

# aircraft

Tight Rope v0.6

15th December 2015

## 1 ID Files

### 1.1 MissionIds

**section** *MissionIds* **parents** *scj\_prelude*, *MissionId*

*MainMissionID* : *MissionID*  
*TakeOffMissionID* : *MissionID*  
*CruiseMissionID* : *MissionID*  
*LandMissionID* : *MissionID*

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*distinct*(*nullMissionId*, *MainMissionID*, *TakeOffMissionID*,  
*CruiseMissionID*, *LandMissionID*)

## 1.2 SchedulablesIds

**section** *SchedulableIds* **parents** *scj\_prelude*, *SchedulableId*

*MainMissionSequencerID* : *SchedulableID*  
*ACModeChangerID* : *SchedulableID*  
*EnvironmentMonitorID* : *SchedulableID*  
*ControlHandlerID* : *SchedulableID*  
*FlightSensorsMonitorID* : *SchedulableID*  
*CommunicationsHandlerID* : *SchedulableID*  
*AperiodicSimulatorID* : *SchedulableID*  
*LandingGearHandlerTakeOffID* : *SchedulableID*  
*TakeOffMonitorID* : *SchedulableID*  
*TakeOffFailureHandlerID* : *SchedulableID*  
*BeginLandingHandlerID* : *SchedulableID*  
*NavigationMonitorID* : *SchedulableID*  
*GroundDistanceMonitorID* : *SchedulableID*  
*LandingGearHandlerLandID* : *SchedulableID*  
*InstrumentLandingSystemMonitorID* : *SchedulableID*  
*SafeLandingHandlerID* : *SchedulableID*

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*distinct*(*nullSequencerId*, *nullSchedulableId*, *MainMissionSequencerID*,  
*ACModeChangerID*, *EnvironmentMonitorID*,  
*ControlHandlerID*, *FlightSensorsMonitorID*,  
*CommunicationsHandlerID*, *AperiodicSimulatorID*,  
*LandingGearHandlerTakeOffID*, *TakeOffMonitorID*,  
*TakeOffFailureHandlerID*, *BeginLandingHandlerID*,  
*NavigationMonitorID*, *GroundDistanceMonitorID*,  
*LandingGearHandlerLandID*, *InstrumentLandingSystemMonitorID*,  
*SafeLandingHandlerID*)

### 1.3 ThreadIds

**section** *ThreadId*s **parents** *scj\_prelude*, *GlobalTypes*

*SafeLandingHandlerThreadID* : *ThreadID*  
*ACModeChangerThreadID* : *ThreadID*  
*TakeOffFailureHandlerThreadID* : *ThreadID*  
*InstrumentLandingSystemMonitorThreadID* : *ThreadID*  
*FlightSensorsMonitorThreadID* : *ThreadID*  
*TakeOffMonitorThreadID* : *ThreadID*  
*AperiodicSimulatorThreadID* : *ThreadID*  
*LandingGearHandlerLandThreadID* : *ThreadID*  
*LandingGearHandlerTakeOffThreadID* : *ThreadID*  
*GroundDistanceMonitorThreadID* : *ThreadID*  
*ControlHandlerThreadID* : *ThreadID*  
*CommunicationsHandlerThreadID* : *ThreadID*  
*BeginLandingHandlerThreadID* : *ThreadID*  
*NavigationMonitorThreadID* : *ThreadID*  
*EnvironmentMonitorThreadID* : *ThreadID*

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*distinct*(*SafeletThreadId*, *nullThreadId*,  
*SafeLandingHandlerThreadID*, *ACModeChangerThreadID*,  
*TakeOffFailureHandlerThreadID*, *InstrumentLandingSystemMonitorThreadID*,  
*FlightSensorsMonitorThreadID*, *TakeOffMonitorThreadID*,  
*AperiodicSimulatorThreadID*, *LandingGearHandlerLandThreadID*,  
*LandingGearHandlerTakeOffThreadID*, *GroundDistanceMonitorThreadID*,  
*ControlHandlerThreadID*, *CommunicationsHandlerThreadID*,  
*BeginLandingHandlerThreadID*, *NavigationMonitorThreadID*,  
*EnvironmentMonitorThreadID*)

## 1.4 ObjectIds

section *ObjectIds* parents *scj\_prelude*, *GlobalTypes*

*ACSafeletObjectID* : *ObjectID*  
*MainMissionObjectID* : *ObjectID*  
*ACModeChangerObjectID* : *ObjectID*  
*EnvironmentMonitorObjectID* : *ObjectID*  
*ControlHandlerObjectID* : *ObjectID*  
*FlightSensorsMonitorObjectID* : *ObjectID*  
*CommunicationsHandlerObjectID* : *ObjectID*  
*AperiodicSimulatorObjectID* : *ObjectID*  
*TakeOffMissionObjectID* : *ObjectID*  
*LandingGearHandlerTakeOffObjectID* : *ObjectID*  
*TakeOffMonitorObjectID* : *ObjectID*  
*TakeOffFailureHandlerObjectID* : *ObjectID*  
*CruiseMissionObjectID* : *ObjectID*  
*BeginLandingHandlerObjectID* : *ObjectID*  
*NavigationMonitorObjectID* : *ObjectID*  
*LandMissionObjectID* : *ObjectID*  
*GroundDistanceMonitorObjectID* : *ObjectID*  
*LandingGearHandlerLandObjectID* : *ObjectID*  
*InstrumentLandingSystemMonitorObjectID* : *ObjectID*  
*SafeLandingHandlerObjectID* : *ObjectID*

*distinct*(*ACSafeletObjectID*, *MainMissionObjectID*,  
*ACModeChangerObjectID*, *EnvironmentMonitorObjectID*,  
*ControlHandlerObjectID*, *FlightSensorsMonitorObjectID*,  
*CommunicationsHandlerObjectID*, *AperiodicSimulatorObjectID*,  
*TakeOffMissionObjectID*, *LandingGearHandlerTakeOffObjectID*,  
*TakeOffMonitorObjectID*, *TakeOffFailureHandlerObjectID*,  
*CruiseMissionObjectID*, *BeginLandingHandlerObjectID*,  
*NavigationMonitorObjectID*, *LandMissionObjectID*,  
*GroundDistanceMonitorObjectID*, *LandingGearHandlerLandObjectID*,  
*InstrumentLandingSystemMonitorObjectID*, *SafeLandingHandlerObjectID*)

## 2 Network

**section** *NetworkChannels* **parents** *scj\_prelude, MissionId, MissionIds, SchedulableId, SchedulableIds, MissionChan, SchedulableChan, TopLevelMissionSequencerFWChan, FrameworkChan, SafeletChan*

**channelset** *TerminateSync* ==  
    {*schedulables\_terminated, schedulables\_stopped, get\_activeSchedulables* }

**channelset** *ControlTierSync* ==  
    {*start\_toplevel\_sequencer, done\_toplevel\_sequencer, done\_safeletFW* }

**channelset** *TierSync* ==  
    {*start\_mission ., done\_mission ., done\_safeletFW, done\_toplevel\_sequencer* }

**channelset** *MissionSync* ==  
    {*done\_safeletFW, done\_toplevel\_sequencer, register, signalTerminationCall, signalTerminationRet, activate\_schedulables, done\_schedulable, cleanupSchedulableCall, cleanupSchedulableRet* }

**channelset** *SchedulablesSync* ==  
    {*activate\_schedulables, done\_safeletFW, done\_toplevel\_sequencer* }

**channelset** *ClusterSync* ==  
    {*done\_toplevel\_sequencer, done\_safeletFW* }

**channelset** *AppSync* ==  
    {*SafeltAppSync, MissionSequencerAppSync, MissionAppSync, MTAppSync, OSEHSync, APEHSync, getSequencer, end\_mission\_app, end\_managedThread\_app, setCeilingPriority, requestTerminationCall, requestTerminationRet, terminationPendingCall, terminationPendingRet, handleAsyncEventCall, handleAsyncEventRet* }

**channelset** *ThreadSync* ==  
    {*raise\_thread\_priority, lower\_thread\_priority, isInterruptedCall, isInterruptedRet, get\_priorityLevel* }

**channelset** *LockingSync* ==  
    {*lockAcquired, startSyncMeth, endSyncMeth, waitCall, waitRet, notify, isInterruptedCall, isInterruptedRet, interruptedCall, interruptedRet, done\_toplevel\_sequencer, get\_priorityLevel* }

**channelset** *Tier0Sync* ==  
    {*done\_toplevel\_sequencer, done\_safeletFW, start\_mission . TakeOffMission, done\_mission . TakeOffMission, initializeRet . TakeOffMission, requestTermination . TakeOffMission . MainMissionSequencer, start\_mission . CruiseMission, done\_mission . CruiseMission, initializeRet . CruiseMission, requestTermination . CruiseMission . MainMissionSequencer, start\_mission . LandMission, done\_mission . LandMission, initializeRet . LandMission, requestTermination . LandMission . MainMissionSequencer* }

**section** *Program parents* *scj\_prelude*, *MissionId*, *MissionIds*,  
*SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *MissionFW*,  
*SafeletFW*, *TopLevelMissionSequencerFW*, *NetworkChannels*, *ManagedThreadFW*,  
*SchedulableMissionSequencerFW*, *PeriodicEventHandlerFW*, *OneShotEventHandlerFW*,  
*AperiodicEventHandlerFW*, *ObjectFW*, *ThreadFW*,  
*ACSafeletApp*, *MainMissionSequencerApp*, *MainMissionApp*, *ACModeChangerApp*, *ControlHandlerApp*,  
*CommunicationsHandlerApp*, *EnvironmentMonitorApp*, *FlightSensorsMonitorApp*,  
*AperiodicSimulatorApp*, *TakeOffMissionApp*, *LandingGearHandlerTakeOffApp*, *TakeOffFailureHandlerApp*,  
*TakeOffMonitorApp*, *CruiseMissionApp*, *BeginLandingHandlerApp*, *NavigationMonitorApp*,  
*LandMissionApp*, *LandingGearHandlerLandApp*, *SafeLandingHandlerApp*, *GroundDistanceMonitorApp*,  
*InstrumentLandingSystemMonitorApp*

**process** *ControlTier*  $\hat{=}$   
 $\left( \begin{array}{l} \text{SafeletFW} \\ \llbracket \text{ControlTierSync} \rrbracket \\ \text{TopLevelMissionSequencerFW}(\text{MainMissionSequencer}) \end{array} \right)$

**process** *Tier0*  $\hat{=}$   
 $\left( \begin{array}{l} \text{MissionFW}(\text{MainMissionID}) \\ \llbracket \text{MissionSync} \rrbracket \\ \left( \begin{array}{l} \text{SchedulableMissionSequencerFW}(\text{ACModeChangerID}) \\ \llbracket \text{SchedulablesSync} \rrbracket \\ \left( \begin{array}{l} \text{AperiodicEventHandlerFW}(\text{ControlHandlerID}, (\text{time}(10, 0), \text{null})) \\ \llbracket \text{SchedulablesSync} \rrbracket \\ \text{AperiodicEventHandlerFW}(\text{CommunicationsHandlerID}, (\text{NULL}, \text{nullSchedulableId})) \end{array} \right) \\ \llbracket \text{SchedulablesSync} \rrbracket \\ \left( \begin{array}{l} \text{PeriodicEventHandlerFW}(\text{EnvironmentMonitorID}, (\text{time}(10, 0), \text{NULL}, \text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{SchedulablesSync} \rrbracket \\ \text{PeriodicEventHandlerFW}(\text{FlightSensorsMonitorID}, (\text{time}(10, 0), \text{NULL}, \text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{SchedulablesSync} \rrbracket \\ \text{PeriodicEventHandlerFW}(\text{AperiodicSimulatorID}, (\text{time}(10, 0), \text{NULL}, \text{NULL}, \text{nullSchedulableId})) \end{array} \right) \end{array} \right) \end{array} \right)$

**process** *Tier1*  $\hat{=}$   
 $\left( \begin{array}{l} \text{MissionFW}(\text{TakeOffMissionID}) \\ \llbracket \text{MissionSync} \rrbracket \\ \left( \begin{array}{l} \left( \begin{array}{l} \text{AperiodicEventHandlerFW}(\text{LandingGearHandlerTakeOffID}, (\text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{SchedulablesSync} \rrbracket \end{array} \right) \\ \text{AperiodicEventHandlerFW}(\text{TakeOffFailureHandlerID}, (\text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{SchedulablesSync} \rrbracket \end{array} \right) \\ \text{PeriodicEventHandlerFW}(\text{TakeOffMonitorID}, (\text{time}(0, 0), \text{time}(500, 0), \text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{ClusterSync} \rrbracket \\ \text{MissionFW}(\text{CruiseMissionID}) \\ \llbracket \text{MissionSync} \rrbracket \\ \left( \begin{array}{l} \text{AperiodicEventHandlerFW}(\text{BeginLandingHandlerID}, (\text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{SchedulablesSync} \rrbracket \\ \text{PeriodicEventHandlerFW}(\text{NavigationMonitorID}, (\text{time}(0, 0), \text{time}(10, 0), \text{NULL}, \text{nullSchedulableId})) \end{array} \right) \\ \llbracket \text{ClusterSync} \rrbracket \\ \text{MissionFW}(\text{LandMissionID}) \\ \llbracket \text{MissionSync} \rrbracket \\ \left( \begin{array}{l} \left( \begin{array}{l} \text{AperiodicEventHandlerFW}(\text{LandingGearHandlerLandID}, (\text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{SchedulablesSync} \rrbracket \end{array} \right) \\ \text{AperiodicEventHandlerFW}(\text{SafeLandingHandlerID}, (\text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{SchedulablesSync} \rrbracket \\ \left( \begin{array}{l} \text{PeriodicEventHandlerFW}(\text{GroundDistanceMonitorID}, (\text{time}(0, 0), \text{time}(10, 0), \text{NULL}, \text{nullSchedulableId})) \\ \llbracket \text{SchedulablesSync} \rrbracket \\ \text{PeriodicEventHandlerFW}(\text{InstrumentLandingSystemMonitorID}, (\text{time}(0, 0), \text{time}(10, 0), \text{NULL}, \text{nullSchedulableId})) \end{array} \right) \end{array} \right) \end{array} \right)$

**process** *Framework*  $\hat{=}$   

$$\left( \begin{array}{c} \textit{ControlTier} \\ \llbracket \textit{TierSync} \rrbracket \\ \left( \begin{array}{c} \textit{Tier0} \\ \llbracket \textit{Tier0Sync} \rrbracket \end{array} \right) \\ \textit{Tier1} \end{array} \right)$$

**process** *Application*  $\hat{=}$   

$$\left( \begin{array}{l} \textit{ACSafeletApp} \\ ||| \\ \textit{MainMissionSequencerApp} \\ ||| \\ \textit{MainMissionApp} \\ ||| \\ \textit{ACModeChangerApp}(\textit{MainMissionID}) \\ ||| \\ \textit{ControlHandlerApp} \\ ||| \\ \textit{CommunicationsHandlerApp} \\ ||| \\ \textit{EnvironmentMonitorApp}(\textit{MainMissionID}) \\ ||| \\ \textit{FlightSensorsMonitorApp}(\textit{MainMissionID}) \\ ||| \\ \textit{AperiodicSimulatorApp}(\textit{controlHandlerID}) \\ ||| \\ \textit{TakeOffMissionApp} \\ ||| \\ \textit{LandingGearHandlerTakeOffApp}(\textit{TakeOffMissionID}) \\ ||| \\ \textit{TakeOffFailureHandlerApp}(\textit{MainMission}, \textit{TakeOffMissionID}, ) \\ ||| \\ \textit{TakeOffMonitorApp}(\textit{MainMission}, \textit{TakeOffMissionID}, , \textit{landingGearHandlerID}) \\ ||| \\ \textit{CruiseMissionApp} \\ ||| \\ \textit{BeginLandingHandlerApp}(\textit{MainMission}) \\ ||| \\ \textit{NavigationMonitorApp}(\textit{MainMission}) \\ ||| \\ \textit{LandMissionApp} \\ ||| \\ \textit{LandingGearHandlerLandApp}(\textit{LandMissionID}) \\ ||| \\ \textit{SafeLandingHandlerApp}(\textit{MainMission}, ) \\ ||| \\ \textit{GroundDistanceMonitorApp}(\textit{MainMission}) \\ ||| \\ \textit{InstrumentLandingSystemMonitorApp}(\textit{LandMissionID}) \end{array} \right)$$

*MethodCallBinder*  $\hat{=}$   
 $\textit{testMethodBinder} |||$   
 $\textit{testMethodBinder}$

**channelset** *testLocs* ==  $\{ \textit{testLoc} \}$   
**channelset** *testCallers* ==  $\{ \textit{testCaller} \}$

$$test_MethoBinder \hat{=} \left( \begin{array}{l} binder_t estCall ? loc : (testLocs) ? caller : (testCallers) \longrightarrow \\ testCall . loc . caller \longrightarrow \\ testRet . loc . caller ? ret \longrightarrow \\ binder_t estRet . loc . caller ! ret \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

**channelset**  $testLocs == \{\!| testLoc |\!\}$   
**channelset**  $testCallers == \{\!| testCaller |\!\}$

$$test_MethoBinder \hat{=} \left( \begin{array}{l} binder_t estCall ? loc : (testLocs) ? caller : (testCallers) \longrightarrow \\ testCall . loc . caller \longrightarrow \\ testRet . loc . caller ? ret \longrightarrow \\ binder_t estRet . loc . caller ! ret \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$Threads \hat{=} \left( \begin{array}{l} ThreadFW(SafeLandingHandlerThreadID, 5) \\ ||| \\ ThreadFW(ACModeChangerThreadID, 5) \\ ||| \\ ThreadFW(TakeOffFailureHandlerThreadID, 5) \\ ||| \\ ThreadFW(InstrumentLandingSystemMonitorThreadID, 5) \\ ||| \\ ThreadFW(FlightSensorsMonitorThreadID, 5) \\ ||| \\ ThreadFW(TakeOffMonitorThreadID, 5) \\ ||| \\ ThreadFW(AperiodicSimulatorThreadID, 5) \\ ||| \\ ThreadFW(LandingGearHandlerLandThreadID, 5) \\ ||| \\ ThreadFW(LandingGearHandlerTakeOffThreadID, 5) \\ ||| \\ ThreadFW(GroundDistanceMonitorThreadID, 5) \\ ||| \\ ThreadFW(ControlHandlerThreadID, 5) \\ ||| \\ ThreadFW(CommunicationsHandlerThreadID, 5) \\ ||| \\ ThreadFW(BeginLandingHandlerThreadID, 5) \\ ||| \\ ThreadFW(NavigationMonitorThreadID, 5) \\ ||| \\ ThreadFW(EnvironmentMonitorThreadID, 5) \end{array} \right)$$



$$\begin{aligned}
\text{Objects} \hat{=} & \left( \begin{array}{l}
\text{ObjectFW}(\text{ACSafeletObjectID}) \\
||| \\
\text{ObjectFW}(\text{MainMissionObjectID}) \\
||| \\
\text{ObjectFW}(\text{ACModeChangerObjectID}) \\
||| \\
\text{ObjectFW}(\text{EnvironmentMonitorObjectID}) \\
||| \\
\text{ObjectFW}(\text{ControlHandlerObjectID}) \\
||| \\
\text{ObjectFW}(\text{FlightSensorsMonitorObjectID}) \\
||| \\
\text{ObjectFW}(\text{CommunicationsHandlerObjectID}) \\
||| \\
\text{ObjectFW}(\text{AperiodicSimulatorObjectID}) \\
||| \\
\text{ObjectFW}(\text{TakeOffMissionObjectID}) \\
||| \\
\text{ObjectFW}(\text{LandingGearHandlerTakeOffObjectID}) \\
||| \\
\text{ObjectFW}(\text{TakeOffMonitorObjectID}) \\
||| \\
\text{ObjectFW}(\text{TakeOffFailureHandlerObjectID}) \\
||| \\
\text{ObjectFW}(\text{CruiseMissionObjectID}) \\
||| \\
\text{ObjectFW}(\text{BeginLandingHandlerObjectID}) \\
||| \\
\text{ObjectFW}(\text{NavigationMonitorObjectID}) \\
||| \\
\text{ObjectFW}(\text{LandMissionObjectID}) \\
||| \\
\text{ObjectFW}(\text{GroundDistanceMonitorObjectID}) \\
||| \\
\text{ObjectFW}(\text{LandingGearHandlerLandObjectID}) \\
||| \\
\text{ObjectFW}(\text{InstrumentLandingSystemMonitorObjectID}) \\
||| \\
\text{ObjectFW}(\text{SafeLandingHandlerObjectID})
\end{array} \right)
\end{aligned}$$

$$\text{Locking} \hat{=} \text{Threads} \llbracket \text{ThreadSync} \rrbracket \text{Objects}$$

$$\mathbf{process} \text{ Program} \hat{=} (\text{Framework} \llbracket \text{AppSync} \rrbracket \text{Application}) \llbracket \text{LockingSync} \rrbracket \text{Locking}$$

### 3 Safelet

**section** *ACSafeletApp* **parents** *scj\_prelude, SchedulableId, SchedulableIds, SafeletChan*

**process** *ACSafeletApp*  $\hat{=}$  **begin**

*InitializeApplication*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{initializeApplicationCall} \longrightarrow \\ \textit{initializeApplicationRet} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$

*GetSequencer*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{getSequencerCall} \longrightarrow \\ \textit{getSequencerRet} ! \textit{MainMissionSequencer} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$

*Methods*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{GetSequencer} \\ \square \\ \textit{InitializeApplication} \end{array} \right); \textit{Methods}$

•  $(\textit{Methods}) \triangle (\textit{end\_safelet\_app} \longrightarrow \mathbf{Skip})$

**end**

## 4 Top Level Mission Sequencer

**section** *MainMissionSequencerApp* **parents** *TopLevelMissionSequencerChan*,  
*MissionId*, *MissionIds*, *SchedulableId*, *MainMissionSequencerClass*

**process** *MainMissionSequencerApp*  $\hat{=}$  **begin**

<i>State</i> <i>this</i> : <b>ref</b> <i>MainMissionSequencerClass</i>
---

**state** *State*

<i>Init</i> <i>State</i> ' <i>this</i> ' = <b>new</b> <i>MainMissionSequencerClass</i> ()
---

*GetNextMission*  $\hat{=}$  **var** *ret* : *MissionID* •  
 $\left( \begin{array}{l} \textit{getNextMissionCall} . \textit{MainMissionSequencer} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{getNextMission}(); \\ \textit{getNextMissionRet} . \textit{MainMissionSequencer} ! \textit{ret} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$

*Methods*  $\hat{=}$   
( *GetNextMission* ) ; *Methods*

• ( *Init* ; *Methods* )  $\triangle$  ( *end\_sequencer\_app* . *MainMissionSequencer*  $\longrightarrow$  **Skip** )

**end**

**class** *MainMissionSequencerClass*  $\hat{=}$  **begin**

<b>state</b> <i>State</i> <i>returnedMission</i> : $\mathbb{B}$
--

**state** *State*

<b>initial</b> <i>Init</i> <i>State</i> '
<i>returnedMission</i> ' = <i>false</i>

**protected** *getNextMission*  $\hat{=}$  **var** *ret* : *MissionID* •

$\left( \begin{array}{l} \text{if } (\neg \text{returnedMission} = \mathbf{True}) \longrightarrow \\ \quad \left( \begin{array}{l} \text{this}.\text{returnedMission} := \text{true}; \\ \text{ret} := \text{MainMission} \end{array} \right) \\ \parallel \neg (\neg \text{returnedMission} = \mathbf{True}) \longrightarrow \\ \quad (\text{ret} := \text{nullMissionId}) \\ \text{fi} \end{array} \right)$

• **Skip**

**end**

## 5 Missions

### 5.1 MainMission

**section** *MainMissionApp* **parents** *scj\_prelude*, *MissionId*, *MissionIds*,  
*SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *MainMissionClass*  
, *MainMissionMethChan*

**process** *MainMissionApp*  $\hat{=}$  **begin**

---

*State*  
*this* : **ref** *MainMissionClass*

---

**state** *State*

---

*Init*  
*State'*  


---

*this'* = **new** *MainMissionClass*()

---

*InitializePhase*  $\hat{=}$   

$$\left( \begin{array}{l} \textit{initializeCall} . \textit{MainMission} \longrightarrow \\ \textit{register} ! \textit{ACModeChanger} ! \textit{MainMission} \longrightarrow \\ \textit{register} ! \textit{EnvironmentMonitor} ! \textit{MainMission} \longrightarrow \\ \textit{register} ! \textit{ControlHandler} ! \textit{MainMission} \longrightarrow \\ \textit{register} ! \textit{FlightSensorsMonitor} ! \textit{MainMission} \longrightarrow \\ \textit{register} ! \textit{CommunicationsHandler} ! \textit{MainMission} \longrightarrow \\ \textit{register} ! \textit{AperiodicSimulator} ! \textit{MainMission} \longrightarrow \\ \textit{initializeRet} . \textit{MainMission} \longrightarrow \\ \textbf{Skip} \end{array} \right)$$

*CleanupPhase*  $\hat{=}$   

$$\left( \begin{array}{l} \textit{cleanupMissionCall} . \textit{MainMission} \longrightarrow \\ \textit{cleanupMissionRet} . \textit{MainMission} ! \textbf{True} \longrightarrow \\ \textbf{Skip} \end{array} \right)$$

*getAirSpeedMeth*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  

$$\left( \begin{array}{l} \textit{getAirSpeedCall} . \textit{MainMission} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{getAirSpeed}(); \\ \textit{getAirSpeedRet} . \textit{MainMission} ! \textit{ret} \longrightarrow \\ \textbf{Skip} \end{array} \right)$$

*getAltitudeMeth*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  

$$\left( \begin{array}{l} \textit{getAltitudeCall} . \textit{MainMission} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{getAltitude}(); \\ \textit{getAltitudeRet} . \textit{MainMission} ! \textit{ret} \longrightarrow \\ \textbf{Skip} \end{array} \right)$$

*getCabinPressureMeth*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  

$$\left( \begin{array}{l} \textit{getCabinPressureCall} . \textit{MainMission} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{getCabinPressure}(); \\ \textit{getCabinPressureRet} . \textit{MainMission} ! \textit{ret} \longrightarrow \\ \textbf{Skip} \end{array} \right)$$

$$\text{getEmergencyOxygenMeth} \hat{=} \mathbf{var} \text{ ret} : \mathbb{R} \bullet \left( \begin{array}{l} \text{getEmergencyOxygenCall} . \text{MainMission} \longrightarrow \\ \text{ret} := \text{this} . \text{getEmergencyOxygen}(); \\ \text{getEmergencyOxygenRet} . \text{MainMission} ! \text{ret} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{getFuelRemainingMeth} \hat{=} \mathbf{var} \text{ ret} : \mathbb{R} \bullet \left( \begin{array}{l} \text{getFuelRemainingCall} . \text{MainMission} \longrightarrow \\ \text{ret} := \text{this} . \text{getFuelRemaining}(); \\ \text{getFuelRemainingRet} . \text{MainMission} ! \text{ret} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{getHeadingMeth} \hat{=} \mathbf{var} \text{ ret} : \mathbb{R} \bullet \left( \begin{array}{l} \text{getHeadingCall} . \text{MainMission} \longrightarrow \\ \text{ret} := \text{this} . \text{getHeading}(); \\ \text{getHeadingRet} . \text{MainMission} ! \text{ret} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{setAirSpeedMeth} \hat{=} \left( \begin{array}{l} \text{setAirSpeedCall} . \text{MainMission} ? \text{airSpeed} \longrightarrow \\ \text{this} . \text{setAirSpeed}(\text{airSpeed}); \\ \text{setAirSpeedRet} . \text{MainMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{setAltitudeMeth} \hat{=} \left( \begin{array}{l} \text{setAltitudeCall} . \text{MainMission} ? \text{altitude} \longrightarrow \\ \text{this} . \text{setAltitude}(\text{altitude}); \\ \text{setAltitudeRet} . \text{MainMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{setCabinPressureMeth} \hat{=} \left( \begin{array}{l} \text{setCabinPressureCall} . \text{MainMission} ? \text{cabinPressure} \longrightarrow \\ \text{this} . \text{setCabinPressure}(\text{cabinPressure}); \\ \text{setCabinPressureRet} . \text{MainMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{setEmergencyOxygenMeth} \hat{=} \left( \begin{array}{l} \text{setEmergencyOxygenCall} . \text{MainMission} ? \text{emergencyOxygen} \longrightarrow \\ \text{this} . \text{setEmergencyOxygen}(\text{emergencyOxygen}); \\ \text{setEmergencyOxygenRet} . \text{MainMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{setFuelRemainingMeth} \hat{=} \left( \begin{array}{l} \text{setFuelRemainingCall} . \text{MainMission} ? \text{fuelRemaining} \longrightarrow \\ \text{this} . \text{setFuelRemaining}(\text{fuelRemaining}); \\ \text{setFuelRemainingRet} . \text{MainMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{setHeadingMeth} \hat{=} \left( \begin{array}{l} \text{setHeadingCall} . \text{MainMission} ? \text{heading} \longrightarrow \\ \text{this} . \text{setHeading}(\text{heading}); \\ \text{setHeadingRet} . \text{MainMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$Methods \hat{=} \left( \begin{array}{l} InitializePhase \\ \square \\ CleanupPhase \\ \square \\ getAirSpeedMeth \\ \square \\ getAltitudeMeth \\ \square \\ getCabinPressureMeth \\ \square \\ getEmergencyOxygenMeth \\ \square \\ getFuelRemainingMeth \\ \square \\ getHeadingMeth \\ \square \\ setAirSpeedMeth \\ \square \\ setAltitudeMeth \\ \square \\ setCabinPressureMeth \\ \square \\ setEmergencyOxygenMeth \\ \square \\ setFuelRemainingMeth \\ \square \\ setHeadingMeth \end{array} \right) ; Methods$$

- $(Init ; Methods) \triangle (end\_mission\_app . MainMission \longrightarrow \mathbf{Skip})$

**end**

**class** *MainMissionClass*  $\hat{=}$  **begin**

**state** *State*

*ALTITUDE\_READING\_ON\_GROUND* :  $\mathbb{R}$   
*test* :  $\mathbb{Z}$   
*cabinPressure* :  $\mathbb{R}$   
*emergencyOxygen* :  $\mathbb{R}$   
*fuelRemaining* :  $\mathbb{R}$   
*altitude* :  $\mathbb{R}$   
*airSpeed* :  $\mathbb{R}$   
*heading* :  $\mathbb{R}$

**state** *State*

**initial** *Init*

*State'*  
*ALTITUDE\_READING\_ON\_GROUND'* = 0.0  
*test'* = 0

**public** *getAirSpeed*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  
(*ret* := *airSpeed*)

**public** *getAltitude*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  
(*ret* := *altitude*)

**public** *getCabinPressure*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  
(*ret* := *cabinPressure*)

**public** *getEmergencyOxygen*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  
(*ret* := *emergencyOxygen*)

**public** *getFuelRemaining*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  
(*ret* := *fuelRemaining*)

**public** *getHeading*  $\hat{=}$  **var** *ret* :  $\mathbb{R}$  •  
(*ret* := *heading*)

**public** *setAirSpeed*  $\hat{=}$   
(*this.this.airSpeed* := *airSpeed*)

**public** *setAltitude*  $\hat{=}$   
(*this.this.altitude* := *altitude*)

**public** *setCabinPressure*  $\hat{=}$   
(*this.this.cabinPressure* := *cabinPressure*)

**public** *setEmergencyOxygen*  $\hat{=}$   
(*this.this.emergencyOxygen* := *emergencyOxygen*)



```
public setFuelRemaining  $\hat{=}$   
(this.this.fuelRemaining := fuelRemaining)
```

```
public setHeading  $\hat{=}$   
(this.this.heading := heading)
```

- **Skip**

```
end
```

## 5.2 Schedulables of MainMission

**section** *ACModeChangerApp* **parents** *TopLevelMissionSequencerChan*,  
*MissionId*, *MissionIds*, *SchedulableId*, *ACModeChangerClass*

**process** *ACModeChangerApp*  $\hat{=}$   
*controllingMission* : *MissionID* • **begin**

*GetNextMission*  $\hat{=}$  **var** *ret* : *MissionID* •  
 $\left( \begin{array}{l} \textit{getNextMissionCall} . \textit{ACModeChanger} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{getNextMission}(); \\ \textit{getNextMissionRet} . \textit{ACModeChanger} ! \textit{ret} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$

*Methods*  $\hat{=}$   
 $(\textit{GetNextMission}) ; \textit{Methods}$

•  $(\textit{Methods}) \triangle (\textit{end\_sequencer\_app} . \textit{ACModeChanger} \longrightarrow \mathbf{Skip})$

**end**

**class** *ACModeChangerClass*  $\hat{=}$  **begin**

**state** *State*

*controllingMission* : *MainMission*  
*modesLeft* :  $\mathbb{Z}$

**state** *State*

**initial** *Init*

*State'*

*modesLeft'* = 3

**protected** *getNextMission*  $\hat{=}$  **var** *ret* : *MissionID* •

$$\left( \begin{array}{l} \text{if } (modesLeft = 3) \longrightarrow \\ \quad \left( \begin{array}{l} modesLeft := modesLeft - 1; \\ ret := TakeOffMission \end{array} \right) \\ \square \neg (modesLeft = 3) \longrightarrow \\ \quad \text{if } (modesLeft = 2) \longrightarrow \\ \quad \quad \left( \begin{array}{l} modesLeft := modesLeft - 1; \\ ret := CruiseMission \end{array} \right) \\ \square \neg (modesLeft = 2) \longrightarrow \\ \quad \text{if } (modesLeft = 1) \longrightarrow \\ \quad \quad \left( \begin{array}{l} modesLeft := modesLeft - 1; \\ ret := LandMission \end{array} \right) \\ \square \neg (modesLeft = 1) \longrightarrow \\ \quad \quad (ret := nullMissionId) \\ \text{fi} \\ \text{fi} \\ \text{fi} \end{array} \right)$$

• **Skip**

**end**

**section** *ControlHandlerApp* **parents** *AperiodicEventHandlerChan, SchedulableId, SchedulableIds*

**process** *ControlHandlerApp*  $\hat{=}$  **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{ControlHandler} \longrightarrow \\ (\mathbf{Skip}) ; \\ \text{handleAsyncEventRet} . \text{ControlHandler} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
 $(\text{handlerAsyncEvent}) ; \text{Methods}$

•  $(\text{Methods}) \triangle (\text{end\_aperiodic\_app} . \text{ControlHandler} \longrightarrow \mathbf{Skip})$

**end**

**section** *CommunicationsHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*

**process** *CommunicationsHandlerApp*  $\hat{=}$  **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{CommunicationsHandler} \longrightarrow \\ (\mathbf{Skip}) ; \\ \text{handleAsyncEventRet} . \text{CommunicationsHandler} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
 $(\text{handlerAsyncEvent}) ; \text{Methods}$

•  $(\text{Methods}) \triangle (\text{end\_aperiodic\_app} . \text{CommunicationsHandler} \longrightarrow \mathbf{Skip})$

**end**

**section** *EnvironmentMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*MainMissionMethChan*

**process** *EnvironmentMonitorApp*  $\hat{=}$   
*mainMission* : *MissionID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{EnvironmentMonitor} \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \text{setCabinPressureCall} . \text{controllingMission} ! 0 \longrightarrow \\ \text{setCabinPressureRet} . \text{controllingMission} \longrightarrow \\ \mathbf{Skip}; \\ \text{setEmergencyOxygenCall} . \text{controllingMission} ! 0 \longrightarrow \\ \text{setEmergencyOxygenRet} . \text{controllingMission} \longrightarrow \\ \mathbf{Skip}; \\ \text{setFuelRemainingCall} . \text{controllingMission} ! 0 \longrightarrow \\ \text{setFuelRemainingRet} . \text{controllingMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right) \\ \text{handleAsyncEventRet} . \text{EnvironmentMonitor} \longrightarrow \\ \mathbf{Skip} \end{array} \right) ;$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_periodic\_app* . *EnvironmentMonitor*  $\longrightarrow$  **Skip**)

**end**

**class** *EnvironmentMonitorClass*  $\hat{=}$  **begin**

**state** *State*

*controllingMission* : *MainMission*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

**section** *FlightSensorsMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*MainMissionMethChan*

**process** *FlightSensorsMonitorApp*  $\hat{=}$   
*mainMission* : *MissionID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{FlightSensorsMonitor} \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \text{setAirSpeedCall} . \text{controllingMission} ! 0 \longrightarrow \\ \text{setAirSpeedRet} . \text{controllingMission} \longrightarrow \\ \mathbf{Skip}; \\ \text{setAltitudeCall} . \text{controllingMission} ! 0 \longrightarrow \\ \text{setAltitudeRet} . \text{controllingMission} \longrightarrow \\ \mathbf{Skip}; \\ \text{setHeadingCall} . \text{controllingMission} ! 0 \longrightarrow \\ \text{setHeadingRet} . \text{controllingMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right) ; \\ \text{handleAsyncEventRet} . \text{FlightSensorsMonitor} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_periodic\_app* . *FlightSensorsMonitor*  $\longrightarrow$  **Skip**)

**end**



**class** *FlightSensorsMonitorClass*  $\hat{=}$  **begin**

**state** *State*

*controllingMission* : *MainMission*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

**section** *AperiodicSimulatorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*

**process** *AperiodicSimulatorApp*  $\hat{=}$   
*aperiodicEvent* : *SchedulableID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{AperiodicSimulator} \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \text{releaseCall} . \text{event} \longrightarrow \\ \text{releaseRet} . \text{event} ? \text{release} \longrightarrow \end{array} \right); \\ \mathbf{Skip} \\ \text{handleAsyncEventRet} . \text{AperiodicSimulator} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_periodic\_app* . *AperiodicSimulator*  $\longrightarrow$  **Skip**)

**end**

**class** *AperiodicSimulatorClass*  $\hat{=}$  **begin**

**state** *State*

*event* : *AperiodicEventHandler*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

### 5.3 TakeOffMission

**section** *TakeOffMissionApp* **parents** *scj\_prelude*, *MissionId*, *MissionIds*,  
*SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *TakeOffMissionClass*  
*, TakeOffMissionMethChan*

**process** *TakeOffMissionApp*  $\hat{=}$   
*controllingMission* : *MissionID* • **begin**

---

*State*  
*this* : **ref** *TakeOffMissionClass*

---

**state** *State*

---

*Init*  
*State'*  


---

*this'* = **new** *TakeOffMissionClass*()

---

*InitializePhase*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{initializeCall} . \textit{TakeOffMission} \longrightarrow \\ \textit{register} ! \textit{LandingGearHandlerTakeOff} ! \textit{TakeOffMission} \longrightarrow \\ \textit{register} ! \textit{TakeOffMonitor} ! \textit{TakeOffMission} \longrightarrow \\ \textit{register} ! \textit{TakeOffFailureHandler} ! \textit{TakeOffMission} \longrightarrow \\ \textit{initializeRet} . \textit{TakeOffMission} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*CleanupPhase*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{cleanupMissionCall} . \textit{TakeOffMission} \longrightarrow \\ \textit{cleanupMissionRet} . \textit{TakeOffMission} ! \textbf{True} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*abortMeth*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{abortCall} . \textit{TakeOffMission} \longrightarrow \\ \textit{this} . \textit{abort}(); \\ \textit{abortRet} . \textit{TakeOffMission} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*getControllingMissionMeth*  $\hat{=}$  **var** *ret* : *MissionID* •  
 $\left( \begin{array}{l} \textit{getControllingMissionCall} . \textit{TakeOffMission} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{getControllingMission}(); \\ \textit{getControllingMissionRet} . \textit{TakeOffMission} ! \textit{ret} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*setControllingMissionMeth*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{setControllingMissionCall} . \textit{TakeOffMission} ? \textit{controllingMission} \longrightarrow \\ \textit{this} . \textit{setControllingMission}(\textit{controllingMission}); \\ \textit{setControllingMissionRet} . \textit{TakeOffMission} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

$$\text{cleanUpMeth} \hat{=} \mathbf{var} \text{ ret} : \mathbb{B} \bullet \left( \begin{array}{l} \text{cleanUpCall} . \text{TakeOffMission} \longrightarrow \\ \text{ret} := \text{this} . \text{cleanUp}(); \\ \text{cleanUpRet} . \text{TakeOffMission} ! \text{ret} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{stowLandingGearMeth} \hat{=} \left( \begin{array}{l} \text{stowLandingGearCall} . \text{TakeOffMission} \longrightarrow \\ \text{this} . \text{stowLandingGear}(); \\ \text{stowLandingGearRet} . \text{TakeOffMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{isLandingGearDeployedMeth} \hat{=} \mathbf{var} \text{ ret} : \mathbb{B} \bullet \left( \begin{array}{l} \text{isLandingGearDeployedCall} . \text{TakeOffMission} \longrightarrow \\ \text{ret} := \text{this} . \text{isLandingGearDeployed}(); \\ \text{isLandingGearDeployedRet} . \text{TakeOffMission} ! \text{ret} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{deployLandingGearSyncMeth} \hat{=} \left( \begin{array}{l} \text{deployLandingGearCall} . \text{TakeOffMission} ? \text{thread} \longrightarrow \\ \left( \begin{array}{l} \text{startSyncMeth} . \text{TakeOffMissionObject} . \text{thread} \longrightarrow \\ \text{lockAcquired} . \text{TakeOffMissionObject} . \text{thread} \longrightarrow \\ (\text{this} . \text{landingGearDeployed} := \text{true}); \\ \text{endSyncMeth} . \text{TakeOffMissionObject} . \text{thread} \longrightarrow \\ \text{deployLandingGearRet} . \text{TakeOffMission} . \text{thread} \longrightarrow \end{array} \right) \\ \mathbf{Skip} \end{array} \right)$$

$$\text{Methods} \hat{=} \left( \begin{array}{l} \text{InitializePhase} \\ \square \\ \text{CleanupPhase} \\ \square \\ \text{abortMeth} \\ \square \\ \text{getControllingMissionMeth} \\ \square \\ \text{setControllingMissionMeth} \\ \square \\ \text{cleanUpMeth} \\ \square \\ \text{stowLandingGearMeth} \\ \square \\ \text{isLandingGearDeployedMeth} \\ \square \\ \text{deployLandingGearSyncMeth} \end{array} \right) ; \text{Methods}$$

$$\bullet (\text{Init} ; \text{Methods}) \triangle (\text{end\_mission\_app} . \text{TakeOffMission} \longrightarrow \mathbf{Skip})$$

**end**

**class** *TakeOffMissionClass*  $\hat{=}$  **begin**

**state** *State*

---

*SAFE\_AIRSPPEED\_THRESHOLD* :  $\mathbb{R}$   
*TAKEOFF\_ALTITUDE* :  $\mathbb{R}$   
*controllingMission* : *MainMission*  
*abort* :  $\mathbb{B}$   
*landingGearDeployed* :  $\mathbb{B}$

---

**state** *State*

**initial** *Init*

*State'*

---

*SAFE\_AIRSPPEED\_THRESHOLD'* = 10.0  
*TAKEOFF\_ALTITUDE'* = 10.0  
*abort'* = *false*

---

**public** *abort*  $\hat{=}$   
(*this* . *abort* := *true*)

**public** *getControllingMission*  $\hat{=}$  **var** *ret* : *MissionID* •  
(*ret* := *controllingMission*)

**public** *setControllingMission*  $\hat{=}$   
(*this* . *this* . *controllingMission* := *controllingMission*)

**public** *cleanUp*  $\hat{=}$  **var** *ret* :  $\mathbb{B}$  •  
(**Skip**;  
*ret* := ( $\neg$  *abort* = **True**))

**public** *stowLandingGear*  $\hat{=}$   
(*this* . *landingGearDeployed* := *false*)

**public** *isLandingGearDeployed*  $\hat{=}$  **var** *ret* :  $\mathbb{B}$  •  
(*ret* := *landingGearDeployed* = **True**)

• **Skip**

**end**

**section** *TakeOffMissionMethChan* **parents** *scj\_prelude, GlobalTypes, MissionId, SchedulableId*

**channel** *abortCall* : *SchedulableID*  
**channel** *abortRet* : *SchedulableID*

**channel** *getControllingMissionCall* : *SchedulableID*  
**channel** *getControllingMissionRet* : *SchedulableID*  $\times$  *MissionID*

**channel** *setControllingMissionCall* : *SchedulableID*  $\times$  *MissionID*  
**channel** *setControllingMissionRet* : *SchedulableID*

**channel** *cleanUpCall* : *SchedulableID*  
**channel** *cleanUpRet* : *SchedulableID*  $\times$   $\mathbb{B}$

**channel** *stowLandingGearCall* : *SchedulableID*  
**channel** *stowLandingGearRet* : *SchedulableID*

**channel** *isLandingGearDeployedCall* : *SchedulableID*  
**channel** *isLandingGearDeployedRet* : *SchedulableID*  $\times$   $\mathbb{B}$

**channel** *deployLandingGearCall* : *SchedulableID*  $\times$  *ThreadID*  
**channel** *deployLandingGearRet* : *SchedulableID*  $\times$  *ThreadID*

## 5.4 Schedulables of TakeOffMission

**section** *LandingGearHandlerTakeOffApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*TakeOffMissionMethChan*, *ObjectIds*, *ThreadIds*

**process** *LandingGearHandlerTakeOffApp*  $\hat{=}$   
*mission* : *MissionID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{LandingGearHandlerTakeOff} \longrightarrow \\ \left( \begin{array}{l} \text{Skip}; \\ \text{isLandingGearDeployedCall} . \text{mission} \longrightarrow \\ \text{isLandingGearDeployedRet} . \text{mission} ? \text{isLandingGearDeployed} \longrightarrow \\ \\ \text{var landingGearIsDeployed} : \mathbb{B} \bullet \text{landingGearIsDeployed} := \text{isLandingGearDeployed} \\ \text{if landingGearIsDeployed} = \text{True} \longrightarrow \\ \left( \begin{array}{l} \text{stowLandingGearCall} . \text{mission} \longrightarrow \\ \text{stowLandingGearRet} . \text{mission} \longrightarrow \\ \text{Skip} \end{array} \right) \\ \square \neg \text{landingGearIsDeployed} = \text{True} \longrightarrow \\ \left( \begin{array}{l} \text{deployLandingGearCall} . \text{mission} . \text{LandingGearHandlerTakeOffThread} \longrightarrow \\ \text{deployLandingGearRet} . \text{mission} . \text{LandingGearHandlerTakeOffThread} \longrightarrow \\ \text{Skip} \end{array} \right) \\ \text{fi} \end{array} \right) \text{handleAsyncEventRet} . \text{LandingGearHandlerTakeOff} \longrightarrow \\ \text{Skip} \end{array} \right);$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_aperiodic\_app* . *LandingGearHandlerTakeOff*  $\longrightarrow$  **Skip**)

**end**



**class** *LandingGearHandlerTakeOffClass*  $\hat{=}$  **begin**

**state** *State*

*mission* : *TakeOffMission*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

**section** *TakeOffFailureHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*MainMissionMethChan*, *TakeOffMissionMethChan*

**process** *TakeOffFailureHandlerApp*  $\hat{=}$   
*mainMission* : *MissionID*,  
*takeoffMission* : *MissionID*,  
*threshold* : *Double* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{TakeOffFailureHandler} \longrightarrow \\ \left( \begin{array}{l} \text{getAirSpeedCall} . \text{mainMission} \longrightarrow \\ \text{getAirSpeedRet} . \text{mainMission} ? \text{getAirSpeed} \longrightarrow \end{array} \right) \\ \\ \mathbf{var} \text{ currentSpeed} : \mathbb{R} \bullet \text{currentSpeed} := \text{getAirSpeed} \\ \mathbf{if} (\text{currentSpeed} < \text{threshold}) \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \left( \begin{array}{l} \text{abortCall} . \text{takeoffMission} \longrightarrow \\ \text{abortRet} . \text{takeoffMission} \longrightarrow \end{array} \right) \\ \mathbf{Skip}; \\ \left( \begin{array}{l} \text{requestTerminationCall} . \text{takeoffMission} \longrightarrow \\ \text{requestTerminationRet} . \text{takeoffMission} ? \text{requestTermination} \longrightarrow \end{array} \right) \\ \mathbf{Skip} \end{array} \right) \\ \parallel \neg (\text{currentSpeed} < \text{threshold}) \longrightarrow \\ (\mathbf{Skip}) \\ \mathbf{fi} \mathbf{Skip} \end{array} \right) ;$$
  

$$\left( \begin{array}{l} \text{handleAsyncEventRet} . \text{TakeOffFailureHandler} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_aperiodic\_app* . *TakeOffFailureHandler*  $\longrightarrow$  **Skip**)

**end**

**class** *TakeOffFailureHandlerClass*  $\hat{=}$  **begin**

**state** *State*

*mainMission* : *MainMission*  
*takeoffMission* : *TakeOffMission*  
*threshold* :  $\mathbb{R}$

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

**section** *TakeOffMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*MainMissionMethChan*

**process** *TakeOffMonitorApp*  $\hat{=}$   
*mainMission* : *MissionID*,  
*takeOffMission* : *MissionID*,  
*takeOffAltitude* :  $\mathbb{R}$ ,  
*landingGearHandler* : *SchedulableID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   
 $\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{TakeOffMonitor} \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \text{getAltitudeCall} . \text{mainMission} \longrightarrow \\ \text{getAltitudeRet} . \text{mainMission} ? \text{getAltitude} \longrightarrow \\ \\ \mathbf{var} \text{altitude} : \mathbb{R} \bullet \text{altitude} := \text{getAltitude} \\ \mathbf{if} (\text{altitude} > \text{takeOffAltitude}) \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \text{releaseCall} . \text{landingGearHandler} \longrightarrow \\ \text{releaseRet} . \text{landingGearHandler} ? \text{release} \longrightarrow \\ \text{requestTerminationCall} . \text{takeoffMission} \longrightarrow \\ \text{requestTerminationRet} . \text{takeoffMission} ? \text{requestTermination} \longrightarrow \\ \mathbf{Skip} \end{array} \right) ; \\ \mathbb{I} \neg (\text{altitude} > \text{takeOffAltitude}) \longrightarrow \mathbf{Skip} \\ \mathbf{fi}; \\ \mathbf{Skip} \end{array} \right) \\ \text{handleAsyncEventRet} . \text{TakeOffMonitor} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_periodic\_app* . *TakeOffMonitor*  $\longrightarrow$  **Skip**)

**end**

**class** *TakeOffMonitorClass*  $\hat{=}$  **begin**

**state** *State*

*mainMission* : *MainMission*

*takeoffMission* : *TakeOffMission*

*takeOffAltitude* :  $\mathbb{R}$

*landingGearHandler* : *AperiodicEventHandler*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

## 5.5 CruiseMission

**section** *CruiseMissionApp* **parents** *scj\_prelude*, *MissionId*, *MissionIds*,  
*SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *CruiseMissionClass*  
*CruiseMissionMethChan*

**process** *CruiseMissionApp*  $\hat{=}$   
*controllingMission* : *MissionID* • **begin**

---

*State*  
*this* : **ref** *CruiseMissionClass*

---

**state** *State*

---

*Init*  
*State'*  


---

*this'* = **new** *CruiseMissionClass*()

---

*InitializePhase*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{initializeCall} . \textit{CruiseMission} \longrightarrow \\ \textit{register!BeginLandingHandler!CruiseMission} \longrightarrow \\ \textit{register!NavigationMonitor!CruiseMission} \longrightarrow \\ \textit{initializeRet} . \textit{CruiseMission} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*CleanupPhase*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{cleanupMissionCall} . \textit{CruiseMission} \longrightarrow \\ \textit{cleanupMissionRet} . \textit{CruiseMission!True} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*getControllingMissionMeth*  $\hat{=}$  **var** *ret* : *MissionID* •  
 $\left( \begin{array}{l} \textit{getControllingMissionCall} . \textit{CruiseMission} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{getControllingMission}(); \\ \textit{getControllingMissionRet} . \textit{CruiseMission!ret} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*Methods*  $\hat{=}$   $\left( \begin{array}{l} \textit{InitializePhase} \\ \square \\ \textit{CleanupPhase} \\ \square \\ \textit{getControllingMissionMeth} \end{array} \right)$  ; *Methods*

• (*Init* ; *Methods*)  $\triangle$  (*end\_mission\_app* . *CruiseMission*  $\longrightarrow$  **Skip**)

**end**

**class** *CruiseMissionClass*  $\hat{=}$  **begin**

**state** *State*

*controllingMission* : *MainMission*

**state** *State*

**initial** *Init*

*State'*

**public** *getControllingMission*  $\hat{=}$  **var** *ret* : *MissionID* •  
(*ret* := *controllingMission*)

• **Skip**

**end**

## 5.6 Schedulables of CruiseMission

**section** *BeginLandingHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*

**process** *BeginLandingHandlerApp*  $\hat{=}$   
*controllingMission* : *MissionID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{BeginLandingHandler} \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \text{requestTerminationCall} . \text{controllingMission} \longrightarrow \\ \text{requestTerminationRet} . \text{controllingMission} ? \text{requestTermination} \longrightarrow \\ \mathbf{Skip} \end{array} \right) ; \\ \text{handleAsyncEventRet} . \text{BeginLandingHandler} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_aperiodic\_app* . *BeginLandingHandler*  $\longrightarrow$  **Skip**)

**end**



**class** *BeginLandingHandlerClass*  $\hat{=}$  **begin**

**state** *State*

*controllingMission* : *Mission*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

**section** *NavigationMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*MainMissionMethChan*

**process** *NavigationMonitorApp*  $\hat{=}$   
*mainMission* : *MissionID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{NavigationMonitor} \longrightarrow \\ \left( \begin{array}{l} \text{getHeadingCall} . \text{mainMission} \longrightarrow \\ \text{getHeadingRet} . \text{mainMission} ? \text{getHeading} \longrightarrow \\ \\ \text{var heading} : \mathbb{R} \bullet \text{heading} := \text{getHeading} \\ \text{getAirSpeedCall} . \text{mainMission} \longrightarrow \\ \text{getAirSpeedRet} . \text{mainMission} ? \text{getAirSpeed} \longrightarrow \\ \\ \text{var airSpeed} : \mathbb{R} \bullet \text{airSpeed} := \text{getAirSpeed} \\ \text{getAltitudeCall} . \text{mainMission} \longrightarrow \\ \text{getAltitudeRet} . \text{mainMission} ? \text{getAltitude} \longrightarrow \\ \\ \text{var altitude} : \mathbb{R} \bullet \text{altitude} := \text{getAltitude} \\ \text{Skip} \end{array} \right) ; \\ \text{handleAsyncEventRet} . \text{NavigationMonitor} \longrightarrow \\ \text{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_periodic\_app* . *NavigationMonitor*  $\longrightarrow$  **Skip**)

**end**

**class** *NavigationMonitorClass*  $\hat{=}$  **begin**

**state** *State*

*mainMission* : *MainMission*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

## 5.7 LandMission

**section** *LandMissionApp* **parents** *scj\_prelude*, *MissionId*, *MissionIds*,  
*SchedulableId*, *SchedulableIds*, *MissionChan*, *SchedulableMethChan*, *LandMissionClass*  
*LandMissionMethChan*

**process** *LandMissionApp*  $\hat{=}$   
*controllingMission* : *MissionID* • **begin**

---

*State*  
*this* : **ref** *LandMissionClass*

---

**state** *State*

---

*Init*  
*State'*  


---

*this'* = **new** *LandMissionClass*()

---

*InitializePhase*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{initializeCall} . \textit{LandMission} \longrightarrow \\ \textit{register} ! \textit{GroundDistanceMonitor} ! \textit{LandMission} \longrightarrow \\ \textit{register} ! \textit{LandingGearHandlerLand} ! \textit{LandMission} \longrightarrow \\ \textit{register} ! \textit{InstrumentLandingSystemMonitor} ! \textit{LandMission} \longrightarrow \\ \textit{register} ! \textit{SafeLandingHandler} ! \textit{LandMission} \longrightarrow \\ \textit{initializeRet} . \textit{LandMission} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*CleanupPhase*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{cleanupMissionCall} . \textit{LandMission} \longrightarrow \\ \textit{cleanupMissionRet} . \textit{LandMission} ! \textbf{True} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*stowLandingGearMeth*  $\hat{=}$   
 $\left( \begin{array}{l} \textit{stowLandingGearCall} . \textit{LandMission} \longrightarrow \\ \textit{this} . \textit{stowLandingGear}(); \\ \textit{stowLandingGearRet} . \textit{LandMission} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*isLandingGearDeployedMeth*  $\hat{=}$  **var** *ret* :  $\mathbb{B}$  •  
 $\left( \begin{array}{l} \textit{isLandingGearDeployedCall} . \textit{LandMission} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{isLandingGearDeployed}(); \\ \textit{isLandingGearDeployedRet} . \textit{LandMission} ! \textit{ret} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

*getControllingMissionMeth*  $\hat{=}$  **var** *ret* : *MissionID* •  
 $\left( \begin{array}{l} \textit{getControllingMissionCall} . \textit{LandMission} \longrightarrow \\ \textit{ret} := \textit{this} . \textit{getControllingMission}(); \\ \textit{getControllingMissionRet} . \textit{LandMission} ! \textit{ret} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

$$\text{abortMeth} \hat{=} \left( \begin{array}{l} \text{abortCall} . \text{LandMission} \longrightarrow \\ \text{this} . \text{abort}(); \\ \text{abortRet} . \text{LandMission} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{cleanUpMeth} \hat{=} \mathbf{var} \text{ ret} : \mathbb{B} \bullet \left( \begin{array}{l} \text{cleanUpCall} . \text{LandMission} \longrightarrow \\ \text{ret} := \text{this} . \text{cleanUp}(); \\ \text{cleanUpRet} . \text{LandMission} ! \text{ret} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\text{deployLandingGearSyncMeth} \hat{=} \left( \begin{array}{l} \text{deployLandingGearCall} . \text{LandMission} ? \text{thread} \longrightarrow \\ \left( \begin{array}{l} \text{startSyncMeth} . \text{LandMissionObject} . \text{thread} \longrightarrow \\ \text{lockAcquired} . \text{LandMissionObject} . \text{thread} \longrightarrow \\ (\text{this} . \text{landingGearDeployed} := \text{true}); \\ \text{endSyncMeth} . \text{LandMissionObject} . \text{thread} \longrightarrow \\ \text{deployLandingGearRet} . \text{LandMission} . \text{thread} \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array} \right)$$

$$\text{Methods} \hat{=} \left( \begin{array}{l} \text{InitializePhase} \\ \square \\ \text{CleanupPhase} \\ \square \\ \text{stowLandingGearMeth} \\ \square \\ \text{isLandingGearDeployedMeth} \\ \square \\ \text{getControllingMissionMeth} \\ \square \\ \text{abortMeth} \\ \square \\ \text{cleanUpMeth} \\ \square \\ \text{deployLandingGearSyncMeth} \end{array} \right) ; \text{Methods}$$

$$\bullet (\text{Init} ; \text{Methods}) \triangle (\text{end\_mission\_app} . \text{LandMission} \longrightarrow \mathbf{Skip})$$

**end**

**class** *LandMissionClass*  $\hat{=}$  **begin**

**state** *State*

*controllingMission* : *MainMission*  
*SAFE\_LANDING\_ALTITUDE* :  $\mathbb{R}$   
*abort* :  $\mathbb{B}$   
*landingGearDeployed* :  $\mathbb{B}$

**state** *State*

**initial** *Init*

*State'*

*SAFE\_LANDING\_ALTITUDE'* = 10.0  
*abort'* = *false*

**public** *stowLandingGear*  $\hat{=}$   
(*this* . *landingGearDeployed* := *false*)

**public** *isLandingGearDeployed*  $\hat{=}$  **var** *ret* :  $\mathbb{B}$  •  
(*ret* := *landingGearDeployed* = **True**)

**public** *getControllingMission*  $\hat{=}$  **var** *ret* : *MissionID* •  
(*ret* := *controllingMission*)

**public** *abort*  $\hat{=}$   
(*this* . *abort* := *true*)

**public** *cleanUp*  $\hat{=}$  **var** *ret* :  $\mathbb{B}$  •  
(**Skip**;  
*ret* := ( $\neg$  *abort* = **True**))

• **Skip**

**end**

**section** *LandMissionMethChan* **parents** *scj\_prelude, GlobalTypes, MissionId, SchedulableId*

**channel** *stowLandingGearCall* : *SchedulableID*

**channel** *stowLandingGearRet* : *SchedulableID*

**channel** *isLandingGearDeployedCall* : *SchedulableID*

**channel** *isLandingGearDeployedRet* : *SchedulableID*  $\times$   $\mathbb{B}$

**channel** *getControllingMissionCall* : *SchedulableID*

**channel** *getControllingMissionRet* : *SchedulableID*  $\times$  *MissionID*

**channel** *abortCall* : *SchedulableID*

**channel** *abortRet* : *SchedulableID*

**channel** *cleanUpCall* : *SchedulableID*

**channel** *cleanUpRet* : *SchedulableID*  $\times$   $\mathbb{B}$

**channel** *deployLandingGearCall* : *SchedulableID*  $\times$  *ThreadID*

**channel** *deployLandingGearRet* : *SchedulableID*  $\times$  *ThreadID*

## 5.8 Schedulables of LandMission

**section** *LandingGearHandlerLandApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*LandMissionMethChan*, *ObjectIds*, *ThreadIds*

**process** *LandingGearHandlerLandApp*  $\hat{=}$   
*mission* : *MissionID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{LandingGearHandlerLand} \longrightarrow \\ \left( \begin{array}{l} \text{Skip}; \\ \text{isLandingGearDeployedCall} . \text{mission} \longrightarrow \\ \text{isLandingGearDeployedRet} . \text{mission} ? \text{isLandingGearDeployed} \longrightarrow \\ \\ \text{var } \text{landingGearIsDeployed} : \mathbb{B} \bullet \text{landingGearIsDeployed} := \text{isLandingGearDeployed} \\ \text{if } \text{landingGearIsDeployed} = \text{True} \longrightarrow \\ \quad \left( \begin{array}{l} \text{stowLandingGearCall} . \text{mission} \longrightarrow \\ \text{stowLandingGearRet} . \text{mission} \longrightarrow \\ \text{Skip} \end{array} \right) \\ \quad \parallel \neg \text{landingGearIsDeployed} = \text{True} \longrightarrow \\ \quad \quad \left( \begin{array}{l} \text{deployLandingGearCall} . \text{mission} . \text{LandingGearHandlerLandThread} \longrightarrow \\ \text{deployLandingGearRet} . \text{mission} . \text{LandingGearHandlerLandThread} \longrightarrow \\ \text{Skip} \end{array} \right) \\ \text{fi} \end{array} \right) \\ \text{handleAsyncEventRet} . \text{LandingGearHandlerLand} \longrightarrow \\ \text{Skip} \end{array} \right);$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_aperiodic\_app* . *LandingGearHandlerLand*  $\longrightarrow$  **Skip**)

**end**



**class** *LandingGearHandlerLandClass*  $\hat{=}$  **begin**

**state** *State*

*mission* : *LandMission*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

**section** *SafeLandingHandlerApp* **parents** *AperiodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*MainMissionMethChan*

**process** *SafeLandingHandlerApp*  $\hat{=}$   
*mainMission* : *MissionID*,  
*threshold* : *Double* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{SafeLandingHandler} \longrightarrow \\ \left( \begin{array}{l} \text{getAltitudeCall} . \text{mainMission} \longrightarrow \\ \text{getAltitudeRet} . \text{mainMission} ? \text{getAltitude} \longrightarrow \end{array} \right) \\ \\ \mathbf{var} \text{altitude} : \mathbb{R} \bullet \text{altitude} := \text{getAltitude} \\ \mathbf{if} (\text{altitude} < \text{threshold}) \longrightarrow \\ \quad (\mathbf{Skip}) \\ \quad \square \neg (\text{altitude} < \text{threshold}) \longrightarrow \\ \quad \quad (\mathbf{Skip}) \\ \mathbf{fi} \\ \text{handleAsyncEventRet} . \text{SafeLandingHandler} \longrightarrow \\ \mathbf{Skip} \end{array} \right) ;$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_aperiodic\_app* . *SafeLandingHandler*  $\longrightarrow$  **Skip**)

**end**

**class** *SafeLandingHandlerClass*  $\hat{=}$  **begin**

**state** *State*

*mainMission* : *MainMission*

*threshold* :  $\mathbb{R}$

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

**section** *GroundDistanceMonitorApp* **parents** *PeriodicEventHandlerChan*, *SchedulableId*, *SchedulableIds*  
*MainMissionMethChan*

**process** *GroundDistanceMonitorApp*  $\hat{=}$   
*mainMission* : *MissionID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{GroundDistanceMonitor} \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \text{getAltitudeCall} . \text{mainMission} \longrightarrow \\ \text{getAltitudeRet} . \text{mainMission} ? \text{getAltitude} \longrightarrow \\ \\ \mathbf{var} \text{ distance} : \mathbb{R} \bullet \text{distance} := \text{getAltitude} \\ \mathbf{if} (\text{distance} = \text{readingOnGround}) \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ \text{requestTerminationCall} . \text{mainMission} \longrightarrow \\ \text{requestTerminationRet} . \text{mainMission} ? \text{requestTermination} \longrightarrow \\ \mathbf{Skip} \end{array} \right) \\ \mathbb{I} \neg (\text{distance} = \text{readingOnGround}) \longrightarrow \mathbf{Skip} \\ \mathbf{fi}; \\ \mathbf{Skip} \end{array} \right) ; \\ \text{handleAsyncEventRet} . \text{GroundDistanceMonitor} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_periodic\_app* . *GroundDistanceMonitor*  $\longrightarrow$  **Skip**)

**end**

**class** *GroundDistanceMonitorClass*  $\hat{=}$  **begin**

**state** *State*

*mainMission* : *MainMission*

*readingOnGround* :  $\mathbb{R}$

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**

**section** *InstrumentLandingSystemMonitorApp* **parents** *PeriodicEventHandlerChan, SchedulableId, SchedulableIds*

**process** *InstrumentLandingSystemMonitorApp*  $\hat{=}$   
*mission* : *MissionID* • **begin**

*handlerAsyncEvent*  $\hat{=}$   

$$\left( \begin{array}{l} \text{handleAsyncEventCall} . \text{InstrumentLandingSystemMonitor} \longrightarrow \\ (\mathbf{Skip}) ; \\ \text{handleAsyncEventRet} . \text{InstrumentLandingSystemMonitor} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

*Methods*  $\hat{=}$   
(*handlerAsyncEvent*) ; *Methods*

• (*Methods*)  $\triangle$  (*end\_periodic\_app* . *InstrumentLandingSystemMonitor*  $\longrightarrow$  **Skip**)

**end**

**class** *InstrumentLandingSystemMonitorClass*  $\hat{=}$  **begin**

**state** *State*

*mission* : *LandMission*

**state** *State*

**initial** *Init*

*State'*

• **Skip**

**end**