aircraft

Tight Rope v0.65

9th March 2016

1 ID Files

1.1 MissionIds

 ${\bf section}\ {\it MissionIds}\ {\bf parents}\ {\it scj_prelude}, {\it MissionId}$

$$\label{lem:main_model} \begin{split} & \textit{MainMissionMID}: \textit{MissionID} \\ & \textit{TakeOffMissionMID}: \textit{MissionID} \\ & \textit{CruiseMissionMID}: \textit{MissionID} \\ & \textit{LandMissionMID}: \textit{MissionID} \end{split}$$

 $distinct \langle null Mission Id, Main Mission MID, Take Off Mission MID, Cruise Mission MID, Land Mission MID \rangle$

1.2 SchedulablesIds

section SchedulableIds parents scj_prelude, SchedulableId

MainMissionSequencerSID : SchedulableID
ACModeChangerSID : SchedulableID
EnvironmentMonitorSID : SchedulableID
ControlHandlerSID : SchedulableID
FlightSensorsMonitorSID : SchedulableID
CommunicationsHandlerSID : SchedulableID
AperiodicSimulatorSID : SchedulableID

Landing Gear Handler Take Off SID: Schedulable ID

 $Take Off Monitor SID: Schedulable ID\\ Take Off Failure Handler SID: Schedulable ID\\ Begin Landing Handler SID: Schedulable ID\\ Navigation Monitor SID: Schedulable ID\\ Ground Distance Monitor SID: Schedulable ID\\ Landing Gear Handler Land SID: Schedulable ID\\$

Instrument Landing System Monitor SID: Schedulable ID

Safe Landing Handler SID: Schedulable ID

 $distinct \langle null Sequencer Id, null Schedulable Id, Main Mission Sequencer SID,$

 $A {\it CMode Changer SID}, Environment Monitor SID,$

Control Handler SID, Flight Sensors Monitor SID,

CommunicationsHandlerSID, AperiodicSimulatorSID,

 $Landing Gear Handler Take O\!f\!f\!SID, \, Take O\!f\!f\!Monitor SID,$

Take Off Failure Handler SID, Begin Landing Handler SID,

 $Navigation Monitor SID, \ Ground Distance Monitor SID,$

Landing Gear Handler Land SID, Instrument Landing System Monitor SID,

SafeLandingHandlerSID

1.3 ThreadIds

${\bf section}\ ThreadIds\ {\bf parents}\ scj_prelude, GlobalTypes$

Instrument Landing System Monitor TID: Thread ID

 $Safe Landing Handler TID: Thread ID \\ Ground Distance Monitor TID: Thread ID \\ Communications Handler TID: Thread ID$

ControlHandlerTID: ThreadID AperiodicSimulatorTID: ThreadID TakeOffFailureHandlerTID: ThreadID LandingGearHandlerLandTID: ThreadID EnvironmentMonitorTID: ThreadID FlightSensorsMonitorTID: ThreadID NavigationMonitorTID: ThreadID ACModeChangerTID: ThreadID BeginLandingHandlerTID: ThreadID

Landing Gear Handler Take Off TID: Thread ID

 $Take Off Monitor TID:\ Thread ID$

 $distinct \langle SafeletTId, nullThreadId,$

Instrument Landing System Monitor TID, Safe Landing Handler TID,

Ground Distance Monitor TID, Communications Handler TID,

Control Handler TID, Aperiodic Simulator TID,

Take Off Failure Handler TID, Landing Gear Handler Land TID,

Environment Monitor TID, Flight Sensors Monitor TID,

NavigationMonitorTID, ACModeChangerTID,

BeginLandingHandlerTID, LandingGearHandlerTakeOffTID,

TakeOffMonitorTID

1.4 ObjectIds

 ${\bf section}\ Object Ids\ {\bf parents}\ scj_prelude, Global Types$

 ${\it Take Off Mission OID: Object ID} \\ {\it Land Mission OID: Object ID}$

 $\overline{\textit{distinct} \langle \textit{TakeOffMissionOID}, \textit{LandMissionOID} \rangle}$

2 Network

2.1 Network Channel Sets

```
section NetworkChannels parents scj_prelude, MissionId, MissionIds,
          SchedulableId, SchedulableIds, FrameworkChan, SafeletChan, MissionChan,
          TopLevel Mission Sequencer FWChan, Aperiodic Event Handler Chan, Managed Thread Chan,
          One Shot Event Handler Chan, Periodic Event Handler Chan, Mission Sequencer Chan,
          ObjecChan, ThreadChan
channelset TerminateSync ==
          \{ schedulables\_terminated, schedulables\_stopped, get\_activeSchedulables \} 
channelset ControlTierSync ==
          \{ | start\_toplevel\_sequencer, done\_toplevel\_sequencer, done\_safeletFW \} 
{f channel set} \ {\it TierSync} ==
          \{ | start\_mission . MainMission, done\_mission . MainMission, \} 
          done\_safeletFW, done\_toplevel\_sequencer
channelset SchedulablesSync ==
          \{|activate\_schedulables, done\_safeletFW, done\_toplevel\_sequencer|\}
channelset ClusterSync ==
          \{|done\_toplevel\_sequencer, done\_safeletFW|\}
channelset AppSync ==
          \{ getSequencerCall, getSequencerRet, initializeApplicationCall, initializeApplicationRet, end\_safelet\_app, \} \}
          initialize Call, initialize Ret, register, cleanup Mission Call, cleanup Mission Ret, end\_mission\_app, and the control of th
          getNextMissionCall, getNextMissionRet, end\_sequencer\_app,
          handleAsyncEventCall, handleAsyncEventRet, end_periodic_app,
          handle A syncLong Event Call, handle A syncLong Event Ret, end\_aperiodic\_app,
          deschedule Call, deschedule Ret, schedule NextRelease, get NextRelease Time Call, get NextRelease Time Ret, end\_one Shot\_lease Time Call, get NextRelease Time Ret, end\_one Shot\_lease Time Call, get NextRelease Time Call, get NextReleas
          runCall, runRet, end\_managedThread\_app,
          set Ceiling Priority, request Termination Call, request Termination Ret, termination Pending Call, termination Pending Ret
          done\_safeletFW, done\_toplevel\_sequencer, signalTerminationCall, signalTerminationRet,
          activate\_schedulables, done\_schedulable, cleanupSchedulableCall, cleanupSchedulableRet
{\bf channel set} \ \mathit{ThreadSync} ==
          \{ raise\_thread\_priority, lower\_thread\_priority, isInterruptedCall, isInterruptedRet, get\_priorityLevel \} \}
channelset LockingSync ==
          \{ lockAcquired, startSyncMeth, endSyncMeth, waitCall, waitRet, notify, isInterruptedCall, isInterruptedRet, \} \}
          interruptedCall, interruptedRet, done\_toplevel\_sequencer, get\_priorityLevel
channelset Tier0Sync ==
          \{|done\_toplevel\_sequencer, done\_safeletFW,
          start_mission. TakeOffMission, done_mission. TakeOffMission,
          initializeRet. TakeOffMission, requestTermination. TakeOffMission. MainMissionSequencer,
          start_mission. CruiseMission, done_mission. CruiseMission,
          initializeRet. CruiseMission, requestTermination. CruiseMission. MainMissionSequencer,
          start_mission . LandMission , done_mission . LandMission ,
          initializeRet. LandMission, requestTermination. LandMission. MainMissionSequencer
```

2.2 MethodCallBinder

 $\begin{array}{l} \textbf{section} \ \ Method Call Binding Channels \ \textbf{parents} \ \ scj_prelude, \ Global Types, Framework Chan, Mission Id, Mission Ids, \\ Schedulable Id, Schedulable Ids, \ Thread Ids \end{array}$

```
\mathbf{channel}\ binder\_setCabinPressureCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
\mathbf{channel}\ binder\_setCabinPressureRet: MissionID \times SchedulableID
setCabinPressureLocs == \{MainMissionMID\}
setCabinPressureCallers == \{EnvironmentMonitorSID\}
\mathbf{channel}\ binder\_setEmergencyOxygenCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
channel binder\_setEmergencyOxygenRet: MissionID \times SchedulableID
setEmergencyOxygenLocs == \{MainMissionMID\}
setEmergencyOxygenCallers == \{EnvironmentMonitorSID\}
channel binder\_setFuelRemainingCall: MissionID \times SchedulableID \times \mathbb{P} \, \mathbb{A}
\mathbf{channel}\ binder\_setFuelRemainingRet: MissionID \times SchedulableID
setFuelRemainingLocs == \{MainMissionMID\}
setFuelRemainingCallers == \{EnvironmentMonitorSID\}
channel binder\_setAirSpeedCall: MissionID \times SchedulableID \times \mathbb{P} A
{\bf channel}\ binder\_setAirSpeedRet: MissionID \times SchedulableID
setAirSpeedLocs == \{MainMissionMID\}
setAirSpeedCallers == \{FlightSensorsMonitorSID\}
channel binder\_setAltitudeCall: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
channel\ binder\_setAltitudeRet: MissionID \times SchedulableID
setAltitudeLocs == \{MainMissionMID\}
setAltitudeCallers == \{FlightSensorsMonitorSID\}
\mathbf{channel}\ binder\_setHeadingCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
{\bf channel}\ binder\_setHeadingRet: MissionID \times SchedulableID
setHeadingLocs == \{MainMissionMID\}
setHeadingCallers == \{FlightSensorsMonitorSID\}
\textbf{channel} \ binder\_isLanding Gear Deployed Call: Mission ID \times Schedulable ID
\mathbf{channel}\ binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times \mathbb{B}
isLandingGearDeployedLocs == \{ TakeOffMissionMID \}
isLandingGearDeployedCallers == \{LandingGearHandlerTakeOffSID\}
```

```
{\bf channel}\ binder\_stowLandingGearCall: MissionID 	imes SchedulableID
{\bf channel}\ binder\_stowLandingGearRet: MissionID 	imes SchedulableID
stowLandingGearLocs == \{ TakeOffMissionMID \}
stowLandingGearCallers == \{LandingGearHandlerTakeOffSID\}
channel\ binder\_deployLandingGearCall: MissionID 	imes SchedulableID 	imes ThreadID
\textbf{channel} \ binder\_deployLandingGearRet: MissionID \times SchedulableID \times ThreadID
deployLandingGearLocs == \{ TakeOffMissionMID \}
deployLandingGearCallers == \{LandingGearHandlerTakeOffSID\}
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAltitudeRet: \mathit{MissionID} \times \mathit{SchedulableID} \times \mathbb{P}\,\mathbb{A}
getAltitudeLocs == \{MainMissionMID\}
getAltitudeCallers == \{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, GroundDistanceMonitorS
\mathbf{channel}\ binder\_getAirSpeedCall: MissionID \times SchedulableID
channel binder\_getAirSpeedRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getAirSpeedLocs == \{MainMissionMID\}
getAirSpeedCallers == \{NavigationMonitorSID, TakeOffFailureHandlerSID\}
\mathbf{channel}\ binder\_abortCall: MissionID \times SchedulableID
{\bf channel}\ binder\_abortRet: MissionID \times SchedulableID
abortLocs == \{ TakeOffMissionMID \}
abortCallers == \{ TakeOffFailureHandlerSID \}
\mathbf{channel}\ binder\_getHeadingCall: MissionID \times SchedulableID
channel binder\_getHeadingRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getHeadingLocs == \{MainMissionMID\}
getHeadingCallers == \{NavigationMonitorSID\}
{\bf channel}\ binder\_isLandingGearDeployedCall: MissionID 	imes SchedulableID
\textbf{channel} \ binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times \mathbb{B}
isLandingGearDeployedLocs == \{LandMissionMID\}
isLandingGearDeployedCallers == \{LandingGearHandlerLandSID\}
\mathbf{channel}\ binder\_stowLandingGearCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_stowLandingGearRet: \mathit{MissionID} \times SchedulableID
```

```
stowLandingGearLocs == \{LandMissionMID\}
stowLandingGearCallers == \{LandingGearHandlerLandSID\}
{\bf channel}\ binder\_deployLandingGearCall: MissionID 	imes SchedulableID 	imes ThreadID
{\bf channel}\ binder\_deployLandingGearRet: MissionID 	imes SchedulableID 	imes ThreadID
deployLandingGearLocs == \{LandMissionMID\}
deployLandingGearCallers == \{LandingGearHandlerLandSID\}
channelset MethodCallBinderSync == \{ | done\_toplevel\_sequencer, \}
binder\_setCabinPressureCall, binder\_setCabinPressureRet,
binder\_setEmergencyOxygenCall, binder\_setEmergencyOxygenRet,
binder\_setFuelRemainingCall, binder\_setFuelRemainingRet,
binder_setAirSpeedCall, binder_setAirSpeedRet,
binder\_setAltitudeCall, binder\_setAltitudeRet,
binder\_setHeadingCall, binder\_setHeadingRet,
binder\_isLandingGearDeployedCall, binder\_isLandingGearDeployedRet,
binder\_stowLandingGearCall, binder\_stowLandingGearRet,
binder\_deployLandingGearCall, binder\_deployLandingGearRet,
binder\_getAltitudeCall, binder\_getAltitudeRet,
binder\_getAirSpeedCall, binder\_getAirSpeedRet,
binder\_abortCall, binder\_abortRet,
binder\_getHeadingCall, binder\_getHeadingRet,
binder\_isLandingGearDeployedCall, binder\_isLandingGearDeployedRet,
binder\_stowLandingGearCall, binder\_stowLandingGearRet,
binder\_deployLandingGearCall, binder\_deployLandingGearRet
{\bf section}\ Method Call Binder\ {\bf parents}\ scj\_prelude, Mission Id, Mission Ids,
    Schedulable Id, Schedulable Ids, Method Call Binding Channels
, Main Mission Meth Chan, Take Off Mission Meth Chan, Land Mission Meth Chan\\
\mathbf{process} \ Method Call Binder \ \widehat{=} \ \mathbf{begin}
setCabinPressure\_MethodBinder \ \widehat{=} 
      binder\_setCabinPressureCall? loc: (loc \in setCabinPressureLocs)? caller: (caller \in setCabinPressureCallers)? p1-
      setCabinPressureCall.loc.caller!p1 \longrightarrow
      setCabinPressureRet.\,loc.\,caller {\longrightarrow}
      binder\_setCabinPressureRet.\,loc.\,caller \longrightarrow
      setCabinPressure\_MethodBinder
setEmergencyOxygen\_MethodBinder \triangleq
      binder\_setEmergencyOxygenCall? loc:(loc \in setEmergencyOxygenLocs)? caller:(caller \in setEmergencyOxygenCocs)?
      setEmergencyOxygenCall. loc. caller! p1—\rightarrow
      setEmergencyOxygenRet.\,loc.\,caller {\longrightarrow}
      binder\_setEmergencyOxygenRet. loc. caller \longrightarrow
      setEmergencyOxygen\_MethodBinder
setFuelRemaining\_MethodBinder \cong
      binder\_setFuelRemainingCall?loc: (loc \in setFuelRemainingLocs)?caller: (caller \in setFuelRemainingCallers)?p1
      setFuelRemainingCall\:.\:loc\:.\:caller\:!\:p1 {\longrightarrow}
      setFuelRemainingRet.loc.caller \longrightarrow
      binder\_setFuelRemainingRet.loc.caller \longrightarrow
      setFuelRemaining\_MethodBinder
```

```
setAirSpeed\_MethodBinder \stackrel{\frown}{=}
       binder\_setAirSpeedCall? loc:(loc \in setAirSpeedLocs)? caller:(caller \in setAirSpeedCallers)? p1 \longrightarrow
       setAirSpeedCall.loc.caller!p1 \longrightarrow
       setAirSpeedRet.loc.caller \longrightarrow
       binder\_setAirSpeedRet.loc.caller \longrightarrow
       setAirSpeed\_MethodBinder
setAltitude\_MethodBinder \triangleq
       binder\_setAltitudeCall?loc: (loc \in setAltitudeLocs)?caller: (caller \in setAltitudeCallers)?p1 \longrightarrow
       setAltitudeCall . loc . caller ! p1 \longrightarrow
       setAltitudeRet.loc.caller \longrightarrow
       binder\_setAltitudeRet . loc . caller \longrightarrow
       setAltitude\_MethodBinder
setHeading\_MethodBinder \stackrel{\frown}{=}
       binder\_setHeadingCall?loc: (loc \in setHeadingLocs)? caller: (caller \in setHeadingCallers)?p1-
       setHeadingCall.loc.caller!p1 \longrightarrow
       setHeadingRet.loc.caller \longrightarrow
       binder\_setHeadingRet. loc. caller \longrightarrow
       setHeading\_MethodBinder
isLandingGearDeployed\_MethodBinder \cong
       binder\_isLandingGearDeployedCall? loc:(loc \in isLandingGearDeployedLocs)? caller:(caller \in isLandingGearDeployedLocs)?
       isLandingGearDeployedCall. loc. caller \longrightarrow
       isLandingGearDeployedRet . loc . caller ? ret \longrightarrow
       binder\_isLandingGearDeployedRet.loc.caller!ret \longrightarrow
       is Landing Gear Deployed\_Method Binder
stowLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)
       stowLandingGearCall. loc. caller \longrightarrow
       stowLandingGearRet . loc . caller \longrightarrow
       binder\_stowLandingGearRet.loc.caller \longrightarrow
       stowLandingGear\_MethodBinder
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_deployLandingGearCall? loc:(loc \in deployLandingGearLocs)? caller:(caller \in deployLandingGearCallers)
       deployLandingGearCall. loc. caller. callingThread \longrightarrow
       deployLandingGearRet.\,loc.\,caller.\,callingThread {\longrightarrow}
       binder\_deployLandingGearRet. loc. caller. callingThread \longrightarrow
       deployLandingGear\_MethodBinder
qetAltitude\_MethodBinder \stackrel{\frown}{=}
       binder\_qetAltitudeCall? loc: (loc \in qetAltitudeLocs)? caller: (caller \in qetAltitudeCallers)-
       getAltitudeCall.loc.caller \longrightarrow
       getAltitudeRet.loc.caller?ret \longrightarrow
       binder\_getAltitudeRet.loc.caller!ret \longrightarrow
       getAltitude\_MethodBinder
getAirSpeed\_MethodBinder \cong
       binder\_getAirSpeedCall? loc: (loc \in getAirSpeedLocs)? caller: (caller \in getAirSpeedCallers) \longrightarrow
       getAirSpeedCall . loc . caller \longrightarrow
       getAirSpeedRet.loc.caller?ret \longrightarrow
       binder\_getAirSpeedRet.loc.caller!ret \longrightarrow
       getAirSpeed\_MethodBinder
```

```
abort\_MethodBinder \stackrel{\frown}{=}
       binder\_abortCall?\ loc: (loc \in abortLocs)?\ caller: (caller \in abortCallers)-
       abortCall\:.\:loc\:.\:caller {\longrightarrow}
       abortRet.\,loc.\,caller{\longrightarrow}
       binder\_abortRet.\,loc.\,caller \longrightarrow
       abort\_MethodBinder
getHeading\_MethodBinder \stackrel{\frown}{=}
       binder\_getHeadingCall?loc: (loc \in getHeadingLocs)?caller: (caller \in getHeadingCallers) -
       getHeadingCall\:.\:loc\:.\:caller {\longrightarrow}
       getHeadingRet . loc . caller ? ret \longrightarrow
       binder\_getHeadingRet.loc.caller!ret \longrightarrow
       getHeading\_MethodBinder
isLandingGearDeployed\_MethodBinder \stackrel{\frown}{=}
       binder\_isLandingGearDeployedCall? loc:(loc \in isLandingGearDeployedLocs)? caller:(caller \in isLandingGearDeployedLocs)?
       isLandingGearDeployedCall.loc.caller \longrightarrow
       isLandingGearDeployedRet . loc . caller ? ret \longrightarrow
       binder\_isLandingGearDeployedRet.loc.caller!ret \longrightarrow
       is Landing Gear Deployed\_Method Binder
stowLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)
       stowLandingGearCall\:.\:loc\:.\:caller {\longrightarrow}
       stowLandingGearRet . loc . caller \longrightarrow
       binder\_stowLandingGearRet.loc.caller \longrightarrow
       stowLandingGear\_MethodBinder
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_deployLandingGearCall?\ loc: (loc \in deployLandingGearLocs)?\ caller: (caller \in deployLandingGearCallers)
       deployLandingGearCall. loc. caller. callingThread \longrightarrow
       deployLandingGearRet. loc. caller. callingThread \longrightarrow
       binder\_deployLandingGearRet. loc. caller. callingThread \longrightarrow
```

 $deployLandingGear_MethodBinder$

$BinderActions \stackrel{\frown}{=}$

```
setCabinPressure\_MethodBinder
setEmergencyOxygen\_MethodBinder
setFuelRemaining\_MethodBinder
setAirSpeed\_MethodBinder
setAltitude\_MethodBinder
setHeading\_MethodBinder
is Landing Gear Deployed\_Method Binder
stowLandingGear\_MethodBinder
deployLandingGear\_MethodBinder
getAltitude\_MethodBinder
getAirSpeed\_MethodBinder
abort\_MethodBinder
getHeading\_MethodBinder
is Landing Gear Deployed\_Method Binder
stowLandingGear\_MethodBinder
deployLandingGear\_MethodBinder
```

• $BinderActions \triangle (done_toplevel_sequencer \longrightarrow \mathbf{Skip})$

 \mathbf{end}

2.3 Locking

 $\begin{array}{l} \textbf{section} \ \ NetworkLocking \ \textbf{parents} \ \ scj_prelude, \ GlobalTypes, \ FrameworkChan, \ MissionId, \ MissionIds, \ ThreadIds, \ ObjectIds, \ NetworkChannels, \ ObjectFW, \ ThreadFW \end{array}$

```
process Threads \cong
 ThreadFW(InstrumentLandingSystemMonitorTID, 5)
 ThreadFW(SafeLandingHandlerTID, 5)
 ThreadFW (GroundDistanceMonitorTID, 5)
 ThreadFW(CommunicationsHandlerTID, 5)
 ThreadFW ({\it Control Handler TID}, 5)
 ThreadFW(AperiodicSimulatorTID, 5)
 ThreadFW(TakeOffFailureHandlerTID, 5)
 ThreadFW(LandingGearHandlerLandTID, 5)
 ThreadFW(EnvironmentMonitorTID, 5)
 ThreadFW(FlightSensorsMonitorTID, 5)
 ThreadFW(NavigationMonitorTID, 5)
 ThreadFW(ACModeChangerTID, 5)
 ThreadFW(BeginLandingHandlerTID, 5)
 ThreadFW(LandingGear HandlerTakeOffTID, 5)
 ThreadFW(TakeOffMonitorTID, 5)
process Objects =
 ObjectFW(TakeOffMissionOID)
 ObjectFW(LandMissionOID)
```

 $\mathbf{process} \ Locking \ \widehat{=} \ ThreadSync \ \mathbb{I} \ Objects$

2.4 Program

```
section Program parents scj_prelude, MissionId, MissionIds,
    Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Mission FW,
    Safe let FW, Top Level Mission Sequencer FW, Network Channels, Managed Thread FW,
    Schedulable Mission Sequencer FW, Periodic Event Handler FW, One Shot Event Handler FW,
    AperiodicEventHandlerFW, ObjectFW, ThreadFW,
    ACSafeletApp, MainMissionSequencerApp, MainMissionApp, ACModeChangerApp, ControlHandlerApp,
    Communications Handler App, Environment Monitor App, Flight Sensors Monitor App,
    Aperiodic Simulator App, Take Off Mission App, Landing Gear Handler Take Off App, Take Off Failure Handler App,
    Take Off Monitor App, Cruise Mission App, Begin Landing Handler App, Navigation Monitor App
    , LandMissionApp, LandingGearHandlerLandApp, SafeLandingHandlerApp, GroundDistanceMonitorApp,
    InstrumentLandingSystemMonitorApp
process ControlTier =
  SafeletFW
      [ControlTierSync]
  TopLevel Mission Sequencer FW (Main Mission Sequencer)
process Tier0 =
  MissionFW(MainMissionID)
      [MissionSync]
    Schedulable Mission Sequencer FW(ACMode Changer ID)
        [SchedulablesSync]
      Aperiodic Event Handler FW(Control Handler ID, (time (10, 0), null))
          [SchedulablesSync]
      Aperiodic Event Handler FW (Communications Handler ID, (NULL, null Schedulable Id))
        [SchedulablesSync]
      PeriodicEventHandlerFW (EnvironmentMonitorID, (time(10,0), NULL, NULL, nullSchedulableId))
          [SchedulablesSync]
      Periodic Event Handler FW (Flight Sensors Monitor ID, (time (10,0), NULL, NULL, null Schedulable Id))
          [SchedulablesSync]
       PeriodicEventHandlerFW(AperiodicSimulatorID, (time (10, 0), NULL, NULL, nullSchedulableId))
process Tier1 =
  MissionFW(TakeOffMissionID)
      [MissionSync]
      Aperiodic Event Handler FW (Landing Gear Handler Take Off ID, (NULL, null Schedulable Id))
          [SchedulablesSync]
      AperiodicEventHandlerFW (TakeOffFailureHandlerID, (NULL, nullSchedulableId))
        [SchedulablesSync]
    PeriodicEventHandlerFW(TakeOffMonitorID, (time(0,0), time(500,0), NULL, nullSchedulableId))
    [ClusterSync]
  MissionFW(CruiseMissionID)
      [MissionSync]
    Aperiodic Event Handler FW (Begin Landing Handler ID, (NULL, null Schedulable Id))
        [SchedulablesSync]
    Periodic Event Handler FW (Navigation Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
    [ClusterSync]
  MissionFW(LandMissionID)
      [MissionSync]
      Aperiodic Event Handler FW (Landing Gear Handler Land ID, (NULL, null Schedulable Id))
          [SchedulablesSync]
      Aperiodic Event Handler FW (Safe Landing Handler ID, (NULL, null Schedulable Id))
        [SchedulablesSync]
      Periodic Event Handler FW (Ground Distance Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id))
          [SchedulablesSync]
      Periodic Event Handler FW (Instrument Landing System Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
```

```
\mathbf{process}\,\mathit{Framework}\,\,\widehat{=}\,
  ControlTier
      [\![\mathit{TierSync}]\!]
        [\![\mathit{Tier}0\mathit{Sync}]\!]
\mathbf{process} Application \cong
  ACS a felet App
  Main Mission Sequencer App
  MainMissionApp
  ACModeChangerApp(MainMissionID)
  Control Handler App
  Communications Handler App
  EnvironmentMonitorApp(MainMissionID)
  FlightSensorsMonitorApp(MainMissionID)
  AperiodicSimulatorApp(controlHandlerID)
  Take Off Mission App
  Landing Gear Handler Take Off App (\ Take Off Mission ID)
  Take Off Failure Handler App (Mission ID, Take Off Mission ID, 10.0)
  TakeOffMonitorApp(MissionID, TakeOffMissionID, 10.0, landingGearHandlerID)
  Cruise Mission App
  BeginLandingHandlerApp(MissionID)
  NavigationMonitorApp(MissionID)
  Land Mission App
  LandingGearHandlerLandApp(LandMissionID)
  Safe Landing Handler App (Mission ID, 10.0)
  GroundDistanceMonitorApp(MissionID)
 InstrumentLandingSystemMonitorApp(LandMissionID)
```

```
section Network parents scj_prelude,
```

 $\mathbf{process} \ Program \ \widehat{=} \ (Framework \ \llbracket \ AppSync \ \rrbracket \ Application B) \ \llbracket \ LockingSync \ \rrbracket \ Locking$

3 Safelet

 $\textbf{section} \ ACS a felet App \ \textbf{parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels Schedulable Ids, Safelet Chan, Method Channels Schedulable Ids, Safelet Channels Schedulable Ids, Safelet Chann$

```
\mathbf{process}\,\mathit{ACSafeletApp}\,\,\widehat{=}\,\,\mathbf{begin}
```

```
Initialize Application \ \widehat{=} \ \left( egin{array}{ll} initialize Application Call \longrightarrow \\ initialize Application Ret \longrightarrow \\ \mathbf{Skip} \end{array} \right)
```

 $\bullet \; (Methods) \; \triangle \; (end_safelet_app \longrightarrow \mathbf{Skip})$

4 Top Level Mission Sequencer

end

 $\begin{array}{c} \textit{State} \\ \textit{this}: \mathbf{ref} \ \textit{MainMissionSequencerClass} \\ \\ \hline \textit{State} \ \textit{State'} \\ \hline \textit{this'} = \mathbf{new} \ \textit{MainMissionSequencerClass}() \\ \\ \\ \textit{GetNextMission} \cong \mathbf{var} \ \textit{ret} : \textit{MissionID} \bullet \\ \textit{(getNextMissionCall . MainMissionSequencerSID} \longrightarrow \\ \textit{ret} := \textit{this . getNextMission}(); \\ \textit{getNextMissionRet . MainMissionSequencerSID} ! \ \textit{ret} \longrightarrow \\ \mathbf{Skip} \\ \\ \\ \textit{Methods} \cong \\ \textit{(GetNextMission)}; \ \textit{Methods} \\ \\ \bullet \ \textit{(Init ; Methods)} \triangle \ \textit{(end_sequencer_app . MainMissionSequencerSID} \longrightarrow \mathbf{Skip}) \\ \\ \end{array}$

 $\begin{array}{l} \textbf{section} \ \textit{MainMissionSequencerClass} \ \textbf{parents} \ \textit{scj_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan} \\, \textit{MethodCallBindingChannels}, \textit{MissionId}, \textit{MissionIds} \\ \end{array}$

 ${\bf class}\, {\it Main Mission Sequencer Class} \,\, \widehat{=} \,\, {\bf begin}$

```
\begin{array}{c} \textbf{state } \textit{State} \\ \textit{returnedMission} : \mathbb{B} \end{array}
```

 $\mathbf{state}\,\mathit{State}$

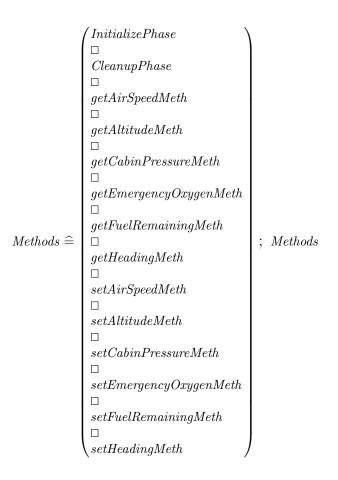
• Skip

5 Missions

5.1 MainMission

```
section MainMissionApp parents sci_prelude, MissionId, MissionIds,
    Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Main Mission Meth Chan
, Main Mission Class, Method Call Binding Channels \\
process MainMissionApp \stackrel{\frown}{=} begin
   State_{-}
   this: {f ref}\ Main Mission Class
\mathbf{state}\,\mathit{State}
  Init
   State'
   this' = \mathbf{new} \, MainMissionClass()
InitializePhase =
  'initializeCall . MainMissionMID \longrightarrow
  register! ACModeChangerSID! MainMissionMID \longrightarrow
  register \ ! \ Environment Monitor SID \ ! \ Main Mission MID
  register \: ! \: Control Handler SID \: ! \: Main Mission MID \longrightarrow
  register! FlightSensorsMonitorSID! MainMissionMID \longrightarrow
  register! Communications Handler SID! Main Mission MID-
  register! AperiodicSimulatorSID! MainMissionMID \longrightarrow
  initializeRet \;.\; MainMissionMID {\longrightarrow}
  Skip
CleanupPhase \stackrel{\frown}{=}
  cleanup {\it MissionRet} \ . \ Main {\it MissionMID} \ ! \ {\bf True} -
  Skip
getAirSpeedMeth \cong \mathbf{var}\ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getAirSpeed();
  getAirSpeedRet.\ MainMissionMID.\ caller\ !\ ret
getAltitudeMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getAltitude();
  getAltitudeRet.\ MainMissionMID.\ caller\ !\ ret-
  Skip
getCabinPressureMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getCabinPressure();
  get Cabin Pressure Ret \;.\; Main Mission MID \;!\; ret
  Skip
```

```
getEmergencyOxygenMeth = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getEmergencyOxygenCall. MainMissionMID \longrightarrow
  ret := this.getEmergencyOxygen();
  getEmergencyOxygenRet . MainMissionMID! ret
  Skip
getFuelRemainingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getFuelRemaining();
  getFuelRemainingRet \ . \ MainMissionMID \ ! \ ret
getHeadingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getHeadingCall. MainMissionMID? caller \longrightarrow
  ret := this.getHeading();
  getHeadingRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
setAirSpeedMeth \stackrel{\frown}{=}
  \ 'setAirSpeedCall . MainMissionMID ? caller ? airSpeed-
  this . setAirSpeed(airSpeed);
  setAirSpeedRet . MainMissionMID . caller-
 Skip
setAltitudeMeth \triangleq
  \ 'set Altitude Call . Main Mission MID ? caller ? altitude-
  this.setAltitude(altitude);
  setAltitudeRet. MainMissionMID. caller-
  Skip
setCabinPressureMeth \ \widehat{=} \\
  \ 'set Cabin Pressure Call . Main Mission MID ? caller ? cabin Pressure -
  this.setCabinPressure(cabinPressure);
  set Cabin Pressure Ret . Main Mission MID . caller-
  Skip
setEmergencyOxygenMeth \stackrel{\frown}{=}
  setEmergencyOxygenCall . MainMissionMID? caller? emergencyOxygen
  this.setEmergencyOxygen(emergencyOxygen);
  setEmergencyOxygenRet . MainMissionMID . caller-
 Skip
setFuelRemainingMeth \stackrel{\frown}{=}
  \ 'setFuelRemainingCall . MainMissionMID ? caller ? fuelRemaining .
  this.setFuelRemaining(fuelRemaining);
  setFuelRemainingRet. MainMissionMID. caller \longrightarrow
 Skip
setHeadingMeth \stackrel{\frown}{=}
  \ 'setHeadingCall . MainMissionMID ? caller ? heading-
  this.setHeading(heading);
  setHeadingRet . MainMissionMID . caller
 Skip
```



 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end_mission_app} \; . \; \mathit{MainMissionMID} \longrightarrow \mathbf{Skip})$

 $\begin{array}{l} \textbf{section} \ \textit{MainMissionClass} \ \textbf{parents} \ \textit{scj_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan}, \textit{MethodCallBindingChannels} \\ \end{array}$

${f class}\, {\it Main Mission Class} \ \widehat{=} \ {f begin}$

```
state State
     ALTITUDE\_READING\_ON\_GROUND: \mathbb{P} \mathbb{A}
     test: \mathbb{Z}
     cabinPressure: \mathbb{P}\,\mathbb{A}
     emergencyOxygen: \mathbb{P} \mathbb{A}
    fuelRemaining: \mathbb{P} \mathbb{A}
     altitude: \mathbb{P}\,\mathbb{A}
     airSpeed: \mathbb{P} \mathbb{A}
     heading: \mathbb{P} \mathbb{A}
{f state}\ State
    \mathbf{initial}\ Init
     State'
public getAirSpeed = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := airSpeed)
\mathbf{public}\ getAltitude\ \widehat{=}\ \mathbf{var}\ ret: \mathbb{P}\,\mathbb{A}\,\bullet
(ret := altitude)
public getCabinPressure = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := cabinPressure)
public getEmergencyOxygen \cong \mathbf{var}\ ret : \mathbb{P}\ \mathbb{A} \bullet
(ret := emergencyOxygen)
public getFuelRemaining \cong \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := fuelRemaining)
\mathbf{public}\ \mathit{getHeading}\ \widehat{=}\ \mathbf{var}\ \mathit{ret}: \mathbb{P}\,\mathbb{A}\,\bullet
(ret := heading)
public setAirSpeed \stackrel{\frown}{=}
(this.this.airSpeed := airSpeed)
public setAltitude \stackrel{\frown}{=}
(this.this.altitude := altitude)
\mathbf{public}\ \mathit{setCabinPressure}\ \widehat{=}
```

(this.this.cabinPressure := cabinPressure)

```
\begin{array}{l} \textbf{public} \ setEmergencyOxygen \ \widehat{=} \\ \big(this.this.emergencyOxygen := emergencyOxygen\big) \\ \\ \textbf{public} \ setFuelRemaining \ \widehat{=} \\ \big(this.this.fuelRemaining := fuelRemaining\big) \\ \\ \textbf{public} \ setHeading \ \widehat{=} \\ \big(this.this.heading := heading\big) \\ \end{array}
```

 \bullet Skip

 \mathbf{end}

5.2 Schedulables of MainMission

 $\begin{array}{l} \textbf{section} \ A C Mode Changer App \ \textbf{parents} \ Top Level Mission Sequencer Chan, \\ Mission Ids, Schedulable Id, Schedulable Ids, A C Mode Changer Class, Method Call Binding Channels \\ \end{array}$

```
 \begin{aligned} & \textbf{process } ACModeChangerApp \; \widehat{=} \\ & controllingMission : MissionID \; \bullet \; \textbf{begin} \end{aligned}   \begin{aligned} & GetNextMission \; \widehat{=} \; \textbf{var} \; ret : \; MissionID \; \bullet \\ & \left( getNextMissionCall \; . \; ACModeChangerSID \longrightarrow \\ & ret \; := \; this \; . \; getNextMission(); \\ & getNextMissionRet \; . \; ACModeChangerSID ! \; ret \longrightarrow \\ & \textbf{Skip} \end{aligned}   \begin{aligned} & \textbf{Methods} \; \widehat{=} \\ & \left( GetNextMission \right) \; ; \; \; Methods \end{aligned}   \begin{aligned} & \bullet \; \left( Methods \right) \; \triangle \; \left( end\_sequencer\_app \; . \; ACModeChangerSID \longrightarrow \textbf{Skip} \right) \end{aligned}   \end{aligned}   \begin{aligned} & \textbf{end} \end{aligned}
```

 $\begin{array}{l} \textbf{section} \ A C Mode Changer Class \ \textbf{parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels, Mission Id, Mission Ids \\ \end{array}$

 $\mathbf{class}\,\mathit{ACModeChangerClass}\,\,\widehat{=}\,\,\mathbf{begin}$

```
egin{array}{c} \mathbf{state} \ \mathit{State} \ \mathit{St
```

 $\mathbf{state}\,\mathit{State}$

```
__ initial Init _____
State'
```

protected $getNextMission = \mathbf{var} \ ret : MissionID \bullet$

```
'if (modesLeft = 3) \longrightarrow
      (modesLeft := modesLeft - 1;
      \ \ \ \ \mathit{ret} := \mathit{TakeOffMissionMID}
[] \neg (modesLeft = 3) \longrightarrow
     if (modesLeft = 2) \longrightarrow
      (modesLeft := modesLeft - 1;)
      [] \neg (\dot{modesLeft} = 2) \longrightarrow
     if (modesLeft = 1) \longrightarrow
     (modesLeft := modesLeft - 1;)
      \ \ ret := LandMissionMID
[] \neg (\dot{modesLeft} = 1) \longrightarrow
     (ret := nullMissionId)
fi
fi
fi
```

• Skip

$\mathbf{process} \ \mathit{ControlHandlerApp} \ \widehat{=} \ \mathbf{begin}$

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; ControlHandlerSID \longrightarrow \\ \mathbf{Skip}; \\ handleAsyncEventRet \; . \; ControlHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
Methods = (handleAsyncEvent); Methods
```

 $\bullet \; (\mathit{Methods}) \; \triangle \; (\mathit{end_aperiodic_app} \; . \; \mathit{ControlHandlerSID} \longrightarrow \mathbf{Skip})$

$\mathbf{process} \ \mathit{CommunicationsHandlerApp} \ \widehat{=} \ \mathbf{begin}$

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; CommunicationsHandlerSID \longrightarrow \\ \mathbf{Skip}; \\ handleAsyncEventRet \; . \; CommunicationsHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
Methods = (handleAsyncEvent); Methods
```

ullet (Methods) \triangle (end_aperiodic_app . CommunicationsHandlerSID \longrightarrow Skip)

 ${\bf section} \ \ Environment Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding, Main Mission Meth Chan$

```
process \ EnvironmentMonitorApp \ \widehat{=} \\ mainMission : MissionID \bullet \mathbf{begin} \\ handle A sync Event \ \widehat{=} \\ handle A sync Event \ \widehat{=} \\ handle A sync Event Call . Environment Monitor SID \longrightarrow \\ binder\_set Cabin Pressure Call . controlling Mission . Environment Monitor SID ! 0 \longrightarrow \\ binder\_set Cabin Pressure Ret . controlling Mission . Environment Monitor SID ! 0 \longrightarrow \\ \mathbf{Skip}; \\ binder\_set Emergency Oxygen Call . controlling Mission . Environment Monitor SID ! 0 \longrightarrow \\ binder\_set Emergency Oxygen Ret . controlling Mission . Environment Monitor SID ! 0 \longrightarrow \\ \mathbf{Skip}; \\ binder\_set Fuel Remaining Call . controlling Mission . Environment Monitor SID ! 0 \longrightarrow \\ binder\_set Fuel Remaining Ret . controlling Mission . Environment Monitor SID \ Skip \\ handle A sync Event Ret . Environment Monitor SID \longrightarrow \\ \mathbf{Skip} \\ Methods \ \widehat{=} \\ (handle A sync Event); Methods \\ \bullet (Methods) \triangle (end\_periodic\_app . Environment Monitor SID \longrightarrow \mathbf{Skip}) \\ \end{cases}
```

${\bf section}\ Environment Monitor Class\ {\bf parents}\ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class} Environment Monitor Class \widehat{=} {\bf begin}$
state State
controlling Mission: Main Mission
state Stateinitial Init
State'
• Skip
end

 ${\bf section} \ \ Flight Sensors Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding, Main Mission Meth Chan$

```
\begin{aligned} & process \textit{FlightSensorsMonitorApp} \, \widehat{=} \\ & \textit{mainMission} : \textit{MissionID} \bullet \mathbf{begin} \end{aligned} \\ & \textit{handleAsyncEvent} \, \widehat{=} \\ & \textit{(handleAsyncEventCall : FlightSensorsMonitorSID} \longrightarrow \\ & \textit{(binder\_setAirSpeedCall : controllingMission : FlightSensorsMonitorSID ! 0 \longrightarrow } \\ & \mathbf{binder\_setAirSpeedRet : controllingMission : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip;} \\ & \textit{binder\_setAltitudeCall : controllingMission : FlightSensorsMonitorSID ! 0 \longrightarrow } \\ & \mathbf{binder\_setAltitudeRet : controllingMission : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip;} \\ & \textit{binder\_setHeadingCall : controllingMission : FlightSensorsMonitorSID ! 0 \longrightarrow } \\ & \mathbf{binder\_setHeadingRet : controllingMission : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip} \\ & \mathbf{binder\_setHeadingRet : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip} \\ & \mathbf{Methods} \, \widehat{=} \\ & \textit{(handleAsyncEventRet : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip} \\ & \mathbf{Methods} \, \widehat{=} \\ & \textit{(handleAsyncEvent)} \; ; \; \textit{Methods} \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip} ) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip}) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip}) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip}) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{Skip}) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID} \longrightarrow \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID}) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID}) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID}) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID}) \\ & \mathbf{\bullet} \; (\textit{Methods}) \, \triangle \, (\textit{end\_periodic\_app : FlightSensorsMonitorSID}) \\ & \mathbf{\bullet} \; (\textit{end\_periodic\_app : FlightSensorsMonitorSID}) \\ & \mathbf{\bullet} \; (\textit{end\_periodic\_app : FlightSensorsMonitorSID}) \\ & \mathbf{\bullet} \; (\textit{end\_periodic\_app : FlightSensorsMonitorSID}) \\ & \mathbf{\bullet} \;
```

$ {\bf section} \ Flight Sensors Monitor Class \ {\bf parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels $
${\bf class} Flight Sensors Monitor Class \widehat{=} {\bf begin}$
_ state State
controlling Mission: Main Mission
$\mathbf{state}\mathit{State}$
initial Init
State'
• Skip
end

```
\begin{aligned} \mathbf{process} & AperiodicSimulatorApp \; \widehat{=} \\ & aperiodicEvent : SchedulableID \bullet \mathbf{begin} \end{aligned} \begin{aligned} handleAsyncEvent \; \widehat{=} \\ \begin{pmatrix} handleAsyncEventCall \; . \; AperiodicSimulatorSID \longrightarrow \\ releaseCall \; . \; event \longrightarrow \\ releaseRet \; . \; event ? \; release \longrightarrow \\ \mathbf{Skip} \end{aligned} \; ; \\ \mathbf{Skip} \\ handleAsyncEventRet \; . \; AperiodicSimulatorSID \longrightarrow \\ \mathbf{Skip} \end{aligned} \begin{aligned} Methods \; \widehat{=} \\ \begin{pmatrix} handleAsyncEvent \end{pmatrix} \; ; \; Methods \end{aligned} \bullet \; (Methods) \; \triangle \; (end\_periodic\_app \; . \; AperiodicSimulatorSID \longrightarrow \mathbf{Skip}) \end{aligned}
```

${\bf section} \ A periodic Simulator Class \ {\bf parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}AperiodicSimulatorClass \stackrel{\frown}{=} {\bf begin}$
state State
event: Aperiodic Event Handler
$\mathbf{state}\mathit{State}$
initial Init
State'
• Skip
end

5.3 TakeOffMission

section TakeOffMissionApp **parents** scj_prelude, MissionId, MissionIds,

```
Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Take Off Mission Meth Chan
 , Take Off Mission Class, Method Call Binding Channels, Object FW Chan, Object Ids
process TakeOffMissionApp \cong
                   controlling Mission: Mission ID \bullet \mathbf{begin}
            State
               this: {f ref}\ Take Off Mission Class
\mathbf{state}\,\mathit{State}
           Init
               State'
              this' = \mathbf{new} \ TakeOffMissionClass()
InitializePhase \stackrel{\frown}{=}
          initializeCall. TakeOffMissionMID \longrightarrow
           register \,!\, Landing Gear Handler Take Off SID \,!\, Take Off Mission MID-register \,!\, Landing Gear Handler Take Off SID \,!\, Take Off Mission MID-register \,!\, Landing Gear Handler Take Off SID \,!\, Take Off Mission MID-register \,!\, Landing Gear Handler Mission Miss
           register! TakeOffMonitorSID! TakeOffMissionMID \longrightarrow
          register \ ! \ Take Off Failure Handler SID \ ! \ Take Off Mission MID \longrightarrow
           initializeRet. TakeOffMissionMID \longrightarrow
          Skip
 CleanupPhase \stackrel{\frown}{=}
         cleanupMissionCall. TakeOffMissionMID \longrightarrow
           clean up {\it MissionRet} : Take {\it OffMissionMID} \ ! \ {\bf True} -
        Skip
abortMeth \stackrel{\frown}{=}
          [abortCall\ .\ TakeOffMissionMID\ ?\ caller-
          this. abort();
           abortRet.\ Take Off Mission MID.\ caller
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
         getControllingMissionCall. TakeOffMissionMID \longrightarrow
         ret := this.getControllingMission();
           getControllingMissionRet\ .\ TakeOffMissionMID\ !\ ret
        Skip
setControllingMissionMeth =
         's et Controlling {\it Mission Call} \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission-property is the controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission MID \;? \; controlling Mission Call \;. \; Take O \!f\! f\! Mission MID \;? \; controlling Mission MID \;? \; cont
           this.setControllingMission(controllingMission);
           setControllingMissionRet. TakeOffMissionMID \longrightarrow
        Skip
```

```
clean UpMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  ret := this \cdot clean Up();
  clean UpRet . Take Off Mission MID ! re
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  \ 'stow Landing Gear Call . Take Off Mission MID? caller-
  this.stowLandingGear();
  stow Landing Gear Ret.\ Take Off Mission MID.\ caller
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  is Landing Gear Deployed Call . Take Off Mission MID? caller \longrightarrow
  ret := this.isLandingGearDeployed();
  is Landing Gear Deployed Ret.\ Take Off Mission MID.\ caller\ !\ ret
 Skip
deployLandingGearSyncMeth =
  deployLandingGearCall. TakeOffMissionMID? caller? thread \longrightarrow
    startSyncMeth. TakeOffMissionOID. thread \longrightarrow
    lockAcquired. TakeOffMissionOID. thread \longrightarrow
    (this.landingGearDeployed := True);
    \stackrel{.}{e}ndSyncMeth. TakeOffMissionOID. \stackrel{.}{thread} \longrightarrow
    deploy Landing Gear Ret.\ Take Off Mission MID.\ caller.\ thread
    Skip
               Initialize Phase
               CleanupPhase
               abortMeth
               getControllingMissionMeth \\
Methods =
               set Controlling Mission Meth \\
                                                    : Methods
               clean\, UpMeth
               stowLandingGearMeth
               is Landing Gear Deployed Meth
               deploy Landing Gear Sync Meth \\
```

 $\bullet \ (\mathit{Init} \ ; \ \mathit{Methods}) \ \triangle \ (\mathit{end_mission_app} \ . \ \mathit{TakeOffMissionMID} \longrightarrow \mathbf{Skip})$

 $\begin{array}{l} \textbf{section} \ \ Take Off Mission Class \ \ \textbf{parents} \ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels \end{array}$

class $TakeOffMissionClass \stackrel{\frown}{=} \mathbf{begin}$

```
state State
    SAFE\_AIRSPEED\_THRESHOLD: \mathbb{P} \, \mathbb{A}
    TAKEOFF\_ALTITUDE: \mathbb{P}\,\mathbb{A}
    controlling Mission: Main Mission\\
    abort: \mathbb{B}
    landing Gear Deployed: \mathbb{B}
{f state}\ State
   \mathbf{initial}\ Init
    State'
\mathbf{public}\ \mathit{abort}\ \widehat{=}
(this.abort := True)
public getControllingMission = \mathbf{var} \ ret : MissionID \bullet
(ret := controllingMission)
public setControllingMission  <math>\hat{=}
(this.this.controllingMission := controllingMission)
public clean Up = \mathbf{var} \ ret : \mathbb{B} \bullet
(ret := (\neg abort = \mathbf{True}))
public stowLandingGear \stackrel{\frown}{=}
(this.landingGearDeployed := False)
public isLandingGearDeployed <math>\stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
(ret := landingGearDeployed = True)
• Skip
```

${\bf section}\ \textit{TakeOffMissionMethChan}\ {\bf parents}\ \textit{scj_prelude}, \textit{GlobalTypes}, \textit{MissionId}, \textit{SchedulableId}$

 $\begin{array}{l} \textbf{channel} \ abortCall: MissionID \times SchedulableID \\ \textbf{channel} \ abortRet: MissionID \times SchedulableID \\ \end{array}$

 ${\bf channel}\ getControlling Mission Call: Mission ID$

 $\mathbf{channel}\ getControllingMissionRet: MissionID \times MissionID$

 $\mathbf{channel}\ setControllingMissionCall: MissionID \times MissionID$

 ${\bf channel}\ set Controlling {\it Mission Ret}: {\it Mission ID}$

channel cleanUpCall : MissionID**channel** $cleanUpRet : MissionID \times \mathbb{B}$

 $\begin{cal}{c} {\bf channel} \ stowLandingGearCall: MissionID \times SchedulableID \\ {\bf channel} \ stowLandingGearRet: MissionID \times SchedulableID \\ \end{cal}$

 $\begin{tabular}{l} {\bf channel} \ is Landing Gear Deployed Call: Mission ID \times Schedulable ID \\ {\bf channel} \ is Landing Gear Deployed Ret: Mission ID \times Schedulable ID \times \mathbb{B} \\ \end{tabular}$

 $\label{lem:channel} \textbf{channel} \ deployLandingGearCall: MissionID \times SchedulableID \times ThreadID \\ \textbf{channel} \ deployLandingGearRet: MissionID \times SchedulableID \times ThreadID \\$

5.4 Schedulables of TakeOffMission

 $\begin{array}{l} \textbf{section} \ Landing Gear Handler Take Off App \ \textbf{parents} \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Control of the Chan, Object Ids, Thread Ids \\ \end{array} , Take Off Mission Meth Chan, Object Ids, Thread Ids \\ \end{array}$

```
process Landing Gear Handler Take Off App \cong
                   mission: MissionID \bullet \mathbf{begin}
handle A sync Event \cong
         handle A sync Event Call. Landing Gear Handler Take Off SID \longrightarrow
                     binder\_isLandingGearDeployedCall . mission . LandingGearHandlerTakeOffSID \longrightarrow
                    binder\_is Landing Gear Deployed Ret: mission: Landing Gear Handler Take Off SID? is Landing Gear Deployed \longrightarrow the control of t
                    \mathbf{var}\ landing Gear Is Deployed: \mathbb{B} \bullet landing Gear Is Deployed: = is Landing Gear Deployed;
                   if landingGearIsDeployed = True \longrightarrow
                                                  binder\_stowLandingGearCall\ .\ mission\ .\ LandingGearHandlerTakeOffSID-dearCall\ .
                                                binder\_stowLandingGearRet \ . \ mission \ . \ LandingGearHandlerTakeOffSID {\longrightarrow}
                                                Skip
                    \ 'binder\_deployLandingGearCall . mission . LandingGearHandlerTakeOffSID . LandingGearHandlerTakeOffTID .
                                                 binder\_deployLandingGearRet.\ mission.\ LandingGearHandlerTakeOffSID.\ LandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHa
          handle A sync Event Ret . Landing Gear Handler Take Off SID \longrightarrow
        Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_aperiodic\_app . LandingGearHandlerTakeOffSID \longrightarrow \mathbf{Skip})
end
```

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffFailureHandlerApp} \ \ \textbf{parents} \ \ \textit{AperiodicEventHandlerChan}, SchedulableId, SchedulableIds, MethodCallBing, MainMissionMethChan, TakeOffMissionMethChan \\ \end{array} \\$

```
process TakeOffFailureHandlerApp \cong
              mainMission: MissionID,
takeoffMission: MissionID,
threshold : \mathbb{P} \mathbb{A} \bullet \mathbf{begin}
handleAsyncEvent =
      'handle A sync Event Call . Take Off Failure Handler SID \longrightarrow
              binder\_getAirSpeedCall . mainMission . TakeOffFailureHandlerSID \longrightarrow
              binder\_getAirSpeedRet. mainMission. TakeOffFailureHandlerSID? getAirSpeed \longrightarrow
              \mathbf{var}\ currentSpeed : \mathbb{P}\mathbb{A} \bullet currentSpeed := getAirSpeed;
              if(currentSpeed < threshold) \longrightarrow
                                    binder\_abortCall . takeoffMission . TakeOffFailureHandlerSID \longrightarrow
                                    binder\_abortRet. takeoffMission. TakeOffFailureHandlerSID \longrightarrow
                                    request Termination Call\ .\ take off Mission\ .\ Take Off Failure Handler SID \longrightarrow
                                    request Termination Ret.\ take off Mission.\ Take Off Failure Handler SID\ ?\ request Termination Take Off Failure Handler SID\ ?\ reque
                                   Skip
              [] \neg (currentSpeed < threshold) \longrightarrow
       handle A sync Event Ret: Take Off Failure Handler SID {\longrightarrow}
      Skip
Methods \mathrel{\widehat{=}}
(handleAsyncEvent); Methods
```

 $\bullet \ (\textit{Methods}) \ \triangle \ (\textit{end_aperiodic_app} \ . \ \textit{TakeOffFailureHandlerSID} \longrightarrow \mathbf{Skip})$

$section \ \textit{TakeOffFatureHandlerClass} \ \textbf{parents} \ \textit{scj_pretude}, \textit{Schedulable1d}, \textit{Schedulable1ds}, \textit{SafetetChan} \ \textit{MethodCallBindingChannels}$
$\textbf{class} \ \textit{TakeOffFailureHandlerClass} \ \widehat{=} \ \textbf{begin}$
state State
$threshold: \mathbb{P}\mathbb{A}$
state State initial Init
State'
• Skip
end

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffMonitorApp} \ \ \textbf{parents} \ \ \textit{PeriodicEventHandlerChan}, SchedulableId, SchedulableIds, MethodCallBindingChan, MainMissionMethChan \end{array}$

```
process TakeOffMonitorApp \cong
     main Mission: Mission ID,
takeOffMission: MissionID,
takeOffAltitude : \mathbb{P} \mathbb{A},
landingGear Handler: Schedulable ID ullet \mathbf{begin}
handleAsyncEvent \triangleq
  binder\_getAltitudeCall . mainMission . TakeOffMonitorSID \longrightarrow
     binder\_getAltitudeRet..mainMission..TakeOffMonitorSID?getAltitude {\longrightarrow}
     \mathbf{var}\ altitude : \mathbb{P}\,\mathbb{A} \bullet altitude := getAltitude;
    if (altitude > takeOffAltitude) \longrightarrow
            \'releaseCall . landingGearHandler \longrightarrow
            releaseRet\:.\:landingGear Handler\:?\:release {\longrightarrow}
            request Termination Call. take off Mission. Take Off Monitor SID \longrightarrow
            request Termination Ret.\ take of fM is sion.\ Take Off Monitor SID\ ?\ request Termination
            Skip
    \[ ] \neg (altitude > takeOffAltitude) \longrightarrow \mathbf{Skip} \]
  handle A sync Event Ret. Take Off Monitor SID \longrightarrow
  Skip
Methods \mathrel{\widehat{=}}
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_periodic\_app . TakeOffMonitorSID \longrightarrow \mathbf{Skip})
```

${\bf section}\ \ Take Off Monitor Class\ {\bf parents}\ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}\ {\it TakeOffMonitorClass}\ \widehat{=}\ {\bf begin}$
state State
$take Off Mission: Take Off Mission \ take Off Altitude: \mathbb{P} \mathbb{A}$
state State
initial Init
• Skip
end

5.5 CruiseMission

```
 \begin{array}{l} \textbf{section} \ \textit{CruiseMissionApp} \ \textbf{parents} \ \textit{scj\_prelude}, \textit{MissionId}, \textit{MissionIds}, \\ \textit{SchedulableId}, \textit{SchedulableIds}, \textit{MissionChan}, \textit{SchedulableMethChan}, \textit{CruiseMissionMethChan}, \\ \textit{CruiseMissionClass}, \textit{MethodCallBindingChannels} \\ \\ \textbf{process} \ \textit{CruiseMissionApp} \ \widehat{=} \\ \textit{controllingMission} : \textit{MissionID} \ \bullet \ \textbf{begin} \\ \end{aligned}
```

```
State
this: \mathbf{ref}\ CruiseMissionClass

\mathbf{state}\ State

Init
State'
this' = \mathbf{new}\ CruiseMissionClass()
```

```
\begin{array}{l} InitializePhase \; \widehat{=} \\ \left( \begin{array}{l} initializeCall \; . \; CruiseMissionMID \longrightarrow \\ register \; ! \; BeginLandingHandlerSID \; ! \; CruiseMissionMID \longrightarrow \\ register \; ! \; NavigationMonitorSID \; ! \; CruiseMissionMID \longrightarrow \\ initializeRet \; . \; CruiseMissionMID \longrightarrow \\ \mathbf{Skip} \end{array} \right)
```

```
 \begin{array}{l} \textit{CleanupPhase} \; \widehat{=} \\ \left( \begin{array}{l} \textit{cleanupMissionCall} \; . \; \textit{CruiseMissionMID} \longrightarrow \\ \textit{cleanupMissionRet} \; . \; \textit{CruiseMissionMID} \; ! \; \textbf{True} \longrightarrow \\ \textbf{Skip} \end{array} \right)
```

```
 \begin{array}{l} getControllingMissionMeth \ \widehat{=} \ \mathbf{var} \ ret : MissionID \ \bullet \\ \left( \begin{array}{l} getControllingMissionCall \ . \ CruiseMissionMID \longrightarrow \\ ret := this \ . \ getControllingMission(); \\ getControllingMissionRet \ . \ CruiseMissionMID \ ! \ ret \longrightarrow \\ \mathbf{Skip} \end{array} \right)
```

$$Methods = \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ getControllingMissionMeth \end{pmatrix}; Methods$$

• (Init; Methods) \triangle (end_mission_app. CruiseMissionMID \longrightarrow Skip)

$ \textbf{section} \ \ Cruise Mission Class \ \ \textbf{parents} \ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels $
${\bf class}\ Cruise Mission Class\ \widehat{=}\ {\bf begin}$
state State
controlling Mission: Main Mission
state State
initial Init State'
State
$ \begin{aligned} \mathbf{public} \ getControllingMission & \widehat{=} \mathbf{var} \ ret : MissionID \bullet \\ \big(ret := controllingMission\big) \end{aligned} $
· Skip
end

5.6 Schedulables of CruiseMission

 ${\bf section}\ Begin Landing Handler App\ {\bf parents}\ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binder Chan, Method Chan, Me$

```
 \begin{aligned} & \textbf{process } \textit{BeginLandingHandlerApp} \ \stackrel{\frown}{=} \\ & \textit{controllingMission} : \textit{MissionID} \bullet \textbf{begin} \end{aligned}   \begin{aligned} & \textit{handleAsyncEvent} \ \stackrel{\frown}{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \ . \ \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textit{crequestTerminationCall} \ . \ \textit{controllingMission} \ . \ \textit{BeginLandingHandlerSID} \ \stackrel{\frown}{>} \\ & \textit{requestTerminationRet} \ . \ \textit{controllingMission} \ . \ \textit{BeginLandingHandlerSID} \ ? \ \textit{requestTermination} \longrightarrow \end{pmatrix} ; \\ & \textbf{Skip} \\ & \textit{handleAsyncEventRet} \ . \ \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textbf{Skip} \end{aligned}   \begin{aligned} & \textit{Methods} \ \stackrel{\frown}{=} \\ & \textit{(handleAsyncEvent)} \ ; \ \textit{Methods} \end{aligned}   \end{aligned} \qquad \bullet \ (\textit{Methods}) \ \triangle \ (\textit{end\_aperiodic\_app} \ . \ \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip}) \end{aligned}   \end{aligned}   \end{aligned}   \end{aligned}   \end{aligned}   \end{aligned}   \end{aligned} \qquad \bullet \ (\textit{Methods}) \ \triangle \ (\textit{end\_aperiodic\_app} \ . \ \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip})   \end{aligned}   \end{aligned}   \end{aligned}
```

 $\textbf{section} \ \textit{NavigationMonitorApp} \ \textbf{parents} \ \textit{PeriodicEventHandlerChan}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{MethodCallBindingOption}, \textit{MainMissionMethChan}$

```
\mathbf{process} \ Navigation Monitor App \ \widehat{=} \ 
     mainMission: MissionID \bullet \mathbf{begin}
handle A sync Event \triangleq
  'handle A sync Event Call . Navigation Monitor SID \longrightarrow
     binder\_getHeadingCall\ .\ mainMission\ .\ NavigationMonitorSID {\longrightarrow}
     binder\_getHeadingRet..mainMission..NavigationMonitorSID~?~getHeading \longrightarrow
     \mathbf{var}\ heading : \mathbb{P}\ \mathbb{A} \bullet heading := getHeading;
     binder\_getAirSpeedCall. mainMission. NavigationMonitorSID \longrightarrow
     binder\_getAirSpeedRet.mainMission.NavigationMonitorSID?getAirSpeed\longrightarrow
     \mathbf{var} \ airSpeed : \mathbb{P} \mathbb{A} \bullet airSpeed := getAirSpeed;
     binder\_getAltitudeCall\:.\:mainMission\:.\:NavigationMonitorSID \longrightarrow
     binder\_getAltitudeRet \ . \ mainMission \ . \ NavigationMonitorSID \ ? \ getAltitude \longrightarrow
     \mathbf{var}\ altitude : \mathbb{P}\,\mathbb{A} \bullet altitude := getAltitude
   handle A sync Event Ret. Navigation Monitor SID \longrightarrow
  Skip
Methods =
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_periodic\_app . NavigationMonitorSID \longrightarrow \mathbf{Skip})
```

5.7 LandMission

Skip

section LandMissionApp parents scj_prelude, MissionId, MissionIds,

```
Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Land Mission Meth Chan
, Land Mission Class, Method Call Binding Channels, Object FW Chan, Object Ids
process Land Mission App \cong
     controlling Mission: Mission ID \bullet \mathbf{begin}
   State
    this: \mathbf{ref}\ Land Mission Class
\mathbf{state}\,\mathit{State}
   Init
    State'
   this' = \mathbf{new} \ Land Mission Class()
InitializePhase \stackrel{\frown}{=}
  initializeCall. LandMissionMID \longrightarrow
  register \ ! \ Ground Distance Monitor SID \ ! \ Land Mission MID \longrightarrow
  register! LandingGearHandlerLandSID! LandMissionMID \longrightarrow
  register \,! \, Instrument Landing System Monitor SID \,! \, Land Mission MID
  register! SafeLandingHandlerSID! LandMissionMID \longrightarrow
  initializeRet . LandMissionMID \longrightarrow
  Skip
CleanupPhase =
  cleanup {\it Mission Ret} \; . \; Land {\it Mission MID} \; ! \; {\bf True} -
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  \ 'stow Landing Gear Call . Land Mission MID? caller
  this.stowLandingGear();
  stow Landing Gear Ret\ .\ Land Mission MID\ .\ caller
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  is Landing Gear Deployed Call . Land Mission MID? caller-
  ret := this.isLandingGearDeployed();
  is Landing Gear Deployed Ret.\ Land Mission MID.\ caller\ !\ ret-
  Skip
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
  ret := this.getControllingMission();
  getControlling {\it MissionRet} \;.\; Land {\it MissionMID} \;!\; ret \\
```

```
abortMeth \stackrel{\frown}{=}
  abort Call . Land Mission MID -
  this.\ abort();
  abortRet\ .\ Land Mission MID
  Skip
clean UpMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  \'clean Up Call . Land Mission MID -
  ret := this.cleanUp();
  clean \textit{UpRet} . \textit{LandMissionMID} ! \textit{ret}
deployLandingGearSyncMeth \stackrel{\frown}{=}
  startSyncMeth. LandMissionOID. thread \longrightarrow
    lockAcquired . LandMissionOID . thread \longrightarrow
    (this.landingGearDeployed := True);
    endSyncMeth . LandMissionOID . thread \longrightarrow
    deploy Landing Gear Ret.\ Land Mission MID.\ caller.\ thread-
    Skip
               Initialize Phase \\
               CleanupPhase
               stow Landing Gear Meth \\
               is Landing Gear Deployed Meth
Methods \stackrel{\frown}{=}
                                                   ; Methods
               get Controlling Mission Meth \\
               abortMeth
               clean\,UpMeth
               deployLandingGearSyncMeth
```

ullet (Init; Methods) \triangle (end_mission_app. LandMissionMID \longrightarrow **Skip**)

 ${\bf section}\ Land Mission Class\ {\bf parents}\ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan$, Method Call Binding Channels

 $\mathbf{class}\,\mathit{LandMissionClass}\,\,\widehat{=}\,\,\mathbf{begin}$

```
\mathbf{state}\,\mathit{State}\,.
    controlling Mission: Main Mission\\
    SAFE\_LANDING\_ALTITUDE: \mathbb{P} \, \mathbb{A}
    abort: \mathbb{B}
    landingGearDeployed: \mathbb{B}
\mathbf{state}\,\mathit{State}
    initial Init
    State'
public stowLandingGear \stackrel{\frown}{=}
(this.landingGearDeployed := False)
public isLandingGearDeployed  <math>\hat{=}  var ret : \mathbb{B} \bullet 
(ret := landingGearDeployed = True)
\mathbf{public}\ \mathit{getControllingMission}\ \widehat{=}\ \mathbf{var}\ \mathit{ret}: \mathit{MissionID}\ \bullet
(ret := controllingMission)
public abort \stackrel{\frown}{=}
(this. abort := True)
public clean Up \cong \mathbf{var} \ ret : \mathbb{B} \bullet
(ret := (\neg abort = \mathbf{True}))
• Skip
```

${\bf section}\ Land {\it Mission Meth Chan}\ {\bf parents}\ scj_prelude, {\it Global Types}, {\it Mission Id}, {\it Schedulable Id}$

$$\label{lem:channel} \begin{split} \textbf{channel} & stowLandingGearCall: MissionID \times SchedulableID \\ \textbf{channel} & stowLandingGearRet: MissionID \times SchedulableID \\ \end{split}$$

 $\textbf{channel} \ is Landing Gear Deployed Call: \ Mission ID \times Schedulable ID \\ \textbf{channel} \ is Landing Gear Deployed Ret: \ Mission ID \times Schedulable ID \times \mathbb{B}$

 ${\bf channel}\ getControlling {\it Mission Call}: {\it Mission ID}$

 $\mathbf{channel}\, getControllingMissionRet: MissionID \times MissionID$

 $\begin{array}{l} \textbf{channel} \ abort Call: Mission ID \\ \textbf{channel} \ abort Ret: Mission ID \end{array}$

 $\begin{array}{l} \textbf{channel} \ clean Up Call : \textit{MissionID} \\ \textbf{channel} \ clean Up Ret : \textit{MissionID} \times \mathbb{B} \end{array}$

$$\label{lem:channel} \begin{split} \textbf{channel} \ deployLandingGearCall: \textit{MissionID} \times \textit{SchedulableID} \times \textit{ThreadID} \\ \textbf{channel} \ deployLandingGearRet: \textit{MissionID} \times \textit{SchedulableID} \times \textit{ThreadID} \end{split}$$

5.8 Schedulables of LandMission

end

 ${\bf section} \ Landing Gear Handler Land App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Ids, Method Calley, Land Mission Meth Chan, Object Ids, Thread Ids$

```
process Landing Gear Handler Land App \cong
                    mission: MissionID \bullet \mathbf{begin}
handle A sync Event \cong
          handle A sync Event Call. Landing Gear Handler Land SID \longrightarrow
                     binder\_isLandingGearDeployedCall. mission. LandingGearHandlerLandSID \longrightarrow
                    binder\_is Landing Gear Deployed Ret: mission: Landing Gear Handler Land SID? is Landing Gear Deployed \longrightarrow Compared Compa
                    \mathbf{var}\ landing Gear Is Deployed: \mathbb{B} \bullet landing Gear Is Deployed: is Landing Gear Deployed;
                    if landingGearIsDeployed = True \longrightarrow
                                                    binder\_stowLandingGearCall\ .\ mission\ .\ LandingGearHandlerLandSID\ .
                                                   binder\_stowLandingGearRet.\ mission.\ LandingGearHandlerLandSID-mission.\ LandingGearHandlerLandSID-
                                                  Skip
                    binder\_deployLandingGearCall . mission . LandingGearHandlerLandSID . LandingGearHandlerLandTID
                                                   binder\_deployLandingGearRet\ .\ mission\ .\ LandingGearHandlerLandSID\ .\ LandingGearHandlerLandTID
          handle A sync Event Ret . Landing Gear Handler Land SID \longrightarrow
         Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_aperiodic\_app . LandingGearHandlerLandSID \longrightarrow \mathbf{Skip})
```

```
process SafeLandingHandlerApp \cong
mainMission : MissionID,
threshold : \mathbb{P} \mathbb{A} \bullet \mathbf{begin}

handleAsyncEvent \cong

\begin{pmatrix} handleAsyncEvent \subseteq \\ handleAsyncEventCall . SafeLandingHandlerSID \longrightarrow \\ binder\_getAltitudeCall . mainMission . SafeLandingHandlerSID <math>\cong

var altitude : \mathbb{P} \mathbb{A} \bullet \mathbf{altitude} := \mathbf{getAltitude} : \mathbf{getAltitu
```

${\bf section} \ Safe Landing Handler Class \ {\bf parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safe let Chan, Method Call Binding Channels$
${\bf class} Safe Landing Handler Class \stackrel{\frown}{=} {\bf begin}$
state State
$threshold: \mathbb{P} \mathbb{A}$
state State _ initial Init
State'
• Skip
end

 ${\bf section} \ \ Ground Distance Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Ids, Method Call Birger, Main Mission Meth Chan$

```
\begin{aligned} & process \ Ground Distance Monitor App \ \cong\\ & main Mission : Mission ID \bullet \mathbf{begin} \end{aligned} hand le A sync Event \ \cong\\ & \begin{pmatrix} hand le A sync Event \ \cong\\ & \begin{pmatrix} hand le A sync Event \ Call \ . \ Ground Distance Monitor SID \longrightarrow\\ & binder\_get Altitude Call \ . \ main Mission \ . \ Ground Distance Monitor SID \ ?\ get Altitude \longrightarrow\\ & \mathbf{var}\ distance : \ \mathbb{P} \ \mathbb{A} \bullet\ distance :=\ get Altitude;\\ & \mathbf{if}\ (distance =\ reading On Ground) \longrightarrow\\ & \begin{pmatrix} request Termination Call \ . \ main Mission \ . \ Ground Distance Monitor SID \longrightarrow\\ & request Termination Ret \ . \ main Mission \ . \ Ground Distance Monitor SID \ ?\ request Termination \longrightarrow\\ & \mathbf{Skip} \\ & \mathbf{fi} \\ & hand le A sync Event Ret \ . \ Ground Distance Monitor SID \longrightarrow\\ & \mathbf{Skip} \\ \end{aligned} Methods \ \cong\\ & \begin{pmatrix} hand le A sync Event Ret \ . \ Ground Distance Monitor SID \longrightarrow\\ & \mathbf{Skip} \\ \end{aligned}
```

ullet (Methods) \triangle (end_periodic_app . GroundDistanceMonitorSID \longrightarrow **Skip**)

${\bf section} \ \ Ground Distance Monitor Class \ \ {\bf parents} \ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}\ Ground Distance Monitor Class\ \widehat{=}\ {\bf begin}$
state State
$readingOnGround: \mathbb{P}\mathbb{A}$
$\mathbf{state}\mathit{State}$
_ initial Init
State'
• Skip
end

```
 \begin{aligned} \mathbf{process} & \textit{InstrumentLandingSystemMonitorApp} \; \widehat{=} \\ & \textit{mission} : \textit{MissionID} \; \bullet \; \mathbf{begin} \\ \\ & \textit{handleAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ & \mathbf{Skip}; \\ & \textit{handleAsyncEventRet} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ & \mathbf{Skip} \\ \\ & \mathbf{Methods} \; \widehat{=} \\ & (\textit{handleAsyncEvent}) \; ; \; \; \textit{Methods} \\ \\ & \bullet \; (\textit{Methods}) \; \triangle \; (\textit{end\_periodic\_app} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \mathbf{Skip}) \\ \\ & \mathbf{end} \end{aligned}
```