

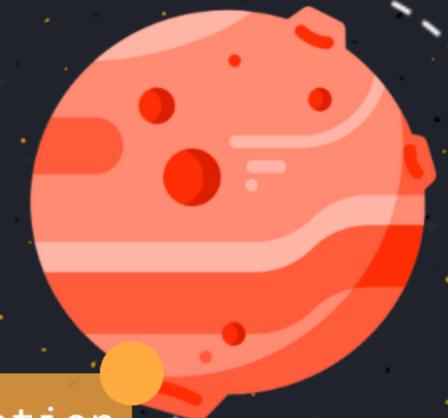


Mapping & Localization

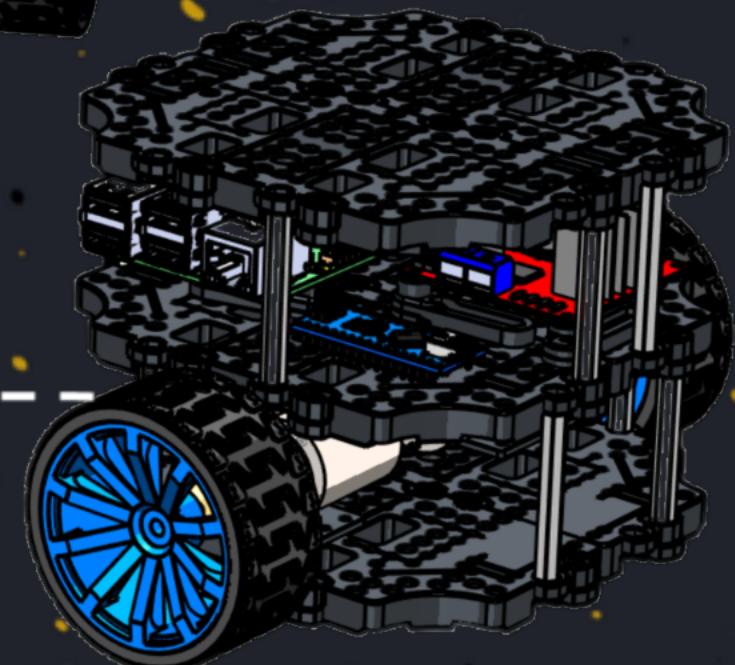
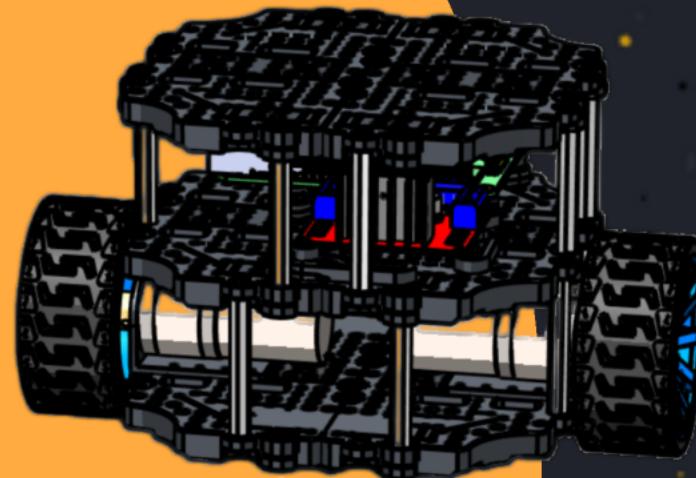
Planning & Navigation

Vision & Perception

Odometry & Control

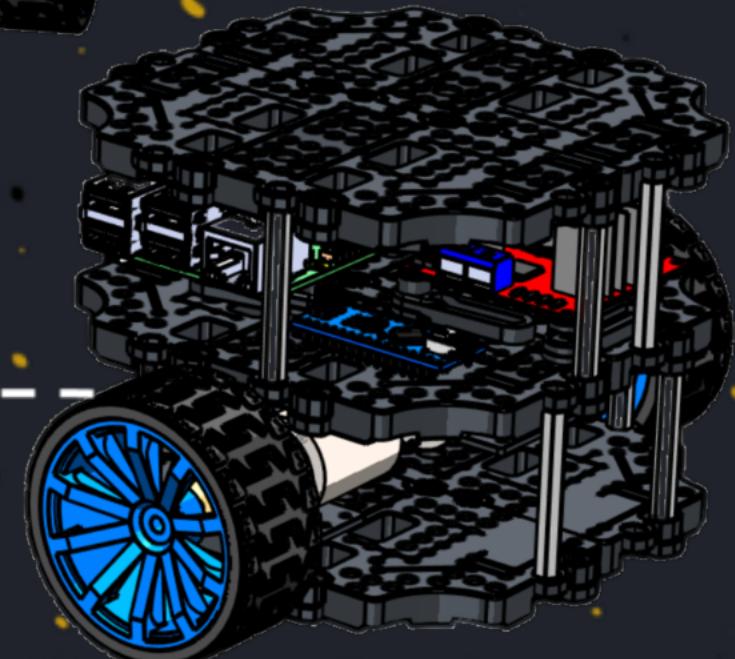
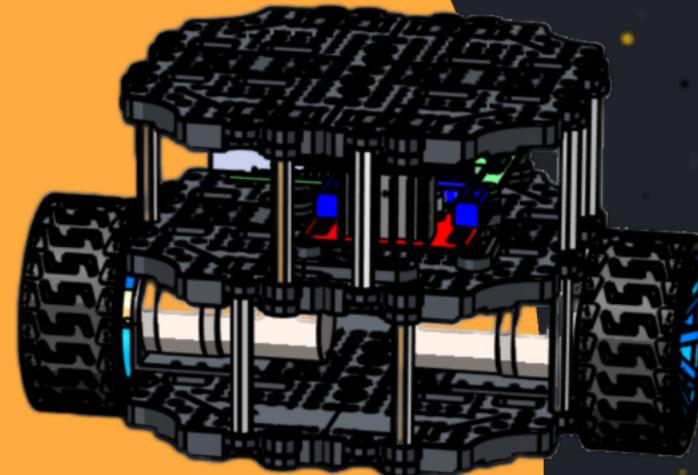


# Odometry and Control



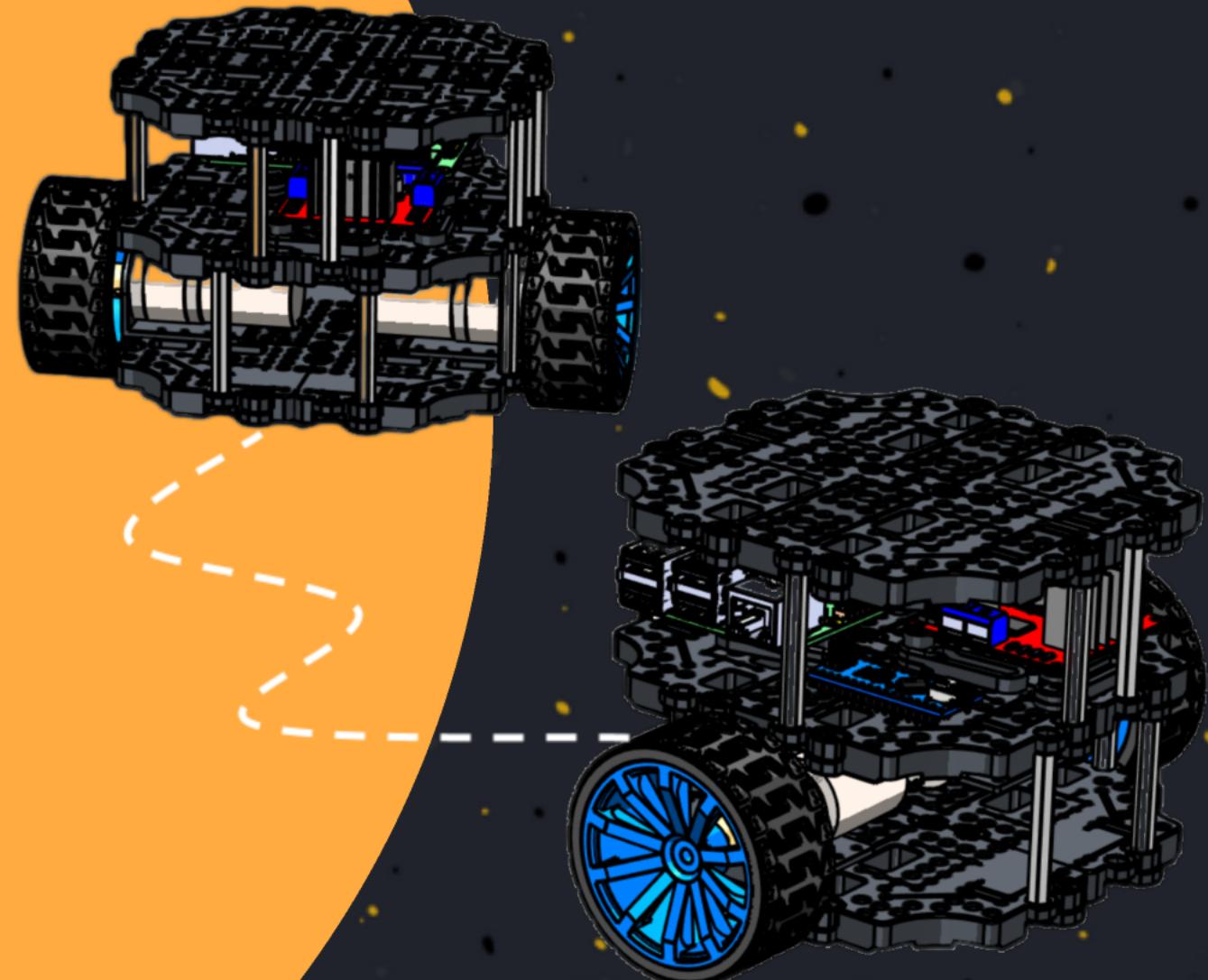
# Odometry and Control

- Differential Kinematics



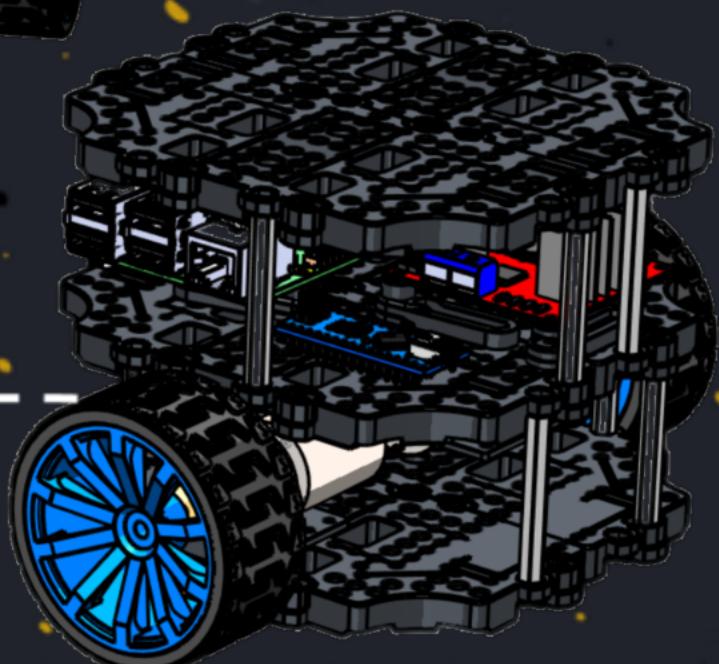
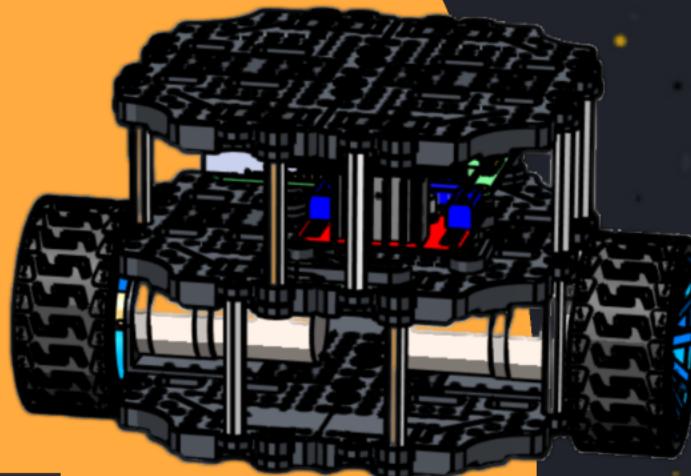
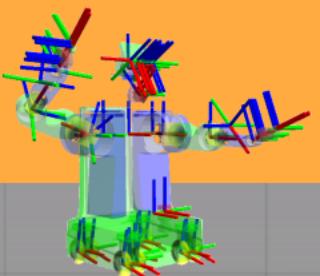
# Odometry and Control

- Differential Kinematics



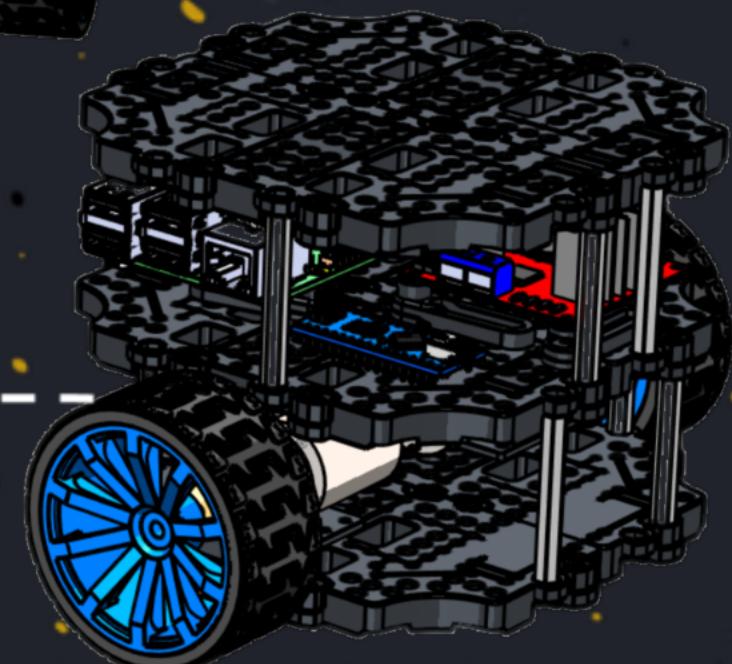
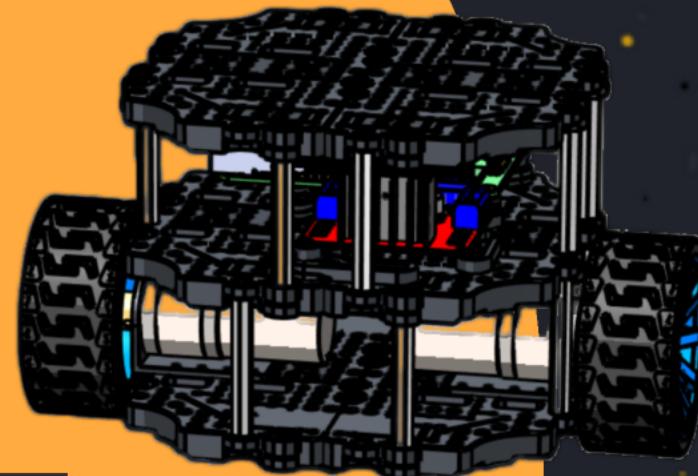
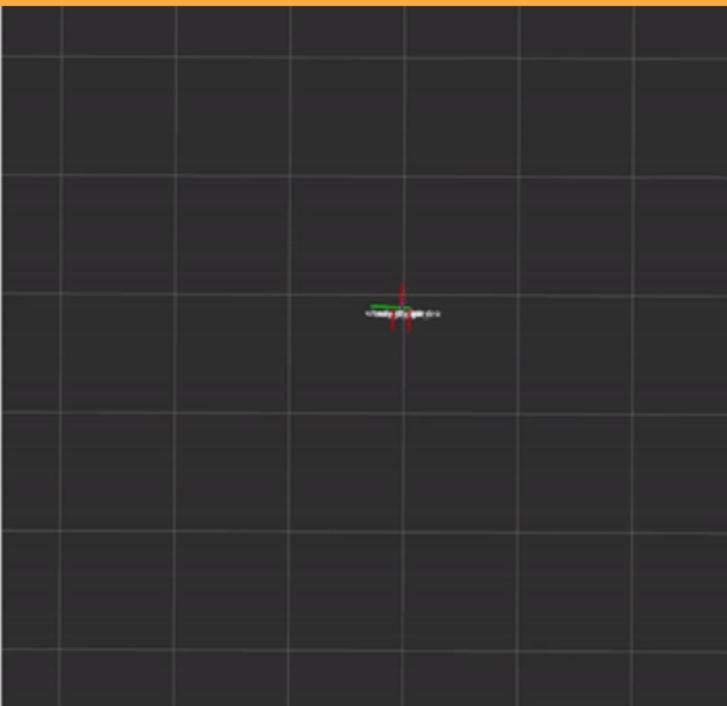
# Odometry and Control

- Differential Kinematics



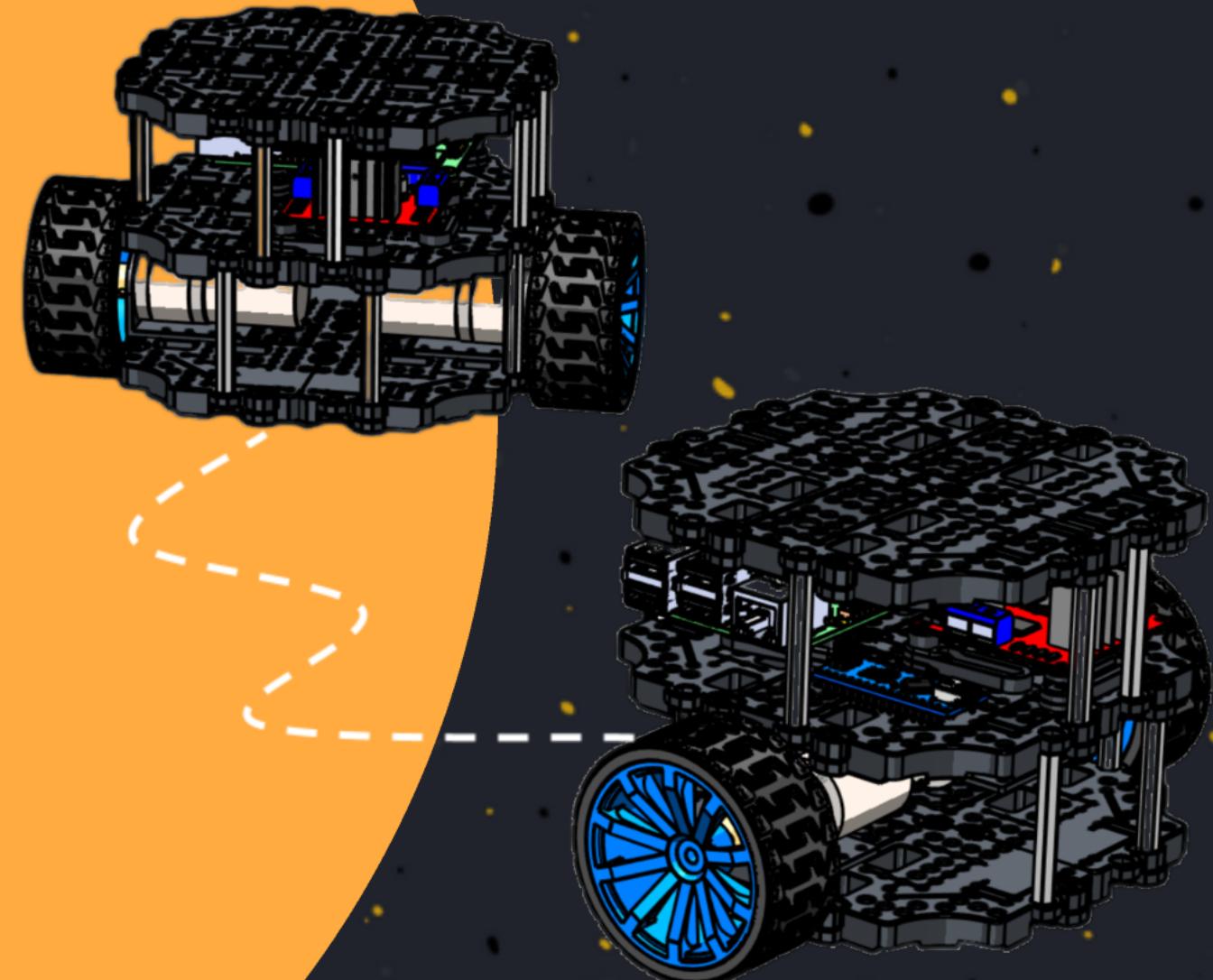
# Odometry and Control

- Differential Kinematics
- Odometry



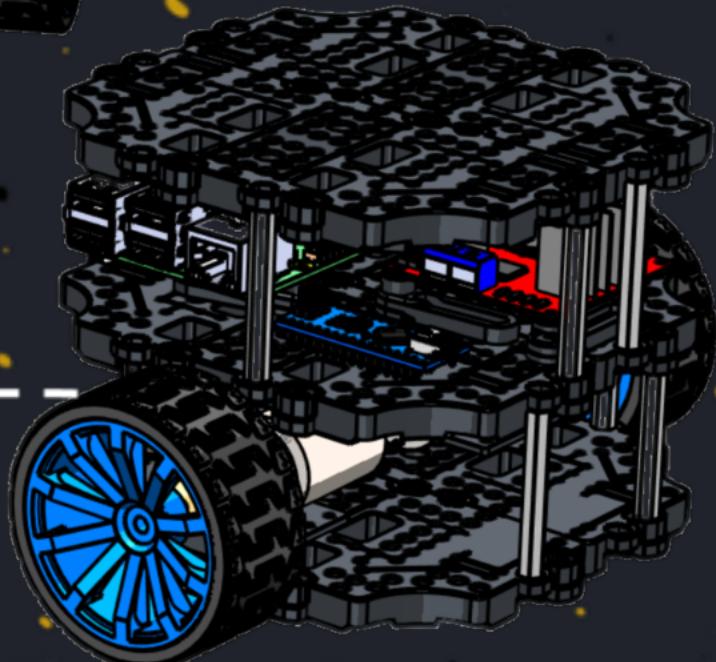
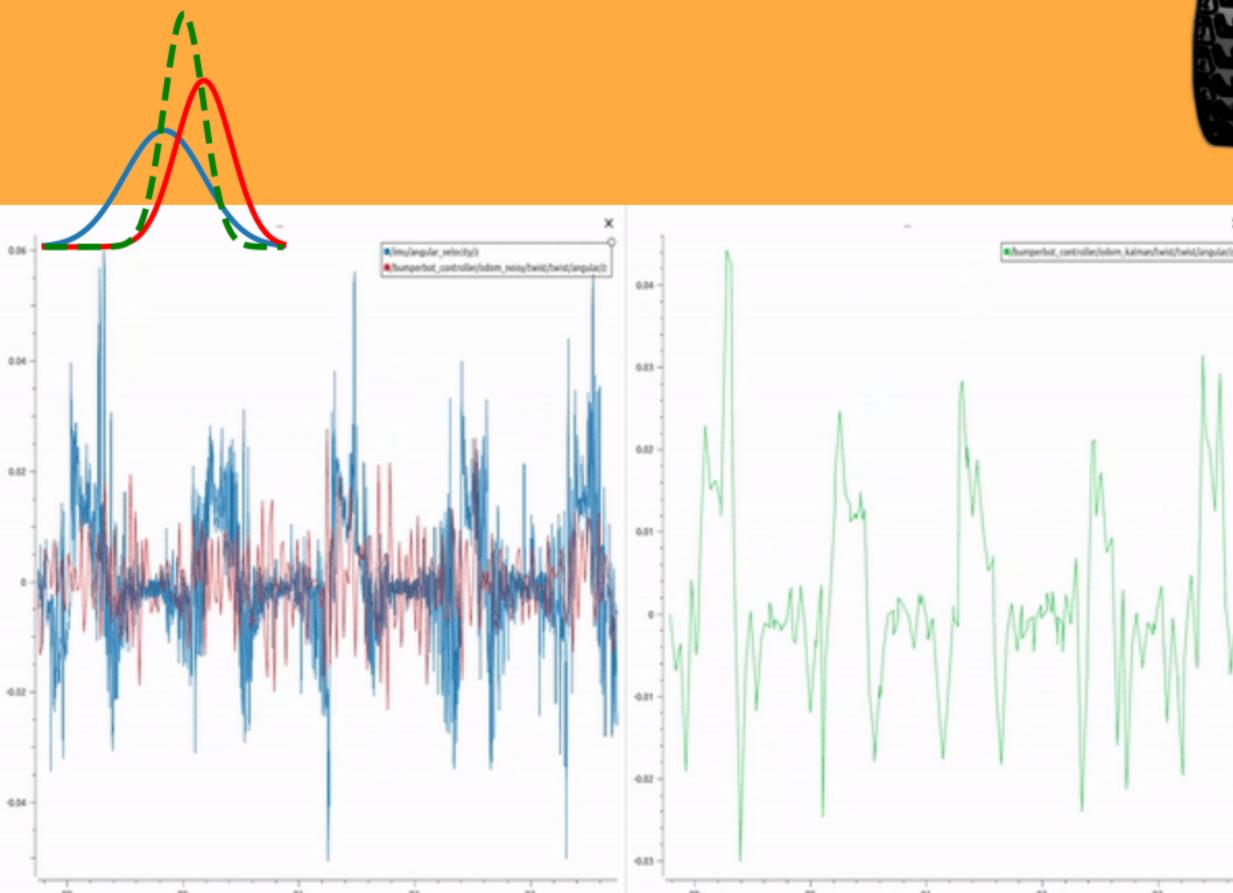
# Odometry and Control

- Differential Kinematics
- Odometry



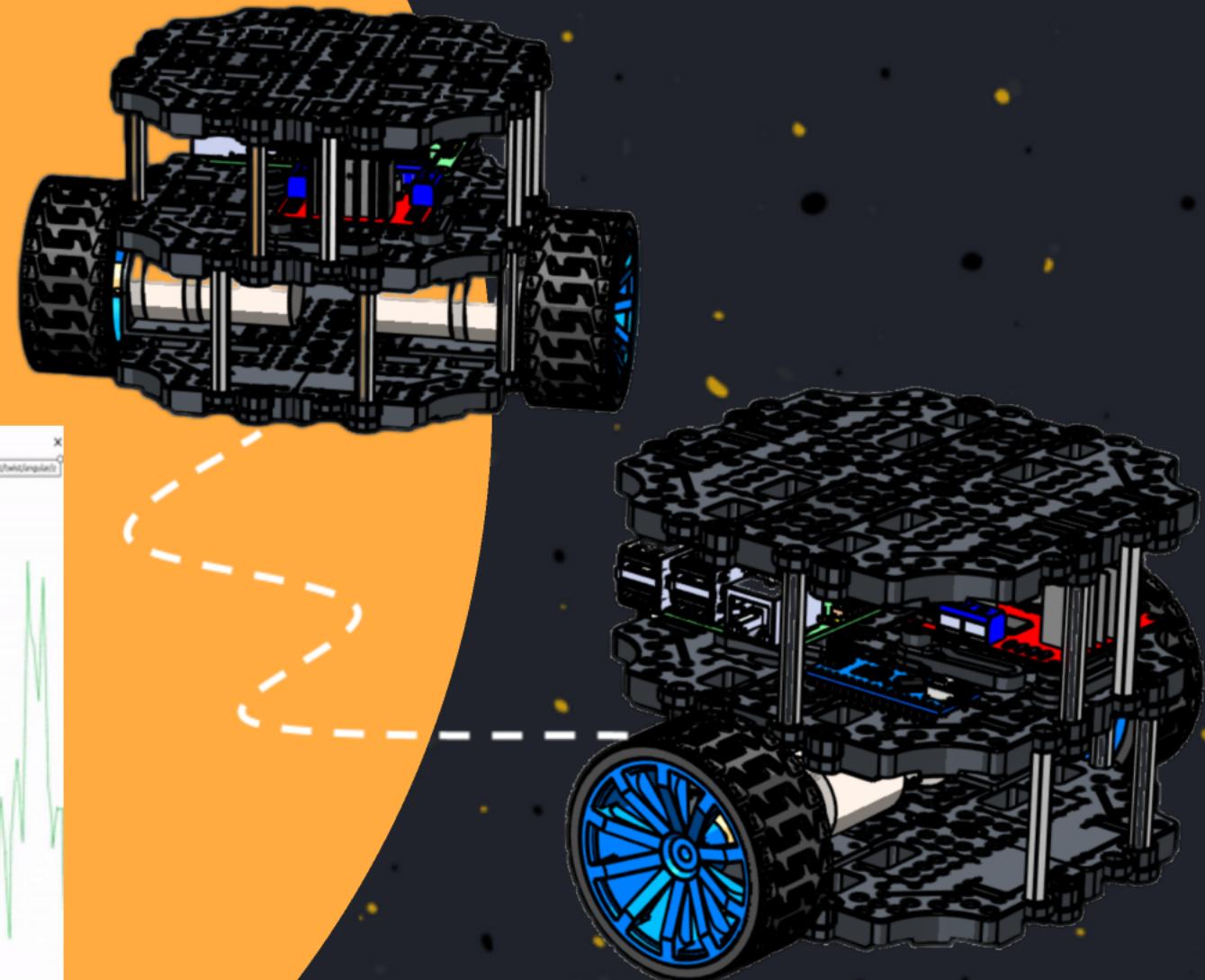
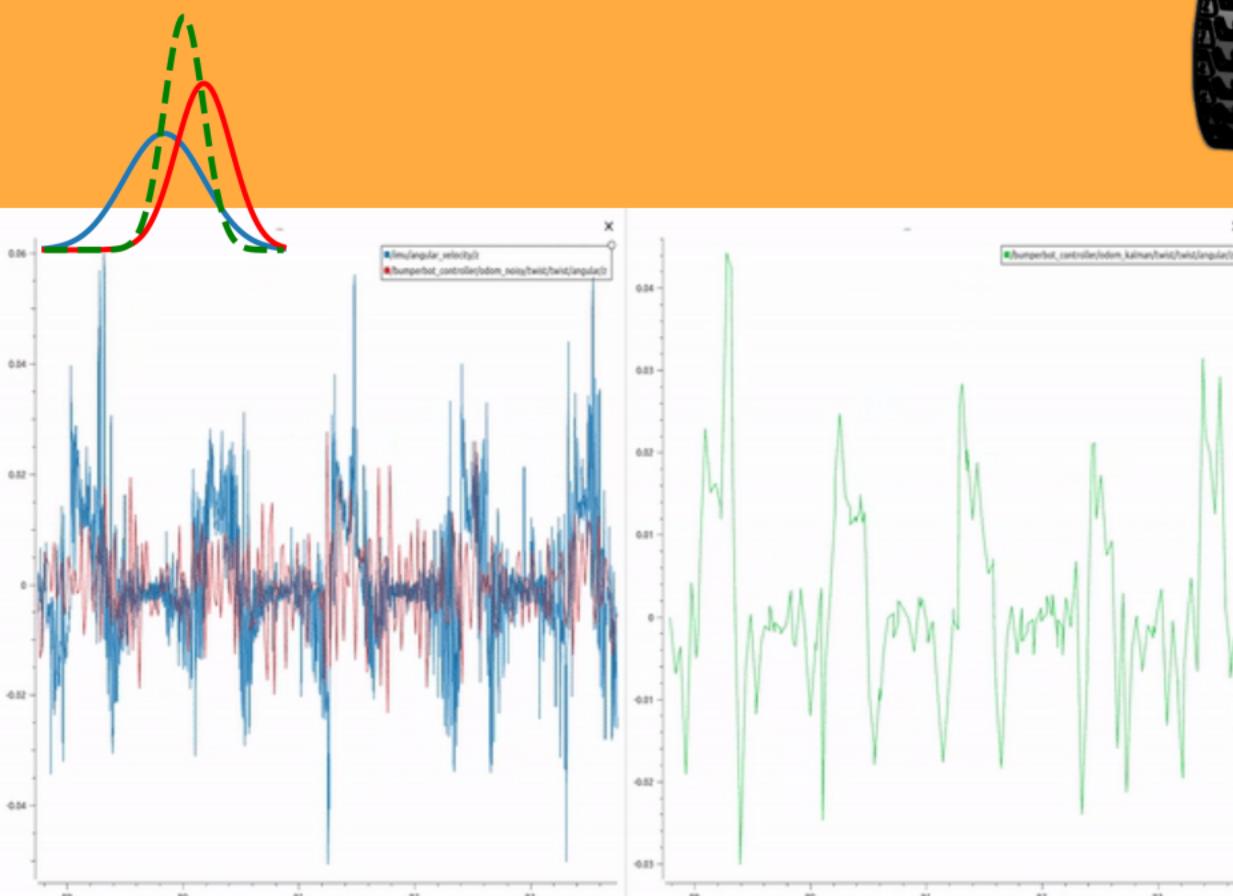
# Odometry and Control

- Differential Kinematics
- Odometry



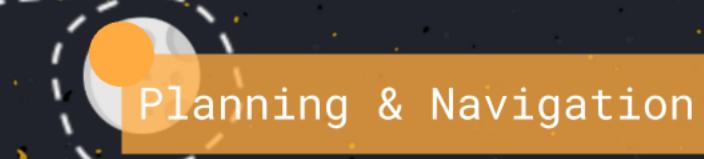
# Odometry and Control

- Differential Kinematics
- Odometry
- Sensor Fusion





Mapping & Localization

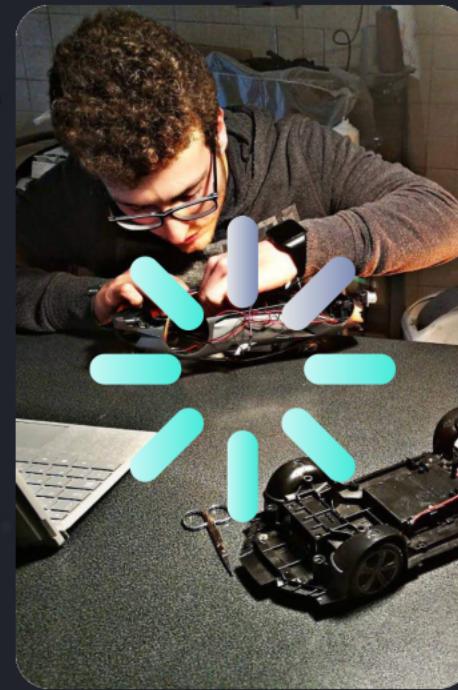


Planning & Navigation

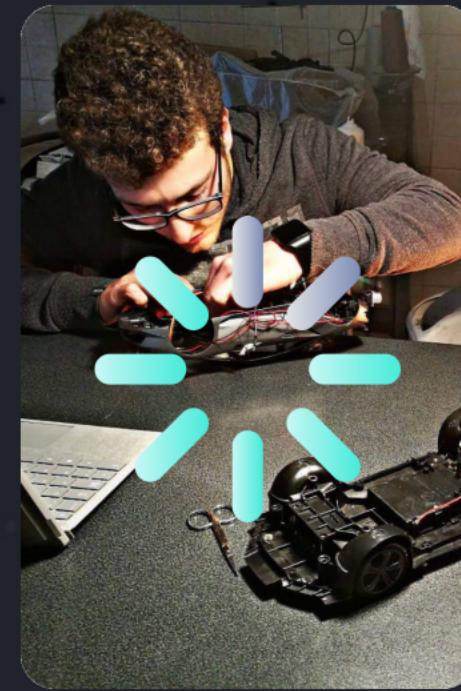
Odometry & Control



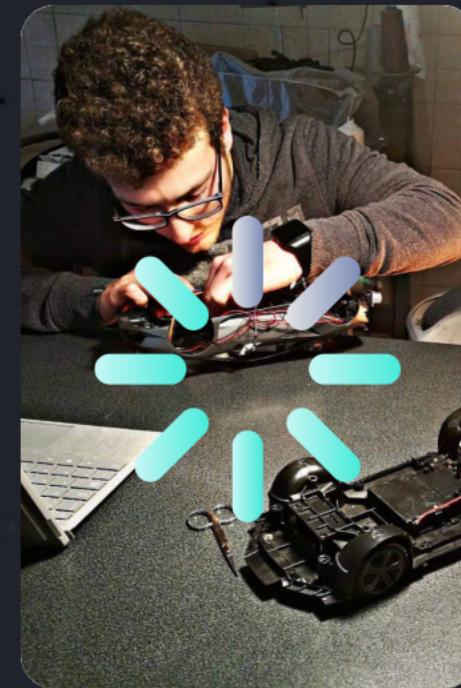
Vision & Perception



Leave a Review



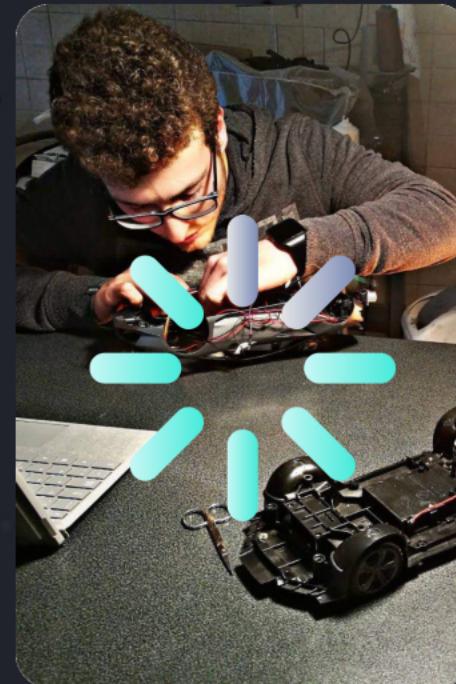
Leave a Review



Leave a Review



100X





Self-Driving and ROS 2 - Learn by Doing!  
Map & Localization



Robotics and ROS - Learn by Doing!  
Manipulators



Robotics and ROS 2 - Learn by Doing!  
Manipulators



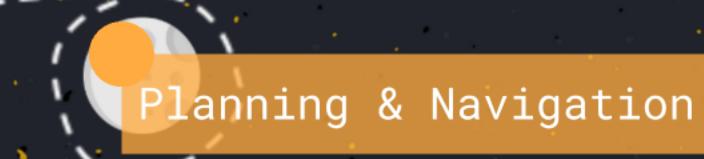
Self Driving and ROS - Learn by Doing!  
Odometry & Control



udemy



Mapping & Localization



Planning & Navigation

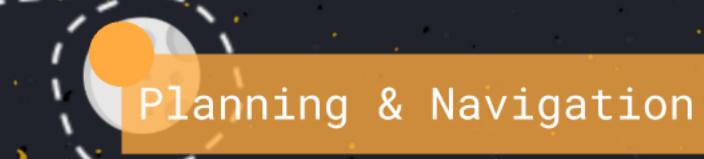


Vision & Perception





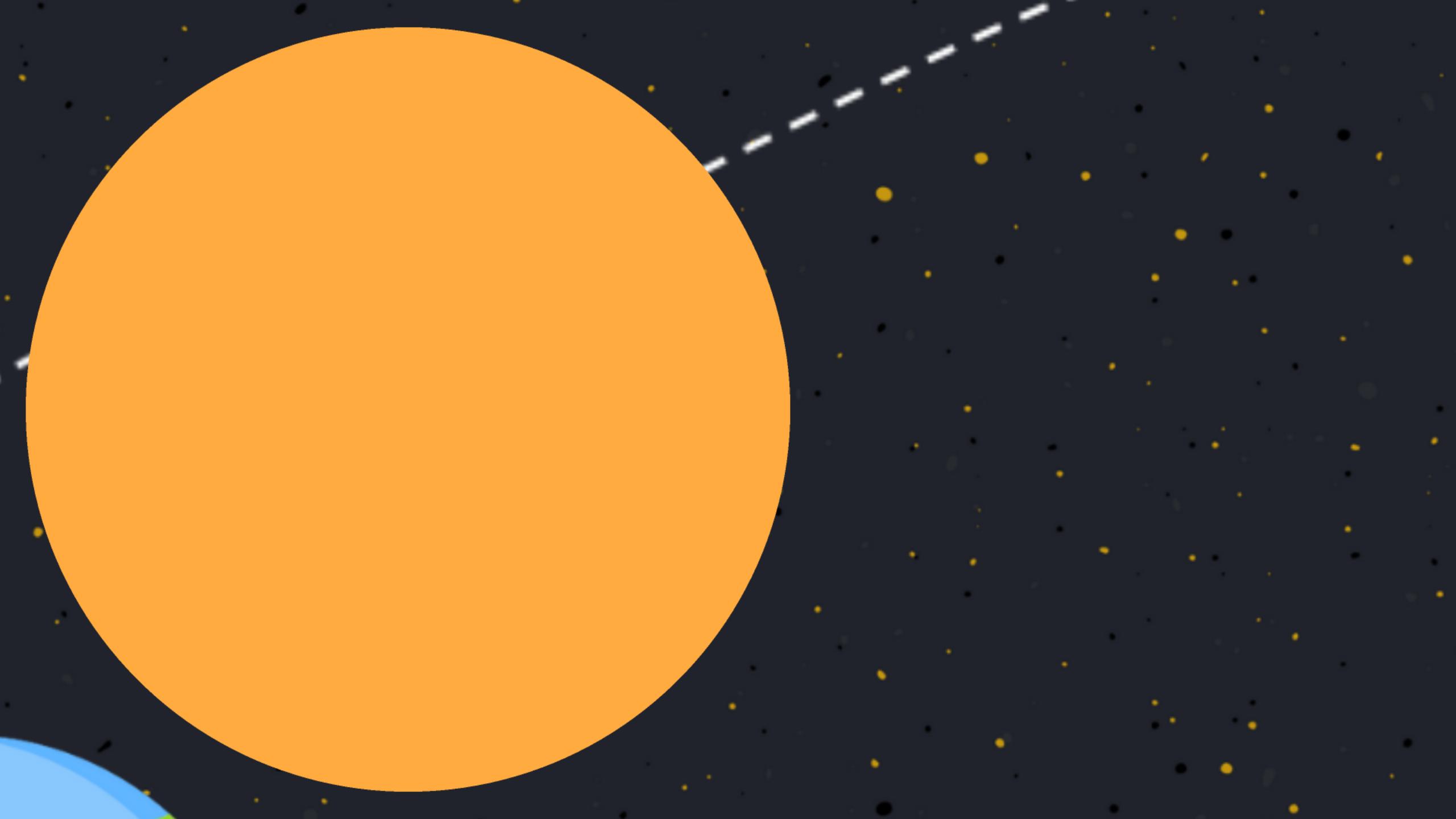
Mapping & Localization



Planning & Navigation

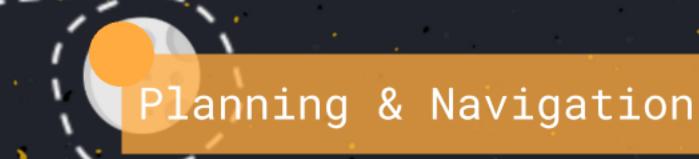


Vision & Perception





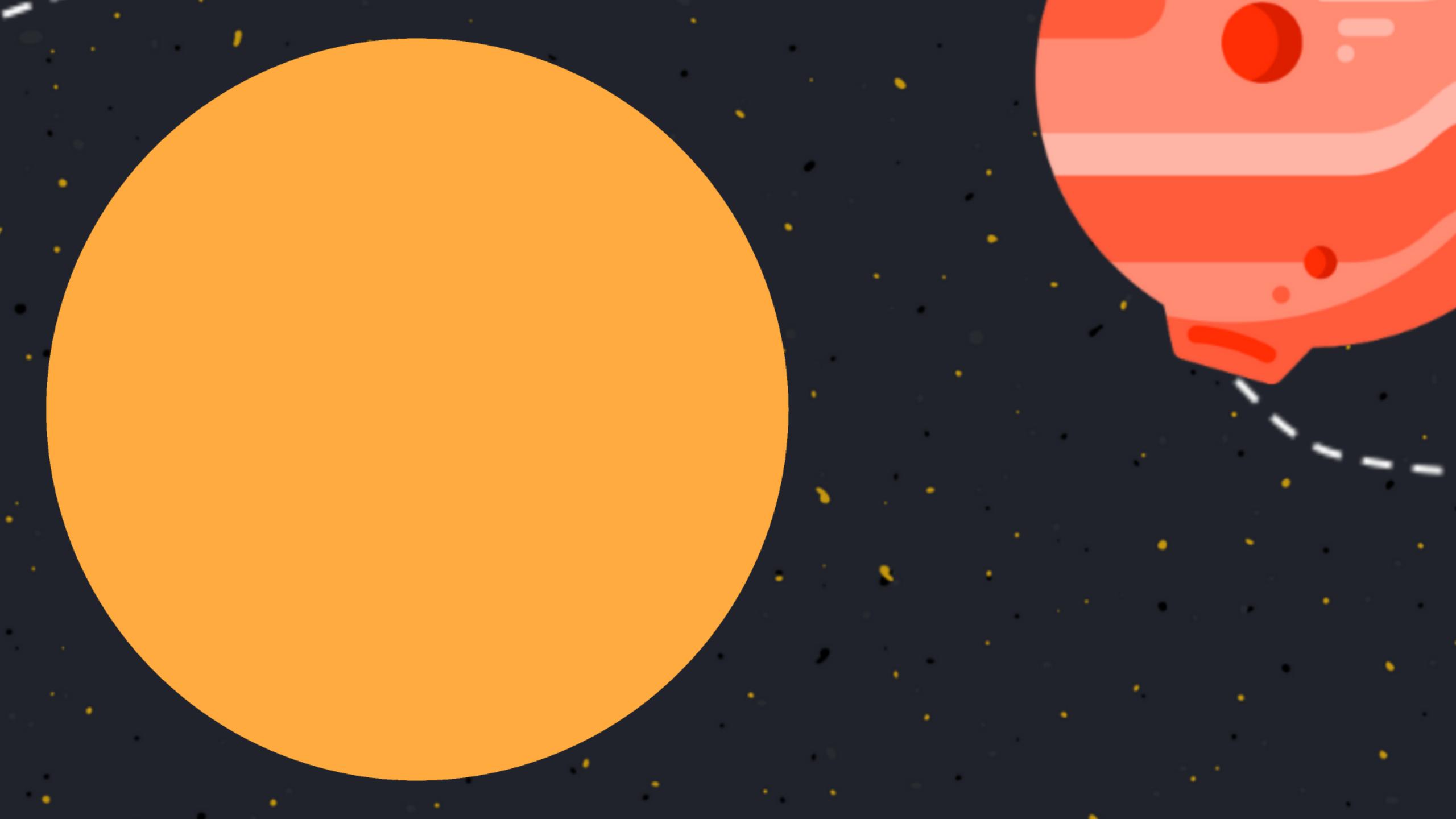
Mapping & Localization



Planning & Navigation

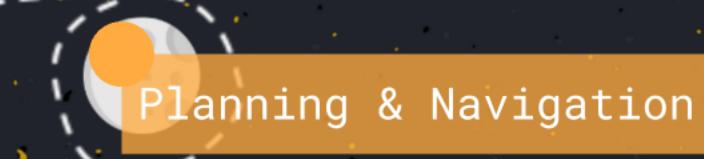


Vision & Perception





Mapping & Localization



Planning & Navigation



Vision & Perception