

# Change-point detection in a Poisson process

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# Example

Bat cries (night of the 17 jul. 2019)



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Point process on  $t \in [0, 1]$ .

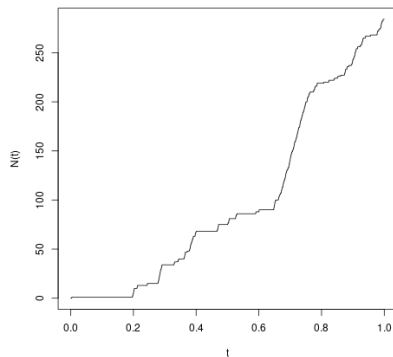
Event times:

$$0 < T_1 < \dots T_i < \dots T_n < 1$$

Counting process:

$$N(t) = \sum_{i=1}^n \mathbb{I}\{T_i \leq t\}$$

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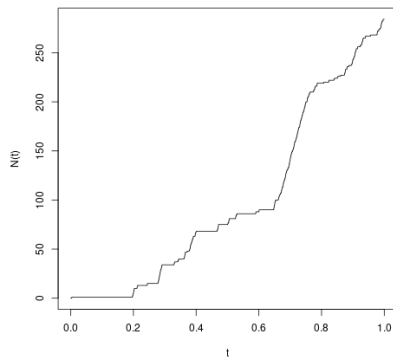
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Poisson Process.

$$\{N(t)\}_{0 \leq t \leq 1} \sim PP(\lambda(t))$$

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Intensity function  $\lambda(t)$ :

$$\lambda(t) = \lim_{\Delta t \rightarrow 0} \frac{\mathbb{P}\{N(t + \Delta t) - N(t) = 1\}}{\Delta t},$$

$$\mathbb{E}N(s) - \mathbb{E}N(t) = \int_t^s \lambda(u) \, du$$

# Change-point detection

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Piecewise constant intensity function.

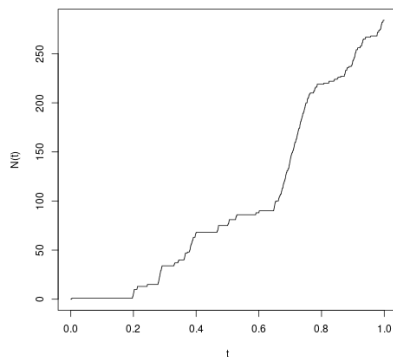
Change-points

$$(\tau_0 =) 0 < \tau_1 \cdots < \tau_{K-1} < 1 (= \tau_K)$$

For  $t \in I_k = ]\tau_{k-1}, \tau_k]$ :

$$\lambda(t) = \lambda_k$$

→ Continuous piece-wise linear cumulated intensity function



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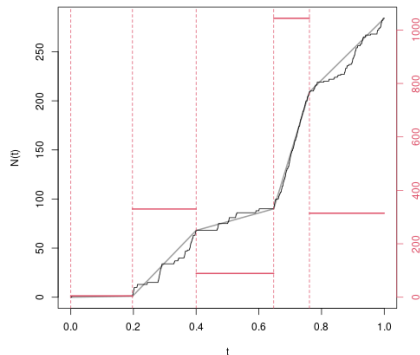
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- ▶ Segmentation: estimate  $(\tau, \lambda)$  reasonably fast
- ▶ Model selection: choose  $K$

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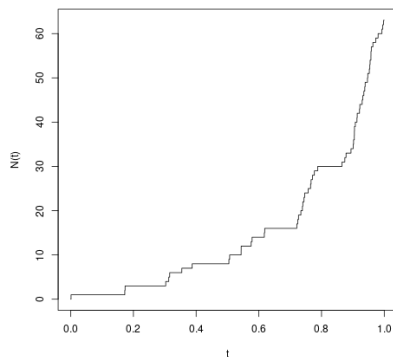
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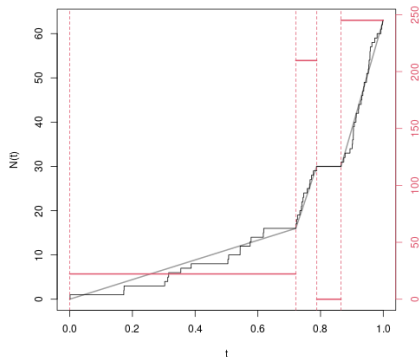
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## Estimation

## Model selection

## Extensions

# Maximum-likelihood segmentation

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**Optimization problem.**

$$(\hat{\tau}, \hat{\lambda}) = \arg \min_{\tau \in \mathcal{T}^K} \min_{\lambda} \gamma(\tau, \lambda)$$

where  $\mathcal{T}^K$  is a *continuous set* and  $\gamma(\tau, \lambda)$  is *not convex* nor even *continuous*.

# Shape of the contrast fonction

Optimization wrt  $\lambda$ :

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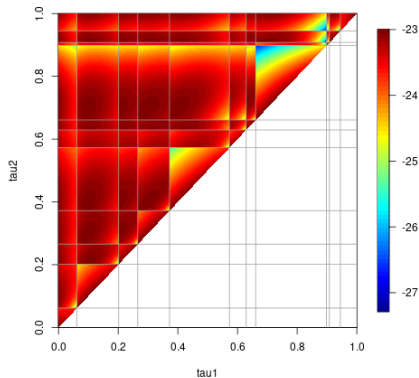
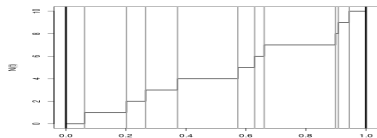
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**Example:**  $n = 10$ ,  $K = 3$ .

Each block corresponds to a specific vector

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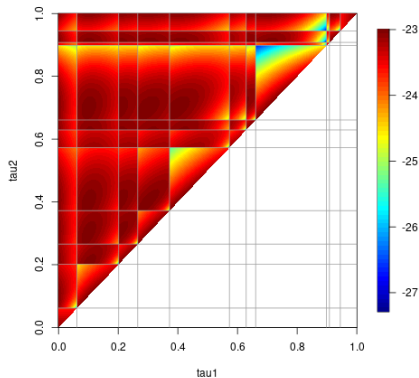
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Partitioning the number of events. Define  $\mathcal{N}^K = \left\{ \nu \in \mathbb{N}^K : \sum_{k=1}^K \nu_k = n \right\}$ .

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**Property.** If  $K \leq n$  and, for each  $\nu \in \mathcal{N}^K$ ,  $\hat{\gamma}(\tau)$  is **strictly concave wrt**  $\tau \in \mathcal{T}_\nu^K$ , then

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**Consequence.**  $\hat{\tau}$  can be obtained by dynamic programming over the  $2n + 2$  possible change-points

$$\mathcal{S} = \{ 0, T_1^-, T_1, T_2^-, T_2, \dots, T_n^-, T_n, 1 \}.$$

## Alternative constraint

### Remark.

- ▶  $\mathcal{S}$  includes segments with length 0 (e.g.:  $I = ]T_k^-, T_k]$ ,  $\Delta N_k = 1$ ),
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**Poisson-Gamma model.** For each segment  $1 \leq k \leq K$ :

$$\Lambda_k \sim \mathcal{Gam}(a, b), \quad \{N(t)\}_{t \in I_k} \mid \Lambda_k \sim PP(\Lambda_k),$$

which gives:

$$\begin{aligned} C(\Delta N_k, \Delta \tau_k) &= -\log p_{a,b}(\{N(t)\}_{t \in I_k}) \\ &= \text{cst} - \log \Gamma(a + \Delta N_k) + (a + \Delta N_k) \log(b + \Delta \tau_k) \end{aligned}$$

→ Enjoys the concavity property, but avoids segments with null length.



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- ▶  $\lambda^L(t)$  piece-wise constant with change points  $(\tau_k)$  and intensities  $(\nu\lambda_k)$ ,
- ▶  $\lambda^T(t)$  piece-wise constant with change points  $(\tau_k)$  and intensities  $((1-\nu)\lambda_k)$ ,
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► Repeat for  $1 \leq m \leq M$  :

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3 – Compute the contrast  $\gamma_K^{T,m} = \gamma\left(\{N^T(t)\}; \hat{\tau}^{L,m}, \frac{1-v}{v} \hat{\lambda}^{L,m}\right)$ .

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► Select

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## Illustration

**Poisson-Gamma contrast.** Set  $a^L = a^T = 1$ ,  $b^L = 1/n_L$ ,  $b^T = 1/n_T$ , and compute

$$\begin{aligned}
 -\log p(\{N^T(t)\} \mid \hat{\tau}^L) &= \sum_{k=1}^K (a + \Delta N_k^T) \log(a + \Delta \tau_k) - \log \Gamma(a + \Delta N_k^L) \\
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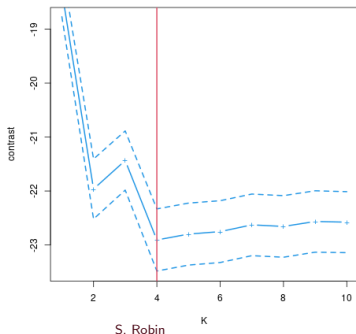
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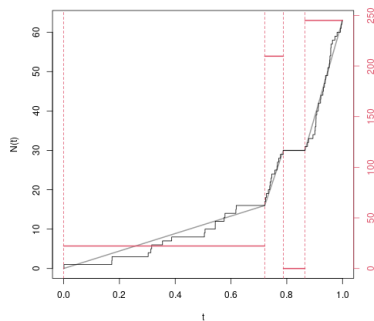
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## Kilauea eruptions

Model selection via CV



Resulting segmentation



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## Marked Poisson Process.

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- ▶ Each segment belongs to a class  $1 \leq q \leq Q$  (with probability  $\pi_q$  and intensity  $\lambda_k = \ell_q$ ),
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### And also.

- ▶ Theoretically grounded model selection criterion,
- ▶ Other desirable contrasts, ...

# References I

-  C-H Ho and M Bhaduri. A quantitative insight into the dependence dynamics of the Kilauea and Mauna Loa volcanoes, Hawaii. *Mathematical Geosciences*, 49(7):893–911, 2017.
-  F Picard, S. Robin, E Lebarbier, and J-J Daudin. A segmentation/clustering model for the analysis of array CGH data. *Biometrics*, 63(3):758–766, 2007.



# Appendix

$$|\mathcal{N}_K| = \sum_{h=\lfloor (K-1)/2 \rfloor}^K \binom{n-1}{h-1} \binom{h+1}{K-h}$$