

Mechanical Comparison of Arrangement Strategies for Topological Interlocking Assemblies

Lukas Schnelle

This is joint work with Tom Goertzen, Domen Macek, Meike Weiß, Stefanie Reese, Hagen Holthusen and Alice C. Niemeyer

Based on [2]

Dec 2023

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- planar topological interlocking assemblies, i.e. between two parallel planes in 3D-space,
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- only copies of the same block differently arranged.

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and triangular faces

$$\begin{aligned} B_2 := & \{\{v_1, v_2, v_3\}, \{v_1, v_2, v_5\}, \{v_1, v_3, v_4\}, \{v_1, v_4, v_9\}, \{v_1, v_5, v_9\}, \\ & \{v_2, v_3, v_7\}, \{v_2, v_5, v_6\}, \{v_2, v_6, v_7\}, \{v_3, v_4, v_7\}, \{v_4, v_7, v_8\}, \\ & \{v_4, v_8, v_9\}, \{v_5, v_6, v_7\}, \{v_5, v_7, v_9\}, \{v_7, v_8, v_9\}\}. \end{aligned}$$

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$$v_1 = (0, 0, 0), v_2 = (1, 1, 0), v_3 = (2, 0, 0),$$

$$v_4 = (1, -1, 0), v_5 = (0, 1, 1), v_6 = (1, 1, 1),$$

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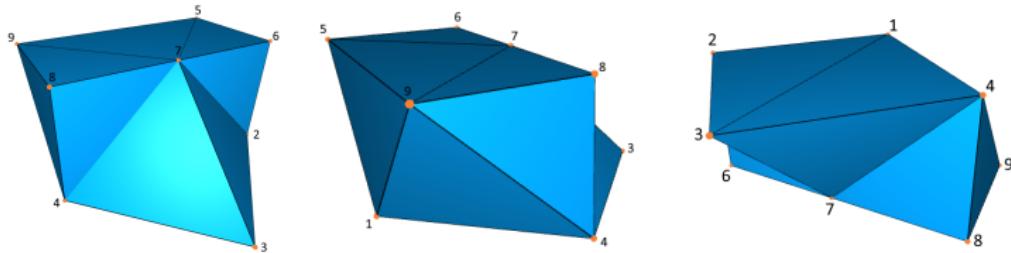
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The isometries of a given euclidean vectorspace are a group with the concatenation

$$((A, a) \circ (B, b))(x) := (A \cdot B, A \cdot a + b)$$

denoted by $E(n)$ ($\implies E(n) = O(n) \ltimes \mathbb{R}^n$).

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Let $\Gamma \leq E(n)$.

Then Γ is cocompact if the space $E(n)/\Gamma$ is compact.

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The translation lattice is always a fundamental domain.

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Theorem (3. Bieberbach) [3, Satz 1.6]

An isomorphism between two crystallographic groups in $E(n)$ is induced by conjugation with an affine map.

Examples of wallpaper groups

$p1 :=$

$$\left\langle \left(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right), \left(\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right) \right\rangle$$

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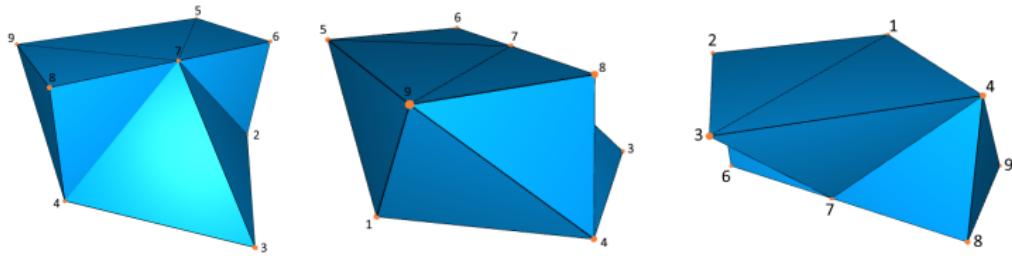
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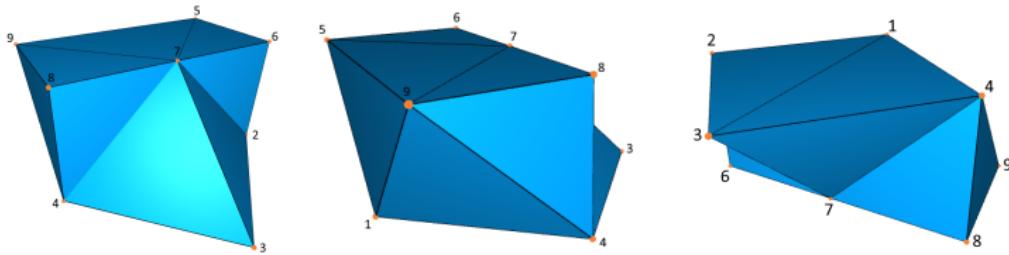
$p4 :=$

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crystallographic groups on the Versatile Block



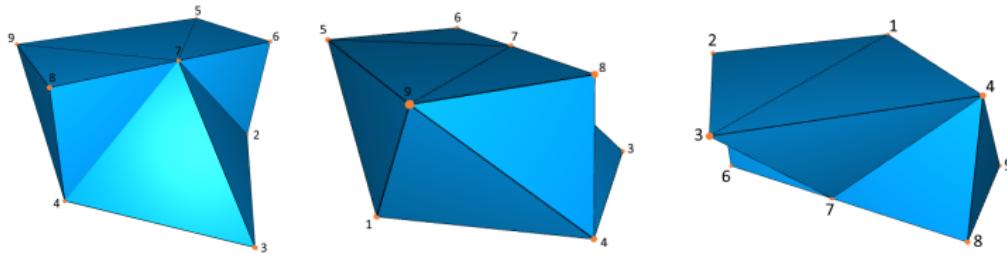
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Notice: Versatile Block has only vertices with $z = 0$ and $z = 1$.
Now consider the an isometry φ from before lifted to \mathbb{R}^3 by

$$\hat{\varphi} : \mathbb{R}^3 \rightarrow \mathbb{R}^3, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} \varphi \begin{pmatrix} x \\ y \end{pmatrix} \\ z \end{pmatrix}$$

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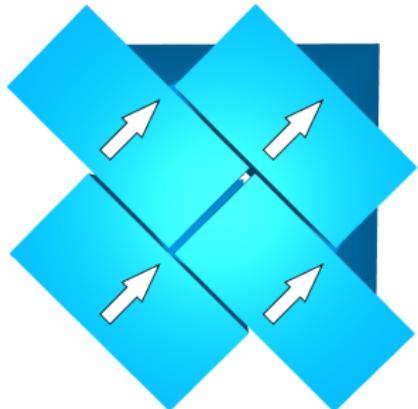
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Applied to all coordinates of the vertices of the Versatile Block we get a Versatile Block between the same planes.

Planar Assemblies of the Versatile Block

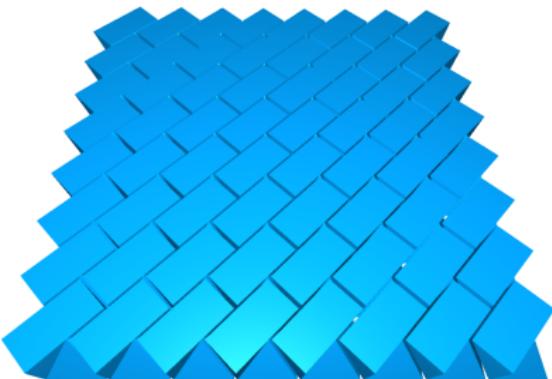
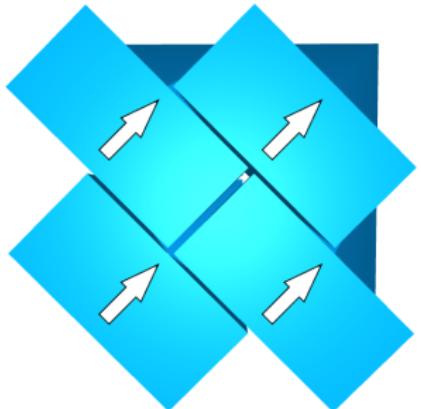
With the groups $p1$, pg and $p4$ from before we get three interlocking assemblies consisting only of copies of the Versatile Block:



$p1$

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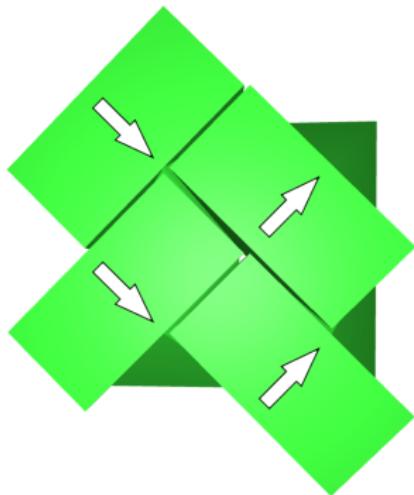
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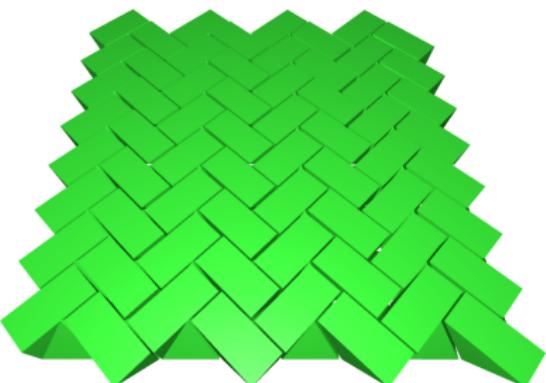
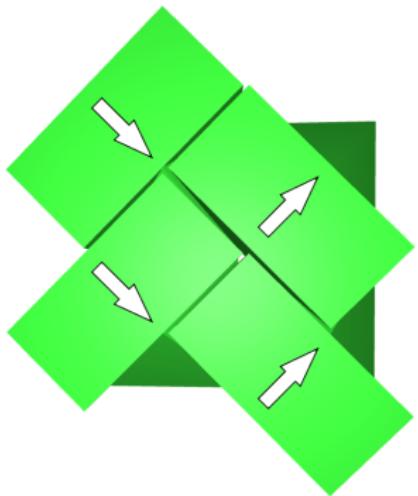
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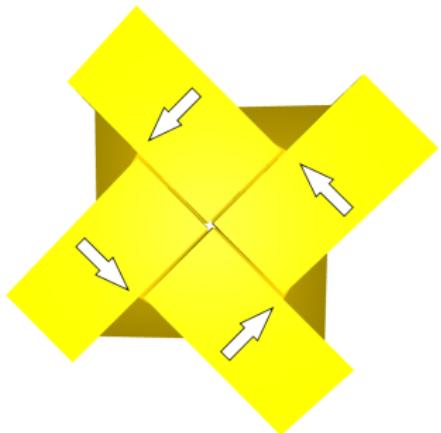
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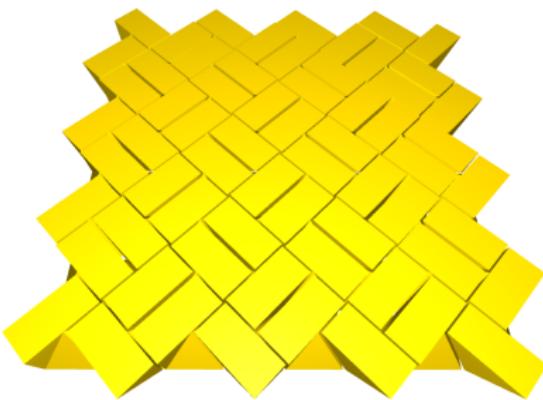
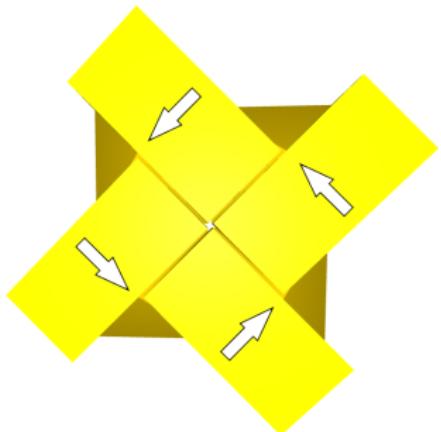
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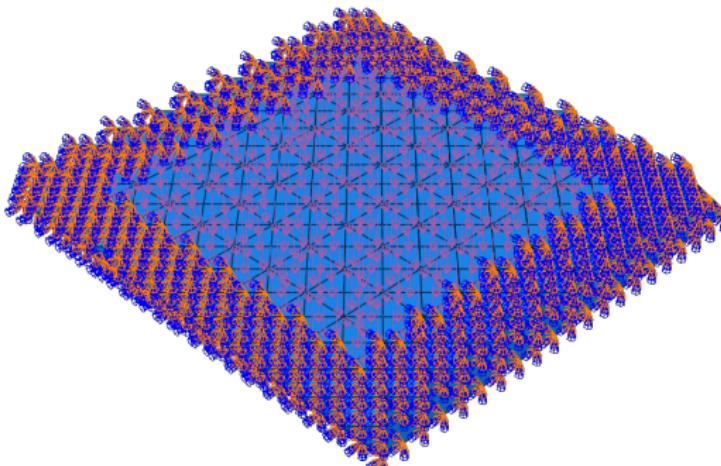
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Setup like this:



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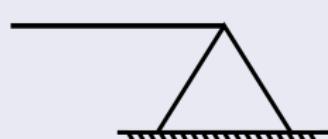
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Solve remaining unknowns with principle of minimum potential.
E.g. principle of virtual work

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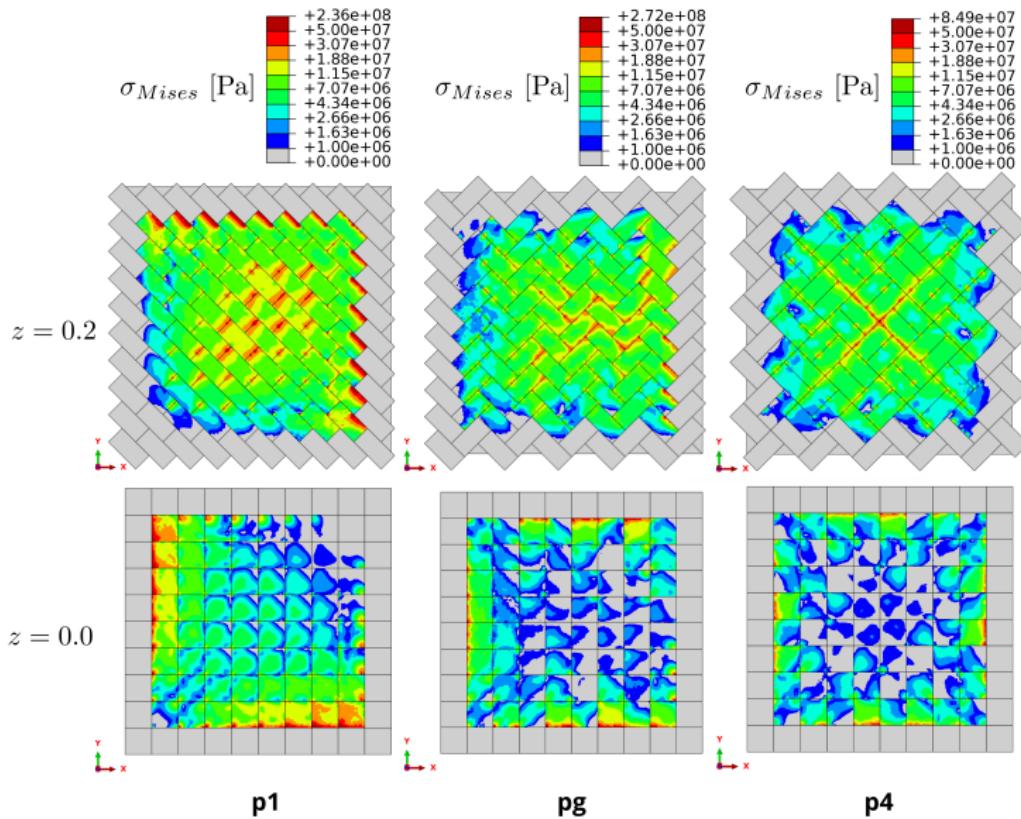


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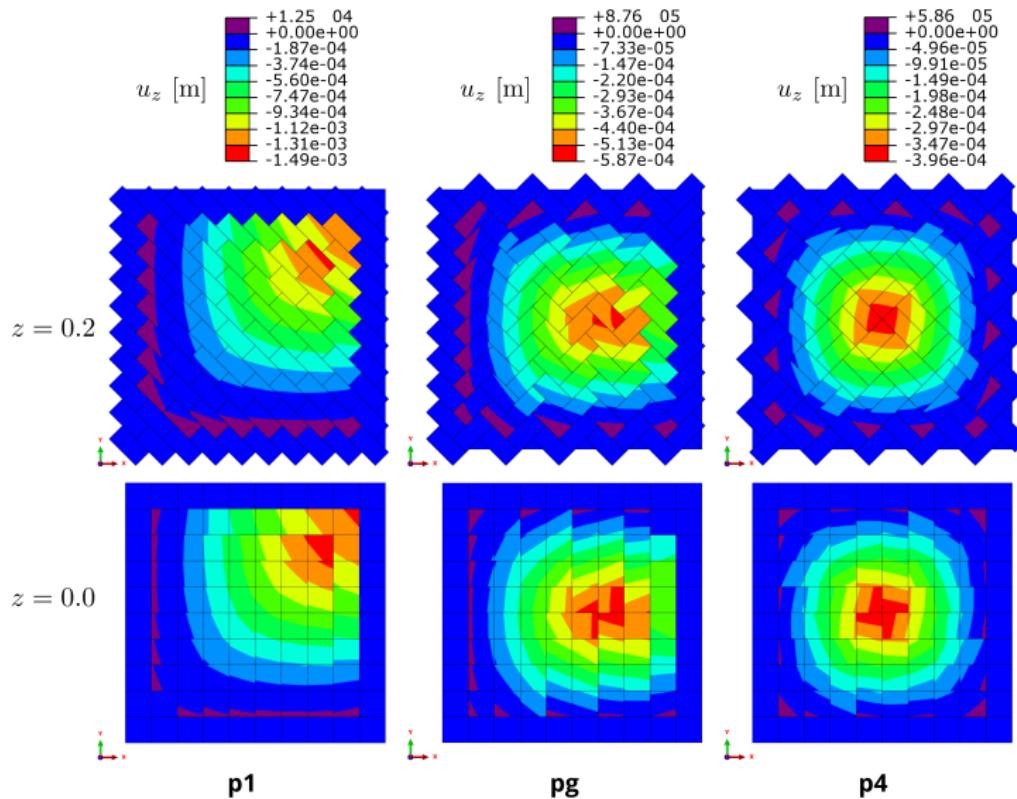


Run simulation

Stresses



Deformations



Combinatorial Method

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Let $A = \{X_i \mid i \in I\}$, a topological interlocking assembly consisting of blocks $X_i \subset \mathbb{R}^3$ indexed by a finite index set I with a frame indexed by $J \subset I$, the core indexed by $C := I \setminus J$ and $d \in \mathbb{R}^3$ a vector.

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- arcs $i \rightarrow j$ if X_i is restrained by X_j in direction d for $i, j \in I$.

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$$v(i \rightarrow j) := \begin{cases} 0 & \text{if } (i, j) \notin \mathcal{G}(A, d) \\ \frac{1}{2}, & \text{if } i \neq j, \\ 1, & \text{if } i = j. \end{cases}$$

so a block divides the load between the two neighbors of it if it is in the core.

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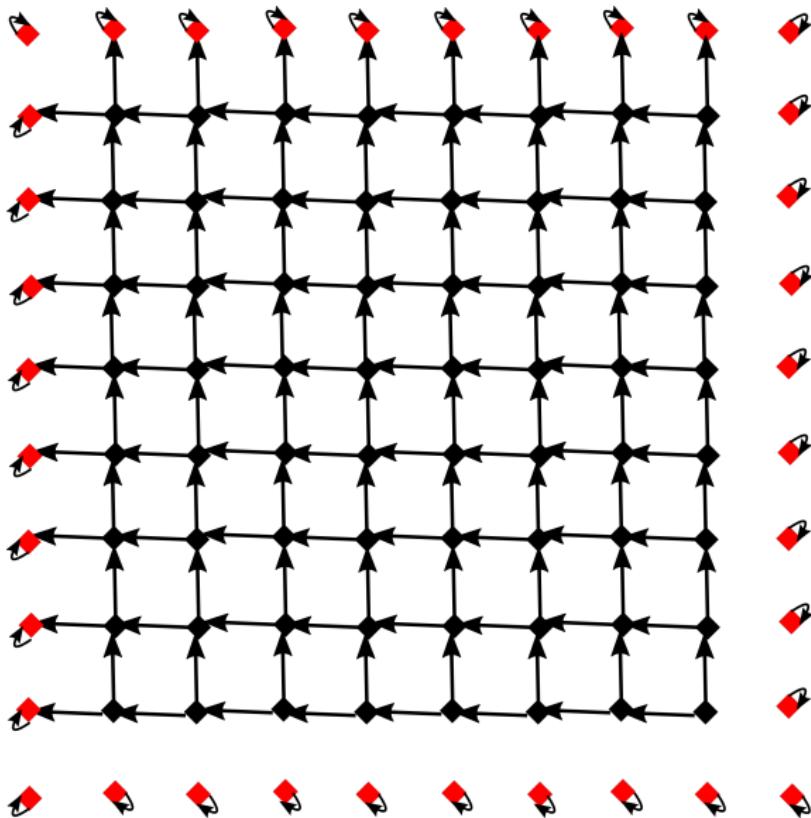
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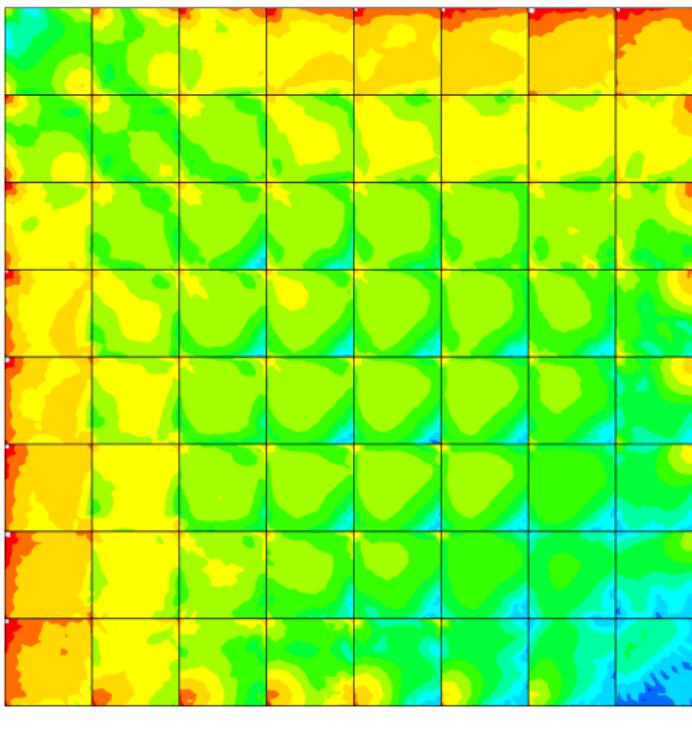
For k high enough $A^k \cdot x$ yields the amount of load transferred into the frame.

Combinatorial Results



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Thank you for your attention

- [1] Reymond Akpanya et al. "Topological Interlocking, Truchet Tiles and Self-Assemblies: A Construction-Kit for Civil Engineering Design". In: *Proceedings of Bridges 2023: Mathematics, Art, Music, Architecture, Culture*. Ed. by Judy Holdener et al. Phoenix, Arizona: Tessellations Publishing, 2023, pp. 61–68.
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