

Exercise 3 - Recurrent Networks and NLP

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3.1. Backpropagation through Time

i)

Show that:

$$\frac{\partial L}{\partial W} = \sum_{t=1}^T \sum_{k=1}^t \frac{\partial L_t}{\partial h_t} \frac{\partial h_t}{\partial h_k} \frac{\partial h_k}{\partial W}$$

The loss functions is defined as:

$$L = \sum_{t=1}^T L_t$$

$$\frac{\partial L}{\partial W} = \sum_{t=1}^T \frac{\partial L_t}{\partial W}$$

Lets expand the sum:

$$\frac{\partial L_t}{\partial W} = \frac{\partial L_t}{\partial h_t} \cdot \left(\frac{\partial h_t}{\partial W} + \frac{\partial h_t}{\partial h_{t-1}} \cdot \frac{\partial h_{t-1}}{\partial W} + \dots + \frac{\partial h_t}{\partial h_1} \cdot \frac{\partial h_1}{\partial W} \right)$$

$$\frac{\partial L_t}{\partial W} = \frac{\partial L_t}{\partial h_t} \sum_{k=1}^t \frac{\partial h_t}{\partial h_k} \cdot \frac{\partial h_k}{\partial W}$$

$$\frac{\partial L}{\partial W} = \sum_{t=1}^T \frac{\partial L_t}{\partial h_t} \sum_{k=1}^t \frac{\partial h_t}{\partial h_k} \cdot \frac{\partial h_k}{\partial W}$$

$$\frac{\partial L}{\partial W} = \sum_{t=1}^T \sum_{k=1}^t \frac{\partial L_t}{\partial h_t} \frac{\partial h_t}{\partial h_k} \frac{\partial h_k}{\partial W}$$

ii)

Given:

$$f(h) = \sigma(W \cdot h)$$

Show that:

$$\frac{\partial f}{\partial h} = \text{diag}(\sigma'(Wh))W$$

iii)

iv)

3.2. Gated recurrent units

i)

Given:

$$u_t = \sigma(w.h_{t-1} + w.x_t) \quad (1)$$

$$s_t = w.(h_{t-1} + x_t) \quad (2)$$

$$h_t = u_t.h_{t-1} + (1 - u_t).s_t \quad (3)$$

First, let's differentiate equation (3) with respect to h_{t-1} :

$$\frac{\partial h_t}{\partial h_{t-1}} = \frac{u_t * h_{t-1} + (1 - u_t) * s_t}{\partial h_{t-1}} \quad (4)$$

On applying the chain rule :

$$\frac{\partial h_t}{\partial h_{t-1}} = u_t \cdot \frac{\partial h_{t-1}}{\partial h_{t-1}} + (1 - u_t) \cdot \frac{\partial s_t}{\partial h_{t-1}} \quad (5)$$

We have the value of s from equation 2:

$$(6)$$

$$s_t = w.(h_{t-1} + x_t) \quad (7)$$

$$\frac{\partial s_t}{\partial h_{t-1}} = w \cdot \frac{\partial h_{t-1}}{\partial h_{t-1}} + 0 \quad (8)$$

$$= w \quad (9)$$

On substituting it back to our previous equation, we have:

$$\frac{\partial h_t}{\partial h_{t-1}} = u_t + (1 - u_t).w \quad (10)$$

On comparing it with the required form $A_t \cdot w + B_t$, we get:

$$A_t = 1 - u_t \quad (11)$$

$$B_t = u_t \quad (12)$$

ii)

The long-term derivative can be written as:

$$\frac{\partial h_t}{\partial h_0} = \frac{\partial h_t}{\partial h_{t-1}} \cdot \frac{\partial h_{t-1}}{\partial h_{t-2}} \cdot \frac{\partial h_{t-2}}{\partial h_{t-3}} \cdots \frac{\partial h_1}{\partial h_0} \quad (13)$$

From part (i) we have found that, for every term:

$$\frac{\partial h_t}{\partial h_{t-1}} = (1 - u_t) \cdot w + u_t \quad (14)$$

u_t is the output of a sigmoid function that has a value in the range of (0,1). Hence, the term remains non-zero. This helps to avoid the vanishing gradient problem, as no exponential decay term can cause the gradients to vanish over long sequences. When u_t is 1, it implies that the new hidden state retains the value of the previous hidden state and when u_t is 0, it ignores the information from the previous step.