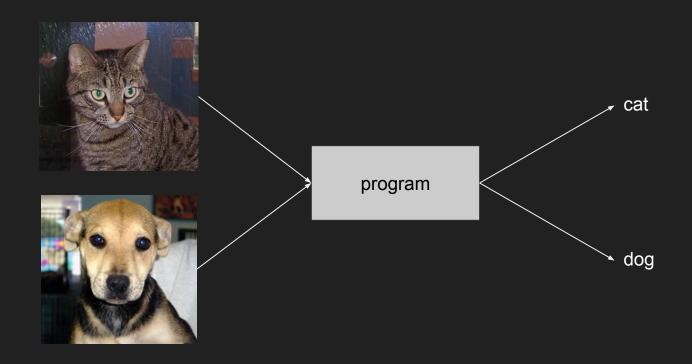
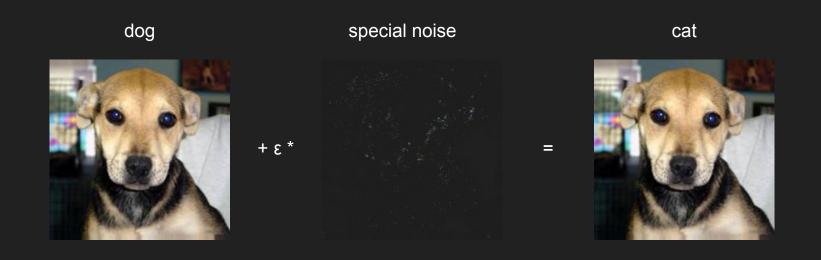
Ceci n'est pas un chat

Convolutional neural networks from scratch and Adversarial examples

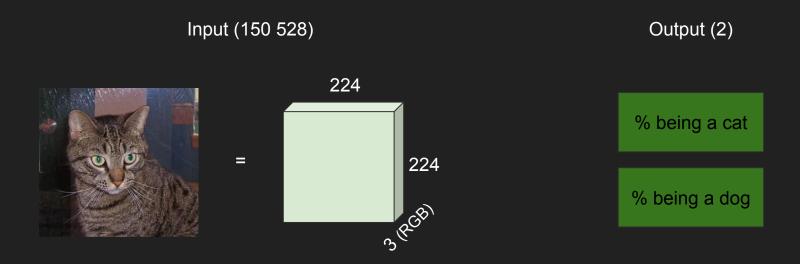
First Goal: create a good cat vs dog classifier



Second Goal: find adversary images that fool it



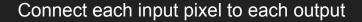
It's all numbers

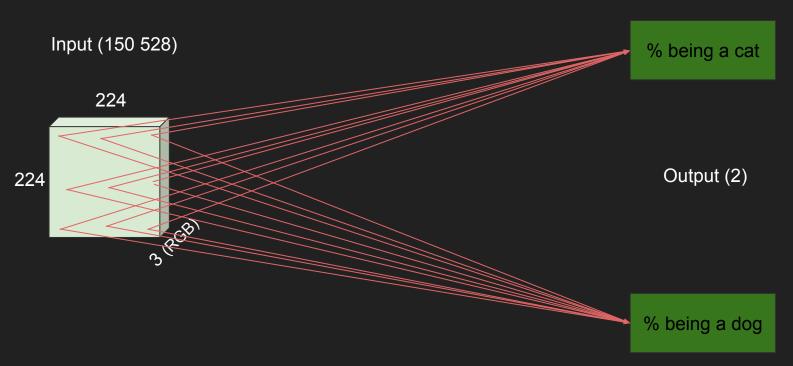


An awesome introduction to neural nets:

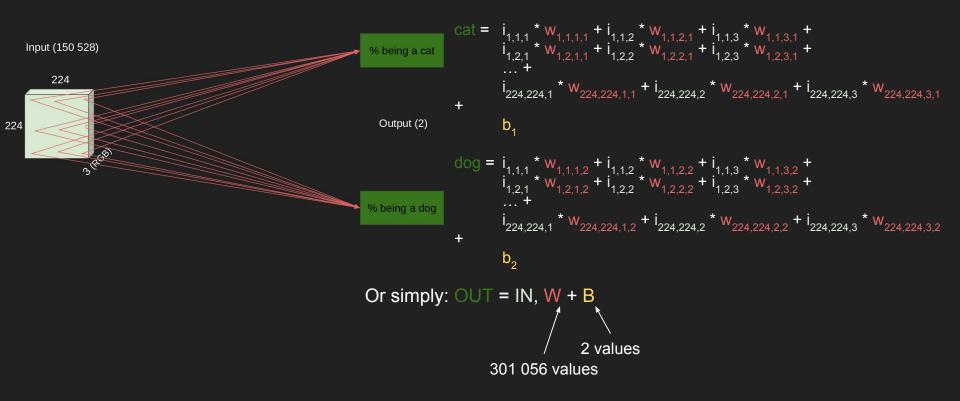
3Blue1Brown: But what is a Neural Network?

Neural networks = MANY! simple operations

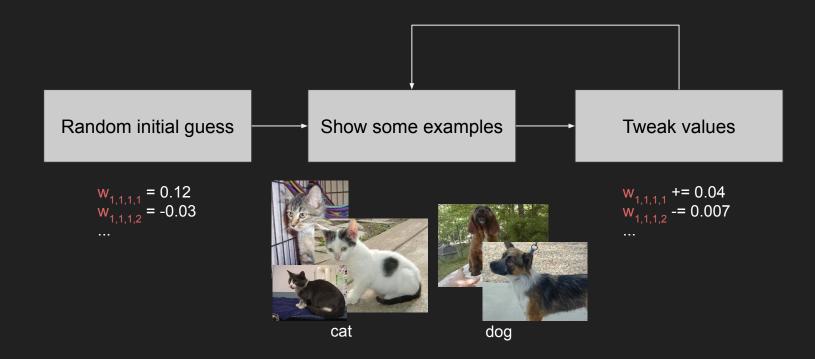




Neural networks = MANY! simple operations



Train a NN = find those values (W and B)



Keywords: stochastic gradient descent (SGD), back-propagation Nice takes on the subjects:

<u>3Blue1Brown: Gradient descent, how neural networks learn</u> <u>colah's blog: Calculus on Computational Graphs: Backpropagation</u>

Softmax: keep the output under control

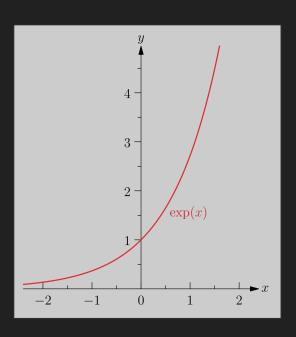
We must guarantee:

- cat + dog = 1
- 0 ≤ cat,dog ≤ 1



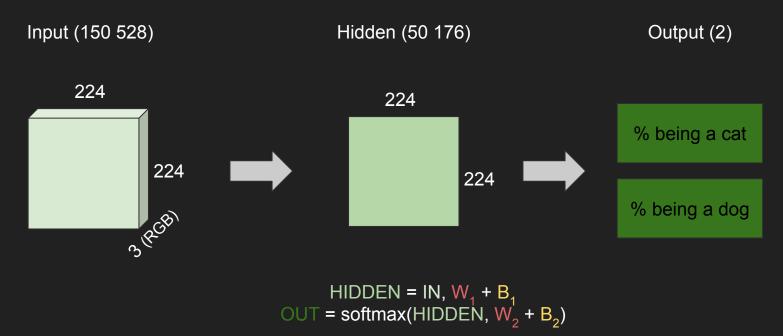
cat =
$$e^a / (e^a + e^b)$$

dog = $e^b / (e^a + e^b)$



Or simply: OUT = softmax(IN, W + B)

Let's go deeper



Problem 1: linear collapse

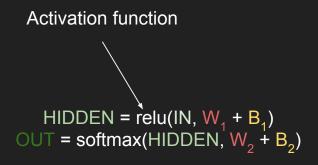
$$\begin{aligned} & \text{HIDDEN} = \text{IN, } \textbf{W}_1 + \textbf{B}_1 \\ \text{OUT} = \text{softmax}(\text{HIDDEN, } \textbf{W}_2 + \textbf{B}_2) \end{aligned}$$

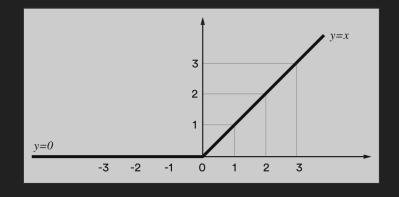


OUT = softmax(IN,
$$(W_1, W_2) + (B_1, W_2 + B_2)$$
)

Exactly the same equation form without the hidden layer

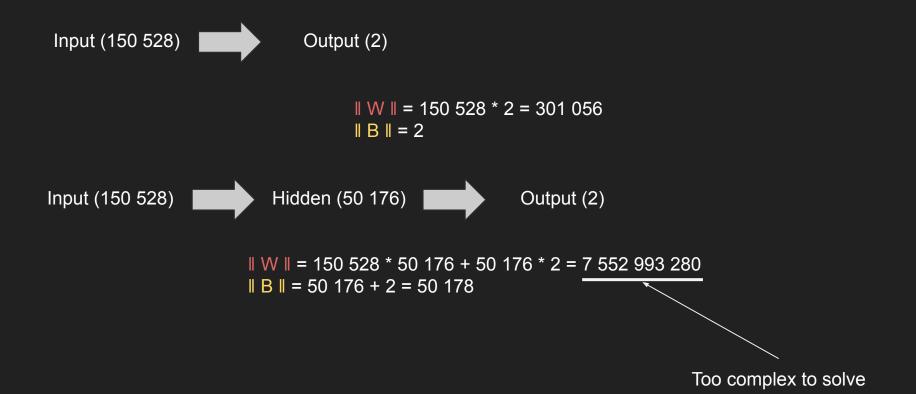
Solution: toss some non-linearity



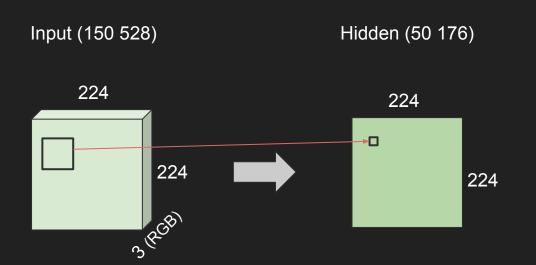


$$relu(x) = max(0,,)$$

Problem 2: parameter explosion



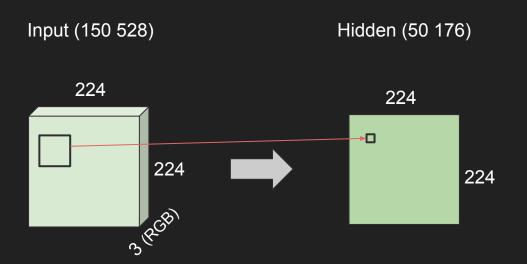
Solution - part 1: local connection



Connect each unit to only a neighboring input region, instead of all of it

Typical size: 3x3

Solution - part 2: shared kernel



Use the same set of values for each unit (invariant to translation)

Typical size: 3x3

|| W || = 9

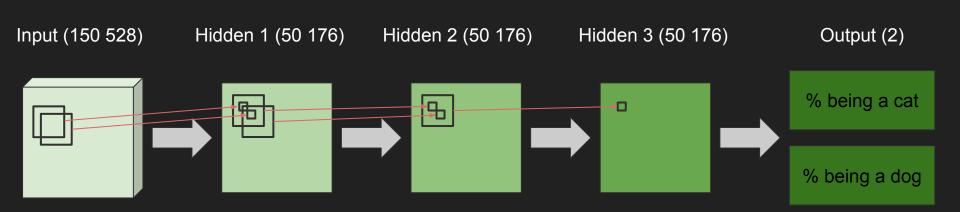
|| B || = 1

Nice extras:

Computerphile: How Blurs & Filters Work
Computerphile: Separable Filters and a Bauble

CONVOLITION

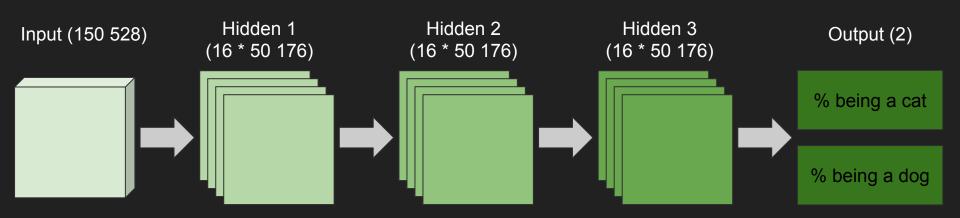
Let's go deeper



Each new layer has a more abstract representation of the input:

pixels edge corner eye

Let's go wider



Each new layer has **multiple** abstract representations of the input:

pixels vertical edge horizontal edge brightness blueness

square circle triangle

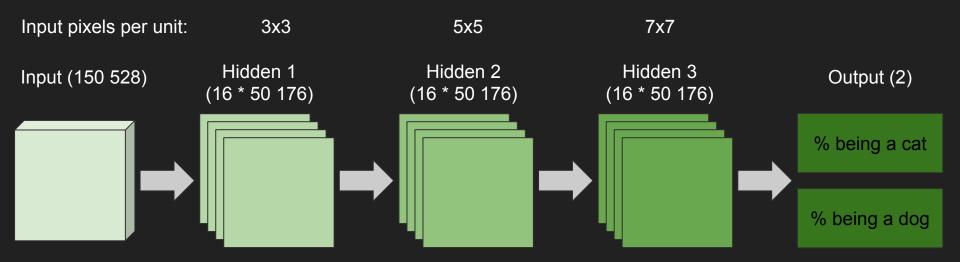
eye mouth ear

Two problems

1: Too much detail at higher layers: no need to know that many times that an eye was detected Hidden 1 Hidden 2 Hidden 3 Input (150 528) Output (2) (16 * 50 176)(16 * 50 176) (16 * 50 176) % being a cat % being a dog

Two problems

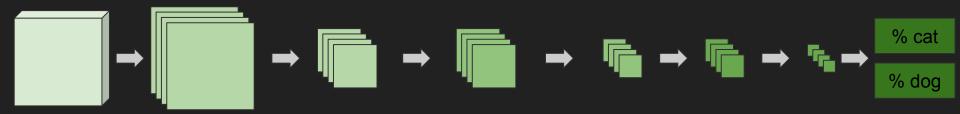
2: Too slow composition: it doesn't see the "big picture"



Solution: group pixels (pooling)

Typical: that the max of each group of 2x2 units





Let's code it

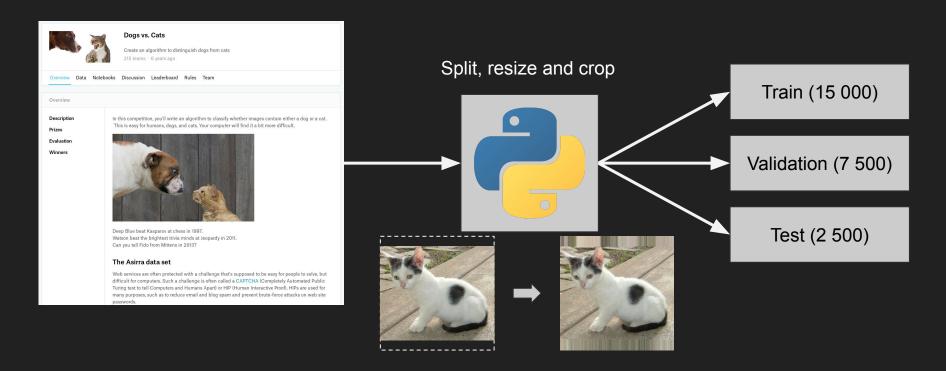


```
model = Sequential([
    Lambda(lambda x: x / 255 - 0.5, input_shape=(224, 224, 3)),
    Conv2D(16, (3, 3), padding='same', activation='relu'),
    MaxPool2D(),
    Conv2D(16, (3, 3), padding='same', activation='relu'),
    MaxPool2D(),
    Conv2D(16, (3, 3), padding='same', activation='relu'),
    MaxPool2D(),
    Flatten(),
    Dense(2, activation='softmax')
])
```

Model: "sequential"			
Layer (type)	0utput	Shape	Param #
lambda (Lambda)	(None,	224, 224, 3)	0
conv2d (Conv2D)	(None,	224, 224, 16)	448
max_pooling2d (MaxPooling2D)	(None,	112, 112, 16)	0
conv2d_1 (Conv2D)	(None,	112, 112, 16)	2320
max_pooling2d_1 (MaxPooling2	(None,	56, 56, 16)	0
conv2d_2 (Conv2D)	(None,	56, 56, 16)	2320
max_pooling2d_2 (MaxPooling2	(None,	28, 28, 16)	0
flatten (Flatten)	(None,	12544)	0
dense (Dense)	(None,	2)	25090
Total params: 30,178 Trainable params: 30,178 Non-trainable params: 0			

Documentation: <u>tf.keras.Sequential</u> Repository: <u>ceci-nest-pas-un-chat</u>

Let's prepare our data

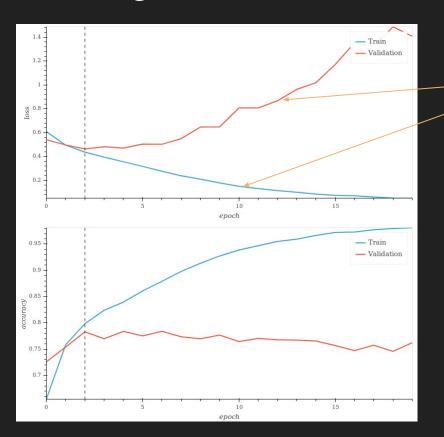


Kaggle: <u>Dogs vs. Cats</u> Python: <u>prepare_data.pv</u>

Let's train it

```
base gen = ImageDataGenerator()
train generator = base gen.flow from directory('data/training', (224, 224))
validation generator = base gen.flow from directory('data/validation', (224, 224))
test generator = base gen.flow from directory('data/test', (224, 224))
model.compile(optimizer='adam', loss='categorical crossentropy', metrics=['accuracy'])
model.fit generator(train generator, epochs=20, validation data=validation generator)
                                                      = -log(right class)
                                                                                 = right answers / total
                                pass through the
                               training set 20x
```

Training stats



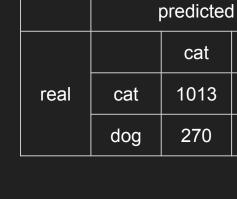
Overfit: model "memorizes" answers for test set, and generalization is compromised

Use validation to known when to stop:

More robust techniques: dropout, batch normalization, residual convolution

Results over test set





dog

237

980

cat

270



dog at 99%

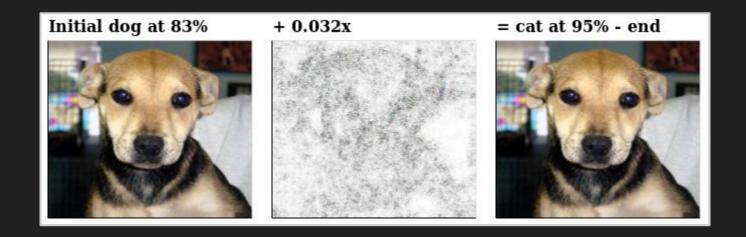






Cool! Let's break it

Goal: modify an image to manipulate the result



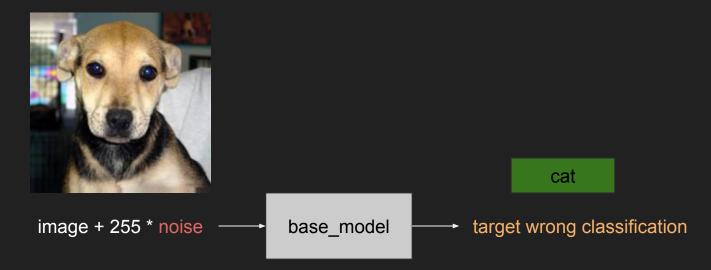
In the real world



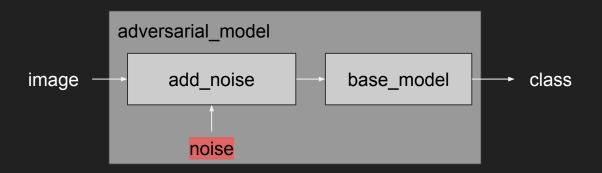
Mistaken by 45 mi/h speed limit https://arxiv.org/abs/1707.08945

Active research area

Open-source collection of attacks and defences: https://github.com/tensorflow/cleverhans

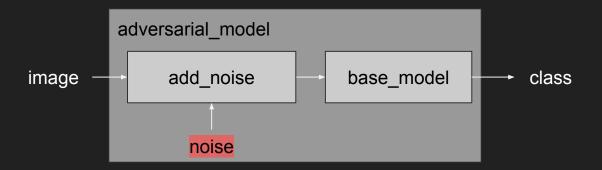


loss = 0.1 * I2(noise) - log(target_wrong_category)

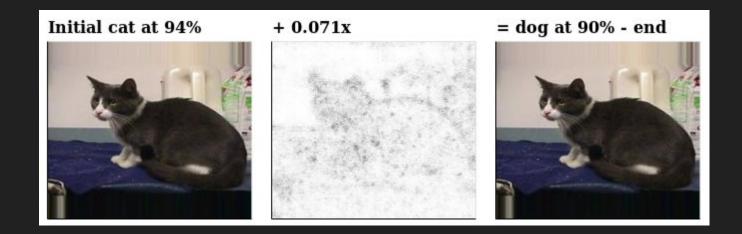


```
base_model = load_model('models/simple')
base_model.trainable = False

base_img_input = Input((224, 224, 3))
adversarial_img_layer = AddNoise(12(0.1), 255)
adversarial_img = adversarial_img_layer(base_img_input)
model_output = base_model(adversarial_img)
adversarial_model = Model(inputs=base img input, outputs=model output)
control the tradeoff
between image similarity
and fooling power
```



```
class AddNoise(Layer):
    def __init__(self, regularizer=None, scale=1, **kwargs):
        self.scale = scale
        self.regularizer = regularizer
        super().__init__(**kwargs)
    def build(self, input_shape):
        self.noise = self.add_weight('noise', input_shape[1:], regularizer=self.regularizer)
        super().build(input_shape)
    def call(self, inputs):
        return tf.clip_by_value(inputs + self.scale * self.noise, 0, 255)
```



Extra: transfer learning with VGG16

```
model input = Input((224, 224, 3))
base model input = Lambda(vqq16.preprocess input) (model input)
base model = VGG16(include top=False,
    input tensor=base model input,
    pooling='avg')
base model.trainable = False
x = base model.output
x = Dense(128, activation='relu', name='fc1')(x)
x = Dense(16, activation='relu', name='fc2')(x)
x = Dense(2, activation='softmax', name='predictions')(x)
model = Model(model input, x)
```

Model: "model"		
Layer (type)	Output Shape	Param #
input_1 (InputLayer)	[(None, 224, 224, 3)]	0
lambda (Lambda)	(None, 224, 224, 3)	0
block1_conv1 (Conv2D)	(None, 224, 224, 64)	1792
block1_conv2 (Conv2D)	(None, 224, 224, 64)	36928
block1_pool (MaxPooling2D)	(None, 112, 112, 64)	0
block2_conv1 (Conv2D)	(None, 112, 112, 128)	73856
block2_conv2 (Conv2D)	(None, 112, 112, 128)	147584
block2_pool (MaxPooling2D)	(None, 56, 56, 128)	0
block3_conv1 (Conv2D)	(None, 56, 56, 256)	295168
block3_conv2 (Conv2D)	(None, 56, 56, 256)	590080
block3_conv3 (Conv2D)	(None, 56, 56, 256)	590080
block3_pool (MaxPooling2D)	(None, 28, 28, 256)	0
block4_conv1 (Conv2D)	(None, 28, 28, 512)	1180160
block4_conv2 (Conv2D)	(None, 28, 28, 512)	2359808
block4_conv3 (Conv2D)	(None, 28, 28, 512)	2359808
block4_pool (MaxPooling2D)	(None, 14, 14, 512)	0
block5_conv1 (Conv2D)	(None, 14, 14, 512)	2359808
block5_conv2 (Conv2D)	(None, 14, 14, 512)	2359808
block5_conv3 (Conv2D)	(None, 14, 14, 512)	2359808
block5_pool (MaxPooling2D)	(None, 7, 7, 512)	0
global_average_pooling2d (Gl	(None, 512)	Θ
fc1 (Dense)	(None, 128)	65664
fc2 (Dense)	(None, 16)	2064
predictions (Dense)	(None, 2)	34
Total params: 14.782.450		

Total params: 14,782,450 Trainable params: 67,762 Non-trainable params: 14,714,688

Quite of an improvement!

previous model accuracy = 79.7%

VGG16 accuracy = 97.8%

	predicted		
real		cat	dog
	cat	1013	237
	dog	270	980

	predicted		
real		cat	dog
	cat	1223	27
	dog	28	1222

Let's break it

