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NAME OF THE LABORATORY : Control Systems

Name Gr-STI Granga Pranav Roll No. 1602-21-735-117 Page No.

## · Black diagram reduction

Aim: To reduce the given complex preparesentation of control system into simpler one and model and verify it in MATLAB.

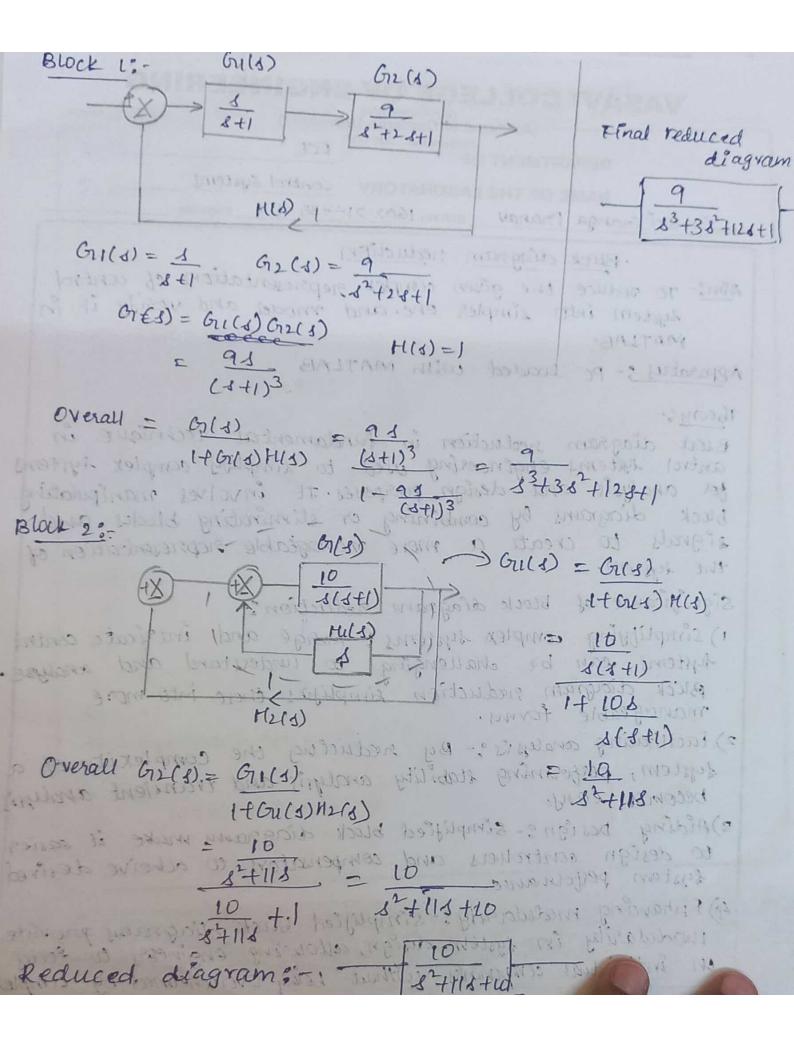
Apparatus 5- Pc loaded with MATLAB

#### Theory :-

Block diagram reduction in fundamental technique in control systems engeneering used to simplify complex systems to analysis and design purposes. It involves manipulating block diagrams by combining or eliminating blocks and signals to create a more manageable representation of the system.

Significance of block diagram reduction:

- 1) simplifying complex systems: Large and intricate control hystems can be challenging to understand and analyse. stock diagram neduction simplifies these into more manageable forms.
- 2) facilitating analysis: By reducing the complexity of a system, performing stability analysis and transient analysis
- 3) Aiding Design? simplified block diagnamy make it assies to design controllers and compensators to acheive desired system performance.
- 4) Enhancing modularity: Simplified block diagrams provide modularity in system design, allowing engineers to focus on individual components without being overwhelmed by complex it



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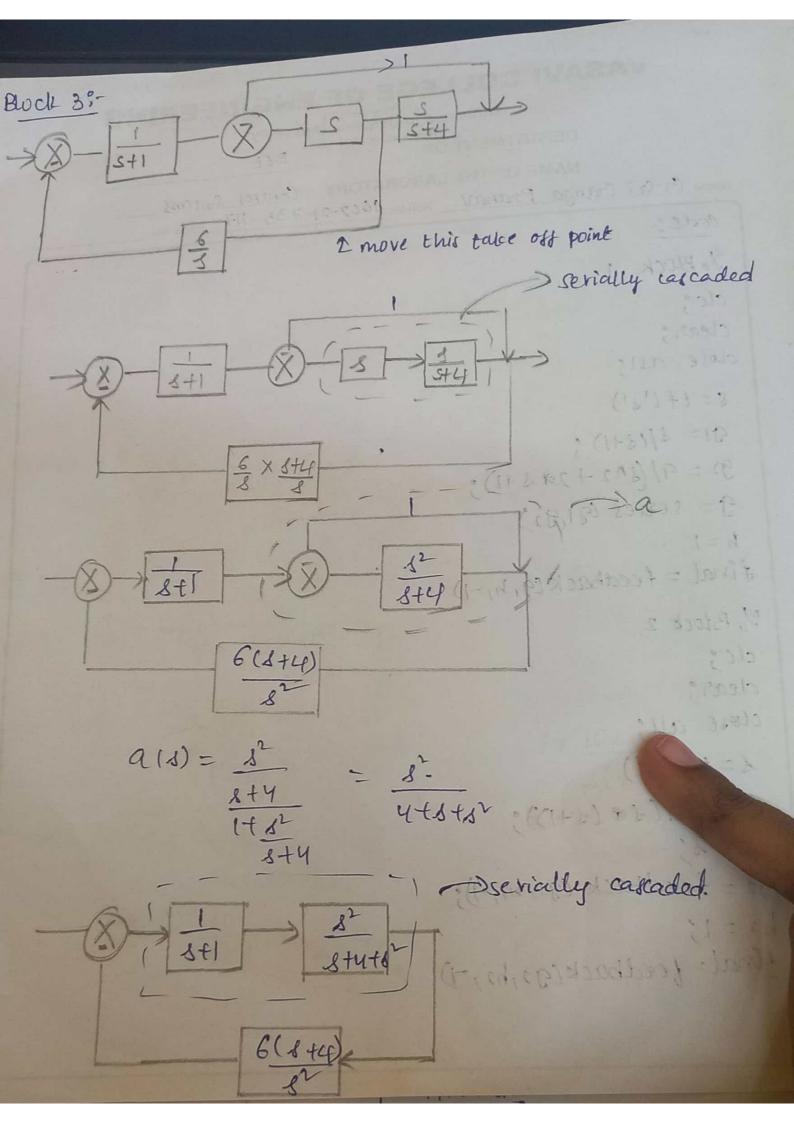
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```
code: soing no solos sind svom I
% Block 1
clc;
clear;
dose all;
S= tf ['s')
91= 8/13+1);
92=9/(8/2+2015+1);
9 = series (91,92)
final = feedback (g, h, -1)
% Block 2
dc;
dear;
close all;
                                      a(d) = d2
8= tf ('s')
 91=10/(3@(3+1));
h1 = s',
92 = feedback (91, h1,-1);
h2=1;
tinal= feedback (g2, h2, -1)
```



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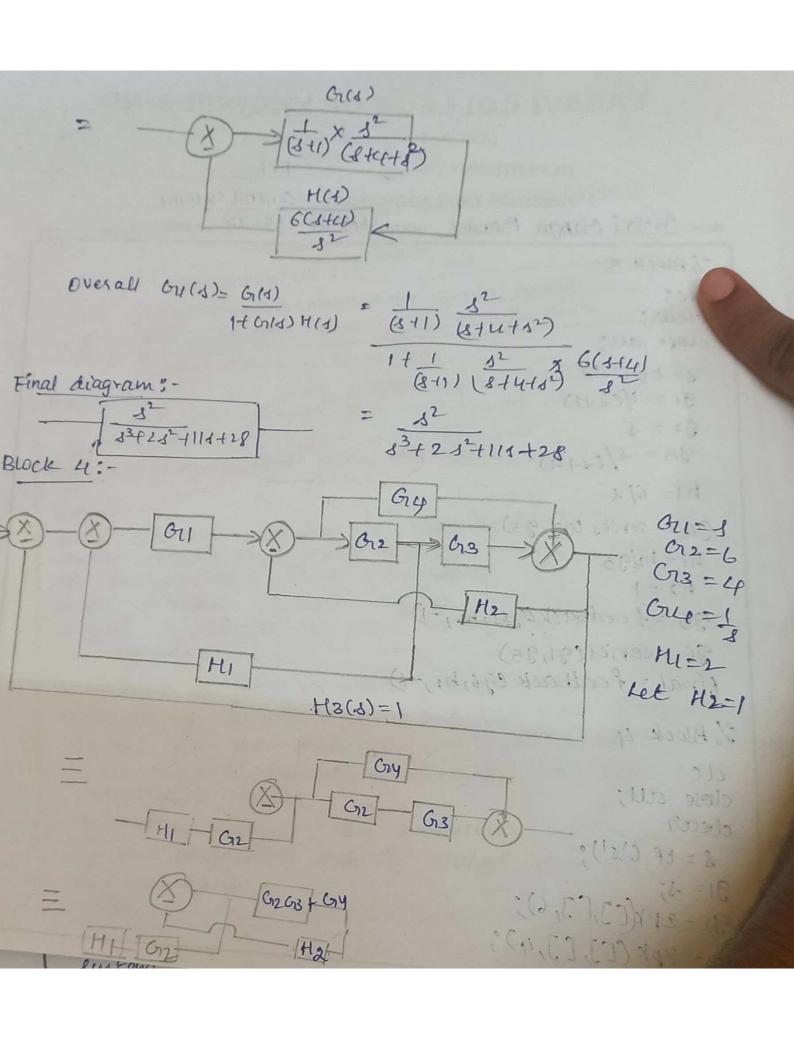
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```
% Block 3
                                    EVERAL GALADE GAR)
de;
             HCHAINIS (118) (611) LETWIST
clear;
dose all;
 d=tb('s')
 91 = 1/(s+1)
 92 = 3
 93 = 8/(1+4)
 h1-6/1
94 = series (92,93)
 hi=hilgs
  h2=1
95 = feedback(guin, -1)
 96 = series (94,95)
 final = feedback egs, h1,-1)
% Block 4
 de
close all;
dear
 8 = tf ('8'):
 91= 3;
 92=2PK[[],[],6);
                               Med 4 50 00
93= 2pk(C], [], 4);
```



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 $h_1 = 2pk (CJ,CJ,2);$   $h_{10} = 2pk (CJ,CJ,2);$   $h_{2} = 2pk (CJ,CJ,1);$   $h_{3} = 2pk (CJ,CJ,1);$   $h_{1} = 8evies (h_{11},92);$   $ext{May} = Sevies (g_{2},g_{3});$ 

Cry = Cr44843, 0001 ( 000) 11

95 = feedback (Gr4, h2, -1);

96 = sevies (95,31)

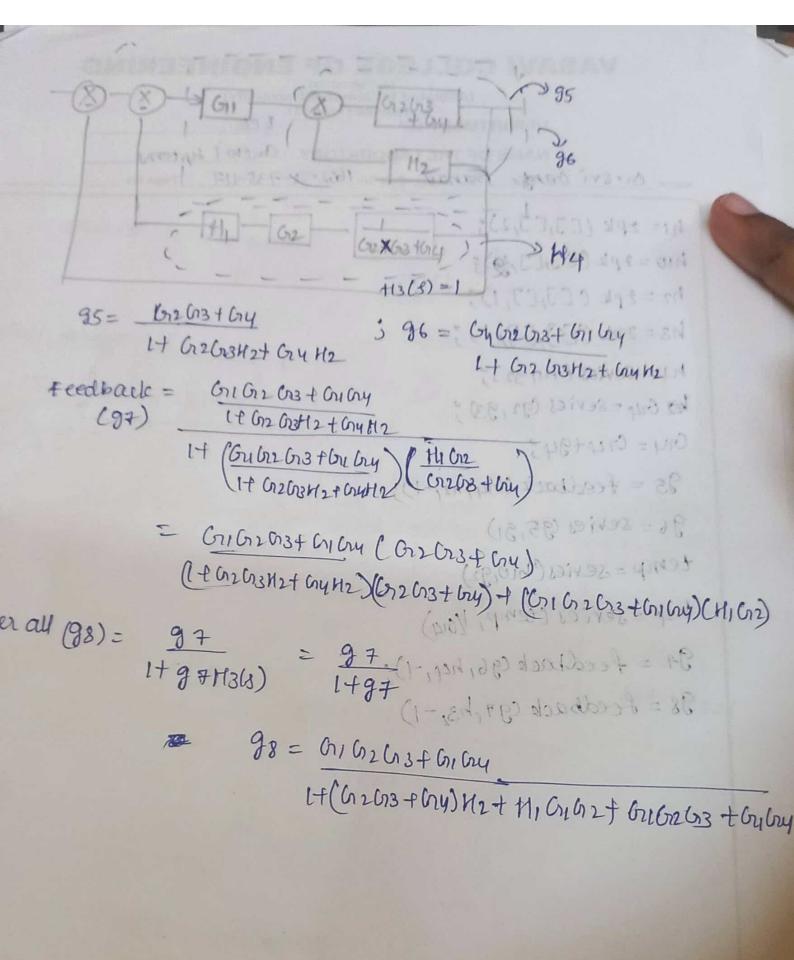
temp = series Chiorgz)

hy = series (temp, 1/04)

94 = feedback (96, her. 1);

98 = feedback (g+,h3,-1)

et (6 2613 + 614) 1(2+ 11) Grazt brother -



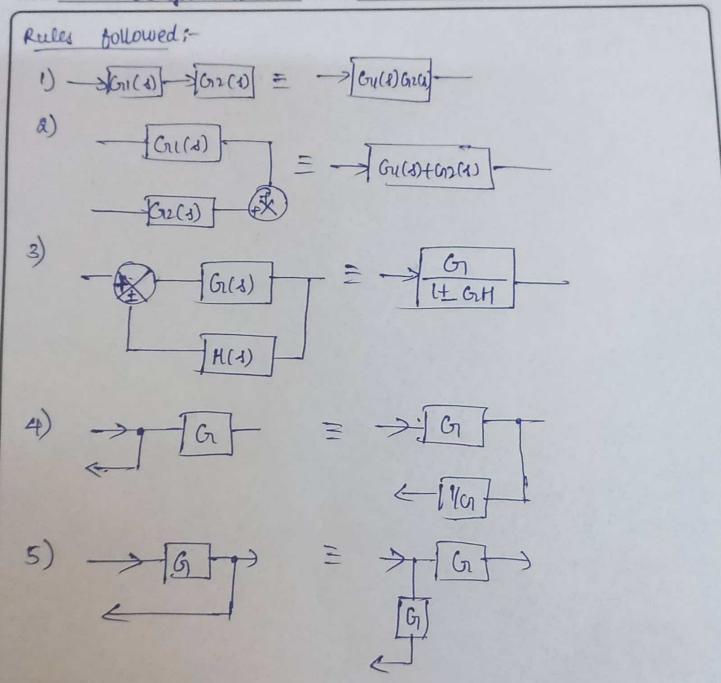
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Result: Reduced the given complex buck diagrams
by simulating in MATLAB