# aircraft

# Tight Rope v0.75 24th February 2017

# 1 ID Files

### 1.1 MissionIds

 ${\bf section}\ {\it MissionIds}\ {\bf parents}\ {\it scj\_prelude}, {\it MissionId}$ 

$$\label{lem:main_model} \begin{split} & \textit{MainMissionMID}: \textit{MissionID} \\ & \textit{TakeOffMissionMID}: \textit{MissionID} \\ & \textit{CruiseMissionMID}: \textit{MissionID} \\ & \textit{LandMissionMID}: \textit{MissionID} \end{split}$$

 $distinct \langle null Mission Id, Main Mission MID, Take Off Mission MID, Cruise Mission MID, Land Mission MID \rangle$ 

### 1.2 SchedulablesIds

 ${\bf section} \ Schedulable Ids \ {\bf parents} \ scj\_prelude, Schedulable Id$ 

 $\label{lem:main} MainMissionSequencerSID: SchedulableID\\ ACModeChanger2SID: SchedulableID\\ EnvironmentMonitorSID: SchedulableID\\ ControlHandlerSID: SchedulableID\\ FlightSensorsMonitorSID: SchedulableID\\ CommunicationsHandlerSID: SchedulableID\\ LandingGearHandlerSID: SchedulableID\\ TakeOffMonitorSID: SchedulableID\\ TakeOffFailureHandlerSID: SchedulableID\\ TakeOf$ 

 $Begin Landing Handler SID: Schedulable ID\\ Navigation Monitor SID: Schedulable ID\\ Ground Distance Monitor SID: Schedulable ID\\ Landing Gear Handler Land SID: Schedulable ID$ 

In strument Landing System Monitor SID: Schedulable ID

Safe Landing Handler SID: Schedulable ID

 $distinct \langle null Sequencer Id, null Schedulable Id, Main Mission Sequencer SID,$ 

 $A {\it CMode Changer 2SID}, {\it Environment Monitor SID},$ 

Control Handler SID, Flight Sensors Monitor SID,

Communications Handler SID, Landing Gear Handler SID,

TakeOffMonitorSID, TakeOffFailureHandlerSID,

BeginLanding Handler SID, Navigation Monitor SID,

Ground Distance Monitor SID, Landing Gear Handler Land SID,

InstrumentLandingSystemMonitorSID, SafeLandingHandlerSID

1.3	Non-Paradigm	<b>Objects</b>
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# 1.4 ThreadIds

 ${\bf section}\ ThreadIds\ {\bf parents}\ scj\_prelude, GlobalTypes$ 

 $Safe let TId: Thread ID \\ null Thread Id: Thread ID$ 

 $\overline{distinct\langle SafeletTId, nullThreadId\rangle}$ 

# 1.5 ObjectIds

### 2 Network

#### 2.1 Network Channel Sets

```
section NetworkChannels parents scj\_prelude, MissionId, MissionIds,
       Schedulable Id, Schedulable Ids, Mission Chan, Top Level Mission Sequencer FWChan,
       Framework Chan, Safelet Chan, Aperiodic Event Handler Chan, Managed Thread Chan,
       One Shot Event Handler Chan, Periodic Event Handler Chan, Mission Sequencer Meth Chan
channelset TerminateSync ==
       \{ schedulables\_terminated, schedulables\_stopped, get\_activeSchedulables \} 
channelset ControlTierSync ==
       \{ | start\_toplevel\_sequencer, done\_toplevel\_sequencer, done\_safeletFW | \}
channelset TierSync ==
       \{| start\_mission . MainMission, done\_mission . MainMission,
       done\_safeletFW, done\_toplevel\_sequencer }
{f channel set} \ {\it Mission Sync} ==
       \{|done\_safeletFW, done\_toplevel\_sequencer, register, \}
signal Termination Call, signal Termination Ret, activate\_schedulables, done\_schedulable,
cleanupSchedulableCall, cleanupSchedulableRet
channelset SchedulablesSync ==
       \{|activate\_schedulables, done\_safeletFW, done\_toplevel\_sequencer\}\}
channelset ClusterSync ==
       \{|done\_toplevel\_sequencer, done\_safeletFW|\}
channelset SafeltAppSync \cong
\{ getSequencerCall, getSequencerRet, initializeApplicationCall, initializeApplicationRet, end\_safelet\_app \} \}
channelset MissionSequencerAppSync ==
\{|getNextMissionCall, getNextMissionRet, end\_sequencer\_app|\}
channelset MissionAppSync ==
\{|initializeCall, register, initializeRet, cleanupMissionCall, cleanupMissionRet|\}
channelset AppSync ==
       \bigcup \{SafeltAppSync, MissionSequencerAppSync, MissionAppSync, \\
       MTAppSync, OSEHSync, APEHSync, PEHSync,
       \{|getSequencer, end\_mission\_app, end\_managedThread\_app, | end\_managed
       set Ceiling Priority, request Termination Call, request Termination Ret, termination Pending Call,
       terminationPendingRet, handleAsyncEventCall, handleAsyncEventRet \} 
channelset ThreadSunc ==
       \{ raise\_thread\_priority, lower\_thread\_priority, isInterruptedCall, isInterruptedRet, get\_priorityLevel \} \}
channelset LockingSync ==
       \{ lockAcquired, startSyncMeth, endSyncMeth, waitCall, waitRet, notify, isInterruptedCall, isInterruptedRet, \} \}
       interruptedCall, interruptedRet, done\_toplevel\_sequencer, get\_priorityLevel
channelset Tier0Sync ==
       \{|done\_toplevel\_sequencer, done\_safeletFW,
       start\_mission \ . \ Take O\!f\!f\!Mission, done\_mission \ . \ Take O\!f\!f\!Mission,
       initializeRet. TakeOffMission, requestTermination. TakeOffMission. MainMissionSequencer,
       start_mission. CruiseMission, done_mission. CruiseMission,
       initializeRet. CruiseMission, requestTermination. CruiseMission. MainMissionSequencer,
       start_mission . LandMission, done_mission . LandMission,
       initializeRet. LandMission, requestTermination. LandMission. MainMissionSequencer
```

#### 2.2 MethodCallBinder

```
section MethodCallBindingChannels parents scj_prelude, GlobalTypes, FrameworkChan, MissionId, MissionIds,
         Schedulable Id, Schedulable Ids, Thread Ids
\mathbf{channel}\ binder\_setCabinPressureCall: \mathit{MissionID} \times \mathit{SchedulableID} \times \mathbb{P}\,\mathbb{A}
\mathbf{channel}\ binder\_setCabinPressureRet: MissionID \times SchedulableID
setCabinPressureLocs == \{MainMissionMID\}
setCabinPressureCallers == \{EnvironmentMonitorSID\}
channel binder\_setFuelRemainingCall: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
\mathbf{channel}\ binder\_setFuelRemainingRet: MissionID \times SchedulableID
setFuelRemainingLocs == \{MainMissionMID\}
setFuelRemainingCallers == \{EnvironmentMonitorSID\}
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
channel binder\_getAltitudeRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getAltitudeLocs == \{MainMissionMID\}
getAltitudeCallers == \{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerS, S
\mathbf{channel}\ binder\_setHeadingCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
{\bf channel}\ binder\_setHeadingRet: MissionID \times SchedulableID
setHeadingLocs == \{MainMissionMID\}
setHeadingCallers == \{FlightSensorsMonitorSID\}
{\bf channel}\ binder\_stowLandingGearCall: MissionID 	imes SchedulableID
\mathbf{channel}\ binder\_stowLandingGearRet: MissionID \times SchedulableID
stowLandingGearLocs == \{ TakeOffMissionMID, LandMissionMID \}
stowLandingGearCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
\mathbf{channel}\ binder\_takeOffAbortCall: MissionID \times SchedulableID
{\bf channel}\ binder\_takeOffAbortRet: MissionID \times SchedulableID
takeOffAbortLocs == \{ TakeOffMissionMID \}
takeOffAbortCallers == \{ TakeOffFailureHandlerSID \}
\mathbf{channel}\ binder\_setAltitudeCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
{\bf channel}\ binder\_setAltitudeRet: MissionID \times SchedulableID
```

 $setAltitudeLocs == \{MainMissionMID\}$ 

 $setAltitudeCallers == \{FlightSensorsMonitorSID\}$ 

```
channel binder\_qetHeadingCall: MissionID \times SchedulableID
channel binder\_getHeadingRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getHeadingLocs == \{MainMissionMID\}
getHeadingCallers == \{NavigationMonitorSID\}
\mathbf{channel}\ binder\_getAirSpeedCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAirSpeedRet: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
getAirSpeedLocs == \{MainMissionMID\}
getAirSpeedCallers == \{NavigationMonitorSID, TakeOffFailureHandlerSID\}
channel\ binder\_deployLandingGearCall: MissionID 	imes SchedulableID
channel binder\_deployLandingGearRet: MissionID 	imes SchedulableID
deployLandingGearLocs == \{ TakeOffMissionMID, LandMissionMID \}
deployLandingGearCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
channel binder\_setEmergencyOxygenCall: MissionID \times SchedulableID \times \mathbb{P} \, \mathbb{A}
channel binder\_setEmergencyOxygenRet: MissionID \times SchedulableID
setEmergencyOxygenLocs == \{MainMissionMID\}
setEmergencyOxygenCallers == \{EnvironmentMonitorSID\}
\mathbf{channel}\ binder\_setAirSpeedCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
\mathbf{channel}\ binder\_setAirSpeedRet: MissionID \times SchedulableID
setAirSpeedLocs == \{MainMissionMID\}
setAirSpeedCallers == \{FlightSensorsMonitorSID\}
{\bf channel}\ binder\_isLandingGearDeployedCall: MissionID 	imes SchedulableID
channel binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times \mathbb{B}
isLandingGearDeployedLocs == \{ TakeOffMissionMID, LandMissionMID \}
isLandingGearDeployedCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
channelset MethodCallBinderSync == \{ | done\_toplevel\_sequencer, \}
binder\_setCabinPressureCall, binder\_setCabinPressureRet,
binder\_setFuelRemainingCall, binder\_setFuelRemainingRet,
binder\_getAltitudeCall, binder\_getAltitudeRet,
binder_setHeadingCall, binder_setHeadingRet,
binder\_stowLandingGearCall, binder\_stowLandingGearRet,
binder\_takeOffAbortCall, binder\_takeOffAbortRet,
binder\_setAltitudeCall, binder\_setAltitudeRet,
binder\_getHeadingCall, binder\_getHeadingRet,
binder\_getAirSpeedCall, binder\_getAirSpeedRet,
binder\_deployLandingGearCall, binder\_deployLandingGearRet,
binder\_setEmergencyOxygenCall, binder\_setEmergencyOxygenRet,
binder\_setAirSpeedCall, binder\_setAirSpeedRet,
binder\_isLandingGearDeployedCall, binder\_isLandingGearDeployedRet
```

```
process Method Call Binder \stackrel{\frown}{=} begin
setCabinPressure\_MethodBinder \ \widehat{=}
              binder\_setCabinPressureCall? loc:(loc \in setCabinPressureLocs)? caller:(caller \in setCabinPressureCallers)? p1-
             setCabinPressureCall. loc. caller! p1 \longrightarrow
              setCabinPressureRet.loc.caller \longrightarrow
              binder\_setCabinPressureRet.\,loc.\,caller \longrightarrow
              setCabinPressure\_MethodBinder
setFuelRemaining\_MethodBinder \stackrel{\frown}{=}
              binder\_setFuelRemainingCall?loc:(loc \in setFuelRemainingLocs)?caller:(caller \in setFuelRemainingCallers)?p1
             setFuelRemainingCall.loc.caller!p1 \longrightarrow
             setFuelRemainingRet.loc.caller \longrightarrow
              binder\_setFuelRemainingRet.loc.caller \longrightarrow
              setFuelRemaining\_MethodBinder
getAltitude\_MethodBinder \stackrel{\frown}{=}
              binder\_getAltitudeCall? loc: (loc \in getAltitudeLocs)? caller: (caller \in getAltitudeCallers)—
              getAltitudeCall \:.\: loc \:.\: caller {\longrightarrow}
              getAltitudeRet.loc.caller?ret \longrightarrow
              binder\_getAltitudeRet \:.\: loc \:.\: caller \: !\: ret \longrightarrow
              getAltitude\_MethodBinder
setHeading\_MethodBinder \cong
              binder\_setHeadingCall?\ loc: (loc \in setHeadingLocs)?\ caller: (caller \in setHeadingCallers)?\ p1-setHeadingCallers)
              setHeadingCall.loc.caller!p1 \longrightarrow
              setHeadingRet.loc.caller \longrightarrow
              binder\_setHeadingRet. loc. caller \longrightarrow
              setHeading\_MethodBinder
stowLandingGear\_MethodBinder \stackrel{\frown}{=}
              binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)
              stowLandingGearCall. loc. caller \longrightarrow
              stowLandingGearRet.loc.caller \longrightarrow
              binder\_stowLandingGearRet.loc.caller \longrightarrow
              stowLandingGear\_MethodBinder
takeOffAbort\_MethodBinder \stackrel{\frown}{=}
              binder\_takeOffAbortCall?loc: (loc \in takeOffAbortLocs)? caller: (caller \in takeOffAbortCallers)
              takeOf\!fAbortCall\:.\:loc\:.\:caller {\longrightarrow}
              takeOffAbortRet.\,loc.\,caller {\longrightarrow}
              binder\_takeOffAbortRet. loc. caller \longrightarrow
              takeOffAbort\_MethodBinder
setAltitude\_MethodBinder \triangleq
              binder\_setAltitudeCall? loc: (loc \in setAltitudeLocs)? caller: (caller \in setAltitudeCallers)? p1-setAltitudeCallers)? p1-setAltitudeCallers? p1-setAltitudeCal
              setAltitudeCall . loc . caller ! p1 \longrightarrow
              setAltitudeRet . loc . caller \longrightarrow
              binder\_setAltitudeRet. loc. caller \longrightarrow
              setAltitude\_MethodBinder
```

section MethodCallBinder parents scj\_prelude, MissionId, MissionIds, SchedulableId, SchedulableIds, MethodCallBindingChannels

, Main Mission Meth Chan, Land Mission Meth Chan

```
getHeading\_MethodBinder \ \widehat{=}
       binder\_getHeadingCall?\ loc: (loc \in getHeadingLocs)?\ caller: (caller \in getHeadingCallers)
       getHeadingCall\:.\:loc\:.\:caller {\longrightarrow}
       getHeadingRet.\,loc.\,caller\,?\,ret {\longrightarrow}
       binder\_getHeadingRet.loc.caller!ret \longrightarrow
       getHeading\_MethodBinder
getAirSpeed\_MethodBinder \stackrel{\frown}{=}
       binder\_getAirSpeedCall? loc:(loc \in getAirSpeedLocs)? caller:(caller \in getAirSpeedCallers) \longrightarrow
       getAirSpeedCall . loc . caller \longrightarrow
       getAirSpeedRet . loc . caller ? ret \longrightarrow
       binder\_getAirSpeedRet.loc.caller!ret \longrightarrow
       getAirSpeed\_MethodBinder
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_deployLandingGearCall? loc:(loc \in deployLandingGearLocs)? caller:(caller \in deployLandingGearCallers)
       deployLandingGearCall. loc. caller \longrightarrow
       deployLandingGearRet. loc. caller \longrightarrow
       binder\_deployLandingGearRet. loc. caller \longrightarrow
       deployLandingGear\_MethodBinder
setEmergencyOxygen\_MethodBinder \triangleq
       binder\_setEmergencyOxygenCall? loc:(loc \in setEmergencyOxygenLocs)? caller:(caller \in setEmergencyOxygenCocs)?
       setEmergencyOxygenCall\:.\:loc\:.\:caller\:!\:p1 {\longrightarrow}
       setEmergencyOxygenRet . loc . caller \longrightarrow
       binder\_setEmergencyOxygenRet.loc.caller \longrightarrow
       setEmergencyOxygen\_MethodBinder
setAirSpeed\_MethodBinder \stackrel{\frown}{=}
       binder\_setAirSpeedCall?loc:(loc \in setAirSpeedLocs)?caller:(caller \in setAirSpeedCallers)?p1-
       setAirSpeedCall.loc.caller!p1 \longrightarrow
       setAirSpeedRet.loc.caller \longrightarrow
       binder\_setAirSpeedRet.loc.caller \longrightarrow
       setAirSpeed\_MethodBinder
isLandingGearDeployed\_MethodBinder \cong
       binder\_isLandingGearDeployedCall? loc:(loc \in isLandingGearDeployedLocs)? caller:(caller \in isLandingGearDeployedLocs)?
       is Landing Gear Deployed Call\:.\:loc\:.\:caller {\longrightarrow}
       is Landing Gear Deployed Ret \:.\: loc \:.\: caller \:?\: ret {\longrightarrow}
       binder\_isLandingGearDeployedRet. loc. caller! ret \longrightarrow
```

 $is Landing Gear Deployed\_Method Binder$ 

### $\textit{BinderActions} \ \widehat{=} \\$

```
| setCabinPressure_MethodBinder | | | setFuelRemaining_MethodBinder | | getAltitude_MethodBinder | | setHeading_MethodBinder | | setHeading_MethodBinder | | stowLandingGear_MethodBinder | | takeOffAbort_MethodBinder | | setAltitude_MethodBinder | | getHeading_MethodBinder | | getAirSpeed_MethodBinder | | deployLandingGear_MethodBinder | | setEmergencyOxygen_MethodBinder | | setAirSpeed_MethodBinder | | setAindingGearDeployed_MethodBinder | | setAindingGearDeployed_MethodBinder | | setAindingGearDeployed_MethodBinder | setAindin
```

 $\bullet \ \mathit{BinderActions} \ \triangle \ (\mathit{done\_toplevel\_sequencer} \longrightarrow \mathbf{Skip})$ 

 $\mathbf{end}$ 

# 2.3 Locking

 $\begin{array}{l} \textbf{section} \ \ NetworkLocking \ \ \textbf{parents} \ \ scj\_prelude, \ GlobalTypes, \ FrameworkChan, \ MissionId, \ MissionIds, \ ThreadIds, \ NetworkChannels, \ ObjectFW, \ ThreadFW, \ Priority \end{array}$ 

```
\begin{array}{l} \mathbf{process} \ Threads \ \widehat{=} \\ \mathbf{(Skip)} \\ \\ \mathbf{process} \ Objects \ \widehat{=} \\ \mathbf{(Skip)} \\ \\ \mathbf{process} \ Locking \ \widehat{=} \ Threads \ \llbracket \ ThreadSync \ \rrbracket \ Objects \\ \end{array}
```

### 2.4 Program

```
section Program parents scj_prelude, MissionId, MissionIds,
       Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Mission FW,
       Safe let FW, Top Level Mission Sequencer FW, Network Channels, Managed Thread FW,
       Schedulable {\it Mission Sequencer FW}, Periodic {\it Event Handler FW}, One {\it Shot Event Hand
       AperiodicEventHandlerFW, ObjectFW, ThreadFW,
       ACSafeletApp, MainMissionSequencerApp, MainMissionApp, ACModeChanger2App, ControlHandlerApp,
       Communications Handler App, Environment Monitor App, Flight Sensors Monitor App
       , Take Off Mission App, Landing Gear Handler App, Take Off Failure Handler App,
       Take Off Monitor App, Cruise Mission App, Begin Landing Handler App, Navigation Monitor App
       , LandMissionApp, LandingGearHandlerLandApp, SafeLandingHandlerApp, GroundDistanceMonitorApp,
       InstrumentLandingSystemMonitorApp
process ControlTier =
   SafeletFW
           [ControlTierSync]
   TopLevel Mission Sequencer FW (Main Mission Sequencer)
process Tier0 =
   MissionFW(MainMissionID)
           [MissionSync]
        Schedulable Mission Sequencer FW(ACMode Changer 2ID)
               [SchedulablesSync]
        Aperiodic Event Handler FW (Control Handler ID, aperiodic, (time (10, 0), null Schedulable Id))
               [SchedulablesSync]
       Aperiodic Event Handler FW (Communications Handler ID, aperiodic, (NULL, nullSchedulable Id))
               [SchedulablesSync]
        PeriodicEventHandlerFW(EnvironmentMonitorID, (time (10,0), NULL, NULL, nullSchedulableId))
               [SchedulablesSync]
         PeriodicEventHandlerFW (FlightSensorsMonitorID, (time (10,0), NULL, NULL, nullSchedulableId))
process Tier1 =
    MissionFW(TakeOffMissionID)
           [MissionSync]
        Aperiodic Event Handler FW (Landing Gear Handler ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       Aperiodic Event Handler FW (Take Off Failure Handler ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       Periodic Event Handler FW (Take Off Monitor ID, (time (0,0), time (500,0), NULL, null Schedulable Id))
        [ClusterSync]
   MissionFW(CruiseMissionID)
           [MissionSync]
        AperiodicEventHandlerFW(BeginLandingHandlerID, aperiodic, (NULL, nullSchedulableId))
               [SchedulablesSync]
        Periodic Event Handler FW (Navigation Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
       [ClusterSync]
   MissionFW(LandMissionID)
           [MissionSync]
        Aperiodic Event Handler FW (Landing Gear Handler Land ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       AperiodicEventHandlerFW(SafeLandingHandlerID, aperiodic, (NULL, nullSchedulableId))
               [SchedulablesSync]
       Periodic Event Handler FW (Ground Distance Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id))
               [SchedulablesSync]
        Periodic Event Handler FW (Instrument Landing System Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id))
```

```
\mathbf{process}\,\mathit{Framework}\,\,\widehat{=}\,
  ControlTier
      [\![\mathit{TierSync}]\!]
        [Tier0Sync]
\mathbf{process} Application \cong
  ACS a felet App
  Main Mission Sequencer App
  MainMissionApp
  ACModeChanger2App(MainMissionID)
  Control Handler App
  Communications Handler App
  EnvironmentMonitorApp(MainMissionID)
  FlightSensorsMonitorApp(MainMissionID)
  Take Off Mission App
  Landing Gear Handler App(Take Off Mission ID)
  Take Off Failure Handler App (Mission ID, Take Off Mission ID, 10.0)
  TakeOffMonitorApp(MissionID, TakeOffMissionID, 10.0, landingGearHandlerID)
  Cruise Mission App
  BeginLandingHandlerApp(MissionID)
  NavigationMonitorApp(MissionID)
  LandMissionApp
  Landing Gear Handler Land App (Land Mission ID)
  SafeLandingHandlerApp(MissionID, 10.0)
  GroundDistanceMonitorApp(MissionID)
 InstrumentLandingSystemMonitorApp(LandMissionID)
```

 $\begin{array}{l} \textbf{process } Bound\_Application \triangleq Application \parallel MethodCallBinderSync \parallel MethodCallBinder\\ \textbf{process } Program \triangleq (Framework \parallel AppSync \parallel Bound\_Application) \parallel LockingSync \parallel LockingSy$ 

# 3 Safelet

 $\textbf{section} \ ACS a felet App \ \textbf{parents} \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels Schedulable Ids, Safelet Chan, Method Channels Schedulable Ids, Safelet Channels Schedulable Ids, Safelet Chann$ 

```
\mathbf{process}\,\mathit{ACSafeletApp}\,\,\widehat{=}\,\,\mathbf{begin}
```

```
Initialize Application \ \widehat{=} \ \left( egin{array}{ll} initialize Application Call \longrightarrow \\ initialize Application Ret \longrightarrow \\ \mathbf{Skip} \end{array} \right)
```

 $\bullet \; (Methods) \; \triangle \; (end\_safelet\_app \longrightarrow \mathbf{Skip})$ 

# 4 Top Level Mission Sequencer

end

 $\begin{array}{c} \textit{State} \\ \textit{this}: \mathbf{ref} \ \textit{MainMissionSequencerClass} \\ \\ \hline \textit{State} \ \textit{State'} \\ \hline \textit{this'} = \mathbf{new} \ \textit{MainMissionSequencerClass}() \\ \\ \\ \textit{GetNextMission} \cong \mathbf{var} \ \textit{ret} : \textit{MissionID} \bullet \\ \textit{(getNextMissionCall . MainMissionSequencerSID} \longrightarrow \\ \textit{ret} := \textit{this . getNextMission}(); \\ \textit{getNextMissionRet . MainMissionSequencerSID ! ret} \longrightarrow \\ \mathbf{Skip} \\ \\ \\ \textit{Methods} \cong \\ \textit{(GetNextMission)}; \ \textit{Methods} \\ \\ \bullet \ \textit{(Init ; Methods)} \triangle \ \textit{(end\_sequencer\_app . MainMissionSequencerSID} \longrightarrow \mathbf{Skip}) \\ \\ \end{array}$ 

 ${\bf section} \ Main Mission Sequencer Class \ {\bf parents} \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels, Mission Id, Mission Ids$ 

 $\mathbf{class}\,\mathit{MainMissionSequencerClass} \; \widehat{=} \; \mathbf{begin}$ 

```
__ initial Init _____
State'
returnedMission' = False
```

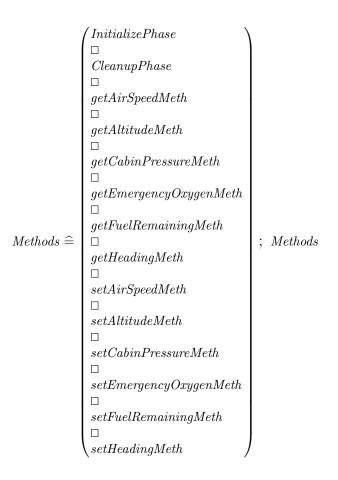
• Skip

### 5 Missions

#### 5.1 MainMission

```
section MainMissionApp parents scj_prelude, MissionId, MissionIds,
     Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Main Mission Meth Chan
, Main Mission Class, Method Call Binding Channels \\
process MainMissionApp \stackrel{\frown}{=} begin
   State .
    this: \mathbf{ref}\ Main Mission\ Class
{f state}\ State
  Init
   State'
    this' = \mathbf{new} \, MainMissionClass()
InitializePhase \stackrel{\frown}{=}
  'initializeCall . MainMissionMID \longrightarrow
  register! ACModeChanger2SID! MainMissionMID \longrightarrow
  register! EnvironmentMonitorSID! MainMissionMID \longrightarrow
  register! ControlHandlerSID! MainMissionMID \longrightarrow
  register! FlightSensorsMonitorSID! MainMissionMID-
  register \ ! \ Communications Handler SID \ ! \ Main Mission MID-
  initializeRet . MainMissionMID \longrightarrow
  Skip
CleanupPhase \stackrel{\frown}{=}
  clean up {\it MissionRet} : {\it MainMissionMID} \ ! \ {\bf True} -
  Skip
getAirSpeedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  'getAirSpeedCall . MainMissionMID ? caller-
  ret := this.getAirSpeed();
  getAirSpeedRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
getAltitudeMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  \ 'getAltitudeCall . MainMissionMID ? caller –
  ret := this.getAltitude();
  getAltitudeRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
getCabinPressureMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getCabinPressure();
  get Cabin Pressure Ret \;.\; Main Mission MID \;!\; ret
  Skip
```

```
getEmergencyOxygenMeth = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getEmergencyOxygenCall. MainMissionMID \longrightarrow
  ret := this.getEmergencyOxygen();
  getEmergencyOxygenRet . MainMissionMID! ret
  Skip
getFuelRemainingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getFuelRemaining();
  getFuelRemainingRet \ . \ MainMissionMID \ ! \ ret
getHeadingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getHeadingCall. MainMissionMID? caller \longrightarrow
  ret := this.getHeading();
  getHeadingRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
setAirSpeedMeth \stackrel{\frown}{=}
  \ 'setAirSpeedCall . MainMissionMID ? caller ? airSpeed-
  this . setAirSpeed(airSpeed);
  setAirSpeedRet . MainMissionMID . caller-
 Skip
setAltitudeMeth \triangleq
  \ 'set Altitude Call . Main Mission MID ? caller ? altitude-
  this.setAltitude(altitude);
  setAltitudeRet. MainMissionMID. caller-
  Skip
setCabinPressureMeth \ \widehat{=} \\
  \ 'set Cabin Pressure Call . Main Mission MID ? caller ? cabin Pressure -
  this.setCabinPressure(cabinPressure);
  set Cabin Pressure Ret . Main Mission MID . caller-
  Skip
setEmergencyOxygenMeth \stackrel{\frown}{=}
  setEmergencyOxygenCall . MainMissionMID? caller? emergencyOxygen
  this.setEmergencyOxygen(emergencyOxygen);
  setEmergencyOxygenRet . MainMissionMID . caller-
 Skip
setFuelRemainingMeth \stackrel{\frown}{=}
  \ 'setFuelRemainingCall\ . MainMissionMID\ ? caller\ ? fuelRemaining-
  this.setFuelRemaining(fuelRemaining);
  setFuelRemainingRet. MainMissionMID. caller \longrightarrow
 Skip
setHeadingMeth \stackrel{\frown}{=}
  \ 'setHeadingCall . MainMissionMID ? caller ? heading-
  this.setHeading(heading);
  setHeadingRet . MainMissionMID . caller
 Skip
```



 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end\_mission\_app} \; . \; \mathit{MainMissionMID} \longrightarrow \mathbf{Skip})$ 

 $\begin{array}{l} \textbf{section} \ \textit{MainMissionClass} \ \textbf{parents} \ \textit{scj\_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan}, \textit{MethodCallBindingChannels} \\ \end{array}$ 

#### ${f class}\, {\it Main Mission Class} \ \widehat{=} \ {f begin}$

 $\mathbf{public}\ \mathit{setCabinPressure}\ \widehat{=}$ 

```
{f state}\ State
      ALTITUDE\_READING\_ON\_GROUND: \mathbb{P} \mathbb{A}
      cabinPressure: \mathbb{P}\,\mathbb{A}
      emergencyOxygen: \mathbb{P} \mathbb{A}
     fuelRemaining: \mathbb{P} \mathbb{A}
      altitude: \mathbb{P}\,\mathbb{A}
      airSpeed: \mathbb{P}\,\mathbb{A}
     heading: \mathbb{P} \mathbb{A}
\mathbf{state}\,\mathit{State}
     initial Init
     State'
      ALTITUDE\_READING\_ON\_GROUND' = 0.0
public getAirSpeed = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
\mathbf{public}\ getAltitude\ \widehat{=}\ \mathbf{var}\ ret: \mathbb{P}\,\mathbb{A}\,\bullet
\mathbf{public}\ \mathit{getCabinPressure}\ \widehat{=}\ \mathbf{var}\ \mathit{ret}: \mathbb{P}\,\mathbb{A}\,\bullet
public getEmergencyOxygen \stackrel{\frown}{=} \mathbf{var}\ ret : \mathbb{P}\ \mathbb{A} \bullet
public getFuelRemaining \cong \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
\mathbf{public}\ \mathit{getHeading}\ \widehat{=}\ \mathbf{var}\ \mathit{ret}: \mathbb{P}\,\mathbb{A}\,\bullet
public setAirSpeed \stackrel{\frown}{=}
public setAltitude \stackrel{\frown}{=}
```

 $\begin{array}{l} \mathbf{public} \ setEmergencyOxygen \ \widehat{=} \\ \\ \mathbf{public} \ setFuelRemaining \ \widehat{=} \\ \\ \mathbf{public} \ setHeading \ \widehat{=} \end{array}$ 

• Skip

 $\quad \mathbf{end} \quad$ 

### 5.2 Schedulables of MainMission

end

 $\mathbf{section}\ ACModeChanger2App\ \mathbf{parents}\ TopLevelMissionSequencerChan,$ Mission Id, Mission Id, Schedulable Id, Schedulable Id, ACMode Changer 2 Class, Method Call Binding Channels $\mathbf{process}\,ACModeChanger2App\,\,\widehat{=}\,\,$  $controlling Mission: Mission ID \bullet \mathbf{begin}$  $State_{\perp}$ controlling Mission: Main Mission $\mathbf{state}\,\mathit{State}$ InitState'controlling Mission' = $GetNextMission \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet$  $ret := this . getNextMission(); \\ getNextMissionRet . ACModeChanger2SID ! ret \longrightarrow$  $Methods \mathrel{\widehat{=}}$ (GetNextMission); Methods • (Init; Methods)  $\triangle$  (end\_sequencer\_app. ACModeChanger2SID  $\longrightarrow$  Skip)

 $\begin{array}{l} \textbf{section} \ A C Mode Changer 2 \ Class \ \textbf{parents} \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels, Mission Id, Mission Ids \end{array}$ 

 $\mathbf{class}\,\mathit{ACModeChanger2Class}\,\,\widehat{=}\,\,\mathbf{begin}$ 

```
\begin{array}{c} \textbf{state } State \\ modes Left : \mathbb{Z} \end{array}
```

 $\mathbf{state}\, State$ 

```
State'
modesLeft' = 3
```

```
'if (modesLeft = 3) \longrightarrow
     (modesLeft := modesLeft - 1;
     [] \neg (modesLeft = 3) \longrightarrow
    if (modesLeft = 2) \longrightarrow
     (modesLeft := modesLeft - 1;
     [] \neg (\dot{modesLeft} = 2) \longrightarrow
    if (modesLeft = 1) \longrightarrow
     (modesLeft := modesLeft - 1;)
     \ \ ret := LandMissionMID
[] \neg (\textit{modesLeft} = 1) \longrightarrow
     (ret := nullMissionId)
fi
fi
fi
```

• Skip

```
\mathbf{process} \ \mathit{ControlHandlerApp} \ \widehat{=} \ \mathbf{begin}
```

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; ControlHandlerSID \longrightarrow \\ \vdots \\ handleAsyncEventRet \; . \; ControlHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
Methods = (handleAsyncEvent); Methods
```

 $\bullet \; (\mathit{Methods}) \; \triangle \; (\mathit{end\_aperiodic\_app} \; . \; \mathit{ControlHandlerSID} \longrightarrow \mathbf{Skip})$ 

```
\mathbf{process} \ \mathit{CommunicationsHandlerApp} \ \widehat{=} \ \mathbf{begin}
```

```
handleAsyncEvent \cong \\ \begin{pmatrix} handleAsyncEventCall \ . \ CommunicationsHandlerSID \longrightarrow \\ \vdots \\ handleAsyncEventRet \ . \ CommunicationsHandlerSID \longrightarrow \\ \mathbf{Skip} \end{pmatrix}
```

```
Methods = (handleAsyncEvent); Methods
```

ullet (Methods)  $\triangle$  (end\_aperiodic\_app . CommunicationsHandlerSID  $\longrightarrow$  Skip)

 $\textbf{section} \ Environment Monitor App \ \textbf{parents} \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding, Main Mission Meth Chan$ 

```
 \begin{aligned} & \textbf{process } \textit{EnvironmentMonitorApp} \; \widehat{=} \\ & \textit{mainMission} : \textit{MissionID} \; \bullet \; \textbf{begin} \end{aligned}   \begin{aligned} & State \\ & \textit{controllingMission} : \textit{MainMission} \end{aligned}   \begin{aligned} & \textbf{state } \textit{State} \\ & & \textbf{Init} \\ & \textit{State'} \\ & & \textit{controllingMission'} = \end{aligned}   \begin{aligned} & & \textbf{handleAsyncEvent} \; \widehat{=} \\ & & \textit{handleAsyncEventCall . EnvironmentMonitorSID} \longrightarrow \\ & \vdots \\ & \textit{handleAsyncEventRet . EnvironmentMonitorSID} \longrightarrow \\ & \textbf{Skip} \end{aligned}   \begin{aligned} & \textbf{Methods} \; \widehat{=} \\ & (\textit{handleAsyncEvent}) \; ; \; \textit{Methods} \end{aligned}   \end{aligned} \bullet (\textit{Init} \; ; \; \textit{Methods}) \; \triangle (\textit{end\_periodic\_app . EnvironmentMonitorSID} \longrightarrow \mathbf{Skip})   \end{aligned}   \end{aligned}   \end{aligned} end
```

${\bf section}\ Environment Monitor Class\ {\bf parents}\ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class} Environment Monitor Class   \widehat{=}   {\bf begin}$
state State
controlling Mission: Main Mission
state Stateinitial Init
State'
• Skip
end

 $\textbf{section} \ Flight Sensors Monitor App \ \textbf{parents} \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Bindies, Main Mission Meth Chan$ 

```
 \begin{aligned} & \textbf{process FlightSensorsMonitorApp} \; \widehat{=} \\ & \textit{mainMission} : \textit{MissionID} \; \bullet \; \textbf{begin} \end{aligned}   \begin{aligned} & State \\ & \textit{controllingMission} : \textit{MainMission} \end{aligned}   \begin{aligned} & \textbf{State} \\ & \textbf{Init} \\ & State' \\ & \textit{controllingMission'} = \end{aligned}   \begin{aligned} & & \textbf{handleAsyncEvent} \; \widehat{=} \\ & & \begin{pmatrix} \textit{handleAsyncEvent} \; \widehat{=} \\ \textit{handleAsyncEventCall} \; . \; \textit{FlightSensorsMonitorSID} \longrightarrow \\ & \textbf{Skip} \\ \end{aligned}   \begin{aligned} & & \textbf{Methods} \; \widehat{=} \\ & & (\textit{handleAsyncEvent}) \; ; \; \textit{Methods} \end{aligned}   \end{aligned}   \end{aligned}   \end{aligned} (\textit{Init} \; ; \; \textit{Methods} ) \; \triangle \; (\textit{end\_periodic\_app . FlightSensorsMonitorSID} \longrightarrow \mathbf{Skip})
```

$ {\bf section} \ Flight Sensors Monitor Class \ {\bf parents} \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels $
${\bf class}  Flight Sensors Monitor Class  \widehat{=}  {\bf begin}$
_ state State
controlling Mission: Main Mission
$\mathbf{state}\mathit{State}$
initial Init
State'
• Skip
end

#### 5.3 TakeOffMission

```
section TakeOffMissionApp parents scj_prelude, MissionId, MissionIds,
     Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Take Off Mission Meth Chan
, \, Take Off Mission Class, \, Method Call Binding Channels
process TakeOffMissionApp \stackrel{\frown}{=}
     controlling Mission: Mission ID \bullet \mathbf{begin}
   State\_
   this: {f ref}\ Take Off Mission Class
   controlling Mission: Main Mission\\
{f state}\ State
  Init
   State'
   this' = \mathbf{new} \ TakeOffMissionClass()
   controlling Mission' =
InitializePhase =
  initializeCall. TakeOffMissionMID \longrightarrow
  register \,!\, Landing Gear Handler SID \,!\, Take Off Mission MID-
  register! TakeOffMonitorSID! TakeOffMissionMID \longrightarrow
  register \ ! \ Take Off Failure Handler SID \ ! \ Take Off Mission MID \longrightarrow
  initializeRet. TakeOffMissionMID \longrightarrow
  Skip
CleanupPhase \stackrel{\frown}{=}
  \mathbf{var}\,\mathbb{B}:ret\,ullet
  cleanup {\it Mission Call}\:.\: Take Off Mission MID-
  cleanup {\it MissionRet}\:.\: Take {\it Off Mission MID}\:!\: ret
  Skip
takeOffAbortMeth \stackrel{\frown}{=}
  \ 'take Off Abort Call . Take Off Mission MID? caller-
  this. takeOffAbort();
  take {\it OffAbortRet}\;.\; Take {\it OffMissionMID}\;.\; caller
deployLandingGearMeth \stackrel{\frown}{=}
  deployLandingGearCall. TakeOffMissionMID? caller
  this.\ deployLandingGear();
  deploy Landing Gear Ret.\ Take Off Mission MID\ .\ caller
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  ^{'}stowLandingGearCall . TakeOffMissionMID ? caller-
  this.stowLandingGear();
  stowLandingGearRet.\ TakeOffMissionMID\ .\ caller
  Skip
```

```
is Landing Gear Deployed Meth \ensuremath{\widehat{=}} \mathbf{var} \ ret : \mathbb{B} \bullet \\ is Landing Gear Deployed Call \ . \ Take Off Mission MID \ ? \ caller \longrightarrow \\ ret := this \ . \ is Landing Gear Deployed (); \\ is Landing Gear Deployed Ret \ . \ Take Off Mission MID \ . \ caller \ ! \ ret \longrightarrow \\ \mathbf{Skip}
```

```
Methods \triangleq \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ takeOffAbortMeth \\ \Box \\ deployLandingGearMeth \\ \Box \\ stowLandingGearMeth \\ \Box \\ isLandingGearDeployedMeth \end{pmatrix}; Methods
```

 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end\_mission\_app} \; . \; \mathit{TakeOffMissionMID} \longrightarrow \mathbf{Skip})$ 

 $\begin{array}{l} \textbf{section} \ \ Take Off Mission Class \ \ \textbf{parents} \ \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels \end{array}$ 

 $\mathbf{class}\;\mathit{TakeOffMissionClass}\;\widehat{=}\;\mathbf{begin}$ 

```
\begin{array}{c} \textbf{state } State = \\ SAFE\_AIRSPEED\_THRESHOLD : \mathbb{P} \, \mathbb{A} \\ TAKEOFF\_ALTITUDE : \mathbb{P} \, \mathbb{A} \\ abort : \mathbb{B} \\ landing Gear Deployed : \mathbb{B} \end{array}
```

 $\mathbf{state}\,\mathit{State}$ 

```
\begin{array}{l} \mathbf{public} \ takeOffAbort \ \widehat{=} \\ \\ \mathbf{public} \ deployLandingGear \ \widehat{=} \\ \\ \mathbf{public} \ stowLandingGear \ \widehat{=} \\ \\ \mathbf{public} \ isLandingGearDeployed \ \widehat{=} \ \mathbf{var} \ ret : \mathbb{B} \ \bullet \end{array}
```

• Skip

### ${\bf section}\ \textit{TakeOffMissionMethChan}\ {\bf parents}\ \textit{scj\_prelude}, \textit{GlobalTypes}, \textit{MissionId}, \textit{SchedulableId}$

$$\label{lem:channel} \begin{split} \textbf{channel} \ takeOffAbortCall: MissionID \times SchedulableID \\ \textbf{channel} \ takeOffAbortRet: MissionID \times SchedulableID \end{split}$$

channel clean Up Call : Mission IDchannel  $clean Up Ret : Mission ID \times \mathbb{B}$ 

$$\label{lem:channel} \begin{split} \textbf{channel} \ stowLandingGearCall: \ MissionID \times SchedulableID \\ \textbf{channel} \ stowLandingGearRet: \ MissionID \times SchedulableID \end{split}$$

 $\label{lem:channel} \textbf{channel} \ is Landing Gear Deployed Call: \ Mission ID \times Schedulable ID \\ \textbf{channel} \ is Landing Gear Deployed Ret: \ Mission ID \times Schedulable ID \times \mathbb{B}$ 

$$\label{lem:channel} \begin{split} \textbf{channel} \ deployLandingGearCall: \textit{MissionID} \times \textit{SchedulableID} \times \textit{ThreadID} \\ \textbf{channel} \ deployLandingGearRet: \textit{MissionID} \times \textit{SchedulableID} \times \textit{ThreadID} \end{split}$$

### 5.4 Schedulables of TakeOffMission

 ${\bf section} \ Landing Gear Handler App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Bindre, Take Off Mission Meth Chan$ 

```
 \begin{aligned} \mathbf{process} \ Landing Gear Handler App \ \widehat{=} \\ mission : Mission ID \bullet \mathbf{begin} \end{aligned}   \begin{aligned} handle A sync Event \ \widehat{=} \\ \left( \begin{aligned} handle A sync Event Call \ . \ Landing Gear Handler SID \longrightarrow \\ \vdots \\ handle A sync Event Ret \ . \ Landing Gear Handler SID \longrightarrow \\ \mathbf{Skip} \end{aligned} \right)   \begin{aligned} \mathbf{Methods} \ \widehat{=} \\ \left( handle A sync Event \right) \ ; \ Methods \end{aligned}   \begin{aligned} \bullet \ (Methods) \ \triangle \ (end\_aperiodic\_app \ . \ Landing Gear Handler SID \longrightarrow \mathbf{Skip}) \end{aligned}   \end{aligned}
```

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffFailureHandlerApp} \ \ \textbf{parents} \ \ \textit{AperiodicEventHandlerChan}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{MethodCallBinden}, \textit{MainMissionMethChan}, \textit{TakeOffMissionMethChan} \\ \end{array}$ 

```
 \begin{array}{l} \mathbf{process} \ TakeOffFailureHandlerApp \ \stackrel{\frown}{=} \\ mainMission : MissionID, \\ takeoffMission : MissionID, \\ threshold : \mathbb{P} \mathbb{A} \bullet \mathbf{begin} \\ \\ handleAsyncEvent \ \stackrel{\frown}{=} \\ \begin{pmatrix} handleAsyncEvent Call \ . \ TakeOffFailureHandlerSID \longrightarrow \\ \vdots \\ handleAsyncEventRet \ . \ TakeOffFailureHandlerSID \longrightarrow \\ \mathbf{Skip} \\ \\ \\ Methods \ \stackrel{\frown}{=} \\ (handleAsyncEvent) \ ; \ Methods \\ \\ \bullet \ (Methods) \ \triangle \ (end\_aperiodic\_app \ . \ TakeOffFailureHandlerSID \longrightarrow \mathbf{Skip}) \\ \\ \mathbf{end} \\ \\ \end{array}
```

$section \ \textit{TakeOffFatureHandlerClass} \ \textbf{parents} \ \textit{scj\_pretude}, \textit{Schedulable1d}, \textit{Schedulable1ds}, \textit{SafetetChan} \ \textit{MethodCallBindingChannels}$
$\textbf{class} \ \textit{TakeOffFailureHandlerClass} \ \widehat{=} \ \textbf{begin}$
state State
$threshold: \mathbb{P}\mathbb{A}$
state State initial Init
State'
• Skip
end

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffMonitorApp} \ \ \textbf{parents} \ \ \textit{PeriodicEventHandlerChan}, SchedulableId, SchedulableIds, MethodCallBindingChan, MainMissionMethChan \end{array}$ 

```
\mathbf{process}\;\mathit{TakeOffMonitorApp}\;\widehat{=}\;
     mainMission: MissionID,
take O\!f\!f\!Mission: Mission ID,
takeOffAltitude : \mathbb{P} \mathbb{A},
landing Gear Handler: Schedulable ID \bullet \mathbf{begin}
   State.
    take o\!f\!f\!Mission: Take O\!f\!f\!Mission
\mathbf{state}\,\mathit{State}
   Init.
    State'
    take of fMission' =
handleAsyncEvent =
  'handle Async Event Call . Take Off Monitor SID \longrightarrow
  ; handleAsyncEventRet. TakeOffMonitorSID \longrightarrow
Methods \mathrel{\widehat{=}}
(handle A sync Event); Methods
ullet (Init; Methods) \triangle (end_periodic_app. TakeOffMonitorSID \longrightarrow Skip)
```

${\bf section}\ \ Take Off Monitor Class\ \ {\bf parents}\ \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}\ TakeOffMonitorClass\ \widehat{=}\ {\bf begin}$
state State
$takeOffAltitude: \mathbb{P}  \mathbb{A}$
state Stateinitial Init
• Skip
end

## 5.5 CruiseMission

 $InitializePhase = \\ \left( \begin{array}{l} initializeCall \; . \; CruiseMissionMID \longrightarrow \\ register \; ! \; BeginLandingHandlerSID \; ! \; CruiseMissionMID \longrightarrow \\ register \; ! \; NavigationMonitorSID \; ! \; CruiseMissionMID \longrightarrow \\ initializeRet \; . \; CruiseMissionMID \longrightarrow \\ \mathbf{Skip} \end{array} \right)$ 

 $\begin{array}{l} \textit{CleanupPhase} \; \widehat{=} \\ \left( \begin{array}{l} \textit{cleanupMissionCall} \; . \; \textit{CruiseMissionMID} \longrightarrow \\ \textit{cleanupMissionRet} \; . \; \textit{CruiseMissionMID} \; ! \; \textbf{True} \longrightarrow \\ \textbf{Skip} \end{array} \right)$ 

$$Methods \cong \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix}$$
;  $Methods$ 

ullet (Init; Methods)  $\triangle$  (end\_mission\_app. CruiseMissionMID  $\longrightarrow$  **Skip**)

${\bf section}\ Cruise Mission Class\ {\bf parents}\ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}\ Cruise Mission Class\ \widehat{=}\ {\bf begin}$
state State
controlling Mission: Main Mission
state Stateinitial Init
State'
• Skip
end

# 5.6 Schedulables of CruiseMission

 ${\bf section}\ Begin Landing Handler App\ {\bf parents}\ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binder Chan, Method Chan, Me$ 

```
 \begin{aligned} & \textbf{process } \textit{BeginLandingHandlerApp} \; \widehat{=} \\ & \textit{controllingMission} : \textit{MissionID} \; \bullet \; \textbf{begin} \end{aligned} \\ & \textit{handleAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{BeginLandingHandlerSID} \longrightarrow \\ ; \\ & \textit{handleAsyncEventRet} \; . \; \textit{BeginLandingHandlerSID} \longrightarrow \\ \textbf{Skip} \\ \\ & \textit{Methods} \; \widehat{=} \\ & \textit{(handleAsyncEvent)} \; ; \; \textit{Methods} \end{aligned} \\ & \bullet \; (\textit{Methods}) \; \triangle \; (\textit{end\_aperiodic\_app} \; . \; \textit{BeginLandingHandlerSID} \longrightarrow \textbf{Skip}) \end{aligned} \\ & \textbf{end}
```

 $\textbf{section} \ \textit{NavigationMonitorApp} \ \textbf{parents} \ \textit{PeriodicEventHandlerChan}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{MethodCallBindingOption}, \textit{MainMissionMethChan}$ 

```
\begin{array}{l} \mathbf{process} \ NavigationMonitorApp \ \widehat{=} \\ mainMission : MissionID \bullet \mathbf{begin} \\ \\ handle Async Event \ \widehat{=} \\ \left( \begin{array}{l} handle Async Event Call \ . \ NavigationMonitorSID \longrightarrow \\ \vdots \\ handle Async Event Ret \ . \ NavigationMonitorSID \longrightarrow \\ \mathbf{Skip} \\ \end{array} \right) \\ Methods \ \widehat{=} \\ \left( handle Async Event \right) \ ; \ Methods \\ \\ \bullet \ (Methods) \ \triangle \ (end\_periodic\_app \ . \ NavigationMonitorSID \longrightarrow \mathbf{Skip}) \\ \mathbf{end} \\ \end{array}
```

## 5.7 LandMission

```
section LandMissionApp parents scj_prelude, MissionId, MissionIds,
     Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Land Mission Meth Chan
, Land Mission Class, Method Call Binding Channels \\
process Land Mission App \cong
     controlling Mission: Mission ID ullet \mathbf{begin}
  State_
   this: \mathbf{ref}\ Land Mission Class
   controlling Mission: Main Mission\\
{f state}\ State
  Init
   State'
   this' = \mathbf{new} \ Land Mission Class()
   controlling Mission' =
InitializePhase \stackrel{\frown}{=}
  initializeCall . LandMissionMID \longrightarrow
  register! GroundDistanceMonitorSID! LandMissionMID \longrightarrow
  register! LandingGearHandlerLandSID! LandMissionMID \longrightarrow
  register! InstrumentLandingSystemMonitorSID! LandMissionMID-
  register! SafeLandingHandlerSID! LandMissionMID \longrightarrow
  initializeRet . LandMissionMID \longrightarrow
  Skip
CleanupPhase \ \widehat{=} \ 
  \mathbf{var}\,\mathbb{B}:ret\,ullet
  clean up {\it Mission Call}\ .\ Land {\it Mission MID}\ -
  cleanup {\it MissionRet} \;. \; Land {\it MissionMID} \;! \; ret
deployLandingGearMeth \stackrel{\frown}{=}
  \ 'deploy Landing Gear Call . Land Mission MID ? caller-
  this. deployLandingGear();
  deploy Landing Gear Ret\ .\ Land Mission MID\ .\ caller
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  stowLandingGearCall . LandMissionMID? caller-
  this.stowLandingGear();
  stow Landing Gear Ret\ .\ Land Mission MID\ .\ caller
  Skip
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  is Landing Gear Deployed Call . Land Mission MID ? caller \longrightarrow
  ret := this.isLandingGearDeployed();
  is Landing Gear Deployed Ret \ . \ Land Mission MID \ . \ caller \ ! \ ret-
  Skip
```

$$Methods \triangleq \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ deployLandingGearMeth \\ \Box \\ stowLandingGearMeth \\ \Box \\ isLandingGearDeployedMeth \end{pmatrix}; Methods$$

 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end\_mission\_app} \; . \; \mathit{LandMissionMID} \longrightarrow \mathbf{Skip})$ 

 $\mathbf{end}$ 

 ${\bf section}\ Land Mission Class\ {\bf parents}\ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan$ , Method Call Binding Channels $\mathbf{class}\,\mathit{LandMissionClass}\,\,\widehat{=}\,\,\mathbf{begin}$  ${f state}\, State$  \_  $SAFE\_LANDING\_ALTITUDE: \mathbb{P}\,\mathbb{A}$  $abort: \mathbb{B}$  $landing Gear Deployed: \mathbb{B}$  ${f state}\, State$  $\mathbf{initial}\ Init$ State'  $SAFE\_LANDING\_ALTITUDE' = 10.0$ abort'=false $\mathbf{public}\ \mathit{deployLandingGear}\ \widehat{=}$  $\mathbf{public}\ stowLandingGear\ \widehat{=}\$ **public**  $isLandingGearDeployed <math>\stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet$ • Skip

 $\quad \mathbf{end} \quad$ 

# ${\bf section}\ Land {\it Mission Meth Chan}\ {\bf parents}\ scj\_prelude, {\it Global Types}, {\it Mission Id}, {\it Schedulable Id}$

 $\begin{cal}{c} {\bf channel} \ stowLandingGearCall: MissionID \times \\ {\bf channel} \ stowLandingGearRet: MissionID \times \\ \end{cal}$ 

 $\begin{tabular}{ll} {\bf channel} \ is Landing Gear Deployed Call: Mission ID \times \\ {\bf channel} \ is Landing Gear Deployed Ret: Mission ID \times \times \mathbb{B} \\ \end{tabular}$ 

 $\begin{tabular}{ll} {\bf channel} \ clean Up Call : {\it Mission ID} \\ {\bf channel} \ clean Up Ret : {\it Mission ID} \times \mathbb{B} \\ \end{tabular}$ 

$$\label{lem:channel} \begin{split} \textbf{channel} \ deployLandingGearCall} : \textit{MissionID} \times \times \textit{ThreadID} \\ \textbf{channel} \ deployLandingGearRet} : \textit{MissionID} \times \times \textit{ThreadID} \end{split}$$

# 5.8 Schedulables of LandMission

 ${\bf section} \ Landing Gear Handler Land App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Ids, Method Calley, Land Mission Meth Chan$ 

```
 \begin{aligned} \mathbf{process} \ Landing Gear Handler Land App} & \cong \\ mission : Mission ID \bullet \mathbf{begin} \end{aligned} \\ handle A sync E vent & \cong \\ \begin{pmatrix} handle A sync E vent Call \ . \ Landing Gear Handler Land SID \longrightarrow \\ \vdots \\ handle A sync E vent Ret \ . \ Landing Gear Handler Land SID \longrightarrow \\ \mathbf{Skip} \end{aligned} \\ Methods & \cong \\ \begin{pmatrix} handle A sync E vent \end{pmatrix}; \ Methods \\ \bullet \ (Methods) \triangle \ (end\_aperiodic\_app \ . \ Landing Gear Handler Land SID \longrightarrow \mathbf{Skip}) \end{aligned} \\ \mathbf{end}
```

 $\textbf{section} \ \ \textit{SafeLandingHandlerApp} \ \ \textbf{parents} \ \ \textit{AperiodicEventHandlerChan}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{MethodCallBindingHandlerChan}, \textit{MainMissionMethChan}$ 

```
\begin{aligned} &\mathbf{process}\,Safe Landing Handler App} \; \widehat{=} \\ & \textit{mainMission}: \textit{MissionID}, \\ &\textit{threshold}: \mathbb{P}\,\mathbb{A} \bullet \mathbf{begin} \end{aligned} \begin{aligned} &\textit{handle Async Event} \; \widehat{=} \\ & \begin{pmatrix} \textit{handle Async Event Call} \; . \; Safe Landing Handler SID \longrightarrow \\ \vdots \\ &\textit{handle Async Event Ret} \; . \; Safe Landing Handler SID \longrightarrow \\ &\mathbf{Skip} \end{aligned} \begin{aligned} &\mathsf{Methods} \; \widehat{=} \\ & (\textit{handle Async Event}) \; ; \; \textit{Methods} \end{aligned} \bullet \; (\textit{Methods}) \; \triangle \; (\textit{end\_aperiodic\_app} \; . \; Safe Landing Handler SID \longrightarrow \mathbf{Skip}) \end{aligned}
```

${\bf section} \ \ Safe Landing Handler Class \ \ {\bf parents} \ \ scj\_prelude, Schedulable Id, Schedulable Ids, Safe let Chan, Method Call Binding Channels$
${\bf class} Safe Landing Handler Class \ \widehat{=} \ {\bf begin}$
state State
$threshold: \mathbb{P} \mathbb{A}$
state State
State'
• Skip
end

 ${\bf section} \ \ Ground Distance Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Ids, Method Call Birger, Main Mission Meth Chan$ 

```
\begin{aligned} \mathbf{process} & \textit{GroundDistanceMonitorApp} \; \widehat{=} \\ & \textit{mainMission} : \textit{MissionID} \; \bullet \; \mathbf{begin} \\ \\ & \textit{handleAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{GroundDistanceMonitorSID} \longrightarrow \\ ; \\ & \textit{handleAsyncEventRet} \; . \; \textit{GroundDistanceMonitorSID} \longrightarrow \\ \mathbf{Skip} \\ \\ & \textit{Methods} \; \widehat{=} \\ & (\textit{handleAsyncEvent}) \; ; \; \textit{Methods} \\ \\ & \bullet \; (\textit{Methods}) \; \triangle \; (\textit{end\_periodic\_app} \; . \; \textit{GroundDistanceMonitorSID} \longrightarrow \mathbf{Skip}) \\ \end{aligned}
```

${\bf section} \ \ Ground Distance Monitor Class \ \ {\bf parents} \ \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels$
${\bf class}\ Ground Distance Monitor Class\ \widehat{=}\ {\bf begin}$
state State
$readingOnGround: \mathbb{P}\mathbb{A}$
$\mathbf{state}\mathit{State}$
_ initial Init
State'
• Skip
end

```
 \begin{aligned} \mathbf{process} & \textit{InstrumentLandingSystemMonitorApp} \; \widehat{=} \\ & \textit{mission} : \textit{MissionID} \; \bullet \; \mathbf{begin} \\ \\ & \textit{handleAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ \\ & \vdots \\ & \textit{handleAsyncEventRet} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ & \mathbf{Skip} \\ \\ \\ & Methods \; \widehat{=} \\ & (\textit{handleAsyncEvent}) \; ; \; \; \textit{Methods} \\ \\ & \bullet \; \; (\textit{Methods}) \; \triangle \; (\textit{end\_periodic\_app} \; . \; \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \mathbf{Skip}) \\ \\ & \mathbf{end} \end{aligned}
```