

# Branes and DAHA Representations

Junkang Huang (Fudan University)

Based on work with S.Nawata, Y.Zhang, S.Zhuang [[arXiv:2412.19647](https://arxiv.org/abs/2412.19647)]

# Contents

- **INTRODUCTION TO BRANE QUANTIZATION**
- **GEOMETRIC SIDE: A-BRANES**
- **ALGEBRAIC SIDE: REPRESENTATIONS OF DAHA**
- **MATCHING A-BRANES & REPRESENTATIONS**

# INTRODUCTION TO BRANE QUANTIZATION

# Quantization of a symplectic manifold

## Classical system

symplectic manifold  $(M, \omega)$  + Observable functions  $f$  over  $M$

## Quantization

- Construct the **Hilbert space**  $\mathcal{H}(M, \omega)$
- Convert the functions  $f$  over  $M$  into **Hermitian operators**  $\hat{f}$  acting on  $\mathcal{H}(M, \omega)$ , i.e. construct a **quantization map**

$$Q: C^\infty(M) \rightarrow \text{Herm}(\mathcal{H}(M, \omega))$$

# Dirac axioms of quantization

Dirac proposed  $Q: C^\infty(M) \rightarrow \text{Herm}(\mathcal{H}(M, \omega))$  should satisfy:

1.  $Q$  is linear
2.  $[Q(f), Q(g)] = -i\hbar Q([f, g]_{\text{P.B.}})$  for any  $f, g \in C^\infty(M)$
3.  $Q(1) = \text{id}$

The natural guess is to take

$$Q(f) = -i\hbar X_f \equiv -i\hbar \left( \frac{\partial f}{\partial p_j} \frac{\partial}{\partial q^j} - \frac{\partial f}{\partial q^j} \frac{\partial}{\partial p_j} \right)$$

since  $[X_f, X_g] = X_{[f, g]_{\text{P.B.}}}$ , but axiom 3 is violated.

# Prequantization

Locally  $\omega = d\eta$ , and define the prequantization map

$$Q(f) = -i\hbar X_f + (-i_{X_f}\eta + f) \text{id}$$

which satisfies all three axioms. But it has two issues:

1.  $\eta$  is defined locally
2.  $\eta$  has a redundancy  $\eta \mapsto \eta + d\phi$

**Solution:** view  $\eta$  as defining a  $U(1)$  connection over  $M$  on some complex line bundle  $\mathcal{N}$  called the prequantum line bundle, then

$$Q(f) = -i\hbar \nabla_{X_f} + f \text{id} \text{ and } \omega \text{ is simply the curvature on } \mathcal{N}.$$

# Geometric quantization

However, the space  $Q(f)$  acts is  $\Gamma(\mathcal{N})$ : sections over  $M$ , while **wavefunctions** are local sections over the **configuration space** with half dimension as  $M$ .

**Solution:** Introduce a **polarization** on the space  $\Gamma(\mathcal{N})$ , and declare the **polarized sections** to be the wavefunctions, resulting in a **Hilbert space**  $\mathcal{H}(M, \omega)$ .

# Deformation quantization

Deform a function  $f \in C^\infty(M)$  to be a formal series  $f \mapsto \sum_{k=0}^{\infty} f_k \hbar^k$  w.r.t. a formal parameter  $\hbar$ , and introduce a **star product**  $f \star g$  s.t.

$$[f, g] \equiv f \star g - g \star f \xrightarrow{\hbar \rightarrow 0} -i\hbar[f, g]_{\text{P.B.}} + O(\hbar)$$

The resulting algebra  $(C^\infty(M)^q, \star)$  is called the **deformation quantization** of  $(M, \omega)$  where  $q = e^{2\pi i \hbar}$  and Kontsevich proved: Every Poisson manifold has a deformation quantization.

# Topological A-model

Consider the **topological A-model** with target a Kähler manifold  $\mathfrak{X}$  with Kähler form  $\omega_{\mathfrak{X}} \equiv \text{Im}\Omega$  for some holomorphic 2-form  $\Omega$ .

The ring  $\mathcal{O}(\mathfrak{X})$  of **holomorphic functions** over  $\mathfrak{X}$  has a **deformation quantization** with respect to  $\Omega$ , denoted as  $\mathcal{O}^q(\mathfrak{X})$  for some  $q = e^{2\pi i \hbar}$

# Topological A-model

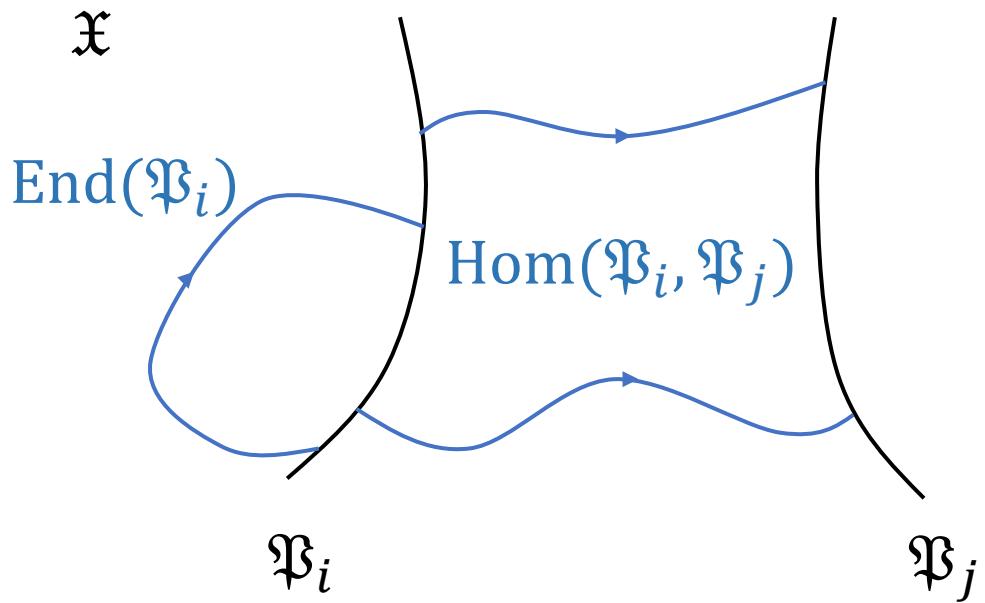
An (rank-1) **A-brane** is defined as a complex line bundle  $\mathfrak{P}: \mathcal{L} \rightarrow Y$  for a submanifold  $Y \subset \mathfrak{X}$  with a  **$U(1)$  connection** that can provide an A-type boundary condition to the worldsheet theory.

It is proved that

- $Y$  must be a **co-isotropic submanifold** of  $\mathfrak{X}$
- the curvature should satisfy certain **A-brane conditions**.

# Topological A-model

The A-brane category  $\text{A-Brane}(\mathfrak{X}, \omega_{\mathfrak{X}})$ .

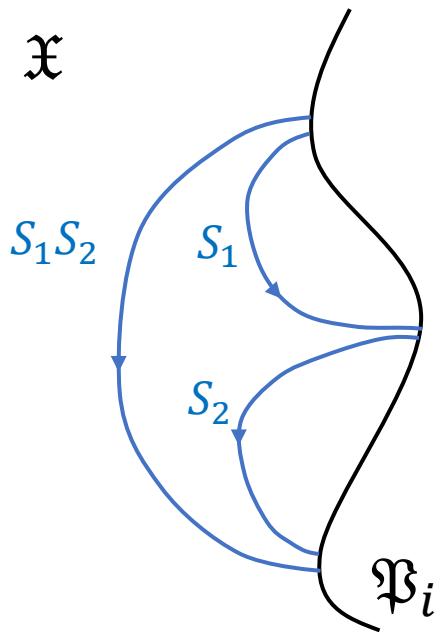


$\text{Hom}(\mathfrak{P}_i, \mathfrak{P}_j)$  :  
The space of the topological strings between  $\mathfrak{P}_i$  and  $\mathfrak{P}_j$ .

$\text{End}(\mathfrak{P}_i)$  :  
The space of the topological strings from  $\mathfrak{P}_i$  to itself.

# Canonical co-isotropic A-brane

$\text{End}(\mathfrak{P}_i)$  has an algebra structure by joining strings.



There is a unique A-brane  $\mathfrak{P}_{cc}: \mathcal{L} \rightarrow \mathfrak{X}$ , called the **canonical co-isotropic A-brane**, parametrized by a parameter  $\hbar$  that:

$$\text{End}(\mathfrak{P}_{cc}) \cong \frac{\mathcal{O}^q(\mathfrak{X})}{\text{deformation quantization}}$$

for  $q = e^{2\pi i \hbar}$  satisfying the A-brane condition

$$F + B = \text{Re}\Omega$$

# Lagrangian A-branes

Every Lagrangian submanifold  $M \subset \mathfrak{X}$ , i.e.  $\omega_{\mathfrak{X}}|_M = 0$  has a symplectic structure by the restriction  $\text{Re}\Omega|_M$ .

It can support an A-brane  $\mathfrak{P}_M: \tilde{\mathcal{L}} \otimes K_M^{-1/2} \rightarrow M$  with the A-brane condition becoming a **flatness condition**

$$\tilde{F} + B \Big|_M = 0$$

# Lagrangian A-branes

Then it can be shown

$$\text{Hom}(\mathfrak{P}_M, \mathfrak{P}_{cc}) \cong \underline{\mathcal{H}\left(M, \text{Re}\Omega\Big|_M\right)}$$

Hilbert space after  
geometric quantization

w.r.t the prequantum line bundle  $\mathcal{N} = \mathfrak{P}_M \otimes \mathfrak{P}_{cc}^{-1}$ .

**When**  $\dim_{\mathbb{C}} \mathfrak{X} = 2$  we can use the B-model perspective to calculate the dimension of the Hilbert space to be

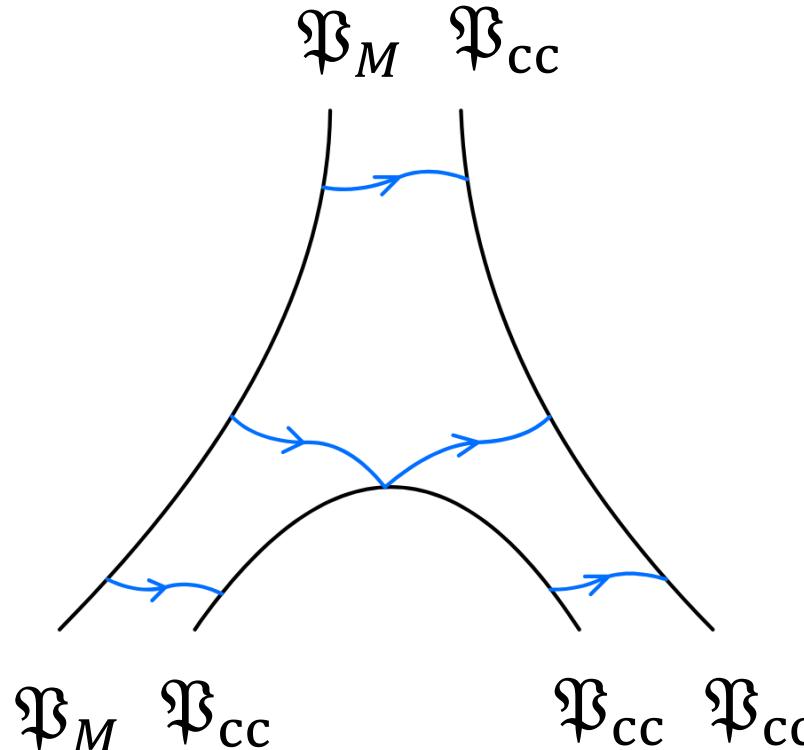
$$\dim \mathcal{H}\left(M, \text{Re}\Omega\Big|_M\right) = \frac{\text{vol}(M)}{\hbar} = \boxed{\int_M \frac{\text{Re}\Omega}{2\pi} \in \mathbb{Z}}$$

quantization  
condition

which provides a criterion of the existence of a Lagrangian A-brane on  $M$ .

# Relate Geometry to Algebra

$\text{End}(\mathfrak{P}_{cc})$  acts naturally on  $\text{Hom}(\mathfrak{P}_M, \mathfrak{P}_{cc})$  by right composition:



This provides a correspondence:

$$\text{A-Brane}(\mathfrak{X}, \omega_{\mathfrak{X}}) \leftrightarrow \text{Rep}(\mathcal{O}^q(\mathfrak{X}))$$

In particular:

compact A-branes  $\leftrightarrow$  finite-dim reps

non-compact A-branes  $\leftrightarrow$  infinite-dim reps

# In our project

$\mathfrak{X}$  is the **Coulomb branch** of vacua of the 4d  $\mathcal{N} = 2$   $SU(2)$  SQCD with 4 hypermultiplets, compactified on  $S^1$ , which is a **hyper-Kähler manifold** with:

complex structures  $I, J, K$ , Kähler forms  $\omega_I, \omega_J, \omega_K$

holomorphic symplectic forms

$$\Omega_I = \omega_J + i\omega_K, \quad \Omega_J = \omega_K + i\omega_I, \quad \Omega_K = \omega_I + i\omega_J$$

# In our project

Set  $\Omega = \Omega_J/i\hbar$ , the deformation quantization  $\mathcal{O}^q(\mathfrak{X}) \cong S\ddot{H}$  is the spherical Double Affine Hecke Algebra(DAHA) of type  $C^\vee C_1$ .

Assume  $\hbar = |\hbar| e^{i\vartheta}$  then

$$\text{Re}\Omega = \frac{1}{|\hbar|} (\omega_I \cos\vartheta - \omega_K \sin\vartheta)$$

$$\omega_{\mathfrak{X}} = \text{Im}\Omega = -\frac{1}{|\hbar|} (\omega_I \sin\vartheta + \omega_K \cos\vartheta)$$

If  $\hbar$  is real  $\text{Re}\Omega = \omega_I/|\hbar|$ ,  $\omega_{\mathfrak{X}} = -\omega_K/|\hbar|$

If  $\hbar$  is pure imaginary  $\text{Re}\Omega = -\omega_K/|\hbar|$ ,  $\omega_{\mathfrak{X}} = \omega_I/|\hbar|$

# In our project

## 1. Geometric side:

Identify the Lagrangian submanifolds  $M$  i.e.  $\omega_{\mathfrak{X}}|_M = 0$  in  $\mathfrak{X}$ , and find their quantization conditions  $\text{vol}(M)/\hbar = \int_M \text{Re}\Omega/2\pi \in \mathbb{Z}$

## 2. Algebraic side:

Construct the representations of  $S\ddot{H}$ , find the conditions of appearance of these representations: shortening conditions.

## 3. Matching A-branes and representations:

By explicitly matching the quantization conditions and the shortening conditions.

# **GEOMETRIC SIDE: A-BRANES**

# Geometry of Coulomb branch

Views from distinct complex structures provide multiple tools to analyze the geometry of  $\mathfrak{X}$ :

**In complex structure  $I$**   $\mathfrak{X}$  is the total space of a **Hitchin system**

**In complex structure  $J$**   $\mathfrak{X}$  is an **affine cubic surface**

**In complex structure  $K$**   $\mathfrak{X}$  is the conjugation as in complex structure  $I$

# In complex structure I: Hitchin system

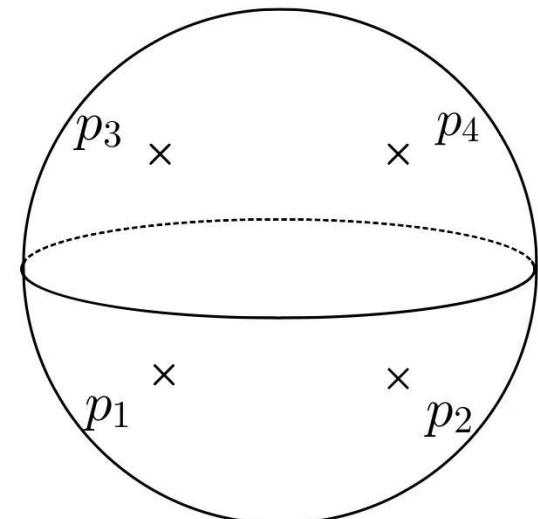
$\mathfrak{X}$  is the moduli space  $\mathcal{M}_H \left( C_{0,4}, SU(2) \right)$  of **Higgs bundles**  $(E, A, \varphi)$

over  $C_{0,4}$ , with ramification parameters  $\alpha_j, \beta_j, \gamma_j$  around puncture

$p_j$  ( $j = 1, 2, 3, 4$ ):

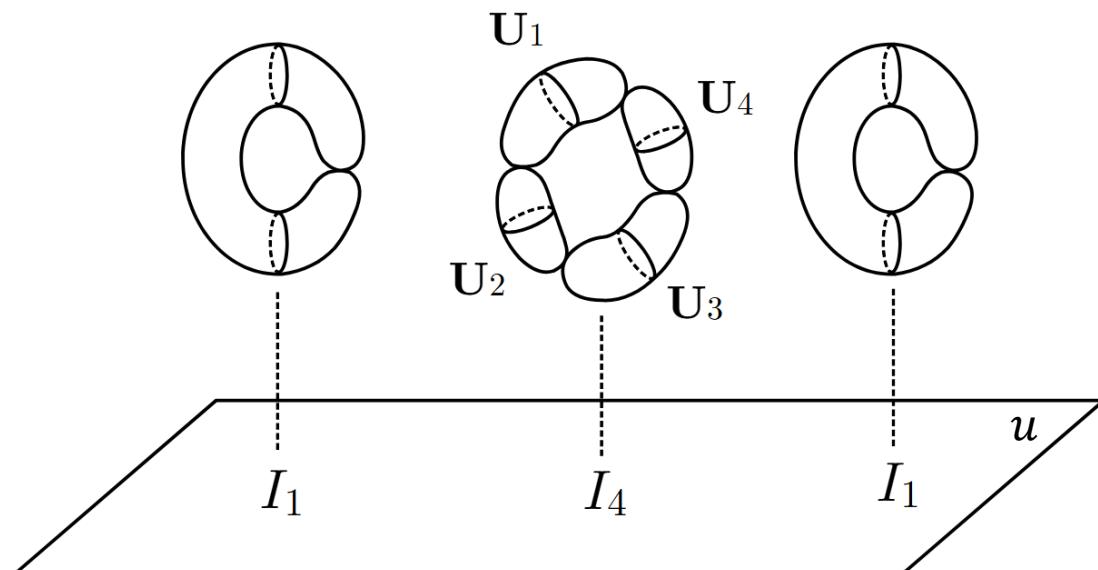
$$A = \alpha_j d\vartheta + \dots$$
$$\varphi = (\beta_j + \gamma_j) \frac{dz}{2z} + \dots$$

where  $z = re^{i\vartheta}$  is the local coordinates.



# In complex structure I: Hitchin system

$\mathfrak{X}$  admits a fibration structure, called the **Hitchin fibration**, projecting to the Hitchin base ( $u$ -plane).



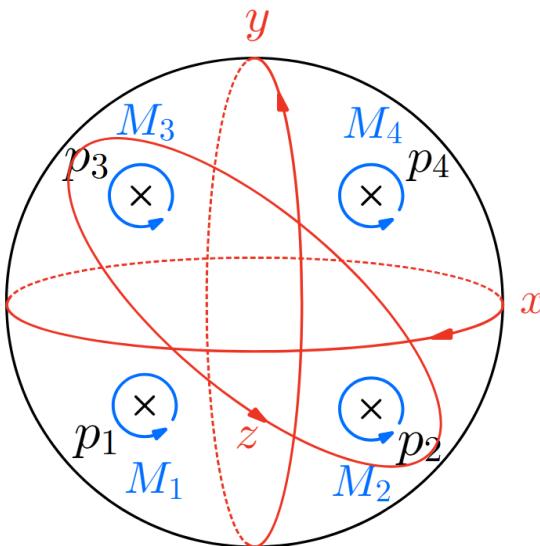
**Generic fibers**  
compact tori

**Singular fibers**  
by Kodaira classification

# In complex structure $J$ : cubic surface

$\mathfrak{X}$  is the moduli space  $\mathcal{M}_{\text{flat}}(C_{0,4}, SL(2, \mathbb{C}))$  of **flat  $SL(2, \mathbb{C})$ -connections** over  $C_{0,4}$ , described by the cubic equation

$$-xyz + x^2 + y^2 + z^2 + \theta_1x + \theta_2y + \theta_3z + \theta_4 = 0$$



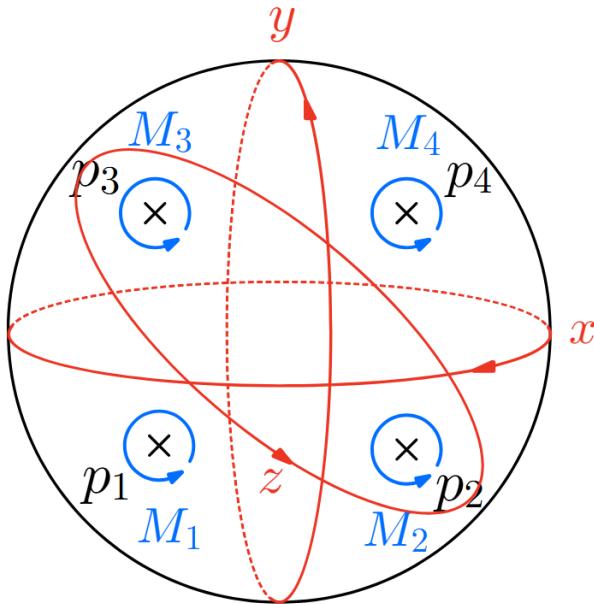
$$\theta_1 = \bar{t}_1 \bar{t}_2 + \bar{t}_3 \bar{t}_4$$

$$\theta_2 = \bar{t}_1 \bar{t}_3 + \bar{t}_2 \bar{t}_4$$

$$\theta_3 = \bar{t}_1 \bar{t}_4 + \bar{t}_2 \bar{t}_3$$

for four parameters  $t_j$ .

# In complex structure $J$ : cubic surface



parameters  $t_j$  can be interpreted as monodromy parameters around  $p_j$  that

$$t_j + t_j^{-1} = \text{Tr}(M_j)$$

related to  $\alpha_j, \beta_j, \gamma_j$  by

$$t_j = \exp(-2\pi(\gamma_j + i\alpha_j))$$

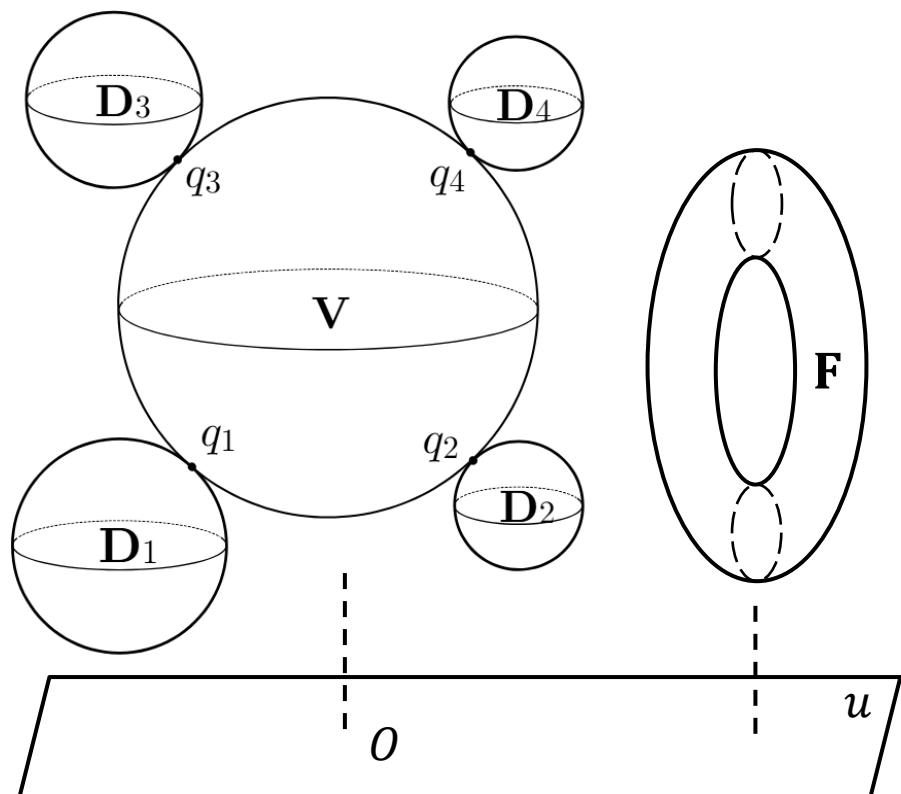
# Identifying Lagrangian submanifolds

**Set  $\beta_j = \gamma_j = 0$**  there is a single singular fiber of type  $I_0^*$  at  $u = 0$ .

**Set  $\hbar$  real** the compact Lagrangian submanifolds are the components of fibers:

Generic fiber  $\mathbf{F}$  with unit volume  
Components  $\mathbf{D}_j, \mathbf{V}$  of the  $I_0^*$  singular fiber satisfying

$$2\text{vol}(\mathbf{V}) + \sum_{j=1}^4 \text{vol}(\mathbf{D}_j) = 1$$



# Volumes and wall-crossing

The volumes are parametrized by the ramification parameter  $\alpha_j$  as

$$\text{vol}(\mathbf{D}_1) = 1 - \theta \cdot \alpha,$$

$$\text{vol}(\mathbf{D}_3) = e^2 \cdot \alpha,$$

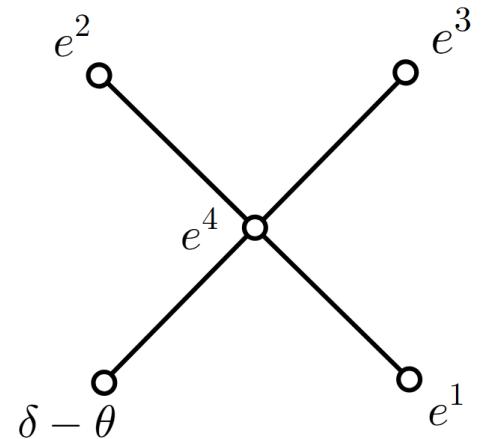
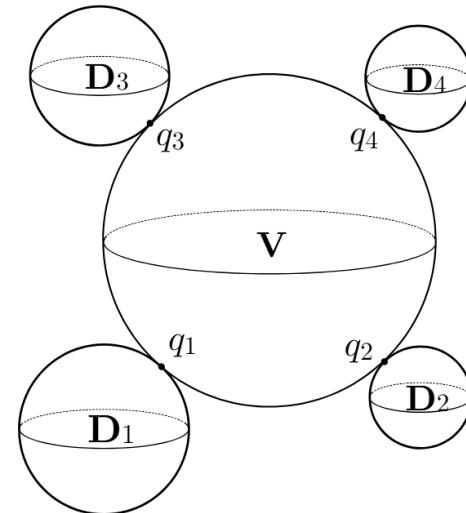
$$\text{vol}(\mathbf{V}) = e^4 \cdot \alpha$$

$$\text{vol}(\mathbf{D}_2) = e^1 \cdot \alpha,$$

$$\text{vol}(\mathbf{D}_4) = e^3 \cdot \alpha,$$

with  $e^\alpha$  the simple  $D_4$  roots,  $\theta$  the highest  $D_4$  root and

$$\theta \cdot \alpha = \sum_{j=1}^4 \theta_j \alpha_j, \quad e^\alpha \cdot \alpha \equiv \sum_{j=1}^4 (e^\alpha)_j \alpha_j$$



# Volumes and wall-crossing

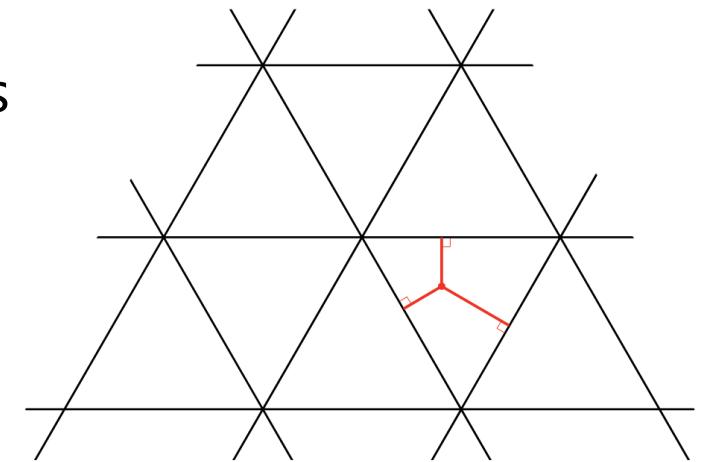
The volumes exhibit complicated **wall-crossing** behavior with walls determined by

$$t^r = t_1^{r_1} t_2^{r_2} t_3^{r_3} t_4^{r_4} = 1, \quad \forall r = (r_1, r_2, r_3, r_4) \in R(D_4)$$

When crossing the wall determined by a root  $r^a$ , the volumes transform by Weyl reflecting the root vectors

$$r^b \mapsto s_{r^a}(r^b)$$

The chambers then correspond to the **affine Weyl alcove** of type  $D_4$ .



# **ALGEBRAIC SIDE: REPRESENTATIONS OF DAHA**

# Spherical DAHA of type $C^\vee C_1$

$\ddot{SH}$  is parametrized by 4 parameters  $t_j$  and a deformation parameter  $q$ , and can be presented as

$$[x, y]_q = (q^{-1} - q)z + \left(q^{-\frac{1}{2}} - q^{\frac{1}{2}}\right)\theta_3,$$

$$[y, z]_q = (q^{-1} - q)x + \left(q^{-\frac{1}{2}} - q^{\frac{1}{2}}\right)\theta_1,$$

$$[z, x]_q = (q^{-1} - q)y + \left(q^{-\frac{1}{2}} - q^{\frac{1}{2}}\right)\theta_2,$$

$$-q^{-\frac{1}{2}}xyz + q^{-1}x^2 + qy^2 + q^{-1}z^2 + q^{-\frac{1}{2}}\theta_1x + q^{\frac{1}{2}}\theta_2y + q^{-\frac{1}{2}}\theta_3z + \theta_4(q) = 0,$$

where

$$[x, y]_q \equiv q^{-\frac{1}{2}}xy - q^{\frac{1}{2}}yx$$

# Spherical DAHA of type $C^\vee C_1$

$$\theta_1 = \bar{t}_1 \bar{t}_2 + \bar{t}_3 \bar{t}_4 = \chi_v$$

$$\theta_2 = \bar{t}_1 \bar{t}_3 + \bar{t}_2 \bar{t}_4 = \chi_s$$

$$\theta_3 = \bar{t}_1 \bar{t}_4 + \bar{t}_2 \bar{t}_3 = \chi_c$$

$$\theta_4(q) = \bar{t}_1^{-2} + \bar{t}_2^{-2} + \bar{t}_3^{-2} + \bar{t}_4^{-2} + \bar{t}_1 \bar{t}_2 \bar{t}_3 \bar{t}_4 - \bar{q} - 2 = \chi_{\text{adj}} - \bar{q} + 2$$

with  $\bar{t} \equiv t + t^{-1}$  and  $\chi_{\mathfrak{R}}$  the character of the representation  $\mathfrak{R}$  of  $D_4$  Lie algebra.  $\Leftarrow SO(8)$  flavor symmetry

# Interpretation from physics

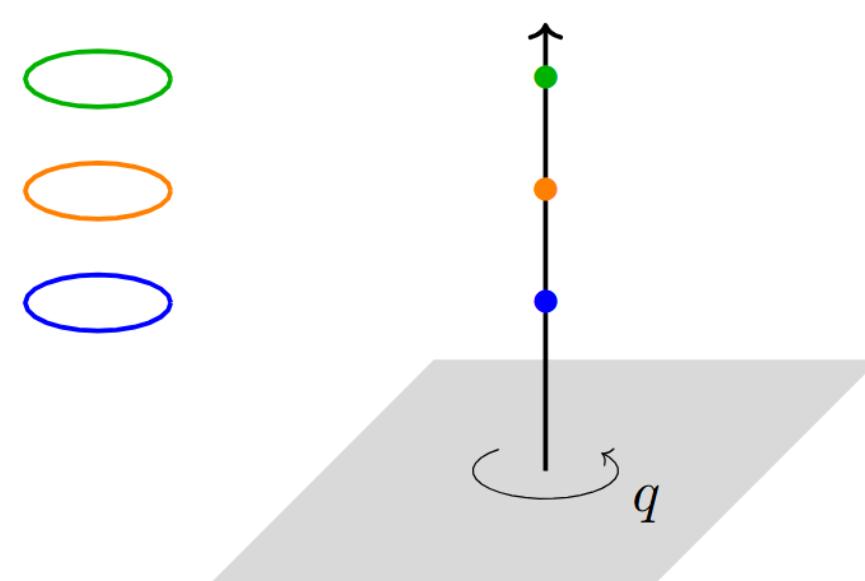
The coordinate ring  $\mathcal{O}(\mathfrak{X})$  is generated by  $x, y, z$ . Physically

$x \leftrightarrow$  Wilson loop

$y \leftrightarrow$  't Hooft loop

$z \leftrightarrow$  dyonic loop

The deformation quantization  $\mathcal{O}^q(\mathfrak{X}) \cong S\ddot{H}$  can be interpreted as putting the 4d theory on an  $\Omega$ -background with parameter  $q$ .



$$S^1 \times$$

$$\mathbb{R} \times_q \mathbb{R}^2$$

# Symmetries of $S\ddot{H}$

**Weyl group**  $W(D_4)$  Since parameters are in  $D_4$  characters.

**Braid group**  $B_3$

$$\tau_+: (x, y, z, \theta_1, \theta_2, \theta_3, \theta_4) \mapsto (x, q^{-\frac{1}{2}}(xy - q^{-\frac{1}{2}}z - \theta_3), y, \theta_1, \theta_3, \theta_2, \theta_4)$$

$$\tau_-: (x, y, z, \theta_1, \theta_2, \theta_3, \theta_4) \mapsto (q^{-\frac{1}{2}}(xy - q^{-\frac{1}{2}}z - \theta_3), y, x, \theta_3, \theta_2, \theta_1, \theta_4)$$

$$\sigma: (x, y, z, \theta_1, \theta_2, \theta_3, \theta_4) \mapsto (y, x, q^{-\frac{1}{2}}(xy - q^{-\frac{1}{2}}z - \theta_3), \theta_2, \theta_1, \theta_3, \theta_4)$$

**Sign-flip**  $\mathbb{Z}_2 \times \mathbb{Z}_2$

$$\xi_1: (x, y, z, \theta_1, \theta_2, \theta_3, \theta_4) \mapsto (-x, y, -z, -\theta_1, \theta_2, -\theta_3, \theta_4)$$

$$\xi_2: (x, y, z, \theta_1, \theta_2, \theta_3, \theta_4) \mapsto (x, -y, -z, \theta_1, -\theta_2, -\theta_3, \theta_4)$$

$$\xi_3: (x, y, z, \theta_1, \theta_2, \theta_3, \theta_4) \mapsto (-x, -y, z, -\theta_1, -\theta_2, \theta_3, \theta_4)$$

# Polynomial representations

The **Askey-Wilson polynomials** are defined by

$$P_n(X; q, t) = \frac{(qab, qac, qad; q)_n}{\frac{n}{q^{\frac{1}{2}}} a^n (abcdq^{n+1}; q)_n} \phi_3^4 \left( \begin{matrix} q^{-n}, q^{n+1}abcd, q^{\frac{1}{2}}aX, q^{\frac{1}{2}}aX^{-1} \\ qab, qac, qad \end{matrix}; q, q \right)$$
$$a = -t_1 t_2, \quad b = -\frac{t_1}{t_2}, \quad c = -t_3 t_4, \quad d = -\frac{t_3}{t_4}$$

which is acted by  $S\ddot{H}$  by

$$x \cdot P_n(X) = P_{n+1}(X) + (\cdots)P_n(X) + (\cdots)P_{n-1}(X)$$

$$y \cdot P_n(X) = (\cdots)P_n(X)$$

$$z \cdot P_n(X) = (\cdots)P_{n+1}(X) + (\cdots)P_n(X) + (\cdots)P_{n-1}(X)$$

# Polynomial representations

Construct raising and lowering operators

$$R_n = -q^{1-n}x - qt_1t_3z + A_n, \quad L_n = -q^{n+2}x - \frac{q}{t_1t_3}z + B_n$$

for some constants  $A_n, B_n$ . They act by

$$R_n \cdot P_n(X) = r_n P_{n+1}(X), \quad L_n \cdot P_n(X) = l_n P_{n-1}(X)$$

for some constant coefficients  $r_n$  and  $l_n$  depending on  $q$  and  $t_j$ .

By imposing the Weyl group actions and the braid group actions on  $P_n(X)$ , we can obtain 24 distinct polynomial representations.

# Shortening conditions

Under certain conditions (**shortening conditions**),  $l_n$  can vanish for some  $n$ , then  $P_n, P_{n+1} \dots$  generate an infinite-dimensional submodule. And thus, we can construct a finite-dimensional representation by taking the quotient with the submodule.

$$0 \xleftarrow{L_0} P_0 \xrightleftharpoons[R_0]{R_1} P_1 \xrightleftharpoons[L_1]{L_2} \dots \xrightleftharpoons[R_{n-2}]{R_{n-1}} P_{n-1} \xrightleftharpoons[L_{n-1}]{L_n} P_n \xrightleftharpoons{\dots}$$

The shortening conditions of all the 24 polynomial representations can be expressed as

$$q^n \equiv t_1^{-r_1} t_2^{-r_2} t_3^{-r_3} t_4^{-r_4} = t^{-r}, \forall r = (r_1, r_2, r_3, r_4) \in R(D_4) \cup \{0,0,0,0\}$$

# **MATCHING GEOMETRY & ALGEBRA**

# Explicit matching

A-branes	A-brane volumes	A-brane conditions	Shortening conditions
$\mathfrak{P}_F$	1	$\frac{1}{\hbar} = m \in \mathbb{Z}$	$q^m = 1$
$\mathfrak{P}_{D_1}$	$1 - \theta \cdot \alpha$	$\frac{1 - \theta \cdot \alpha}{\hbar} = l_1 \in \mathbb{Z}$	$q^{l_1} = t^\theta$
$\mathfrak{P}_{D_2}$	$e^1 \cdot \alpha$	$\frac{e^1 \cdot \alpha}{\hbar} = l_2 \in \mathbb{Z}$	$q^{l_2} = t^{-e^1}$
$\mathfrak{P}_{D_3}$	$e^2 \cdot \alpha$	$\frac{e^2 \cdot \alpha}{\hbar} = l_3 \in \mathbb{Z}$	$q^{l_3} = t^{-e^2}$
$\mathfrak{P}_{D_4}$	$e^3 \cdot \alpha$	$\frac{e^3 \cdot \alpha}{\hbar} = l_4 \in \mathbb{Z}$	$q^{l_4} = t^{-e^3}$
$\mathfrak{P}_V$	$e^4 \cdot \alpha$	$\frac{e^4 \cdot \alpha}{\hbar} = k \in \mathbb{Z}$	$q^k = t^{-e^4}$

$q = e^{2\pi i \hbar}$   
 $t_j = e^{-2\pi i \alpha_j}$

# Summary

1. Analysis of the Lagrangian submanifolds of  $\mathfrak{X}$ , calculation of their volumes and obtain their quantization conditions.
2. Classification of the finite dimensional representations of the  $S\ddot{H}$  algebra by shortening conditions of the polynomial representations
3. One-to-one correspondence between quantization conditions and shortening conditions.