

68000 Stack-Related Instructions

PEA <EA> Push Effective Address

- **Calculates an effective address <ea> and pushes it onto the stack pointed to by address register A7 (the stack pointer, SP).**
- **The difference between PEA and LEA**
 - **LEA loads an effective address in any address register.**
 - **PEA pushes an effective address onto the stack.**
- **PEA <EA> is equivalent to:**

LEA	<EA>,Ai
MOVEA.L	Ai,-(A7)

Where Ai is an address register other than A7 (A0-A6)

The MOVE Multiple: MOVEM Instruction

- This instruction saves or restores multiple registers.
- Useful in subroutines to save the values of registers not used to pass parameters. MOVEM has two forms:

MOVEM register_list,<ea>

MOVEM <ea>,register_list

- No effect on CCR

Example: Saving/restoring registers to from memory

```
SUBR1  MOVEM  D0-D7/A0-A6,SAVEBLOCK      SAVE D0-D7/A0-A6
      ...
      MOVEM  SAVEBLOCK,D0-D7/A0-A6      Restore D0-D7/A0-A6
      RTS
```

Example: Saving/restoring registers using the stack (preferred method).

```
SUBR1  MOVEM  D0-D7/A0-A6,-(SP)          Push D0-D7/A0-A6 onto the stack
      ...
      MOVEM  (SP)+,D0-D7/A0-A6          Restore D0-D7/A0-A6 from the stack
      RTS
```

The Stack and Local Subroutine

Variables: Stack Frames

- In order for a subroutine to be *recursive* or *re-entrant* , the subroutine's local workspace must be *attached* to each use or call of the subroutine.
- A stack frame (SF) of size d bytes is defined as a region of temporary storage in memory of size d bytes at the top of the current stack.
- Upon creating a stack frame:
 - The frame pointer (FP) points to the bottom of the stack frame. Register A6 is normally used as the frame pointer.
 - The stack pointer, SP is updated to point to the top of the frame.
- In 68000 assembly, the LINK and UNLK instructions are used to facilitate the creation/destruction of local subroutine storage using stack frames.

LINK $A_n, -\# d$

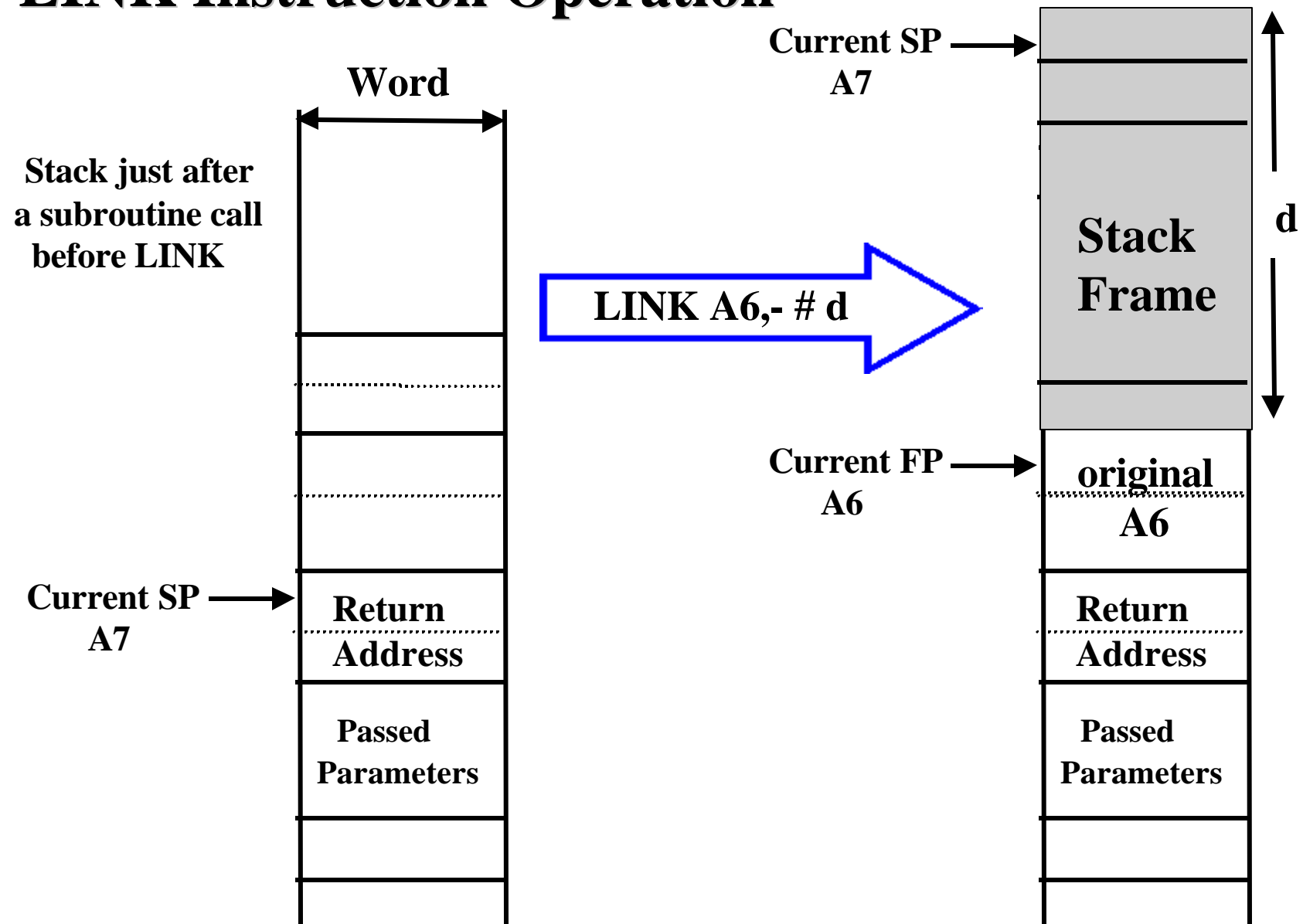
LINK Instruction

- Allocates or creates a frame in the stack for local use by the subroutine of size d bytes.
- A_n is an address register serving as the frame pointer (FP); A6 is used.
- **Function:**
 - Push the contents of address register A_n onto the stack. (includes pre-decrementing SP by 4).
 - Save the stack pointer in A_n (A_n points to bottom of frame)
 - Decrement the stack pointer by d (points to the top of the frame)
 - Similar in functionality to the following instruction sequence:

MOVEA.L	A6, -(SP)
LEA	(SP), A6
LEA	-d(SP), SP

- **After creating the frame:**
 - Passed parameters are accessed with a positive displacement with respect to FP, A6 i.e. **MOVE.W 8(A6), D0**
 - Local temporary storage variables are accessed with negative displacement with respect to A6 i.e. **MOVE.L D2, -10(A6)**

LINK Instruction Operation



UNLK UNLinK Instruction

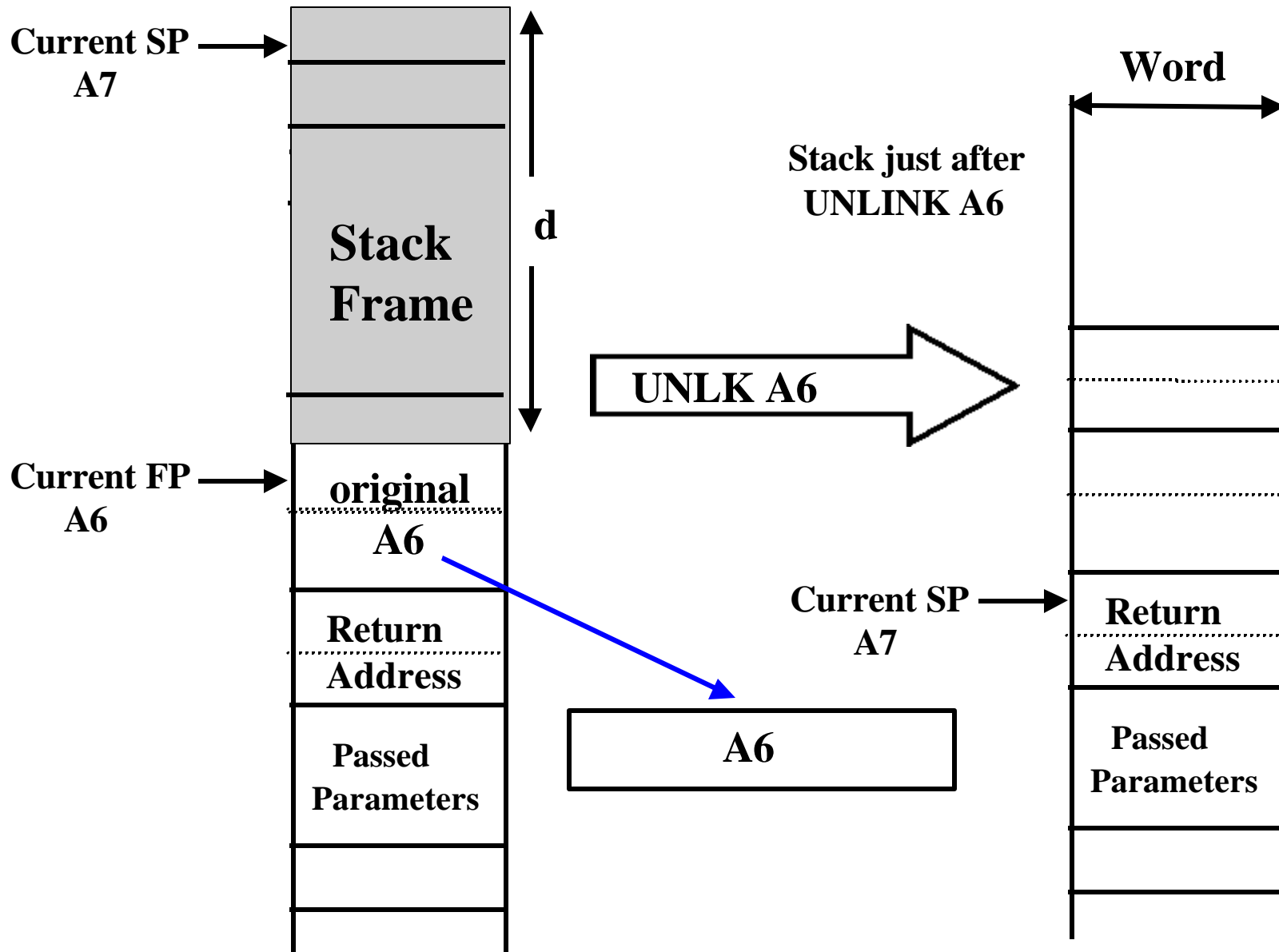
UNLK An

- Deallocates or destroys a stack frame. Where An is the address register used as frame pointer (FP); usually A6
- Function:
 - Restore the stack pointer to the value in address register An
i.e $SP = An$ or $SP = SP + d$
 - Restore register An by popping its value from the stack.
(includes post-incrementing SP by 4).

Similar in functionality to the following instruction sequence:

LEA	d(SP),SP
MOVEA.L	(SP)+,An

UNLK Instruction Operation



Recursive Subroutine Calls Example

The purpose of this example is to examine how all parameters, local variables, return addresses, and frame pointers are stored on the stack when a main program calls a procedure "Process" as well as when the procedure calls itself again in a recursion. We assume the following:

- The stack pointer initially has the value value \$00000F00 just before Process is invoked (before any parameters are pushed onto the stack).
- Array "X", "Y", "Z" and "ALPHA" are passed by reference.
- Parameter "N" is passed by value (both ways - i.e. into the called procedure and also copied by value back into the calling routine).
- A6 is used as the frame pointer (assumed to have initial value \$00002000).
- Procedure "Process" uses registers D0 - D4 as well as registers A0 - A4.
- Array X starts at location \$1800, Y starts at \$17F8, Z is at \$17FC, ALPHA is at \$17FD, and N is at \$17FE.

Recursive Subroutine Calls Example

Problem specification (continued):

{main routine}

X: array [0..30] of words

Y: longword

Z, ALPHA, N: byte

Process(var: X, var: Y, var: Z, var: ALPHA, N)

- **We are to show all the M68000 assembly language instructions necessary to pass these parameters as well as to copy the return value N into its regular storage location (off the stack) (at \$17FE).**

Recursive Subroutine Calls Example

Problem specification (continued):

Procedure Process (A, B, C, D, E)

A: array [0..?] of words {passed by reference}

B: longword {passed by reference}

C, D: byte {passed by reference}

E: byte {passed both ways by value}

local variables -

T: longword

U: word

V: byte

{ some place within the first invocation of "Process" it calls itself as follows: }

Process(var: A, var: T, var: C, var: V, E) {Note that some input parameters are passed through to the next iteration.}

Recursive Subroutine Calls Example

Solution

The main program is assumed to allocate the original storage for:

	ORG \$17F8	
Y	DS.L 1	This will resolve to address \$000017F8
Z	DS.B 1	This will resolve to address \$000017FC
ALPHA	DS.B 1	This will resolve to address \$000017FD
N	DS.B 1	This will resolve to address \$000017FE
*		
	ORG \$1800	
X	DS.W 31	an array of longwords 0..30

Recursive Subroutine Calls Example

Solution (Continued)

ORG \$1000 (assumed where main program starts - not critical)

*

* In main program the procedure (subroutine) is called in HLL:

*

* Process (var:X, var:Y, var:Z, var:ALPHA, N) where N is the only one passed by value

* The assembly language version/translation of this invocation is:

*

CLR.W D2	zeroes out an entire word for pushing on stack
MOVE.B N,D2	copies value of byte N into lowest byte of D2
MOVE.W D2,-(A7)	pushes that word containing value of N on stack
PEA ALPHA	pushes pointers to other arguments in reverse
PEA Z	order
PEA Y	
PEA X	
JSR Process	actually call the subroutine here
MOVE.B 17(A7),N	copy returned value back into N
ADDA.L #18,A7	fix up stack from all parameters pushed for
	subroutine call.

*

Recursive Subroutine Calls Example

Solution (Continued)

Stack Utilization Diagram

0E5E	not used	0E94	local 2 "T"	0ECA	A0
0E60			(longword)		
0E64	not used	0E98	local 2 "U"	0ECE	A1 (high)
0E68	not used	0E9A	- - "v" 2	0ED2	A1 (low)
		** 0E9C	link reg val		A2
			= \$00000EE6		
		0EA0	return addr	0ED6	A3
0E6C	D0 (high) 2		into Process		
	D0 (low)	0EA4	Addr of "X"	0EDA	A4
0E70	D1 2		="A" in Proc		
		0EA8	Addr of "T"1	0EDE	local 1 "T"
0E74	D2 2		= \$00000EDE		(longword)
		0EAC	Addr of "Z"	0EE2	local 1 "U"
0E78	D3 2		equiv "C" 1	0EE4	- - "v" 1
		0EB0	Addr of "V"1	*0EE6	orig linkreg
0E7C	D4 2		= \$00000EE5		= \$00002000
		0EB4	\$00 "E"2	0EEA	return addr
0E80	A0 2	0EB6	D0 (high) 1		into main pr
			D0 (low)	0EEE	Addr of "X"
0E84	A1 2	0EBA	D1 1		= \$00001800
		0EBE	D2 1	0EF2	Addr of "Y"
0E88	A2 2				= \$000017F8
		0EC2	D3 1	0EF6	Addr of "Z"
0E8C	A3 2				= \$000017FC
		0EC6	D4 1	0EFA	Addr "ALPHA"
0E90	A4 2				= \$000017FD
				0EFE	\$00 "N"val

* indicates the value of link register A6 during first call of Process

** indicates the value of link register A6 during the second call to Process

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Recursive Subroutine Calls Example Solution

(Continued) procedure Process

- The coding of procedure Process would be something like this:

Procedure Process (var:A, var:B, var:C, var:D, E)

* where A: is an array of words [0.. ?] passed by reference

* B: longword passed by reference

* C, D: byte passed by reference

* E: byte passed by value (in BOTH directions)

* and local variables:

* T: longword

* U: word

* V: byte

Ap _{ptr}	equ	8	displacements for finding pass by reference
Bp _{ptr}	equ	12	addresses from the frame pointer: A6
Cp _{ptr}	equ	16	
Dp _{ptr}	equ	20	
E	equ	25	this one is a byte which is passed by value
V	equ	-1	
U	equ	-4	
T	equ	-8	

Recursive Subroutine Calls Example

Solution (Continued) procedure Process

* The start of the code of Process looks like this:

*

Process **LINK A6,#-8**

MOVEM.L D0-D4/A0-A4,-(A7) save registers as required

*

* The invocation of Process from within Process:

*

* Process (A, T, C, V, E)

*

CLR.W D0

MOVE.B E(A6),D0

MOVE.W D0,-(A7)

PEA V(A6)

MOVE.L Cptr(A6),-(A7)

PEA T(A6),A0

MOVE.L Apr(A6),-(A7)

JSR Process

MOVE.B 17(A7),E(A6)

ADDA.L #18,A7

note how we access "E" - we could have modified "E" before sending it

this is basically how we can use "V" too

we push the pointer to "Z" on stack

push pointer to local variable "T" on stack

push pointer to "X" ("A" in Process)

copy return value of "E" to local copy

fix up stack from all parameters pushed

*

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Recursive Subroutine Calls Example

Solution (Continued) procedure Process

* This is how we'd access some of the variables in the subroutine:

*

MOVEA.L Aptr(A6),A0
MOVE.L (A0),U(A6)

This is how we'd copy the first array
element of X ("A" in procedure) into "U"

*

MOVEA.L Bptr(A6),A1
MOVE.W (A1),T(A6)

This is how we'd copy input parameter "B"
into local word "T"

*

MOVEA.L Cptr(A6),A2
MOVE.B (A2),D1

This is how we actually reference "C"

*

MOVEA.L Dptr(A6),A3
CLR.B (A3)

This is how we could access/change
"D" in procedure = "ALPHA" in main

*

* Before leaving the procedure we'd need to restore registers and destroy stack frame:

*

MOVEM.L (A7)+,D0-D4/A0-A4
UNLK A6
RTS

68000 Binary Coded Decimal (BCD) Arithmetic

- **Binary Coded Decimal (BCD)** is a way to store decimal numbers in binary. This number representation uses 4 bits to store each digit from 0 to 9. For example:

$$1998_{10} = 0001\ 1001\ 1001\ 1000 \text{ in BCD}$$

- BCD wastes storage space since 4 bits are used to store 10 combinations rather than the maximum possible 16.
- BCD is often used in business applications and calculators.
- The 68000 instruction set includes three instructions that offer some support for BCD arithmetic:
 - **ABCD** Add BCD with extend
 - **SBCD** Subtract BCD with extend
 - **NBCD** Negate BCD
- BCD instructions use and affect the X-bit because they are intended to be used in chained calculations where arithmetic is done on strings of BCD digits.
 - For addition: the X-bit records the carry
 - For subtraction: the X-bit records the borrow

ABCD

Add Decimal with Extend (M68000 Family)

ABCD

Operation: Source10 + Destination10 + X → Destination

Assembler Syntax: ABCD Dy,Dx
ABCD – (Ay), – (Ax)

Attributes: Size = (Byte)

Description: Adds the source operand to the destination operand along with the extend bit, and stores the result in the destination location. The addition is performed using binary-coded decimal arithmetic. The operands, which are packed binary-coded decimal numbers, can be addressed in two different ways:

1. Data Register to Data Register: The operands are contained in the data registers specified in the instruction.
2. Memory to Memory: The operands are addressed with the predecrement addressing mode using the address registers specified in the instruction.

This operation is a byte operation only.

ABCD

Add Decimal with Extend (M68000 Family)

ABCD

Condition Codes:

X	N	Z	V	C
.	U	.	U	.

X — Set the same as the carry bit.

N — Undefined.

Z — Cleared if the result is nonzero; unchanged otherwise.

V — Undefined.

C — Set if a decimal carry was generated; cleared otherwise.

NOTE

Normally, the Z condition code bit is set via programming before the start of an operation. This allows successful tests for zero results upon completion of multiple-precision operations.

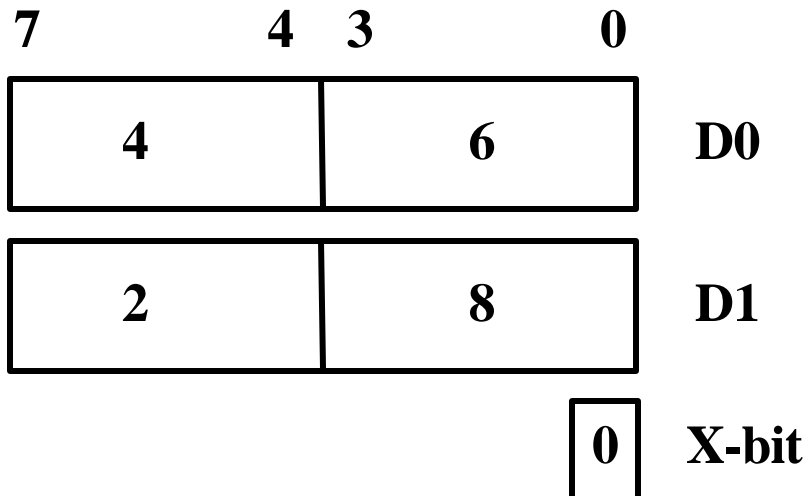
Effect of ABCD

When $X = 0$ initially

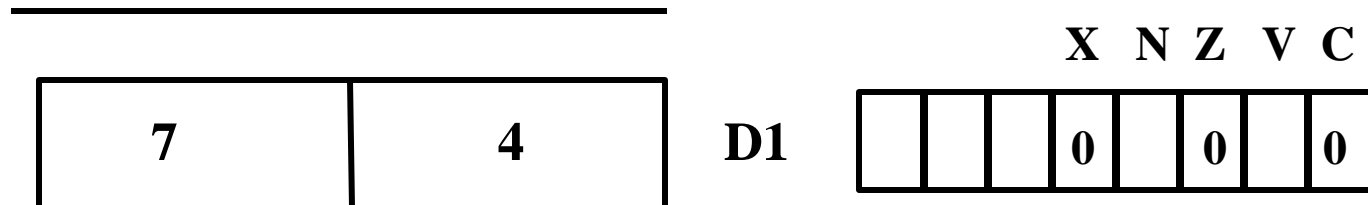
ABCD D0,D1

Add D0 to D1 with the X-bit

Before



After



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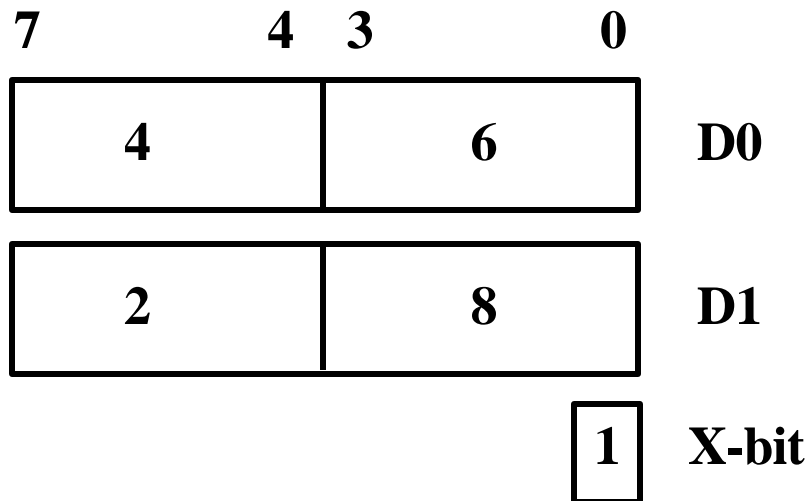
Effect of ABCD

When $X = 1$ initially

ABCD D0,D1

Add D0 to D1 with the X-bit

Before



After



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SBCD

Subtract Decimal with Extend (M68000 Family)

SBCD

Operation: Destination10 – Source10 – X → Destination

Assembler Syntax: SBCD Dx,Dy
SBCD – (Ax), – (Ay)

Attributes: Size = (Byte)

Description: Subtracts the source operand and the extend bit from the destination operand and stores the result in the destination location. The subtraction is performed using binary-coded decimal arithmetic; the operands are packed binary-coded decimal numbers. The instruction has two modes:

1. Data register to data register—the data registers specified in the instruction contain the operands.
2. Memory to memory—the address registers specified in the instruction access the operands from memory using the predecrement addressing mode.

This operation is a byte operation only.

SBCD

Subtract Decimal with Extend (M68000 Family)

SBCD

Condition Codes:

X	N	Z	V	C
*	U	*	U	*

X — Set the same as the carry bit.

N — Undefined.

Z — Cleared if the result is nonzero; unchanged otherwise.

V — Undefined.

C — Set if a borrow (decimal) is generated; cleared otherwise.

NOTE

Normally the Z condition code bit is set via programming before the start of an operation. This allows successful tests for zero results upon completion of multiple-precision operations.

Effect of SBCD

When $X = 0$ initially

SBCD D1,D0

Subtract D1 from D0 with the X-bit

Before

7	4	3	0	
4		6		D0
2		8		D1
			0	X-bit

After

1	8	D0
---	---	----

X N Z V C

			0		0		0
--	--	--	---	--	---	--	---

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Effect of SBCD

When $X = 1$ initially

SBCD D1,D0

Subtract D1 from D0 with the X-bit

Before

7	4	3	0	
4		6		D0
2		8		D1
				1 X-bit

After

1	7	D0
---	---	----

X N Z V C

			0		0		0
--	--	--	---	--	---	--	---

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NBCD

Negate Decimal with Extend (M68000 Family)

NBCD

Operation: $0 - \text{Destination}_{10} - X \rightarrow \text{Destination}$

**Assembler
Syntax:** NBCD < ea >

Attributes: Size = (Byte)

Description: Subtracts the destination operand and the extend bit from zero. The operation is performed using binary-coded decimal arithmetic. The packed binary-coded decimal result is saved in the destination location. This instruction produces the tens complement of the destination if the extend bit is zero or the nines complement if the extend bit is one. This is a byte operation only.

Condition Codes:

X	N	Z	V	C
*	U	*	U	*

X — Set the same as the carry bit.

N — Undefined.

Z — Cleared if the result is nonzero; unchanged otherwise.

V — Undefined.

C — Set if a decimal borrow occurs; cleared otherwise.

Effect of NBCD

When $X = 0$ initially

NBCD D0

Subtract D0 from 0 with the X-bit

Before

7	4	3	0
0	0		

2	8
---	---

D0

0

X-bit

After

7	2
---	---

D0

X N Z V C

			1		0		1
--	--	--	---	--	---	--	---

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Effect of NBCD

When $X = 1$ initially

NBCD D0

Subtract D0 from 0 with the X-bit

Before

7	4	3	0
0		0	
2		8	

D0

1

X-bit

After

7	1
---	---

D0

X N Z V C

			1		0		1
--	--	--	---	--	---	--	---

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BCD Addition Example

- Two BCD strings each with 12 BCD digits (six bytes) and stored in memory starting at locations: String1, String2, are to be added together with the result to be stored in memory starting at String2

	ORG	\$1000	
ADDBCD	MOVE.W	#5,D0	Loop counter, six bytes to be added
	ANDI	#\$EF,CCR	Clear X-bit in CCR
	LEA	String1+6,A0	A0 points at end of source string +1
	LEA	String2+6,A1	A0 points at end of destination string +1
LOOP	ABCD	-(A0),-(A1)	Add pair of digits with carry-in
	DBRA	D0,LOOP	Repeat until 12 digits are added
	RTS		
	.		
	.		
String1	DS.B	6	DBRA used here because it does not affect the X-bit needed in BCD arithmetic
String2	DS.B	6	

68000 Multiple-Precision Arithmetic

- For numerical values, *precision* refers to the number of significant digits in the numerical value.
 - If more precision is needed in a numerical value, more significant digits must be used to yield a more precise result.
- The maximum single-precision operand length supported by the 68000 is 32 bits. Thus, values with greater length cannot be handled as a single arithmetic operand by the CPU.
- To extend the precision, several 32-bit operands can be used and considered mathematically as a single value.
- The 68000 offers three special instructions to facilitate addition, subtraction, and negation of multiple-precision integers:

- **ADDX** **ADD** with **eXtend**
- **SUBX** **SUB**tract with **eXtend**
- **NEGX** **NEG**ate with **eXtend**

ADDX

Add Extended
(M68000 Family)

ADDX

Operation: Source + Destination + X → Destination

Assembler Syntax: ADDX Dy,Dx
ADDX – (Ay), – (Ax)

Attributes: Size = (Byte, Word, Long)

Description: Adds the source operand and the extend bit to the destination operand and stores the result in the destination location.

Condition Codes:

X	N	Z	V	C
.

- X — Set the same as the carry bit.
- N — Set if the result is negative; cleared otherwise.
- Z — Cleared if the result is nonzero; unchanged otherwise.
- V — Set if an overflow occurs; cleared otherwise.
- C — Set if a carry is generated; cleared otherwise.

SUBX

Subtract with Extend (M68000 Family)

SUBX

Operation: Destination – Source – X → Destination

Assembler Syntax: SUBX Dx,Dy
SUBX – (Ax), – (Ay)

Attributes: Size = (Byte, Word, Long)

Description: Subtracts the source operand and the extend bit from the destination operand and stores the result in the destination

Condition Codes:

X	N	Z	V	C
*	*	*	*	*

- X — Set to the value of the carry bit.
- N — Set if the result is negative; cleared otherwise.
- Z — Cleared if the result is nonzero; unchanged otherwise.
- V — Set if an overflow occurs; cleared otherwise.
- C — Set if a borrow occurs; cleared otherwise.

NEGX

Negate with Extend (M68000 Family)

NEGX

Operation: $0 - \text{Destination} - X \rightarrow \text{Destination}$

Assembler Syntax: `NEGX <ea>`

Attributes: Size = (Byte, Word, Long)

Description: Subtracts the destination operand and the extend bit from zero. Stores the result in the destination location. The size of the operation is specified as byte, word, or long.

Condition Codes:

X	N	Z	V	C
*	*	*	*	*

X — Set the same as the carry bit.
N — Set if the result is negative; cleared otherwise.
Z — Cleared if the result is nonzero; unchanged otherwise.
V — Set if an overflow occurs; cleared otherwise.
C — Set if a borrow occurs; cleared otherwise.

Multiple-Precision Addition Example

- Two unsigned binary numbers each with 128 bits (16 bytes) and stored in memory starting at locations Num1, Num2 are to be added together with the result to be stored in memory starting at Num2

	ORG	\$1000	
MPADD	MOVE.W	#3,D0	Four long words to be added
	ANDI	#\$EF,CCR	Clear X-bit in CCR
	LEA	Num1,A0	A0 points at start of source
	ADDA	#16,A0	A0 points to end of source + 1
	LEA	Num2,A1	A1 points at start of destination
	ADDA	#16,A1	A1 points to end of destination + 1
LOOP	ADDX.L	-(A0),-(A1)	Add pair of long words with carry-in
	DBRA	D0,LOOP	Repeat until 4 long words are added
	RTS		
	.		
	.		
Num1	DS.L	4	
Num2	DS.L	4	

DBRA is used here because it does not affect the X-bit needed in multiple-precision arithmetic

Estimation of Assembly Programs Execution Time

- For a CPU running at a constant clock rate:
 $\text{clock rate} = 1 / \text{clock cycle time}$
- Every machine or assembly instruction takes one or more clock cycles to complete.
- The total time an assembly program requires to run is given by:

$$\begin{aligned}\text{Execution time} &= \text{Total number of cycles} \times \text{Clock cycle time} \\ &= \text{Instruction count} \times \text{cycles per instruction} \times \text{clock cycle time} \\ &= \text{Instruction count} \times \text{cycles per instruction} / \text{clock rate}\end{aligned}$$

Example:

For a CPU running at 8MHZ is executing a program with a total of 100 000 instructions. Assuming that each instruction takes 10 clock cycles to complete:

$$\text{Execution time} = 100\,000 \times 10 / 8\,000\,000 = 0.125 \text{ seconds}$$

68000 Cycles For MOVE Instructions

Operand Size		Addressing Mode							
.b.w/.l		dn	an	(an)	(an)+	-(an)	d(an)	d(an),dn	abs.s abs.l
dn		4/4	4/4	8/12	8/12	8/14	12/16	14/18	12/16 16/20
an		4/4	4/4	8/12	8/12	8/14	12/16	14/18	12/16 16/20
(an)		8/12	8/12	12/20	12/20	12/20	16/24	18/26	16/24 20/28
(an)+		8/12	8/12	12/20	12/20	12/20	16/24	18/26	16/24 20/28
-(an)		10/14	10/14	14/22	14/22	14/22	18/26	20/28	18/26 22/30
d(an)		12/16	12/16	16/24	16/24	16/24	20/28	22/30	20/28 24/32
d(an, dn)		14/18	14/18	18/26	18/26	18/26	22/30	24/32	22/30 26/34
abs.s		12/16	12/16	16/24	16/24	16/24	20/28	22/30	20/28 24/32
abs.l		16/20	16/20	20/28	20/28	20/28	24/32	26/34	24/32 28/36
d(pc)		12/16	12/16	16/24	16/24	16/24	20/28	22/30	20/28 24/32
d(pc, dn)		14/18	14/18	18/26	18/26	18/26	22/30	24/32	22/30 26/34
Immediate		8/12	8/12	12/20	12/20	12/20	16/24	18/26	16/24 20/28

Clock Cycles

Time to Calculate Effective Addresses

	Addressing Mode				
	(an)	$(an) +$	$-(an)$	$d(an)$	$d(an, dn)$
.b.w/.l	4/8	4/8	6/10	8/12	10/14
Operand Size					

	Addressing Mode				
	abs.s	abs.l	$d(pc)$	$d(pc, dn)$	Imm
.b.w/.l	8/12	12/16	8/12	10/14	4/8
Operand Size					

The time taken to calculate the effective address must be added to instructions that affect a memory address.

68000 Cycles For Standard Instructions

Operand Size	Addressing Mode		
.b .w/ .l	ea , an	ea , dn	dn , mem
add	8 / 6 (8)	4 / 6 (8)	8 / 12
and	-	4 / 6 (8)	8 / 12
cmp	6 / 6	4 / 6	-
divs	-	158max	-
divu	-	140max	-
eor	-	4 / 8	8 / 12
mul s	-	70max	-
mul u	-	70max	-
or	-	4 / 6 (8)	8 / 12
sub	8 / 6 (8)	4 / 6 (8)	8 / 12

Clock Cycles

(8) time if effective address is direct

Add effective address times from above for mem addresses

Cycles For Immediate Instructions

Operand Size	Addressing Mode		
.b .w / .l	#, dn	#, an	#, mem
addi	8/16	-	12/20
addq	4/8	8/8	8/12
andi	8/16	-	12/20
cmpi	8/14	8/14	8/12
eori	8/16	-	12/20
moveq	4	-	-
ori	8/16	-	12/20
subi	8/16	-	12/20
subq	4/8	8/8	8/12

Clock Cycles

Moveq.l only
nbcd+tas.b only

scc false/true

Add effective address
times from above
for mem addresses

Cycles for Single-Operand Instructions

Operand Size	Addressing Mode		
.b.w/.l	#,dn	#,an	#,mem
clr	4 / 6	4 / 6	8 / 12
nbcd	6	6	8
neg	4 / 6	4 / 6	8 / 12
negx	4 / 6	4 / 6	8 / 12
not	4 / 6	4 / 6	8 / 12
scc	4 / 6	4 / 6	8 / 8
tas	4	4	10
tst	4 / 4	4 / 4	4 / 4

Add effective address times from above for mem addresses

Clock Cycles

Cycles for Shift/Rotate Instructions

Operand Size	Addressing Mode		
	dn	an	mem
.b .w / .l			
asr, asl	6 / 8	6 / 8	8
lsr, lsl	6 / 8	6 / 8	8
ror, rol	6 / 8	6 / 8	8
roxr, roxl	6 / 8	6 / 8	8

Clock Cycles

**Memory is byte only
For register add 2x
the shift count**

Misc. Instructions

Addressing Mode

		(an)	(an)+	-(an)	d(an)	d(an),dn)	abs.s	abs.l	d(pc)	d(pc),dn)
jmp		8	-	-	10	14	10	12	10	14
jsr		16	-	-	18	22	18	20	18	22
lea		4	-	-	8	12	8	12	8	12
pea		12	-	-	16	20	16	20	16	20
movem	t=4									
m>r		12	12	-	16	18	16	20	16	18
movem	t=5									
r>m		8	-	8	12	14	12	16	-	-
movem	add t x number of registers for .w									
movem	add 2t x number of registers for .l									

Clock Cycles

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Cycles for Bit Manipulation Instructions

Operand Size .b/ .l	Addressing Mode	
	register .l	memory .b
	only	only
bchg	8/12	8/12
bclr	10/14	8/12
bset	8/12	8/12
btst	6/10	4/8

Clock Cycles

Cycles To Process Exceptions

Address Error	50
Bus Error	50
Interrupt	44
Illegal Instr.	34
Privilege Viol.	34
Trace	34

Cycles for Other Instructions

Operand Size

.b .w / .l

dn, dn

m, m

Addressing Mode

addx	4 / 8	18 / 30	
cmpm	-	12 / 20	
subx	4 / 8	18 / 30	
abcd	6	18	.b only
sbcd	6	18	.b only
Bcc	.b / .w	10 / 10	8 / 12
bra	.b / .w	10 / 10	-
bsr	.b / .w	18 / 18	-
DBcc	t / f	10	12 / 14
chk	-	40 max	8
trap	-	34	-
trapv	-	34	4

Add effective address
times from above
for mem addresses

Clock Cycles

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Cycles for Other Instructions

reg<>mem

movep .w/.l 16/24

Addressing Mode			Addressing Mode	
	Reg	Mem		Reg
andi to ccr	20	-	move from usp	4
andi to sr	20	-	nop	4
eori to ccr	20	-	ori to ccr	20
eori to sr	20	-	ori to sr	20
exg	6	-	reset	132
ext	4	-	rte	20
link	18	-	rtr	20
move to ccr	12	12	rts	16
move to sr	12	12	stop	4
move from sr	6	8	swap	4
move to usp	4	-	unlk	12

Clock Cycles

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Timing Example 1

Instruction			Clock Cycles
RANDOM	ADDI.B	#17,D0	8
	LSL.B	#3,D0	12
	NOT.B	D0	4
	RTS		16
Total Cycles needed:			40 cycles

For a 68000 running at 8MHZ:

Clock cycle = 125 nsec

Execution time = 40 X 125 nsec = 5 μ s = 5 x 10⁻⁶ second

Timing Example 2

			Clock Cycles	
Instruction			Overhead	Loop
READ	MOVE.B	#255,D0	8	
	ADD.W	(A0)+,D1		8
	SUBQ.B	#1,D0		4
	BNE	READ		10

$$\begin{aligned}
 \text{Total Cycles Needed} &= 8 + 255 (8 + 4 + 10) \\
 &= 8 + 255 \times 22 \\
 &= 5618 \text{ cycles}
 \end{aligned}$$

$$\begin{aligned}
 \text{Execution time for 8MHZ 68000} &= 5618 \times 125 \text{ nsec} \\
 &= 0.00070225 \text{ Seconds} = .702 \text{ msec}
 \end{aligned}$$

Timing Example 3

- **TOBIN** converts a four-digit BCD number in the lower word of D0 into a binary number returned in D2

			Clock Cycles		
	Instructions		overhead	outer loop	inner loop
TOBIN	CLR.L	D2	6		
	MOVEQ	#3,D6	4		
NEXTDIGIT	MOVEQ	#3,D5		4	
	CLR.W	D1		4	
GETNUM	LSL.W	#1,D0			8
	ROXL.W	#1,D1			8
	DBRA	D5,GETNUM			10
	MULU	#10,D2		42	
	ADD.W	D1,D2		4	
	DBRA	D6,NEXTDIGIT		10	
	RTS		16		

$$\begin{aligned}
 \text{Total Clock cycles} &= \text{overhead} + ((\text{inner loop cycles} \times 4) + \text{outer loop cycles}) \times 4 \\
 &= 26 + ((26 \times 4) + 64) \times 4 \\
 &= 26 + 168 \times 4 = 698 \text{ cycles} \\
 &= 698 \times 125 \text{ nsec} = 87.25 \text{ ms}
 \end{aligned}$$

or over 11 400 BCD numbers converted to binary every second.

Representation of Floating Point Numbers in Single Precision *IEEE 754 Standard*

$$\text{Value} = N = (-1)^S \times 2^{E-127} \times (1.M)$$

$0 < E < 255$
Actual exponent is:
 $e = E - 127$



exponent:
excess 127
binary integer
added

mantissa:
sign + magnitude, normalized
binary significand with
a hidden integer bit: 1.M

Example: $0 = 0$ 00000000 0 ... 0

$-1.5 = 1$ 01111111 10 ... 0

Magnitude of numbers that
can be represented is in the range:

$$2^{-126} (1.0) \quad \text{to} \quad 2^{127} (2 - 2^{-23})$$

Which is approximately:

$$1.8 \times 10^{-38} \quad \text{to} \quad 3.40 \times 10^{38}$$

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Floating Point Conversion Example

- The decimal number $.75_{10}$ is to be represented in the *IEEE 754* 32-bit single precision format:

$$.75_{10} = 0.11_2 \quad (\text{converted to a binary number})$$

$$= 1.1 \times 2^{-1} \quad (\text{normalized a binary number})$$

Hidden

- The mantissa is positive so the sign S is given by:

$$S = 0$$

- The biased exponent E is given by $E = e + 127$

$$E = -1 + 127 = 126_{10} = 01111110_2$$

- Fractional part of mantissa M :

$$M = .100000000000000000000000 \quad (\text{in 23 bits})$$

The *IEEE 754* single precision representation is given by:

0	01111110	100000000000000000000000
---	----------	--------------------------

S	E	M
---	---	---

1 bit

8 bits

23 bits

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Floating Point Conversion Example

- The decimal number -2345.125_{10} is to be represented in the *IEEE 754* 32-bit single precision format:

$$-2345.125_{10} = -100100101001.001_2 \quad (\text{converted to binary})$$

$$= -1.00100101001001 \times 2^{11} \quad (\text{normalized binary})$$

Hidden

- The mantissa is negative so the sign S is given by:

$$S = 1$$

- The biased exponent E is given by $E = e + 127$

$$E = 11 + 127 = 138_{10} = 10001010_2$$

- Fractional part of mantissa M :

$$M = .001001010010010000000000 \quad (\text{in 23 bits})$$

The *IEEE 754* single precision representation is given by:

1	10001010	001001010010010000000000
---	----------	--------------------------

S	E	M
---	---	---

1 bit

8 bits

23 bits

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Basic Floating Point Addition Algorithm

Assuming that the operands are already in the IEEE 754 format, performing floating point addition: $\text{Result} = X + Y = (X_m \times 2^{X_e}) + (Y_m \times 2^{Y_e})$

involves the following steps:

(1) Align binary point:

- Initial result exponent: the larger of X_e , Y_e
- Compute exponent difference: $Y_e - X_e$
- If $Y_e > X_e$ Right shift X_m that many positions to form $X_m 2^{X_e - Y_e}$
- If $X_e > Y_e$ Right shift Y_m that many positions to form $Y_m 2^{Y_e - X_e}$

(2) Compute sum of aligned mantissas:

i.e $X_m 2^{X_e - Y_e} + Y_m$ or $X_m + X_m 2^{Y_e - X_e}$

(3) If normalization of result is needed, then a normalization step follows:

- Left shift result, decrement result exponent (e.g., if result is 0.001xx...) or
- Right shift result, increment result exponent (e.g., if result is 10.1xx...)

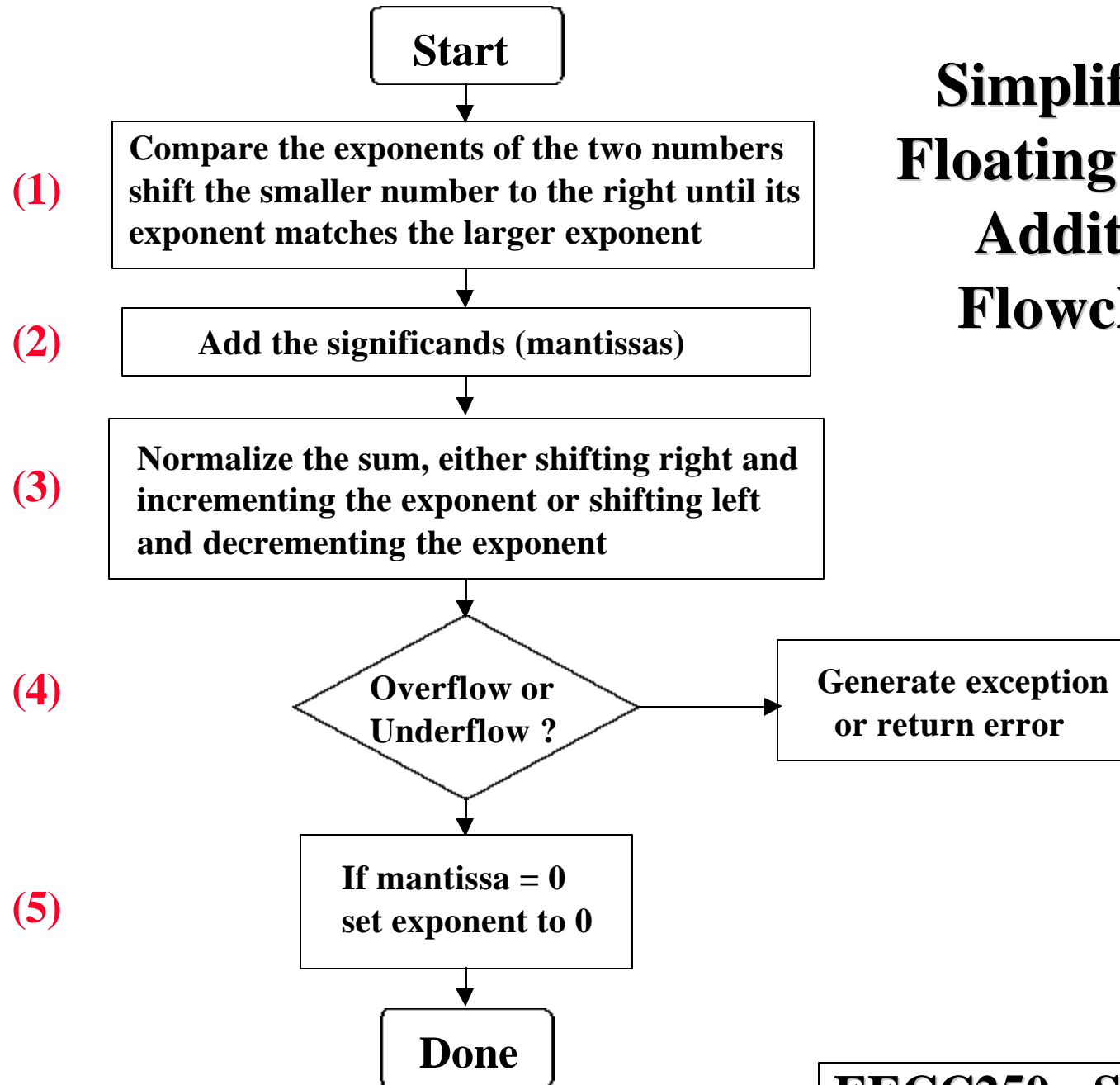
Continue until MSB of data is 1 (NOTE: Hidden bit in IEEE Standard)

(4) Check result exponent:

- If larger than maximum exponent allowed return exponent overflow
- If smaller than minimum exponent allowed return exponent underflow

(5) If result mantissa is 0, may need to set the exponent to zero by a special step to return a proper zero.

Simplified Floating Point Addition Flowchart



Floating Point Addition Example

- Add the following two numbers represented in the *IEEE 754* single precision format: $X = 2345.125_{10}$ represented as:

0	10001010	001001010010010000000000
---	----------	--------------------------

to $Y = .75_{10}$ represented as:

0	01111110	100000000000000000000000
---	----------	--------------------------

(1) Align binary point:

- $X_e > Y_e$ initial result exponent = $Y_e = 10001010 = 138_{10}$
- $X_e - Y_e = 10001010 - 01111110 = 00000110 = 12_{10}$
- Shift Y_m 12_{10} positions to the right to form

$$Y_m 2^{Y_e - X_e} = Y_m 2^{-12} = 0.000000000001100000000000$$

(2) Add mantissas:

$$\begin{aligned} X_m + Y_m 2^{-12} &= 1.001001010010010000000000 \\ &+ 0.000000000001100000000000 = \\ &1.001001010011110000000000 \end{aligned}$$

(3) Normalized? Yes

(4) Overflow? No. Underflow? No (5) zero result? No

Result	0	10001010	001001010011110000000000
--------	---	----------	--------------------------

IEEE 754 Single precision Addition Notes

- If the exponents differ by more than 24, the smaller number will be shifted right entirely out of the mantissa field, producing a zero mantissa.
 - The sum will then equal the larger number.
 - Such truncation errors occur when the numbers differ by a factor of more than 2^{24} , which is approximately 1.6×10^7 .
 - Thus, the precision of IEEE single precision floating point arithmetic is approximately 7 decimal digits.
- Negative mantissas are handled by first converting to 2's complement and then performing the addition.
 - After the addition is performed, the result is converted back to sign-magnitude form.
- When adding numbers of opposite sign, cancellation may occur, resulting in a sum which is arbitrarily small, or even zero if the numbers are equal in magnitude.
 - Normalization in this case may require shifting by the total number of bits in the mantissa, resulting in a large loss of accuracy.
- Floating point subtraction is achieved simply by inverting the sign bit and performing addition of signed mantissas as outlined above.

Assembly Language Macros

- Most assemblers include support for macros. The term macro refers to a word that stands for an entire group of instructions.
- Using macros in an assembly program involves two steps:

1 Defining a macro:

The definition of a macro consists of three parts: the header, body, and terminator:

<label> MACRO	The header
. . . .	The body: instructions to be executed
ENDM	The terminator

- ## 2 Invoking a macro by using its given <label> on a separate line followed by the list of parameters used if any:

<label> [parameter list]

Differences Between Macros and Subroutines

- Both permit a group of instructions to be defined as a single entity with a unique given label or name called up when needed.
- A subroutine is called by the BSR or JSR instructions, while a macro is called by simply using its name.
- Macros are not a substitute for subroutines:
 - Since the macro is substituted with the code which constitutes the body of the macro into the code, very long macros that are used many times in a program will result in an enormous expansion of the code size.
 - In this case, a subroutine would be a better choice, since the code in the body of the subroutine is not inserted into source code many when called.
- Support for subroutines is provided by the CPU --here, the 68000-- as part of the instruction set, while support for macros is part of the assembler (similar to assembler directives).

Defining the macro:

A Macro Example

AddMul MACRO
ADD.B
AND.W
MULU
ENDM

Macro definition

D0 = D0 + 7

Mask D0 to a byte

D0 = D0 x 12

End of macro def.

Invoking the macro:

MOVE.B
AddMul
. . .
MOVE.B
AddMul

X,D0

Get X

Call the macro

Y,D0

Get Y

Call the macro

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Macros and Parameters

- A macro parameter is designated within the body of the macro by a backslash "\" followed by a single digit or capital letter:

`\1, \2, \3 . . . \A, \B, \C . . . \Z`

- Thus, up to 35 different, substitutable arguments may be used in the body of a macro definition.
- The enumerated sequence corresponds to the sequence of parameters passed on invocation.
 - The first parameter corresponds to `\1` and the 10th parameter corresponds to `\A`.
 - At the time of invocation, these arguments are replaced by the parameters given in the parameter list.

Macro Example with Parameter Substitution

Defining the macro:

AddMul MACRO
ADD.B #7,\1
AND.W #00FF,\1
MULU #12,\1
ENDM

Macro definition

Reg = Reg + 7

Mask Reg to a byte

Reg = Reg x 12

End of macro def.

Invoking the macro:

MOVE.B X,D0

Get X

AddMul D0

Call the macro

. . .

MOVE.B Y,D1

Get Y

AddMul D1

Call the macro

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Labels Within Macros

- Since a macro may be invoked multiple times within the same program, it is essential that there are no conflicting labels result from the multiple invocation.
- The special designator `"\@"` is used to request unique labels from the assembler macro preprocessor.
- For each macro invocation, the `"\@"` designator is replaced by a number unique to that particular invocation.
- The `"\@"` is appended to the end of a label, and the preprocessor replaces it with a unique number.

Internal Macro Label Example

Macro SUM adds the sequence of integers in the range: $i, i+1, \dots, n$

Macro Definition:

SUM	MACRO		$\backslash 1 = \text{start}$ $\backslash 2 = \text{stop}$ $\backslash 3 = \text{sum}$
	CLR.W	$\backslash 3$	sum = 0
	ADDQ.W	#1, $\backslash 2$	stop = stop + 1
SUM1\@	ADD.W	$\backslash 1, \backslash 3$	For $i = \text{start}$ to stop
	ADD.W	#1, $\backslash 1$	sum = sum + i
	CMP.W	$\backslash 1, \backslash 2$	
	BNE	SUM1\@	
	ENDM		

Sample macro SUM invocation:

SUM	D1,D2,D3	$D1 = \text{start}$ $D2 = \text{stop}$ $D3 = \text{sum}$
-----	----------	--

Macro Example:

ToUpper, A String Conversion Macro

* ToUpper Address-Register
* This macro converts a string from lower case to upper case.
* The argument is an address register. The string MUST be
* terminated with \$0
*

```
ToUpper      macro
convert\@    cmpi.b    #0,(\1)      test for end of string
              beq      done\@
              cmpi.b    #'a',(\1)   if < 'a' not lower case
              blt      increment\@
              cmpi.b    #'z',(\1)   if <= 'z' is a lower case
              ble      process\@
increment\@   adda.w    #1,\1
              bra      convert\@
process\@     subi.b    #32,(\1)+   convert to upper case
              bra      convert\@
done\@        NOP
              endm                End of macro
```