# Mechanical Comparison of Arrangement Strategies for Topological Interlocking Assemblies

Lukas Schnelle

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# Topological Interlocking

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A topological interlocking assembly can be defined as an arrangement of blocks that are in contact with each other together with a frame such that, if the frame is fixed, any non-empty finite subset of blocks of the arrangement is prevented from moving.

Outlook

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- planar topological interlocking assemblies, i.e. between two parallel planes in 3D-space,
- use perimeter as the frame,
- only copies of the same block differently arranged.

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$$B_1 := \{\{v_1, v_2\}, \{v_1, v_3\}, \{v_1, v_4\}, \{v_1, v_5\}, \{v_1, v_9\}, \{v_2, v_3\}, \{v_2, v_5\},$$

$$\{v_2, v_6\}, \{v_2, v_7\}, \{v_3, v_4\}, \{v_3, v_7\}, \{v_4, v_7\}, \{v_4, v_8\}, \{v_4, v_9\},$$

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$$\begin{split} B_1 &:= \{\{v_1, v_2\}, \{v_1, v_3\}, \{v_1, v_4\}, \{v_1, v_5\}, \{v_1, v_9\}, \{v_2, v_3\}, \{v_2, v_5\}, \\ & \{v_2, v_6\}, \{v_2, v_7\}, \{v_3, v_4\}, \{v_3, v_7\}, \{v_4, v_7\}, \{v_4, v_8\}, \{v_4, v_9\}, \\ & \{v_5, v_6\}, \{v_5, v_7\}, \{v_5, v_9\}, \{v_6, v_7\}, \{v_7, v_8\}, \{v_7, v_9\}, \{v_8, v_9\}\}, \end{split}$$

and triangular faces

$$\begin{split} B_2 &\coloneqq \{\{v_1, v_2, v_3\}, \{v_1, v_2, v_5\}, \{v_1, v_3, v_4\}, \{v_1, v_4, v_9\}, \{v_1, v_5, v_9\}, \\ & \{v_2, v_3, v_7\}, \{v_2, v_5, v_6\}, \{v_2, v_6, v_7\}, \{v_3, v_4, v_7\}, \{v_4, v_7, v_8\}, \\ & \{v_4, v_8, v_9\}, \{v_5, v_6, v_7\}, \{v_5, v_7, v_9\}, \{v_7, v_8, v_9\}\}. \end{split}$$

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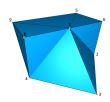
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$$v_1 = (0,0,0), v_2 = (1,1,0), v_3 = (2,0,0),$$
  
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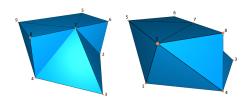
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denoted by E(n) ( $\Longrightarrow E(n) = O(n) \ltimes \mathbb{R}^n$ ).

# Wallpaper Groups

#### Definition

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Crystallograhpic/Wallpaper Groups Let  $\Gamma \leq E(n)$  a subgroup of the group of isometries of dimension n.

Then  $\Gamma$  is called *crystallographic group* if  $\Gamma$  is cocompact and discrete, it is called *wallpaper group* if n = 2.

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# Proposition ([1, Prop. 1.9])

Let  $\Gamma < E(n)$ .

Then  $E(n)/\Gamma$  is compact iff the orbit space  $\mathbb{R}^n/\Gamma$  is compact.

# Examples of wallpaper groups

$$p1 :=$$

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$$\left\langle \left( \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right), \left( \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right) \right\rangle$$

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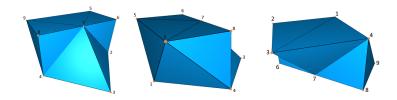
$$\begin{aligned}
&\rho 1 := \\
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&\left\langle \left( \begin{pmatrix} 0 & -1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \end{pmatrix} \right), \left( \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right) \right\rangle
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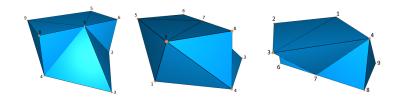
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# crystallographic groups on the Versatile Block



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**Notice:** Versatile Block has only vertices with z=0 and z=1. Now consider the an isometry  $\varphi$  from before lifted to  $\mathbb{R}^3$  by

$$\hat{\varphi}: \mathbb{R}^3 \to \mathbb{R}^3, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} \varphi \begin{pmatrix} x \\ y \end{pmatrix} \end{pmatrix}$$

Applied to all coordinates of the vertices of the Versatile Block we get a Versatile Block between the same planes.

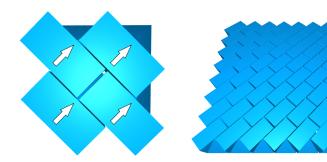
With the groups p1, pg and p4 from before we get three interlocking assemblies consisting only of copies of the Versatile Block:



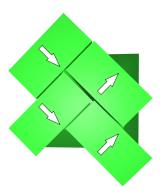
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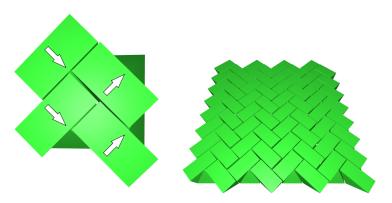
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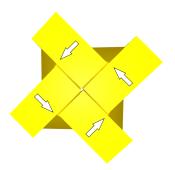
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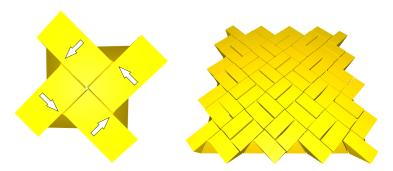


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## Planar Assemblies of the Versatile Block

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## Problem statement

#### Problem

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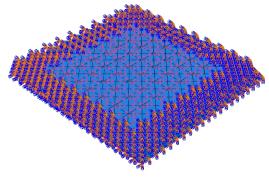
Do the p1, pg and p4 assemblies perform differently when pressure is applied from one side?

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Do the p1, pg and p4 assemblies perform differently when pressure is applied from one side?

Setup like this:





How to answer such a question?

How to answer such a question?  $\rightarrow$  Finite Element Method For now, let us switch to the  $\mathbb{R}^2$  case.

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**Note:** in  $\mathbb{R}^2$  there are two (linearly independent) directions of movement and one rotation that classify all movements.

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### Definition (Beam)

A beam is a body in the shape of a cuboid in  $\mathbb{R}^2$  that has one dimension much larger than the other two.

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# Definition (Supports)



No rotation or translation.

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A beam is a body in the shape of a cuboid in  $\mathbb{R}^2$  that has one dimension much larger than the other two.

# Definition (Supports)



No rotation or translation.



Only movement in direction of line below triangle and rotation.

# Problem formulation

# Simulation Setup

# Stresses

# Combinatorial Method

# Combinatorial Results

[1] A. Szczepanski and W. Scientific. *Geometry of Crystallographic Groups*. Algebra and discrete mathematics. World Scientific, 2012. URL:

https://books.google.de/books?id=wX26CgAAQBAJ.