

1 Schedules - RC, ACA, Strict (1 P.)

For the following schedules, decide in which of the classes RC, ACA, or ST they are.

$$\begin{aligned}
 s_1 &:= r_1(a) \ w_1(a) \ r_2(a) \ r_2(b) \ r_2(a) \ r_1(b) \ c_1 \ w_2(b) \ c_2 \\
 s_2 &:= w_1(b) \ r_1(a) \ r_2(a) \ r_1(b) \ w_2(a) \ w_1(b) \ w_2(b) \ c_2 \ c_1 \\
 s_3 &:= r_2(a) \ r_1(b) \ r_1(a) \ w_2(a) \ w_1(b) \ w_3(b) \ r_3(b) \ c_3 \ c_1 \ r_2(b) \ c_2
 \end{aligned}$$

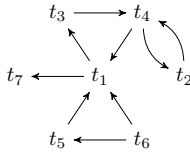
2 2-Phase-Locking and Waits-for-Graph (1 P.)

1. Given the following schedules:

$$\begin{aligned}
 s_1 &= r_1(c) \ w_2(a) \ r_1(a) \ r_3(b) \ w_3(a) \ c_3 \ w_2(c) \ w_1(c) \ c_1 \ c_2 \\
 s_2 &= w_1(b) \ r_2(c) \ w_3(a) \ w_2(b) \ r_1(a) \ c_1 \ c_3 \ w_2(a) \ c_2
 \end{aligned}$$

Create a 2PL history for both schedules and note the Waits-for-Graph (WfG) every time it changes. If you encounter a deadlock, abort the transaction that caused the deadlock (No deadlock prevention strategy).

2. Given the following WfG. Which nodes are chosen for the strategies **most cycles** and **most edges**.



3 Deadlock prevention (1 P.)

Implement a scheduler, which creates a (SS)2PL schedule, using the deadlock prevention strategies wait-die and immediate restart.

Test your program with the given schedule. It has to print the output schedule for each of the prevention strategies and indicate when a transaction has to wait or abort. After a transaction waits or aborts, you do not have to continue/restart it in the solution history.

$$s := w_1(x) \ r_2(x) \ w_3(y) \ r_1(y) \ r_3(z) \ w_1(x) \ c_1 \ w_2(y) \ c_2 \ w_3(y) \ c_3$$

You can use the template provided in OLAT, which implements an internal representation of a history and all required operations.

Submit the code as separate file and submit the output of running your program with the solution PDF.

4 Timestamp-Based Approaches

(1 P.)

$$s_1 = w_1(x) \ r_2(x) \ w_2(x) \ r_1(x)$$

$$s_2 = r_1(y) \ w_1(x) \ r_2(x) \ w_3(x) \ w_1(y) \ w_2(x) \ r_1(x)$$

Describe how a timestamp ordering (TO) based scheduler would execute the operations. Complete the following tables. Note the used rule in the “Comment” column. The max- r and max- w columns contain the value of max- q -scheduled for the given object. One row contains the entry after applying the rule. You may assume $ts(t_1) < ts(t_2)$. Do not restart aborted transactions.

s_1 :

Operation	max- $r(x)$	max- $w(x)$	Comment
BOT_1	$-\infty$	$-\infty$	$ts(t_1) = 1$
BOT_2	$-\infty$	$-\infty$	$ts(t_2) = 2$

s_2 without Thomas' write rule:

Operation	max- $r(x)$	max- $w(x)$	max- $r(y)$	max- $w(y)$	Comment
BOT_1	$-\infty$	$-\infty$	$-\infty$	$-\infty$	$ts(t_1) = 1$
BOT_2	$-\infty$	$-\infty$	$-\infty$	$-\infty$	$ts(t_2) = 2$
BOT_3	$-\infty$	$-\infty$	$-\infty$	$-\infty$	$ts(t_3) = 3$

s_2 with Thomas' write rule:

Operation	$\max\text{-}r(x)$	$\max\text{-}w(x)$	$\max\text{-}r(y)$	$\max\text{-}w(y)$	Comment
BOT_1	$-\infty$	$-\infty$	$-\infty$	$-\infty$	$ts(t_1) = 1$
BOT_2	$-\infty$	$-\infty$	$-\infty$	$-\infty$	$ts(t_2) = 2$
BOT_3	$-\infty$	$-\infty$	$-\infty$	$-\infty$	$ts(t_3) = 3$