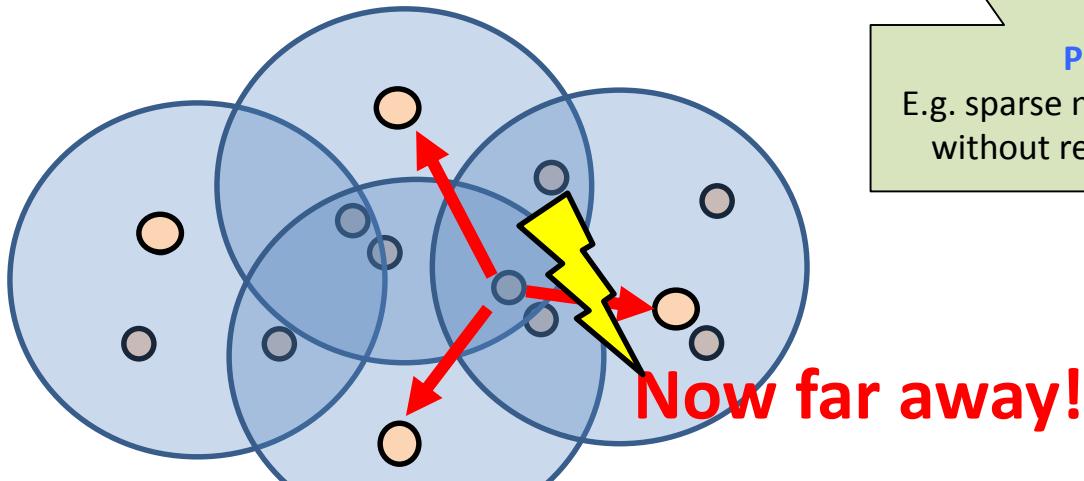
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- Assign one node per cluster («**cluster head**») collects «**who sensed event**» information
- Since **low diameter**: nodes can send to cluster head in **$\log n$ hops**
- Since **sparse**: Nodes need to send to at most **\log**

Cluster heads can **communicate neighborhood**.
Total message complexity in **$O(s \text{ polylog } n)$**
(for neighborhood discovery alone).

complexity $O(\text{polylog } n)$

But what if we cannot use “event nodes”
(e.g., due to smoke/heat)?! Off-duty model!



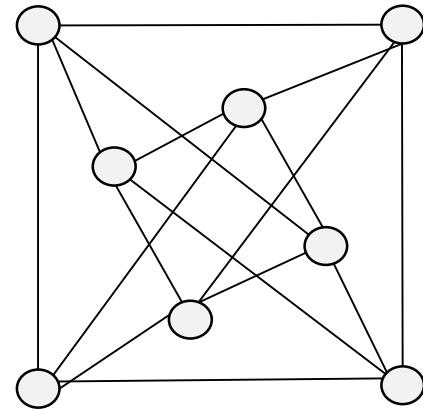
Preprocessing useful at all?

E.g. sparse neighborhood cover *loses properties*:
without relay, cluster head may be *far away*!

Precomputation in Off-Duty Model: Covering Forests

- Consider graph of **arboricity** α
- **Pre-compute** rooted and directed **forests** $\{F_1, \dots, F_\alpha\}$: α forests **covering** the entire original network

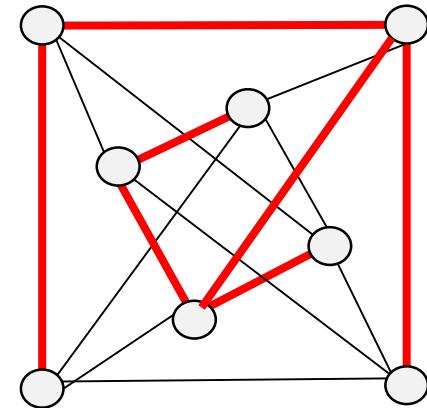
Minimum number of forests
into which graph **edges**
can be partitioned.



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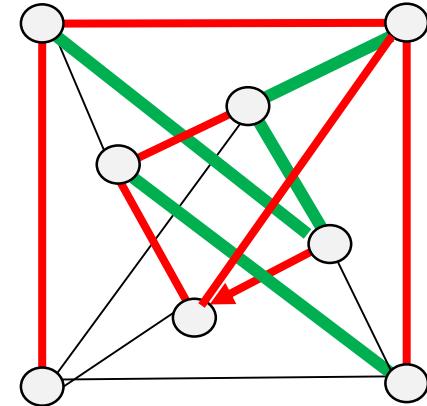


Forest F_1 (a tree)

Precomputation in Off-Duty Model: Covering Forests

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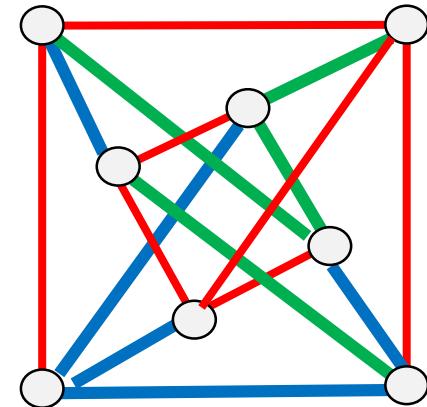


Forest F_2

Precomputation in Off-Duty Model: Covering Forests

- Consider graph of **arboricity** α
- **Pre-compute** rooted and directed **forests** $\{F_1, \dots, F_\alpha\}$: α forests **covering** the entire original network

Minimum number of forests
into which graph **edges**
can be partitioned.



Forest F_3

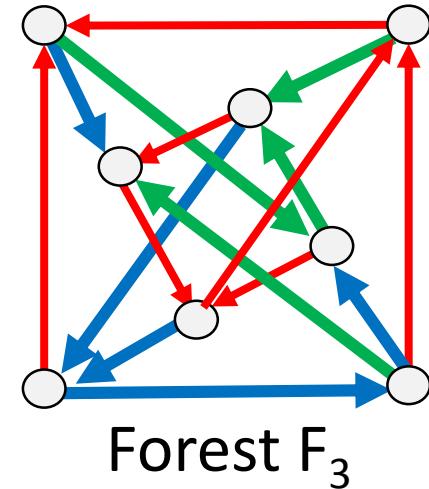
Edge partition!

Precomputation in Off-Duty Model: Covering Forests

- Consider graph of **arboricity** α
- **Pre-compute** rooted and directed **forests** $\{F_1, \dots, F_\alpha\}$: α forests **covering** the entire original network

Minimum number of forests
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Solution to “**neighborhood problem**”: Preprocess forests by making them **rooted and directed**.



Forest F_3

Precomputation in Off-Duty Model: Covering Forests

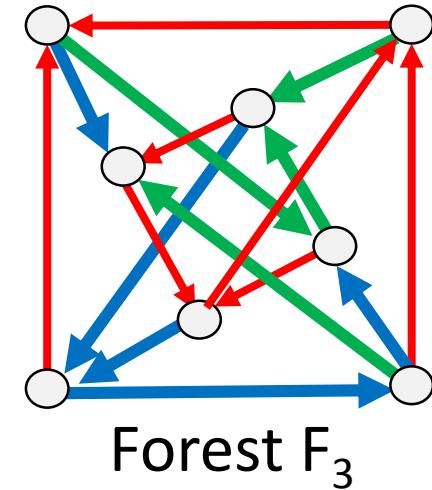
- Consider graph of **arboricity** a
- Pre-compute** rooted and directed **forests** $\{F_1, \dots, F_a\}$: a forests **covering** the entire original network

Minimum number of forests
into which graph **edges**
can be partitioned.

Solution to “**neighborhood problem**”: **Preprocess** forests by making them **rooted and directed**.

- Let P_v be set of all parents of a node in these forests: $|P_v| \leq a$

The clue: degree may be high, but number of parents not!



Precomputation in Off-Duty Model: Covering Forests

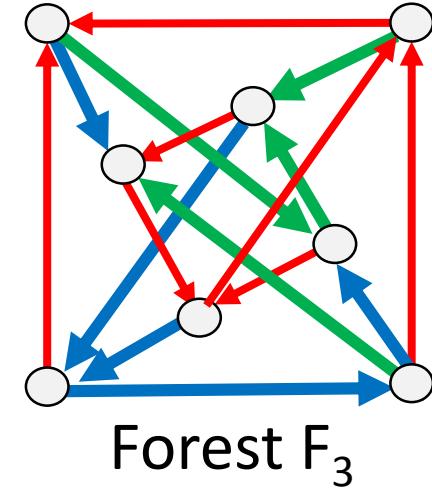
- Consider graph of **arboricity** α
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Solution to “**neighborhood problem**”: **Preprocess** forests by making them **rooted and directed**.

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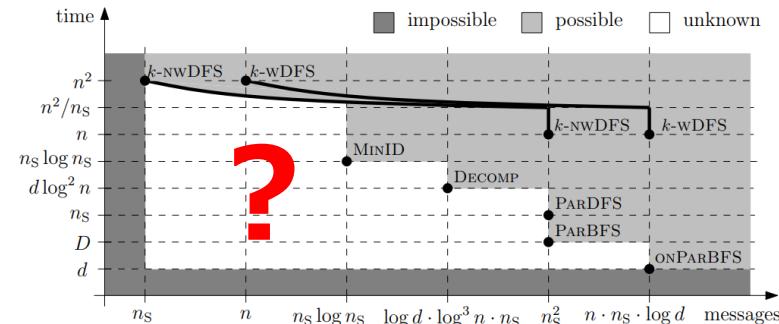
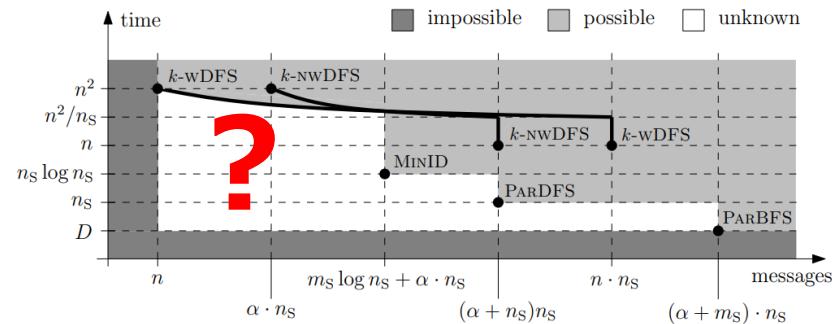
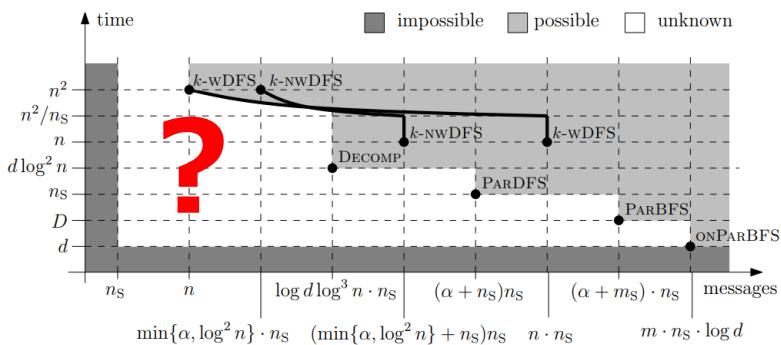


At runtime:

- Each “event node” v sends a **hello message** to all its **neighbors in P_v** (at most $|P_v| \leq \alpha$ many)
 - Those “event nodes” that receive **hello messages** reply in the second round (at most $|P_v| \leq \alpha$ many)
- Since it is a **cover**: each event node either receives a **hello message** **or a reply** from all neighbors that are event nodes, and thus may effectively **learn their neighborhood**.

Many Open Problems

- For distributed disaster size detection alone: On-duty, Off-duty, randomized

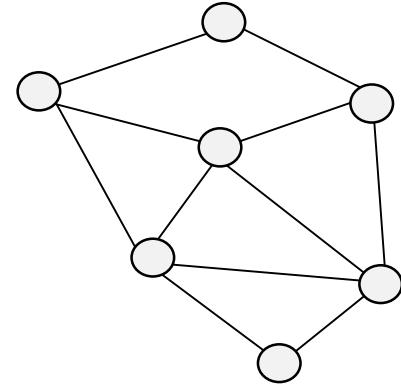


- ... but many other problems!

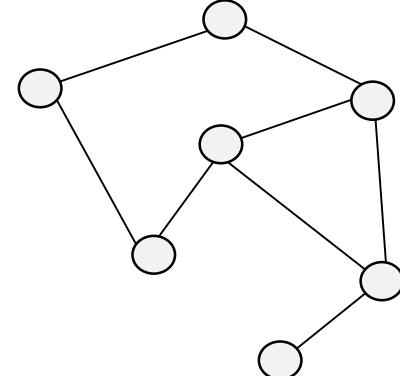
Another Use of Preprocessing: Preparing for Link Failures and “Fast Fixing” (aka. SUPPORTED Model)

- What can we precompute to quickly fix a solution (e.g., coloring, DS, MIS, ...) under link failures?
- Problem has two phases and there are two graphs:
 - **Support graph H**: on which one can do *precomputation*
 - **Input graph $G \subseteq H$** : on which solution should be computed *fast*
- Motivation: **Fast fixing**
 - After failures (induce subgraph), want to fix solution quickly

Support graph H:



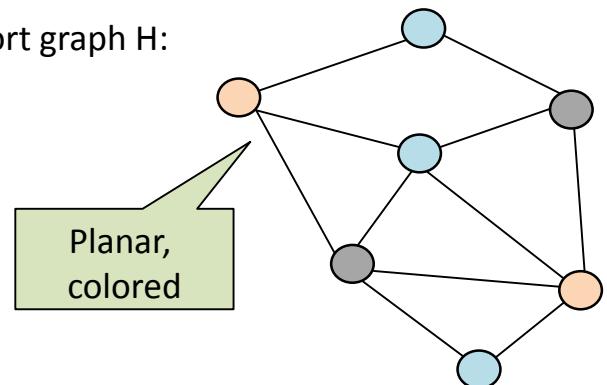
Input graph $G \subseteq H$:



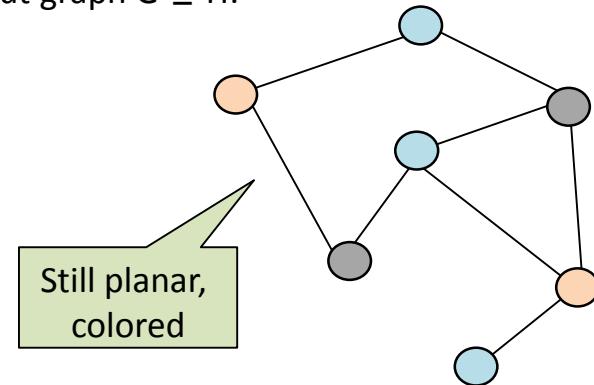
Idea: Exploit Properties That Are Preserved!

- As input graph is subgraph, some **properties remain**:
 - E.g., if it was *sparse/planar/bounded-genus*... it remains
- Consequence: Legal coloring stays legal coloring
 - Can **precompute** it!
- Case study: Czygrinow et al. algorithm to compute $(1+\varepsilon)$ -approx. **MIS** in **non-constant time** in planar graphs
 - First computes **pseudo-forest** in $O(1)$ time
 - Then performs **3-coloring**: allows to find “**heavy-stars**” of constant diameter

Support graph H:



Input graph $G \subseteq H$:



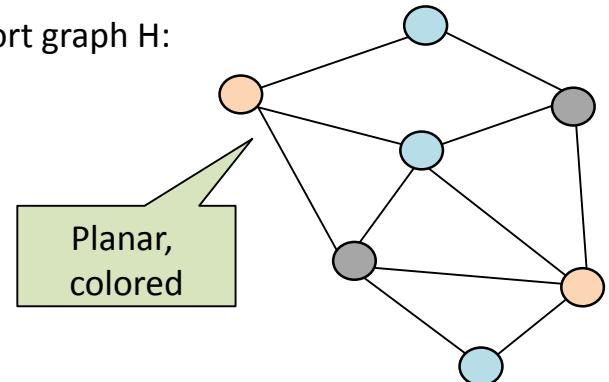
SUPPORTED Model: Some Observations

- As input graph is subgraph, some **properties remain**:
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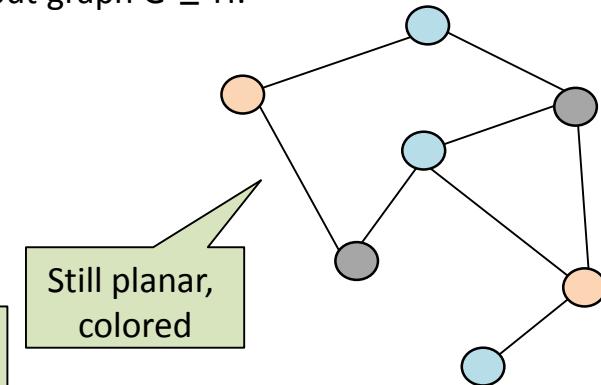


Only non-constant time part. But planar graph 4-colorable (**precomputed**), and can reduce from 4 to 3 colors in **constant time**!

Support graph H:



Input graph $G \subseteq H$:



Distributed Disaster Detection and SUPPORT: Many Open Questions

- Some ***positive results*** for SUPPORT, e.g.,
 - See above: MIS, MaxMatching, MDS can be computed in constant time in **bounded-genus** graphs in SUPPORTED.
 - Many other examples: **Dominating Set** algorithm by Friedman and Kogan consists of two phases: symmetry breaking (distance-2 coloring) and optimization (greedy). In supported model, both phases in $O(1)$.
- Some **lower bounds** can be generalized: (maybe surprising) ***limits*** on what can be achieved with precomputation
- Everything else pretty much ***open***

Further Reading

- [Online Aggregation of the Forwarding Information Base: Accounting for Locality and Churn](#)
Marcin Bienkowski, Nadi Sarrar, Stefan Schmid, and Steve Uhlig.
IEEE/ACM Transactions on Networking (**TON**), 2018.
- [Exploiting Locality in Distributed SDN Control](#)
Stefan Schmid and Jukka Suomela.
ACM SIGCOMM Workshop on Hot Topics in Software Defined Networking
(**HotSDN**), Hong Kong, China, August 2013.

Opportunity: Topology Control for Data-Intensive Networks?

Traditional Networks

- Usually optimized for the “worst-case” (**all-to-all** communication)
- Typical criteria:
 - Classic network design: small **degree**, small **diameter**, high **mincut**
 - Topology control: short routes, contains **min energy path**
- Lower bounds and hard **trade-offs**, e.g., degree vs diameter

Traditional Networks

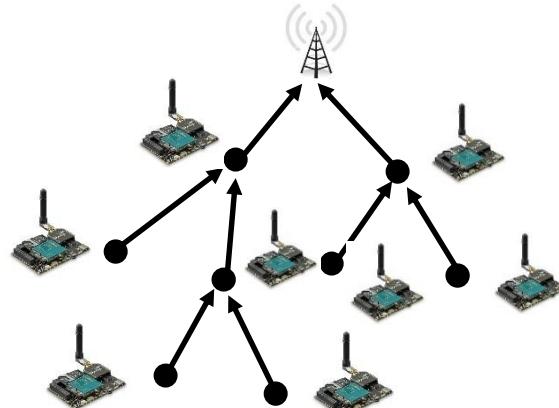
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Data-Intensive Networks

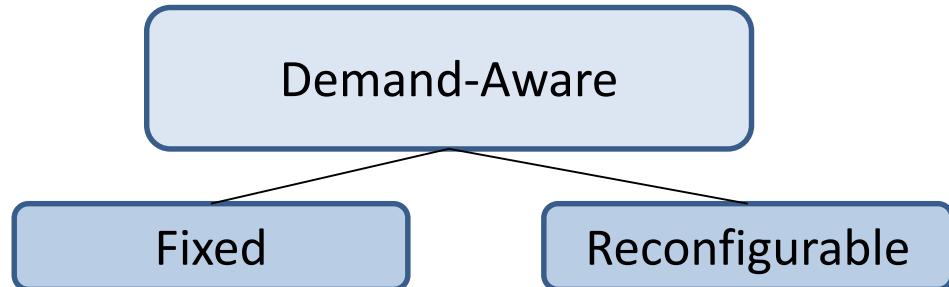
- Recall: not only size of networks grows but also *amount of data*
- At the same time, traffic often has *specific patterns* and is far from all-to-all
 - E.g., all-to-one: **sink node** collects results
 - Also in **datacenter**: *sparse*

Can we make networks more data/demand-aware?



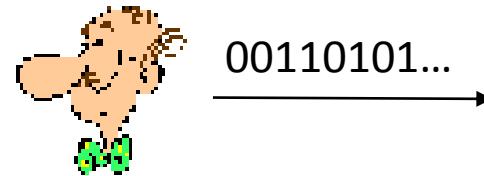
Demand-Aware Networks: 2 Flavors

- **DAN**: Demand-Aware Network
 - Statically optimized **toward the demand**
- **SAN**: Self-Adjusting Network
 - **Dynamically optimized toward** the (time-varying) demand

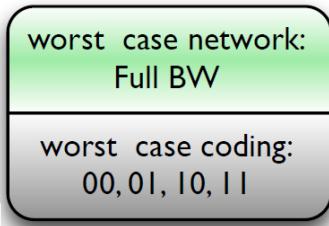


An Analogy to Coding

Coming to ALGOSENSORS?

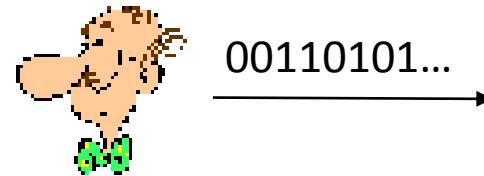


structure: static / future demand: unknown

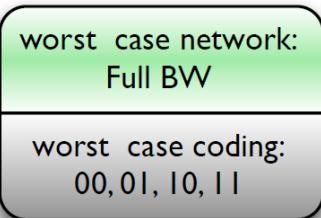


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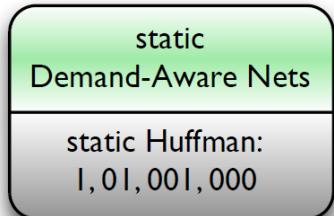


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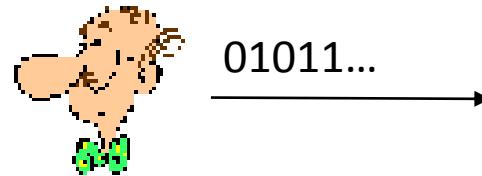
Requires **statistics!**

static / known

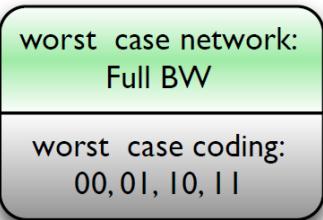


An Analogy to Coding

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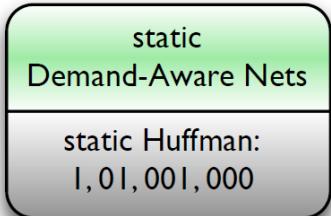


Requires **statistics!**

static / known



DAN!



An Analogy to Coding

Coming to ALGOSENSORS?



101...



Better or worse?

structure: static / future demand: unknown

worst case network:
Full BW

worst case coding:
00, 01, 10, 11

static / known

dynamic / unknown

static
Demand-Aware Nets

static Huffman:
1, 01, 001, 000

dynamic
Demand-Aware Nets

dynamic
Huffman codes

An Analogy to Coding

Coming to ALGOSENSORS?

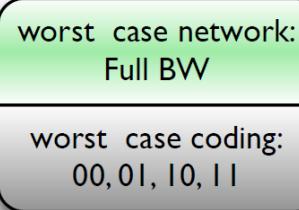


101...

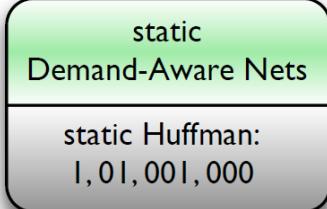


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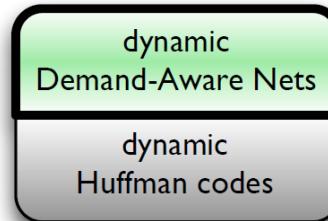
structure: static / future demand: unknown



static / known



dynamic / unknown



It depends:



Can exploit
temporal locality!

But: No statistics:
online!

An Analogy to Coding

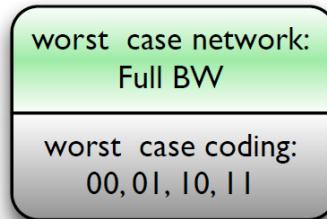
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101...



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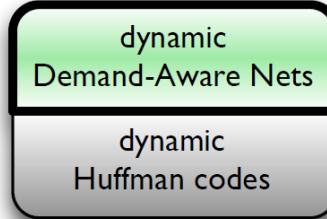
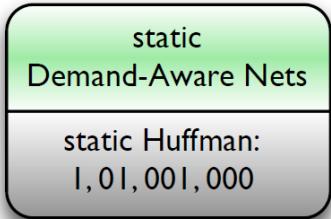
dynamic / unknown



DAN!



Can exploit
spatial locality!



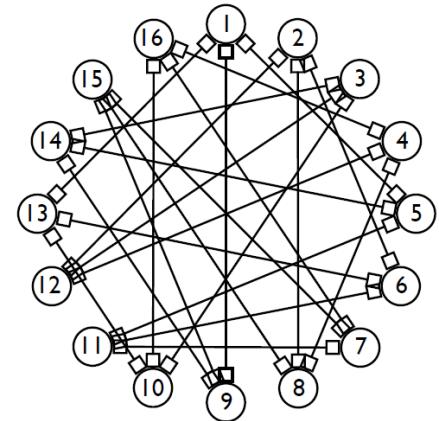
SAN!



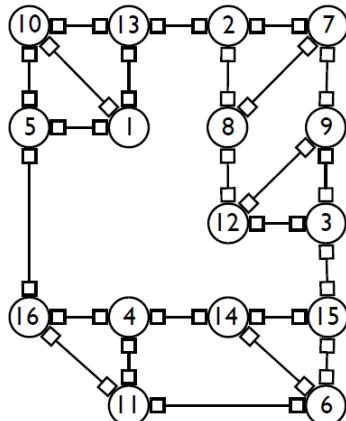
Additionally exploit
temporal locality!

Spectrum of Flexible Networks

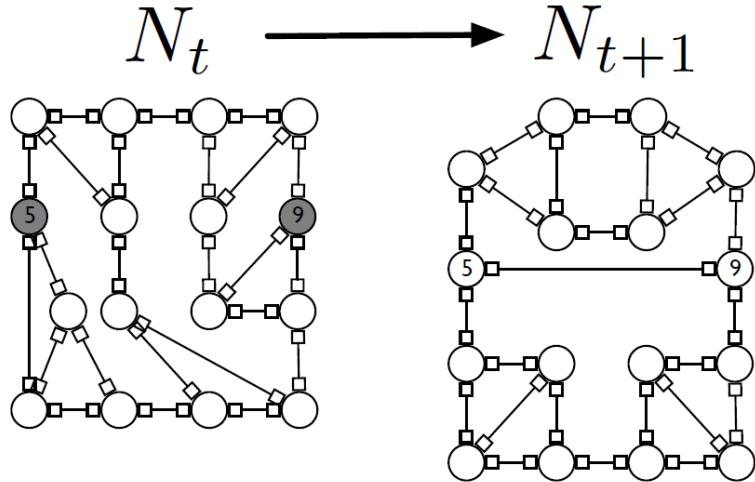
Oblivious



DAN



SAN



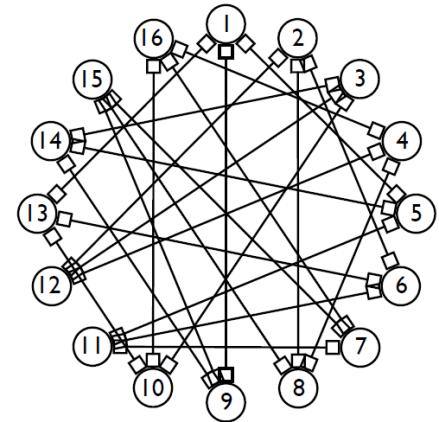
Const degree
(e.g., **expander**):
route lengths $O(\log n)$

Exploit **spatial locality**: Route
lengths ***depend on demand***

Exploit **temporal locality** as well

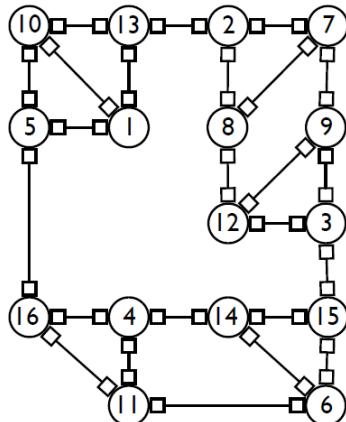
Spectrum of Flexible Networks

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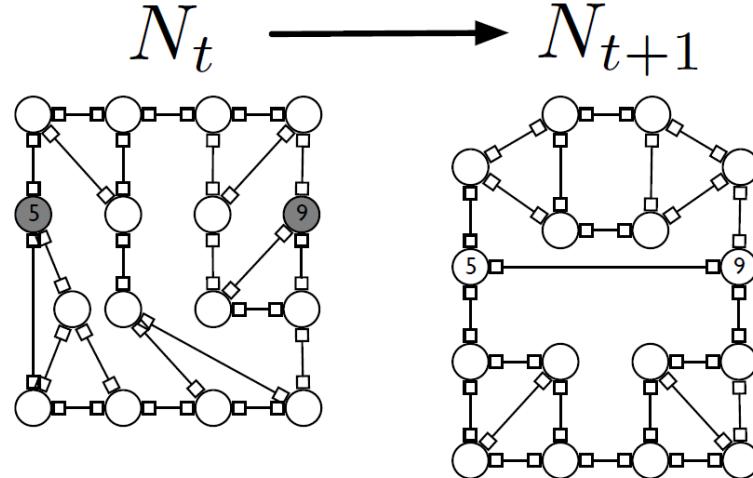
DAN



Exploit **spatial locality**: Route
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Good metric?

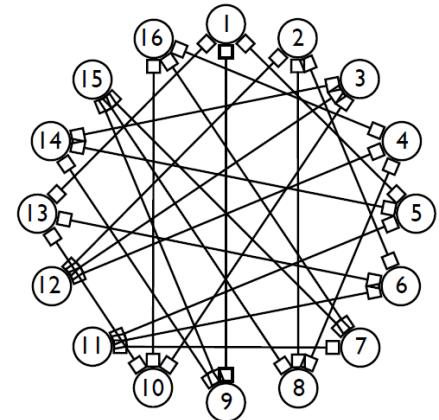
SAN



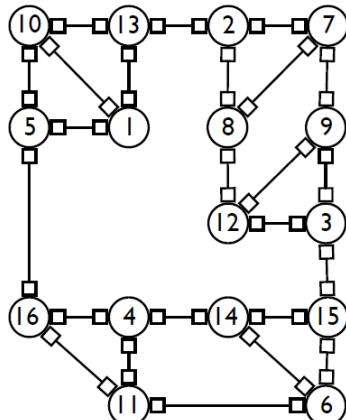
Exploit **temporal locality** as well

Spectrum of Flexible Networks

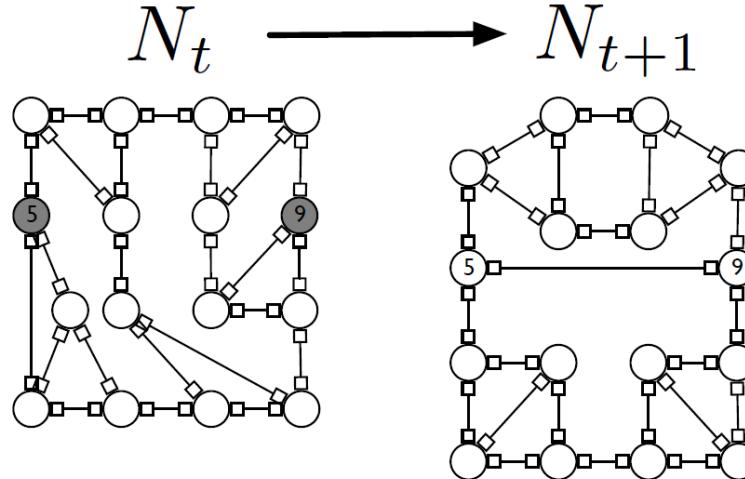
Oblivious



DAN



SAN



Const degree
(e.g., **expander**):
route lengths **$O(\log n)$**

Exploit **spatial locality**: Route
lengths ***depend on demand***

Exploit **temporal locality** as well

Good metric?

e.g., ***entropy***!

Example of A DAN Design Problem

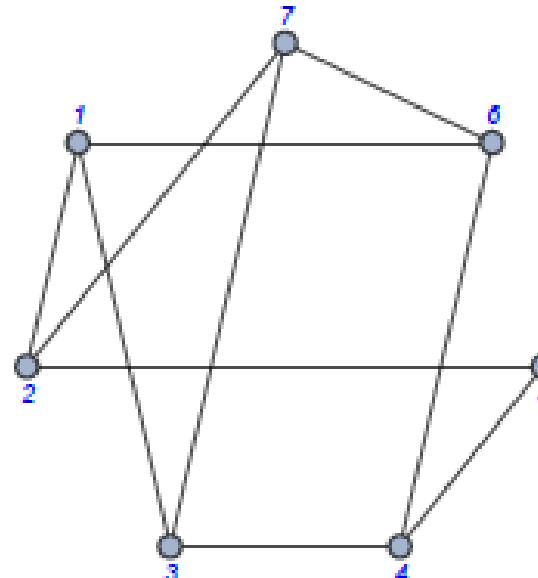
Input: Workload

Destinations

		Destinations						
		1	2	3	4	5	6	7
Sources	1	0	$\frac{2}{65}$	$\frac{1}{13}$	$\frac{1}{65}$	$\frac{1}{65}$	$\frac{2}{65}$	$\frac{3}{65}$
	2	$\frac{2}{65}$	0	$\frac{1}{65}$	0	0	0	$\frac{2}{65}$
	3	$\frac{1}{13}$	$\frac{1}{65}$	0	$\frac{2}{65}$	0	0	$\frac{1}{13}$
	4	$\frac{1}{65}$	0	$\frac{2}{65}$	0	$\frac{4}{65}$	0	0
	5	$\frac{1}{65}$	0	$\frac{3}{65}$	$\frac{4}{65}$	0	0	0
	6	$\frac{2}{65}$	0	0	0	0	0	$\frac{3}{65}$
	7	$\frac{3}{65}$	$\frac{2}{65}$	$\frac{1}{13}$	0	0	$\frac{3}{65}$	0

design

Output: DAN



Demand matrix: joint distribution

... of constant degree (**scalability**)

Example of A DAN Design Problem

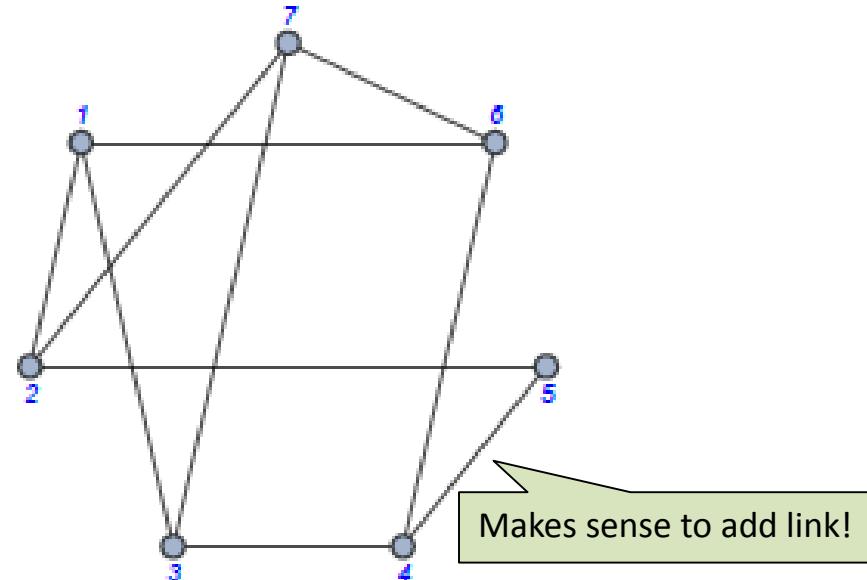
Input: Workload

Destinations

Sources	1	2	3	4	5	6	7
1	0	$\frac{2}{65}$	$\frac{1}{13}$	$\frac{1}{65}$	$\frac{1}{65}$	$\frac{2}{65}$	$\frac{3}{65}$
2	$\frac{2}{65}$	0	$\frac{1}{65}$	0	0	0	$\frac{2}{65}$
3	$\frac{1}{13}$	$\frac{1}{65}$	0	$\frac{2}{65}$	0	$\frac{13}{65}$	0
4	$\frac{1}{65}$	0	$\frac{2}{65}$	0	$\frac{4}{65}$	0	0
5	$\frac{1}{65}$	0	$\frac{3}{65}$	$\frac{4}{65}$	0	0	0
6	$\frac{2}{65}$	0	0	0	0	0	$\frac{3}{65}$
7	$\frac{3}{65}$	$\frac{2}{65}$	$\frac{1}{13}$	0	0	$\frac{3}{65}$	0

design

Output: DAN



Demand matrix: joint distribution

... of constant degree (**scalability**)

Example of A DAN Design Problem

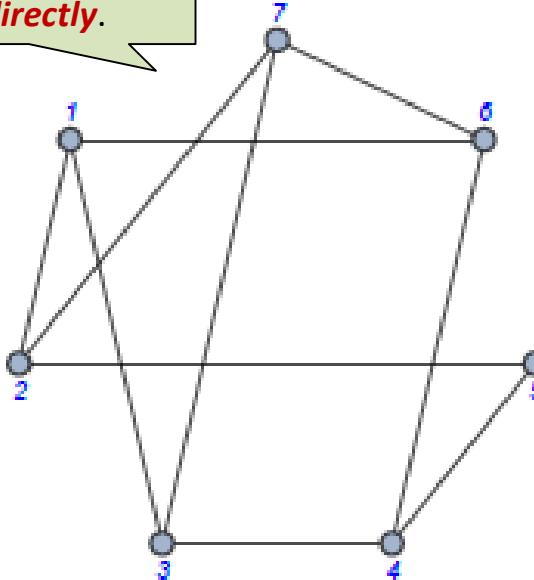
Input: Workload

Destinations								
		1 communicates to many.						
		6	7					
1	0	$\frac{2}{65}$	$\frac{1}{13}$	$\frac{1}{65}$	$\frac{1}{65}$	$\frac{2}{65}$	$\frac{3}{65}$	
2	$\frac{2}{65}$	0	$\frac{1}{65}$	0	0	0	$\frac{2}{65}$	
3	$\frac{1}{13}$	$\frac{1}{65}$	0	$\frac{2}{65}$	0	0	$\frac{1}{13}$	
4	$\frac{1}{65}$	0	$\frac{2}{65}$	0	$\frac{4}{65}$	0	0	
5	$\frac{1}{65}$	0	$\frac{3}{65}$	$\frac{4}{65}$	0	0	0	
6	$\frac{2}{65}$	0	0	0	0	0	$\frac{3}{65}$	
7	$\frac{3}{65}$	$\frac{2}{65}$	$\frac{1}{13}$	0	0	$\frac{3}{65}$	0	

Output: DAN

Bounded degree: route
to 7 *indirectly*.

design



Demand matrix: joint distribution

... of constant degree (**scalability**)

Example of A DAN Design Problem

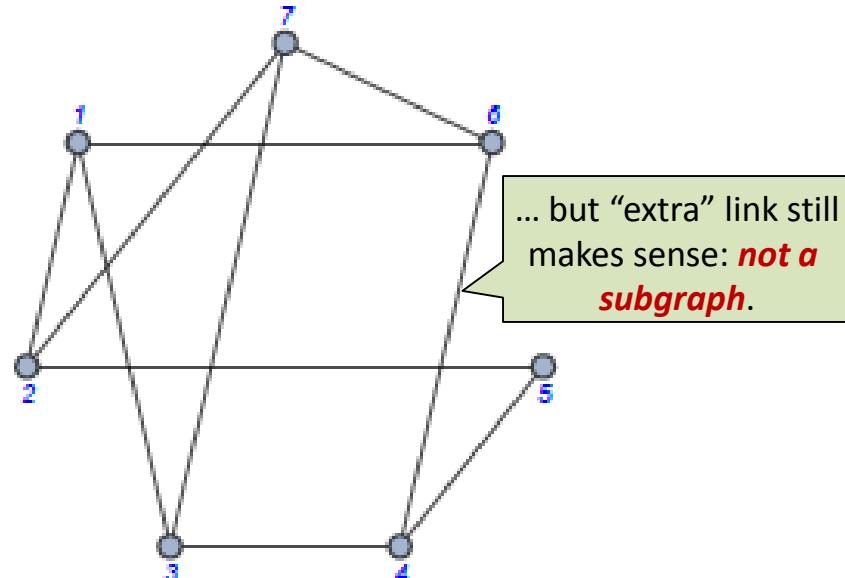
Input: Workload

Destinations

Sources	1	2	3	4	5	6	7
1	0	$\frac{2}{65}$	$\frac{1}{13}$	$\frac{1}{65}$	$\frac{1}{65}$	$\frac{2}{65}$	$\frac{3}{65}$
2	$\frac{2}{65}$	0	$\frac{1}{65}$	0	0	0	$\frac{2}{65}$
3	$\frac{1}{13}$	$\frac{1}{65}$	0	$\frac{2}{65}$	0	0	$\frac{1}{13}$
4	$\frac{1}{65}$	0	$\frac{2}{65}$	0	$\frac{4}{65}$	0	0
5	$\frac{1}{65}$	0	$\frac{3}{65}$	$\frac{4}{65}$	0		
6	$\frac{2}{65}$	0	0	0	0		
7	$\frac{3}{65}$	$\frac{2}{65}$	$\frac{1}{13}$	0	0	$\frac{3}{65}$	0

design

Output: DAN



Demand matrix: joint distribution

... of constant degree (**scalability**)

More Formally: DAN Design Problem

Input:

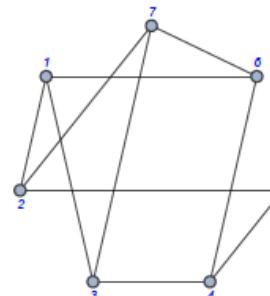
$\mathcal{D}[p(i, j)]$: joint distribution, Δ

		Y						
		1	2	3	4	5	6	7
X	1	0	<u>2</u>	<u>1</u>	<u>1</u>	<u>1</u>	<u>2</u>	<u>3</u>
	2	<u>2</u>	0	<u>1</u>	0	0	0	<u>2</u>
	3	<u>1</u>	<u>1</u>	0	<u>2</u>	0	0	<u>1</u>
	4	<u>1</u>	0	<u>2</u>	0	<u>4</u>	0	0
	5	<u>1</u>	0	<u>3</u>	<u>4</u>	0	0	0
	6	<u>2</u>	0	0	0	0	0	<u>3</u>
	7	<u>3</u>	<u>2</u>	<u>1</u>	0	0	<u>3</u>	0



Output:

N: DAN



Bounded degree $\Delta = 3$

Expected Path Length (EPL): Basic measure of efficiency

Path length *on DAN*.

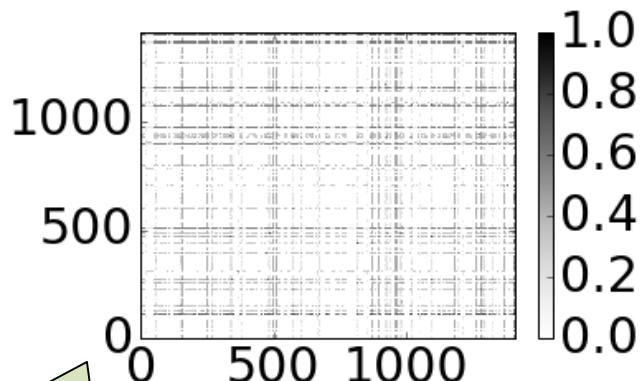
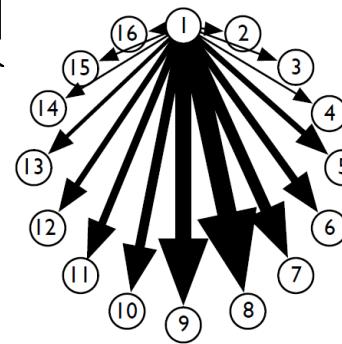
$$\text{EPL}(\mathcal{D}, N) = E_{\mathcal{D}}[d_N(\cdot, \cdot)] = \sum_{(u,v) \in \mathcal{D}} p(u, v) \cdot d_N(u, v)$$

Frequency

Good Metrics for DANs?

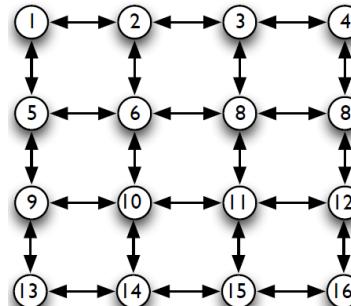
- Clique communication (**all-to-all**) is hard:
nothing to exploit
- But what about such traffic patterns:

Skewed!



Spatial locality!

or

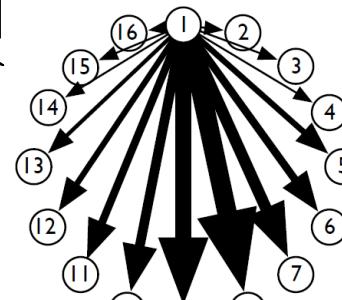


Structure!

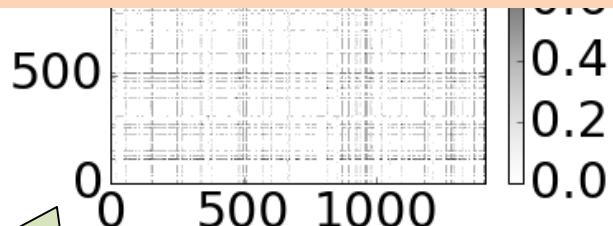
Good Metrics for DANs?

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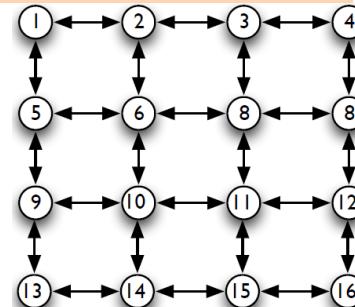
Skewed!



These traffic matrices have low **entropy**: allows
for excellent demand-aware networks!

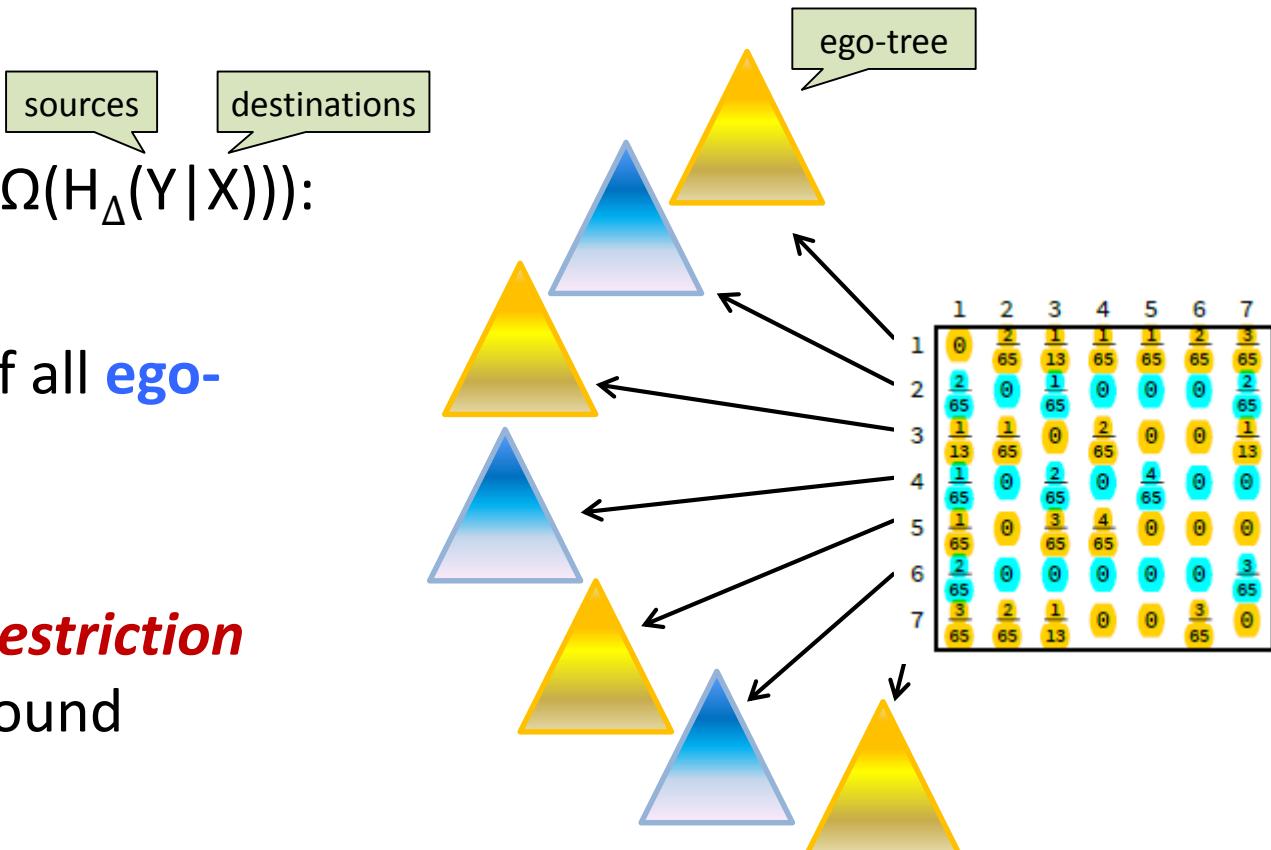


Spatial locality!



Indeed: Entropy is a Lower Bound (Sources)

- Proof idea ($EPL = \Omega(H_{\Delta}(Y|X))$):
- Consider *union* of all ego-trees
- Violates *degree restriction* but valid lower bound



Lower Bound: Sources + Destinations

Do this in **both dimensions**:

$$\text{EPL} \geq \Omega(\max\{\mathsf{H}_\Delta(Y|X), \mathsf{H}_\Delta(X|Y)\})$$

$\Omega(\mathsf{H}_\Delta(X Y))$						
1	2	3	4	5	6	7
1	0 65	$\frac{2}{65}$ 13	$\frac{1}{65}$ 65	$\frac{1}{65}$ 65	$\frac{2}{65}$ 65	$\frac{3}{65}$
2	$\frac{2}{65}$ 65	0 65	$\frac{1}{65}$ 0	0 0	0 0	$\frac{2}{65}$ 65
3	$\frac{1}{13}$ 65	$\frac{1}{65}$ 0	0 65	$\frac{2}{65}$ 0	0 0	$\frac{1}{13}$
4	$\frac{1}{65}$ 65	0 65	$\frac{2}{65}$ 0	0 65	0 0	0 0
5	$\frac{1}{65}$ 65	0 65	$\frac{3}{65}$ 65	$\frac{4}{65}$ 65	0 0	0 0
6	$\frac{2}{65}$ 65	0 65	0 13	0 0	0 0	$\frac{3}{65}$ 0
7	$\frac{3}{65}$ 65	$\frac{2}{65}$ 65	$\frac{1}{13}$ 13	0 0	$\frac{3}{65}$ 65	0 0

\mathcal{D}

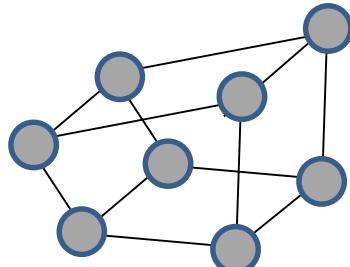
Problem Related To...:

- Sparse, distance-preserving (low-distortion) **spanners**
- But:
 - Spanners aim at low distortion among ***all pairs***; in our case, we are only interested in the ***local distortion***, 1-hop communication neighbors
 - We allow **auxiliary edges** (not a subgraph): similar to **geometric spanners**
 - We require ***constant degree***
- Nevertheless: we can sometimes ***leverage the connection*** to spanners!

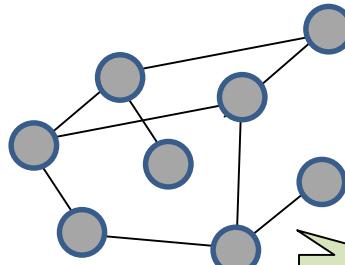
Leveraging The Connection to Spanners

Theorem: If request distribution \mathcal{D} is **regular and uniform**, and if we can find a constant distortion, linear sized (i.e., **constant, sparse**) spanner for this request graph: can design a constant degree DAN providing an ***optimal expected path length*** (i.e., $O(H(X|Y) + H(Y|X))$).

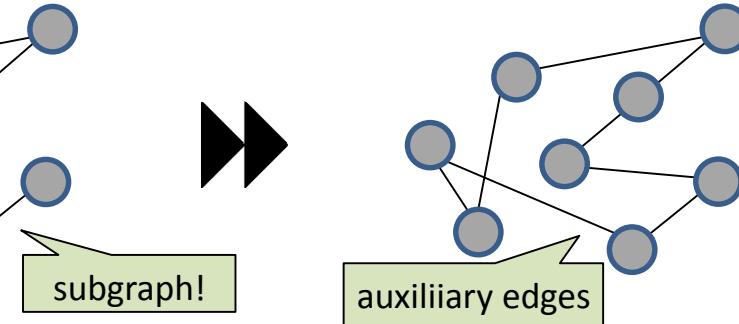
*r-regular and uniform
request:*



*Sparse, irregular
(constant) spanner:*



*Constant degree optimal
DAN (EPL at most $\log r$):*

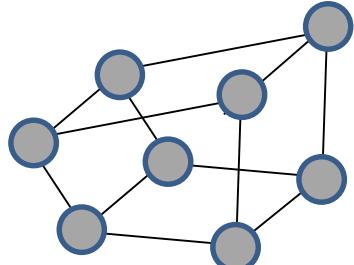


Leveraging The Conn...rs

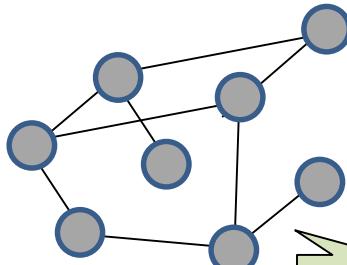
By taking the union of “ego-trees” and balance degrees.

Theorem: If request distribution \mathcal{D} is **regular and uniform**, and if we can find a constant distortion, linear sized (i.e., **constant, sparse**) spanner for this request graph: can design a constant degree DAN providing an ***optimal expected path length*** (i.e., $O(H(X|Y) + H(Y|X))$).

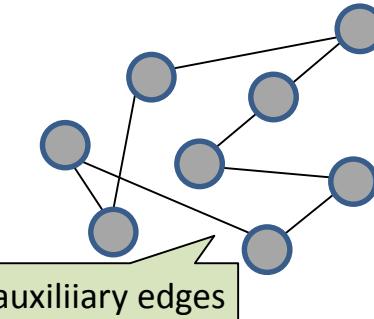
r-regular and uniform request:



Sparse, irregular (constant) spanner:



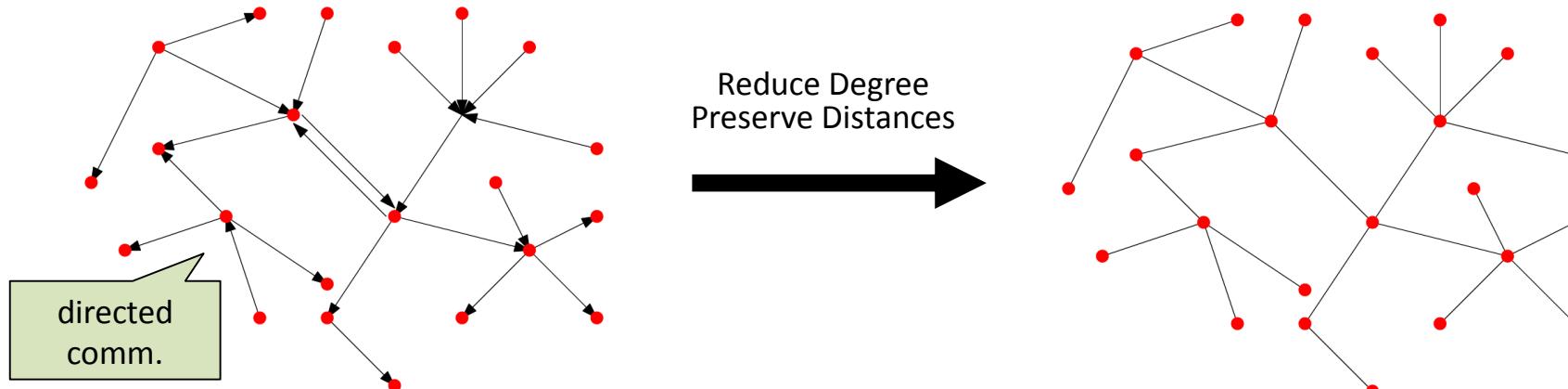
Constant degree optimal DAN (EPL at most log r):



Proof Intuition: How to Balance Degrees

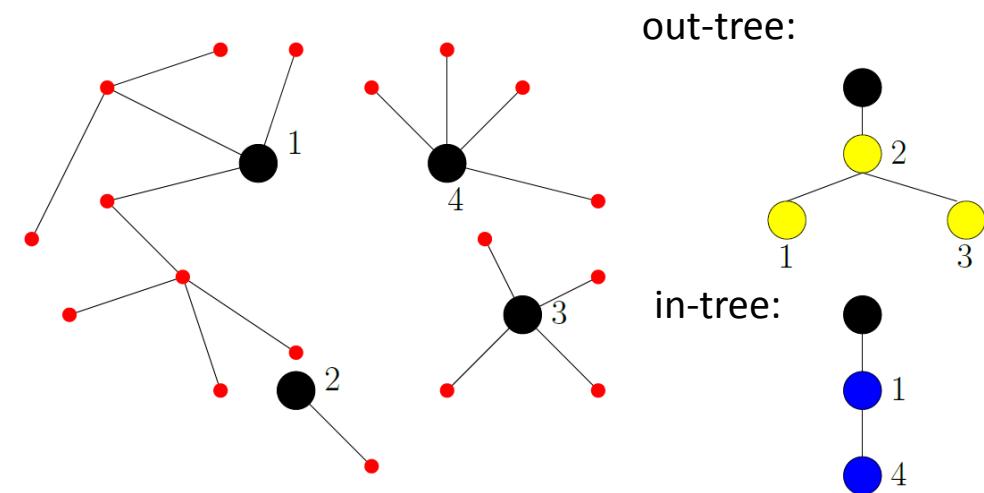
Example: Tree Distributions

- Basic idea to get from irregular spanner to constant-degree tree of low distortion:



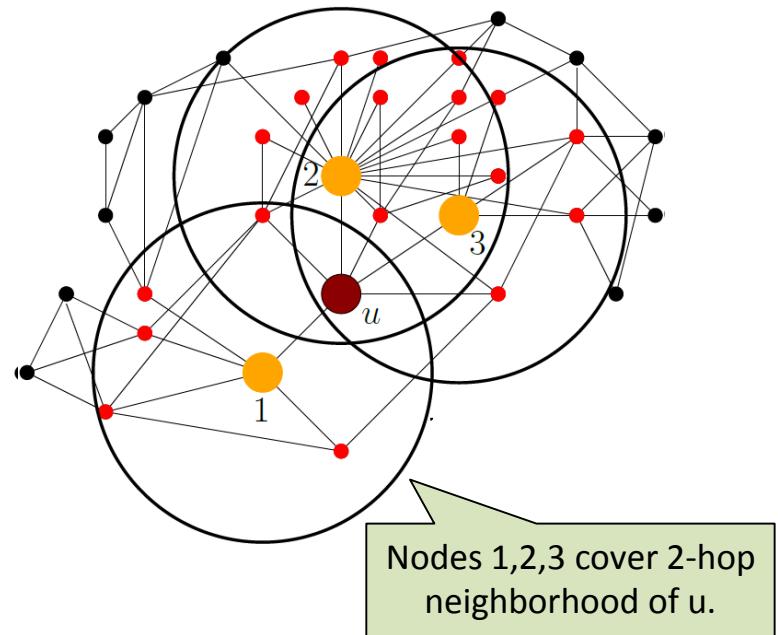
Proof Idea: Construct Huffman Trees

- Make tree **rooted** and directed: gives **parent-child** relationship
- Arrange the outgoing edges (to children) of each node in a **binary (Huffman) tree**
- Repeat for the incoming edges: make another **another binary (Huffman) tree** with incoming edges from children
- Analysis
 - Can **appear in at most 4 trees**: in&out own tree and in&out tree of parent (parent-child helps to avoid many “children trees”)
 - **Degree** at most $4 \times 3 = 12$
 - Huffman trees maintain **distortion**: proportional to **conditional entropy**



Example: Constant-Sparse Spanner for Demands of Locally-Bounded Doubling Dimension

- LDD: G_{\emptyset} has a **Locally-bounded Doubling Dimension** (LDD) iff all 2-hop neighbors are covered by 1-hop neighbors of just λ nodes
 - Note: care only about **2-neighborhood**
- We only consider 2 hops!
- Formally, $B(u, 2) \subseteq \bigcup_{i=1}^{\lambda} B(v_i, 1)$
- Note: LDD graph can still be of **high degree**!



DAN for Locally-Bounded Doubling Dimension

Lemma: There exists a sparse 9-(subgraph)spanner for LDD.

This *implies optimal DAN*: still focus on regular and uniform!

Def. (ε -net): A subset V' of V is a **ε -net** for a graph $G = (V, E)$ if

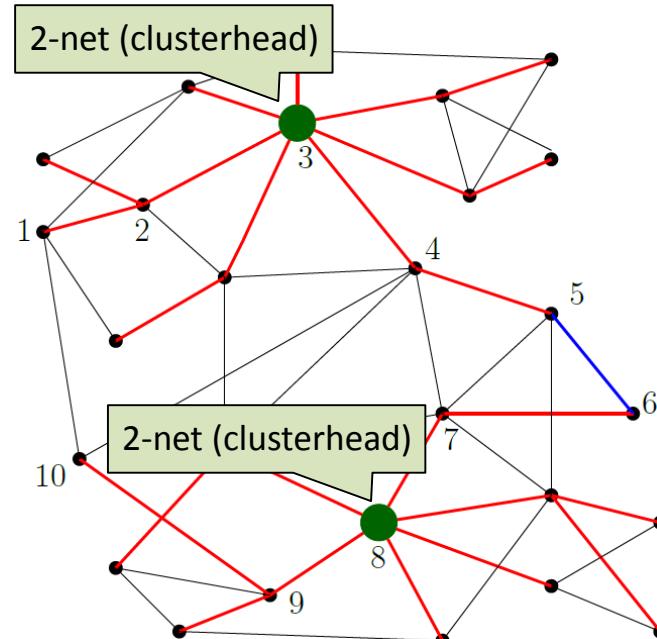
- V' sufficiently “**independent**”: for every $u, v \in V'$, $d_G(u, v) > \varepsilon$
- “**dominating**” V : for each $w \in V$, \exists at least one $u \in V'$ such that, $d_G(u, w) \leq \varepsilon$

9-Spanner for LDD (= optimal DAN)

Simple algorithm:

1. Find a 2-net

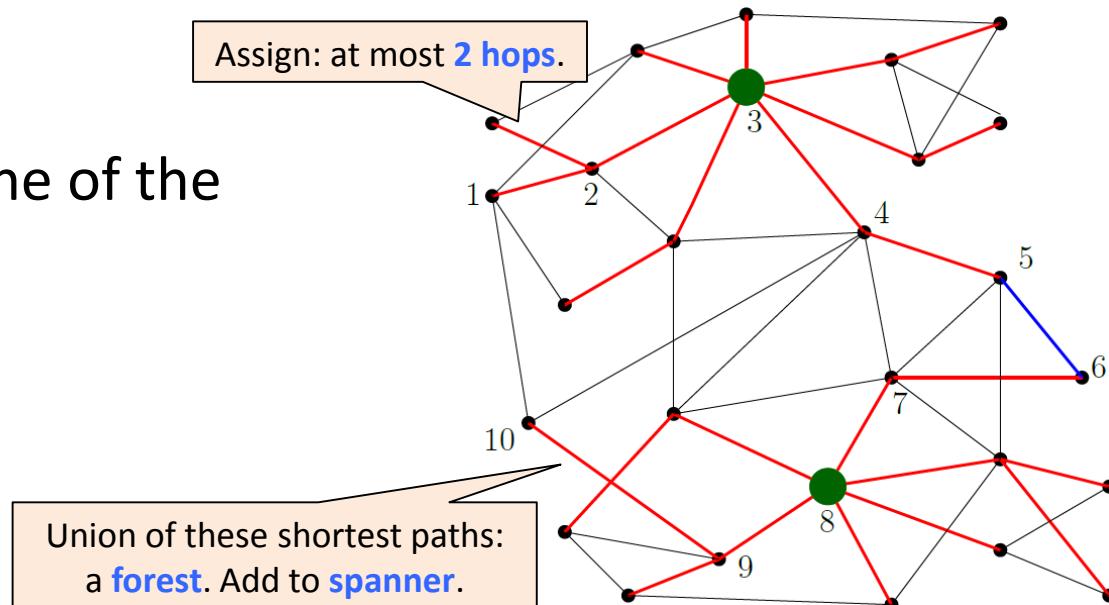
Easy: Select nodes into 2-net **one-by-one** in decreasing (remaining) degrees, **remove 2-neighborhood**. Iterate.



9-Spanner for LDD (= optimal DAN)

Simple algorithm:

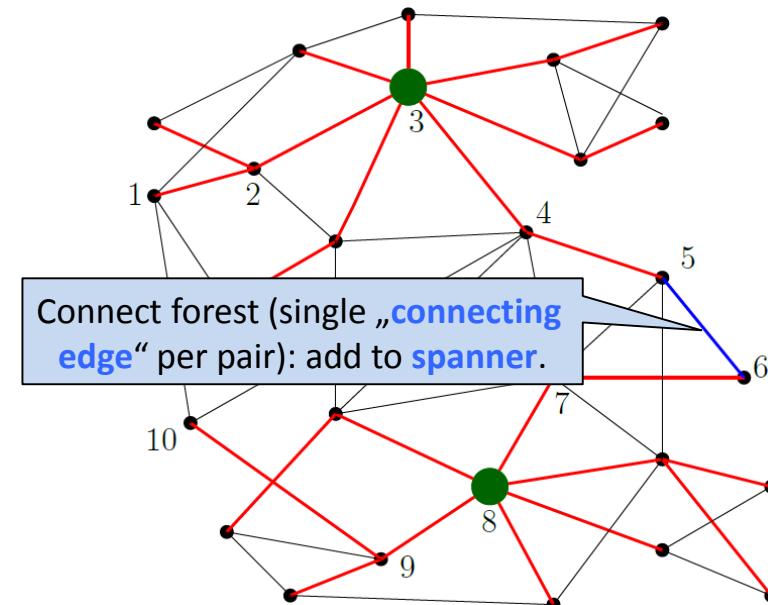
1. Find a 2-net
2. Assign nodes to one of the closest 2-net nodes



9-Spanner for LDD (= optimal DAN)

Simple algorithm:

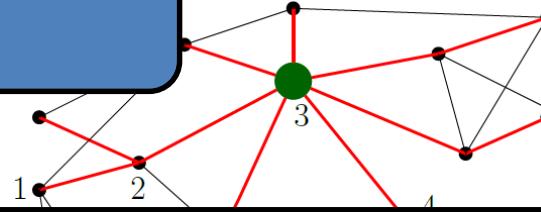
1. Find a 2-net
2. Assign nodes to one of the closest 2-net nodes
3. Join two clusters if there are edges in between



9-Spanner for LDD (= optimal DAN)



Distortion 9: Detour via clusterheads and bridge:
from u to v via $u, ch(u), x, y, ch(v), v$



1. Find a 2-net
2. Assign nodes to one of the
closest 2-net nodes

3. Join two clusters
edges in between

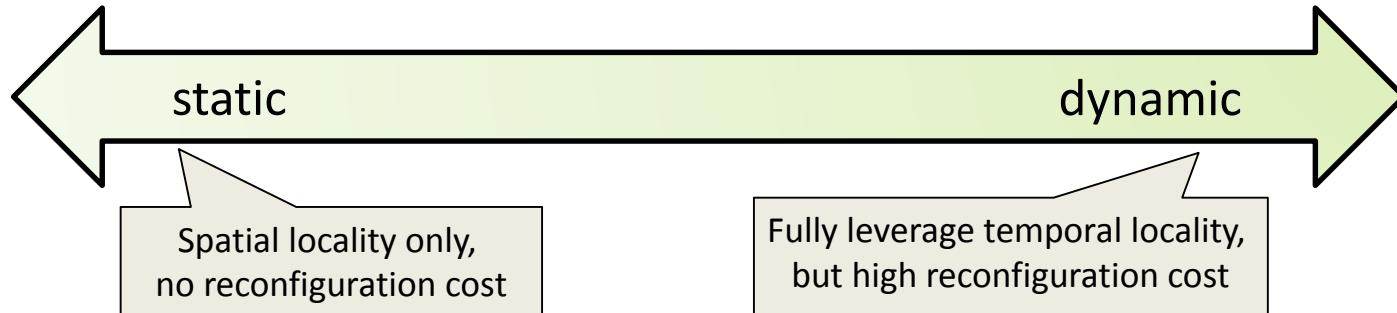
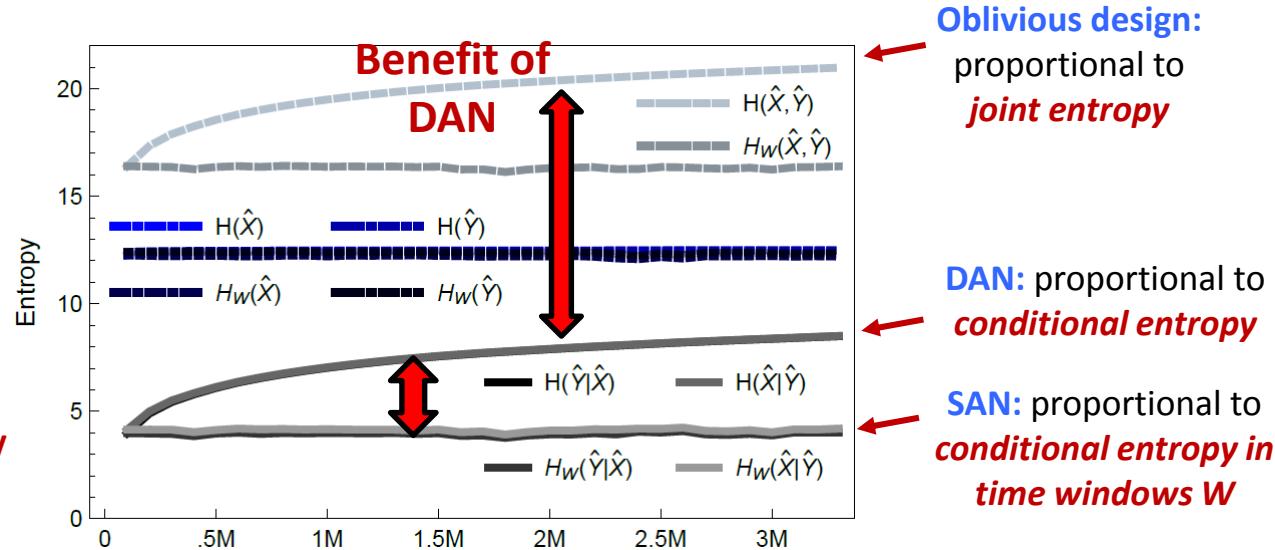


Sparse: Spanner only includes forest (sparse) **plus**
“connecting edges”: but since in a locally doubling
dimension graph the **number of cluster heads at
distance 5 is bounded**, only a small number of
neighboring clusters will communicate.



Flexibility: How Often to Reconfigure?

Benefit of SAN
(if we change every
100k requests)



What About Distributed Algos?

- What about **geometric** demand-aware graphs to connect robots in a plane?
- What about **distributed** algorithms for self-adjusting networks?
- Can we additionally provide **self-stabilizing** properties?
- **A (general?) technique:** each node repeatedly computes “correct graph” **on neighbors** only: seems to be powerful but open question...

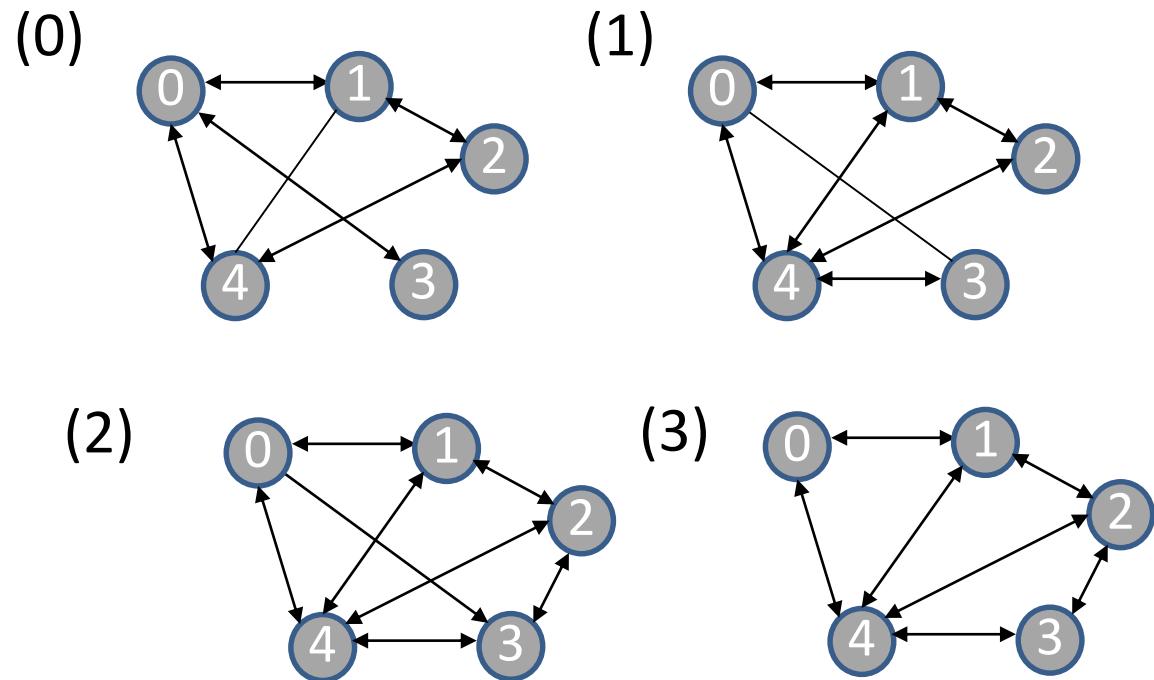
Example: Delaunay Graph

Slightly simplified:

Distributed Algo

1. Compute local
Delaunay
2. Goto 1.

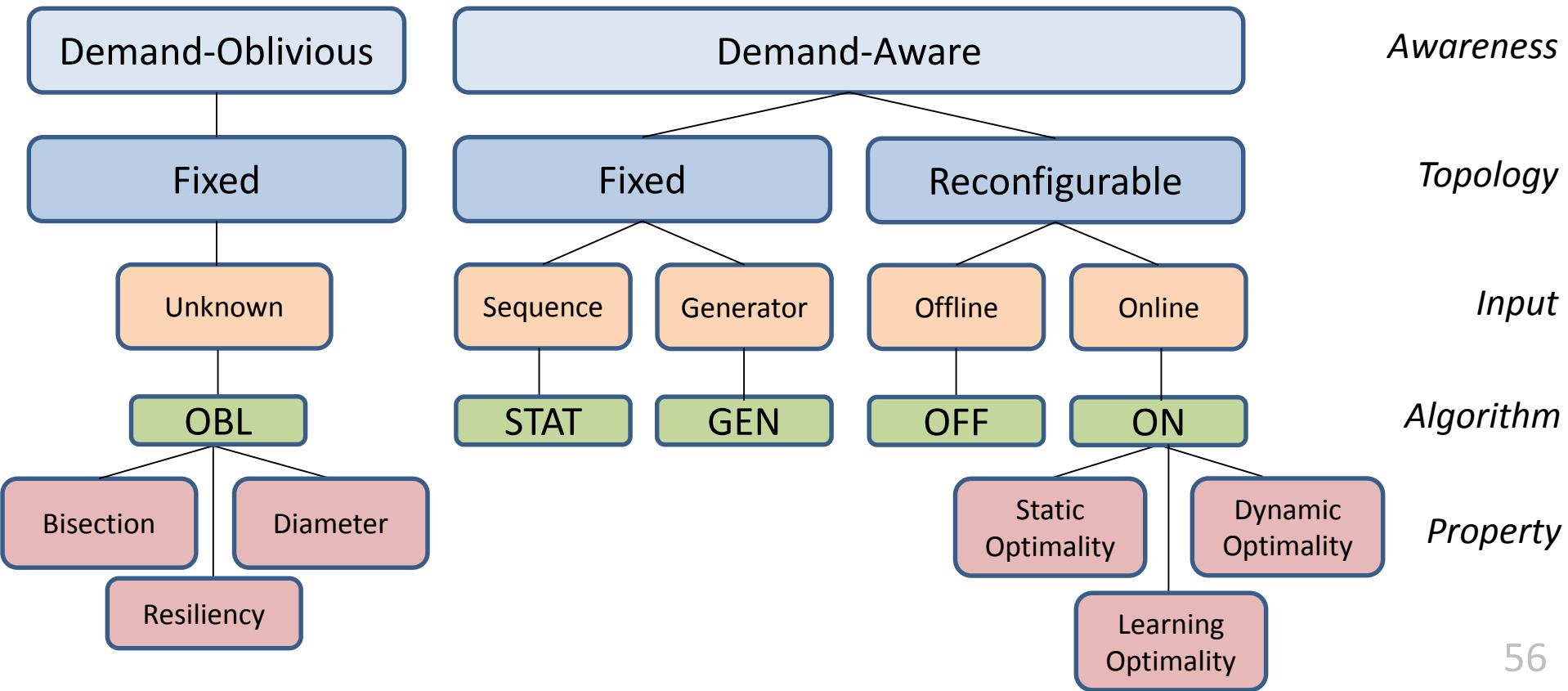
Converges to global
Delaunay graph!



How to generalize to DANs?

Taxonomy

Toward Demand-Aware Networking: A Theory for
Self-Adjusting Networks. ArXiv 2018.



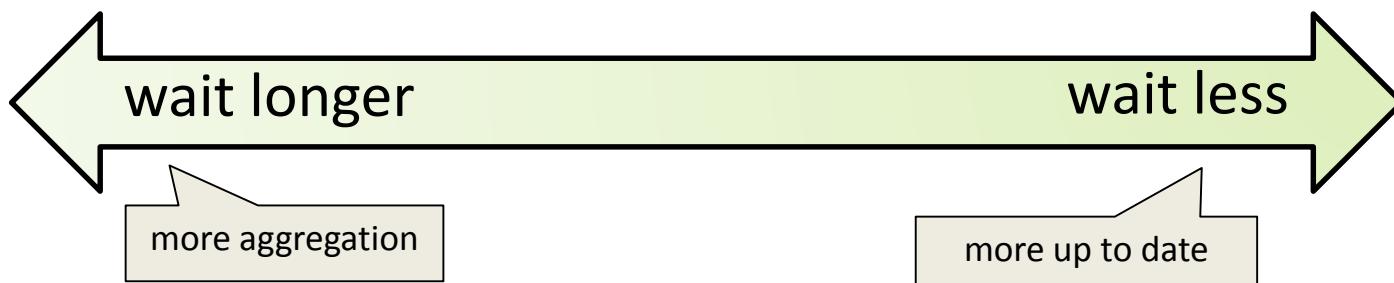
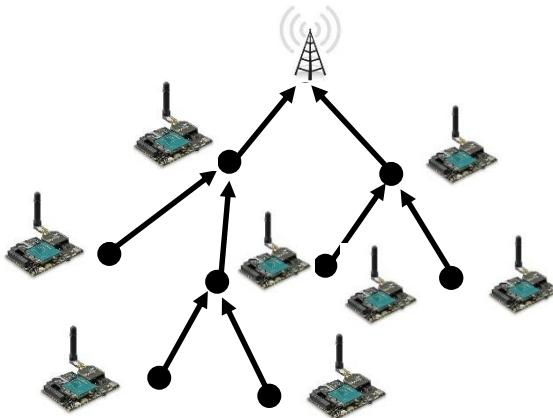
Further Reading

- [Toward Demand-Aware Networking: A Theory for Self-Adjusting Networks](#)
Chen Avin and Stefan Schmid.
ArXiv Technical Report, July 2018.
- [Demand-Aware Network Designs of Bounded Degree](#)
Chen Avin, Kaushik Mondal, and Stefan Schmid.
31st International Symposium on Distributed Computing (**DISC**), Vienna, Austria, October 2017.
- [SplayNet: Towards Locally Self-Adjusting Networks](#)
Stefan Schmid, Chen Avin, Christian Scheideler, Michael Borokhovich, Bernhard Haeupler, and Zvi Lotker.
IEEE/ACM Transactions on Networking (**TON**), Volume 24, Issue 3, 2016. Early version: IEEE **IPDPS** 2013.
- [Characterizing the Algorithmic Complexity of Reconfigurable Data Center Architectures](#)
Klaus-Tycho Foerster, Monia Ghobadi, and Stefan Schmid.
ACM/IEEE Symposium on Architectures for Networking and Communications Systems (**ANCS**), Ithaca, New York, USA, July 2018.

Opportunity: Scheduling

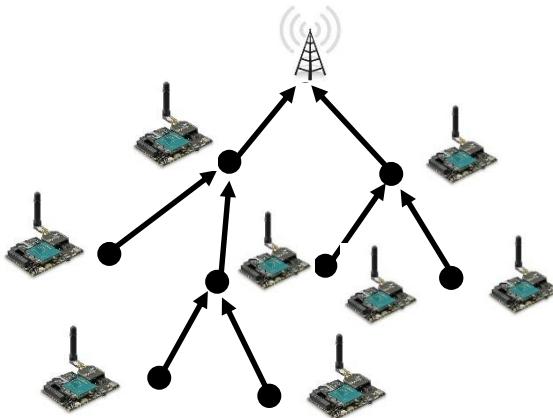
Many Networks Are Delay-Tolerant: Introduces Flexibility “Wait or Proceed”?

e.g., online
aggregation:

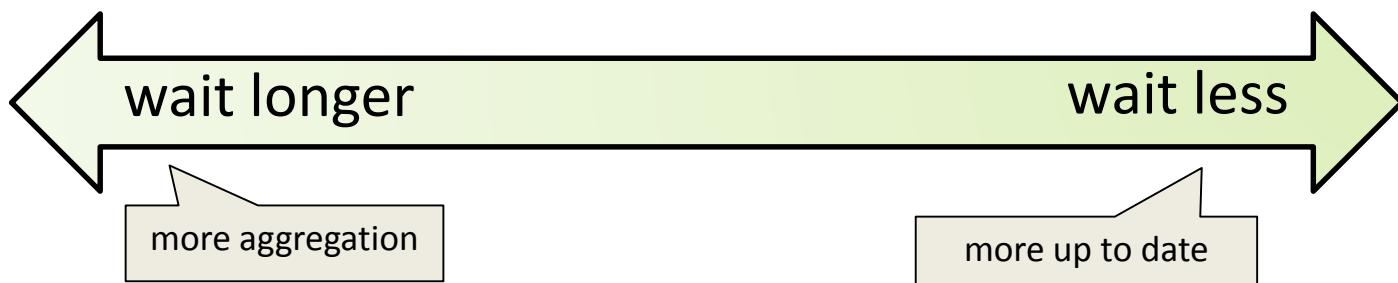


Many Networks Are Delay-Tolerant: Introduces Flexibility “Wait or Proceed”?

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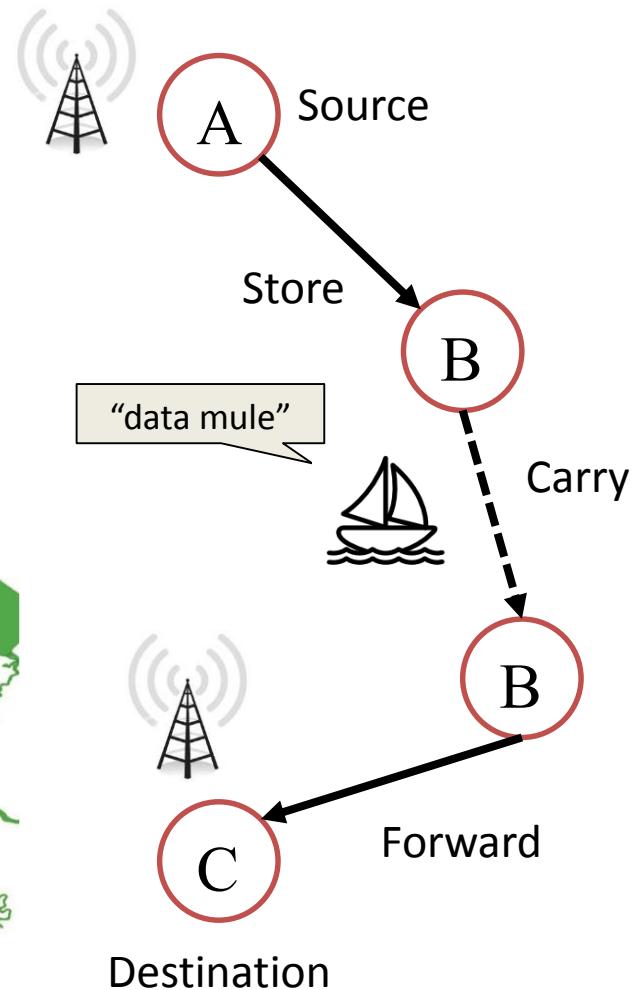
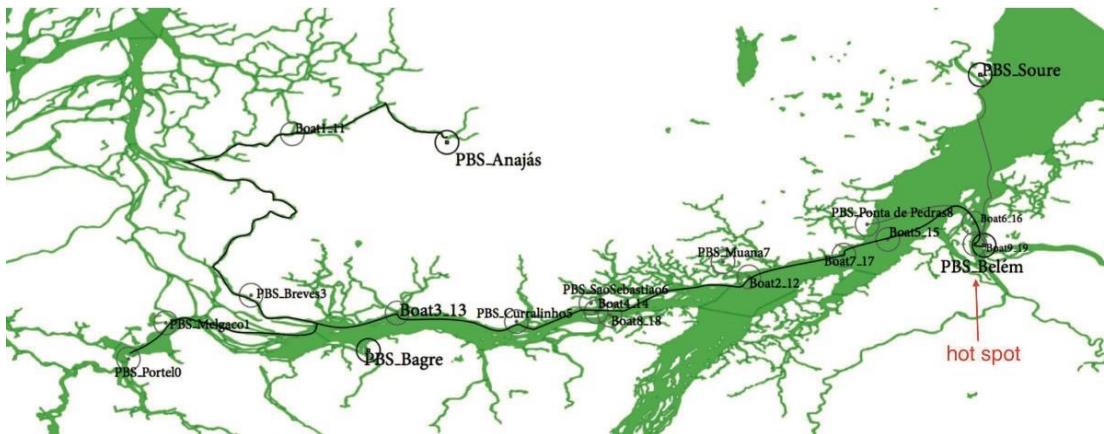


Little known today about
*scheduling in delay
tolerant networks.*



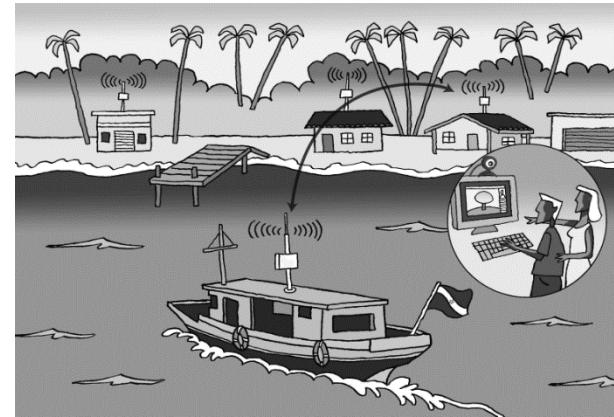
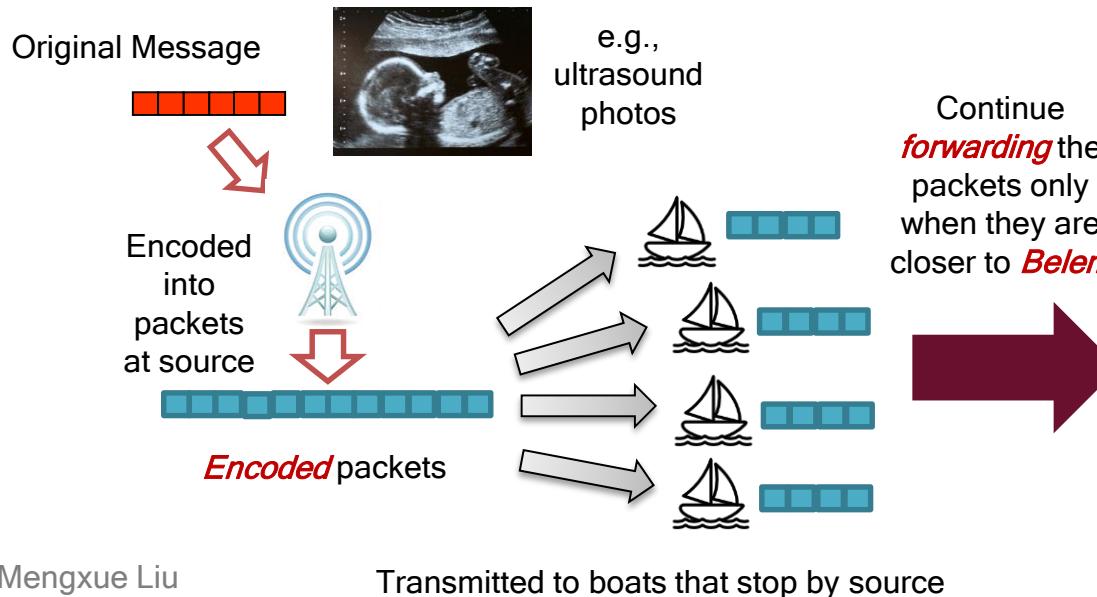
Scheduling in DTNs: Back to Amazon Delta!

- Recall: **mobile smart devices** with limited opportunities for transfer
- E.g., **Amazon** delta riverine:



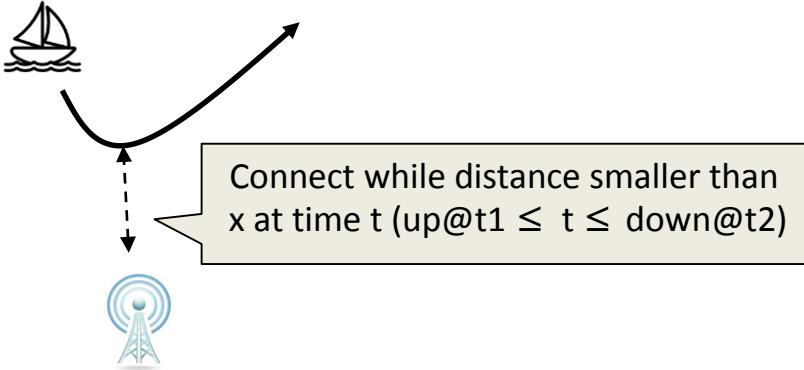
A Simple Model: Time-Schedule Networks

- Assume: boats have a fixed time schedule
(Time Scheduled Networks)
- Idea: transmit packets to nearby boats
(according to schedule):



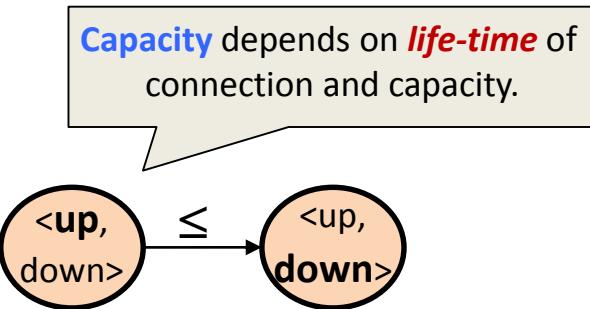
Goal (e.g.):
maximize throughput over DTN

Model can be transformed...



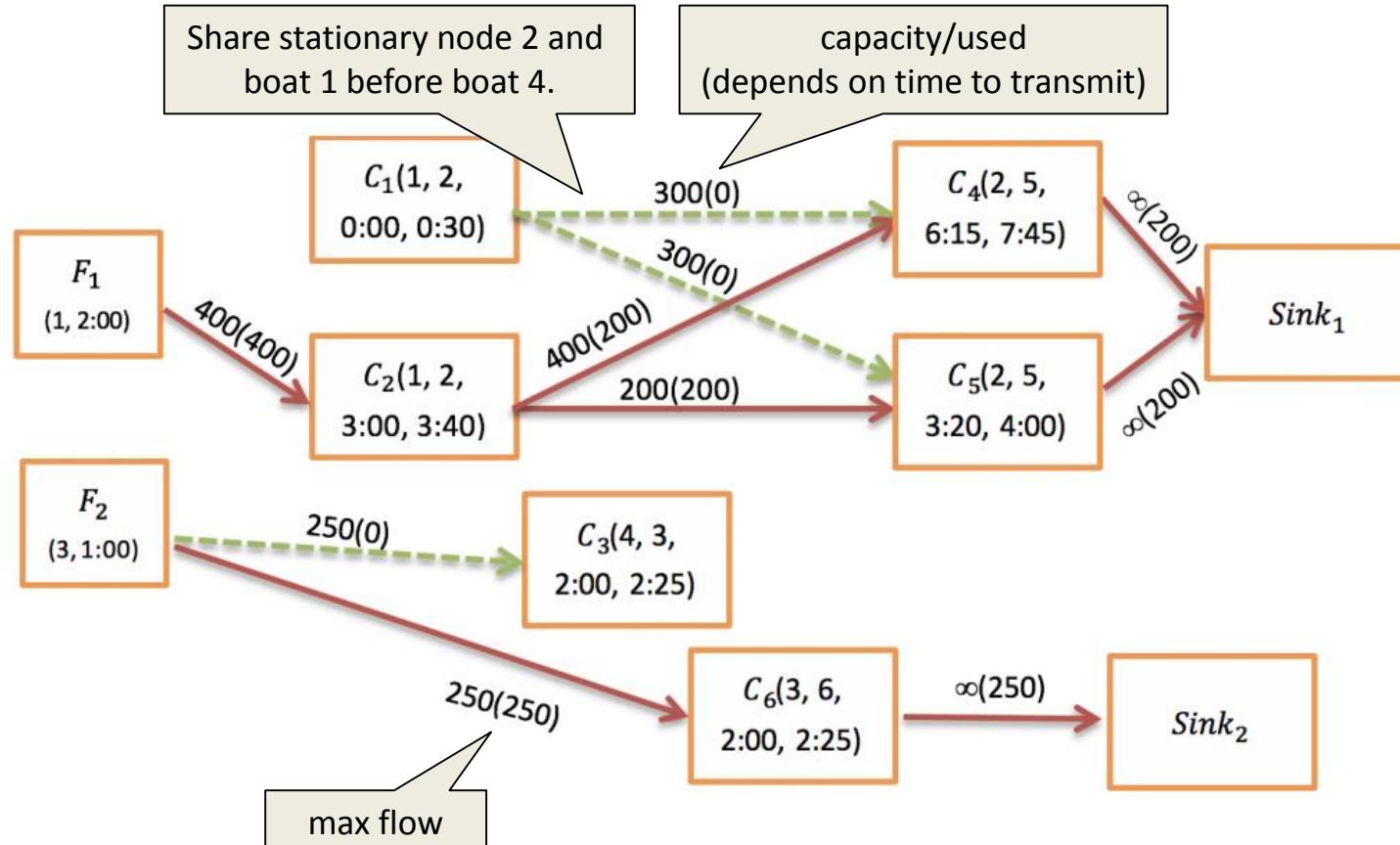
- m **moving nodes** : has schedule P_i
- n **stationary nodes**
- k **commodities** between (possibly different sources and destinations)

... into a connection graph and MCF problem:



- Vertices:
 - moving and stationary nodes **plus** commodity sources **plus** connection nodes
- Directed edges:
 - From connection node C_x to connection node C_y if they **share a common object and $\text{Up}_x \leq \text{Down}_y$**

Connection Graph Example



All-or-Nothing (Splittable) Multicommodity Flow (ANF)

- Observation:
valid **multicommodity** flow in the connection graph



feasible routing **schedule** in the DTN network

- Maximum throughput corresponds to All-or-Nothing (Splittable) Multicommodity Flow (**ADF**)

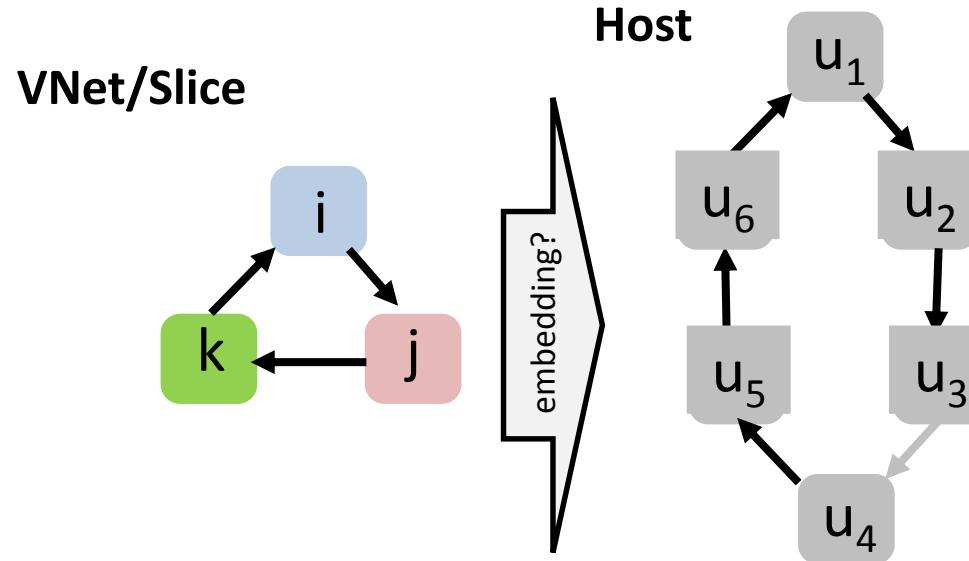
Relaxed version of Maximum Edge Disjoint Path (MEDP) problem: ***fractional***.
Find max subset of commodities that can be simultaneously routed.

ANF: Still not well understood!

- Problem **NP-hard**
- Goal (α, β) - approximation: α factor from optimum and capacity violation at most factor β
- ***Challenge 1: Randomized rounding*** with low augmentation: so far $\alpha = O(1), \beta = \sqrt{n}$
- Can we do better?!

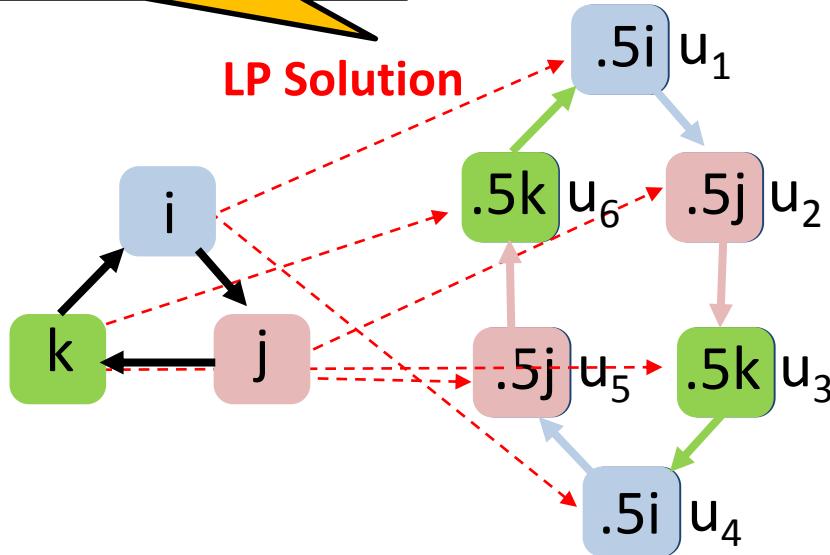
Liu, Richa, Rost, Schmid, 2018.

Challenge 2 - Decomposable ILP Formulations: Randomized Rounding based on MCF Can Fail!



Challenge 2 - Decomposable ILP Formulations: Routing based on MCF Can Fail!

Valid LP solution: virtual node mappings sum to 1 and each virtual node connects to its neighboring node **with half a unit of flow...**

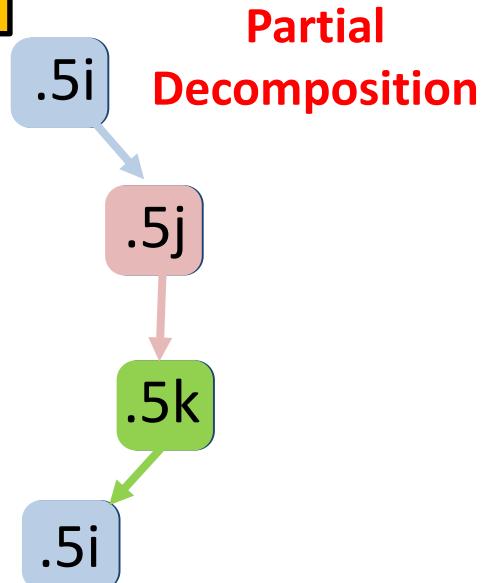
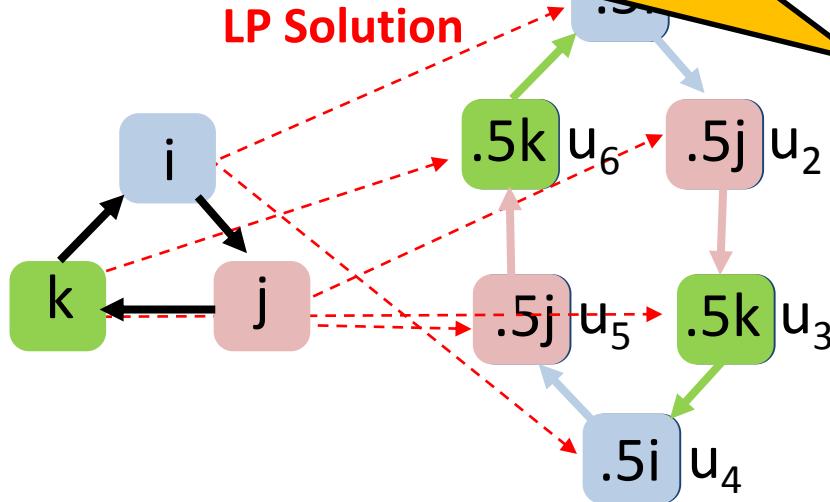


Relaxations of classic MCF formulation **cannot be decomposed** into convex combinations of valid mappings (so we **need different formulations!**)

Formulations: MCF Can Fail!

Impossible to decompose and extract **any single valid mapping**.

Intuition: Node i is mapped to u_1 and **the only neighboring node** that hosts j is u_2 , so i must be fully mapped on u_1 and j on u_2 . Similarly, k must be mapped on u_3 . But flow of virtual edge (k,i) leaving u_3 only leads to u_4 , so **i must be mapped on both u_1 and u_4** . This is **impossible**.



Relaxations of classic MCF formulation **cannot be decomposed** into convex combinations of valid mappings (so we **need different formulations!**)

Further Reading

- [Robust data mule networks with remote healthcare applications in the Amazon region: A fountain code approach](#) Mengxue Liu, Thienne Johnson, Rachit Agarwal, Alon Efrat, Andrea Richa, Mauro Margalho Coutinho. **HealthCom** 2015.
- [Charting the Complexity Landscape of Virtual Network Embeddings](#) Matthias Rost and Stefan Schmid. **IFIP Networking**, Zurich, Switzerland, May 2018.

Conclusion

- Much work ahead: sensor and wireless networks become **larger** and carry more **data**
- An opportunity to make networks **data-/demand-aware**?
- Or to exploit **flexibilities** to precompute, to schedule, to find new tradeoffs between distributed and centralized?
- Sometimes boils down to classic problems (e.g., DTN scheduling): a great time to reconsider!
- Technology is evolving quickly (e.g., drone-to-drone communication): what are the right **models**?

Thank you! Question?

Further Reading

[Online Aggregation of the Forwarding Information Base: Accounting for Locality and Churn](#)

Marcin Bienkowski, Nadi Sarrar, Stefan Schmid, and Steve Uhlig.

IEEE/ACM Transactions on Networking (**TON**), 2018.

[Exploiting Locality in Distributed SDN Control](#)

Stefan Schmid and Jukka Suomela.

ACM SIGCOMM Workshop on Hot Topics in Software Defined Networking (**HotSDN**), Hong Kong, China, August 2013.

[Tight Bounds for Delay-Sensitive Aggregation](#)

Yvonne Anne Oswald, Stefan Schmid, and Roger Wattenhofer.

27th Annual ACM Symposium on Principles of Distributed Computing (**PODC**), Toronto, Canada, August 2008.

[Toward Demand-Aware Networking: A Theory for Self-Adjusting Networks](#)

Chen Avin and Stefan Schmid.

ArXiv Technical Report, July 2018.

[Demand-Aware Network Designs of Bounded Degree](#)

Chen Avin, Kaushik Mondal, and Stefan Schmid.

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