aircraft

Tight Rope v0.75

$25 \mathrm{th}$ February 2017

1 ID Files

1.1 MissionIds

 ${\bf section}\ {\it MissionIds}\ {\bf parents}\ {\it scj_prelude}, {\it MissionId}$

$$\label{lem:main_model} \begin{split} & \textit{MainMissionMID}: \textit{MissionID} \\ & \textit{TakeOffMissionMID}: \textit{MissionID} \\ & \textit{CruiseMissionMID}: \textit{MissionID} \\ & \textit{LandMissionMID}: \textit{MissionID} \end{split}$$

 $distinct \langle null Mission Id, Main Mission MID, Take Off Mission MID, Cruise Mission MID, Land Mission MID \rangle$

1.2 SchedulablesIds

 ${\bf section} \ Schedulable Ids \ {\bf parents} \ scj_prelude, Schedulable Id$

 $\label{lem:main} MainMissionSequencerSID: SchedulableID\\ ACModeChanger2SID: SchedulableID\\ EnvironmentMonitorSID: SchedulableID\\ ControlHandlerSID: SchedulableID\\ FlightSensorsMonitorSID: SchedulableID\\ CommunicationsHandlerSID: SchedulableID\\ LandingGearHandlerSID: SchedulableID\\ TakeOffMonitorSID: SchedulableID\\ TakeOffFailureHandlerSID: SchedulableID\\ TakeOf$

 $Begin Landing Handler SID: Schedulable ID\\ Navigation Monitor SID: Schedulable ID\\ Ground Distance Monitor SID: Schedulable ID\\ Landing Gear Handler Land SID: Schedulable ID$

In strument Landing System Monitor SID: Schedulable ID

Safe Landing Handler SID: Schedulable ID

 $distinct \langle null Sequencer Id, null Schedulable Id, Main Mission Sequencer SID,$

 $A {\it CMode Changer 2SID}, {\it Environment Monitor SID},$

Control Handler SID, Flight Sensors Monitor SID,

Communications Handler SID, Landing Gear Handler SID,

TakeOffMonitorSID, TakeOffFailureHandlerSID,

BeginLanding Handler SID, Navigation Monitor SID,

Ground Distance Monitor SID, Landing Gear Handler Land SID,

InstrumentLandingSystemMonitorSID, SafeLandingHandlerSID

1.3	Non-Paradigm	Objects
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1.4 ThreadIds

 ${\bf section}\ ThreadIds\ {\bf parents}\ scj_prelude, GlobalTypes$

 $Safe let TId: Thread ID \\ null Thread Id: Thread ID$

 $\overline{distinct\langle SafeletTId, nullThreadId\rangle}$

1.5 ObjectIds

2 Network

2.1 Network Channel Sets

```
section NetworkChannels parents scj\_prelude, MissionId, MissionIds,
       Schedulable Id, Schedulable Ids, Mission Chan, Top Level Mission Sequencer FWChan,
       Framework Chan, Safelet Chan, Aperiodic Event Handler Chan, Managed Thread Chan,
       One Shot Event Handler Chan, Periodic Event Handler Chan, Mission Sequencer Meth Chan
channelset TerminateSync ==
       \{ schedulables\_terminated, schedulables\_stopped, get\_activeSchedulables \} 
channelset ControlTierSync ==
       \{ | start\_toplevel\_sequencer, done\_toplevel\_sequencer, done\_safeletFW | \}
channelset TierSync ==
       \{| start\_mission . MainMission, done\_mission . MainMission,
       done\_safeletFW, done\_toplevel\_sequencer }
{f channel set} \ {\it Mission Sync} ==
       \{|done\_safeletFW, done\_toplevel\_sequencer, register, \}
signal Termination Call, signal Termination Ret, activate\_schedulables, done\_schedulable,
cleanupSchedulableCall, cleanupSchedulableRet
channelset SchedulablesSync ==
       \{|activate\_schedulables, done\_safeletFW, done\_toplevel\_sequencer\}\}
channelset ClusterSync ==
       \{|done\_toplevel\_sequencer, done\_safeletFW|\}
channelset SafeltAppSync \cong
\{ getSequencerCall, getSequencerRet, initializeApplicationCall, initializeApplicationRet, end\_safelet\_app \} \}
channelset MissionSequencerAppSync ==
\{|getNextMissionCall, getNextMissionRet, end\_sequencer\_app|\}
channelset MissionAppSync ==
\{|initializeCall, register, initializeRet, cleanupMissionCall, cleanupMissionRet|\}
channelset AppSync ==
       \bigcup \{SafeltAppSync, MissionSequencerAppSync, MissionAppSync, \\
       MTAppSync, OSEHSync, APEHSync, PEHSync,
       \{|getSequencer, end\_mission\_app, end\_managedThread\_app, | end\_managed
       setCeilinqPriority, requestTerminationCall, requestTerminationRet, terminationPendinqCall,
       terminationPendingRet, handleAsyncEventCall, handleAsyncEventRet \} 
channelset ThreadSunc ==
       \{ raise\_thread\_priority, lower\_thread\_priority, isInterruptedCall, isInterruptedRet, get\_priorityLevel \} \}
channelset LockingSync ==
       \{ lockAcquired, startSyncMeth, endSyncMeth, waitCall, waitRet, notify, isInterruptedCall, isInterruptedRet, \} \}
       interruptedCall, interruptedRet, done\_toplevel\_sequencer, get\_priorityLevel
channelset Tier0Sync ==
       \{|done\_toplevel\_sequencer, done\_safeletFW,
       start\_mission \ . \ Take O\!f\!f\!Mission, done\_mission \ . \ Take O\!f\!f\!Mission,
       initializeRet. TakeOffMission, requestTermination. TakeOffMission. MainMissionSequencer,
       start_mission. CruiseMission, done_mission. CruiseMission,
       initializeRet. CruiseMission, requestTermination. CruiseMission. MainMissionSequencer,
       start_mission . LandMission, done_mission . LandMission,
       initializeRet. LandMission, requestTermination. LandMission. MainMissionSequencer
```

2.2 MethodCallBinder

```
section MethodCallBindingChannels parents scj_prelude, GlobalTypes, FrameworkChan, MissionId, MissionIds,
         Schedulable Id, Schedulable Ids, Thread Ids
\mathbf{channel}\ binder\_setCabinPressureCall: \mathit{MissionID} \times \mathit{SchedulableID} \times \mathbb{P}\,\mathbb{A}
\mathbf{channel}\ binder\_setCabinPressureRet: MissionID \times SchedulableID
setCabinPressureLocs == \{MainMissionMID\}
setCabinPressureCallers == \{EnvironmentMonitorSID\}
channel binder\_setFuelRemainingCall: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
\mathbf{channel}\ binder\_setFuelRemainingRet: MissionID \times SchedulableID
setFuelRemainingLocs == \{MainMissionMID\}
setFuelRemainingCallers == \{EnvironmentMonitorSID\}
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
channel binder\_getAltitudeRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getAltitudeLocs == \{MainMissionMID\}
getAltitudeCallers == \{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerS, S
\mathbf{channel}\ binder\_setHeadingCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
{\bf channel}\ binder\_setHeadingRet: MissionID \times SchedulableID
setHeadingLocs == \{MainMissionMID\}
setHeadingCallers == \{FlightSensorsMonitorSID\}
{\bf channel}\ binder\_stowLandingGearCall: MissionID 	imes SchedulableID
\mathbf{channel}\ binder\_stowLandingGearRet: MissionID \times SchedulableID
stowLandingGearLocs == \{ TakeOffMissionMID, LandMissionMID \}
stowLandingGearCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
\mathbf{channel}\ binder\_takeOffAbortCall: MissionID \times SchedulableID
{\bf channel}\ binder\_takeOffAbortRet: MissionID \times SchedulableID
takeOffAbortLocs == \{ TakeOffMissionMID \}
takeOffAbortCallers == \{ TakeOffFailureHandlerSID \}
\mathbf{channel}\ binder\_setAltitudeCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
{\bf channel}\ binder\_setAltitudeRet: MissionID \times SchedulableID
```

 $setAltitudeLocs == \{MainMissionMID\}$

 $setAltitudeCallers == \{FlightSensorsMonitorSID\}$

```
channel binder\_qetHeadingCall: MissionID \times SchedulableID
channel binder\_getHeadingRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getHeadingLocs == \{MainMissionMID\}
getHeadingCallers == \{NavigationMonitorSID\}
\mathbf{channel}\ binder\_getAirSpeedCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAirSpeedRet: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
getAirSpeedLocs == \{MainMissionMID\}
getAirSpeedCallers == \{NavigationMonitorSID, TakeOffFailureHandlerSID\}
channel\ binder\_deployLandingGearCall: MissionID 	imes SchedulableID
channel binder\_deployLandingGearRet: MissionID \times SchedulableID
deployLandingGearLocs == \{ TakeOffMissionMID, LandMissionMID \}
deployLandingGearCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
channel binder\_setEmergencyOxygenCall: MissionID \times SchedulableID \times \mathbb{P} \, \mathbb{A}
channel binder\_setEmergencyOxygenRet: MissionID \times SchedulableID
setEmergencyOxygenLocs == \{MainMissionMID\}
setEmergencyOxygenCallers == \{EnvironmentMonitorSID\}
\mathbf{channel}\ binder\_setAirSpeedCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
\mathbf{channel}\ binder\_setAirSpeedRet: MissionID \times SchedulableID
setAirSpeedLocs == \{MainMissionMID\}
setAirSpeedCallers == \{FlightSensorsMonitorSID\}
{\bf channel}\ binder\_isLandingGearDeployedCall: MissionID 	imes SchedulableID
channel binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times \mathbb{B}
isLandingGearDeployedLocs == \{ TakeOffMissionMID, LandMissionMID \}
isLandingGearDeployedCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
channelset MethodCallBinderSync == \{ | done\_toplevel\_sequencer, \}
binder\_setCabinPressureCall, binder\_setCabinPressureRet,
binder\_setFuelRemainingCall, binder\_setFuelRemainingRet,
binder\_getAltitudeCall, binder\_getAltitudeRet,
binder_setHeadingCall, binder_setHeadingRet,
binder\_stowLandingGearCall, binder\_stowLandingGearRet,
binder\_takeOffAbortCall, binder\_takeOffAbortRet,
binder\_setAltitudeCall, binder\_setAltitudeRet,
binder\_getHeadingCall, binder\_getHeadingRet,
binder\_getAirSpeedCall, binder\_getAirSpeedRet,
binder\_deployLandingGearCall, binder\_deployLandingGearRet,
binder\_setEmergencyOxygenCall, binder\_setEmergencyOxygenRet,
binder\_setAirSpeedCall, binder\_setAirSpeedRet,
binder\_isLandingGearDeployedCall, binder\_isLandingGearDeployedRet
```

```
process Method Call Binder \stackrel{\frown}{=} begin
setCabinPressure\_MethodBinder \ \widehat{=}
              binder\_setCabinPressureCall? loc:(loc \in setCabinPressureLocs)? caller:(caller \in setCabinPressureCallers)? p1-
              setCabinPressureCall. loc. caller! p1 \longrightarrow
              setCabinPressureRet.loc.caller \longrightarrow
              binder\_setCabinPressureRet.\,loc.\,caller \longrightarrow
              setCabinPressure\_MethodBinder
setFuelRemaining\_MethodBinder \stackrel{\frown}{=}
              binder\_setFuelRemainingCall?loc:(loc \in setFuelRemainingLocs)?caller:(caller \in setFuelRemainingCallers)?p1
              setFuelRemainingCall.loc.caller!p1 \longrightarrow
              setFuelRemainingRet.loc.caller \longrightarrow
              binder\_setFuelRemainingRet.loc.caller \longrightarrow
              setFuelRemaining\_MethodBinder
getAltitude\_MethodBinder \stackrel{\frown}{=}
              binder\_getAltitudeCall? loc: (loc \in getAltitudeLocs)? caller: (caller \in getAltitudeCallers)—
              getAltitudeCall \:.\: loc \:.\: caller {\longrightarrow}
              getAltitudeRet.loc.caller?ret \longrightarrow
              binder\_getAltitudeRet \:.\: loc \:.\: caller \: !\: ret \longrightarrow
              getAltitude\_MethodBinder
setHeading\_MethodBinder \cong
              binder\_setHeadingCall?\ loc: (loc \in setHeadingLocs)?\ caller: (caller \in setHeadingCallers)?\ p1-binder\_setHeadingCall?\ loc: (loc \in setHeadingLocs)?\ caller: (caller \in setHeadingCallers)?\ p1-binder\_setHeadingCall?\ loc: (loc \in setHeadingLocs)?\ caller: (caller \in setHeadingCallers)?\ p1-binder\_setHeadingCallers)
              setHeadingCall.loc.caller!p1 \longrightarrow
              setHeadingRet.loc.caller \longrightarrow
              binder\_setHeadingRet. loc. caller \longrightarrow
              setHeading\_MethodBinder
stowLandingGear\_MethodBinder \stackrel{\frown}{=}
              binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)
              stowLandingGearCall.loc.caller \longrightarrow
              stowLandingGearRet.loc.caller \longrightarrow
              binder\_stowLandingGearRet.loc.caller \longrightarrow
              stowLandingGear\_MethodBinder
takeOffAbort\_MethodBinder \stackrel{\frown}{=}
              binder\_takeOffAbortCall?loc: (loc \in takeOffAbortLocs)? caller: (caller \in takeOffAbortCallers)
              takeOf\!fAbortCall\:.\:loc\:.\:caller {\longrightarrow}
              takeOffAbortRet.\,loc.\,caller {\longrightarrow}
              binder\_takeOffAbortRet. loc. caller \longrightarrow
              takeOffAbort\_MethodBinder
setAltitude\_MethodBinder \triangleq
              binder\_setAltitudeCall? loc: (loc \in setAltitudeLocs)? caller: (caller \in setAltitudeCallers)? p1-setAltitudeCallers)? p1-setAltitudeCallers? p1-setAltitudeCal
              setAltitudeCall . loc . caller ! p1 \longrightarrow
              setAltitudeRet . loc . caller \longrightarrow
              binder\_setAltitudeRet. loc. caller \longrightarrow
              setAltitude\_MethodBinder
```

section MethodCallBinder parents scj_prelude, MissionId, MissionIds, SchedulableId, SchedulableIds, MethodCallBindingChannels

, Main Mission Meth Chan, Land Mission Meth Chan

```
getHeading\_MethodBinder \ \widehat{=}
       binder\_getHeadingCall?\ loc: (loc \in getHeadingLocs)?\ caller: (caller \in getHeadingCallers)
       getHeadingCall\:.\:loc\:.\:caller {\longrightarrow}
       getHeadingRet.\,loc.\,caller\,?\,ret {\longrightarrow}
       binder\_getHeadingRet.loc.caller!ret \longrightarrow
       getHeading\_MethodBinder
getAirSpeed\_MethodBinder \stackrel{\frown}{=}
       binder\_getAirSpeedCall? loc:(loc \in getAirSpeedLocs)? caller:(caller \in getAirSpeedCallers) \longrightarrow
       getAirSpeedCall . loc . caller \longrightarrow
       getAirSpeedRet . loc . caller ? ret \longrightarrow
       binder\_getAirSpeedRet.loc.caller!ret \longrightarrow
       getAirSpeed\_MethodBinder
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_deployLandingGearCall? loc:(loc \in deployLandingGearLocs)? caller:(caller \in deployLandingGearCallers)
       deployLandingGearCall. loc. caller \longrightarrow
       deployLandingGearRet. loc. caller \longrightarrow
       binder\_deployLandingGearRet. loc. caller \longrightarrow
       deployLandingGear\_MethodBinder
setEmergencyOxygen\_MethodBinder \triangleq
       binder\_setEmergencyOxygenCall? loc:(loc \in setEmergencyOxygenLocs)? caller:(caller \in setEmergencyOxygenCocs)?
       setEmergencyOxygenCall\:.\:loc\:.\:caller\:!\:p1 {\longrightarrow}
       setEmergencyOxygenRet . loc . caller \longrightarrow
       binder\_setEmergencyOxygenRet.loc.caller \longrightarrow
       setEmergencyOxygen\_MethodBinder
setAirSpeed\_MethodBinder \stackrel{\frown}{=}
       binder\_setAirSpeedCall?loc:(loc \in setAirSpeedLocs)?caller:(caller \in setAirSpeedCallers)?p1-
       setAirSpeedCall.loc.caller!p1 \longrightarrow
       setAirSpeedRet.loc.caller \longrightarrow
       binder\_setAirSpeedRet.loc.caller \longrightarrow
       setAirSpeed\_MethodBinder
isLandingGearDeployed\_MethodBinder \cong
       binder\_isLandingGearDeployedCall? loc:(loc \in isLandingGearDeployedLocs)? caller:(caller \in isLandingGearDeployedLocs)?
       is Landing Gear Deployed Call\:.\:loc\:.\:caller {\longrightarrow}
       is Landing Gear Deployed Ret \:.\: loc \:.\: caller \:?\: ret {\longrightarrow}
       binder\_isLandingGearDeployedRet. loc. caller! ret \longrightarrow
```

 $is Landing Gear Deployed_Method Binder$

$\textit{BinderActions} \ \widehat{=} \\$

```
| setCabinPressure_MethodBinder | | | setFuelRemaining_MethodBinder | | getAltitude_MethodBinder | | setHeading_MethodBinder | | setHeading_MethodBinder | | stowLandingGear_MethodBinder | | takeOffAbort_MethodBinder | | setAltitude_MethodBinder | | getHeading_MethodBinder | | getAirSpeed_MethodBinder | | deployLandingGear_MethodBinder | | setEmergencyOxygen_MethodBinder | | setAirSpeed_MethodBinder | | setAindingGearDeployed_MethodBinder | | setAindingGearDeployed_MethodBinder | | setAindingGearDeployed_MethodBinder | setAindin
```

 $\bullet \ \mathit{BinderActions} \ \triangle \ (\mathit{done_toplevel_sequencer} \longrightarrow \mathbf{Skip})$

 \mathbf{end}

2.3 Locking

 $\begin{array}{l} \textbf{section} \ \ NetworkLocking \ \ \textbf{parents} \ \ scj_prelude, \ GlobalTypes, \ FrameworkChan, \ MissionId, \ MissionIds, \ ThreadIds, \ NetworkChannels, \ ObjectFW, \ ThreadFW, \ Priority \end{array}$

```
\begin{array}{l} \mathbf{process} \ Threads \ \widehat{=} \\ \mathbf{(Skip)} \\ \\ \mathbf{process} \ Objects \ \widehat{=} \\ \mathbf{(Skip)} \\ \\ \mathbf{process} \ Locking \ \widehat{=} \ Threads \ \llbracket \ ThreadSync \ \rrbracket \ Objects \\ \end{array}
```

2.4 Program

```
section Program parents scj_prelude, MissionId, MissionIds,
       Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Mission FW,
       Safe let FW, Top Level Mission Sequencer FW, Network Channels, Managed Thread FW,
       Schedulable {\it Mission Sequencer FW}, Periodic {\it Event Handler FW}, One {\it Shot Event Hand
       AperiodicEventHandlerFW, ObjectFW, ThreadFW,
       ACSafeletApp, MainMissionSequencerApp, MainMissionApp, ACModeChanger2App, ControlHandlerApp,
       Communications Handler App, Environment Monitor App, Flight Sensors Monitor App
       , Take Off Mission App, Landing Gear Handler App, Take Off Failure Handler App,
       Take Off Monitor App, Cruise Mission App, Begin Landing Handler App, Navigation Monitor App
       , LandMissionApp, LandingGearHandlerLandApp, SafeLandingHandlerApp, GroundDistanceMonitorApp,
       InstrumentLandingSystemMonitorApp
process ControlTier =
   SafeletFW
           [ControlTierSync]
   TopLevel Mission Sequencer FW (Main Mission Sequencer)
process Tier0 =
   MissionFW(MainMissionID)
           [MissionSync]
        Schedulable Mission Sequencer FW(ACMode Changer 2ID)
               [SchedulablesSync]
        Aperiodic Event Handler FW (Control Handler ID, aperiodic, (time (10, 0), null Schedulable Id))
               [SchedulablesSync]
       Aperiodic Event Handler FW (Communications Handler ID, aperiodic, (NULL, nullSchedulable Id))
               [SchedulablesSync]
        Periodic Event Handler FW (Environment Monitor ID, (time (10,0), NULL, NULL, null Schedulable Id))
               [SchedulablesSync]
         Periodic Event Handler FW (Flight Sensors Monitor ID, (time (10,0), NULL, NULL, null Schedulable Id))
process Tier1 =
    MissionFW(TakeOffMissionID)
           [MissionSync]
        Aperiodic Event Handler FW (Landing Gear Handler ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       Aperiodic Event Handler FW (Take Off Failure Handler ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       Periodic Event Handler FW (Take Off Monitor ID, (time (0,0), time (500,0), NULL, null Schedulable Id))
        [ClusterSync]
   MissionFW(CruiseMissionID)
           [MissionSync]
        AperiodicEventHandlerFW(BeginLandingHandlerID, aperiodic, (NULL, nullSchedulableId))
               [SchedulablesSync]
        Periodic Event Handler FW (Navigation Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
       [ClusterSync]
   MissionFW(LandMissionID)
           [MissionSync]
        Aperiodic Event Handler FW (Landing Gear Handler Land ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       AperiodicEventHandlerFW(SafeLandingHandlerID, aperiodic, (NULL, nullSchedulableId))
               [SchedulablesSync]
       Periodic Event Handler FW (Ground Distance Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id))
               [SchedulablesSync]
        Periodic Event Handler FW (Instrument Landing System Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id))
```

```
\mathbf{process}\,\mathit{Framework}\,\,\widehat{=}\,
  ControlTier
      [\![\mathit{TierSync}]\!]
        [Tier0Sync]
\mathbf{process} Application \cong
  ACS a felet App
  Main Mission Sequencer App
  MainMissionApp
  ACModeChanger2App(MainMissionID)
  Control Handler App
  Communications Handler App
  EnvironmentMonitorApp(MainMissionID)
  FlightSensorsMonitorApp(MainMissionID)
  Take Off Mission App
  Landing Gear Handler App(Take Off Mission ID)
  Take Off Failure Handler App (Mission ID, Take Off Mission ID, 10.0)
  TakeOffMonitorApp(MissionID, TakeOffMissionID, 10.0, landingGearHandlerID)
  Cruise Mission App
  BeginLandingHandlerApp(MissionID)
  NavigationMonitorApp(MissionID)
  LandMissionApp
  Landing Gear Handler Land App (Land Mission ID)
  SafeLandingHandlerApp(MissionID, 10.0)
  GroundDistanceMonitorApp(MissionID)
 InstrumentLandingSystemMonitorApp(LandMissionID)
```

 $\begin{array}{l} \textbf{process } Bound_Application \triangleq Application \parallel MethodCallBinderSync \parallel MethodCallBinder\\ \textbf{process } Program \triangleq (Framework \parallel AppSync \parallel Bound_Application) \parallel LockingSync \parallel LockingSy$

3 Safelet

 $\textbf{section} \ ACS a felet App \ \textbf{parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels Schedulable Ids, Safelet Chan, Method Channels Schedulable Ids, Safelet Channels Schedulable Ids, Safelet Chann$

```
\mathbf{process}\,\mathit{ACSafeletApp}\,\,\widehat{=}\,\,\mathbf{begin}
```

```
Initialize Application \ \widehat{=} \ \left( egin{array}{ll} initialize Application Call \longrightarrow \\ initialize Application Ret \longrightarrow \\ \mathbf{Skip} \end{array} \right)
```

 $\bullet \; (Methods) \; \triangle \; (end_safelet_app \longrightarrow \mathbf{Skip})$

4 Top Level Mission Sequencer

end

 $\begin{array}{c} \textit{State} \\ \textit{this}: \mathbf{ref} \ \textit{MainMissionSequencerClass} \\ \\ \hline \textit{State} \ \textit{State'} \\ \hline \textit{this'} = \mathbf{new} \ \textit{MainMissionSequencerClass}() \\ \\ \\ \textit{GetNextMission} \cong \mathbf{var} \ \textit{ret} : \textit{MissionID} \bullet \\ \textit{(getNextMissionCall . MainMissionSequencerSID} \longrightarrow \\ \textit{ret} := \textit{this . getNextMission}(); \\ \textit{getNextMissionRet . MainMissionSequencerSID} ! \ \textit{ret} \longrightarrow \\ \mathbf{Skip} \\ \\ \\ \textit{Methods} \cong \\ \textit{(GetNextMission)}; \ \textit{Methods} \\ \\ \bullet \ \textit{(Init ; Methods)} \triangle \ \textit{(end_sequencer_app . MainMissionSequencerSID} \longrightarrow \mathbf{Skip}) \\ \\ \end{array}$

 ${\bf section} \ Main Mission Sequencer Class \ {\bf parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels, Mission Id, Mission Ids$

 $\mathbf{class}\,\mathit{MainMissionSequencerClass} \; \widehat{=} \; \mathbf{begin}$

```
__ initial Init _____
State'
returnedMission' = False
```

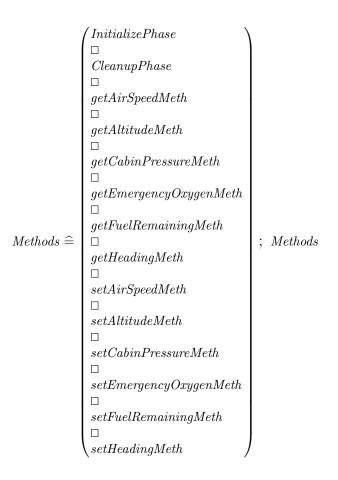
• Skip

5 Missions

5.1 MainMission

```
section MainMissionApp parents scj_prelude, MissionId, MissionIds,
     Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Main Mission Meth Chan
, Main Mission Class, Method Call Binding Channels \\
process MainMissionApp \stackrel{\frown}{=} begin
   State .
    this: \mathbf{ref}\ Main Mission\ Class
{f state}\ State
  Init
   State'
    this' = \mathbf{new} \, MainMissionClass()
InitializePhase \stackrel{\frown}{=}
  'initializeCall . MainMissionMID \longrightarrow
  register! ACModeChanger2SID! MainMissionMID \longrightarrow
  register! EnvironmentMonitorSID! MainMissionMID \longrightarrow
  register! ControlHandlerSID! MainMissionMID \longrightarrow
  register! FlightSensorsMonitorSID! MainMissionMID-
  register \ ! \ Communications Handler SID \ ! \ Main Mission MID-
  initializeRet . MainMissionMID \longrightarrow
  Skip
CleanupPhase \stackrel{\frown}{=}
  clean up {\it MissionRet} : {\it MainMissionMID} \ ! \ {\bf True} -
  Skip
getAirSpeedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  'getAirSpeedCall . MainMissionMID ? caller-
  ret := this.getAirSpeed();
  getAirSpeedRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
getAltitudeMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  \ 'getAltitudeCall . MainMissionMID ? caller –
  ret := this.getAltitude();
  getAltitudeRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
getCabinPressureMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getCabinPressure();
  get Cabin Pressure Ret\ .\ Main Mission MID\ !\ ret
  Skip
```

```
getEmergencyOxygenMeth = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getEmergencyOxygenCall. MainMissionMID \longrightarrow
  ret := this.getEmergencyOxygen();
  getEmergencyOxygenRet . MainMissionMID! ret
  Skip
getFuelRemainingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getFuelRemaining();
  getFuelRemainingRet \ . \ MainMissionMID \ ! \ ret
getHeadingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getHeadingCall. MainMissionMID? caller \longrightarrow
  ret := this.getHeading();
  getHeadingRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
setAirSpeedMeth \stackrel{\frown}{=}
  \ 'setAirSpeedCall . MainMissionMID ? caller ? airSpeed 2-
  this.setAirSpeed(airSpeed2);
  setAirSpeedRet . MainMissionMID . caller –
 Skip
setAltitudeMeth \triangleq
  \ 'set Altitude Call . Main Mission MID ? caller ? altitude-
  this.setAltitude(altitude);
  setAltitudeRet. MainMissionMID. caller-
  Skip
setCabinPressureMeth \ \widehat{=} \\
  \ 'set Cabin Pressure Call . Main Mission MID ? caller ? cabin Pressure -
  this.setCabinPressure(cabinPressure);
  set Cabin Pressure Ret . Main Mission MID . caller-
  Skip
setEmergencyOxygenMeth \stackrel{\frown}{=}
  setEmergencyOxygenCall . MainMissionMID? caller? emergencyOxygen
  this.setEmergencyOxygen(emergencyOxygen);
  setEmergencyOxygenRet . MainMissionMID . caller-
 Skip
setFuelRemainingMeth \stackrel{\frown}{=}
  \ 'setFuelRemainingCall . MainMissionMID ? caller ? fuelRemaining .
  this.setFuelRemaining(fuelRemaining);
  setFuelRemainingRet. MainMissionMID. caller \longrightarrow
 Skip
setHeadingMeth \triangleq
  this.setHeading(heading);
  setHeadingRet . MainMissionMID . caller
 Skip
```



 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end_mission_app} \; . \; \mathit{MainMissionMID} \longrightarrow \mathbf{Skip})$

 $\begin{array}{l} \textbf{section} \ \textit{MainMissionClass} \ \textbf{parents} \ \textit{scj_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan}, \textit{MethodCallBindingChannels} \\ \end{array}$

 ${f class}\, {\it Main Mission Class} \ \widehat{=} \ {f begin}$

 $\mathbf{public}\ \mathit{setCabinPressure}\ \widehat{=}$

(this.this.cabinPressure := cabinPressure)

```
state State
     ALTITUDE\_READING\_ON\_GROUND: \mathbb{P} A
     cabinPressure : \mathbb{P} \mathbb{A}
     emergencyOxygen: \mathbb{P}\,\mathbb{A}
    fuelRemaining: \mathbb{P} \mathbb{A}
     altitude: \mathbb{P}\,\mathbb{A}
     airSpeed: \mathbb{P} \mathbb{A}
     heading: \mathbb{P} \mathbb{A}
{f state}\ State
   initial Init
     State'
     ALTITUDE\_READING\_ON\_GROUND' = 0.0
public getAirSpeed = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := airSpeed)
\mathbf{public}\ getAltitude\ \widehat{=}\ \mathbf{var}\ ret: \mathbb{P}\,\mathbb{A}\,\bullet
(ret := altitude)
public getCabinPressure = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := cabinPressure)
public getEmergencyOxygen \stackrel{\frown}{=} \mathbf{var}\ ret : \mathbb{P}\ \mathbb{A} \bullet
(ret := emergencyOxygen)
public getFuelRemaining \cong \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := fuelRemaining)
public getHeading \cong \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := heading)
public setAirSpeed \stackrel{\frown}{=}
(airSpeed := airSpeed2)
public setAltitude \stackrel{\frown}{=}
(this.this.altitude := altitude)
```

```
\begin{array}{l} \textbf{public} \ setEmergencyOxygen \ \widehat{=} \\ \big(this.this.emergencyOxygen := emergencyOxygen\big) \\ \\ \textbf{public} \ setFuelRemaining \ \widehat{=} \\ \big(this.this.fuelRemaining := fuelRemaining\big) \\ \\ \textbf{public} \ setHeading \ \widehat{=} \\ \big(this.this.heading := heading\big) \\ \end{array}
```

 \bullet Skip

 \mathbf{end}

5.2 Schedulables of MainMission

end

 $\mathbf{section}\ ACModeChanger2App\ \mathbf{parents}\ TopLevelMissionSequencerChan,$ Mission Id, Mission Id, Schedulable Id, Schedulable Id, ACMode Changer 2 Class, Method Call Binding Channels $\mathbf{process}\,ACModeChanger2App\,\,\widehat{=}\,\,$ $controlling Mission: Mission ID \bullet \mathbf{begin}$ $State_{\perp}$ controlling Mission: Main Mission $\mathbf{state}\,\mathit{State}$ InitState'controlling Mission' = $GetNextMission \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet$ $ret := this . getNextMission(); \\ getNextMissionRet . ACModeChanger2SID ! ret \longrightarrow$ $Methods \mathrel{\widehat{=}}$ (GetNextMission); Methods • (Init; Methods) \triangle (end_sequencer_app. ACModeChanger2SID \longrightarrow Skip)

 $\begin{array}{l} \textbf{section} \ A C Mode Changer 2 \ Class \ \textbf{parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels, Mission Id, Mission Ids \end{array}$

 $\mathbf{class}\,\mathit{ACModeChanger2Class}\,\,\widehat{=}\,\,\mathbf{begin}$

```
\begin{array}{c} \textbf{state } State \\ modes Left : \mathbb{Z} \end{array}
```

 $\mathbf{state}\, State$

```
State'
modesLeft' = 3
```

```
'if (modesLeft = 3) \longrightarrow
     (modesLeft := modesLeft - 1;
     [] \neg (modesLeft = 3) \longrightarrow
    if (modesLeft = 2) \longrightarrow
     (modesLeft := modesLeft - 1;
     [] \neg (\dot{modesLeft} = 2) \longrightarrow
    if (modesLeft = 1) \longrightarrow
     (modesLeft := modesLeft - 1;)
     \ \ ret := LandMissionMID
[] \neg (\textit{modesLeft} = 1) \longrightarrow
     (ret := nullMissionId)
fi
fi
fi
```

• Skip

```
\mathbf{process} ControlHandlerApp \cong \mathbf{begin}
```

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; ControlHandlerSID \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip} \end{array} \right) \; ; \\ handleAsyncEventRet \; . \; ControlHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
\begin{aligned} & \textit{Methods} \; \widehat{=} \\ & \left( \textit{handleAsyncEvent} \right) \; ; \; \; \textit{Methods} \end{aligned}
```

 $\bullet \; (\mathit{Methods}) \; \triangle \; (\mathit{end_aperiodic_app} \; . \; \mathit{ControlHandlerSID} \longrightarrow \mathbf{Skip})$

 $\mathbf{process}\ Communications Handler App\ \widehat{=}\ \mathbf{begin}$

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; CommunicationsHandlerSID \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip} \end{array} \right) \; ; \\ handleAsyncEventRet \; . \; CommunicationsHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
Methods = (handleAsyncEvent); Methods
```

 $\bullet \; (Methods) \; \triangle \; (end_aperiodic_app \; . \; Communications Handler SID \longrightarrow \mathbf{Skip})$

 ${\bf section} \ Environment Monitor App \ {\bf parents} \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding, Main Mission Meth Chan$

 $process EnvironmentMonitorApp \stackrel{\frown}{=}$ $mainMission: MissionID \bullet \mathbf{begin}$ $State_$ controlling Mission: Main Mission ${f state}\ State$ InitState'controlling Mission' =handleAsyncEvent =Skip; $binder_setCabinPressureCall\:.\:controllingMission\:.\:EnvironmentMonitorSID\:!\:0 \longrightarrow$ $binder_setCabinPressureRet$. controllingMission. $EnvironmentMonitorSID \longrightarrow$ $binder_setEmergencyOxygenCall\ .\ controllingMission\ .\ EnvironmentMonitorSID\ !\ 0-lingMission\ .$ $binder_setEmergencyOxygenRet..controllingMission..EnvironmentMonitorSID {\longrightarrow}$ $binder_setFuelRemainingCall\ .\ controllingMission\ .\ EnvironmentMonitorSID\ !\ 0 \longrightarrow$ $binder_setFuelRemainingRet.\ controllingMission.\ EnvironmentMonitorSID {\longrightarrow}$ handle A sync Event Ret . $Environment Monitor SID \longrightarrow$ Skip $Methods \stackrel{\frown}{=}$ (handleAsyncEvent); Methods• $(Init; Methods) \triangle (end_periodic_app.EnvironmentMonitorSID \longrightarrow \mathbf{Skip})$ end

 $\textbf{section} \ Flight Sensors Monitor App \ \textbf{parents} \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding, Main Mission Meth Chan$

 $process FlightSensorsMonitorApp \cong$ $mainMission: MissionID \bullet \mathbf{begin}$ $State_$ controlling Mission: Main Mission ${f state}\ State$ InitState'controlling Mission' =handleAsyncEvent = $binder_setAirSpeedCall\ .\ controllingMission\ .\ FlightSensorsMonitorSID\ !\ 0-lightSensorsMonitorSid\ .$ $binder_setAirSpeedRet.\ controllingMission.\ FlightSensorsMonitorSID {\longrightarrow}$ $binder_setAltitudeCall\:.\:controllingMission\:.\:FlightSensorsMonitorSID\:!\:0 \longrightarrow$ $binder_setAltitudeRet \ . \ controllingMission \ . \ FlightSensorsMonitorSID \longrightarrow$ Skip; $binder_setHeadingCall\:.\:controllingMission\:.\:FlightSensorsMonitorSID\:!\:0 \longrightarrow$ $binder_setHeadingRet.controllingMission.FlightSensorsMonitorSID {\longrightarrow}$ handle A sync Event Ret. $Flight Sensors Monitor SID \longrightarrow$ Skip $Methods \stackrel{\frown}{=}$ (handleAsyncEvent); Methods• $(Init; Methods) \triangle (end_periodic_app.FlightSensorsMonitorSID \longrightarrow \mathbf{Skip})$ end

5.3 TakeOffMission

section TakeOffMissionApp **parents** scj_prelude, MissionId, MissionIds,

```
Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Take Off Mission Meth Chan
, \, Take Off Mission Class, \, Method Call Binding Channels \,
process TakeOffMissionApp \cong
     controlling {\it Mission ID} \bullet {\bf begin}
   State_{-}
    this: {f ref}\ Take Off Mission Class
    controlling Mission: Main Mission
{f state}\ State
  Init
   State'
   this' = \mathbf{new} \ TakeOffMissionClass()
    controlling Mission' =
InitializePhase \stackrel{\frown}{=}
  'initializeCall. TakeOffMissionMID \longrightarrow
  register \,!\, Landing Gear Handler SID \,!\, Take Off Mission MID-
  register \ ! \ Take Off Monitor SID \ ! \ Take Off Mission MID \longrightarrow
  register! Take Off Failure Handler SID! Take Off Mission MID
  initializeRet. TakeOffMissionMID \longrightarrow
  Skip
CleanupPhase \stackrel{\frown}{=}
  \mathbf{var}\,\mathbb{B}:ret\,ullet
  clean up {\it Mission Call} \;. \; Take O \! f \! f \! M is sion M ID-
    Skip;
  cleanup {\it Mission Ret} \;. \; Take {\it Off Mission MID} \;! \; ret
  Skip
takeOffAbortMeth \mathrel{\widehat{=}}
  takeOffAbortCall . TakeOffMissionMID ? caller \longrightarrow
  this. takeOffAbort();
  take {\it OffAbortRet}\;.\; Take {\it OffMissionMID}\;.\; caller
  Skip
deployLandingGearMeth \stackrel{\frown}{=}
  deploy Landing Gear Call. Take Off Mission MID? caller-
  this. deployLandingGear();
  deploy Landing Gear Ret.\ Take Off Mission MID.\ caller
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  stowLandingGearCall . TakeOffMissionMID? caller-
  this.stowLandingGear();
  stowLandingGearRet.\ TakeOffMissionMID\ .\ caller
  Skip
```

```
is Landing Gear Deployed Meth \ensuremath{\widehat{=}} \mathbf{var} \ ret : \mathbb{B} \bullet \\ is Landing Gear Deployed Call \ . \ Take Off Mission MID \ ? \ caller \longrightarrow \\ ret := this \ . \ is Landing Gear Deployed (); \\ is Landing Gear Deployed Ret \ . \ Take Off Mission MID \ . \ caller \ ! \ ret \longrightarrow \\ \mathbf{Skip}
```

```
Methods \triangleq \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ takeOffAbortMeth \\ \Box \\ deployLandingGearMeth \\ \Box \\ stowLandingGearMeth \\ \Box \\ isLandingGearDeployedMeth \end{pmatrix}; Methods
```

 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end_mission_app} \; . \; \mathit{TakeOffMissionMID} \longrightarrow \mathbf{Skip})$

 $\begin{array}{l} \textbf{section} \ \ Take Off Mission Class \ \ \textbf{parents} \ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels \end{array}$

class $TakeOffMissionClass \stackrel{\frown}{=} \mathbf{begin}$

```
\begin{array}{c} \textbf{state } State \\ SAFE\_AIRSPEED\_THRESHOLD: \mathbb{P} \, \mathbb{A} \\ TAKEOFF\_ALTITUDE: \mathbb{P} \, \mathbb{A} \\ abort: \mathbb{B} \\ landing Gear Deployed: \mathbb{B} \end{array}
```

 $\mathbf{state}\,\mathit{State}$

```
\begin{array}{l} \mathbf{public} \ takeOffAbort \ \widehat{=} \\ \big(abort := \mathbf{True}\big) \\ \\ \mathbf{public} \ deployLandingGear \ \widehat{=} \\ \big(landingGearDeployed := \mathbf{True}\big) \\ \\ \mathbf{public} \ stowLandingGear \ \widehat{=} \\ \big(landingGearDeployed := \mathbf{False}\big) \\ \\ \mathbf{public} \ isLandingGearDeployed \ \widehat{=} \ \mathbf{var} \ ret : \mathbb{B} \bullet \\ \big(ret := landingGearDeployed\big) \end{array}
```

• Skip

 $\quad \mathbf{end} \quad$

5.4 Schedulables of TakeOffMission

end

 $\begin{array}{l} \textbf{section} \ Landing Gear Handler App \ \textbf{parents} \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Bindard, Take Off Mission Meth Chan \end{array} , \\ \begin{array}{l} Take Off Mission Meth Chan \end{array}$

```
process Landing Gear Handler App \cong
              mission: MissionID \bullet \mathbf{begin}
handle A sync Event \triangleq
       handle A sync Event Call . Landing Gear Handler SID \longrightarrow
              Skip;
              binder\_isLandingGearDeployedCall\ .\ mission\ .\ LandingGearHandlerSID {\longrightarrow}
              binder\_is Landing Gear Deployed Ret.\ mission.\ Landing Gear Handler SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Landing Gear Handler SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Landing Gear Handler SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Landing Gear Handler SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Landing Gear Handler SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Landing Gear Handler SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ Matthew SID\ ?\ is Landing Gear Deployed Ret.\ mission.\ mission.
              Skip; var\ landing\ Gear\ Is\ Deployed: \mathbb{B} \bullet \ landing\ Gear\ Is\ Deployed: = is\ Landing\ Gear\ Deployed;
              \mathbf{if} \ \mathit{landingGearIsDeployed} \longrightarrow
                                  binder\_stowLandingGearCall . mission . LandingGearHandlerSID
                                  binder\_stowLandingGearRet\ .\ mission\ .\ LandingGearHandlerSID
                                  Skip
              binder\_deployLandingGearCall . mission . LandingGearHandlerSID
                                  binder\_deployLandingGearRet\ .\ mission\ .\ LandingGearHandlerSID\ .
       handle A sync Event Ret \;.\; Landing Gear Handler SID {\longrightarrow}
      Skip
Methods =
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_aperiodic\_app . LandingGearHandlerSID \longrightarrow \mathbf{Skip})
```

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffFailureHandlerApp} \ \ \textbf{parents} \ \ \textit{AperiodicEventHandlerChan}, SchedulableId, SchedulableIds, MethodCallBing, MainMissionMethChan, TakeOffMissionMethChan \\ \end{array} \\$

```
process TakeOffFailureHandlerApp \cong
     mainMission: MissionID,
take off Mission: Mission ID,
threshold : \mathbb{P} \mathbb{A} \bullet \mathbf{begin}
handle A sync Event =
  'handle A sync Event Call . Take Off Failure Handler SID \longrightarrow
     binder\_getAirSpeedCall\ .\ mainMission\ .\ TakeOffFailureHandlerSID {\longrightarrow}
     binder\_getAirSpeedRet. mainMission. TakeOffFailureHandlerSID? getAirSpeed \longrightarrow
     Skip; var currentSpeed : \mathbb{P} \mathbb{A} \bullet currentSpeed := getAirSpeed;
     if(currentSpeed < threshold) \longrightarrow
            Skip;
             binder\_takeOffAbortCall\:.\:takeoffMission\:.\:TakeOffFailureHandlerSID \longrightarrow
             binder\_takeOffAbortRet. takeoffMission. TakeOffFailureHandlerSID \longrightarrow
             request Termination Call. take of fMission. Take Of fFailure Handler SID \longrightarrow
             request Termination Ret.\ take off Mission.\ Take Off Failure Handler SID\ ?\ request Termination
     [] \neg (currentSpeed < threshold) \longrightarrow
          (Skip)
  handle A sync Event Ret: Take Off Failure Handler SID {\longrightarrow}
  Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
```

 $\bullet \ (\textit{Methods}) \ \triangle \ (\textit{end_aperiodic_app} \ . \ \textit{TakeOffFailureHandlerSID} \longrightarrow \mathbf{Skip})$

 \mathbf{end}

$section \ \textit{TakeOffFailureHandlerClass} \ \textbf{parents} \ \textit{scj_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan}, \textit{MethodCallBindingChannels}$
class $TakeOffFailureHandlerClass = \mathbf{begin}$
_ state State
$threshold: \mathbb{P}\mathbb{A}$
state Stateinitial Init
State'
• Skip
end

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffMonitorApp} \ \ \textbf{parents} \ \ \textit{PeriodicEventHandlerChan}, SchedulableId, SchedulableIds, MethodCallBindingChan, MainMissionMethChan \end{array}$

```
process TakeOffMonitorApp \cong
     mainMission: MissionID,
takeOffMission: MissionID,
takeOffAltitude : \mathbb{P} \mathbb{A},
landingGear Handler: Schedulable ID ullet \mathbf{begin}
   State
    take o\!f\!f\!Mission: Take O\!f\!f\!Mission
\mathbf{state}\,\mathit{State}
   Init
   State'
   take off Mission' =
handle A sync Event \cong
  binder\_getAltitudeCall\:.\:mainMission\:.\:TakeOffMonitorSID {\longrightarrow}
     binder\_getAltitudeRet. mainMission. TakeOffMonitorSID? getAltitude \longrightarrow
     Skip; var altitude : \mathbb{P} \mathbb{A} \bullet altitude := getAltitude;
     if (altitude > takeOffAltitude) \longrightarrow
            Skip;
            release. landingGearHandler \longrightarrow
            Skip;
            request Termination Call\ .\ take off Mission\ .\ Take Off Monitor SID {\longrightarrow}
             request Termination Ret.\ take of fM is sion.\ Take Off Monitor SID\ ?\ request Termination
       \neg (altitude > takeOffAltitude) \longrightarrow \mathbf{Skip}
  handle A sync Event Ret. Take Off Monitor SID \longrightarrow
  Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
ullet (Init; Methods) \triangle (end_periodic_app. TakeOffMonitorSID \longrightarrow Skip)
```

${\bf section}\ \ Take Off Monitor Class\ {\bf parents}\ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}\; TakeOffMonitorClass\; \widehat{=}\; {\bf begin}$
state State
$takeOffAltitude: \mathbb{P} \mathbb{A}$
$\mathbf{state}\mathit{State}$
initial Init
State'
• Skip
end

5.5 CruiseMission

 $\begin{array}{l} \textbf{section} \ \ Cruise Mission App \ \textbf{parents} \ scj_prelude, Mission Id, Mission Ids, \\ Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Cruise Mission Meth Chan, \\ Method Call Binding Channels \end{array}$

 $\begin{array}{l} \textit{CleanupPhase} \; \widehat{=} \\ \left(\begin{array}{l} \textit{cleanupMissionCall} \; . \; \textit{CruiseMissionMID} \longrightarrow \\ \textit{cleanupMissionRet} \; . \; \textit{CruiseMissionMID} \; ! \; \textbf{True} \longrightarrow \\ \textbf{Skip} \end{array} \right)$

$$Methods \cong \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix}$$
; $Methods$

ullet (Init; Methods) \triangle (end_mission_app. CruiseMissionMID \longrightarrow **Skip**)

5.6 Schedulables of CruiseMission

 ${\bf section} \ Begin Landing Handler App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binder Chan, Method Chan,$

```
 \begin{aligned} & \textbf{process } \textit{BeginLandingHandlerApp} \triangleq \\ & \textit{controllingMission} : \textit{MissionID} \bullet \textbf{begin} \end{aligned}   \begin{aligned} & \textit{handleAsyncEvent} \triangleq \\ & \begin{pmatrix} \textit{handleAsyncEventCall} & \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textbf{Skip} \\ & \textit{requestTerminationCall} & \textit{controllingMission} & \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textbf{requestTerminationRet} & \textit{controllingMission} & \textit{BeginLandingHandlerSID} ? \textit{requestTermination} \longrightarrow \\ & \textbf{Skip} \\ & \textit{handleAsyncEventRet} & \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textbf{Skip} \\ & \\ & \textit{Methods} \triangleq \\ & \textit{(handleAsyncEvent)} ; \textit{ Methods} \end{aligned}   \bullet & \textit{(Methods)} \triangle & \textit{(end\_aperiodic\_app} & \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip} )   \bullet & \text{end}   \bullet & \textit{(Methods)} \triangle & \textit{(end\_aperiodic\_app} & \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip} )   \bullet & \text{end}   \bullet & \textit{(Methods)} \triangle & \textit{(end\_aperiodic\_app} & \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip} )   \bullet & \text{(Methods)} \triangle & \textit{(end\_aperiodic\_app} & \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip} )   \bullet & \text{(Methods)} \triangle & \textit{(end\_aperiodic\_app} & \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip} )   \bullet & \text{(Methods)} \triangle & \textit{(end\_aperiodic\_app} & \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip} )   \bullet & \text{(Methods)} \triangle & \textit{(end\_aperiodic\_app} & \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip} )   \bullet & \text{(Methods)} \triangle & \textit{(end\_aperiodic\_app} & \textit{(e
```

 ${\bf section}\ \ Navigation Monitor App\ \ {\bf parents}\ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding Grant Mission Meth Chan$

```
\mathbf{process} \ Navigation Monitor App \ \widehat{=} 
              mainMission: MissionID \bullet \mathbf{begin}
handle A sync Event \triangleq
       \ 'handle A sync Event Call . Navigation Monitor SID {\longrightarrow}
               binder\_getHeadingCall\:.\:mainMission\:.\:NavigationMonitorSID \longrightarrow
               binder\_getHeadingRet.\ main Mission.\ Navigation Monitor SID\ ?\ getHeading-main Mission.
              Skip; var heading : \mathbb{P} \mathbb{A} \bullet heading := getHeading;
              binder\_getAirSpeedCall. mainMission. NavigationMonitorSID \longrightarrow
               binder\_getAirSpeedRet..mainMission..NavigationMonitorSID?.getAirSpeed \longrightarrow
              Skip; \operatorname{var} airSpeed : \mathbb{P} \mathbb{A} \bullet airSpeed := getAirSpeed;
              binder\_getAltitudeCall. mainMission. NavigationMonitorSID \longrightarrow
              binder\_getAltitudeRet..mainMission..NavigationMonitorSID?getAltitude-mainMission..NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID?getAltitude-mainMission...NavigationMonitorSID.getAltitude-mainMission...NavigationMonitorSID.getAltitude-mainMission...NavigationMonitorSID.getAltitude-mainMission...NavigationMonitorSID.getAltitude-mainMission...NavigationMonitorSID.getAltitude-mainMission...NavigationMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonitorMonito
              \mathbf{Skip}; \mathbf{var} altitude : \mathbb{P} \mathbb{A} \bullet altitude := getAltitude
        handle A sync Event Ret. Navigation Monitor SID \longrightarrow
       Skip
Methods =
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_periodic\_app . NavigationMonitorSID \longrightarrow \mathbf{Skip})
```

5.7 LandMission

section LandMissionApp parents scj_prelude, MissionId, MissionIds,

```
Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Land Mission Meth Chan, Chandel Methodologie, Marchan, M
, Land Mission Class, Method Call Binding Channels \\
process Land Mission App \cong
           controlling Mission: Mission ID \bullet \mathbf{begin}
       State_
         this: \mathbf{ref}\ Land Mission Class
         controlling Mission: Main Mission
state State
      Init
         State'
        this' = \mathbf{new} \ Land Mission Class()
         controllingMission' =
InitializePhase =
     'initializeCall . LandMissionMID \longrightarrow
     register! GroundDistanceMonitorSID! LandMissionMID \longrightarrow
     register! LandingGearHandlerLandSID! LandMissionMID \longrightarrow
     register \,!\, Instrument Landing System Monitor SID \,!\, Land Mission MID-
     register! SafeLandingHandlerSID! LandMissionMID \longrightarrow
      initializeRet . LandMissionMID \longrightarrow
     Skip
CleanupPhase =
     \mathbf{var}\,\mathbb{B}:ret\,ullet
     clean up {\it Mission Call}\:.\: Land {\it Mission MID}-
         Skip;
       ret := \mathbf{False}
      c\`leanup Mission Ret.\ Land Mission MID \ !\ ret-
    Skip
deployLandingGearMeth \stackrel{\frown}{=}
     deploy Landing Gear Call . Land Mission MID? caller-
     this.\ deployLandingGear();
      deploy Landing Gear Ret\ .\ Land Mission MID\ .\ caller-
     Skip
stowLandingGearMeth \stackrel{\frown}{=}
     \ 'stow Landing Gear Call . Land Mission MID ? caller-
      this.stowLandingGear();
      stow Landing Gear Ret\ .\ Land Mission MID\ .\ caller
     Skip
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
     is Landing Gear Deployed Call . Land Mission MID ? caller \longrightarrow
     ret := this.isLandingGearDeployed();
      is Landing Gear Deployed Ret \ . \ Land Mission MID \ . \ caller \ ! \ ret-
     Skip
```

$$Methods \triangleq \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ deployLandingGearMeth \\ \Box \\ stowLandingGearMeth \\ \Box \\ isLandingGearDeployedMeth \end{pmatrix}; Methods$$

 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end_mission_app} \; . \; \mathit{LandMissionMID} \longrightarrow \mathbf{Skip})$

 ${\bf section}\ Land Mission Class\ {\bf parents}\ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$

 $\mathbf{class}\,\mathit{LandMissionClass}\,\,\widehat{=}\,\,\mathbf{begin}$

```
\begin{array}{c} \textbf{state } State \\ SAFE\_LANDING\_ALTITUDE : \mathbb{P} \, \mathbb{A} \\ abort : \mathbb{B} \\ landing Gear Deployed : \mathbb{B} \end{array}
```

 ${f state}\, State$

```
\begin{array}{c} \textbf{initial } Init \\ State' \\ \hline SAFE\_LANDING\_ALTITUDE' = 10.0 \\ abort' = false \end{array}
```

```
\begin{array}{l} \textbf{public} \ deployLandingGear \ \widehat{=} \\ \big(landingGearDeployed := \textbf{True}\big) \\ \\ \textbf{public} \ stowLandingGear \ \widehat{=} \\ \big(landingGearDeployed := \textbf{False}\big) \\ \\ \textbf{public} \ isLandingGearDeployed \ \widehat{=} \ \textbf{var} \ ret : \mathbb{B} \bullet \\ \big(ret := landingGearDeployed\big) \end{array}
```

• Skip

5.8 Schedulables of LandMission

 ${\bf section} \ Landing Gear Handler Land App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Ids, Method Calley, Land Mission Meth Chan$

```
process Landing Gear Handler Land App \cong
                               mission: MissionID \bullet \mathbf{begin}
 handle A sync Event =
                handle A sync Event Call. Landing Gear Handler Land SID \longrightarrow
                               Skip;
                                binder\_isLandingGearDeployedCall\ .\ mission\ .\ LandingGearHandlerLandSID {\longrightarrow}
                                binder\_is Landing Gear Deployed Ret.\ mission.\ Landing Gear Handler Land SID\ ?\ is Landing Gear Deployed - the standard Control of the standard Co
                                Skip; var\ landing\ Gear\ Is\ Deployed: \mathbb{B} \bullet \ landing\ Gear\ Is\ Deployed: = is\ Landing\ Gear\ Deployed;
                               \mathbf{if} \ \mathit{landingGearIsDeployed} \longrightarrow
                                                                             binder\_stowLandingGearCall\ .\ mission\ .\ LandingGearHandlerLandSID
                                                                             binder\_stowLandingGearRet\ .\ mission\ .\ LandingGearHandlerLandSID-theory and the property of the property 
                                                                            Skip
                                [] \neg \mathit{landingGearIsDeployed} \longrightarrow
                                                                             binder\_deployLandingGearCall . mission . LandingGearHandlerLandSID
                                                                             binder\_deployLandingGearRet.\ mission.\ LandingGearHandlerLandSID-mission.\ LandingGearHandlerLandSI
                 handle A sync Event Ret. Landing Gear Handler Land SID \longrightarrow
              Skip
 Methods =
 (handleAsyncEvent); Methods
 • (Methods) \triangle (end\_aperiodic\_app . LandingGearHandlerLandSID \longrightarrow \mathbf{Skip})
```

• $(Methods) \triangle (end_aperiodic_app . SafeLandingHandlerSID \longrightarrow \mathbf{Skip})$

end

, MethodCallBindingChannels
$\textbf{class} Safe Landing Handler Class \widehat{=} \textbf{begin}$
state State
$threshold: \mathbb{P}\mathbb{A}$
state Stateinitial Init
State'
• Skip
end

 ${\bf section} \ \ Ground Distance Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Birgon, Main Mission Meth Chan$

```
process \ Ground Distance Monitor App \ \cong \\ main Mission : Mission ID \bullet begin \\ \\ hand le A sync Event \ \cong \\ \begin{pmatrix} hand le A sync Event Call . \ Ground Distance Monitor SID \longrightarrow \\ Skip; \\ binder\_get Altitude Call . \ main Mission . \ Ground Distance Monitor SID ? \ get Altitude \longrightarrow \\ Skip; \ var \ distance : \mathbb{P} \ \bullet \ \bullet \ distance : get Altitude; \\ if \ (distance = reading On Ground) \longrightarrow \\ \begin{pmatrix} Skip; \\ request Termination Call . \ main Mission . \ Ground Distance Monitor SID \longrightarrow \\ request Termination Ret . \ main Mission . \ Ground Distance Monitor SID ? \ request Termination \longrightarrow \\ Skip \\ \P \cap (distance = reading On Ground) \longrightarrow Skip \\ fi \\ hand le A sync Event Ret . \ Ground Distance Monitor SID \longrightarrow \\ Skip \\ \end{pmatrix}
Methods \ \cong
```

 $\bullet \ (\textit{Methods}) \ \triangle \ (\textit{end_periodic_app} \ . \ \textit{GroundDistanceMonitorSID} \longrightarrow \mathbf{Skip})$

end

(handleAsyncEvent); Methods

$ {\bf section} \ \ Ground Distance Monitor Class \ \ {\bf parents} \ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels $
${\bf class}\ Ground Distance Monitor Class\ \widehat{=}\ {\bf begin}$
state State
$readingOnGround: \mathbb{P} \mathbb{A}$
$\mathbf{state}\mathit{State}$
_ initial Init
State'
• Skip
end

```
 \begin{aligned} \mathbf{process} & \textit{InstrumentLandingSystemMonitorApp} \; \widehat{=} \\ & \textit{mission} : \textit{MissionID} \; \bullet \; \mathbf{begin} \end{aligned} \\ & \textit{handleAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ & \left( \mathbf{Skip} \right) \; ; \\ & \textit{handleAsyncEventRet} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ & \mathbf{Skip} \end{aligned} \\ & \mathcal{M}ethods \; \widehat{=} \\ & \left( \textit{handleAsyncEvent} \right) \; ; \; \textit{Methods} \end{aligned} \\ & \bullet \; \left( \textit{Methods} \right) \triangle \left( \textit{end\_periodic\_app} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \mathbf{Skip} \right) \end{aligned}
```