

Destruction

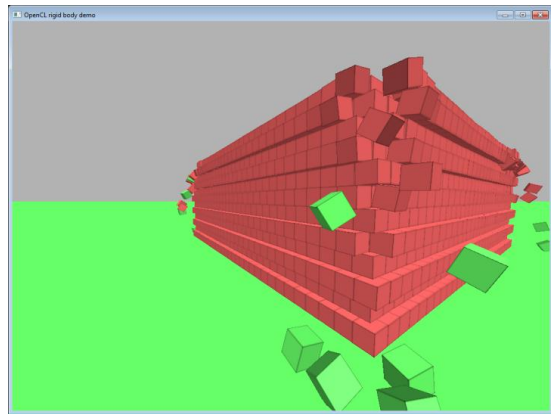
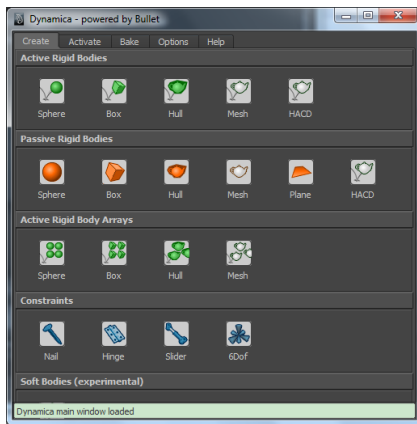
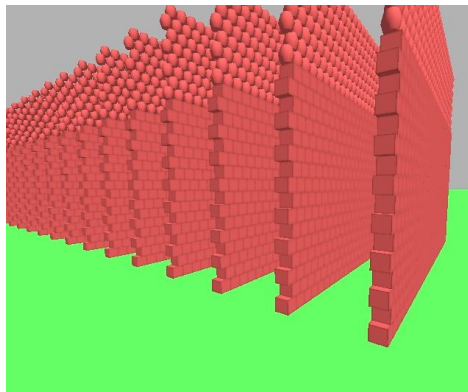
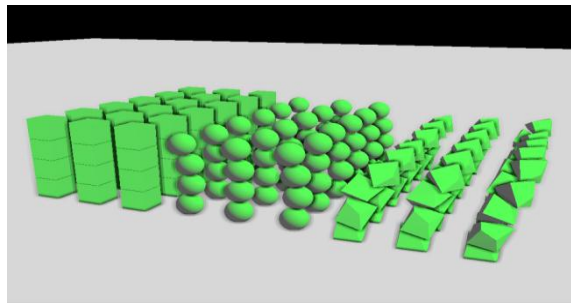
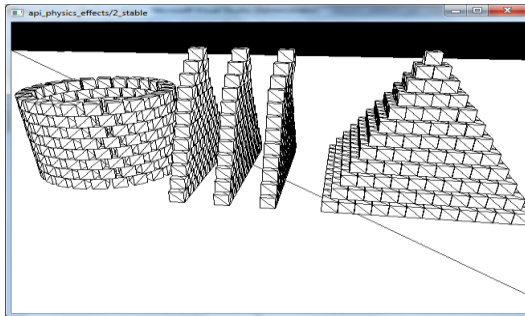
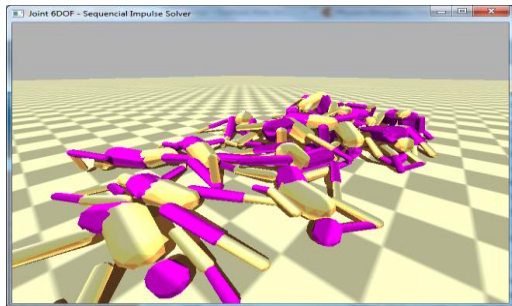
Erwin Coumans

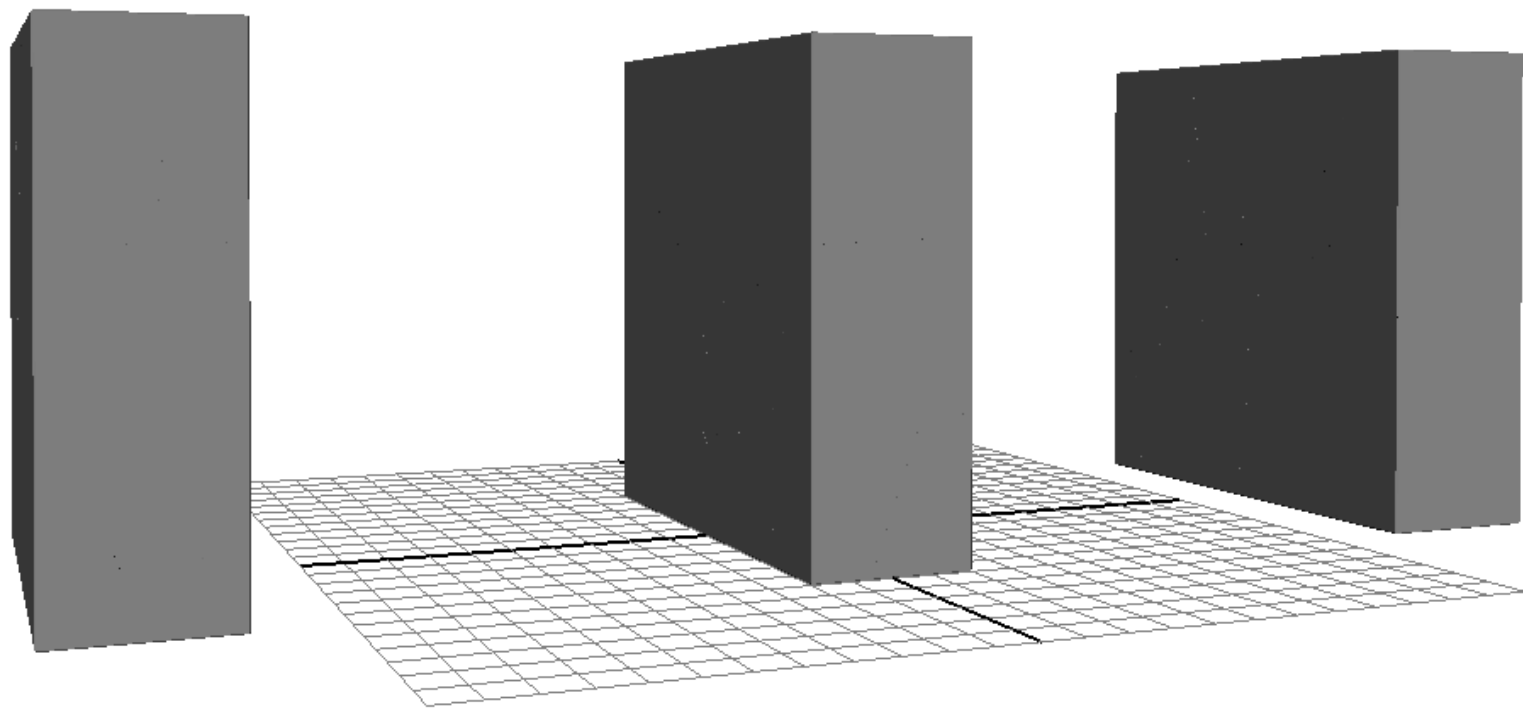
Bullet Architect @ AMD

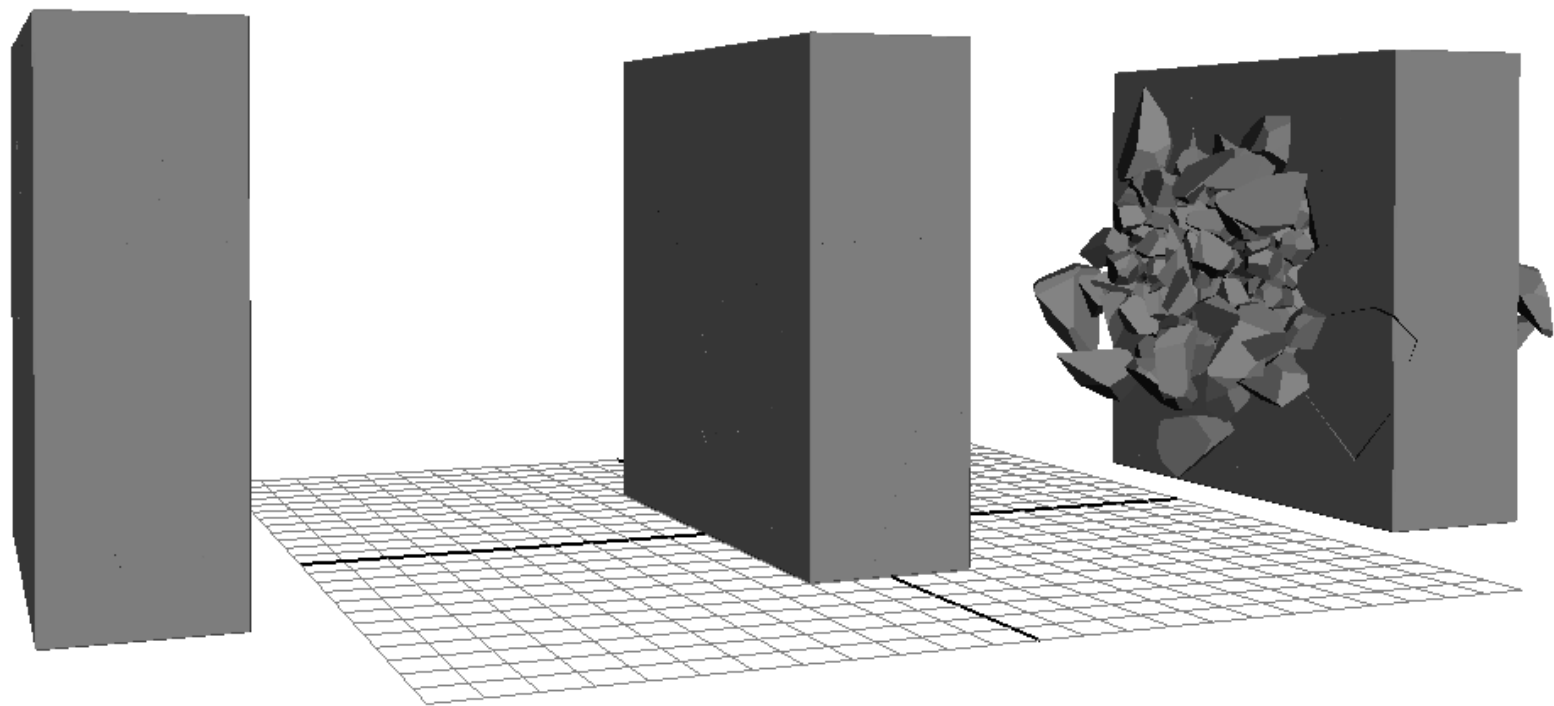
Our open source work

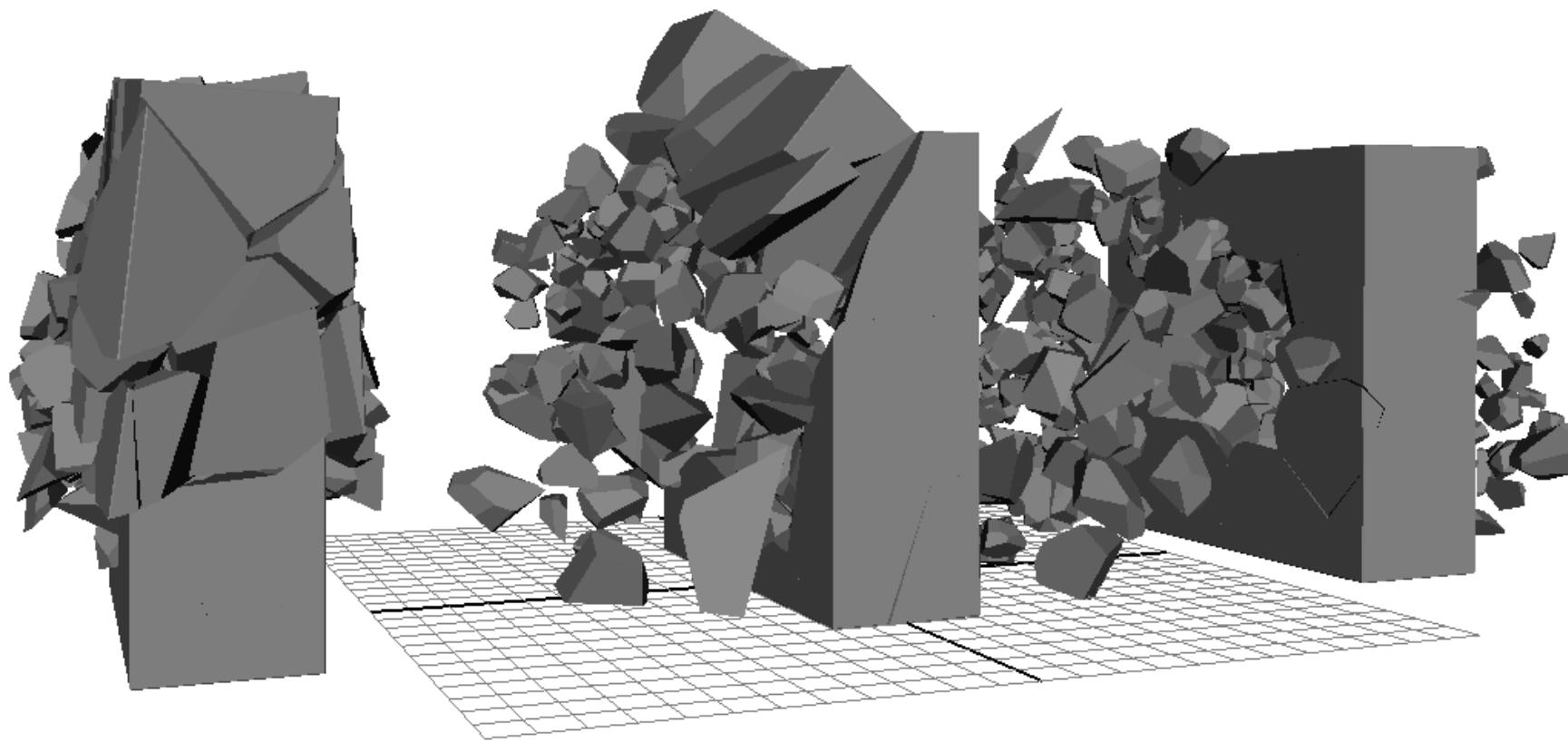
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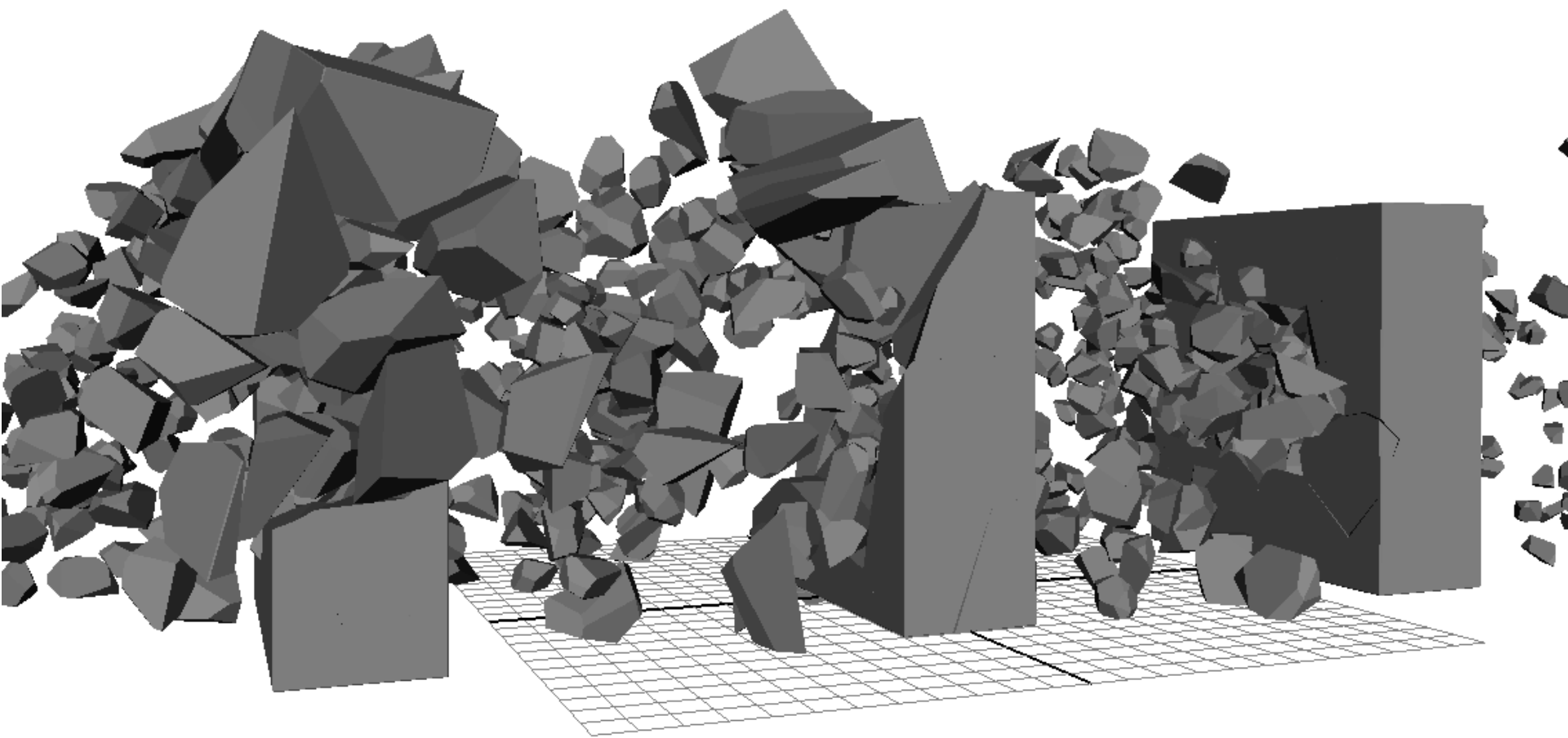
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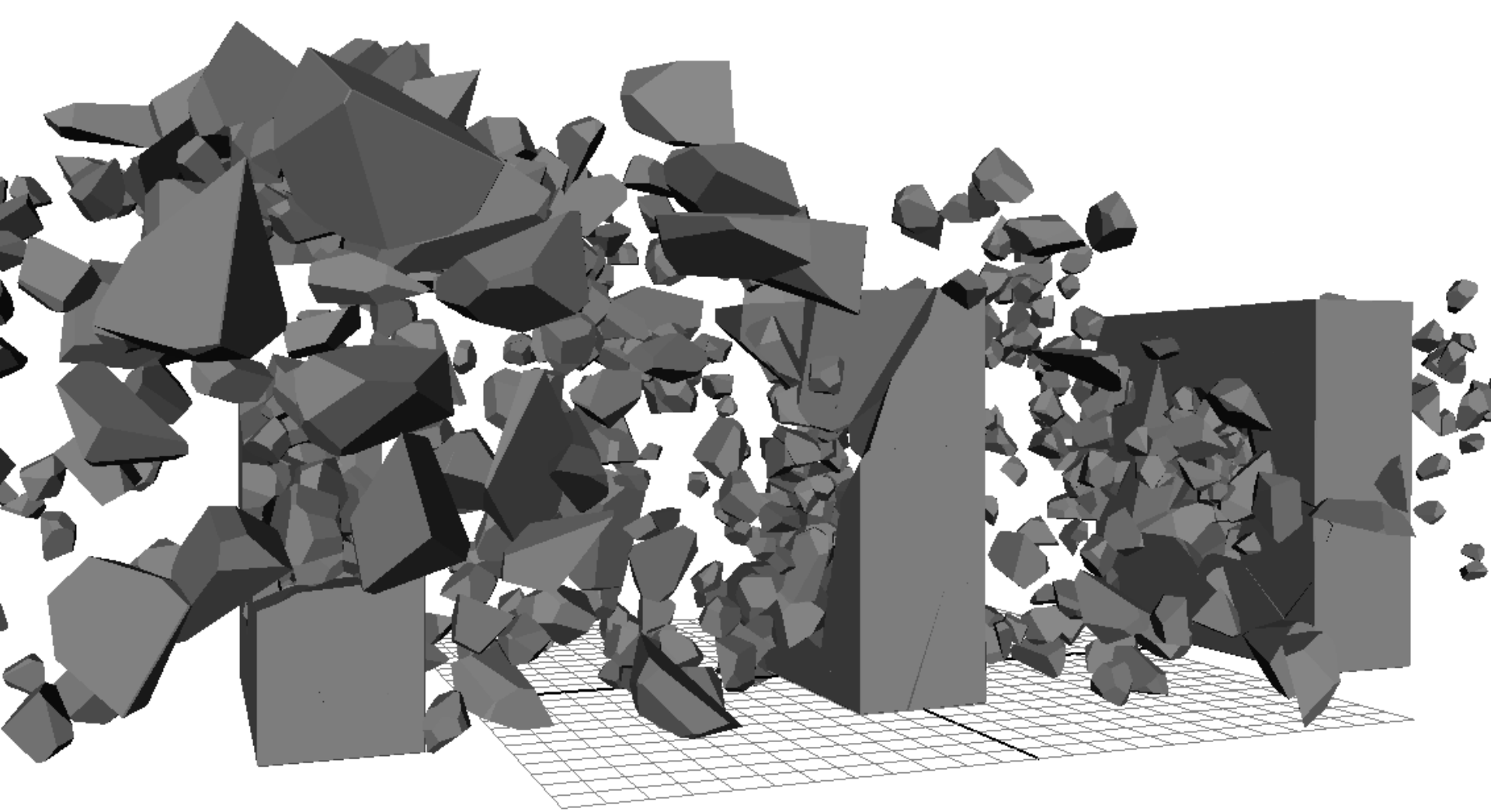


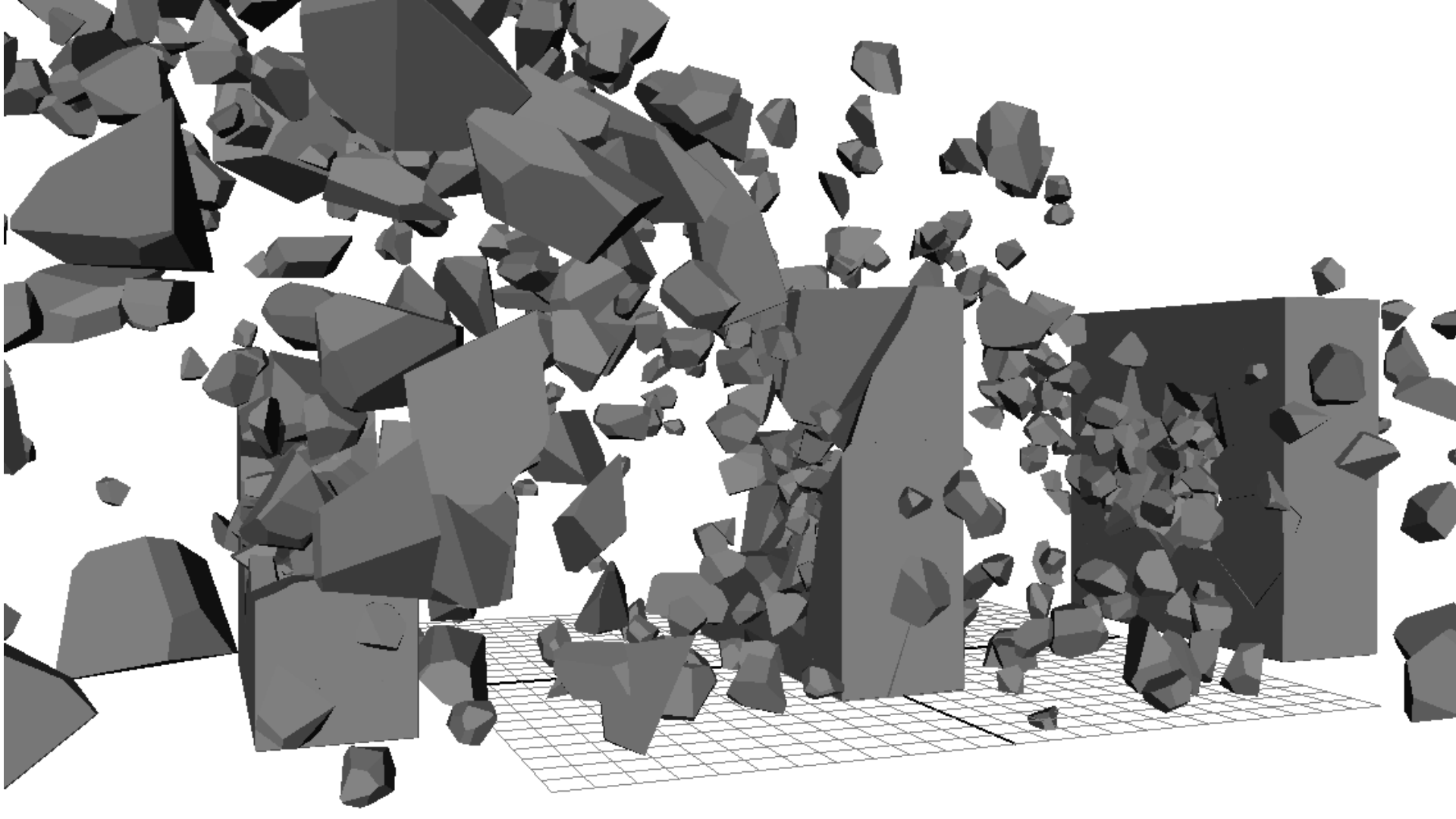


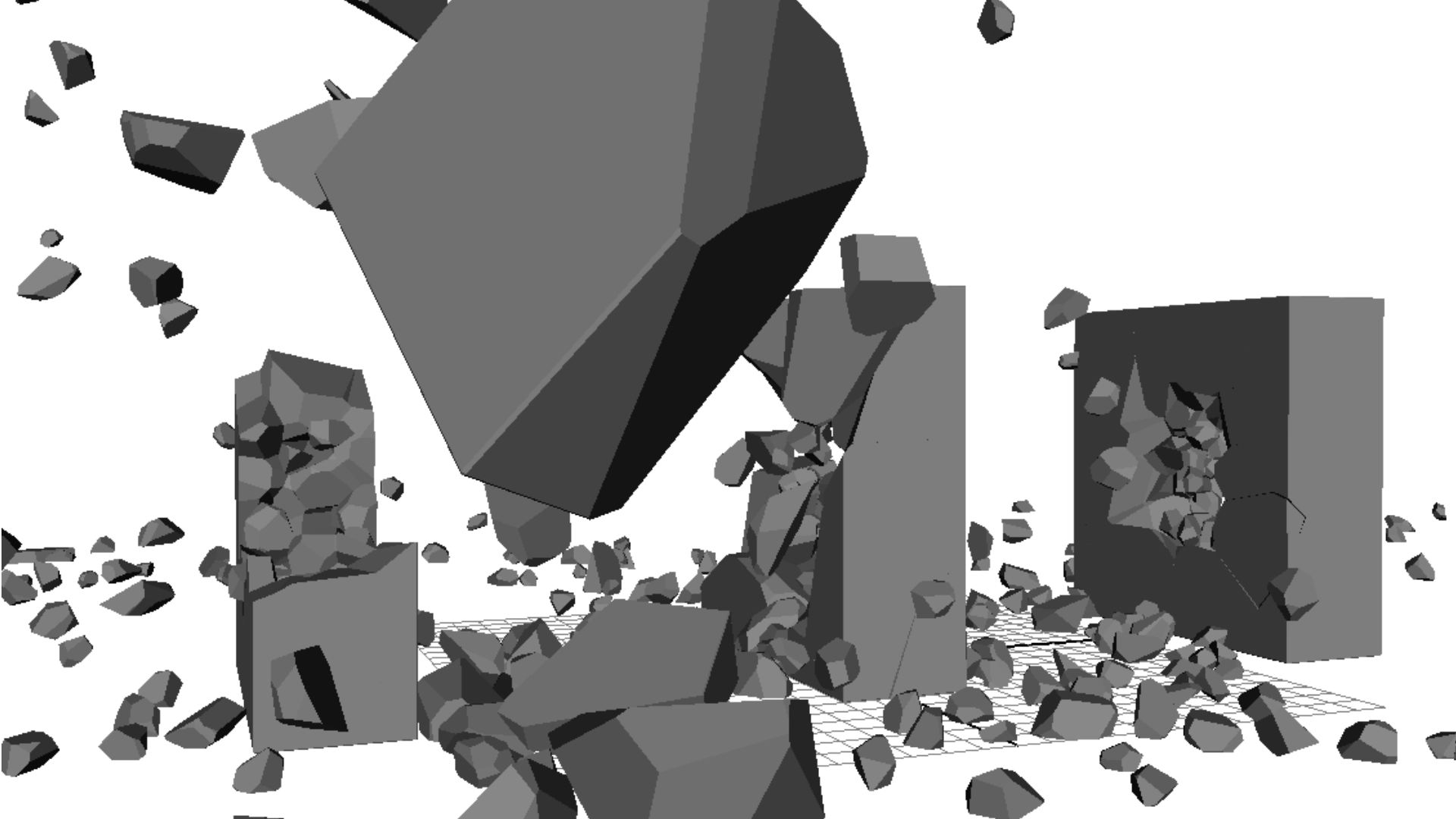


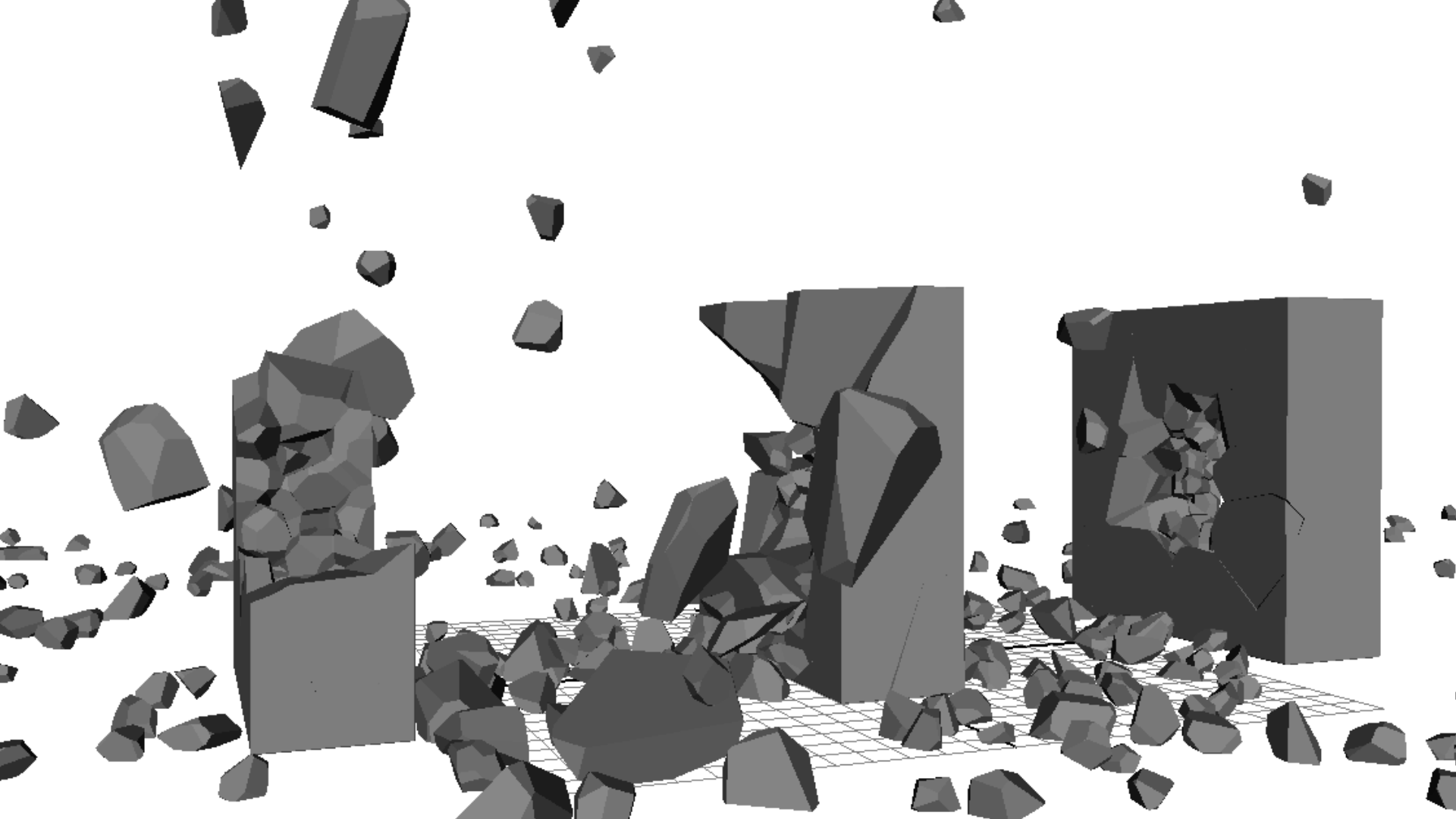


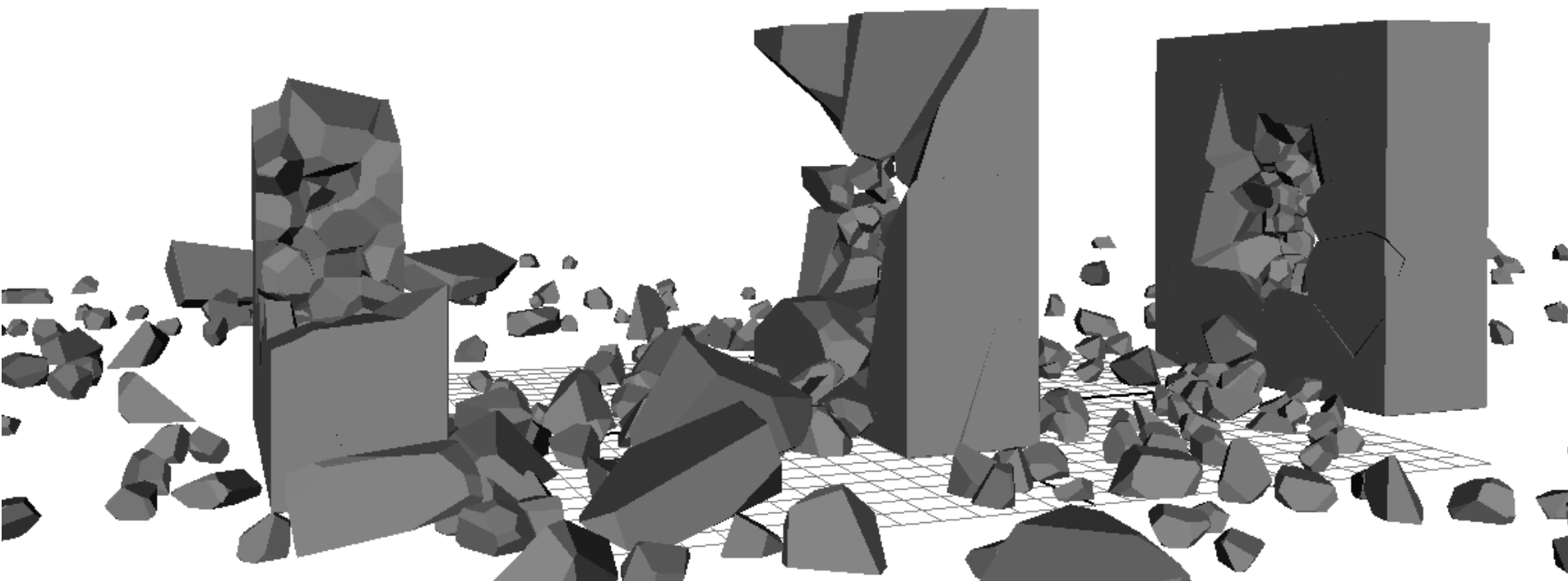










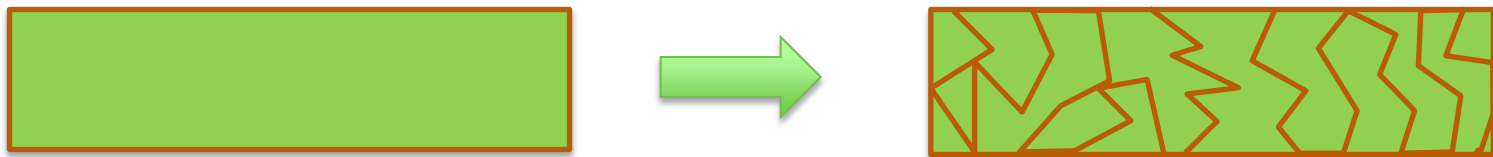


Offline versus runtime

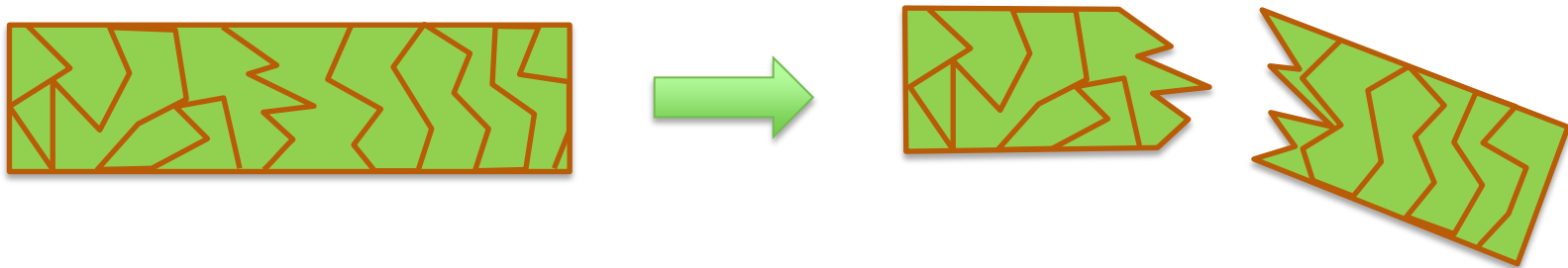
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- Geometry **preparation** and artist tools



- Runtime **destruction** methods



Geometry Preparation

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Voronoi shatter, slicing

**Runtime
Destruction**

Boolean operations

Canned animation

Convex decomposition

Real-time Booleans

Tetrahedralization

FEM, particle based

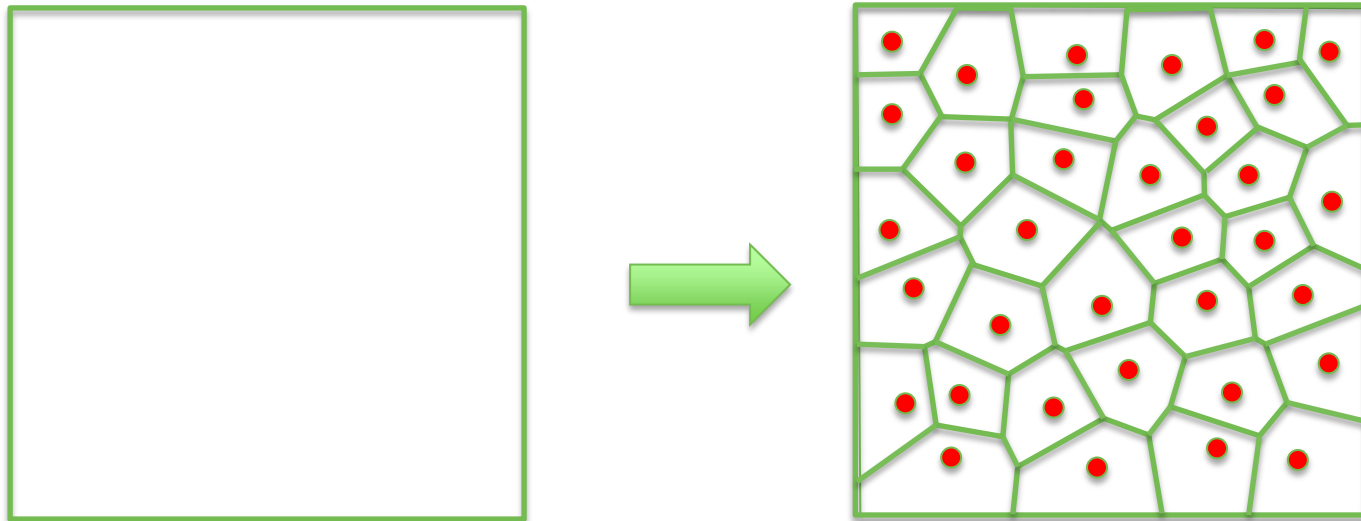
Simplification

Rigid body & Hybrid

Voronoi shatter

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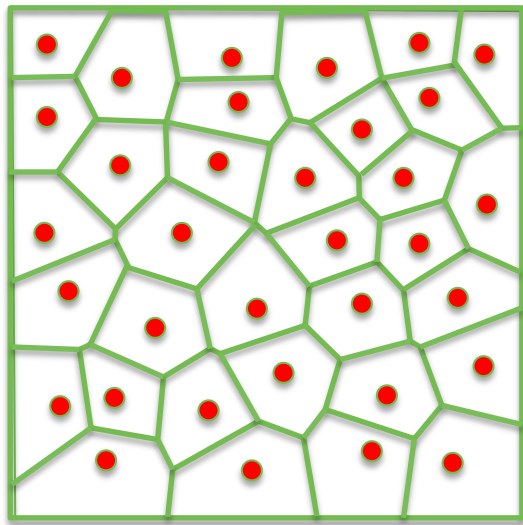


Voronoi generation

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```
Distribute point set S within the 3D model
For each point A in S
{
    Create cube around the point
    For each point B in {S-A}
        Create a plane between point A and B
        Slice the cube by this plane
    Boolean Intersect cube with model
}
```

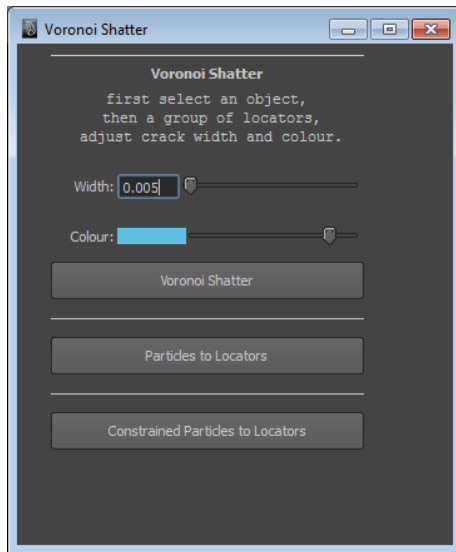


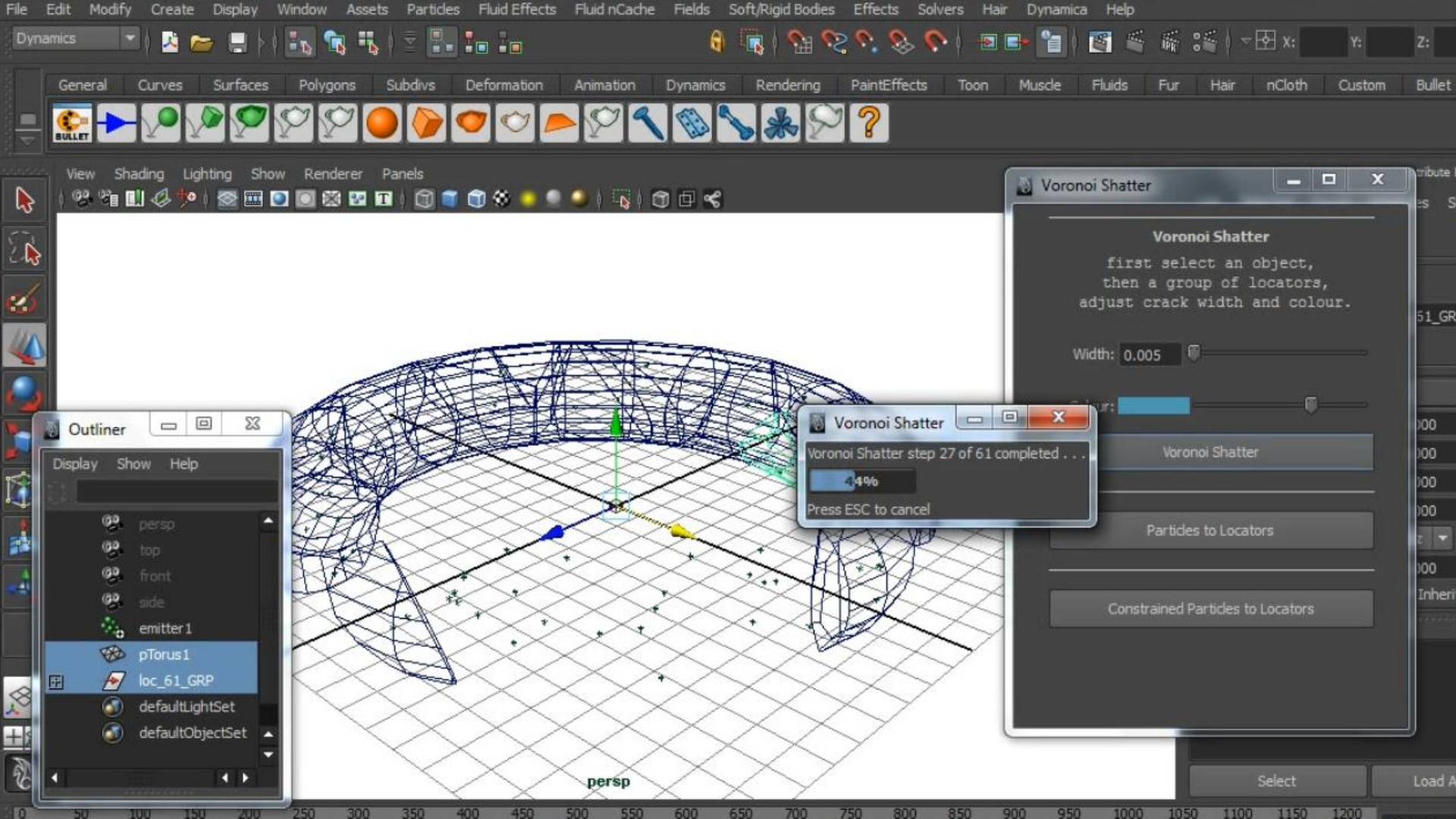
Maya Voronoi Shatter

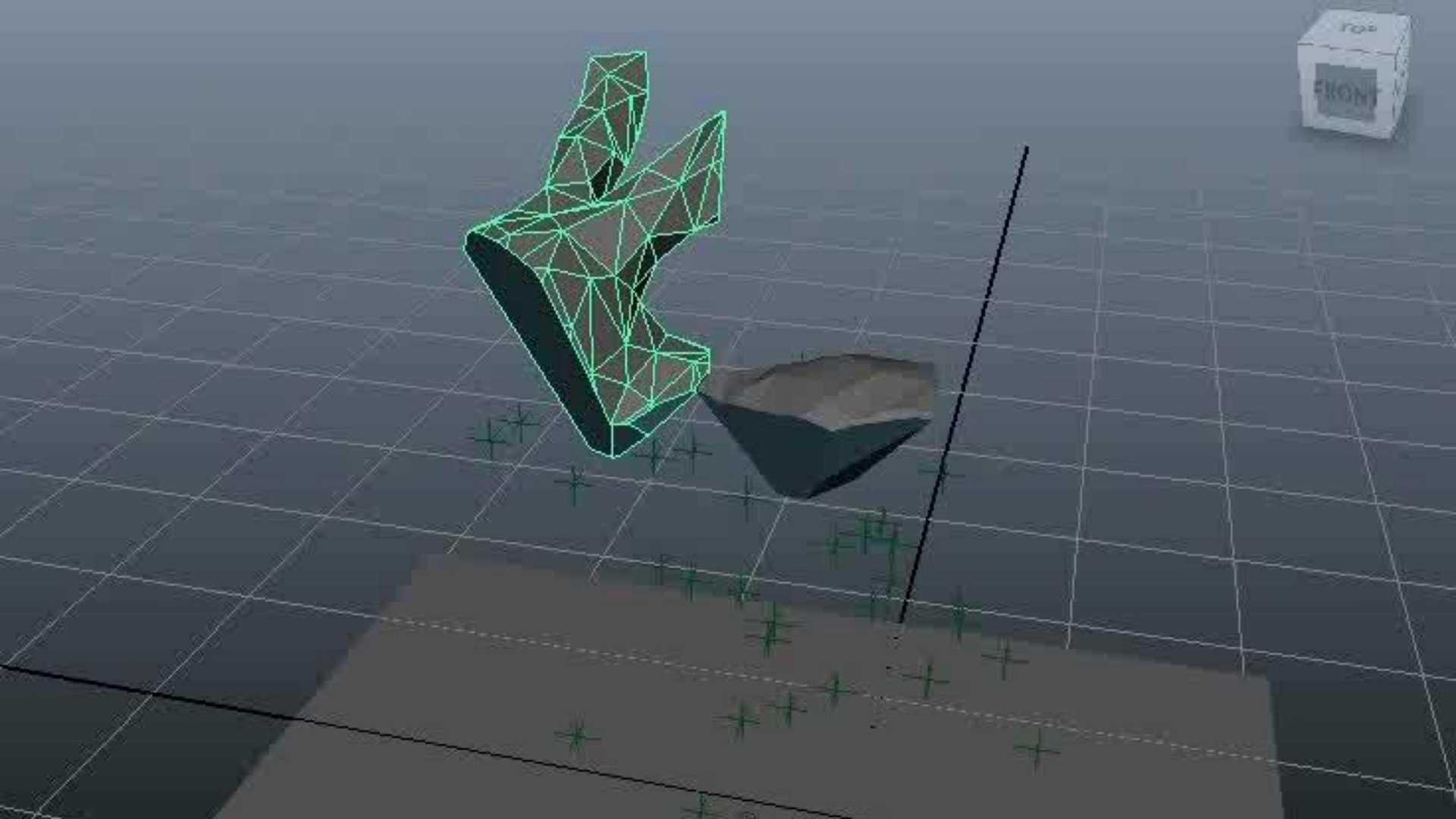
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- MEL/Python script by Dave Greenwood







Maya Shatter Recipe

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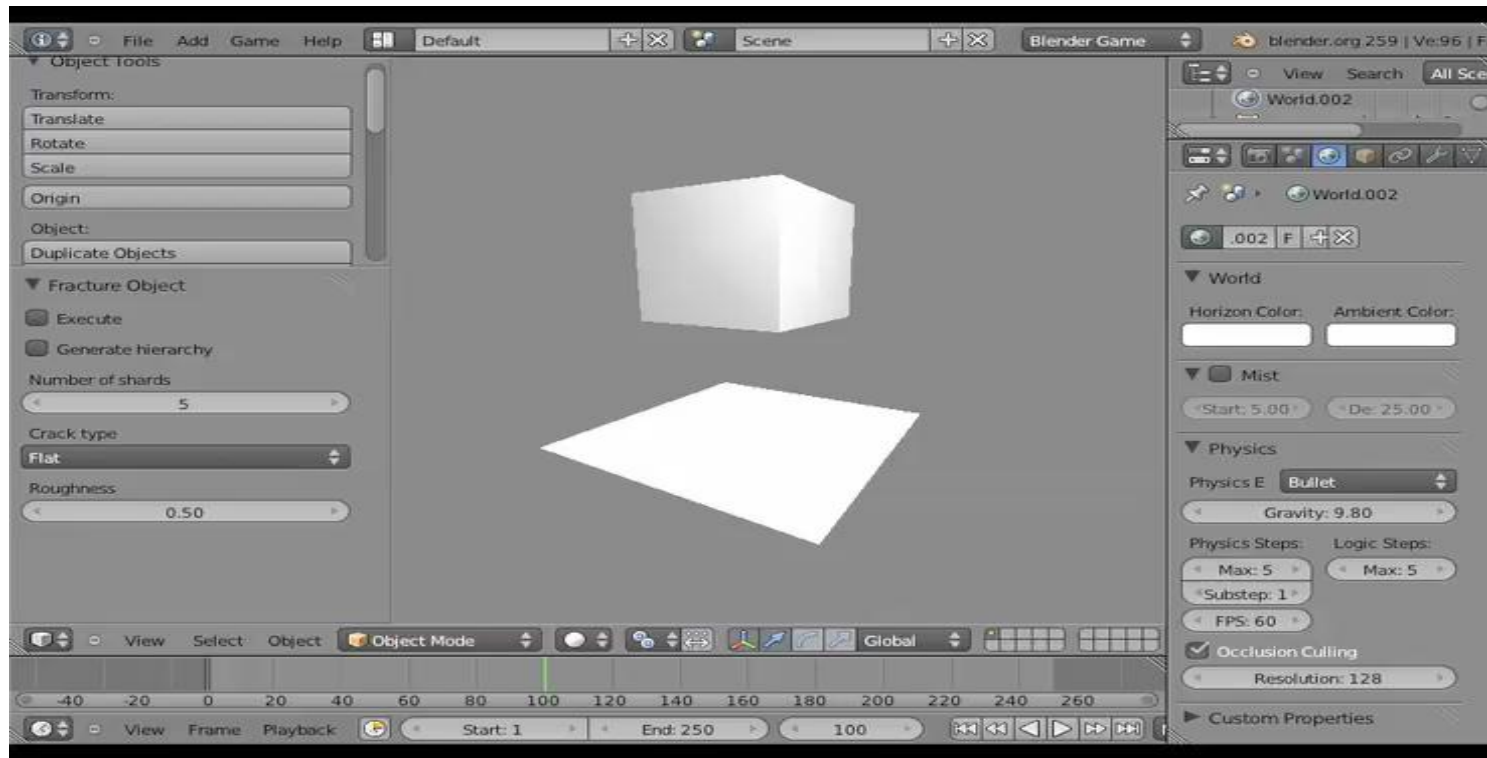
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- Create a particle emitter
- Create a polyhedral mesh
- Convert the particles to locators
 - Select mesh and then particles
- Create a mesh from each locator
 - Select mesh then locators

Blender Fracture Tools

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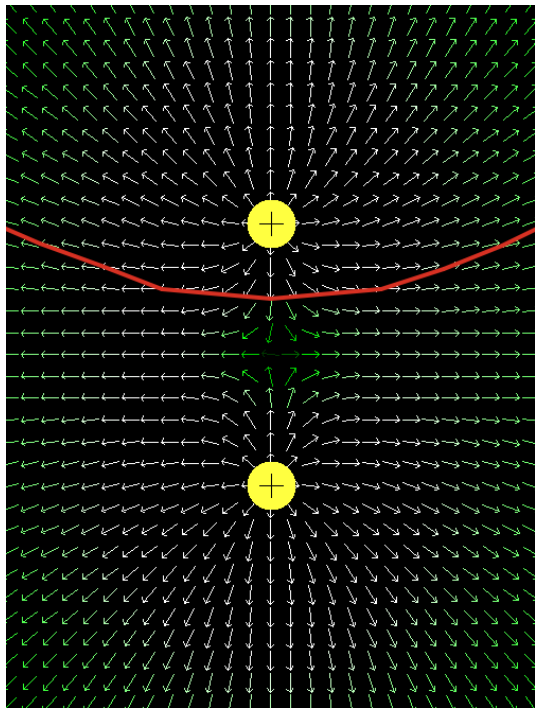


<http://www.directcg.info/how-to-use-fracturetools-inside-blender.html>

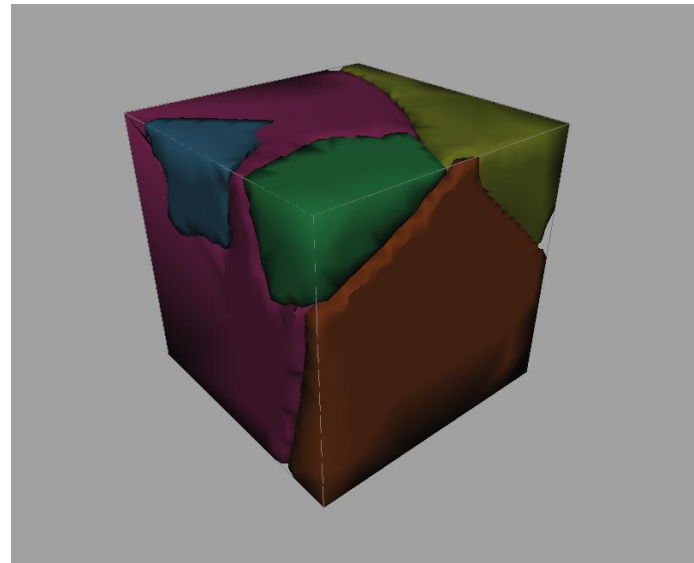
Electric Fields

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$$\mathbf{E} = \sum_{i=1}^n \frac{q_i}{4\pi\epsilon_0 r_i^2} \hat{\mathbf{r}}_i$$



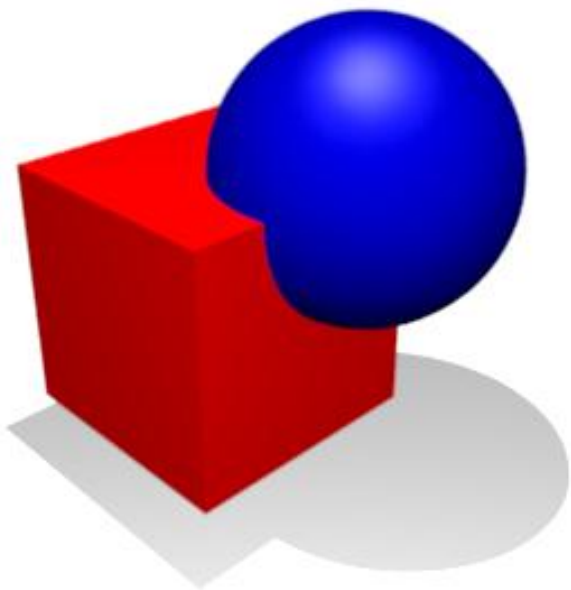
- See the 'Fragged' article in GDMag 2010, December

Boolean operations

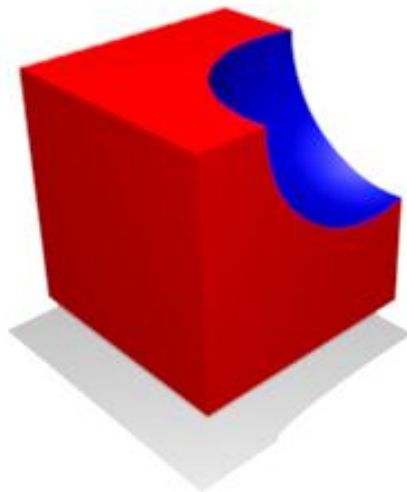
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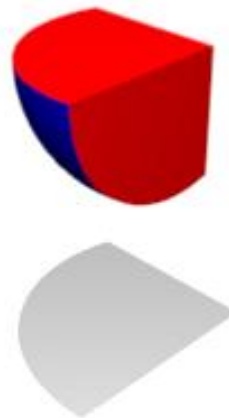
Union



Difference



Intersection



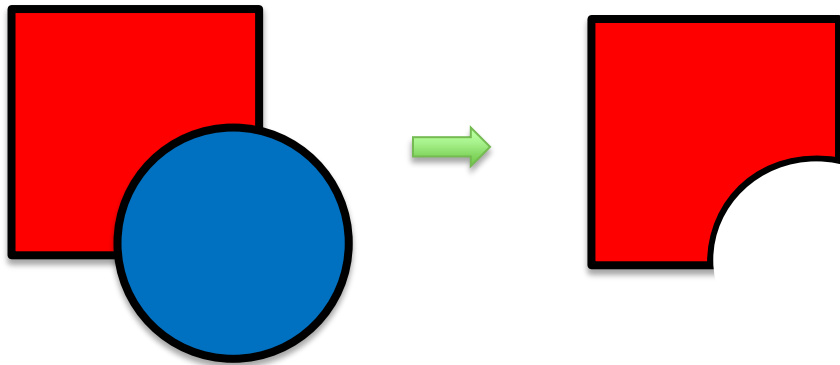
Modeled and Rendered in **Blender**. Made by **Captain Sprite**

Polyhedral Booleans

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- Merging BSP trees yields polyhedral set operations, [Bruce Naylor](#), SIGGRAPH '90

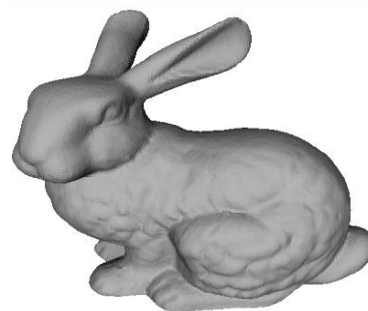
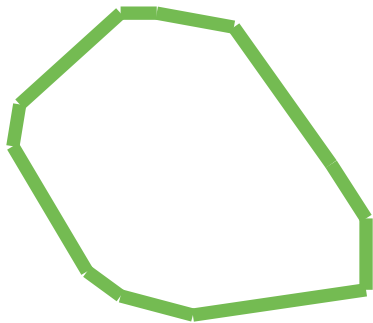
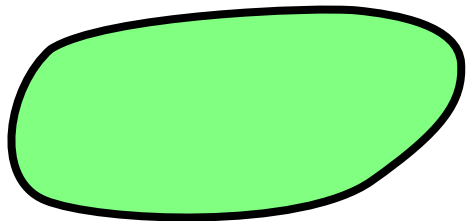


Collision shapes types

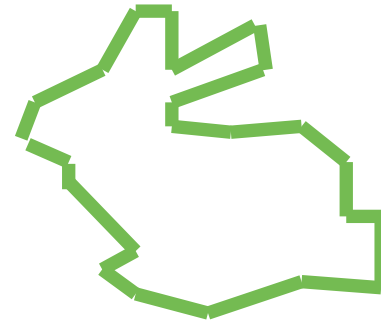
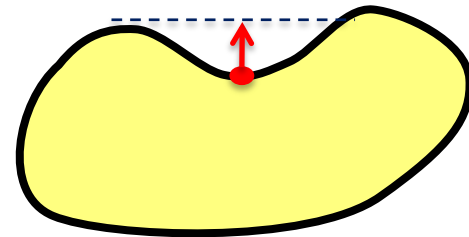
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Convex



Concave

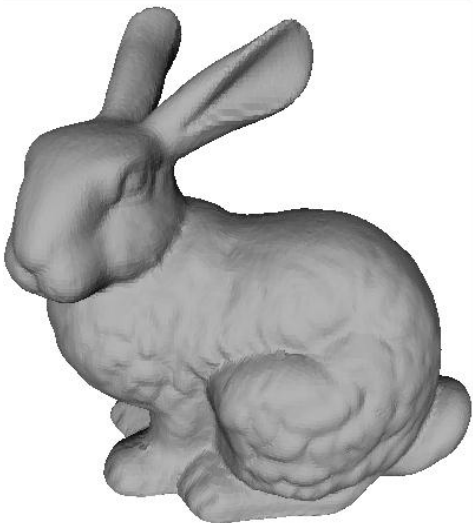


Convex Decomposition

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- (Semi) Automatic physics shape generation



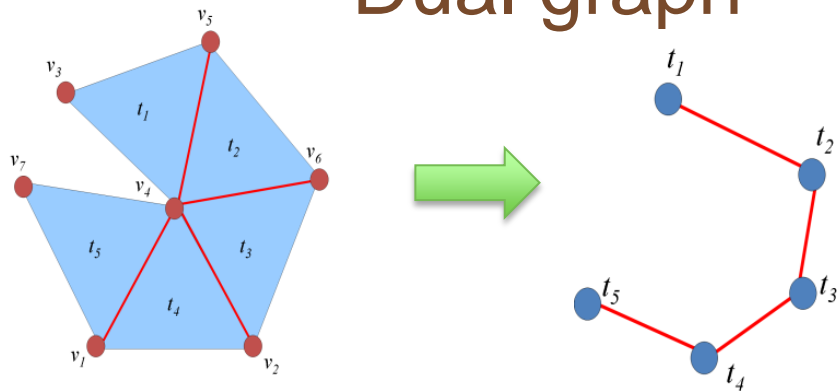
- Hierarchical Approximate Convex Decomposition
by [Khaled Mammou](#), ICIP 09
- [Bottom up](#), merging convex clusters
- <http://sourceforge.net/projects/hacd>

HACD in one slide

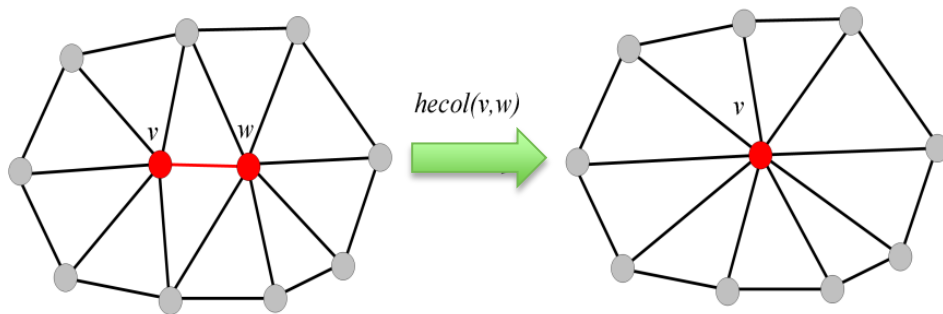
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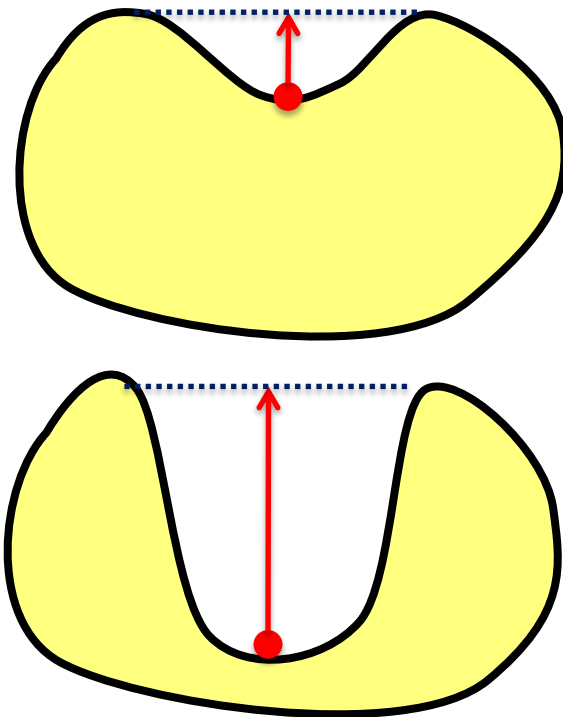
Dual graph

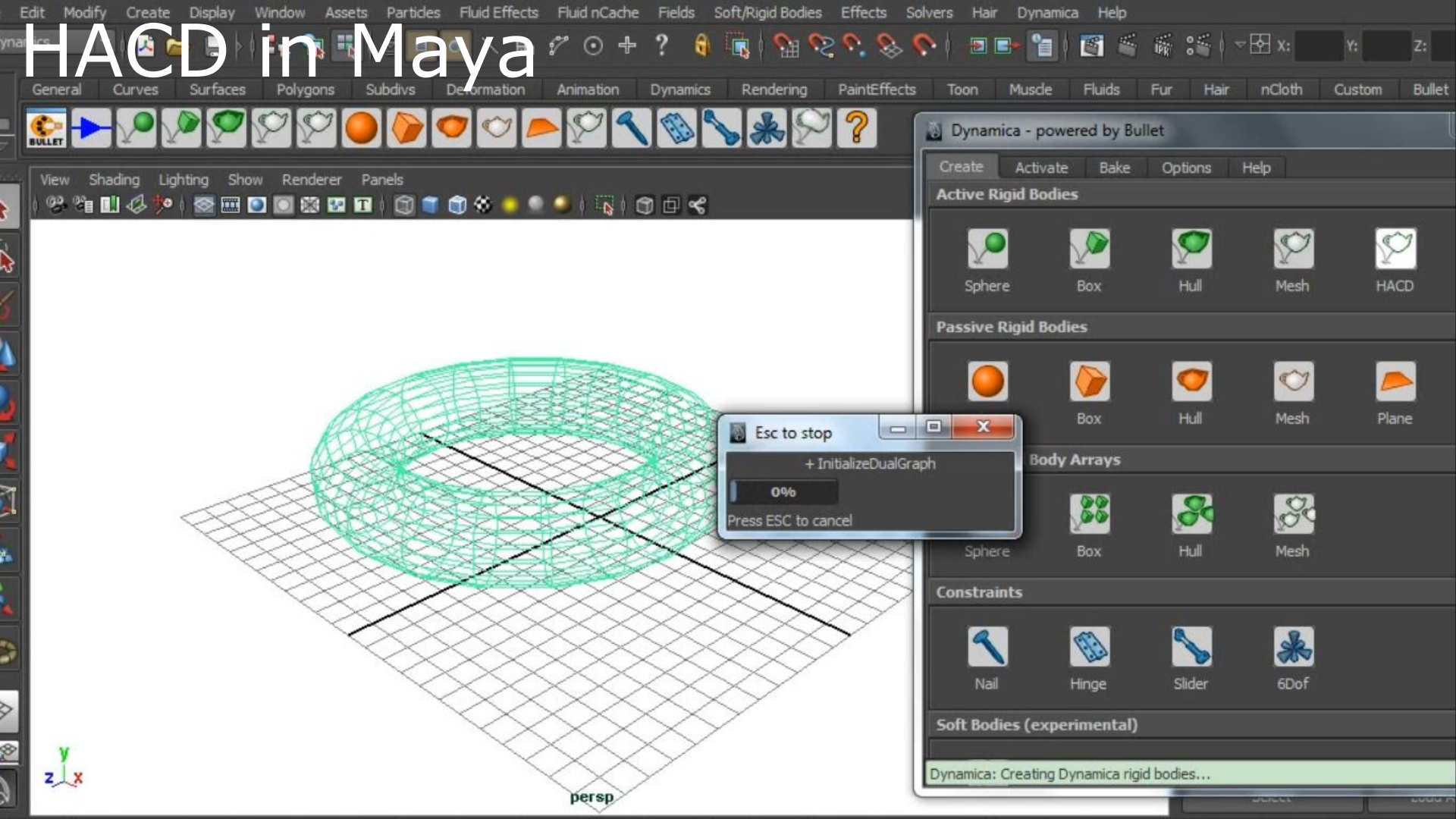


Decimation operator



Measuring concavity



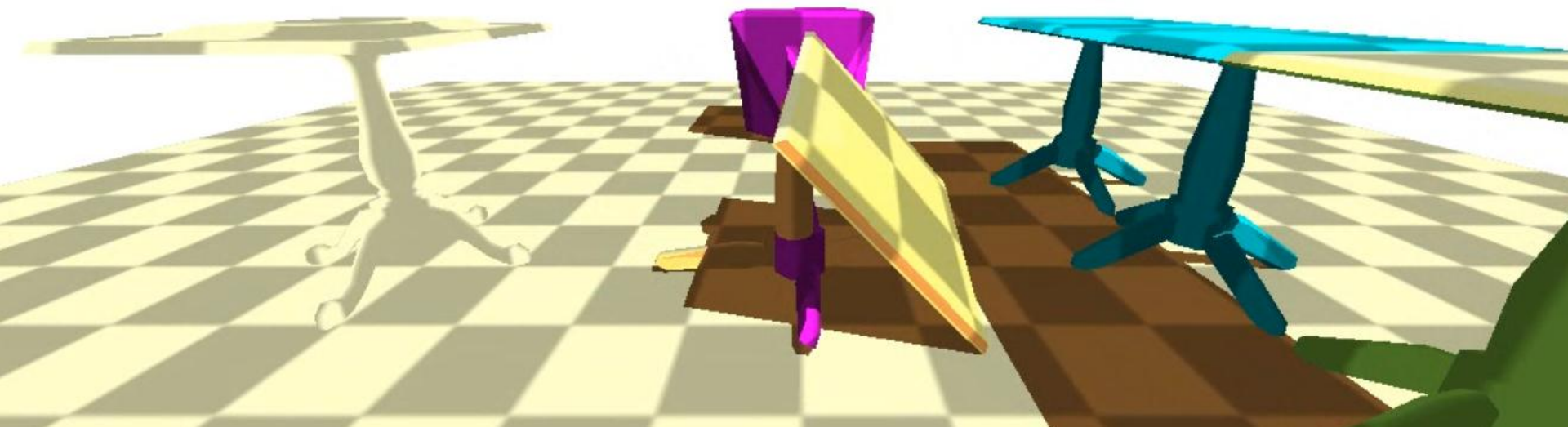


HACD in Maya

HACD in Bullet

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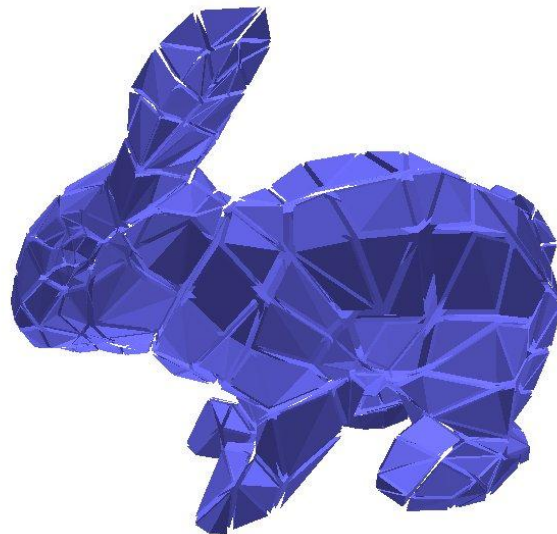
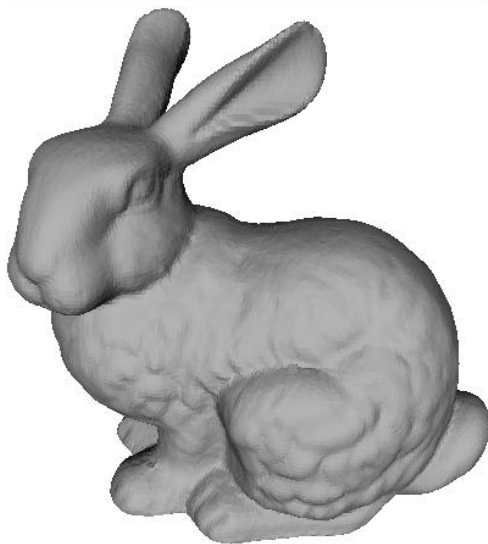
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Tetrahedra Creation

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- Tetrahedralization by 3D Delaunay Triangulation,
Boris Delaunay, 1934

Tetrahedralization

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- Netgen, LGPL,
<http://sourceforge.net/projects/netgen-mesher>
- Tetgen
- Maya 2012 with DMM plugin
[Pixelux Digital Molecular Matter](#)

Geometry Preparation**Runtime
Destruction**

Voronoi shatter, slicing

Canned animation

Boolean operations

Real-time Booleans

Convex decomposition

FEM, particle based

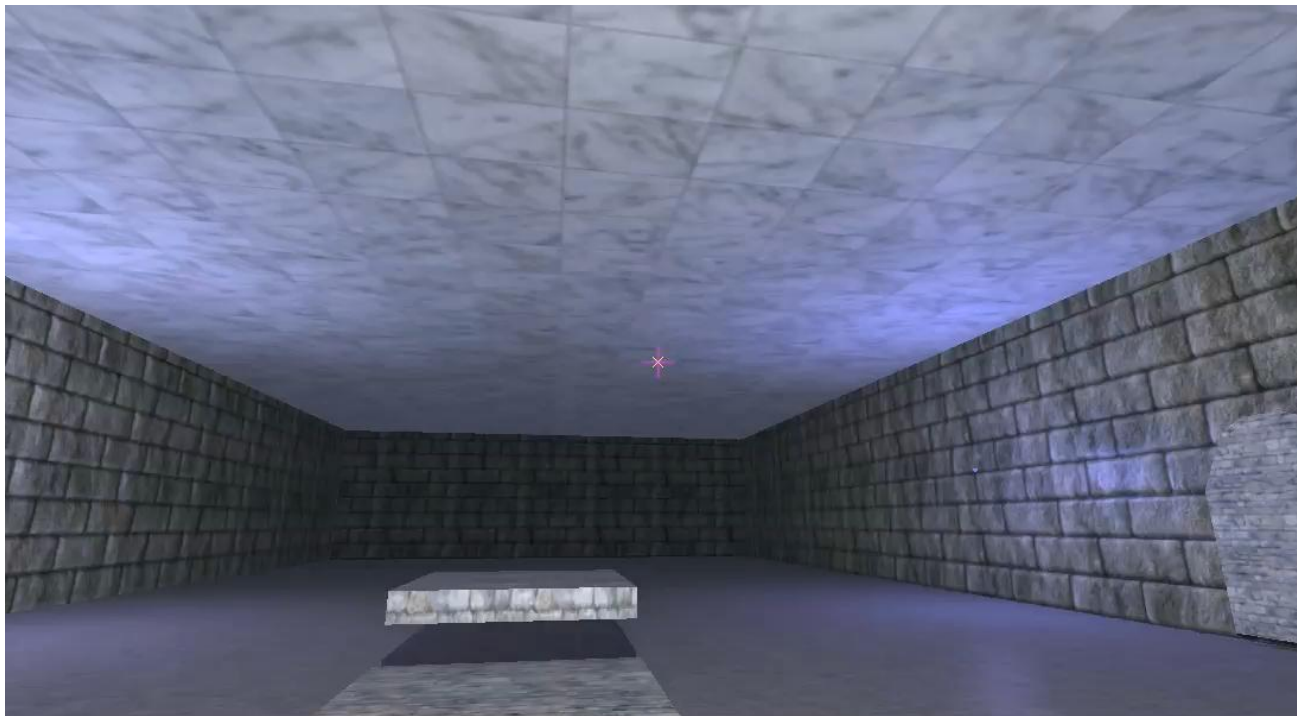
Tetrahedralization

Rigid body & Hybrid

Real-time booleans

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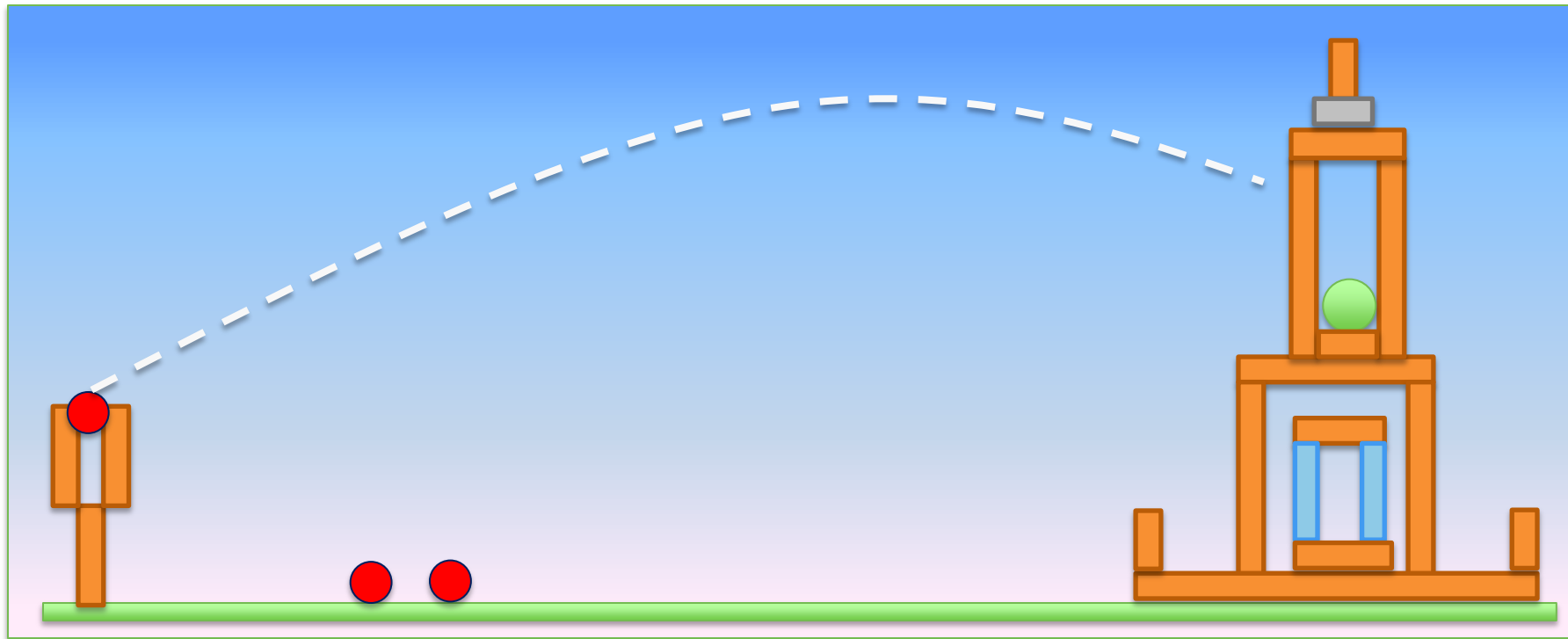


- Stan Melax, <http://melax.googlecode.com>

Rigid bodies

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Breakable Rigid bodies

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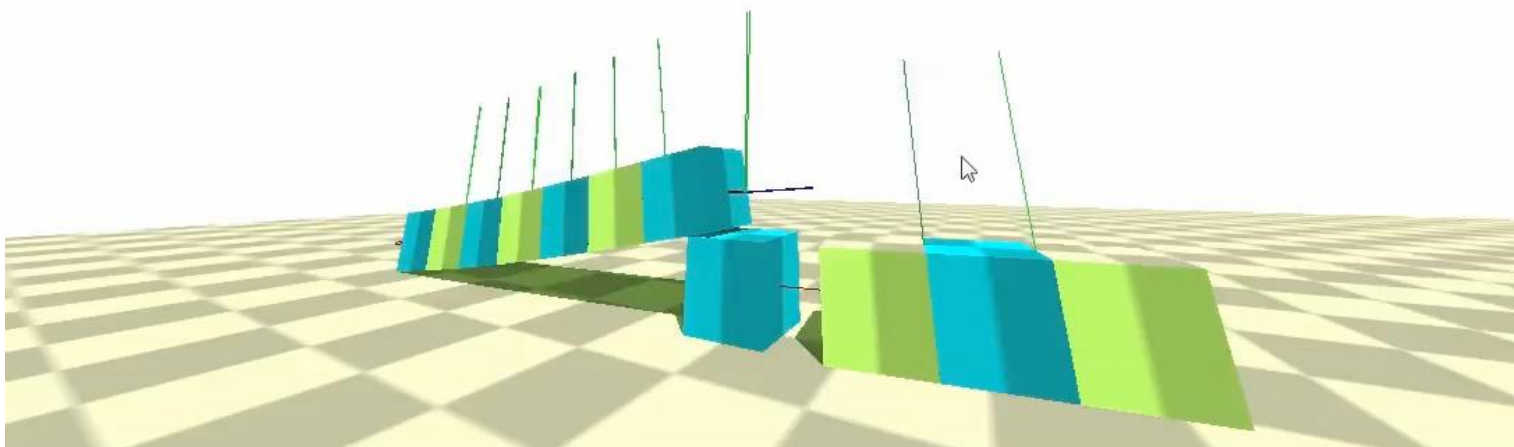
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- Breakable constraints
- Composite single rigid body

Breakable constraints

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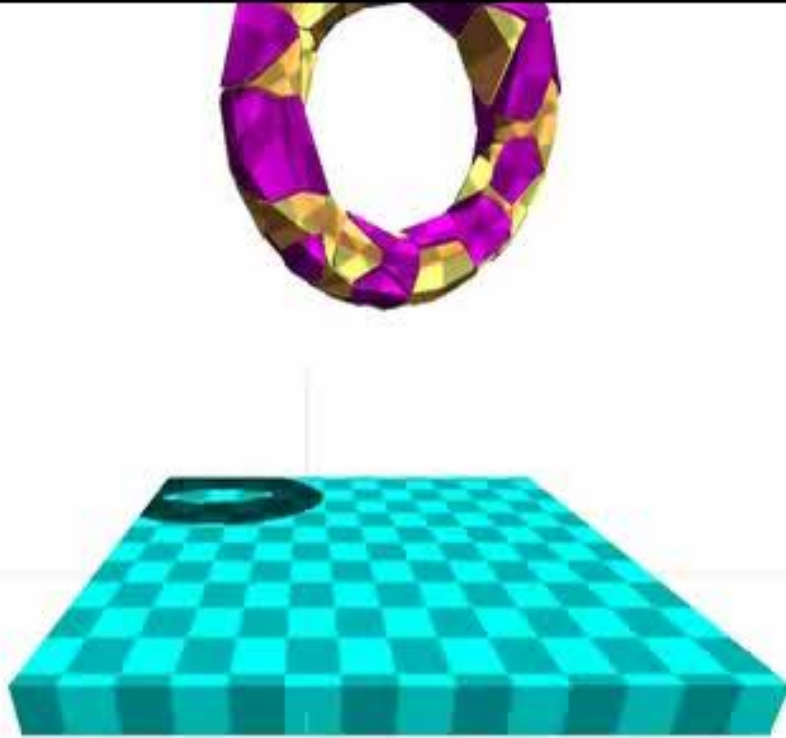
Breakable constraints

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- Break an object into parts
- Automatically create constraints
 - based on **contact points** (collision detection)
 - assign a **breaking threshold** to constraints
- At run-time propagate a collision impulse
 - break connections if the **impulse > threshold**

Stiffer constraints

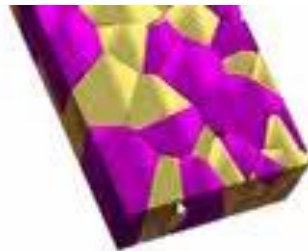


Increase number of constraint solver iterations for the fixed constraints

On-line voronoi shatter

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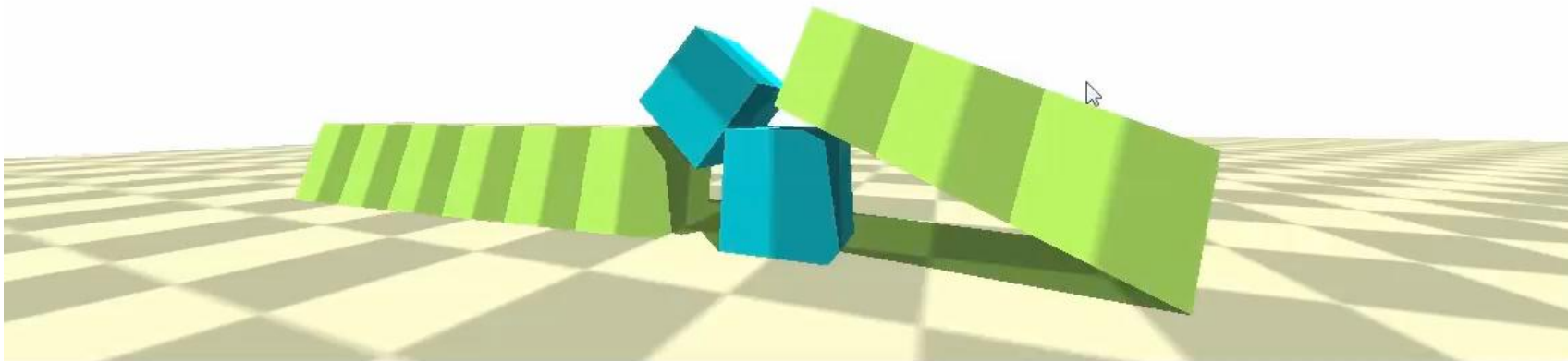
See Bullet/Demos/VoronoiShatterDemo

Composite single body

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See Bullet/Demos/FractureDemo



Composite method

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- Break an object into parts
- Automatically create connections
 - based on **contact points** (collision detection)
 - assign a **breaking threshold** to connections
- At run-time propagate a collision impulse
 - break connections if the **impulse > threshold**
 - determine disconnected parts using **union find**
 - **create new rigid bodies** for each disconnected part
 - update inertia tensor and velocity

Structural Analysis

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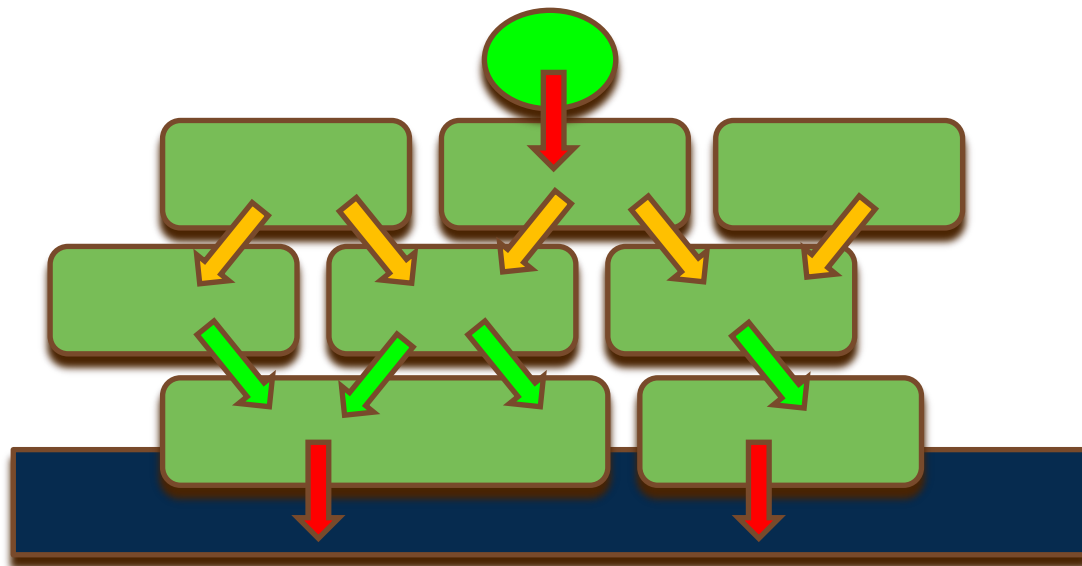
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Layer 3

Layer 2

Layer 1

Ground



Red Faction: Spread calculations over multiple frames

Other methods

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- Position based dynamics
- Finite element method
- Hybrid

Connected particles

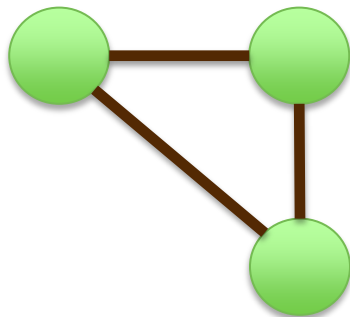
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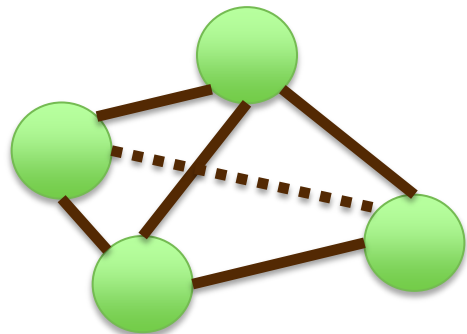
1D Rope



2D Triangle



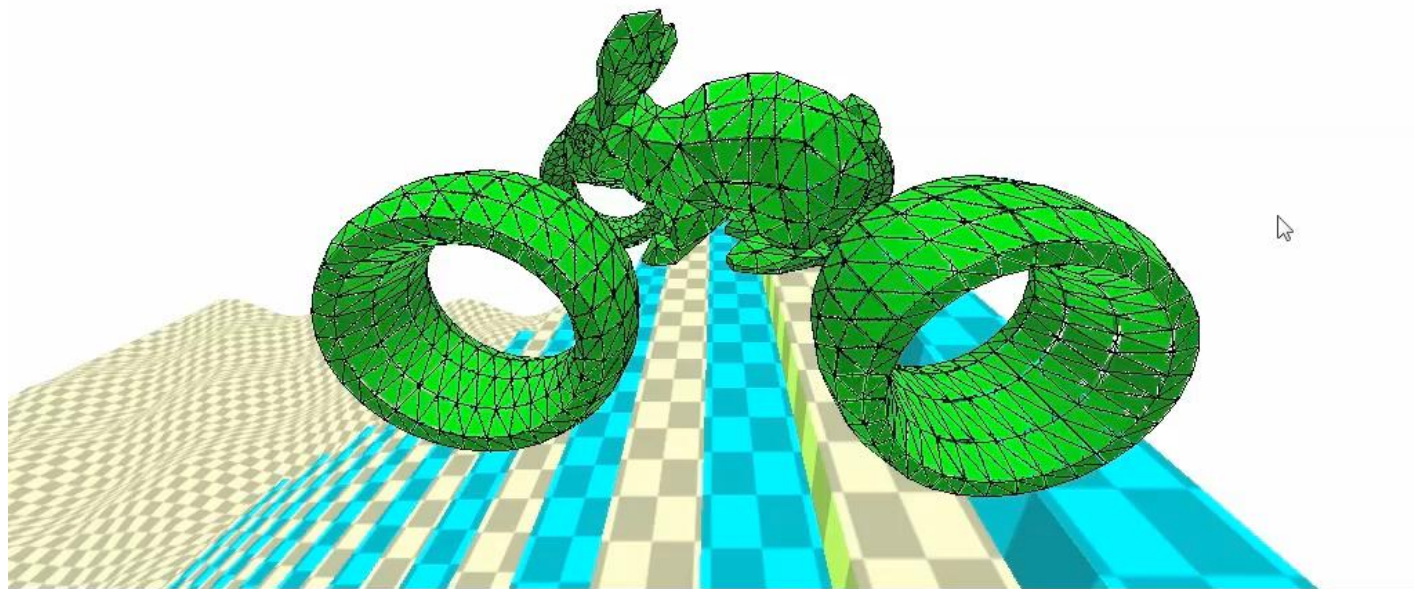
3D Tetrahedron



Position based dynamics

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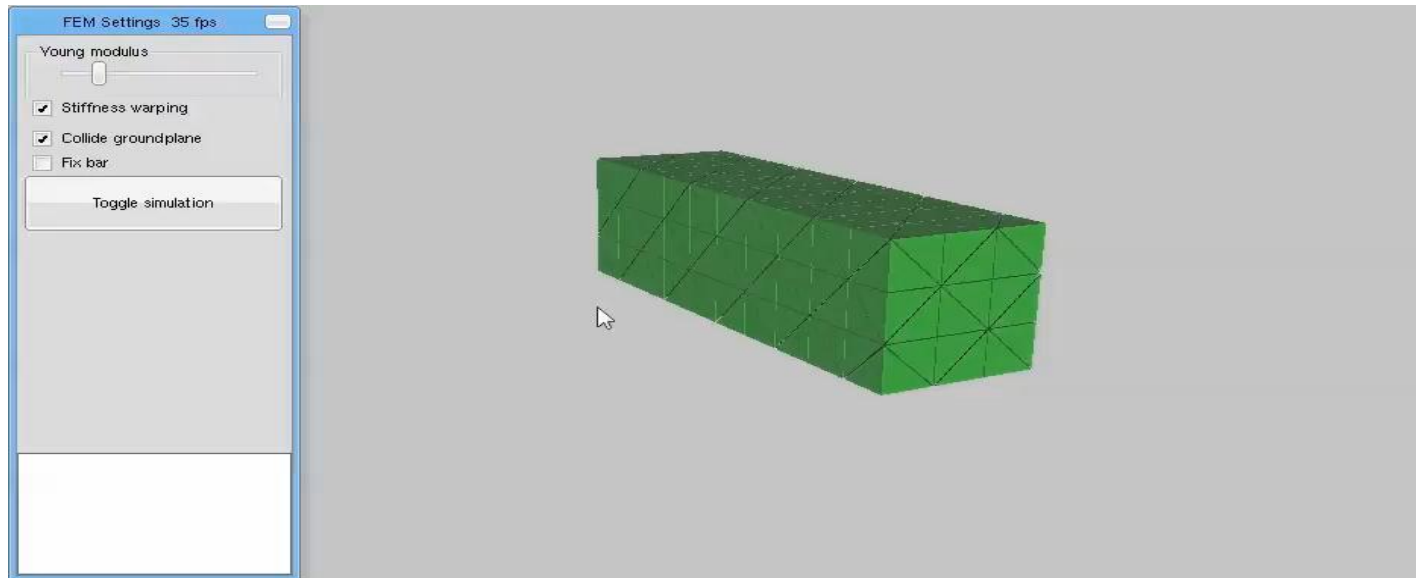


- Bullet, <http://bulletphysics.org>

Finite element method

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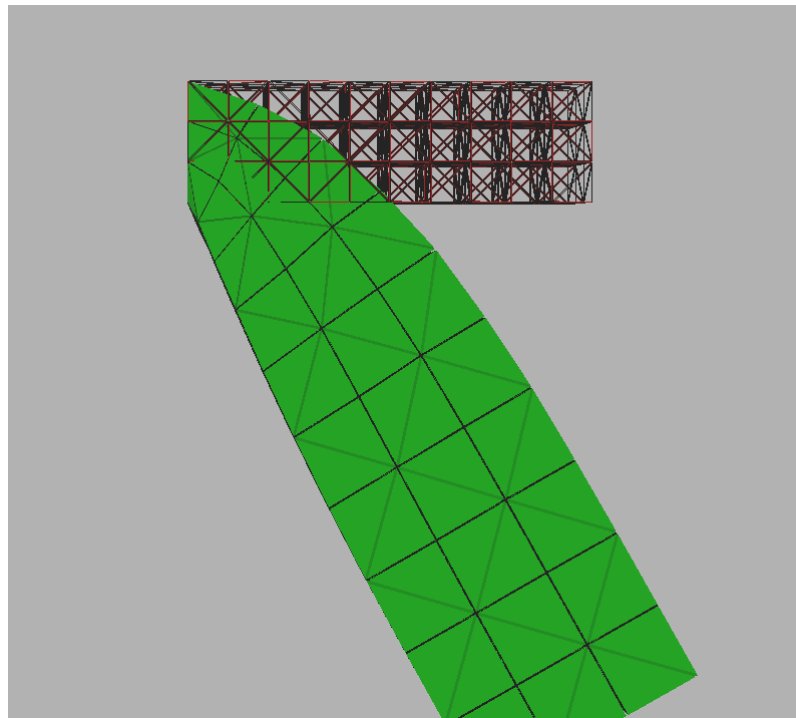
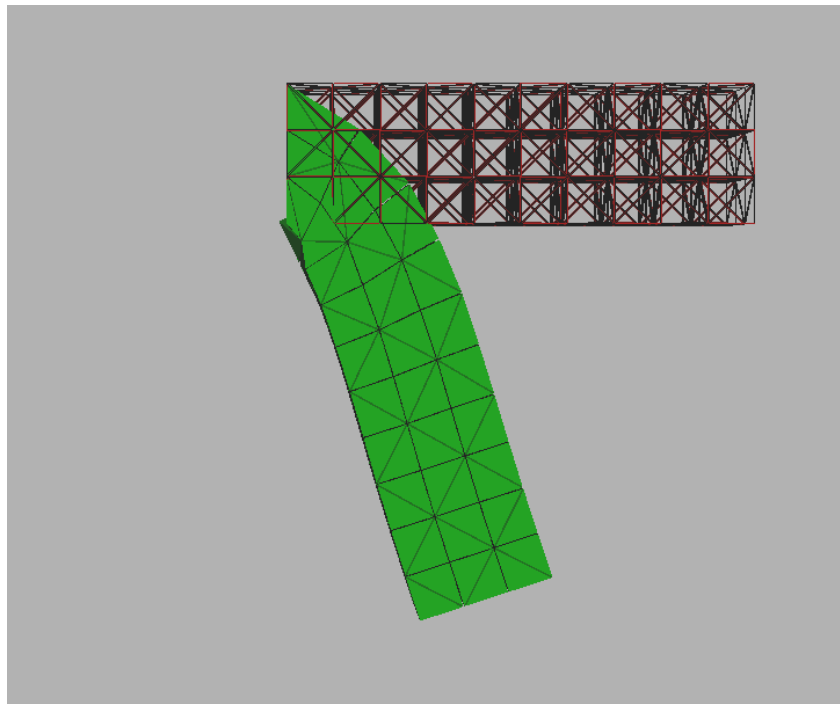


- Original from OpenTissue, Kenny Erleben et. al.
- https://github.com/erwincoumans/experiments/tree/master/dynamics/corotational_fem

Stiffness warping

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FEM on GPU

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FPS: 94.3
GPU: GeForce GTX 580
particles: 13443
elements: 45286
CG iterations: 25



- SOFA, <http://sofa-framework.org>
- Chapter 21 of GPU Computing Gems Jade Edition
- <https://github.com/erwincoumans/experiments/tree/master/dynamics/ivi-sofa-tp1>

Hybrid method

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- Composite rigid body with static FEM analysis
 - [Matthias Müller](#) et al. Eurographics CAS 2001

Thanks!

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- <http://bulletphysics.org>
- <http://github.com/erwincoumans>
- <http://youtube.com/erwincoumans>