

- Task of this class of algorithms: detect and exploit complex patterns in data (eg: by clustering, classifying, ranking, cleaning, etc. the data)
- Typical problems: how to represent complex patterns; and how to exclude spurious (unstable) patterns (= overfitting)
- The first is a computational problem; the second a statistical problem.

#1

#2

- The class of kernel methods implicitly defines the class of possible patterns by introducing a notion of similarity between data
- Example: similarity between documents

p.5

p.4

- Kernel methods exploit information about the inner products between data items
- Many standard algorithms can be rewritten so that they only require inner products between data (inputs)
- Kernel functions = inner products in some feature space (potentially very complex)
- If kernel given, no need to specify what features of the data are being used

#3

p.6

Inner product between vectors

$$\langle \overline{x}, \overline{z} \rangle = \sum_{i} x_{i} z_{i}$$

Hyperplane:

$$\langle w, x \rangle + b = 0$$

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#4

Modularity



- Any kernel-based learning algorithm composed of two modules: A general purpose learning machine
 - A problem specific kernel function
- Any K-B algorithm can be fitted with any kernel
- Kernels themselves can be constructed in a modular way

 $x \in X$

Great for software engineering (and for analysis)

#5

p.10

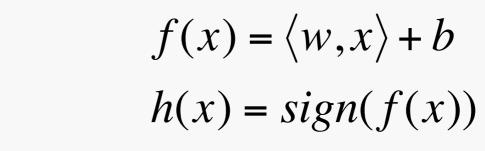
p.12

- Input space $y \in Y = \{-1,+1\}$ Output space
- $h \in H$ Hypothesis
- $f: X \to \mathbf{R}$ Real-valued:
- $S = \{(x_1, y_1), \dots, (x_i, y_i), \dots\}$ Training Set
- Test error ${\cal E}$
- Dot product

 $\langle x, z \rangle$

#6

Perceptron



input space

Linear Separation of the

#7

Support Vector and Kernel Machines

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A Little History

- SVMs introduced in COLT-92 by Boser, Guyon, Vapnik. Greatly developed ever since.
- Initially popularized in the NIPS community, now an important and active field of all Machine Learning research.
- Special issues of Machine Learning Journal, and Journal of Machine Learning Research.
- Kernel Machines: large class of learning algorithms,
 SVMs a particular instance.

A Little History

- Annual workshop at NIPS
- Centralized website: <u>www.kernel-machines.org</u>
- Textbook (2000): see www.support-vector.net
- Now: a large and diverse community: from machine learning, optimization, statistics, neural networks, functional analysis, etc. etc
- Successful applications in many fields (bioinformatics, text, handwriting recognition, etc)
- Fast expanding field, EVERYBODY WELCOME ! ☺

Preliminaries

- Task of this class of algorithms: detect and exploit complex patterns in data (eg: by clustering, classifying, ranking, cleaning, etc. the data)
- Typical problems: how to represent complex patterns; and how to exclude spurious (unstable) patterns (= overfitting)
- The first is a computational problem; the second a statistical problem.

Very Informal Reasoning

- The class of kernel methods <u>implicitly</u> defines the class of possible patterns by introducing a notion of similarity between data
- Example: similarity between documents
 - By length
 - By topic
 - By language ...
- Choice of similarity → Choice of relevant features

More formal reasoning

- Kernel methods exploit information about the inner products between data items
- Many standard algorithms can be rewritten so that they only require inner products between data (inputs)
- Kernel functions = inner products in some feature space (potentially very complex)
- If kernel given, no need to specify what features of the data are being used

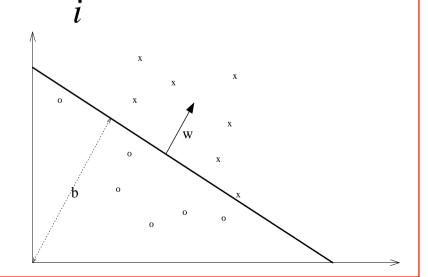
Just in case ...

Inner product between vectors

$$\langle \bar{x}, \bar{z} \rangle = \sum x_i z_i$$

• Hyperplane:

$$\langle w, x \rangle + b = 0$$



Overview of the Tutorial

- Introduce basic concepts with extended example of Kernel Perceptron
- Derive Support Vector Machines
- Other kernel based algorithms
- Properties and Limitations of Kernels
- On Kernel Alignment
- On Optimizing Kernel Alignment

Parts I and II: overview

- Linear Learning Machines (LLM)
- Kernel Induced Feature Spaces
- Generalization Theory
- Optimization Theory
- Support Vector Machines (SVM)

Modularity



- Any kernel-based learning algorithm composed of two modules:
 - A general purpose learning machine
 - A problem specific kernel function
- Any K-B algorithm can be fitted with any kernel
- Kernels themselves can be constructed in a modular way
- Great for software engineering (and for analysis)

1-Linear Learning Machines

- Simplest case: classification. Decision function is a hyperplane in input space
- The Perceptron Algorithm (Rosenblatt, 57)
- Useful to analyze the Perceptron algorithm, before looking at SVMs and Kernel Methods in general

Basic Notation

• Input space $x \in X$

• Output space $y \in Y = \{-1,+1\}$

• Hypothesis $h \in H$

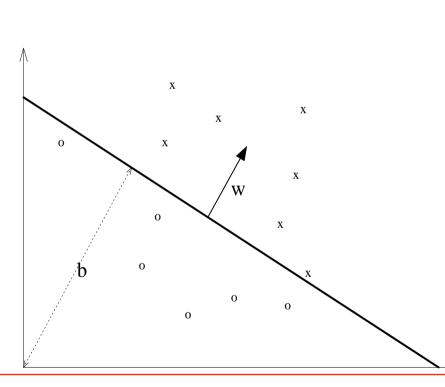
• Real-valued: $f: X \to \mathbb{R}$

• Training Set $S = \{(x_1, y_1), ..., (x_i, y_i),\}$

• Test error

• Dot product $\langle x, z \rangle$

Perceptron



Linear Separation of the input space

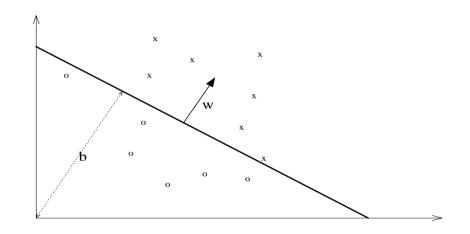
$$f(x) = \langle w, x \rangle + b$$

$$h(x) = sign(f(x))$$

Perceptron Algorithm

Update rule (ignoring threshold):

• if $y_i(\langle w_k, x_i \rangle) \le 0$ then $w_{k+1} \leftarrow w_k + \eta y_i x_i$ $k \leftarrow k+1$



Observations

• Solution is a linear combination of training points $w = \sum \alpha_i y_i x_i$

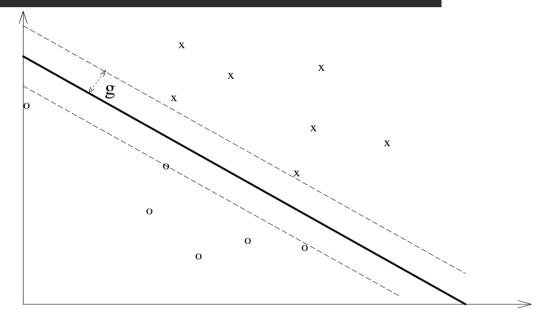
$$\alpha_i \geq 0$$

- Only used informative points (mistake driven)
- The coefficient of a point in combination reflects its 'difficulty'

Observations - 2

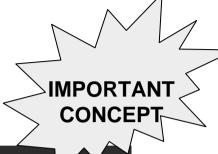
• Mistake bound:

$$M \le \left(\frac{R}{\gamma}\right)^2$$



- coefficients are non-negative
- possible to rewrite the algorithm using this alternative representation





The decision function can be re-written as follows:

$$f(x) = \langle w, x \rangle + b = \sum \alpha_i y_i \langle x_i, x \rangle + b$$

$$w = \sum \alpha_i y_i x_i$$

Dual Representation

And also the update rule can be rewritten as follows:

• if
$$y_i \left(\sum \alpha_j y_j \langle x_j, x_i \rangle + b \right) \le 0$$
 then $\alpha_i \leftarrow \alpha_i + \eta$

 Note: in dual representation, data appears only inside dot products

Duality: First Property of SVMs

- DUALITY is the first feature of Support Vector Machines
- SVMs are Linear Learning Machines represented in a dual fashion

$$f(x) = \langle w, x \rangle + b = \sum \alpha_i y_i \langle x_i, x \rangle + b$$

 Data appear only within dot products (in decision function and in training algorithm)

Limitations of LLMs

Linear classifiers cannot deal with

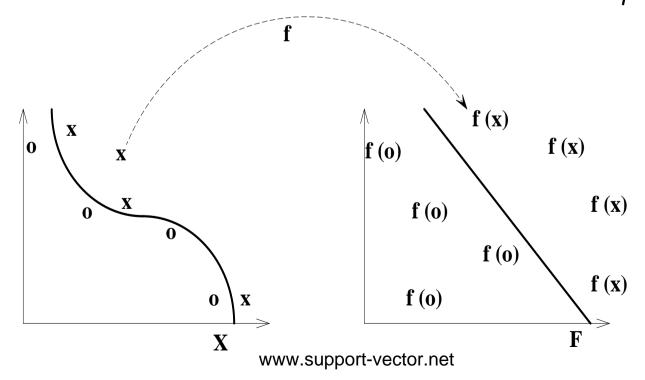
- Non-linearly separable data
- Noisy data
- + this formulation only deals with vectorial data

Non-Linear Classifiers

- One solution: creating a net of simple linear classifiers (neurons): a Neural Network (problems: local minima; many parameters; heuristics needed to train; etc)
- Other solution: map data into a richer feature space including non-linear features, then use a linear classifier

Learning in the Feature Space

ullet Map data into a feature space where they are linearly separable $x
ightharpoonup \phi(x)$



Problems with Feature Space

 Working in high dimensional feature spaces solves the problem of expressing complex functions

BUT:

- There is a computational problem (working with very large vectors)
- And a generalization theory problem (curse of dimensionality)

Implicit Mapping to Feature Space

We will introduce Kernels:

- Solve the <u>computational</u> problem of working with many dimensions
- Can make it possible to use infinite dimensions
 efficiently in time / space
- Other advantages, both practical and conceptual

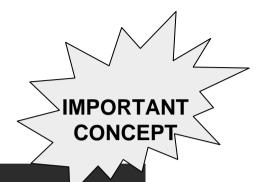
Kernel-Induced Feature Spaces

 In the dual representation, the data points only appear inside dot products:

$$f(x) = \sum \alpha_i y_i \langle \phi(x_i), \phi(x) \rangle + b$$

ullet The dimensionality of space F not necessarily important. May not even know the map ϕ





 A function that returns the value of the dot product between the images of the two arguments

$$K(x_1,x_2) = \langle \phi(x_1),\phi(x_2) \rangle$$

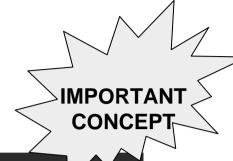
 Given a function K, it is possible to verify that it is a kernel

Kernels

 One can use LLMs in a feature space by simply rewriting it in dual representation and replacing dot products with kernels:

$$\langle x_1, x_2 \rangle \leftarrow K(x_1, x_2) = \langle \phi(x_1), \phi(x_2) \rangle$$





• (aka the Gram matrix):

	K(1,1)	K(1,2)	K(1,3)	 K(1,m)
	K(2,1)	K(2,2)	K(2,3)	 K(2,m)
K=				
	K(m,1)	K(m,2)	K(m,3)	 K(m,m)

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The Kernel Matrix

- The central structure in kernel machines
- Information 'bottleneck': contains all necessary information for the learning algorithm
- Fuses information about the data AND the kernel
- Many interesting properties:

Mercer's Theorem

- The kernel matrix is Symmetric Positive Definite
- Any symmetric positive definite matrix can be regarded as a kernel matrix, that is as an inner product matrix in some space

More Formally: Mercer's Theorem

 Every (semi) positive definite, symmetric function is a kernel: i.e. there exists a mapping

$$\phi$$

such that it is possible to write:

$$K(x_1,x_2) = \langle \phi(x_1),\phi(x_2) \rangle$$

Pos. Def.
$$\int K(x,z) f(x) f(z) dx dz \ge 0$$
$$\forall f \in L_2$$

Mercer's Theorem

• Eigenvalues expansion of Mercer's Kernels:

$$K(x_1, x_2) = \sum_{i} \lambda_i \phi_i(x_1) \phi_i(x_2)$$

• That is: the eigenfunctions act as features!

Examples of Kernels

Simple examples of kernels are:

$$K(x,z) = \langle x, z \rangle^d$$

$$K(x,z) = e^{-\|x-z\|^2/2\sigma}$$

Example: Polynomial Kernels

$$z = (z_{1}, z_{2});$$

$$\langle x, z \rangle^{2} = (x_{1}z_{1} + x_{2}z_{2})^{2} =$$

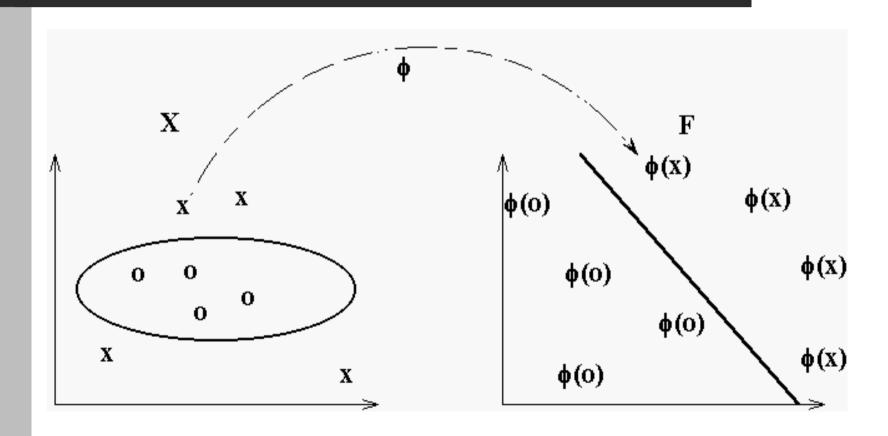
$$= x_{1}^{2}z_{1}^{2} + x_{2}^{2}z_{2}^{2} + 2x_{1}z_{1}x_{2}z_{2} =$$

$$= \langle (x_{1}^{2}, x_{2}^{2}, \sqrt{2}x_{1}x_{2}), (z_{1}^{2}, z_{2}^{2}, \sqrt{2}z_{1}z_{2}) \rangle =$$

$$= \langle \phi(x), \phi(z) \rangle$$
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 $x = (x_1, x_2);$

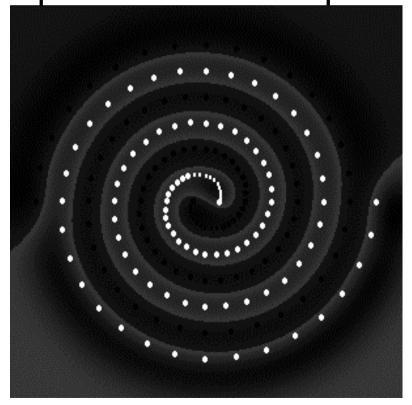
Example: Polynomial Kernels



Example: the two spirals

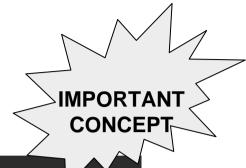
Separated by a hyperplane in feature space

(gaussian kernels)



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- The set of kernels is <u>closed under some</u> operations. If K, K' are kernels, then:
- K+K' is a kernel
- cK is a kernel, if c>0
- aK+bK' is a kernel, for a,b >0
- Etc etc etc.....
- can make complex kernels from simple ones: modularity!

Second Property of SVMs:

SVMs are Linear Learning Machines, that

Use a dual representation

AND

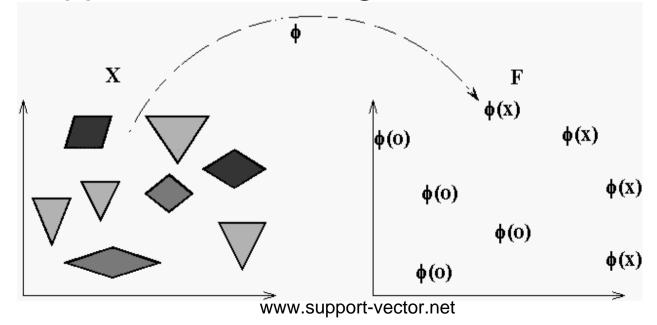
Operate in a kernel induced feature space

(that is:
$$f(x) = \sum \alpha_i y_i \langle \phi(x_i), \phi(x) \rangle + b$$

is a linear function in the feature space implicitely defined by K)

Kernels over General Structures

- Haussler, Watkins, etc: kernels over sets, over sequences, over trees, etc.
- Applied in text categorization, bioinformatics,



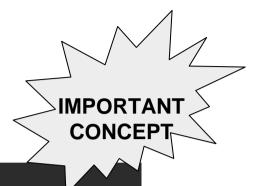
A bad kernel ...

• ... would be a kernel whose kernel matrix is mostly diagonal: all points orthogonal to each other, no clusters, no structure ...

1	0	0	 0
0	1	0	 0
		1	
0	0	0	 1

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No Free Kernel



- If mapping in a space with too many irrelevant features, kernel matrix becomes diagonal
- Need some prior knowledge of target so choose a good kernel

Other Kernel-based algorithms

 Note: other algorithms can use kernels, not just LLMs (e.g. clustering; PCA; etc). Dual representation often possible (in optimization problems, by Representer's theorem).

BREAK





The Generalization Problem

- The curse of dimensionality: easy to overfit in high dimensional spaces (=regularities could be found in the training set that are accidental, that is that would not be found again in a test set)
- The SVM problem is ill posed (finding one hyperplane that separates the data: many such hyperplanes exist)
- Need principled way to choose the best possible hyperplane

The Generalization Problem

- Many methods exist to choose a good hyperplane (inductive principles)
- Bayes, statistical learning theory / pac, MDL,
 ...
- Each can be used, we will focus on a simple case motivated by statistical learning theory (will give the basic SVM)

Statistical (Computational) Learning Theory

- Generalization bounds on the risk of overfitting (in a p.a.c. setting: assumption of I.I.d. data; etc)
- Standard bounds from VC theory give upper and lower bound proportional to VC dimension
- VC dimension of LLMs proportional to dimension of space (can be huge)

Assumptions and Definitions

- distribution D over input space X
- train and test points drawn randomly (I.I.d.) from D
- training error of h: fraction of points in S misclassifed by h
- test error of h: probability under D to misclassify a point
 x
- VC dimension: size of largest subset of X shattered by H (every dichotomy implemented)

$\varepsilon = \widetilde{O}\left(\frac{VC}{m}\right)$

VC Bounds

VC = (number of dimensions of X) + 1

Typically VC >> m, so not useful

Does not tell us which hyperplane to choose

Margin Based Bounds

$$\varepsilon = \tilde{O}\left(\frac{(R / \gamma)^{2}}{m}\right)$$

$$\gamma = \min_{i} \frac{y_{i}f_{i}(x_{i})}{\|f_{i}\|}$$

Note: also compression bounds exist; and online bounds.





 (The worst case bound still holds, but if lucky (margin is large)) the other bound can be applied and better generalization can be achieved:

$$\varepsilon = \widetilde{O}\left(\frac{(R/\gamma)^2}{m}\right)$$

- Best hyperplane: the maximal margin one
- Margin is large is kernel chosen well

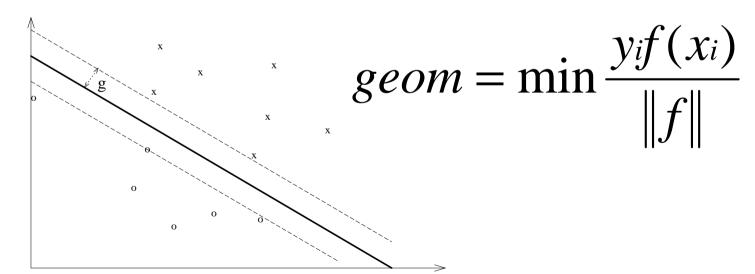
Maximal Margin Classifier

- Minimize the risk of overfitting by choosing the maximal margin hyperplane in feature space
- Third feature of SVMs: maximize the margin
- SVMs control capacity by increasing the margin, not by reducing the number of degrees of freedom (dimension free capacity control).

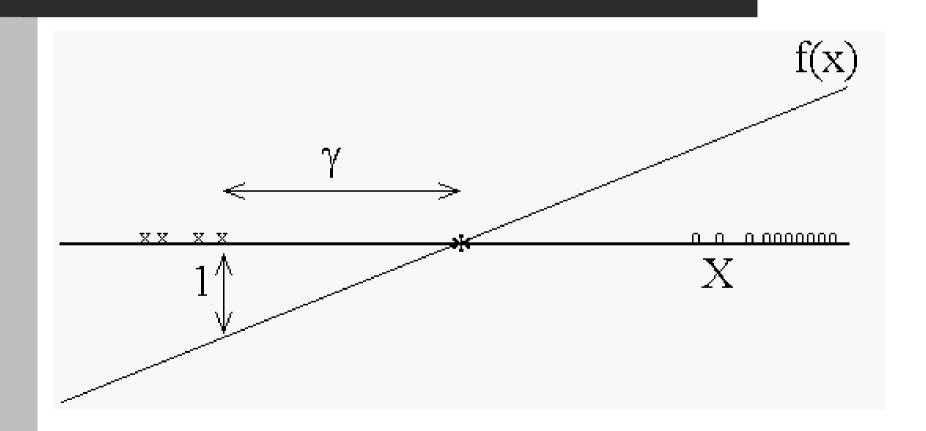
Two kinds of margin

• Functional and geometric margin:

$$funct = \min y_i f(x_i)$$



Two kinds of margin



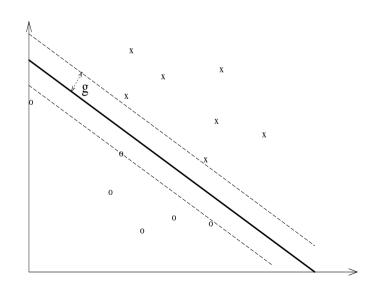
Max Margin = Minimal Norm

- If we fix the functional margin to 1, the geometric margin equal 1/||w||
- Hence, maximize the margin by minimizing the norm

Max Margin = Minimal Norm

Distance between

The two convex hulls



$$\langle w, x^{+} \rangle + b = +1$$

$$\langle w, x^{-} \rangle + b = -1$$

$$\langle w, (x^{+} - x^{-}) \rangle = 2$$

$$\left\langle \frac{w}{\|w\|}, (x^{+} - x^{-}) \right\rangle = \frac{2}{\|w\|}$$





Minimize: subject to:

$$\langle w, w \rangle$$

$$y_i(\langle w, x_i \rangle + b) \ge 1$$

Optimization Theory

- The problem of finding the maximal margin hyperplane: constrained optimization (quadratic programming)
- Use Lagrange theory (or Kuhn-Tucker Theory)
- Lagrangian:

$$\frac{1}{2}\langle w, w \rangle - \sum \alpha_i y_i [(\langle w, x_i \rangle + b) - 1]$$

$$\alpha \geq 0$$

From Primal to Dual

$$L(w) = \frac{1}{2} \langle w, w \rangle - \sum \alpha_i y_i [(\langle w, x_i \rangle + b) - 1]$$

 $\alpha i \geq 0$

Differentiate and substitute:

$$\frac{\partial L}{\partial b} = 0$$

$$\frac{\partial L}{\partial w} = 0$$

The Dual Problem

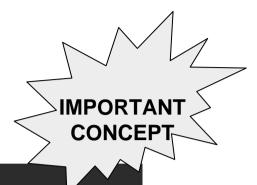


- Maximize: $W(\alpha) = \sum_{i} \alpha_{i} \frac{1}{2} \sum_{i,j} \alpha_{i} \alpha_{j} y_{i} y_{j} \langle x_{i}, x_{j} \rangle$
- Subject to: $\alpha_i \ge 0$

$$\sum_{i} \alpha_{i} y_{i} = 0$$

The duality again! Can use kernels!

Convexity



- This is a Quadratic Optimization problem: convex, no local minima (second effect of Mercer's conditions)
- Solvable in polynomial time ...
- (convexity is another fundamental property of SVMs)

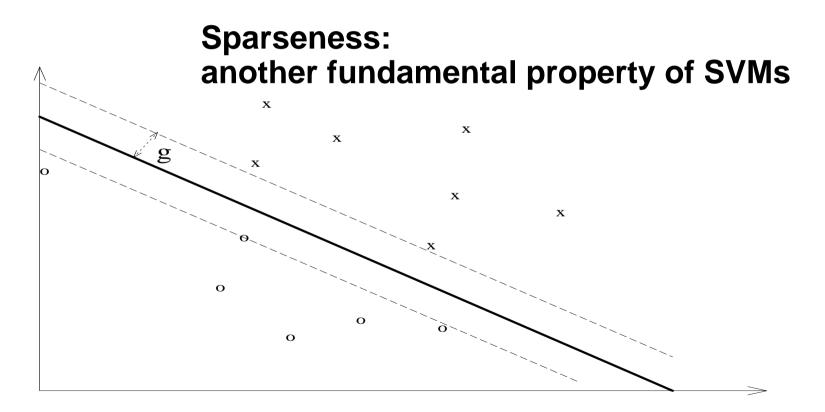
Kuhn-Tucker Theorem

Properties of the solution:

- Duality: can use kernels
- KKT conditions: $\alpha_i [y_i(\langle w, x_i \rangle + b) 1] = 0$
- Sparseness: only the points nearest to the hyperplane (margin = 1) have positive weight $w = \sum \alpha_i y_i x_i$

They are called support vectors

KKT Conditions Imply Sparseness

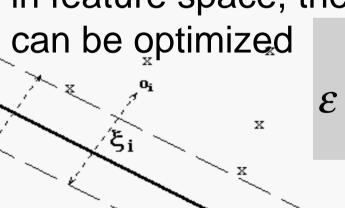


Properties of SVMs - Summary

- ✓ Duality
- √ Kernels
- ✓ Margin
- ✓ Convexity
- √ Sparseness

Dealing with noise

In the case of non-separable data in feature space, the margin distribution



$$\varepsilon \leq \frac{1}{m} \frac{\left(R + \sqrt{\sum \xi^2}\right)^2}{\gamma^2}$$

$$y_i(\langle w, x_i \rangle + b) \ge 1 - \xi_i$$

The Soft-Margin Classifier

Minimize:

$$\frac{1}{2}\langle w, w \rangle + C \sum_{i} \xi_{i}$$

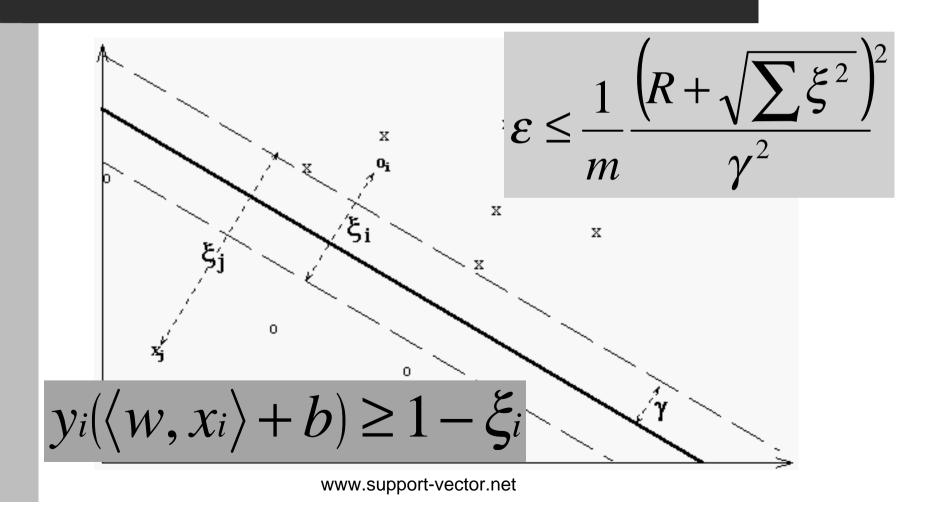
Or:

$$\frac{1}{2}\langle w, w \rangle + C \sum_{i} \xi_{i}^{2}$$

Subject to:

$$y_i(\langle w, x_i \rangle + b) \ge 1 - \xi_i$$

Slack Variables

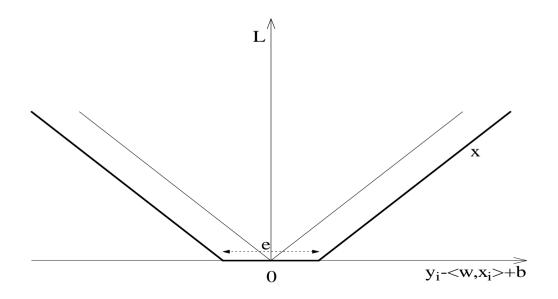


Soft Margin-Dual Lagrangian

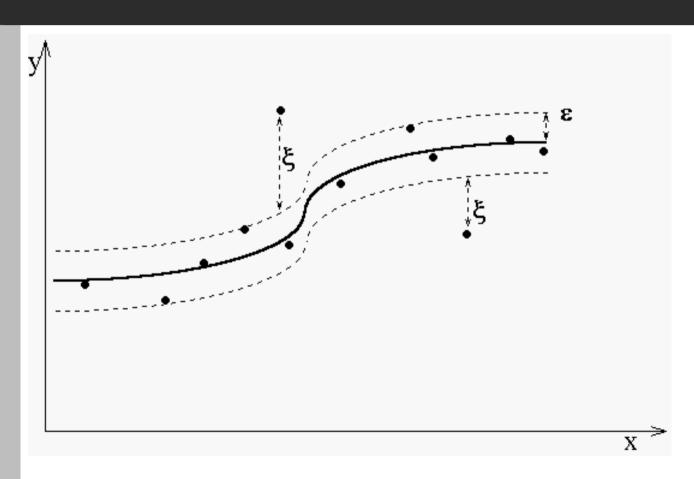
• Box constraints $W(\alpha) = \sum_{i} \alpha_{i} - \frac{1}{2} \sum_{i,j} \alpha_{i} \alpha_{j} y_{i} y_{j} \langle x_{i}, x_{j} \rangle$ $0 \le \alpha_{i} \le C$ $\sum \alpha_{i} y_{i} = 0$

The regression case

 For regression, all the above properties are retained, introducing epsilon-insensitive loss:



Regression: the ϵ -tube



Implementation Techniques

Maximizing a quadratic function, subject to a linear equality constraint (and inequalities as well)

$$W(\alpha) = \sum_{i} \alpha_{i} - \frac{1}{2} \sum_{i,j} \alpha_{i} \alpha_{j} y_{i} y_{j} K(x_{i}, x_{j})$$

$$\alpha_i \geq 0$$

$$\sum_{i} \alpha_{i} y_{i} = 0$$

Simple Approximation

- Initially complex QP pachages were used.
- Stochastic Gradient Ascent (sequentially update 1 weight at the time) gives excellent approximation in most cases

$$\alpha_i \leftarrow \alpha_i + \frac{1}{K(x_i, x_i)} \left(1 - y_i \sum \alpha_i y_i K(x_i, x_j) \right)$$

Full Solution: S.M.O.

- SMO: update two weights simultaneously
- Realizes gradient descent without leaving the linear constraint (J. Platt).

Online versions exist (Li-Long; Gentile)

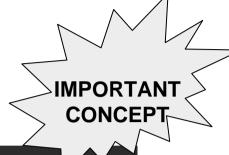
Other "kernelized" Algorithms

- Adatron, nearest neighbour, fisher discriminant, bayes classifier, ridge regression, etc. etc
- Much work in past years into designing kernel based algorithms
- Now: more work on designing good kernels (for any algorithm)

On Combining Kernels

- When is it advantageous to combine kernels?
- Too many features leads to overfitting also in kernel methods
- Kernel combination needs to be based on principles
- Alignment





Notion of similarity between kernels:
 Alignment (= similarity between Gram matrices)

$$A(K1, K2) = \frac{\langle K1, K2 \rangle}{\sqrt{\langle K1, K1 \rangle \langle K2, K2 \rangle}}$$

Many interpretations

- As measure of clustering in data
- As Correlation coefficient between 'oracles'
- Basic idea: the 'ultimate' kernel should be YY', that is should be given by the labels vector (after all: target is the only relevant feature!)

The ideal kernel

YY'=	1	1	-1	 -1
	1	1	-1	 -1
	-1	-1	1	1
	-1	-1	1	 1

Combining Kernels

 Alignment in increased by combining kernels that are aligned to the target and not aligned to each other.

$$A(K_1, YY') = \frac{\langle K_1, YY' \rangle}{\sqrt{\langle K_1, K_1 \rangle \langle YY', YY' \rangle}}$$

Spectral Machines

- Can (approximately) maximize the alignment of a set of labels to a given kernel
- By solving this problem:

$$y = \arg\max\frac{yKy}{yy'}$$

$$y_i \in \{-1,+1\}$$

 Approximated by principal eigenvector (thresholded) (see courant-hilbert theorem)

Courant-Hilbert theorem

- A: symmetric and positive definite,
- Principal Eigenvalue / Eigenvector characterized by:

$$\lambda = \max_{v} \frac{vAv}{vv'}$$

Optimizing Kernel Alignment

- One can either adapt the kernel to the labels or vice versa
- In the first case: model selection method
- Second case: clustering / transduction method

Applications of SVMs

- Bioinformatics
- Machine Vision
- Text Categorization
- Handwritten Character Recognition
- Time series analysis

Text Kernels

- Joachims (bag of words)
- Latent semantic kernels (icml2001)
- String matching kernels
- ...
- See KerMIT project

Bioinformatics

- Gene Expression
- Protein sequences
- Phylogenetic Information
- Promoters
- ...

Conclusions:

- Much more than just a replacement for neural networks. ©
- General and rich class of pattern recognition methods
- Book on SVMs: www.support-vector.net
- Kernel machines website www.kernel-machines.org
- www.NeuroCOLT.org