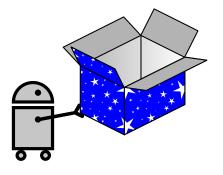
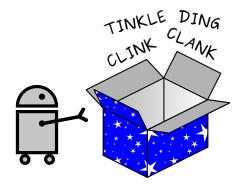
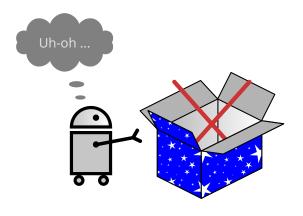
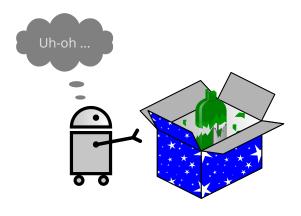
# **Conditional Beliefs in Action**

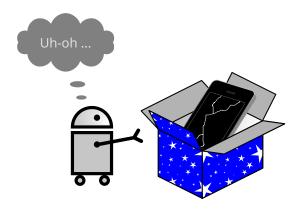
**Christoph Schwering** 

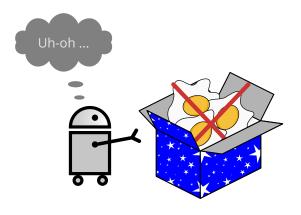


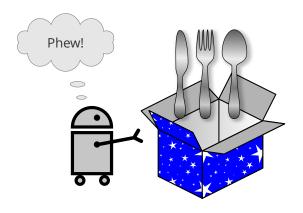












## What's in the box? — <u>Thesis objective</u>

### Involved concepts:

- Conditional beliefs
  - Believe the box is empty
  - But if it's not empty, it most likely contains a gift
- Actions and perception
  - ▶ Drop box → fragile objects breaks
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## What's in the box? — <u>Thesis objective</u>

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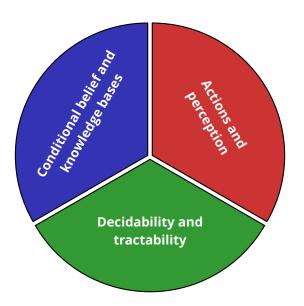
- Conditional beliefs
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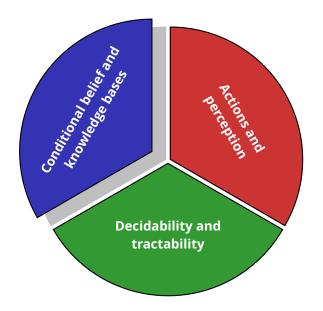
#### Thesis **objective**:

- <u>Formalize</u> these concepts
- Reason about them effectively

### Key questions:

- What is a conditional knowledge base?
- How are beliefs affected by actions and perception?
- When is reasoning computationally feasible?





### What does "believe that if $\alpha$ , then also $\beta$ " mean?

### Believing a **material implication** is insufficient:

- **Semantics**:  $\neg \alpha \lor \beta$  is believed
- Vacuously true when  $\neg \alpha$  is believed
- Often counterintuitive
  - If the box is not empty, there's peace on Earth

#### **Conditional belief** is more intuitive:

- Rank possible worlds by plausibility
- **Semantics**: β holds in the most-plausible α-worlds
- Meaningful even when  $\neg \alpha$  is believed

### Logic of conditional belief

First-order logic with two modal operators:

- $\mathbf{O}\{\alpha_1 \Rightarrow \beta_1,...,\alpha_m \Rightarrow \beta_m\} \triangleq \textit{all}$  we believe is  $\{\alpha_i \Rightarrow \beta_i\}$  a.k.a. only-believing
- Here: no nested beliefs

### Logic of conditional belief

First-order logic with two modal operators:

- $\mathbf{B}(\alpha \Rightarrow \beta)$   $\hat{=}$  we believe that if  $\alpha$ , then  $\beta$
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- Here: no nested beliefs

### Belief implication

Does 
$$\mathbf{O}\{\alpha_1 \Rightarrow \beta_1, ..., \alpha_m \Rightarrow \beta_m\}$$
 entail  $\mathbf{B}(\alpha \Rightarrow \beta)$ ?

- Generalizes Levesque's *logic of only-knowing* to conditional belief
- Next: semantics and properties

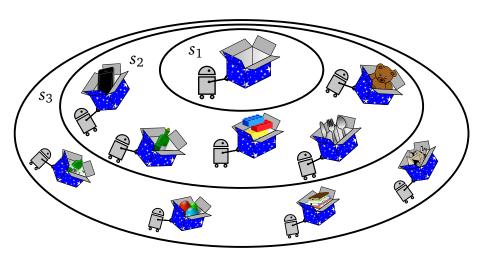
# Worlds and systems of spheres

■ A world is a truth assignment



# Worlds and systems of spheres

- A **world** is a truth assignment
- $\blacksquare$  A **system of spheres**  $\vec{s}$  ranks possible worlds by plausibility

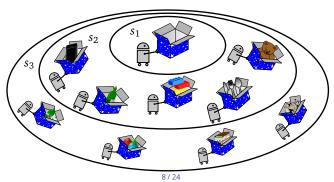


## Conditional believing

### **Semantics**

 $\vec{s}$  satisfies  $\mathbf{B}(\alpha \Rightarrow \beta)$  *iff* the first sphere of  $\vec{s}$  consistent with  $\alpha$  satisfies  $\alpha \supset \beta$ 

$$\mathbf{B}(\mathsf{True} \Rightarrow \forall x \neg \mathsf{InBox}(x))$$
$$\mathbf{B}(\exists y \mathsf{InBox}(y) \Rightarrow \exists x (\mathsf{InBox}(x) \land \mathsf{Gift}(x)))$$



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### Some properties

- Believing  $\alpha \triangleq \mathbf{B}(\text{True} \Rightarrow \alpha)$
- Knowing  $\alpha \triangleq \mathbf{B}(\neg \alpha \Rightarrow \text{False})$
- Quantifying-in  $\neg \exists x \mathbf{B} (\exists y \operatorname{InBox}(y) \Rightarrow \operatorname{InBox}(x))$
- Non-monotonic

#### **Semantics**

 $\vec{s}$  satisfies  $\mathbf{O}\{\alpha_1\Rightarrow\beta_1,...,\alpha_m\Rightarrow\beta_m\}$  iff  $\vec{s}$  is maximal such that  $\vec{s}$  satisfies all  $\mathbf{B}(\alpha_i\Rightarrow\beta_i)$ 

- $\vec{s}$  is maximal  $\hat{=}$  no worlds can be added to any sphere without removing worlds from some sphere
- $\mathbf{O}\{\alpha_1 \Rightarrow \beta_1,...,\alpha_m \Rightarrow \beta_m\}$   $\hat{=}$  all we believe is  $\{\alpha_i \Rightarrow \beta_i\}$

### Unique-model property

A unique  $\vec{s}$  satisfies  $\mathbf{O}\{\alpha_1 \Rightarrow \beta_1, ..., \alpha_m \Rightarrow \beta_m\}$ 

#### Semantics

 $ec{s}$  satisfies  $\mathbf{O}\{lpha_1 \Rightarrow eta_1,...,lpha_m \Rightarrow eta_m\}$  iff  $ec{s}$  is maximal such that  $ec{s}$  satisfies all  $\mathbf{B}(lpha_i \Rightarrow eta_i)$ 

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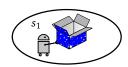
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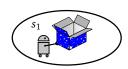
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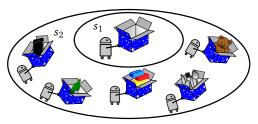
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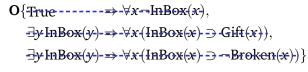
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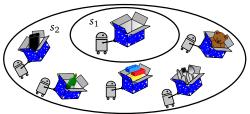
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O{True

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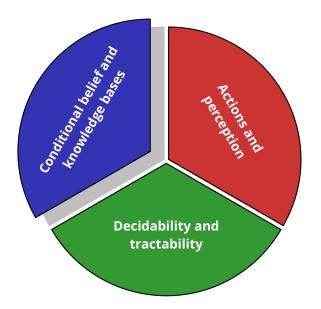
 $\Rightarrow \forall x \neg InBox(x),$ 

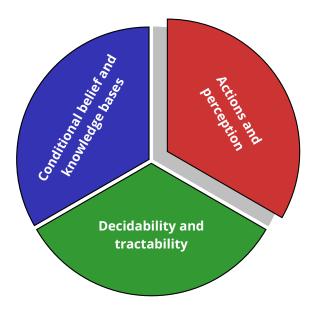
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## <u>Contribution</u>: conditional belief and knowledge bases

- Conditional belief → more and less plausible beliefs
- Only-believing captures idea of conditional KB
- Generalized Levesque's *logic of only-knowing* to conditional belief
  - Our logic subsumes Levesque's
  - Unique-model property of only-believing
  - Levesque's representation theorem extends nicely: decide belief implication with non-modal reasoning
- Related to Pearl's System Z
  - ► System Z is a meta-logical framework
  - Our logic subsumes Pearl's 1-entailment

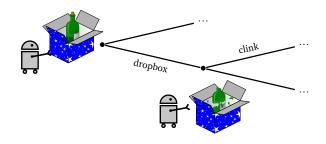




# Action effects: <a href="physical">physical</a> and/or epistemic

### **Physical** effect:

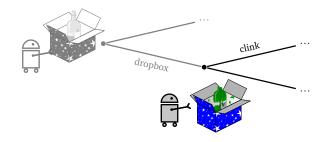
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## Action effects: physical and/or epistemic

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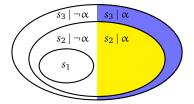
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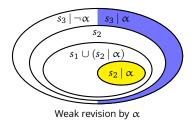
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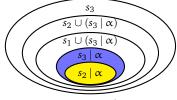
#### **Epistemic** effect:

- $\blacksquare$  Clink  $\rightarrow$  presumably something broke
- Semantics: revise the system of spheres



Original system of spheres





Strong revision by  $\boldsymbol{\alpha}$ 

# Action effects: physical and/or epistemic

### **Epistemic** effect:

- Clink → presumably something broke
- Semantics: revise the system of spheres

#### Actions **inform** the agent:

- **Action** A tells that  $\varphi_A$  is presumably true
- lacktriangledown  $\phi_A$  is incorporated by weak or strong revision
- Contradicting information is no problem

### Situation calculus with conditional belief

Two new modal operators:

- $[A] \alpha = \alpha \text{ holds after action } A$
- $\blacksquare \square \alpha \triangleq \alpha \text{ holds always}$

Action theory  $\mathbf{O}(\Sigma_{bel} \cup \Sigma_{dyn})$ :

- $\Sigma_{\text{bel}} \triangleq \text{initial beliefs}$
- lacksquare  $\Sigma_{dyn}$   $\stackrel{.}{=}$  knowledge about dynamics

 $\Box \forall x ([dropbox]Broken(x) \equiv Broken(x) \lor (Fragile(x) \land InBox(x)))$ 

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### Belief projection

Does 
$$\mathbf{O}(\Sigma_{\mathrm{bel}} \cup \Sigma_{\mathrm{dyn}})$$
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- Solution: reduce belief projection to belief implication
  - ▶ Regression: roll back actions  $A_k,...,A_1$  in query
  - **Progression:** apply effects of  $A_1,...,A_k$  to initial beliefs  $\Sigma_{bel}$

# Projection by regression

### Correctness of regression

$$\mathbf{O}(\Sigma_{bel} \cup \Sigma_{dyn})$$
 entails  $lpha$  iff  $\mathbf{O}\Sigma_{bel}$  entails  $\mathcal{R}[lpha]$ 

 $\mathcal{R}[\alpha]$  obtained by repeating until no [A] operator is left:

- 1. Push [A] operators inwards
- 2. **Predicates**: axioms  $\Sigma_{\text{dyn}}$  relate truth after and before A [dropbox]Broken(x)  $\mapsto$  Broken(x)  $\vee$  (Fragile(x)  $\wedge$  InBox(x))
- 3. **Beliefs**: theorems relate belief after and  $\frac{1}{2}$

$$[A]\mathbf{B}(\alpha \Rightarrow \beta) \mapsto \mathbf{B}(\varphi_A \wedge [A]\alpha \Rightarrow [A]\beta) \wedge \neg \mathbf{B}(\varphi_A \Rightarrow \neg [A]\alpha) \vee \mathbf{B}(\qquad [A]\alpha \Rightarrow [A]\beta) \wedge \mathbf{B}(\varphi_A \Rightarrow \neg [A]\alpha) \vee \mathbf{B}(\varphi_A \Rightarrow \text{False})$$

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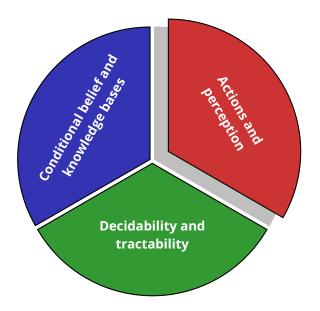
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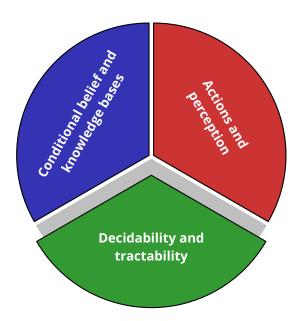
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## **Contribution**: actions and perception

- Conditional belief + situation calculus
- Physical and/or epistemic (informing) effect
- Projection by regression and progression
- Based on Lakemeyer and Levesque's epistemic sitcalc
  - We handle contradicting information
  - Extended regression, progression for conditional belief
- Goes beyond Shapiro et al.'s sitcalc with belief change
  - Our logic supports proper revision
  - We address belief projection





## Why decidable reasoning?

#### Our logic is too powerful:

- Omniscient
- Undecidable (first-order) / intractable (propositional)

#### Possible approaches:

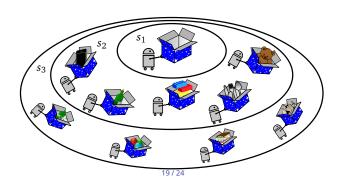
- Restrict expressivity (classical approach)
- Restrict inferences

#### **Limited** reasoning:

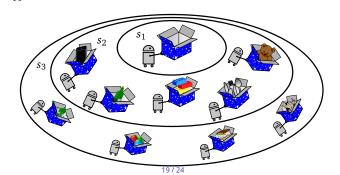
Set of worlds  $\rightarrow$  <u>setup</u>: set of ground clauses closed under subsumption and unit propagation

Add literals  $\rightarrow$  new inferences  $A \lor B \text{ subsumes } A \lor B \lor C$   $A \lor B \text{ subsumes } A \lor B \lor C$   $A \lor B \text{ subsumes } A \lor B \lor C \text{ yield } B \lor C$ 

```
\mathbf{O}\{\text{True} \Rightarrow \forall x \neg \text{InBox}(x), \\ \exists y \text{InBox}(y) \Rightarrow \forall x (\text{InBox}(x) \supset \text{Gift}(x)), \\ \exists y \text{InBox}(y) \Rightarrow \forall x (\text{InBox}(x) \supset \neg \text{Broken}(x))\}
```



```
\begin{aligned} \mathbf{O}\{ \text{True} & \Rightarrow \forall x \neg \text{InBox}(x), \\ & \exists y \, \text{InBox}(y) \Rightarrow \forall x \, (\text{InBox}(x) \supset \text{Gift}(x)), \\ & \exists y \, \text{InBox}(y) \Rightarrow \forall x \, (\text{InBox}(x) \supset \neg \text{Broken}(x)) \} \\ s_1 &= \{ \neg \text{InBox}(n) \mid n \in N \} \\ s_2 &= \{ \neg \text{InBox}(n) \vee \text{Gift}(n), \, \neg \text{InBox}(n) \vee \neg \text{Broken}(n) \mid n \in N \} \\ s_3 &= \{ \} \end{aligned}
```



```
\begin{split} s_1 &= \{\neg \text{InBox}(n) \mid n \in N\} \\ s_2 &= \{\neg \text{InBox}(n) \vee \text{Gift}(n), \ \neg \text{InBox}(n) \vee \neg \text{Broken}(n) \mid n \in N\} \\ s_3 &= \{\} \end{split}
```

Does  $\vec{s}$  satisfy  $\mathbf{B}(\underline{\mathsf{InBox}}(n) \Rightarrow \mathsf{Gift}(n) \land \neg \mathsf{Broken}(n))$ ?

```
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- $\blacksquare$   $s_1$  is <u>not consistent</u> with  $\underline{InBox}(n)$ 
  - $ightharpoonup s_1$  contains  $\neg \operatorname{InBox}(n)$

```
\begin{split} s_1 &= \{\neg \text{InBox}(n) \mid n \in N\} \\ s_2 &= \{\neg \text{InBox}(n) \vee \text{Gift}(n), \ \neg \text{InBox}(n) \vee \neg \text{Broken}(n) \mid n \in N\} \\ s_3 &= \{\} \end{split}
```

Does  $\vec{s}$  satisfy  $\mathbf{B}(\underline{\mathsf{InBox}}(n) \Rightarrow \mathsf{Gift}(n) \land \neg \mathsf{Broken}(n))$ ?

- $\blacksquare$   $s_2$  is <u>consistent</u> with  $\underline{InBox}(n)$ 
  - ▶  $s_2 \cup \{\operatorname{InBox}(n)\}$  is consistent
  - ▶  $s_2 \cup \{\operatorname{InBox}(n)\}\$ contains  $\operatorname{InBox}(n)$

```
\begin{split} s_1 &= \{\neg \mathsf{InBox}(n) \mid n \in N\} \\ s_2 &= \{\neg \mathsf{InBox}(n) \lor \mathsf{Gift}(n), \ \neg \mathsf{InBox}(n) \lor \neg \mathsf{Broken}(n) \mid n \in N\} \\ s_3 &= \{\} \end{split}
```

Does  $\vec{s}$  satisfy  $\mathbf{B}(\operatorname{InBox}(n) \Rightarrow \operatorname{Gift}(n) \land \neg \operatorname{Broken}(n))$ ?

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- $s_2$  satisfies  $InBox(n) \supset (Gift(n) \land \neg Broken(n))$ 
  - ▶  $s_2 \cup \{\neg InBox(n)\}\$  contains  $\neg InBox(n)$
  - ▶  $s_2 \cup \{\operatorname{InBox}(n)\}\$ contains  $\operatorname{Gift}(n)$  and  $\neg \operatorname{Broken}(n)$

```
s_1 = {\neg InBox(n) \mid n \in N}
   s_2 = \{\neg InBox(n) \lor Gift(n), \neg InBox(n) \lor \neg Broken(n) \mid n \in N\}
   s_3 = \{\}
                                          level \(\hat{=}\) added literals
Does \vec{s} satisfy \mathbf{B}_1(\text{In} \cancel{\mathsf{B}} \text{ox}(n) \Rightarrow \text{Gift}(n) \land \neg \text{Broken}(n))? \checkmark
    \blacksquare s_2 is consistent with \underline{\operatorname{InBox}(n)}

ightharpoonup s_2 \cup \{\operatorname{InBox}(n)\} is consistent

ightharpoonup s_2 \cup \{\operatorname{InBox}(n)\}\ \text{contains } \operatorname{InBox}(n)
    \blacksquare s_2 satisfies \underline{InBox(n)} \supset (Gift(n) \land \neg Broken(n))

ightharpoonup s_2 \cup \{\neg \operatorname{InBox}(n)\}\ \text{contains } \neg \operatorname{InBox}(n)

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```
s_1 = {\neg InBox(n) \mid n \in N}
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  s_3 = \{\}
                              Does \vec{s} satisfy \mathbf{B}_0^{\flat}(\operatorname{InBox}(n) \Rightarrow \operatorname{Gift}(n) \wedge \neg \operatorname{Broken}(n))?
Does \vec{s} satisfy \mathbf{B}_1(\underline{\mathsf{InBox}}(n) \Rightarrow \mathsf{Gift}(n) \land \neg \mathsf{Broken}(n))?
   \blacksquare s_2 is consistent with InBox(n)

ightharpoonup s_2 \cup \{\operatorname{InBox}(n)\} is consistent

ightharpoonup s_2 \cup \{\operatorname{InBox}(n)\}\ \text{contains } \operatorname{InBox}(n)
```

- $s_2$  satisfies  $InBox(n) \supset (Gift(n) \land \neg Broken(n))$ 
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  - ▶  $s_2 \cup \{\text{InBox}(n)\}\ \text{contains Gift}(n)\ \text{and } \neg \text{Broken}(n)$

## Logic of <u>limited</u> conditional belief

Belief operators with effort  $k \in \{0, 1, 2, ...\}$ 

- $\mathbf{O}_k\{\alpha_1\Rightarrow\beta_1,...,\alpha_m\Rightarrow\beta_m\}$   $\hat{}=$  only-belief at level k  $\alpha_i$  only mentions  $\land$ ,  $\exists$ , literals  $\beta_i$  only mentions  $\lor$ ,  $\forall$ , literals  $\beta_i$  only mentions  $\lor$ ,  $\forall$ , literals

## Logic of <u>limited</u> conditional belief

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### Limited belief implication

Does 
$$\mathbf{O}_k\{\alpha_1 \Rightarrow \beta_1,...,\alpha_m \Rightarrow \beta_m\}$$
 entail  $\mathbf{B}_{k'}(\alpha \Rightarrow \beta)$ ?

- Based on Liu, Lakemeyer, Levesque's limited knowledge
- Semantics for  $\mathbf{B}_k$  and  $\mathbf{O}_k$  mostly as for  $\mathbf{B}$  and  $\mathbf{O}$  except:
  - ightharpoonup Sets of possible worlds  $\mapsto$  setups
  - Sound but incomplete consistency and satisfaction
- Next: soundness and decidability

# Limited belief implication: <u>soundness</u> and decidability

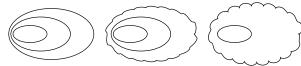
#### Soundness

If 
$$\mathbf{O}_k\{\alpha_1\Rightarrow\beta_1,...,\alpha_m\Rightarrow\beta_m\}$$
 entails  $\mathbf{B}_{k'}(\alpha\Rightarrow\beta)$ , then  $\mathbf{O}\{\alpha_1\Rightarrow\beta_1,...,\alpha_m\Rightarrow\beta_m\}$  entails  $\mathbf{B}(\alpha\Rightarrow\beta)$ 

# Limited belief implication: <u>soundness</u> and decidability

#### Soundness

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#### Why?

- $lackbox{0}_{k}$ 's first spheres are faithful to O's spheres
- $lackbox{0}_{k}$ 's last sphere believes less than  $lackbox{0}$ 's sphere
- lacksquare **B**<sub>k</sub> doesn't select a too-narrow sphere

# Limited belief implication: soundness and <u>decidability</u>

### Complexity

Whether  $\mathbf{O}_k\{\alpha_1 \Rightarrow \beta_1,...,\alpha_m \Rightarrow \beta_m\}$  entails  $\mathbf{B}_{k'}(\alpha \Rightarrow \beta)$  is

- First-order case: decidable
- Propositional case: tractable for fixed effort k, k'

# Limited belief implication: soundness and <u>decidability</u>

### Complexity

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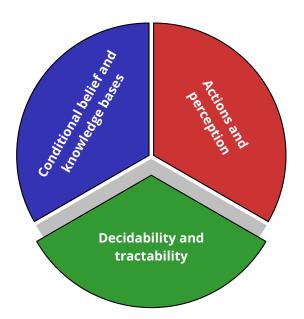
- First-order case: decidable
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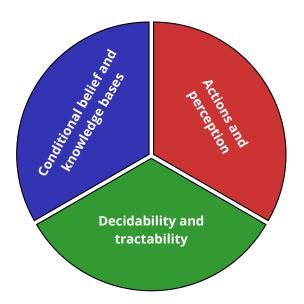
#### Why?

- Unique system of spheres since  $\alpha_i \supset \beta_i$  are clauses
- Only finitely many individuals can be distinguished by formulas
- Only finitely many literals are relevant for adding

### **Contribution:** limited conditional belief

- Effort bounds possible inferences
- Limited belief implication is decidable, sound
- Sacrificed completeness, preserved expressivity
- Based on Liu, Lakemeyer, Levesque's limited knowledge
  - Added sound consistency test
  - Approximative system of spheres





#### **Conditional Beliefs in Action**

■ What is a conditional knowledge base?

■ How are beliefs affected by actions and perception?

■ When is reasoning computationally feasible?

#### **Conditional Beliefs in Action**

- What is a conditional knowledge base?
  - Logic of conditional only-believing
  - Generalizes Levesque's logic, subsumes Pearl's 1-entailment
- How are beliefs affected by actions and perception?

■ When is reasoning computationally feasible?

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- When is reasoning computationally feasible?
  - Sound, decidable, sometimes tractable belief implications
  - Sacrificed completeness, preserved expressivity

# Summary and <u>future work</u>

#### **Conditional Beliefs in Action**

- What is a conditional knowledge base?
  - Logic of conditional only-believing
  - ▶ Generalizes Levesque's logic, subsumes Pearl's 1-entailment
  - Next: Probabilities?
- How are beliefs affected by actions and perception?
  - ▷ Sitcalc-style actions with belief revision
  - Projection by regression and progression
  - <u>Next</u>: More revision operators?
- When is reasoning computationally feasible?
  - Sound, decidable, sometimes tractable belief implications
  - Sacrificed completeness, preserved expressivity
  - <u>Next</u>: Tractable revision by limited reasoning?