aircraft

Tight Rope v0.65 13th May 2016

1 ID Files

1.1 MissionIds

 ${\bf section}\ {\it MissionIds}\ {\bf parents}\ {\it scj_prelude}, {\it MissionId}$

$$\label{lem:main_model} \begin{split} & \textit{MainMissionMID}: \textit{MissionID} \\ & \textit{TakeOffMissionMID}: \textit{MissionID} \\ & \textit{CruiseMissionMID}: \textit{MissionID} \\ & \textit{LandMissionMID}: \textit{MissionID} \end{split}$$

 $distinct \langle null Mission Id, Main Mission MID, Take Off Mission MID, Cruise Mission MID, Land Mission MID \rangle$

1.2 SchedulablesIds

section SchedulableIds parents scj_prelude, SchedulableId

MainMissionSequencerSID : SchedulableID
ACModeChangerSID : SchedulableID
EnvironmentMonitorSID : SchedulableID
ControlHandlerSID : SchedulableID
FlightSensorsMonitorSID : SchedulableID
CommunicationsHandlerSID : SchedulableID
AperiodicSimulatorSID : SchedulableID

Landing Gear Handler Take Off SID: Schedulable ID

 $Take Off Monitor SID: Schedulable ID\\ Take Off Failure Handler SID: Schedulable ID\\ Begin Landing Handler SID: Schedulable ID\\ Navigation Monitor SID: Schedulable ID\\ Ground Distance Monitor SID: Schedulable ID\\ Landing Gear Handler Land SID: Schedulable ID\\$

Instrument Landing System Monitor SID: Schedulable ID

Safe Landing Handler SID: Schedulable ID

 $distinct \langle null Sequencer Id, null Schedulable Id, Main Mission Sequencer SID,$

 $A {\it CMode Changer SID}, Environment Monitor SID,$

Control Handler SID, Flight Sensors Monitor SID,

CommunicationsHandlerSID, AperiodicSimulatorSID,

 $Landing Gear Handler Take O\!f\!f\!SID, \, Take O\!f\!f\!Monitor SID,$

Take Off Failure Handler SID, Begin Landing Handler SID,

 $Navigation Monitor SID, \ Ground Distance Monitor SID,$

Landing Gear Handler Land SID, Instrument Landing System Monitor SID,

SafeLandingHandlerSID

1.3 ThreadIds

${\bf section}\ ThreadIds\ {\bf parents}\ scj_prelude, GlobalTypes$

Instrument Landing System Monitor TID: Thread ID

 $Safe Landing Handler TID: Thread ID \\ Ground Distance Monitor TID: Thread ID \\ Communications Handler TID: Thread ID$

ControlHandlerTID: ThreadID AperiodicSimulatorTID: ThreadID TakeOffFailureHandlerTID: ThreadID LandingGearHandlerLandTID: ThreadID EnvironmentMonitorTID: ThreadID FlightSensorsMonitorTID: ThreadID NavigationMonitorTID: ThreadID ACModeChangerTID: ThreadID BeginLandingHandlerTID: ThreadID

Landing Gear Handler Take Off TID: Thread ID

 $Take Off Monitor TID:\ Thread ID$

 $distinct \langle SafeletTId, nullThreadId,$

Instrument Landing System Monitor TID, Safe Landing Handler TID,

Ground Distance Monitor TID, Communications Handler TID,

Control Handler TID, Aperiodic Simulator TID,

Take Off Failure Handler TID, Landing Gear Handler Land TID,

Environment Monitor TID, Flight Sensors Monitor TID,

NavigationMonitorTID, ACModeChangerTID,

BeginLandingHandlerTID, LandingGearHandlerTakeOffTID,

TakeOffMonitorTID

1.4 ObjectIds

 ${\bf section}\ Object Ids\ {\bf parents}\ scj_prelude, Global Types$

 ${\it Take Off Mission OID: Object ID} \\ {\it Land Mission OID: Object ID}$

 $\overline{\textit{distinct} \langle \textit{TakeOffMissionOID}, \textit{LandMissionOID} \rangle}$

2 Network

2.1 Network Channel Sets

```
section NetworkChannels parents scj\_prelude, MissionId, MissionIds,
       Schedulable Id, Schedulable Ids, Mission Chan, Top Level Mission Sequencer FWChan,
       Framework Chan, Safelet Chan, Aperiodic Event Handler Chan, Managed Thread Chan,
       One Shot Event Handler Chan, Periodic Event Handler Chan, Mission Sequencer Meth Chan
channelset TerminateSync ==
       \{ schedulables\_terminated, schedulables\_stopped, get\_activeSchedulables \} 
channelset ControlTierSync ==
       \{ | start\_toplevel\_sequencer, done\_toplevel\_sequencer, done\_safeletFW | \}
channelset TierSync ==
       \{| start\_mission . MainMission, done\_mission . MainMission,
       done\_safeletFW, done\_toplevel\_sequencer }
{f channel set} \ {\it Mission Sync} ==
       \{|done\_safeletFW, done\_toplevel\_sequencer, register, \}
signal Termination Call, signal Termination Ret, activate\_schedulables, done\_schedulable,
cleanupSchedulableCall, cleanupSchedulableRet
channelset SchedulablesSync ==
       \{|activate\_schedulables, done\_safeletFW, done\_toplevel\_sequencer\}\}
channelset ClusterSync ==
       \{|done\_toplevel\_sequencer, done\_safeletFW|\}
channelset SafeltAppSync \cong
\{ getSequencerCall, getSequencerRet, initializeApplicationCall, initializeApplicationRet, end\_safelet\_app \} \}
channelset MissionSequencerAppSync ==
\{|getNextMissionCall, getNextMissionRet, end\_sequencer\_app|\}
channelset MissionAppSync ==
\{|initializeCall, register, initializeRet, cleanupMissionCall, cleanupMissionRet|\}
channelset AppSync ==
       \bigcup \{SafeltAppSync, MissionSequencerAppSync, MissionAppSync, \\
       MTAppSync, OSEHSync, APEHSync, PEHSync,
       \{|getSequencer, end\_mission\_app, end\_managedThread\_app, | end\_managed
       set Ceiling Priority, request Termination Call, request Termination Ret, termination Pending Call,
       terminationPendingRet, handleAsyncEventCall, handleAsyncEventRet \} 
channelset ThreadSunc ==
       \{ raise\_thread\_priority, lower\_thread\_priority, isInterruptedCall, isInterruptedRet, get\_priorityLevel \} \}
channelset LockingSync ==
       \{ lockAcquired, startSyncMeth, endSyncMeth, waitCall, waitRet, notify, isInterruptedCall, isInterruptedRet, \} \}
       interruptedCall, interruptedRet, done\_toplevel\_sequencer, get\_priorityLevel
channelset Tier0Sync ==
       \{|done\_toplevel\_sequencer, done\_safeletFW,
       start\_mission \ . \ Take O\!f\!f\!Mission, done\_mission \ . \ Take O\!f\!f\!Mission,
       initializeRet. TakeOffMission, requestTermination. TakeOffMission. MainMissionSequencer,
       start_mission. CruiseMission, done_mission. CruiseMission,
       initializeRet. CruiseMission, requestTermination. CruiseMission. MainMissionSequencer,
       start_mission . LandMission, done_mission . LandMission,
       initializeRet . LandMission, requestTermination . LandMission . MainMissionSequencer \}
```

2.2 MethodCallBinder

```
section MethodCallBindingChannels parents scj_prelude, GlobalTypes, FrameworkChan, MissionId, MissionIds,
         Schedulable Id, Schedulable Ids, Thread Ids
\textbf{channel} \ binder\_isLandingGearDeployedCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times \mathbb{B}
isLandingGearDeployedLocs == \{ TakeOffMissionMID \}
isLandingGearDeployedCallers == \{LandingGearHandlerTakeOffSID\}
{\bf channel}\ binder\_stowLandingGearCall: MissionID 	imes SchedulableID
\mathbf{channel}\ binder\_stowLandingGearRet: MissionID \times SchedulableID
stowLandingGearLocs == \{ TakeOffMissionMID \}
stowLandingGearCallers == \{LandingGearHandlerTakeOffSID\}
channel\ binder\_deployLandingGearCall: MissionID 	imes SchedulableID 	imes ThreadID
\textbf{channel} \ binder\_deployLandingGearRet: MissionID \times SchedulableID \times ThreadID
deployLandingGearLocs == \{ TakeOffMissionMID \}
deployLandingGearCallers == \{LandingGearHandlerTakeOffSID\}
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
channel binder\_getAltitudeRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getAltitudeLocs == \{MainMissionMID\}
getAltitudeCallers == \{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerStandard, GroundDistanceMonitorSID, GroundDistanceMoni
\mathbf{channel}\ binder\_getAirSpeedCall: MissionID \times SchedulableID
channel binder\_getAirSpeedRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getAirSpeedLocs == \{MainMissionMID\}
getAirSpeedCallers == \{NavigationMonitorSID, TakeOffFailureHandlerSID\}
{\bf channel}\ binder\_getHeadingCall: MissionID \times SchedulableID
channel binder\_getHeadingRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getHeadingLocs == \{MainMissionMID\}
```

```
\begin{split} getAirSpeedLocs &== \{MainMissionMID\} \\ getAirSpeedCallers &== \{NavigationMonitorSID, TakeOffFailureHandlerSID\} \end{split}
```

 $qetHeadingCallers == \{NavigationMonitorSID\}$

 $\begin{array}{l} \textbf{channel} \ binder_getAirSpeedCall: MissionID \times SchedulableID \\ \textbf{channel} \ binder_getAirSpeedRet: MissionID \times SchedulableID \times \mathbb{P} \, \mathbb{A} \end{array}$

```
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
channel binder\_qetAltitudeRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getAltitudeLocs == \{MainMissionMID\}
getAltitudeCallers == \{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerS, S
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
channel binder\_getAltitudeRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getAltitudeLocs == \{MainMissionMID\}
getAltitudeCallers == \{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerSide(State), S
{\bf channel}\ binder\_isLandingGearDeployedCall: MissionID 	imes SchedulableID
channel binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times \mathbb{B}
isLandingGearDeployedLocs == \{LandMissionMID\}
isLandingGearDeployedCallers == \{LandingGearHandlerLandSID\}
channel binder\_stowLandingGearCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_stowLandingGearRet: MissionID \times SchedulableID
stowLandingGearLocs == \{LandMissionMID\}
stowLandingGearCallers == \{LandingGearHandlerLandSID\}
\textbf{channel} \ binder\_deployLandingGearCall: \textit{MissionID} \times \textit{SchedulableID} \times \textit{ThreadID}
\textbf{channel} \ binder\_deployLandingGearRet: MissionID \times SchedulableID \times ThreadID
deployLandingGearLocs == \{LandMissionMID\}
deployLandingGearCallers == \{LandingGearHandlerLandSID\}
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAltitudeRet: \mathit{MissionID} \times \mathit{SchedulableID} \times \mathbb{P}\,\mathbb{A}
getAltitudeLocs == \{MainMissionMID\}
getAltitudeCallers == \{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerS, S
\mathbf{channelset} \ \mathit{MethodCallBinderSync} == \{ | \ \mathit{done\_toplevel\_sequencer}, \\
binder\_is Landing Gear Deployed Call, binder\_is Landing Gear Deployed Ret,
binder\_stowLandingGearCall, binder\_stowLandingGearRet,
binder\_deployLandingGearCall, binder\_deployLandingGearRet,
binder\_getAltitudeCall, binder\_getAltitudeRet,
binder\_getAirSpeedCall, binder\_getAirSpeedRet,
binder\_getHeadingCall, binder\_getHeadingRet,
```

 $binder_getAirSpeedCall, binder_getAirSpeedRet, \\binder_getAltitudeCall, binder_getAltitudeRet, \\binder_getAltitudeCall, binder_getAltitudeRet, \\$

 $binder_getAltitudeCall, binder_getAltitudeRet$ }

 $binder_is Landing Gear Deployed Call, binder_is Landing Gear Deployed Ret,$

 $binder_stowLandingGearCall, binder_stowLandingGearRet, \\binder_deployLandingGearCall, binder_deployLandingGearRet, \\$

```
process Method Call Binder \stackrel{\frown}{=} begin
isLandingGearDeployed\_MethodBinder \stackrel{\frown}{=}
       binder\_isLandingGearDeployedCall? loc:(loc \in isLandingGearDeployedLocs)? caller:(caller \in isLandingGearDeployedLocs)?
       isLandingGearDeployedCall.loc.caller \longrightarrow
       isLandingGearDeployedRet. loc. caller? ret \longrightarrow
       binder\_isLandingGearDeployedRet.loc.caller!ret \longrightarrow
       is Landing Gear Deployed\_Method Binder
stowLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)-
       stowLandingGearCall.loc.caller \longrightarrow
       stowLandingGearRet.loc.caller \longrightarrow
       binder\_stowLandingGearRet.loc.caller \longrightarrow
       stowLandingGear\_MethodBinder
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_deployLandingGearCall? loc:(loc \in deployLandingGearLocs)? caller:(caller \in deployLandingGearCallers)
       deployLandingGearCall. loc. caller. callingThread \longrightarrow
       deployLandingGearRet. loc. caller. callingThread \longrightarrow
       binder\_deployLandingGearRet. loc. caller. callingThread \longrightarrow
       deployLandingGear\_MethodBinder
qetAltitude\_MethodBinder \stackrel{\frown}{=}
       binder\_getAltitudeCall? loc: (loc \in getAltitudeLocs)? caller: (caller \in getAltitudeCallers) - getAltitudeCallers
       getAltitudeCall.loc.caller \longrightarrow
       getAltitudeRet.loc.caller?ret \longrightarrow
       binder\_getAltitudeRet.loc.caller!ret \longrightarrow
       getAltitude\_MethodBinder
getAirSpeed\_MethodBinder \ \widehat{=}
       binder\_getAirSpeedCall? loc: (loc \in getAirSpeedLocs)? caller: (caller \in getAirSpeedCallers)-
       getAirSpeedCall.loc.caller \longrightarrow
       getAirSpeedRet.loc.caller?ret \longrightarrow
       binder\_getAirSpeedRet.loc.caller!ret \longrightarrow
       getAirSpeed\_MethodBinder
getHeading\_MethodBinder \stackrel{\frown}{=}
       binder\_getHeadingCall? loc: (loc \in getHeadingLocs)? caller: (caller \in getHeadingCallers)-
       getHeadingCall.loc.caller \longrightarrow
       getHeadingRet.\,loc.\,caller\,?\,ret {\longrightarrow}
       binder\_getHeadingRet.loc.caller!ret \longrightarrow
       getHeading\_MethodBinder
getAirSpeed\_MethodBinder \cong
       binder\_getAirSpeedCall? loc: (loc \in getAirSpeedLocs)? caller: (caller \in getAirSpeedCallers)-
       getAirSpeedCall . loc . caller \longrightarrow
       getAirSpeedRet . loc . caller ? ret \longrightarrow
       binder\_getAirSpeedRet.loc.caller!ret \longrightarrow
       getAirSpeed\_MethodBinder
```

section MethodCallBinder parents scj_prelude, MissionId, MissionIds, SchedulableId, SchedulableIds, MethodCallBindingChannels

```
qetAltitude\_MethodBinder \stackrel{\frown}{=}
       binder\_getAltitudeCall?\ loc: (loc \in getAltitudeLocs)?\ caller: (caller \in getAltitudeCallers)-
       getAltitudeCall.loc.caller \longrightarrow
       getAltitudeRet . loc . caller ? ret \longrightarrow
       binder\_getAltitudeRet. loc. caller! ret \longrightarrow
       getAltitude\_MethodBinder
getAltitude\_MethodBinder \stackrel{\frown}{=}
       binder\_getAltitudeCall? loc: (loc \in getAltitudeLocs)? caller: (caller \in getAltitudeCallers)—
       getAltitudeCall\:.\:loc\:.\:caller {\longrightarrow}
       getAltitudeRet.loc.caller?ret \longrightarrow
       binder\_getAltitudeRet.loc.caller!ret \longrightarrow
       qetAltitude\_MethodBinder
isLandingGearDeployed\_MethodBinder \stackrel{\frown}{=}
       binder\_isLandingGearDeployedCall? loc: (loc \in isLandingGearDeployedLocs)? caller: (caller \in isLandingGearDeployedLocs)
       isLandingGearDeployedCall.loc.caller \longrightarrow
       isLandingGearDeployedRet . loc . caller ? ret \longrightarrow
       binder\_isLandingGearDeployedRet.loc.caller!ret \longrightarrow
       is Landing Gear Deployed\_Method Binder
stowLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)
       stowLandingGearCall\:.\:loc\:.\:caller {\longrightarrow}
       stowLandingGearRet . loc . caller \longrightarrow
       binder\_stowLandingGearRet.loc.caller \longrightarrow
       stowLandingGear\_MethodBinder
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_deployLandingGearCall? loc:(loc \in deployLandingGearLocs)? caller:(caller \in deployLandingGearCallers)
       deployLandingGearCall. loc. caller. callingThread \longrightarrow
       deployLandingGearRet. loc. caller. callingThread \longrightarrow
       binder\_deployLandingGearRet. loc. caller. callingThread \longrightarrow
       deployLandingGear\_MethodBinder
qetAltitude\_MethodBinder \stackrel{\frown}{=}
       binder\_getAltitudeCall? loc: (loc \in getAltitudeLocs)? caller: (caller \in getAltitudeCallers)
       getAltitudeCall.loc.caller \longrightarrow
       getAltitudeRet.loc.caller?ret \longrightarrow
       binder\_getAltitudeRet.loc.caller!ret \longrightarrow
       getAltitude\_MethodBinder
```

$BinderActions \stackrel{\frown}{=}$

 $\bullet \ \mathit{BinderActions} \ \triangle \ (\mathit{done_toplevel_sequencer} \longrightarrow \mathbf{Skip})$

 \mathbf{end}

2.3 Locking

 $\begin{array}{l} \textbf{section} \ \ NetworkLocking \ \textbf{parents} \ \ scj_prelude, \ GlobalTypes, \ FrameworkChan, \ MissionId, \ MissionIds, \ ThreadIds, \ NetworkChannels, \ ObjectFW, \ ThreadFW \end{array}$

```
process Threads =
  ThreadFW(InstrumentLandingSystemMonitorTID, 5)
  ThreadFW (Safe Landing Handler TID, 5) \\
  ThreadFW(GroundDistanceMonitorTID, 5)
  ThreadFW(CommunicationsHandlerTID, 5)
  ThreadFW(ControlHandlerTID, 5)
  ThreadFW(AperiodicSimulatorTID, 5)
  ThreadFW(TakeOffFailureHandlerTID, 5)
  ThreadFW(LandingGear Handler LandTID, 5)
  ThreadFW(EnvironmentMonitorTID, 5)
  ThreadFW(FlightSensorsMonitorTID, 5)
  ThreadFW(NavigationMonitorTID, 5)
  ThreadFW(ACModeChangerTID, 5)
  ThreadFW(BeginLandingHandlerTID, 5)
  ThreadFW(LandingGear HandlerTakeOffTID, 5)
 ThreadFW(TakeOffMonitorTID, 5)
process Objects =
  ObjectFW(\mathit{TakeOffMissionOID})
 ObjectFW(LandMissionOID)
```

 $\mathbf{process} \ Locking \ \widehat{=} \ ThreadSync \ \mathbb{I} \ Objects$

2.4 Program

```
section Program parents scj_prelude, MissionId, MissionIds,
       Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Mission FW,
       Safe let FW, Top Level Mission Sequencer FW, Network Channels, Managed Thread FW,
       Schedulable Mission Sequencer FW\,, Periodic Event Handler FW\,, One Shot Event Handle
       AperiodicEventHandlerFW, ObjectFW, ThreadFW,
       ACSafeletApp, MainMissionSequencerApp, MainMissionApp, ACModeChangerApp, ControlHandlerApp,
       Communications Handler App, Environment Monitor App, Flight Sensors Monitor App,
       Aperiodic Simulator App, Take Off Mission App, Landing Gear Handler Take Off App, Take Off Failure Handler App,
       Take Off Monitor App, Cruise Mission App, Begin Landing Handler App, Navigation Monitor App
       , LandMissionApp, LandingGearHandlerLandApp, SafeLandingHandlerApp, GroundDistanceMonitorApp,
       InstrumentLandingSystemMonitorApp
process ControlTier =
   SafeletFW
           [ControlTierSync]
   TopLevel Mission Sequencer FW (Main Mission Sequencer)
process Tier0 =
   MissionFW(MainMissionID)
           [MissionSync]
       Schedulable Mission Sequencer FW(ACMode Changer ID)
              [SchedulablesSync]
           Aperiodic Event Handler FW(Control Handler ID, (time (10,0), null))
                  [SchedulablesSync]
           Aperiodic Event Handler FW (Communications Handler ID, (NULL, null Schedulable Id))
              [SchedulablesSync]
           PeriodicEventHandlerFW (EnvironmentMonitorID, (time(10,0), NULL, NULL, nullSchedulableId))
                  [SchedulablesSync]
           Periodic Event Handler FW (Flight Sensors Monitor ID, (time (10,0), NULL, NULL, null Schedulable Id))
                  [SchedulablesSync]
             PeriodicEventHandlerFW(AperiodicSimulatorID, (time (10, 0), NULL, NULL, nullSchedulableId))
process Tier1 =
    MissionFW(TakeOffMissionID)
          [MissionSync]
           Aperiodic Event Handler FW (Landing Gear Handler Take Off ID, (NULL, null Schedulable Id))
                  [SchedulablesSync]
           AperiodicEventHandlerFW (TakeOffFailureHandlerID, (NULL, nullSchedulableId))
              [SchedulablesSync]
       PeriodicEventHandlerFW(TakeOffMonitorID, (time(0,0), time(500,0), NULL, nullSchedulableId))
       [ClusterSync]
    MissionFW(CruiseMissionID)
          [MissionSync]
       Aperiodic Event Handler FW (Begin Landing Handler ID, (NULL, null Schedulable Id))
              [SchedulablesSync]
       Periodic Event Handler FW (Navigation Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
       [ClusterSync]
   MissionFW(LandMissionID)
          [MissionSync]
           Aperiodic Event Handler FW (Landing Gear Handler Land ID, (NULL, null Schedulable Id))
                  [SchedulablesSync]
           AperiodicEventHandlerFW(SafeLandingHandlerID, (NULL, nullSchedulableId))
              [SchedulablesSync]
           Periodic Event Handler FW (Ground Distance Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id))
                  [SchedulablesSync]
           Periodic Event Handler FW (Instrument Landing System Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
```

```
\mathbf{process}\,\mathit{Framework}\,\,\widehat{=}\,
  ControlTier
      [\![\mathit{TierSync}]\!]
        [\![\mathit{Tier}0\mathit{Sync}]\!]
\mathbf{process} Application \cong
  ACS a felet App
  Main Mission Sequencer App
  MainMissionApp
  ACModeChangerApp(MainMissionID)
  Control Handler App
  Communications Handler App
  EnvironmentMonitorApp(MainMissionID)
  FlightSensorsMonitorApp(MainMissionID)
  AperiodicSimulatorApp(controlHandlerID)
  Take Off Mission App
  Landing Gear Handler Take Off App (\ Take Off Mission ID)
  Take Off Failure Handler App (Mission ID, Take Off Mission ID, 10.0)
  TakeOffMonitorApp(MissionID, TakeOffMissionID, 10.0, landingGearHandlerID)
  Cruise Mission App
  BeginLandingHandlerApp(MissionID)
  NavigationMonitorApp(MissionID)
  Land Mission App
  LandingGearHandlerLandApp(LandMissionID)
  Safe Landing Handler App (Mission ID, 10.0)
  GroundDistanceMonitorApp(MissionID)
 InstrumentLandingSystemMonitorApp(LandMissionID)
```

 $\mathbf{process}\,Program \ \widehat{=}\ \big(\,Framework\ [\![\ AppSync\]\!]\,\,ApplicationB\,\big)\,\,[\![\ LockingSync\]\!]\,\,Locking}$

3 Safelet

 $\mathbf{section}\ ACS a felet App\ \mathbf{parents}\ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$

```
\mathbf{process}\,\mathit{ACSafeletApp}\,\,\widehat{=}\,\,\mathbf{begin}
```

 $\bullet \; (Methods) \; \triangle \; (end_safelet_app \longrightarrow \mathbf{Skip})$

4 Top Level Mission Sequencer

 $\begin{array}{c} \textbf{section} \ \textit{MainMissionSequencerApp} \ \textbf{parents} \ \textit{TopLevelMissionSequencerChan}, \\ \textit{MissionId}, \textit{MissionIds}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{MainMissionSequencerClass}, \textit{MethodCallBindingChannels} \\ \textbf{process} \ \textit{MainMissionSequencerApp} \ \widehat{=} \ \textbf{begin} \\ \end{array}$

```
State = this : \mathbf{ref} \ MainMissionSequencerClass
\mathbf{state} \ State
Init = State' = \mathbf{new} \ MainMissionSequencerClass()
```

```
\begin{array}{l} \textit{Methods} \; \widehat{=} \\ \big( \, \textit{GetNextMission} \, \big) \; ; \; \; \textit{Methods} \end{array}
```

 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end_sequencer_app} \; . \; \mathit{MainMissionSequencerSID} \longrightarrow \mathbf{Skip})$

 $\begin{array}{l} \textbf{section} \ \textit{MainMissionSequencerClass} \ \textbf{parents} \ \textit{scj_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan} \\, \textit{MethodCallBindingChannels}, \textit{MissionId}, \textit{MissionIds} \\ \end{array}$

 ${\bf class}\, {\it Main Mission Sequencer Class} \,\, \widehat{=} \,\, {\bf begin}$

```
\_ state State \_ returned Mission: \mathbb{B}
```

 $\mathbf{state}\, State$

```
__ initial Init _____
State'
______
returnedMission' = False
```

• Skip

5 Missions

5.1 MainMission

```
section MainMissionApp parents sci_prelude, MissionId, MissionIds,
    Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Main Mission Meth Chan
, Main Mission Class, Method Call Binding Channels \\
process MainMissionApp \stackrel{\frown}{=} begin
   State_{-}
   this: {f ref}\ Main Mission Class
\mathbf{state}\,\mathit{State}
  Init
   State'
   this' = \mathbf{new} \, MainMissionClass()
InitializePhase =
  'initializeCall . MainMissionMID \longrightarrow
  register! ACModeChangerSID! MainMissionMID \longrightarrow
  register \ ! \ Environment Monitor SID \ ! \ Main Mission MID
  register \: ! \: Control Handler SID \: ! \: Main Mission MID \longrightarrow
  register! FlightSensorsMonitorSID! MainMissionMID \longrightarrow
  register! Communications Handler SID! Main Mission MID-
  register! AperiodicSimulatorSID! MainMissionMID \longrightarrow
  initializeRet \;.\; MainMissionMID {\longrightarrow}
  Skip
CleanupPhase \stackrel{\frown}{=}
  cleanup {\it MissionRet} \ . \ Main {\it MissionMID} \ ! \ {\bf True} -
  Skip
getAirSpeedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getAirSpeed();
  getAirSpeedRet.\ MainMissionMID.\ caller\ !\ ret
getAltitudeMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getAltitude();
  getAltitudeRet.\ MainMissionMID.\ caller\ !\ ret-
  Skip
getCabinPressureMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getCabinPressure();
  get Cabin Pressure Ret\ .\ Main Mission MID\ !\ ret
  Skip
```

```
getEmergencyOxygenMeth = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getEmergencyOxygenCall. MainMissionMID \longrightarrow
  ret := this.getEmergencyOxygen();
  getEmergencyOxygenRet.\ MainMissionMID \ !\ ret
  Skip
getFuelRemainingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this . getFuelRemaining();
  getFuelRemainingRet \ . \ MainMissionMID \ ! \ ret
getHeadingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getHeadingCall. MainMissionMID? caller \longrightarrow
  ret := this.getHeading();
  getHeadingRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
setAirSpeedMeth \stackrel{\frown}{=}
  \ 'setAirSpeedCall . MainMissionMID ? airSpeed-
  this . setAirSpeed(airSpeed);
  setAirSpeedRet . MainMissionMID
 Skip
setAltitudeMeth \triangleq
  \ 'set Altitude Call . Main Mission MID? altitude-
  this.setAltitude(altitude);
  setAltitudeRet. MainMissionMID \longrightarrow
  Skip
setCabinPressureMeth \stackrel{\frown}{=}
  \ 'set Cabin Pressure Call . Main Mission MID ? cabin Pressure -
  this.setCabinPressure(cabinPressure);
  set Cabin Pressure Ret . Main Mission MID
  Skip
setEmergencyOxygenMeth \stackrel{\frown}{=}
  this.setEmergencyOxygen(emergencyOxygen);
  setEmergencyOxygenRet \;.\; MainMissionMID {\longrightarrow}
 Skip
setFuelRemainingMeth \stackrel{\frown}{=}
  \ 'setFuelRemainingCall . MainMissionMID ? fuelRemaining-
  this . setFuelRemaining(fuelRemaining);
  setFuelRemainingRet. MainMissionMID \longrightarrow
 Skip
setHeadingMeth \stackrel{\frown}{=}
  this.setHeading(heading);
  setHeadingRet. MainMissionMID-
 Skip
```



 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end_mission_app} \; . \; \mathit{MainMissionMID} \longrightarrow \mathbf{Skip})$

 \mathbf{end}

 $\begin{array}{l} \textbf{section} \ \textit{MainMissionClass} \ \textbf{parents} \ \textit{scj_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan}, \textit{MethodCallBindingChannels} \\ \end{array}$

${f class}\, {\it Main Mission Class} \ \widehat{=} \ {f begin}$

```
state State
     ALTITUDE\_READING\_ON\_GROUND: \mathbb{P} \mathbb{A}
     test: \mathbb{Z}
     cabinPressure: \mathbb{P}\,\mathbb{A}
     emergencyOxygen: \mathbb{P} \mathbb{A}
    fuelRemaining: \mathbb{P} \mathbb{A}
     altitude: \mathbb{P}\,\mathbb{A}
     airSpeed: \mathbb{P} \mathbb{A}
     heading: \mathbb{P} \mathbb{A}
{f state}\ State
    \mathbf{initial}\ Init
     State'
public getAirSpeed = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := airSpeed)
\mathbf{public}\ getAltitude\ \widehat{=}\ \mathbf{var}\ ret: \mathbb{P}\,\mathbb{A}\,\bullet
(ret := altitude)
public getCabinPressure = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := cabinPressure)
public getEmergencyOxygen \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := emergencyOxygen)
public getFuelRemaining \cong \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := fuelRemaining)
public getHeading \cong \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
(ret := heading)
public setAirSpeed \stackrel{\frown}{=}
(this.this.airSpeed := airSpeed)
public setAltitude \stackrel{\frown}{=}
(this.this.altitude := altitude)
\mathbf{public}\ \mathit{setCabinPressure}\ \widehat{=}
(this.this.cabinPressure := cabinPressure)
```

```
\begin{array}{l} \textbf{public} \ setEmergencyOxygen \ \widehat{=} \\ \big(this.this.emergencyOxygen := emergencyOxygen\big) \\ \\ \textbf{public} \ setFuelRemaining \ \widehat{=} \\ \big(this.this.fuelRemaining := fuelRemaining\big) \\ \\ \textbf{public} \ setHeading \ \widehat{=} \\ \big(this.this.heading := heading\big) \\ \end{array}
```

 \bullet Skip

 \mathbf{end}

5.2 Schedulables of MainMission

 $\begin{array}{l} \textbf{section} \ A C Mode Changer App \ \textbf{parents} \ Top Level Mission Sequencer Chan, \\ Mission Ids, Schedulable Id, Schedulable Ids, A C Mode Changer Class, Method Call Binding Channels \\ \end{array}$

```
 \begin{aligned} \mathbf{process} & ACModeChangerApp \; \widehat{=} \\ & controllingMission : MissionID \; \bullet \; \mathbf{begin} \end{aligned}   \begin{aligned} & GetNextMission \; \widehat{=} \; \mathbf{var} \; ret : MissionID \; \bullet \\ & \left( getNextMissionCall \; . \; ACModeChangerSID \longrightarrow \\ & ret := this \; . \; getNextMission(); \\ & getNextMissionRet \; . \; ACModeChangerSID ! \; ret \longrightarrow \\ & \mathbf{Skip} \end{aligned}   \begin{aligned} & Methods \; \widehat{=} \\ & \left( GetNextMission \right) \; ; \; Methods \end{aligned}   \begin{aligned} & \bullet \; \left( Methods \right) \triangle \left( end\_sequencer\_app \; . \; ACModeChangerSID \longrightarrow \mathbf{Skip} \right) \end{aligned}   \end{aligned}   \end{aligned}   \end{aligned}   \begin{aligned} & \bullet \; \left( Methods \right) \triangle \left( end\_sequencer\_app \; . \; ACModeChangerSID \longrightarrow \mathbf{Skip} \right) \end{aligned}   \end{aligned}   \end{aligned}   \end{aligned}
```

 $\begin{array}{l} \textbf{section} \ A C Mode Changer Class \ \textbf{parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels, Mission Id, Mission Ids \end{array}$

 $\mathbf{class}\,\mathit{ACModeChangerClass}\,\,\widehat{=}\,\,\mathbf{begin}$

```
egin{array}{c} \mathbf{state} & State \\ & controlling Mission : Main Mission \\ & modes Left : \mathbb{Z} \end{array}
```

 $\mathbf{state}\,\mathit{State}$

```
State'
```

 $protected getNextMission = var ret : MissionID \bullet$

```
'if (modesLeft = 3) \longrightarrow
      (modesLeft := modesLeft - 1;
      \ \ \ \ \mathit{ret} := \mathit{TakeOffMissionMID}
[] \neg (modesLeft = 3) \longrightarrow
     if (modesLeft = 2) \longrightarrow
      (modesLeft := modesLeft - 1;)
      [] \neg (\dot{modesLeft} = 2) \longrightarrow
     if (modesLeft = 1) \longrightarrow
     (modesLeft := modesLeft - 1;)
      \ \ ret := LandMissionMID
[] \neg (\dot{modesLeft} = 1) \longrightarrow
     (ret := nullMissionId)
fi
fi
fi
```

• Skip

$\mathbf{process} \ \mathit{ControlHandlerApp} \ \widehat{=} \ \mathbf{begin}$

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; ControlHandlerSID \longrightarrow \\ \mathbf{Skip}; \\ handleAsyncEventRet \; . \; ControlHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
Methods = (handleAsyncEvent); Methods
```

 $\bullet \; (\mathit{Methods}) \; \triangle \; (\mathit{end_aperiodic_app} \; . \; \mathit{ControlHandlerSID} \longrightarrow \mathbf{Skip})$

$\mathbf{process}\ Communications Handler App\ \widehat{=}\ \mathbf{begin}$

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ handleAsyncEventCall \; . \; CommunicationsHandlerSID \longrightarrow \\ \mathbf{Skip}; \\ handleAsyncEventRet \; . \; CommunicationsHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array}
```

```
\begin{array}{l} \textit{Methods} \ \widehat{=} \\ \left( \textit{handleAsyncEvent} \right) \ ; \ \textit{Methods} \end{array}
```

ullet (Methods) \triangle (end_aperiodic_app . CommunicationsHandlerSID \longrightarrow Skip)

```
\begin{aligned} \mathbf{process} & EnvironmentMonitorApp \; \widehat{=} \\ & mainMission : MissionID \bullet \mathbf{begin} \end{aligned} \begin{aligned} handle & AsyncEvent \; \widehat{=} \\ & \left( \begin{matrix} handle & AsyncEventCall \; . \; EnvironmentMonitorSID \longrightarrow \\ & \mathbf{Skip}; \\ & handle & AsyncEventRet \; . \; EnvironmentMonitorSID \longrightarrow \\ & \mathbf{Skip} \\ \end{matrix} \right) \\ & Methods \; \widehat{=} \\ & \left( handle & AsyncEvent \right) \; ; \; \; Methods \end{aligned} \bullet \; (Methods) \; \triangle \; (end\_periodic\_app \; . \; EnvironmentMonitorSID \longrightarrow \mathbf{Skip}) \end{aligned}
```

${\bf section}\ Environment Monitor Class\ {\bf parents}\ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class} Environment Monitor Class \widehat{=} {\bf begin}$
state State
controlling Mission: Main Mission
state State
• Skip
end

```
 \begin{aligned} \mathbf{process} & \mathit{FlightSensorsMonitorApp} \; \widehat{=} \\ & \mathit{mainMission} : \mathit{MissionID} \; \bullet \; \mathbf{begin} \end{aligned} \\ handle & \mathit{AsyncEvent} \; \widehat{=} \\ \begin{pmatrix} \mathit{handleAsyncEventCall} \; . \; \mathit{FlightSensorsMonitorSID} \longrightarrow \\ \mathbf{Skip}; \\ \mathit{handleAsyncEventRet} \; . \; \mathit{FlightSensorsMonitorSID} \longrightarrow \\ \mathbf{Skip} \end{aligned} \\ Methods \; \widehat{=} \\ (\mathit{handleAsyncEvent}) \; ; \; \mathit{Methods} \end{aligned} \\ \bullet \; (\mathit{Methods}) \; \triangle \; (\mathit{end\_periodic\_app} \; . \; \mathit{FlightSensorsMonitorSID} \longrightarrow \mathbf{Skip}) \end{aligned} \\ \mathbf{end}
```

$ {\bf section} \ Flight Sensors Monitor Class \ {\bf parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels $
${\bf class} Flight Sensors Monitor Class \widehat{=} {\bf begin}$
state State
controlling Mission: Main Mission
state State initial Init
State'
• Skip
end

```
\begin{aligned} &\mathbf{process}\ AperiodicSimulatorApp} \ \widehat{=} \\ &aperiodicEvent: SchedulableID \bullet \mathbf{begin} \end{aligned} handleAsyncEvent \ \widehat{=} \\ &\left( \begin{aligned} handleAsyncEventCall \ .\ AperiodicSimulatorSID \longrightarrow \\ \mathbf{Skip}; \\ handleAsyncEventRet \ .\ AperiodicSimulatorSID \longrightarrow \\ \mathbf{Skip} \end{aligned} \right) \mathbf{Methods} \ \widehat{=} \\ &\left( handleAsyncEvent \right); \ Methods \end{aligned} \bullet \ (Methods) \ \triangle \ (end\_periodic\_app \ .\ AperiodicSimulatorSID \longrightarrow \mathbf{Skip}) \mathbf{end}
```

$ {\bf section} \ A periodic Simulator Class \ {\bf parents} \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels $
${\bf class} Aperiodic Simulator Class \ \widehat{=} \ {\bf begin}$
state State
event: Aperiodic Event Handler
$\mathbf{state}\mathit{State}$
initial Init
State'
• Skip
end

5.3 TakeOffMission

section TakeOffMissionApp **parents** scj_prelude, MissionId, MissionIds,

```
Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Take Off Mission Meth Chan
, Take Off Mission Class, Method Call Binding Channels, Object FW Chan, Object Ids
process TakeOffMissionApp \cong
            controlling Mission: Mission ID \bullet \mathbf{begin}
       State
         this: {f ref}\ Take Off Mission Class
\mathbf{state}\,\mathit{State}
       Init
         State'
         this' = \mathbf{new} \ TakeOffMissionClass()
InitializePhase \stackrel{\frown}{=}
      initializeCall. TakeOffMissionMID \longrightarrow
      register \,!\, Landing Gear Handler Take Off SID \,!\, Take Off Mission MID - Control of the Contr
      register! TakeOffMonitorSID! TakeOffMissionMID \longrightarrow
      register \ ! \ Take Off Failure Handler SID \ ! \ Take Off Mission MID \longrightarrow
      initializeRet. TakeOffMissionMID \longrightarrow
      Skip
CleanupPhase \stackrel{\frown}{=}
     cleanupMissionCall. TakeOffMissionMID \longrightarrow
      cleanup {\it MissionRet}: Take {\it OffMissionMID} \ ! \ {\bf True} -
     Skip
abortMeth \stackrel{\frown}{=}
      abortCall. TakeOffMissionMID-
      this. abort();
      abortRet.\ Take Off Mission MID
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
     getControllingMissionCall. TakeOffMissionMID \longrightarrow
     ret := this.getControllingMission();
      getControllingMissionRet\ .\ TakeOffMissionMID\ !\ ret
     Skip
setControllingMissionMeth =
     's et Controlling {\it Mission Call} \;. \; Take O \!f\! f\! Mission {\it MID} \;? \; controlling {\it Mission-III} \\
      this.setControllingMission(controllingMission);
      setControllingMissionRet. TakeOffMissionMID \longrightarrow
     Skip
```

```
clean UpMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  ret := this \cdot clean Up();
  clean UpRet . Take Off Mission MID ! re
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  \ 'stow Landing Gear Call . Take Off Mission MID? caller-
  this.stowLandingGear();
  stow Landing Gear Ret.\ Take Off Mission MID.\ caller
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  is Landing Gear Deployed Call . Take Off Mission MID ? caller \longrightarrow Caller
  ret := this.isLandingGearDeployed();
  is Landing Gear Deployed Ret.\ Take Off Mission MID.\ caller\ !\ ret
  Skip
deployLandingGearSyncMeth =
  deployLandingGearCall. TakeOffMissionMID? caller? thread \longrightarrow
     startSyncMeth. TakeOffMissionOID. thread \longrightarrow
     lockAcquired. TakeOffMissionOID. thread \longrightarrow
     (this.landingGearDeployed := True);
     \stackrel{.}{e}ndSyncMeth. TakeOffMissionOID. \stackrel{.}{thread} \longrightarrow
     deploy Landing Gear Ret.\ Take Off Mission MID.\ caller.\ thread
    Skip
               Initialize Phase
               CleanupPhase
               abortMeth
               getControllingMissionMeth \\
Methods =
               set Controlling Mission Meth \\
                                                    : Methods
               clean Up Meth
               stowLandingGearMeth
               is Landing Gear Deployed Meth
               deploy Landing Gear Sync Meth \\
```

• (Init; Methods) \triangle (end_mission_app. TakeOffMissionMID \longrightarrow **Skip**)

 $\begin{array}{l} \textbf{section} \ \ Take Off Mission Class \ \ \textbf{parents} \ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels \end{array}$

 $\mathbf{class} \; \mathit{TakeOffMissionClass} \; \widehat{=} \; \mathbf{begin}$

```
\mathbf{state}\,\mathit{State}\,.
    SAFE\_AIRSPEED\_THRESHOLD: \mathbb{P} \, \mathbb{A}
    TAKEOFF\_ALTITUDE: \mathbb{P}\,\mathbb{A}
    controlling Mission: Main Mission\\
    abort: \mathbb{B}
    landing Gear Deployed: \mathbb{B}
\mathbf{state}\,\mathit{State}
   \mathbf{initial}\ Init
    State'
\mathbf{public}\ \mathit{abort}\ \widehat{=}
(this.abort := True)
public getControllingMission = \mathbf{var} \ ret : MissionID \bullet
(ret := controllingMission)
public setControllingMission  <math>\hat{=}
(this.this.controllingMission := controllingMission)
public clean Up = \mathbf{var} \ ret : \mathbb{B} \bullet
(ret := (\neg abort = \mathbf{True}))
public stowLandingGear \stackrel{\frown}{=}
(this.landingGearDeployed := False)
public isLandingGearDeployed <math>\stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
(ret := landingGearDeployed = True)
• Skip
```

${\bf section}\ \ Take Off Mission Meth Chan\ \ {\bf parents}\ \ scj_prelude,\ Global Types,\ Mission Id,\ Schedulable Id$

 $\begin{array}{l} \textbf{channel} \ abort Call: Mission ID \\ \textbf{channel} \ abort Ret: Mission ID \end{array}$

 ${\bf channel}\ get Controlling {\it Mission Call}: {\it Mission ID}$

 $\mathbf{channel}\ getControllingMissionRet: MissionID \times MissionID$

 $\mathbf{channel}\ setControllingMissionCall: MissionID \times MissionID$

 ${\bf channel}\ set Controlling {\it Mission Ret}: {\it Mission ID}$

channel cleanUpCall : MissionID**channel** $cleanUpRet : MissionID \times \mathbb{B}$

$$\label{lem:channel} \begin{split} \textbf{channel} & stowLandingGearCall: \textit{MissionID} \times SchedulableID \\ \textbf{channel} & stowLandingGearRet: \textit{MissionID} \times SchedulableID \end{split}$$

 $\begin{tabular}{l} {\bf channel} \ is Landing Gear Deployed Call: Mission ID \times Schedulable ID \\ {\bf channel} \ is Landing Gear Deployed Ret: Mission ID \times Schedulable ID \times \mathbb{B} \\ \end{tabular}$

 $\label{lem:channel} \textbf{channel} \ deployLandingGearCall: MissionID \times SchedulableID \times ThreadID \\ \textbf{channel} \ deployLandingGearRet: MissionID \times SchedulableID \times ThreadID \\$

5.4 Schedulables of TakeOffMission

 $\begin{array}{l} \textbf{section} \ \ Landing Gear Handler Take Off App \ \ \textbf{parents} \ \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Control of Mission Method Chan, Object Ids, Thread Ids \\ \end{array}$

```
process Landing Gear Handler Take Off App \cong
                          mission: MissionID \bullet \mathbf{begin}
handle A sync Event \cong
             handle A sync Event Call . Landing Gear Handler Take Off SID \longrightarrow
                             binder\_isLandingGearDeployedCall . mission . LandingGearHandlerTakeOffSID \longrightarrow
                           binder\_is Landing Gear Deployed Ret: mission: Landing Gear Handler Take Off SID? is Landing Gear Deployed \longrightarrow the control of t
                          Skip var landingGearIsDeployed : \mathbb{B} \bullet landingGearIsDeployed := isLandingGearDeployed;
                          if landingGearIsDeployed = True \longrightarrow
                                                                     binder\_stowLandingGearCall\ .\ mission\ .\ LandingGearHandlerTakeOffSID-theory and the following the following of the following the following of the following the following of the following o
                                                                    binder\_stowLandingGearRet.\ mission.\ LandingGearHandlerTakeOffSID-mission.
                                                                   Skip
                           \ 'binder\_deployLandingGearCall . mission . LandingGearHandlerTakeOffSID . LandingGearHandlerTakeOffTID .
                                                                    binder\_deployLandingGearRet.\ mission.\ LandingGearHandlerTakeOffSID.\ LandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHandlerTakeOffTID-deployLandingGearHa
              handle A sync Event Ret . Landing Gear Handler Take Off SID \longrightarrow
            Skip
Methods \stackrel{\frown}{=}
 (handleAsyncEvent); Methods
• (Methods) \triangle (end\_aperiodic\_app . LandingGearHandlerTakeOffSID \longrightarrow \mathbf{Skip})
end
```

 ${\bf section}\ \ Take Off Failure Handler App\ \ {\bf parents}\ \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Bing, Main Mission Meth Chan$

, MethodCallBindingChannels
${\bf class}\ {\it Take Off Failure Handler Class}\ \widehat{=}\ {\bf begin}$
state State
$threshold: \mathbb{P}\mathbb{A}$
state Stateinitial Init
State'
• Skip
end

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffMonitorApp} \ \ \textbf{parents} \ \ \textit{PeriodicEventHandlerChan}, SchedulableId, SchedulableIds, MethodCallBindingChan, MainMissionMethChan \end{array}$

```
\begin{aligned} & process \ TakeOffMonitorApp \ \cong\\ & mainMission : MissionID,\\ & takeOffMission : MissionID,\\ & takeOffAltitude : \mathbb{P} \, \mathbb{A},\\ & landingGearHandler : SchedulableID \bullet \mathbf{begin} \end{aligned} \begin{aligned} & handleAsyncEvent \ \cong\\ & \left(\begin{array}{c} handleAsyncEvent \ \cong\\ & \left(\begin{array}{c} handleAsyncEvent \ \cong\\ & \left(\begin{array}{c} binder\_getAltitudeCall \ . \ TakeOffMonitorSID \longrightarrow\\ & binder\_getAltitudeRet \ . \ mainMission \ . \ TakeOffMonitorSID \ ? \ getAltitude \longrightarrow\\ & \mathbf{Skip} \ var \ altitude : \mathbb{P} \, \mathbb{A} \, \bullet \, altitude := \ getAltitude;\\ & \mathbf{if} \ (altitude > takeOffAltitude) \longrightarrow\\ & \mathbf{Skip} \\ & \mathbf{if} \ (altitude > takeOffAltitude) \longrightarrow \mathbf{Skip} \\ & \mathbf{fi} \end{aligned} \begin{cases} & \mathbf{Kip} \\ & \mathbf{F} \\ & \mathbf{Skip} \end{aligned} \begin{pmatrix} & \mathbf{Kip} \\ &
```

${\bf section}\ \ Take Off Monitor Class\ \ {\bf parents}\ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}\ {\it Take Off Monitor Class}\ \widehat{=}\ {\bf begin}$
_ state State
$take Off Mission: Take Off Mission \ take Off Altitude: \mathbb{P} \mathbb{A}$
state Stateinitial Init
State'
• Skip
end

5.5 CruiseMission

```
 \begin{array}{l} \textbf{section} \ \textit{CruiseMissionApp} \ \textbf{parents} \ \textit{scj\_prelude}, \textit{MissionId}, \textit{MissionIds}, \\ \textit{SchedulableId}, \textit{SchedulableIds}, \textit{MissionChan}, \textit{SchedulableMethChan}, \textit{CruiseMissionMethChan}, \\ \textit{CruiseMissionClass}, \textit{MethodCallBindingChannels} \\ \textbf{process} \ \textit{CruiseMissionApp} \ \widehat{=} \\ \end{array}
```

```
State

State

this: ref CruiseMissionClass

state State

Init

State'

this' = new CruiseMissionClass()
```

$$\begin{array}{l} \textit{CleanupPhase} \; \widehat{=} \\ \left(\begin{array}{l} \textit{cleanupMissionCall} \; . \; \textit{CruiseMissionMID} \longrightarrow \\ \textit{cleanupMissionRet} \; . \; \textit{CruiseMissionMID} \; ! \; \mathbf{True} \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$\begin{array}{l} getControllingMissionMeth \ \widehat{=} \ \mathbf{var} \ ret : MissionID \ \bullet \\ \left(\begin{array}{l} getControllingMissionCall \ . \ CruiseMissionMID \longrightarrow \\ ret := this \ . \ getControllingMission(); \\ getControllingMissionRet \ . \ CruiseMissionMID \ ! \ ret \longrightarrow \\ \mathbf{Skip} \end{array} \right)$$

$$Methods = \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ getControllingMissionMeth \end{pmatrix}; Methods$$

• (Init; Methods) \triangle (end_mission_app. CruiseMissionMID \longrightarrow Skip)

$ \textbf{section} \ \ Cruise Mission Class \ \ \textbf{parents} \ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels $
${\bf class}\ Cruise Mission Class\ \widehat{=}\ {\bf begin}$
state State
controlling Mission: Main Mission
state State
initial Init State'
State
$ \begin{aligned} \mathbf{public} \ getControllingMission & \widehat{=} \mathbf{var} \ ret : MissionID \bullet \\ \big(ret := controllingMission\big) \end{aligned} $
· Skip
end

5.6 Schedulables of CruiseMission

 ${\bf section}\ Begin Landing Handler App\ {\bf parents}\ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binder Chan, Method Chan, Me$

```
\begin{array}{l} \mathbf{process} \ BeginLandingHandlerApp} \ \widehat{=} \\ \ controllingMission: MissionID \bullet \mathbf{begin} \\ \\ handleAsyncEvent \ \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \ . \ BeginLandingHandlerSID \longrightarrow \\ \mathbf{Skip}; \\ handleAsyncEventRet \ . \ BeginLandingHandlerSID \longrightarrow \\ \mathbf{Skip} \\ \end{array} \right) \\ Methods \ \widehat{=} \\ \left( handleAsyncEvent \right); \ Methods \\ \\ \bullet \ (Methods) \ \triangle \ (end\_aperiodic\_app \ . \ BeginLandingHandlerSID \longrightarrow \mathbf{Skip}) \\ \\ \mathbf{end} \\ \end{array}
```

 ${\bf section}\ \ Navigation Monitor App\ \ {\bf parents}\ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding Grant Mission Meth Chan$

```
\mathbf{process} \ Navigation Monitor App \ \widehat{=} 
              mainMission: MissionID \bullet \mathbf{begin}
handle A sync Event \triangleq
       'handle A sync Event Call . Navigation Monitor SID \longrightarrow
               binder\_getHeadingCall\:.\:mainMission\:.\:NavigationMonitorSID \longrightarrow
               binder\_getHeadingRet..mainMission..NavigationMonitorSID~?~getHeading-particle for the contract of the contra
              Skip var heading : \mathbb{P} \mathbb{A} \bullet heading := getHeading;
               binder\_getAirSpeedCall. mainMission. NavigationMonitorSID \longrightarrow
               binder\_getAirSpeedRet..mainMission..NavigationMonitorSID?.getAirSpeed \longrightarrow
              Skip var airSpeed : \mathbb{P} \mathbb{A} \bullet airSpeed := getAirSpeed;
              binder\_getAltitudeCall\:.\:mainMission\:.\:NavigationMonitorSID \longrightarrow
              binder\_getAltitudeRet \ . \ mainMission \ . \ NavigationMonitorSID \ ? \ getAltitude \longrightarrow
              \mathbf{Skip} \mathbf{var} \ altitude : \mathbb{P} \mathbb{A} \bullet \ altitude := \ getAltitude
        handle A sync Event Ret. Navigation Monitor SID \longrightarrow
       Skip
Methods =
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_periodic\_app . NavigationMonitorSID \longrightarrow \mathbf{Skip})
```

5.7 LandMission

Skip

section LandMissionApp parents scj_prelude, MissionId, MissionIds,

```
Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Land Mission Meth Chan
, Land Mission Class, Method Call Binding Channels, Object FW Chan, Object Ids
process Land Mission App \cong
     controlling Mission: Mission ID \bullet \mathbf{begin}
   State
    this: \mathbf{ref}\ Land Mission Class
\mathbf{state}\,\mathit{State}
   Init
    State'
   this' = \mathbf{new} \ Land Mission Class()
InitializePhase \stackrel{\frown}{=}
  initializeCall . LandMissionMID \longrightarrow
  register \ ! \ Ground Distance Monitor SID \ ! \ Land Mission MID \longrightarrow
  register! LandingGearHandlerLandSID! LandMissionMID \longrightarrow
  register \,! \, Instrument Landing System Monitor SID \,! \, Land Mission MID
  register! SafeLandingHandlerSID! LandMissionMID \longrightarrow
  initializeRet . LandMissionMID \longrightarrow
  Skip
CleanupPhase =
  cleanup {\it Mission Ret} \; . \; Land {\it Mission MID} \; ! \; {\bf True} -
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  \ 'stow Landing Gear Call . Land Mission MID? caller
  this.stowLandingGear();
  stow Landing Gear Ret\ .\ Land Mission MID\ .\ caller
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  is Landing Gear Deployed Call . Land Mission MID? caller-
  ret := this.isLandingGearDeployed();
  is Landing Gear Deployed Ret.\ Land Mission MID.\ caller\ !\ ret-
  Skip
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
  ret := this.getControllingMission();
  getControlling {\it MissionRet} \;.\; Land {\it MissionMID} \;!\; ret \\
```

```
abortMeth \stackrel{\frown}{=}
  abortCall . LandMissionMID-
  this.\ abort();
  abortRet\ .\ Land Mission MID
  Skip
clean UpMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  \'clean Up Call . Land Mission MID -
  ret := this.cleanUp();
  clean \textit{UpRet} . \textit{LandMissionMID} ! \textit{ret}
deployLandingGearSyncMeth \; \widehat{=} \;
  startSyncMeth. LandMissionOID. thread \longrightarrow
    lockAcquired . LandMissionOID . thread \longrightarrow
    (this.landingGearDeployed := True);
    endSyncMeth . LandMissionOID . thread \longrightarrow
    deploy Landing Gear Ret.\ Land Mission MID.\ caller.\ thread-
    Skip
               Initialize Phase \\
               CleanupPhase
               stow Landing Gear Meth \\
               is Landing Gear Deployed Meth
Methods \stackrel{\frown}{=}
                                                   ; Methods
               get Controlling Mission Meth \\
               abortMeth
               clean\,UpMeth
               deployLandingGearSyncMeth
```

 $\bullet \ (\mathit{Init} \ ; \ \mathit{Methods}) \ \triangle \ (\mathit{end_mission_app} \ . \ \mathit{LandMissionMID} \longrightarrow \mathbf{Skip})$

 $\begin{array}{l} \textbf{section} \ Land \textit{MissionClass} \ \textbf{parents} \ \textit{scj_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan}, \textit{MethodCallBindingChannels} \\ \end{array}$

 $\mathbf{class}\,\mathit{LandMissionClass}\,\,\widehat{=}\,\,\mathbf{begin}$

```
\mathbf{state}\,\mathit{State}\,.
    controlling Mission: Main Mission\\
    SAFE\_LANDING\_ALTITUDE: \mathbb{P} \, \mathbb{A}
    abort: \mathbb{B}
    landingGearDeployed: \mathbb{B}
\mathbf{state}\,\mathit{State}
    initial Init
    State'
public stowLandingGear \stackrel{\frown}{=}
(this.landingGearDeployed := False)
public isLandingGearDeployed  <math>\hat{=}  var ret : \mathbb{B} \bullet
(ret := landingGearDeployed = True)
\mathbf{public}\ \mathit{getControllingMission}\ \widehat{=}\ \mathbf{var}\ \mathit{ret}: \mathit{MissionID}\ \bullet
(ret := controllingMission)
public abort \stackrel{\frown}{=}
(this. abort := True)
public clean Up \cong \mathbf{var} \ ret : \mathbb{B} \bullet
(ret := (\neg abort = \mathbf{True}))
• Skip
```

${\bf section}\ Land {\it Mission Meth Chan}\ {\bf parents}\ scj_prelude, {\it Global Types}, {\it Mission Id}, {\it Schedulable Id}$

$$\label{lem:channel} \begin{split} \textbf{channel} & stowLandingGearCall: MissionID \times SchedulableID \\ \textbf{channel} & stowLandingGearRet: MissionID \times SchedulableID \end{split}$$

 $\textbf{channel} \ is Landing Gear Deployed Call: \ Mission ID \times Schedulable ID \\ \textbf{channel} \ is Landing Gear Deployed Ret: \ Mission ID \times Schedulable ID \times \mathbb{B}$

 ${\bf channel}\ getControlling {\it Mission Call}: {\it Mission ID}$

 $\mathbf{channel}\, getControllingMissionRet: MissionID \times MissionID$

 $\begin{array}{l} \textbf{channel} \ abort Call: Mission ID \\ \textbf{channel} \ abort Ret: Mission ID \end{array}$

 $\begin{array}{l} \textbf{channel} \ clean Up Call : \textit{MissionID} \\ \textbf{channel} \ clean Up Ret : \textit{MissionID} \times \mathbb{B} \end{array}$

$$\label{lem:channel} \begin{split} \textbf{channel} \ deployLandingGearCall: \textit{MissionID} \times \textit{SchedulableID} \times \textit{ThreadID} \\ \textbf{channel} \ deployLandingGearRet: \textit{MissionID} \times \textit{SchedulableID} \times \textit{ThreadID} \end{split}$$

5.8 Schedulables of LandMission

end

 ${\bf section} \ Landing Gear Handler Land App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Ids, Method Calley, Land Mission Meth Chan, Object Ids, Thread Ids$

```
process Landing Gear Handler Land App \cong
                    mission: MissionID \bullet \mathbf{begin}
handle A sync Event \cong
          handle A sync Event Call. Landing Gear Handler Land SID \longrightarrow
                     binder\_isLandingGearDeployedCall. mission. LandingGearHandlerLandSID \longrightarrow
                    binder\_is Landing Gear Deployed Ret: mission: Landing Gear Handler Land SID? is Landing Gear Deployed \longrightarrow Compared Compa
                    Skip var landingGearIsDeployed : \mathbb{B} \bullet landingGearIsDeployed := isLandingGearDeployed;
                    if landingGearIsDeployed = True \longrightarrow
                                                  binder\_stowLandingGearCall\ .\ mission\ .\ LandingGearHandlerLandSID\ .
                                                  binder\_stowLandingGearRet.\ mission.\ LandingGearHandlerLandSID-mission.\ LandingGearHandlerLandSID-
                                                  Skip
                    ^{'}binder\_deployLandingGearCall . mission . LandingGearHandlerLandSID . LandingGearHandlerLandTID
                                                  binder\_deployLandingGearRet\ .\ mission\ .\ LandingGearHandlerLandSID\ .\ LandingGearHandlerLandTID
          handle A sync Event Ret . Landing Gear Handler Land SID \longrightarrow
         Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_aperiodic\_app . LandingGearHandlerLandSID \longrightarrow \mathbf{Skip})
```

```
 \begin{aligned} & \textbf{process SafeLandingHandlerApp} \; \widehat{=} \\ & \textit{mainMission} : \textit{MissionID}, \\ & \textit{threshold} : \mathbb{P} \, \mathbb{A} \, \bullet \, \mathbf{begin} \\ \\ & \textit{handleAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{SafeLandingHandlerSID} \longrightarrow \\ & \textit{binder\_getAltitudeCall} \; . \; \textit{mainMission} \; . \; \textit{SafeLandingHandlerSID} \; \bigcirc \\ & \textit{binder\_getAltitudeRet} \; . \; \textit{mainMission} \; . \; \textit{SafeLandingHandlerSID} \; ? \; \textit{getAltitude} \longrightarrow \\ & \mathbf{Skip} \, \mathbf{var} \; \textit{altitude} \; : \mathbb{P} \, \mathbb{A} \, \bullet \, \textit{altitude} \; : = \; \textit{getAltitude}; \\ & \mathbf{if} \; (\textit{altitude} \; < \; \textit{threshold}) \; \longrightarrow \\ & \mathbf{Skip} \\ & \mathbb{G} \\ & \mathbf{Skip} \\ & \mathbf{fi} \\ & \textit{handleAsyncEventRet} \; . \; \textit{SafeLandingHandlerSID} \longrightarrow \\ & \mathbf{Skip} \\ & \mathbf{Methods} \; \widehat{=} \\ & \textit{(handleAsyncEvent)} \; ; \; \textit{Methods} \end{aligned}
```

 $\bullet \ (Methods) \ \triangle \ (end_aperiodic_app \ . \ SafeLandingHandlerSID \longrightarrow \mathbf{Skip})$

, $MethodCallBindingChannels$	
$\textbf{class} Safe Landing Handler Class \widehat{=} \textbf{begin}$	
$_$ state $State$ $_$ $threshold: \mathbb{P} \mathbb{A}$	
${f state}\ State$	
_ initial Init	
• Skip	
end	

 ${\bf section} \ \ Ground Distance Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Birgon, Main Mission Meth Chan$

```
process GroundDistanceMonitorApp \triangleq

mainMission : MissionID • begin

handleAsyncEvent \cong

(handleAsyncEventCall . GroundDistanceMonitorSID \longrightarrow
binder_getAltitudeCall . mainMission . GroundDistanceMonitorSID ? getAltitude \longrightarrow
Skip var distance : \mathbb{P} \mathbb{A} \bullet distance := getAltitude;
if (distance = readingOnGround) \longrightarrow
Skip

\mathbb{B} \cap (distance = readingOnGround) \longrightarrow Skip
fi

handleAsyncEventRet . GroundDistanceMonitorSID \longrightarrow
Skip

Methods \cong
(handleAsyncEvent); Methods
```

 \mathbf{end}

${\bf section} \ \ Ground Distance Monitor Class \ \ {\bf parents} \ \ scj_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}\ Ground Distance Monitor Class\ \widehat{=}\ {\bf begin}$
state State
$readingOnGround: \mathbb{P}\mathbb{A}$
$\mathbf{state}\mathit{State}$
_ initial Init
State'
• Skip
end

```
 \begin{aligned} \mathbf{process} & \textit{InstrumentLandingSystemMonitorApp} \; \widehat{=} \\ & \textit{mission} : \textit{MissionID} \; \bullet \; \mathbf{begin} \\ \\ & \textit{handleAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ & \mathbf{Skip}; \\ & \textit{handleAsyncEventRet} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ & \mathbf{Skip} \\ \\ & \mathbf{Methods} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEvent} \; \end{pmatrix}; \; \; \textit{Methods} \\ \\ & \bullet \; \; (\textit{Methods}) \; \triangle \; (\textit{end\_periodic\_app} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \mathbf{Skip}) \\ \\ & \mathbf{end} \end{aligned}
```