Linear-Algebra-Numpy-Examples

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0.1 Linear Algebra and Numpy

Examples taken from "An Introduction to Data Analysis through a Geometric Lens" (copyright: Jeff M. Phillips)

```
In [1]: import numpy as np
        from numpy import linalg as LA
In [2]: #create an array, a row vector
        v = np.array([1,2,7,5])
In [3]: v
Out[3]: array([1, 2, 7, 5])
In [4]: v[2]
Out[4]: 7
In [5]: \#create \ a \ n=2 \ x \ d=3 \ matrix
        A = np.array([[3,4,3],[1,6,7]])
In [6]: A
Out[6]: array([[3, 4, 3],
               [1, 6, 7]])
In [7]: # matrix entry at specified position
        A[1,2]
Out[7]: 7
In [8]: #restrict A to a given range of rows and columns
        A[:, 1:3]
Out[8]: array([[4, 3],
               [6, 7]])
In [9]: #adding and multiplying vectors
        u = np.array([3,4,2,2])
```

```
In [10]: #elementwise add
         v+u
Out[10]: array([4, 6, 9, 7])
In [11]: \#elementwise\ multiply
Out[11]: array([ 3, 8, 14, 10])
In [12]: # dot product
         v.dot(u)
Out[12]: 35
In [13]: np.dot(u,v)
Out[13]: 35
In [14]: #matrix multiplication
         B = np.array([[1,2],[6,5],[3,4]])
         A.dot(B)
Out[14]: array([[36, 38],
                [58, 60]])
In [15]: x = np.array([3,4])
In [16]: B.dot(x)
Out[16]: array([11, 38, 25])
In [17]: LA.norm(v)
Out[17]: 8.8881944173155887
In [18]: # Other norms: L1
         LA.norm(v,1)
Out[18]: 15.0
In [19]: #transpose
         A . T
Out[19]: array([[3, 1],
                [4, 6],
                [3, 7]])
In [20]: A
Out[20]: array([[3, 4, 3],
                [1, 6, 7]])
```