aircraft

Tight Rope v0.6

19th November 2015

1 ID Files

1.1 MissionIds

section *MissionIds* **parents** *scj_prelude*, *MissionId*

$$MainMissionID : MissionID$$
$$TakeOffMissionID : MissionID$$
$$CruiseMissionID : MissionID$$
$$LandMissionID : MissionID$$

$$distinct\langle nullMissionId, MainMissionID, TakeOffMissionID, CruiseMissionID, LandMissionID\rangle$$

1.2 SchedulablesIds

section *SchedulableIds* **parents** *scj_prelude*, *SchedulableId*

$$
\begin{array}{l}
MainMissionSequencerID : SchedulableID \\
ACModeChangerID : SchedulableID \\
EnvironmentMonitorID : SchedulableID \\
ControlHandlerID : SchedulableID \\
FlightSensorsMonitorID : SchedulableID \\
CommunicationsHandlerID : SchedulableID \\
AperiodicSimulatorID : SchedulableID \\
LandingGearHandlerTakeOffID : SchedulableID \\
TakeOffMonitorID : SchedulableID \\
TakeOffFailureHandlerID : SchedulableID \\
BeginLandingHandlerID : SchedulableID \\
NavigationMonitorID : SchedulableID \\
GroundDistanceMonitorID : SchedulableID \\
LandingGearHandlerLandID : SchedulableID \\
InstrumentLandingSystemMonitorID : SchedulableID \\
SafeLandingHandlerID : SchedulableID
\end{array}
$$

$$
\begin{array}{l}
distinct\langle nullSequencerId, nullSchedulableId, MainMissionSequencerID, \\
ACModeChangerID, EnvironmentMonitorID, \\
ControlHandlerID, FlightSensorsMonitorID, \\
CommunicationsHandlerID, AperiodicSimulatorID, \\
LandingGearHandlerTakeOffID, TakeOffMonitorID, \\
TakeOffFailureHandlerID, BeginLandingHandlerID, \\
NavigationMonitorID, GroundDistanceMonitorID, \\
LandingGearHandlerLandID, InstrumentLandingSystemMonitorID, \\
SafeLandingHandlerID\rangle
\end{array}
$$

1.3 ThreadIds

section *ThreadIds* **parents** *scj_prelude*, *GlobalTypes*

$$
\begin{array}{l}
ACModeChangerThreadID : ThreadID \\
EnvironmentMonitorThreadID : ThreadID \\
ControlHandlerThreadID : ThreadID \\
FlightSensorsMonitorThreadID : ThreadID \\
CommunicationsHandlerThreadID : ThreadID \\
AperiodicSimulatorThreadID : ThreadID \\
LandingGearHandlerTakeOffThreadID : ThreadID \\
TakeOffMonitorThreadID : ThreadID \\
TakeOffFailureHandlerThreadID : ThreadID \\
BeginLandingHandlerThreadID : ThreadID \\
NavigationMonitorThreadID : ThreadID \\
GroundDistanceMonitorThreadID : ThreadID \\
LandingGearHandlerLandThreadID : ThreadID \\
InstrumentLandingSystemMonitorThreadID : ThreadID \\
SafeLandingHandlerThreadID : ThreadID
\end{array}
$$

$$
\begin{array}{l}
distinct\langle SafeletThreadId, nullThreadId, \\
ACModeChangerThreadID, EnvironmentMonitorThreadID, \\
ControlHandlerThreadID, FlightSensorsMonitorThreadID, \\
CommunicationsHandlerThreadID, AperiodicSimulatorThreadID, \\
LandingGearHandlerTakeOffThreadID, TakeOffMonitorThreadID, \\
TakeOffFailureHandlerThreadID, BeginLandingHandlerThreadID, \\
NavigationMonitorThreadID, GroundDistanceMonitorThreadID, \\
LandingGearHandlerLandThreadID, InstrumentLandingSystemMonitorThreadID, \\
SafeLandingHandlerThreadID\rangle
\end{array}
$$

1.4 ObjectIds

section *ObjectIds* **parents** *scj_prelude*, *GlobalTypes*

$$
\begin{array}{l}
ACSafeletObjectID : ObjectID \\
MainMissionObjectID : ObjectID \\
ACModeChangerObjectID : ObjectID \\
EnvironmentMonitorObjectID : ObjectID \\
ControlHandlerObjectID : ObjectID \\
FlightSensorsMonitorObjectID : ObjectID \\
CommunicationsHandlerObjectID : ObjectID \\
AperiodicSimulatorObjectID : ObjectID \\
TakeOffMissionObjectID : ObjectID \\
LandingGearHandlerTakeOffObjectID : ObjectID \\
TakeOffMonitorObjectID : ObjectID \\
TakeOffFailureHandlerObjectID : ObjectID \\
CruiseMissionObjectID : ObjectID \\
BeginLandingHandlerObjectID : ObjectID \\
NavigationMonitorObjectID : ObjectID \\
LandMissionObjectID : ObjectID \\
GroundDistanceMonitorObjectID : ObjectID \\
LandingGearHandlerLandObjectID : ObjectID \\
InstrumentLandingSystemMonitorObjectID : ObjectID \\
SafeLandingHandlerObjectID : ObjectID
\end{array}
$$

$$
\begin{array}{l}
distinct\langle ACSafeletObjectID, MainMissionObjectID, \\
ACModeChangerObjectID, EnvironmentMonitorObjectID, \\
ControlHandlerObjectID, FlightSensorsMonitorObjectID, \\
CommunicationsHandlerObjectID, AperiodicSimulatorObjectID, \\
TakeOffMissionObjectID, LandingGearHandlerTakeOffObjectID, \\
TakeOffMonitorObjectID, TakeOffFailureHandlerObjectID, \\
CruiseMissionObjectID, BeginLandingHandlerObjectID, \\
NavigationMonitorObjectID, LandMissionObjectID, \\
GroundDistanceMonitorObjectID, LandingGearHandlerLandObjectID, \\
InstrumentLandingSystemMonitorObjectID, SafeLandingHandlerObjectID\rangle
\end{array}
$$

2 Network

section *NetworkChannels* **parents** *scj_prelude*, *MissionId*, *MissionIds*,
SchedulableId, *SchedulableIds*, *MissionChan*, *SchedulableChan*, *TopLevelMissionSequencerFWChan*,
FrameworkChan, *SafeletChan*

channelset *TerminateSync* ==
{| *schedulables_terminated*, *schedulables_stopped*, *get_activeSchedulables* |}

channelset *ControlTierSync* ==
{| *start_toplevel_sequencer*, *done_toplevel_sequencer*, *done_safeletFW* |}

channelset *TierSync* ==
{| *start_mission* . , *done_mission* . ,
done_safeletFW, *done_toplevel_sequencer* |}

channelset *MissionSync* ==
{| *done_safeletFW*, *done_toplevel_sequencer*, *register*,
signalTerminationCall, *signalTerminationRet*, *activate_schedulables*, *done_schedulable*,
cleanupSchedulableCall, *cleanupSchedulableRet* |}

channelset *SchedulablesSync* ==
{| *activate_schedulables*, *done_safeletFW*, *done_toplevel_sequencer* |}

channelset *ClusterSync* ==
{| *done_toplevel_sequencer*, *done_safeletFW* |}

channelset *AppSync* ==
$\bigcup$ {*SafeltAppSync*, *MissionSequencerAppSync*, *MissionAppSync*,
MTAppSync, *OSEHSync*, *APEHSync*,
{| *getSequencer*, *end_mission_app*, *end_managedThread_app*,
setCeilingPriority, *requestTerminationCall*, *requestTerminationRet*, *terminationPendingCall*,
terminationPendingRet, *handleAsyncEventCall*, *handleAsyncEventRet* |}}

channelset *ObjectSync* ==
{| |}

channelset *ThreadSync* ==
{| |}

channelset *LockingSync* ==
{| *lockAcquired*, *startSyncMeth*, *endSyncMeth*, *waitCall*, *waitRet*, *notify* |}

channelset *Tier*0*Sync* ==
{| *done_toplevel_sequencer*, *done_safeletFW*,
start_mission . , *done_mission* . ,
initializeRet . , *requestTermination* . . ,
start_mission . , *done_mission* . ,
initializeRet . , *requestTermination* . . ,
start_mission . , *done_mission* . ,
initializeRet . , *requestTermination* . . |}

section *Program* **parents** *scj_prelude*, *MissionId*, *MissionIds*,
SchedulableId, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *MissionFW*,
SafeletFW, *TopLevelMissionSequencerFW*, *NetworkChannels*, *ManagedThreadFW*,
SchedulableMissionSequencerFW, *PeriodicEventHandlerFW*, *OneShotEventHandlerFW*,
AperiodicEventHandlerFW, *ACSafeletApp*, *MainMissionSequencerApp*,
ObjectFW, *ThreadFW*, *MainMissionApp*, *ACModeChangerApp*, *ControlHandlerApp*, *CommunicationsHandlerAp*

process $ControlTier \mathrel{\widehat=}$
$$\left(\begin{array}{l} SafeletFW \\ \quad [\![ControlTierSync]\!] \\ TopLevelMissionSequencerFW(MainMissionSequencer) \end{array}\right)$$

process $Tier0 \mathrel{\widehat=}$
$$\left(\begin{array}{l} MissionFW(MainMission) \\ \quad [\![MissionSync]\!] \\ \left(\begin{array}{l} SchedulableMissionSequencerFW(ACModeChanger) \\ \quad [\![SchedulablesSync]\!] \\ \left(\begin{array}{l} AperiodicEventHandlerFW(ControlHandler) \\ \quad [\![SchedulablesSync]\!] \\ AperiodicEventHandlerFW(CommunicationsHandler) \end{array}\right) \\ \quad [\![SchedulablesSync]\!] \\ \left(\begin{array}{l} PeriodicEventHandlerFW(EnvironmentMonitor) \\ \quad [\![SchedulablesSync]\!] \\ PeriodicEventHandlerFW(FlightSensorsMonitor) \\ \quad [\![SchedulablesSync]\!] \\ PeriodicEventHandlerFW(AperiodicSimulator) \end{array}\right) \end{array}\right) \end{array}\right)$$

process $Tier1 \mathrel{\widehat=}$
$$\left(\begin{array}{l} MissionFW(TakeOffMission) \\ \quad [\![MissionSync]\!] \\ \left(\left(\begin{array}{l} AperiodicEventHandlerFW(LandingGearHandlerTakeOff) \\ \quad [\![SchedulablesSync]\!] \\ AperiodicEventHandlerFW(TakeOffFailureHandler) \\ \quad [\![SchedulablesSync]\!] \\ PeriodicEventHandlerFW(TakeOffMonitor) \end{array}\right)\right) \\ \quad [\![ClusterSync]\!] \\ \left(\begin{array}{l} MissionFW(CruiseMission) \\ \quad [\![MissionSync]\!] \\ \left(\begin{array}{l} AperiodicEventHandlerFW(BeginLandingHandler) \\ \quad [\![SchedulablesSync]\!] \\ PeriodicEventHandlerFW(NavigationMonitor) \end{array}\right) \end{array}\right) \\ \quad [\![ClusterSync]\!] \\ \left(\begin{array}{l} MissionFW(LandMission) \\ \quad [\![MissionSync]\!] \\ \left(\begin{array}{l} \left(\begin{array}{l} AperiodicEventHandlerFW(LandingGearHandlerLand) \\ \quad [\![SchedulablesSync]\!] \\ AperiodicEventHandlerFW(SafeLandingHandler) \end{array}\right) \\ \quad [\![SchedulablesSync]\!] \\ \left(\begin{array}{l} PeriodicEventHandlerFW(GroundDistanceMonitor) \\ \quad [\![SchedulablesSync]\!] \\ PeriodicEventHandlerFW(InstrumentLandingSystemMonitor) \end{array}\right) \end{array}\right) \end{array}\right) \end{array}\right)$$

process $Framework \mathrel{\widehat=}$
$$\left(\begin{array}{l} ControlTier \\ \quad [\![TierSync]\!] \\ \left(\begin{array}{l} Tier0 \\ \quad [\![Tier0Sync]\!] \\ Tier1 \end{array}\right) \end{array}\right)$$

process $Application \mathrel{\widehat{=}}$

$$
\begin{pmatrix}
ACSafeletApp \\
|||\\
MainMissionSequencerApp \\
|||\\
MainMissionApp \\
|||\\
ACModeChangerApp(5, MainMissionID) \\
|||\\
ControlHandlerApp(5,,) \\
|||\\
CommunicationsHandlerApp(5,,) \\
|||\\
EnvironmentMonitorApp(5,,, MainMissionID) \\
|||\\
FlightSensorsMonitorApp(5,,, MainMissionID) \\
|||\\
AperiodicSimulatorApp(5,, controlHandler, 5,, commsHandler, 5,, beginLandingHandler) \\
|||\\
TakeOffMissionApp \\
|||\\
LandingGearHandlerTakeOffApp(5,,, TakeOffMissionID) \\
|||\\
TakeOffFailureHandlerApp(5,,, TakeOffMissionID,) \\
|||\\
TakeOffMonitorApp(PriorityScheduler.instance().getMaxPriority(),, TakeOffMissionID,, landingGearHandler) \\
|||\\
CruiseMissionApp \\
|||\\
BeginLandingHandlerApp(5,,, CruiseMissionID) \\
|||\\
NavigationMonitorApp(PriorityScheduler.instance().getMaxPriority(),,, CruiseMissionID) \\
|||\\
LandMissionApp \\
|||\\
LandingGearHandlerLandApp(5,,, LandMissionID) \\
|||\\
SafeLandingHandlerApp(5,,, LandMissionID,) \\
|||\\
GroundDistanceMonitorApp(5,, LandMissionID) \\
|||\\
InstrumentLandingSystemMonitorApp(5,,, LandMissionID)
\end{pmatrix}
$$

$$
\begin{array}{l}
Locking \mathrel{\widehat{=}} \\
\Big(\Big(ThreadFW(ACModeChangerThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(EnvironmentMonitorThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(ControlHandlerThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(FlightSensorsMonitorThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(CommunicationsHandlerThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(AperiodicSimulatorThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(LandingGearHandlerTakeOffThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(TakeOffMonitorThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(TakeOffFailureHandlerThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(BeginLandingHandlerThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(NavigationMonitorThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(GroundDistanceMonitorThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(LandingGearHandlerLandThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(InstrumentLandingSystemMonitorThreadID, MinPriority) \\
\quad [\![ThreadSync]\!] \\
\quad ThreadFW(SafeLandingHandlerThreadID, MinPriority) \\
\Big)\Big) \\
|||
\end{array}
$$

$$
\begin{array}{l}
\Big(ObjectFW(ACSafeletObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(MainMissionObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(ACModeChangerObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(EnvironmentMonitorObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(ControlHandlerObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(FlightSensorsMonitorObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(CommunicationsHandlerObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(AperiodicSimulatorObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(TakeOffMissionObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(LandingGearHandlerTakeOffObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(TakeOffMonitorObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(TakeOffFailureHandlerObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(CruiseMissionObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(BeginLandingHandlerObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(NavigationMonitorObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(LandMissionObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(GroundDistanceMonitorObjectID) \\
\quad [\![ObjectSync]\!] \\
\quad ObjectFW(LandingGearHandlerLandObjectID) \\
\Big)
\end{array}
$$

process $Program \mathrel{\widehat{=}} Framework \llbracket AppSync \rrbracket Application \llbracket LockingSync \rrbracket Locking$

3 Safelet

section $ACSafeletApp$ **parents** $scj\_prelude, SchedulableId, SchedulableIds, SafeletChan$

process $ACSafeletApp \mathrel{\widehat=}$ **begin**

$$InitializeApplication \mathrel{\widehat=} \begin{pmatrix} initializeApplicationCall \longrightarrow \\ initializeApplicationRet \longrightarrow \\ \mathbf{Skip} \end{pmatrix}$$

$$GetSequencer \mathrel{\widehat=} \begin{pmatrix} getSequencerCall \longrightarrow \\ getSequencerRet\,!\,MainMissionSequencer \longrightarrow \\ \mathbf{Skip} \end{pmatrix}$$

$$Methods \mathrel{\widehat=} \begin{pmatrix} GetSequencer \\ \Box \\ InitializeApplication \end{pmatrix} ;\ Methods$$

$\bullet\ (Methods) \triangle (end\_safelet\_app \longrightarrow \mathbf{Skip})$

end

4 Top Level Mission Sequencer

section *MainMissionSequencerApp* **parents** *TopLevelMissionSequencerChan*, *MissionId*, *MissionIds*, *SchedulableId*, *MainMissionSequencerClass*

process $MainMissionSequencerApp \mathrel{\widehat=} \textbf{begin}$

State

$this : \textbf{ref}\ MainMissionSequencerClass$

state *State*

Init

$State'$

$this' = \textbf{new}\ MainMissionSequencerClass()$

$GetNextMission \mathrel{\widehat=} \textbf{var}\ ret : MissionID \bullet$
$\left(\begin{array}{l} getNextMissionCall\,.\,MainMissionSequencer \longrightarrow \\ ret := this\,.\,getNextMission(); \\ getNextMissionRet\,.\,MainMissionSequencer\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$

$Methods \mathrel{\widehat=}$
$\big(GetNextMission\big)\ ;\ \ Methods$

$\bullet\ (Init\ ;\ \ Methods) \triangle (end\_sequencer\_app\,.\,MainMissionSequencer \longrightarrow \textbf{Skip})$

end

class *MainMissionSequencerClass* $\widehat{=}$ **begin**

state *State*

$$returnedMission : \mathbb{B}$$

state *State*

initial *Init*

$$State'$$

protected *getNextMission* $\widehat{=}$ **var** *ret* : *MissionID* $\bullet$

$$\left(\begin{array}{l} \textbf{if } (\neg\ returnedMission = \textbf{True}) \longrightarrow \\ \quad \left(\begin{array}{l} this\,.\,returnedMission := true; \\ ret := MainMission \end{array}\right) \\ [] \neg\ (\neg\ returnedMission = \textbf{True}) \longrightarrow \\ \quad \left(ret := nullMissionId\right) \\ \textbf{fi} \end{array}\right)$$

$\bullet$ **Skip**

end

section *MainMissionSequencerMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

channel $getNextMissionCall : SchedulableID$
channel $getNextMissionRet : SchedulableID \times MissionID$

5 Missions

5.1 MainMission

section *MainMissionApp* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *MainMissionClass*, *MainMissionMethChan*

process $MainMissionApp \mathrel{\widehat=}$ **begin**

State

$this : \mathbf{ref}\ MainMissionClass$

state *State*

Init

$State'$

$this' = \mathbf{new}\ MainMissionClass()$

$$InitializePhase \mathrel{\widehat=} \left(\begin{array}{l} initializeCall\,.\,MainMission \longrightarrow \\ register\,!\,ACModeChanger\,!\,MainMission \longrightarrow \\ register\,!\,EnvironmentMonitor\,!\,MainMission \longrightarrow \\ register\,!\,ControlHandler\,!\,MainMission \longrightarrow \\ register\,!\,FlightSensorsMonitor\,!\,MainMission \longrightarrow \\ register\,!\,CommunicationsHandler\,!\,MainMission \longrightarrow \\ register\,!\,AperiodicSimulator\,!\,MainMission \longrightarrow \\ initializeRet\,.\,MainMission \longrightarrow \\ \mathbf{Skip} \end{array}\right)$$

$$CleanupPhase \mathrel{\widehat=} \left(\begin{array}{l} cleanupMissionCall\,.\,MainMission \longrightarrow \\ cleanupMissionRet\,.\,MainMission\,!\,\mathbf{True} \longrightarrow \\ \mathbf{Skip} \end{array}\right)$$

$$getAirSpeedMeth \mathrel{\widehat=} \mathbf{var}\ ret : double \bullet \left(\begin{array}{l} getAirSpeedCall\,.\,MainMission \longrightarrow \\ ret := this\,.\,getAirSpeed(); \\ getAirSpeedRet\,.\,MainMission\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$$

$$getAltitudeMeth \mathrel{\widehat=} \mathbf{var}\ ret : double \bullet \left(\begin{array}{l} getAltitudeCall\,.\,MainMission \longrightarrow \\ ret := this\,.\,getAltitude(); \\ getAltitudeRet\,.\,MainMission\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$$

$$getCabinPressureMeth \mathrel{\widehat=} \mathbf{var}\ ret : double \bullet \left(\begin{array}{l} getCabinPressureCall\,.\,MainMission \longrightarrow \\ ret := this\,.\,getCabinPressure(); \\ getCabinPressureRet\,.\,MainMission\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$$

$$getEmergencyOxygenMeth \mathrel{\widehat=} \textbf{var}\ ret : double \bullet \left(\begin{array}{l} getEmergencyOxygenCall\,.\,MainMission \longrightarrow \\ ret := this\,.\,getEmergencyOxygen(); \\ getEmergencyOxygenRet\,.\,MainMission\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$getFuelRemainingMeth \mathrel{\widehat=} \textbf{var}\ ret : double \bullet \left(\begin{array}{l} getFuelRemainingCall\,.\,MainMission \longrightarrow \\ ret := this\,.\,getFuelRemaining(); \\ getFuelRemainingRet\,.\,MainMission\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$getHeadingMeth \mathrel{\widehat=} \textbf{var}\ ret : double \bullet \left(\begin{array}{l} getHeadingCall\,.\,MainMission \longrightarrow \\ ret := this\,.\,getHeading(); \\ getHeadingRet\,.\,MainMission\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setAirSpeedMeth \mathrel{\widehat=} \left(\begin{array}{l} setAirSpeedCall\,.\,MainMission\,?\,airSpeed \longrightarrow \\ this\,.\,setAirSpeed(airSpeed); \\ setAirSpeedRet\,.\,MainMission \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setAltitudeMeth \mathrel{\widehat=} \left(\begin{array}{l} setAltitudeCall\,.\,MainMission\,?\,altitude \longrightarrow \\ this\,.\,setAltitude(altitude); \\ setAltitudeRet\,.\,MainMission \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setCabinPressureMeth \mathrel{\widehat=} \left(\begin{array}{l} setCabinPressureCall\,.\,MainMission\,?\,cabinPressure \longrightarrow \\ this\,.\,setCabinPressure(cabinPressure); \\ setCabinPressureRet\,.\,MainMission \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setEmergencyOxygenMeth \mathrel{\widehat=} \left(\begin{array}{l} setEmergencyOxygenCall\,.\,MainMission\,?\,emergencyOxygen \longrightarrow \\ this\,.\,setEmergencyOxygen(emergencyOxygen); \\ setEmergencyOxygenRet\,.\,MainMission \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setFuelRemainingMeth \mathrel{\widehat=} \left(\begin{array}{l} setFuelRemainingCall\,.\,MainMission\,?\,fuelRemaining \longrightarrow \\ this\,.\,setFuelRemaining(fuelRemaining); \\ setFuelRemainingRet\,.\,MainMission \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$setHeadingMeth \mathrel{\widehat=} \left(\begin{array}{l} setHeadingCall\,.\,MainMission\,?\,heading \longrightarrow \\ this\,.\,setHeading(heading); \\ setHeadingRet\,.\,MainMission \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$Methods \mathrel{\widehat{=}} \left(\begin{array}{l} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ getAirSpeedMeth \\ \Box \\ getAltitudeMeth \\ \Box \\ getCabinPressureMeth \\ \Box \\ getEmergencyOxygenMeth \\ \Box \\ getFuelRemainingMeth \\ \Box \\ getHeadingMeth \\ \Box \\ setAirSpeedMeth \\ \Box \\ setAltitudeMeth \\ \Box \\ setCabinPressureMeth \\ \Box \\ setEmergencyOxygenMeth \\ \Box \\ setFuelRemainingMeth \\ \Box \\ setHeadingMeth \end{array} \right) ; \; Methods$$

• $(Init \; ; \; Methods) \triangle (end\_mission\_app \,.\, MainMission \longrightarrow \mathbf{Skip})$

end

class *MainMissionClass* $\widehat{=}$ **begin**

state *State*

$ALTITUDE\_READING\_ON\_GROUND : double$
$cabinPressure : double$
$emergencyOxygen : double$
$fuelRemaining : double$
$altitude : double$
$airSpeed : double$
$heading : double$

state *State*

initial *Init*

$State'$

$ALTITUDE\_READING\_ON\_GROUND' = 0.0$

public $getAirSpeed \mathrel{\widehat{=}} \textbf{var}\ ret : double \bullet$
$(ret := airSpeed)$

public $getAltitude \mathrel{\widehat{=}} \textbf{var}\ ret : double \bullet$
$(ret := altitude)$

public $getCabinPressure \mathrel{\widehat{=}} \textbf{var}\ ret : double \bullet$
$(ret := cabinPressure)$

public $getEmergencyOxygen \mathrel{\widehat{=}} \textbf{var}\ ret : double \bullet$
$(ret := emergencyOxygen)$

public $getFuelRemaining \mathrel{\widehat{=}} \textbf{var}\ ret : double \bullet$
$(ret := fuelRemaining)$

public $getHeading \mathrel{\widehat{=}} \textbf{var}\ ret : double \bullet$
$(ret := heading)$

public $setAirSpeed \mathrel{\widehat{=}}$
$(this\,.\,this.airSpeed := airSpeed)$

public $setAltitude \mathrel{\widehat{=}}$
$(this\,.\,this.altitude := altitude)$

public $setCabinPressure \mathrel{\widehat{=}}$
$(this\,.\,this.cabinPressure := cabinPressure)$

public $setEmergencyOxygen \mathrel{\widehat{=}}$
$(this\,.\,this.emergencyOxygen := emergencyOxygen)$

public $setFuelRemaining \mathrel{\widehat{=}}$
$\big(this\,.\,this.fuelRemaining := fuelRemaining\big)$

public $setHeading \mathrel{\widehat{=}}$
$\big(this\,.\,this.heading := heading\big)$

- **Skip**

end

section *MainMissionMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

channel *getAirSpeedCall* : *MissionID*
channel *getAirSpeedRet* : *MissionID* × *double*

channel *getAltitudeCall* : *MissionID*
channel *getAltitudeRet* : *MissionID* × *double*

channel *getCabinPressureCall* : *MissionID*
channel *getCabinPressureRet* : *MissionID* × *double*

channel *getEmergencyOxygenCall* : *MissionID*
channel *getEmergencyOxygenRet* : *MissionID* × *double*

channel *getFuelRemainingCall* : *MissionID*
channel *getFuelRemainingRet* : *MissionID* × *double*

channel *getHeadingCall* : *MissionID*
channel *getHeadingRet* : *MissionID* × *double*

channel *setAirSpeedCall* : *MissionID* × *double*
channel *setAirSpeedRet* : *MissionID*

channel *setAltitudeCall* : *MissionID* × *double*
channel *setAltitudeRet* : *MissionID*

channel *setCabinPressureCall* : *MissionID* × *double*
channel *setCabinPressureRet* : *MissionID*

channel *setEmergencyOxygenCall* : *MissionID* × *double*
channel *setEmergencyOxygenRet* : *MissionID*

channel *setFuelRemainingCall* : *MissionID* × *double*
channel *setFuelRemainingRet* : *MissionID*

channel *setHeadingCall* : *MissionID* × *double*
channel *setHeadingRet* : *MissionID*

5.2 Schedulables of MainMission

section *ACModeChangerApp* **parents** *TopLevelMissionSequencerChan*, *MissionId*, *MissionIds*, *SchedulableId*, *ACModeChangerClass*

process $ACModeChangerApp \mathrel{\widehat=}$
PriorityParameters :,
: *ProbablyMission* • **begin**

$GetNextMission \mathrel{\widehat=} \textbf{var}\ ret : MissionID \bullet$
$\left(\begin{array}{l} getNextMissionCall\,.\,ACModeChanger \longrightarrow \\ ret := this\,.\,getNextMission(); \\ getNextMissionRet\,.\,ACModeChanger\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$

$changeToMeth \mathrel{\widehat=}$
$\left(\begin{array}{l} changeToCall\,.\,ACModeChanger\,?\,newMode \longrightarrow \\ \big(this\,.\,currentMode := newMode\big)\,; \\ changeToRet\,.\,ACModeChanger \longrightarrow \\ \textbf{Skip} \end{array}\right)$

$advanceModeSyncMeth \mathrel{\widehat=}$
$\left(\begin{array}{l} advanceModeCall\,.\,ACModeChanger\,?\,thread \longrightarrow \\ \left(\begin{array}{l} startSyncMeth\,.\,ACModeChangerObject\,.\,thread \longrightarrow \\ lockAcquired\,.\,ACModeChangerObject\,.\,thread \longrightarrow \\ \left(\begin{array}{l} \textbf{Skip}; \\ \textbf{if}\ (modesLeft = 3) \longrightarrow \\ \quad \left(\begin{array}{l} modesLeft := modesLeft - 1; \\ changeTo(launchMode) \end{array}\right) \\ [\!]\ \neg\,(modesLeft = 3) \longrightarrow \\ \quad \textbf{if}\ (modesLeft = 2) \longrightarrow \\ \quad \left(\begin{array}{l} modesLeft := modesLeft - 1; \\ changeTo(cruiseMode) \end{array}\right) \\ [\!]\ \neg\,(modesLeft = 2) \longrightarrow \\ \quad \textbf{if}\ (modesLeft = 1) \longrightarrow \\ \quad \left(\begin{array}{l} modesLeft := modesLeft - 1; \\ changeTo(landMode) \end{array}\right) \\ [\!]\ \neg\,(modesLeft = 1) \longrightarrow \\ \quad \big(changeTo(\textbf{null})\big) \\ \textbf{fi} \\ \textbf{fi} \\ \textbf{fi} \end{array}\right) \\ endSyncMeth\,.\,ACModeChangerObject\,.\,thread \longrightarrow \\ advanceModeRet\,.\,ACModeChanger\,.\,thread \longrightarrow \\ \textbf{Skip} \end{array}\right) \end{array}\right)$

$Methods \mathrel{\widehat=}$
$\left(\begin{array}{l} GetNextMission \\ \Box \\ changeToMeth \\ \Box \\ advanceModeSyncMeth \end{array}\right)\ ;\ Methods$

• $(Methods) \triangle (end\_sequencer\_app\,.\,ACModeChanger \longrightarrow \mathbf{Skip})$

end

class $ACModeChangerClass \mathrel{\widehat=}$ **begin**

state *State*

$modesLeft : \mathbb{Z}$
ref $currentModeClass : ModeClass$
ref $launchModeClass : ModeClass$
ref $cruiseModeClass : ModeClass$
ref $landModeClass : ModeClass$

state *State*

initial *Init*

$State'$

$modesLeft' = 3$
ref $currentModeClass' = \mathbf{new}\ ModeClass()$
ref $launchModeClass' = \mathbf{new}\ ModeClass()$
ref $cruiseModeClass' = \mathbf{new}\ ModeClass()$
ref $landModeClass' = \mathbf{new}\ ModeClass()$

protected $getNextMission \mathrel{\widehat=} \mathbf{var}\ ret : MissionID \bullet$

$$
\begin{pmatrix}
\mathbf{if}\ (modesLeft = 3) \longrightarrow \\
\quad \begin{pmatrix} modesLeft := modesLeft - 1; \\ ret := TakeOffMission \end{pmatrix} \\
[]\ \neg\ (modesLeft = 3) \longrightarrow \\
\quad \mathbf{if}\ (modesLeft = 2) \longrightarrow \\
\quad \begin{pmatrix} modesLeft := modesLeft - 1; \\ ret := CruiseMission \end{pmatrix} \\
[]\ \neg\ (modesLeft = 2) \longrightarrow \\
\quad \mathbf{if}\ (modesLeft = 1) \longrightarrow \\
\quad \begin{pmatrix} modesLeft := modesLeft - 1; \\ ret := LandMission \end{pmatrix} \\
[]\ \neg\ (modesLeft = 1) \longrightarrow \\
\quad \big(ret := nullMissionId\big) \\
\mathbf{fi} \\
\mathbf{fi} \\
\mathbf{fi}
\end{pmatrix}
$$

• **Skip**

end

section $ACModeChangerMethChan$ **parents** $scj\_prelude, GlobalTypes, MissionId, SchedulableId$

channel $changeToCall : SchedulableID \times$
channel $changeToRet : SchedulableID$

channel $advanceModeCall : SchedulableID \times ThreadID$
channel $advanceModeRet : SchedulableID \times ThreadID$

section *ControlHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*

process *ControlHandlerApp* $\widehat{=}$
PriorityParameters :,
AperiodicParameters :,
MainMission :• **begin**

$$
\begin{pmatrix}
handleAsyncEventCall\,.\,ControlHandler \longrightarrow \\
(\mathbf{Skip})\,; \\
handleAsyncEventRet\,.\,ControlHandler \longrightarrow \\
\mathbf{Skip}
\end{pmatrix}
$$

$$
\begin{pmatrix}
handlerAsyncEvent
\end{pmatrix}\,;\; Methods
$$

$$
\bullet\ (Methods) \triangle (end\_\_app\,.\,ControlHandler \longrightarrow \mathbf{Skip})
$$

end

class *ControlHandlerClass* $\widehat{=}$ **begin**

- **Skip**

end

section *ControlHandlerMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

section *CommunicationsHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*

process *CommunicationsHandlerApp* $\widehat{=}$
PriorityParameters :,
AperiodicParameters :,
MainMission :• **begin**

$$
\begin{pmatrix}
handleAsyncEventCall\,.\,CommunicationsHandler \longrightarrow \\
(\mathbf{Skip})\,; \\
handleAsyncEventRet\,.\,CommunicationsHandler \longrightarrow \\
\mathbf{Skip}
\end{pmatrix}
$$

$$
\begin{pmatrix}
handlerAsyncEvent
\end{pmatrix}\,;\ Methods
$$

$$
\bullet\ (Methods) \triangle (end\_\_app\,.\,CommunicationsHandler \longrightarrow \mathbf{Skip})
$$

end

class *CommunicationsHandlerClass* $\widehat{=}$ **begin**

- **Skip**

end

section *CommunicationsHandlerMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

section *EnvironmentMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *MainMissionMethChan*

process $EnvironmentMonitorApp \mathrel{\widehat=}$
$PriorityParameters$:,
$PeriodicParameters$:,
$MainMission$:,
: $ProbablyMission$ • **begin**

$handlerAsyncEvent \mathrel{\widehat=}$
$\Big($ $handleAsyncEventCall$. $EnvironmentMonitor \longrightarrow$
$\Big($ **Skip**;
$setCabinPressureCall$. $controllingMission$! $0 \longrightarrow$
$setCabinPressureRet$. $controllingMission \longrightarrow$
Skip;
$setEmergencyOxygenCall$. $controllingMission$! $0 \longrightarrow$
$setEmergencyOxygenRet$. $controllingMission \longrightarrow$
Skip;
$setFuelRemainingCall$. $controllingMission$! $0 \longrightarrow$
$setFuelRemainingRet$. $controllingMission \longrightarrow$
Skip $\Big)$;
$handleAsyncEventRet$. $EnvironmentMonitor \longrightarrow$
Skip $\Big)$

$Methods \mathrel{\widehat=}$
$\big($ $handlerAsyncEvent$ $\big)$; $Methods$

• $(Methods) \triangle (end\_periodic\_app$. $EnvironmentMonitor \longrightarrow$ **Skip**$)$

end

class *EnvironmentMonitorClass* $\widehat{=}$ **begin**

- **Skip**

end

section *FlightSensorsMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *MainMissionMethChan*

process *FlightSensorsMonitorApp* $\widehat{=}$
PriorityParameters :,
PeriodicParameters :,
MainMission :,
: *ProbablyMission* • **begin**

$$
\begin{array}{l}
handlerAsyncEvent \mathrel{\widehat{=}} \\
\left(\begin{array}{l}
handleAsyncEventCall\,.\,FlightSensorsMonitor \longrightarrow \\
\left(\begin{array}{l}
\textbf{Skip}; \\
setAirSpeedCall\,.\,controllingMission\,!\,0 \longrightarrow \\
setAirSpeedRet\,.\,controllingMission \longrightarrow \\
\textbf{Skip}; \\
setAltitudeCall\,.\,controllingMission\,!\,0 \longrightarrow \\
setAltitudeRet\,.\,controllingMission \longrightarrow \\
\textbf{Skip}; \\
setHeadingCall\,.\,controllingMission\,!\,0 \longrightarrow \\
setHeadingRet\,.\,controllingMission \longrightarrow \\
\textbf{Skip}
\end{array}\right) \\
handleAsyncEventRet\,.\,FlightSensorsMonitor \longrightarrow \\
\textbf{Skip}
\end{array}\right)
\end{array}
$$

$$
\begin{array}{l}
Methods \mathrel{\widehat{=}} \\
\left(handlerAsyncEvent\right)\ ;\ Methods
\end{array}
$$

$$
\bullet\ (Methods) \triangle (end\_periodic\_app\,.\,FlightSensorsMonitor \longrightarrow \textbf{Skip})
$$

end

class *FlightSensorsMonitorClass* $\widehat{=}$ **begin**

- **Skip**

end

section *AperiodicSimulatorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*

process $AperiodicSimulatorApp \mathrel{\widehat=}$
$PriorityParameters$:,
$PeriodicParameters$:,
$controlHandler$:,
$PriorityParameters$:,
$PeriodicParameters$:,
$commsHandler$:,
$PriorityParameters$:,
$PeriodicParameters$:,
$beginLandingHandler$:• **begin**

$$handlerAsyncEvent \mathrel{\widehat=}$$
$$\left(\begin{array}{l} handleAsyncEventCall\,.\,AperiodicSimulator \longrightarrow \\ \left(\begin{array}{l} \mathbf{Skip}; \\ releaseCall\,.\,event \longrightarrow \\ releaseRet\,.\,event\,?\,release \longrightarrow \\ \mathbf{Skip} \end{array}\right); \\ handleAsyncEventRet\,.\,AperiodicSimulator \longrightarrow \\ \mathbf{Skip} \end{array}\right)$$

$$Methods \mathrel{\widehat=}$$
$$\big(handlerAsyncEvent\big)\ ;\ Methods$$

$$\bullet\ (Methods) \triangle (end\_periodic\_app\,.\,AperiodicSimulator \longrightarrow \mathbf{Skip})$$

end

class *AperiodicSimulatorClass* $\widehat{=}$ **begin**

- **Skip**

end

5.3 TakeOffMission

section *TakeOffMissionApp* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *TakeOffMissionClass*, *TakeOffMissionMethChan*

process $TakeOffMissionApp \mathrel{\widehat=}$ **begin**

State

$this : \mathbf{ref}\ TakeOffMissionClass$

state *State*

Init

$State'$

$this' = \mathbf{new}\ TakeOffMissionClass()$

$InitializePhase \mathrel{\widehat=}$
$\left(\begin{array}{l} initializeCall\ .\ TakeOffMission \longrightarrow \\ register\ !\ LandingGearHandlerTakeOff\ !\ TakeOffMission \longrightarrow \\ register\ !\ TakeOffMonitor\ !\ TakeOffMission \longrightarrow \\ register\ !\ TakeOffFailureHandler\ !\ TakeOffMission \longrightarrow \\ initializeRet\ .\ TakeOffMission \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$CleanupPhase \mathrel{\widehat=}$
$\left(\begin{array}{l} cleanupMissionCall\ .\ TakeOffMission \longrightarrow \\ cleanupMissionRet\ .\ TakeOffMission\ !\ \mathbf{True} \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$abortMeth \mathrel{\widehat=}$
$\left(\begin{array}{l} abortCall\ .\ TakeOffMission \longrightarrow \\ this\ .\ abort(); \\ abortRet\ .\ TakeOffMission \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$getControllingMissionMeth \mathrel{\widehat=} \mathbf{var}\ ret : MissionID \bullet$
$\left(\begin{array}{l} getControllingMissionCall\ .\ TakeOffMission \longrightarrow \\ ret := this\ .\ getControllingMission(); \\ getControllingMissionRet\ .\ TakeOffMission\ !\ ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$setControllingMissionMeth \mathrel{\widehat=}$
$\left(\begin{array}{l} setControllingMissionCall\ .\ TakeOffMission\ ?\ controllingMission \longrightarrow \\ this\ .\ setControllingMission(controllingMission); \\ setControllingMissionRet\ .\ TakeOffMission \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$cleanUpMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{B} \bullet$
$\left(\begin{array}{l} cleanUpCall\ .\ TakeOffMission \longrightarrow \\ ret := this\ .\ cleanUp(); \\ cleanUpRet\ .\ TakeOffMission\ !\ ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$$
\begin{array}{l}
stowLandingGearMeth \mathrel{\widehat=} \\
\left(\begin{array}{l}
stowLandingGearCall\,.\,TakeOffMission \longrightarrow \\
this\,.\,stowLandingGear();\\
stowLandingGearRet\,.\,TakeOffMission \longrightarrow \\
\textbf{Skip}
\end{array}\right)
\end{array}
$$

$$
\begin{array}{l}
isLandingGearDeployedMeth \mathrel{\widehat=} \textbf{var}\ ret : \mathbb{B} \bullet \\
\left(\begin{array}{l}
isLandingGearDeployedCall\,.\,TakeOffMission \longrightarrow \\
ret := this\,.\,isLandingGearDeployed();\\
isLandingGearDeployedRet\,.\,TakeOffMission\,!\,ret \longrightarrow \\
\textbf{Skip}
\end{array}\right)
\end{array}
$$

$$
\begin{array}{l}
deployLandingGearSyncMeth \mathrel{\widehat=} \\
\left(\begin{array}{l}
deployLandingGearCall\,.\,TakeOffMission\,?\,thread \longrightarrow \\
\left(\begin{array}{l}
startSyncMeth\,.\,TakeOffMissionObject\,.\,thread \longrightarrow \\
lockAcquired\,.\,TakeOffMissionObject\,.\,thread \longrightarrow \\
\left(this\,.\,landingGearDeployed := true\right);\\
endSyncMeth\,.\,TakeOffMissionObject\,.\,thread \longrightarrow \\
deployLandingGearRet\,.\,TakeOffMission\,.\,thread \longrightarrow \\
\textbf{Skip}
\end{array}\right)
\end{array}\right)
\end{array}
$$

$$
Methods \mathrel{\widehat=} \left(\begin{array}{l}
InitializePhase \\
\Box \\
CleanupPhase \\
\Box \\
abortMeth \\
\Box \\
getControllingMissionMeth \\
\Box \\
setControllingMissionMeth \\
\Box \\
cleanUpMeth \\
\Box \\
stowLandingGearMeth \\
\Box \\
isLandingGearDeployedMeth \\
\Box \\
deployLandingGearSyncMeth
\end{array}\right) ;\ Methods
$$

$$
\bullet\ (Init\ ;\ Methods) \triangle (end\_mission\_app\,.\,TakeOffMission \longrightarrow \textbf{Skip})
$$

end

class *TakeOffMissionClass* $\widehat{=}$ **begin**

state *State*

$SAFE\_AIRSPEED\_THRESHOLD : double$
$TAKEOFF\_ALTITUDE : double$
$abort : \mathbb{B}$
$landingGearDeployed : \mathbb{B}$

state *State*

initial *Init*

$State'$

$SAFE\_AIRSPEED\_THRESHOLD' = 10.0$
$TAKEOFF\_ALTITUDE' = 10.0$
$abort' = false$

public *abort* $\widehat{=}$
$\big(this\,.\,abort := true\big)$

public *getControllingMission* $\widehat{=}$ **var** $ret : MissionID \bullet$
$\big(ret := controllingMission\big)$

public *setControllingMission* $\widehat{=}$
$\big(this\,.\,this.controllingMission := controllingMission\big)$

public *cleanUp* $\widehat{=}$ **var** $ret : \mathbb{B} \bullet$
$\begin{pmatrix} \textbf{Skip}; \\ ret := (\neg\ abort = \textbf{True}) \end{pmatrix}$

public *stowLandingGear* $\widehat{=}$
$\big(this\,.\,landingGearDeployed := false\big)$

public *isLandingGearDeployed* $\widehat{=}$ **var** $ret : \mathbb{B} \bullet$
$\big(ret := landingGearDeployed = \textbf{True}\big)$

• **Skip**

end

section *TakeOffMissionMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

channel *abortCall* : *MissionID*
channel *abortRet* : *MissionID*

channel *getControllingMissionCall* : *MissionID*
channel *getControllingMissionRet* : *MissionID* × *MissionID*

channel *setControllingMissionCall* : *MissionID* × *MissionID*
channel *setControllingMissionRet* : *MissionID*

channel *cleanUpCall* : *MissionID*
channel *cleanUpRet* : *MissionID* × $\mathbb{B}$

channel *stowLandingGearCall* : *MissionID*
channel *stowLandingGearRet* : *MissionID*

channel *isLandingGearDeployedCall* : *MissionID*
channel *isLandingGearDeployedRet* : *MissionID* × $\mathbb{B}$

channel *deployLandingGearCall* : *MissionID* × *ThreadID*
channel *deployLandingGearRet* : *MissionID* × *ThreadID*

5.4 Schedulables of TakeOffMission

section *LandingGearHandlerTakeOffApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *TakeOffMissionMethChan*, *ObjectIds*, *ThreadIds*

process *LandingGearHandlerTakeOffApp* $\widehat{=}$
PriorityParameters :,
AperiodicParameters :,
TakeOffMission :,
: *ProbablyMission* • **begin**

$$
\begin{array}{l}
\mathit{handlerAsyncEvent} \mathrel{\widehat{=}} \\
\left(\begin{array}{l}
\mathit{handleAsyncEventCall} \,.\, \mathit{LandingGearHandlerTakeOff} \longrightarrow \\
\left(\begin{array}{l}
\textbf{Skip}; \\
\mathit{isLandingGearDeployedCall} \,.\, \mathit{mission} \longrightarrow \\
\mathit{isLandingGearDeployedRet} \,.\, \mathit{mission} \,?\, \mathit{isLandingGearDeployed} \longrightarrow \\
\\
\textbf{var}\ \mathit{landingGearIsDeployed} : \mathbb{B} \bullet \mathit{landingGearIsDeployed} := \mathit{isLandingGearDeployed} \\
\textbf{if}\ \mathit{landingGearIsDeployed} = \textbf{True} \longrightarrow \\
\qquad \left(\begin{array}{l}
\mathit{stowLandingGearCall} \,.\, \mathit{mission} \longrightarrow \\
\mathit{stowLandingGearRet} \,.\, \mathit{mission} \longrightarrow \\
\textbf{Skip}
\end{array}\right) \\
[] \neg\ \mathit{landingGearIsDeployed} = \textbf{True} \longrightarrow \\
\qquad \left(\begin{array}{l}
\mathit{deployLandingGearCall} \,.\, \mathit{mission} \,.\, \mathit{LandingGearHandlerTakeOffThread} \longrightarrow \\
\mathit{deployLandingGearRet} \,.\, \mathit{mission} \,.\, \mathit{LandingGearHandlerTakeOffThread} \longrightarrow \\
\textbf{Skip}
\end{array}\right) \\
\textbf{fi}
\end{array}\right) \\
\mathit{handleAsyncEventRet} \,.\, \mathit{LandingGearHandlerTakeOff} \longrightarrow \\
\textbf{Skip}
\end{array}\right) ;
\end{array}
$$

$$
\begin{array}{l}
\mathit{Methods} \mathrel{\widehat{=}} \\
\left(\mathit{handlerAsyncEvent}\right) ;\ \mathit{Methods}
\end{array}
$$

$$
\bullet\ (\mathit{Methods}) \triangle (\mathit{end\_\_app} \,.\, \mathit{LandingGearHandlerTakeOff} \longrightarrow \textbf{Skip})
$$

end

class *LandingGearHandlerTakeOffClass* $\widehat{=}$ **begin**

- **Skip**

end

section *LandingGearHandlerTakeOffMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

section *TakeOffFailureHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *TakeOffMissionMethChan*

process $TakeOffFailureHandlerApp \mathrel{\widehat=}$
$PriorityParameters$:,
$AperiodicParameters$:,
$TakeOffMission$:,
: $ProbablyMission$,
:• **begin**

$handlerAsyncEvent \mathrel{\widehat=}$
$\Big($ $handleAsyncEventCall\,.\,TakeOffFailureHandler \longrightarrow$
$\Big($ $getControllingMissionCall\,.\,takeoffMission.getControllingMission() \longrightarrow$
$getControllingMissionRet\,.\,takeoffMission.getControllingMission()\,?\,getControllingMission \longrightarrow$

var $currentSpeed : double \bullet currentSpeed := getAirSpeed$
if $(currentSpeed < threshold) \longrightarrow$
$\Big($ **Skip**;
$abortCall\,.\,takeoffMission \longrightarrow$
$abortRet\,.\,takeoffMission \longrightarrow$
Skip;
$requestTerminationCall\,.\,takeoffMission \longrightarrow$
$requestTerminationRet\,.\,takeoffMission\,?\,requestTermination \longrightarrow$
Skip $\Big)$
$[]\ \neg\,(currentSpeed < threshold) \longrightarrow$
$\big($**Skip**$\big)$
fi Skip $\Big)$;
$handleAsyncEventRet\,.\,TakeOffFailureHandler \longrightarrow$
Skip $\Big)$

$Methods \mathrel{\widehat=}$
$\big(handlerAsyncEvent\big)\ ;\ Methods$

$\bullet\ (Methods) \triangle (end\_\_app\,.\,TakeOffFailureHandler \longrightarrow \textbf{Skip})$

end

class *TakeOffFailureHandlerClass* $\widehat{=}$ **begin**

state *State*

$threshold : double$

state *State*

initial *Init*

$State'$

- **Skip**

end

section *TakeOffFailureHandlerMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

section *TakeOffMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *TakeOffMissionMethChan*

process $TakeOffMonitorApp \mathrel{\widehat=}$
$PriorityParameters$:,
$PeriodicParameters$:,
: $ProbablyMission$,
:,
$landingGearHandler$:• **begin**

$handlerAsyncEvent \mathrel{\widehat=}$
$\Big($ $handleAsyncEventCall$. $TakeOffMonitor \longrightarrow$
$\Big($ **Skip**;
$getControllingMissionCall$. $takeoffMission.getControllingMission() \longrightarrow$
$getControllingMissionRet$. $takeoffMission.getControllingMission()$? $getControllingMission \longrightarrow$

var $altitude$: $double$ • $altitude := getAltitude$
if $(altitude > takeOffAltitude) \longrightarrow$
$\Big($ **Skip**;
$releaseCall$. $landingGearHandler \longrightarrow$
$releaseRet$. $landingGearHandler$? $release \longrightarrow$
$requestTerminationCall$. $takeoffMission \longrightarrow$
$requestTerminationRet$. $takeoffMission$? $requestTermination \longrightarrow$
Skip $\Big)$
[] $\neg$ $(altitude > takeOffAltitude) \longrightarrow$ **Skip**
fi ;
Skip $\Big)$;
$handleAsyncEventRet$. $TakeOffMonitor \longrightarrow$
Skip $\Big)$

$Methods \mathrel{\widehat=}$
$\big($ $handlerAsyncEvent$ $\big)$; $Methods$

• $(Methods) \triangle (end\_periodic\_app$. $TakeOffMonitor \longrightarrow$ **Skip**$)$

end

class *TakeOffMonitorClass* $\widehat{=}$ **begin**

state *State*

$takeOffAltitude : double$

state *State*

initial *Init*

$State'$

- **Skip**

end

5.5 CruiseMission

section *CruiseMissionApp* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *CruiseMissionClass*, *CruiseMissionMethChan*

process $CruiseMissionApp \mathrel{\widehat=} \textbf{begin}$

State

$this : \textbf{ref}\ CruiseMissionClass$

state *State*

Init

$State'$

$this' = \textbf{new}\ CruiseMissionClass()$

$$InitializePhase \mathrel{\widehat=} \begin{pmatrix} initializeCall\,.\,CruiseMission \longrightarrow \\ register\,!\,BeginLandingHandler\,!\,CruiseMission \longrightarrow \\ register\,!\,NavigationMonitor\,!\,CruiseMission \longrightarrow \\ initializeRet\,.\,CruiseMission \longrightarrow \\ \textbf{Skip} \end{pmatrix}$$

$$CleanupPhase \mathrel{\widehat=} \begin{pmatrix} cleanupMissionCall\,.\,CruiseMission \longrightarrow \\ cleanupMissionRet\,.\,CruiseMission\,!\,\textbf{True} \longrightarrow \\ \textbf{Skip} \end{pmatrix}$$

$$getControllingMissionMeth \mathrel{\widehat=} \textbf{var}\ ret : MissionID \bullet \begin{pmatrix} getControllingMissionCall\,.\,CruiseMission \longrightarrow \\ ret := this\,.\,getControllingMission(); \\ getControllingMissionRet\,.\,CruiseMission\,!\,ret \longrightarrow \\ \textbf{Skip} \end{pmatrix}$$

$$Methods \mathrel{\widehat=} \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ getControllingMissionMeth \end{pmatrix} ;\ Methods$$

$$\bullet\ (Init\ ;\ Methods) \triangle (end\_mission\_app\,.\,CruiseMission \longrightarrow \textbf{Skip})$$

end

class *CruiseMissionClass* $\widehat{=}$ **begin**

public *getControllingMission* $\widehat{=}$ **var** *ret* : *MissionID* $\bullet$
$\big($*ret* := *controllingMission*$\big)$

$\bullet$ **Skip**

end

section *CruiseMissionMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

channel $getControllingMissionCall : MissionID$
channel $getControllingMissionRet : MissionID \times MissionID$

5.6 Schedulables of CruiseMission

section *BeginLandingHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*

process $BeginLandingHandlerApp \mathrel{\widehat=}$
$PriorityParameters$:,
$AperiodicParameters$:,
$CruiseMission$:,
: $ProbablyMission \bullet$ **begin**

$$handlerAsyncEvent \mathrel{\widehat=}$$
$$\left(\begin{array}{l} handleAsyncEventCall\,.\,BeginLandingHandler \longrightarrow \\ \left(\begin{array}{l} \textbf{Skip}; \\ requestTerminationCall\,.\,controllingMission \longrightarrow \\ requestTerminationRet\,.\,controllingMission\,?\,requestTermination \longrightarrow \\ \textbf{Skip} \end{array}\right); \\ handleAsyncEventRet\,.\,BeginLandingHandler \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$Methods \mathrel{\widehat=}$$
$$\big(handlerAsyncEvent\big)\ ;\ Methods$$

$$\bullet\ (Methods) \triangle (end\_\_app\,.\,BeginLandingHandler \longrightarrow \textbf{Skip})$$

end

class *BeginLandingHandlerClass* $\widehat{=}$ **begin**

- **Skip**

end

section *BeginLandingHandlerMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

section *NavigationMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *CruiseMissionMethChan*

process $NavigationMonitorApp \mathrel{\widehat=}$
$PriorityParameters$:,
$PeriodicParameters$:,
$CruiseMission$:,
: $ProbablyMission \bullet$ **begin**

$handlerAsyncEvent \mathrel{\widehat=}$
$\Big($ $handleAsyncEventCall$. $NavigationMonitor \longrightarrow$
$\Big($ $getControllingMissionCall$. $mission.getControllingMission() \longrightarrow$
$getControllingMissionRet$. $mission.getControllingMission() ?\ getControllingMission \longrightarrow$

var $heading : double \bullet heading := getHeading$
$getControllingMissionCall$. $mission.getControllingMission() \longrightarrow$
$getControllingMissionRet$. $mission.getControllingMission() ?\ getControllingMission \longrightarrow$

var $airSpeed : double \bullet airSpeed := getAirSpeed$
$getControllingMissionCall$. $mission.getControllingMission() \longrightarrow$
$getControllingMissionRet$. $mission.getControllingMission() ?\ getControllingMission \longrightarrow$

var $altitude : double \bullet altitude := getAltitude$
Skip
$\Big)$;
$handleAsyncEventRet$. $NavigationMonitor \longrightarrow$
Skip
$\Big)$

$Methods \mathrel{\widehat=}$
$\big(handlerAsyncEvent\big)$; $Methods$

$\bullet\ (Methods) \triangle (end\_periodic\_app$. $NavigationMonitor \longrightarrow$ **Skip**$)$

end

class *NavigationMonitorClass* $\widehat{=}$ **begin**

- **Skip**

end

5.7 LandMission

section *LandMissionApp* **parents** *scj_prelude*, *MissionId*, *MissionIds*, *SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *LandMissionClass*, *LandMissionMethChan*

process $LandMissionApp \mathrel{\widehat=}$ **begin**

State

$this : \mathbf{ref}\ LandMissionClass$

state *State*

Init

$State'$

$this' = \mathbf{new}\ LandMissionClass()$

$InitializePhase \mathrel{\widehat=}$
$\left(\begin{array}{l} initializeCall\,.\,LandMission \longrightarrow \\ register\,!\,GroundDistanceMonitor\,!\,LandMission \longrightarrow \\ register\,!\,LandingGearHandlerLand\,!\,LandMission \longrightarrow \\ register\,!\,InstrumentLandingSystemMonitor\,!\,LandMission \longrightarrow \\ register\,!\,SafeLandingHandler\,!\,LandMission \longrightarrow \\ initializeRet\,.\,LandMission \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$CleanupPhase \mathrel{\widehat=}$
$\left(\begin{array}{l} cleanupMissionCall\,.\,LandMission \longrightarrow \\ cleanupMissionRet\,.\,LandMission\,!\,\mathbf{True} \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$stowLandingGearMeth \mathrel{\widehat=}$
$\left(\begin{array}{l} stowLandingGearCall\,.\,LandMission \longrightarrow \\ this\,.\,stowLandingGear(); \\ stowLandingGearRet\,.\,LandMission \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$isLandingGearDeployedMeth \mathrel{\widehat=} \mathbf{var}\ ret : \mathbb{B} \bullet$
$\left(\begin{array}{l} isLandingGearDeployedCall\,.\,LandMission \longrightarrow \\ ret := this\,.\,isLandingGearDeployed(); \\ isLandingGearDeployedRet\,.\,LandMission\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$getControllingMissionMeth \mathrel{\widehat=} \mathbf{var}\ ret : MissionID \bullet$
$\left(\begin{array}{l} getControllingMissionCall\,.\,LandMission \longrightarrow \\ ret := this\,.\,getControllingMission(); \\ getControllingMissionRet\,.\,LandMission\,!\,ret \longrightarrow \\ \mathbf{Skip} \end{array}\right)$

$$abortMeth \mathrel{\widehat=} \left(\begin{array}{l} abortCall\,.\,LandMission \longrightarrow \\ this\,.\,abort(); \\ abortRet\,.\,LandMission \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$cleanUpMeth \mathrel{\widehat=} \textbf{var}\ ret : \mathbb{B} \bullet \left(\begin{array}{l} cleanUpCall\,.\,LandMission \longrightarrow \\ ret := this\,.\,cleanUp(); \\ cleanUpRet\,.\,LandMission\,!\,ret \longrightarrow \\ \textbf{Skip} \end{array}\right)$$

$$deployLandingGearSyncMeth \mathrel{\widehat=} \left(\begin{array}{l} deployLandingGearCall\,.\,LandMission\,?\,thread \longrightarrow \\ \left(\begin{array}{l} startSyncMeth\,.\,LandMissionObject\,.\,thread \longrightarrow \\ lockAcquired\,.\,LandMissionObject\,.\,thread \longrightarrow \\ \big(this\,.\,landingGearDeployed := true\big)\,; \\ endSyncMeth\,.\,LandMissionObject\,.\,thread \longrightarrow \\ deployLandingGearRet\,.\,LandMission\,.\,thread \longrightarrow \\ \textbf{Skip} \end{array}\right) \end{array}\right)$$

$$Methods \mathrel{\widehat=} \left(\begin{array}{l} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ stowLandingGearMeth \\ \Box \\ isLandingGearDeployedMeth \\ \Box \\ getControllingMissionMeth \\ \Box \\ abortMeth \\ \Box \\ cleanUpMeth \\ \Box \\ deployLandingGearSyncMeth \end{array}\right) ;\ Methods$$

$$\bullet\ (Init\ ;\ Methods) \triangle (end\_mission\_app\,.\,LandMission \longrightarrow \textbf{Skip})$$

end

class *LandMissionClass* $\widehat{=}$ **begin**

state *State*

$SAFE\_LANDING\_ALTITUDE : double$
$abort : \mathbb{B}$
$landingGearDeployed : \mathbb{B}$

state *State*

initial *Init*

$State'$

$SAFE\_LANDING\_ALTITUDE' = 10.0$
$abort' = false$

public *stowLandingGear* $\widehat{=}$
$(this\,.\,landingGearDeployed := false)$

public *isLandingGearDeployed* $\widehat{=}$ **var** $ret : \mathbb{B} \bullet$
$(ret := landingGearDeployed = \mathbf{True})$

public *getControllingMission* $\widehat{=}$ **var** $ret : MissionID \bullet$
$(ret := controllingMission)$

public *abort* $\widehat{=}$
$(this\,.\,abort := true)$

public *cleanUp* $\widehat{=}$ **var** $ret : \mathbb{B} \bullet$
$\begin{pmatrix} \mathbf{Skip}; \\ ret := (\neg\ abort = \mathbf{True}) \end{pmatrix}$

• **Skip**

end

section *LandMissionMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

channel *stowLandingGearCall* : *MissionID*
channel *stowLandingGearRet* : *MissionID*

channel *isLandingGearDeployedCall* : *MissionID*
channel *isLandingGearDeployedRet* : *MissionID* $\times$ $\mathbb{B}$

channel *getControllingMissionCall* : *MissionID*
channel *getControllingMissionRet* : *MissionID* $\times$ *MissionID*

channel *abortCall* : *MissionID*
channel *abortRet* : *MissionID*

channel *cleanUpCall* : *MissionID*
channel *cleanUpRet* : *MissionID* $\times$ $\mathbb{B}$

channel *deployLandingGearCall* : *MissionID* $\times$ *ThreadID*
channel *deployLandingGearRet* : *MissionID* $\times$ *ThreadID*

5.8 Schedulables of LandMission

section *LandingGearHandlerLandApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *LandMissionMethChan*, *ObjectIds*, *ThreadIds*

process *LandingGearHandlerLandApp* $\widehat{=}$
PriorityParameters :,
AperiodicParameters :,
LandMission :,
: *ProbablyMission* • **begin**

$$
\begin{array}{l}
\mathit{handlerAsyncEvent} \mathrel{\widehat{=}} \\
\left(\begin{array}{l}
\mathit{handleAsyncEventCall} \,.\, \mathit{LandingGearHandlerLand} \longrightarrow \\
\left(\begin{array}{l}
\textbf{Skip}; \\
\mathit{isLandingGearDeployedCall} \,.\, \mathit{mission} \longrightarrow \\
\mathit{isLandingGearDeployedRet} \,.\, \mathit{mission} \,?\, \mathit{isLandingGearDeployed} \longrightarrow \\
\\
\textbf{var}\ \mathit{landingGearIsDeployed} : \mathbb{B} \bullet \mathit{landingGearIsDeployed} := \mathit{isLandingGearDeployed} \\
\textbf{if}\ \mathit{landingGearIsDeployed} = \textbf{True} \longrightarrow \\
\qquad \left(\begin{array}{l} \mathit{stowLandingGearCall} \,.\, \mathit{mission} \longrightarrow \\ \mathit{stowLandingGearRet} \,.\, \mathit{mission} \longrightarrow \\ \textbf{Skip} \end{array}\right) \\
[] \neg\ \mathit{landingGearIsDeployed} = \textbf{True} \longrightarrow \\
\qquad \left(\begin{array}{l} \mathit{deployLandingGearCall} \,.\, \mathit{mission} \,.\, \mathit{LandingGearHandlerLandThread} \longrightarrow \\ \mathit{deployLandingGearRet} \,.\, \mathit{mission} \,.\, \mathit{LandingGearHandlerLandThread} \longrightarrow \\ \textbf{Skip} \end{array}\right) \\
\textbf{fi}
\end{array}\right) \\
\mathit{handleAsyncEventRet} \,.\, \mathit{LandingGearHandlerLand} \longrightarrow \\
\textbf{Skip}
\end{array}\right) ;
\end{array}
$$

$$
\begin{array}{l}
\mathit{Methods} \mathrel{\widehat{=}} \\
\big(\mathit{handlerAsyncEvent}\big)\ ;\ \mathit{Methods}
\end{array}
$$

$$
\bullet\ (\mathit{Methods}) \triangle (\mathit{end\_\_app} \,.\, \mathit{LandingGearHandlerLand} \longrightarrow \textbf{Skip})
$$

end

class *LandingGearHandlerLandClass* $\widehat{=}$ **begin**

- **Skip**

end

section *LandingGearHandlerLandMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

section *SafeLandingHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *LandMissionMethChan*

process *SafeLandingHandlerApp* $\widehat{=}$
PriorityParameters :,
AperiodicParameters :,
LandMission :,
: *ProbablyMission*,
:• **begin**

handlerAsyncEvent $\widehat{=}$

$$\left(\begin{array}{l} \mathit{handleAsyncEventCall} \,.\, \mathit{SafeLandingHandler} \longrightarrow \\ \left(\begin{array}{l} \mathit{getControllingMissionCall} \,.\, \mathit{landMission.getControllingMission}() \longrightarrow \\ \mathit{getControllingMissionRet} \,.\, \mathit{landMission.getControllingMission}() \,?\, \mathit{getControllingMission} \longrightarrow \\ \\ \textbf{var}\ \mathit{altitude} : \mathit{double} \bullet \mathit{altitude} := \mathit{getAltitude} \\ \textbf{if}\ (\mathit{altitude} < \mathit{threshold}) \longrightarrow \\ \quad (\textbf{Skip}) \\ [] \neg\ (\mathit{altitude} < \mathit{threshold}) \longrightarrow \\ \quad (\textbf{Skip}) \\ \textbf{fi} \end{array}\right) \\ \mathit{handleAsyncEventRet} \,.\, \mathit{SafeLandingHandler} \longrightarrow \\ \textbf{Skip} \end{array}\right) ;$$

Methods $\widehat{=}$
$(\mathit{handlerAsyncEvent})\ ;\ \mathit{Methods}$

• $(\mathit{Methods}) \triangle (\mathit{end\_app} \,.\, \mathit{SafeLandingHandler} \longrightarrow \textbf{Skip})$

end

class *SafeLandingHandlerClass* $\widehat{=}$ **begin**

state *State*

$threshold : double$

state *State*

initial *Init*

$State'$

- **Skip**

end

section *SafeLandingHandlerMethChan* **parents** *scj_prelude*, *GlobalTypes*, *MissionId*, *SchedulableId*

section *GroundDistanceMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds* , *LandMissionMethChan*

process *GroundDistanceMonitorApp* $\widehat{=}$
PriorityParameters :,
PeriodicParameters :,
: *ProbablyMission* • **begin**

handlerAsyncEvent $\widehat{=}$
$\Big($ *handleAsyncEventCall* . *GroundDistanceMonitor* $\longrightarrow$
$\Big($ **Skip**;
getControllingMissionCall . *mission*.*getControllingMission*() $\longrightarrow$
getControllingMissionRet . *mission*.*getControllingMission*() ? *getControllingMission* $\longrightarrow$

var *distance* : *double* • *distance* := *getAltitude*
if (*distance* = *readingOnGround*) $\longrightarrow$
$\Big($ **Skip**;
requestTerminationCall . *mission* $\longrightarrow$
requestTerminationRet . *mission* ? *requestTermination* $\longrightarrow$
Skip $\Big)$
$[]$ ¬ (*distance* = *readingOnGround*) $\longrightarrow$ **Skip**
fi ;
Skip $\Big)$
handleAsyncEventRet . *GroundDistanceMonitor* $\longrightarrow$
Skip $\Big)$;

Methods $\widehat{=}$
$\big($ *handlerAsyncEvent* $\big)$; *Methods*

• (*Methods*) $\triangle$ (*end_periodic_app* . *GroundDistanceMonitor* $\longrightarrow$ **Skip**)

end

class *GroundDistanceMonitorClass* $\widehat{=}$ **begin**

state *State*

$readingOnGround : double$

state *State*

initial *Init*

$State'$

- **Skip**

end

section *InstrumentLandingSystemMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*

process *InstrumentLandingSystemMonitorApp* $\widehat{=}$
PriorityParameters :,
PeriodicParameters :,
LandMission :,
: *ProbablyMission* • **begin**

$$
\begin{pmatrix}
handleAsyncEventCall\,.\,InstrumentLandingSystemMonitor \longrightarrow \\
(\mathbf{Skip})\,; \\
handleAsyncEventRet\,.\,InstrumentLandingSystemMonitor \longrightarrow \\
\mathbf{Skip}
\end{pmatrix}
$$

$$
\begin{pmatrix}
Methods \widehat{=} \\
(handlerAsyncEvent)\,;\ Methods
\end{pmatrix}
$$

$$
\bullet\ (Methods) \triangle (end\_periodic\_app\,.\,InstrumentLandingSystemMonitor \longrightarrow \mathbf{Skip})
$$

end

class *InstrumentLandingSystemMonitorClass* $\widehat{=}$ **begin**

- **Skip**

end