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Canny Edge Detector :-

- 1) Gaussian Filter
- 2) Calculate Intensity Gradients
- 3) Non-maximum suppression
- 4) Thresholding with Hysteresis

process to Apply a Gaussian Filter :-

* Define matrix size (Usually odd numbers)

Gaussian Function :-

$$G(x, y) = \frac{1}{2\pi\sigma^2 e} \cdot \frac{x^2 + y^2}{2\sigma^2}$$

$x \rightarrow$ x coordinate value

$y \rightarrow$ y coordinate value

$\pi \rightarrow 3.14$

$\sigma \rightarrow$ standard deviation

standard deviation in the Gaussian Function "controls the amount of blurring"

Small standard
Deviation
[blur less]



medium
might be more useful.

A large standard
Deviation
[blur more]

$$x\text{-coordinate} = 10$$

$$y\text{-coordinate} = 20$$

$$\sigma = 1$$

$$\pi = 3.13$$

$$= \frac{1}{2 \times 3.13 \times (1)^2} \times e^{\left(\frac{-(10^2 + 20^2)}{2(1)^2} \right)}$$

$$= \frac{1}{6.26} \times e^{\left(\frac{-500}{2} \right)}$$

$$= \frac{1}{6.26} \times e^{-250}$$

$$= 2.66919e^{-109} \times \frac{1}{6.26}$$

$$= 1.00724e^{-109}$$

Calculate Intensity Gradient:-

150	150	150	255	255
150	150	255	255	1
150	255	255	1	1
255	255	1	1	1
255	1	1	1	1

5 x 5 patch

Gradient in the y-direction (G_y)

$$\begin{bmatrix} 150 & 150 & 150 & 255 & 255 \\ 150 & \textcircled{150} & 255 & 255 & 1 \\ 150 & 255 & 255 & 1 & 1 \\ 255 & 255 & 1 & 1 & 1 \\ 255 & 1 & 1 & 1 & 1 \end{bmatrix}$$

start

$$\begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ 1 & 2 & 1 \end{bmatrix} \quad \begin{array}{l} \text{y-direction} \\ \text{kernel} \end{array}$$

Convolute the selection in the original Image with the y kernel.

$$\begin{bmatrix} 150 * -1 & 150 * -2 & 150 * -1 \\ 150 * 0 & 0 & 255 * 0 \\ 150 * 1 & 255 * 2 & 255 * 1 \end{bmatrix}$$

$$= \begin{bmatrix} -150 & -300 & -150 \\ 0 & 0 & 0 \\ 150 & 150 & 255 \end{bmatrix}$$

Adding up all the numbers in the matrix

→ G_y for the pixel in row 2, col 2 is 315

Calculation of gradient in x-direction (G_x)

Taking the same pixel, the result will be

$$\begin{bmatrix} 150 * -1 & 150 * 0 & 150 * 1 \\ 150 * -2 & 0 & 255 * 2 \\ 150 * -1 & 255 * 0 & 255 * 1 \end{bmatrix}$$

which becomes

$$\begin{bmatrix} -150 & 0 & 150 \\ -300 & 0 & 510 \\ -150 & 0 & 255 \end{bmatrix}$$

G_x for the pixel in row 2, col 2 is 315

$$\text{Magnitude (m)} = \text{Square-root } (G_x^2 + G_y^2)$$

$$= (315^2 + 315^2)$$

$$\approx 445$$

"pixels with highest magnitude (m) are likely part of an EDGES"

Then calculate gradient direction θ ,

$$\begin{aligned}\theta &= \text{atan} \left(\frac{G_y}{G_x} \right) \\ &= \text{atan} (315/315) \\ &= \text{atan} (1) \\ &= 0.78539 \text{ rad}\end{aligned}$$

→ Perform Non-maximum Suppression :-

Scans entire Image to get rid of pixels that are not part of an edge

a → b (edge) → c

If pixel b has more intensity than a and

and

a and c are in gradient direction of b

then
b is considered as edge

→ Thresholding :-

Because Non-maximum suppression is not perfect for noisy situations.

Canny Edge Detector apply thresholding → to remove the weak and keep the strong