aircraft

Tight Rope v0.6

November 1, 2015

1 Network

```
section NetworkChannels parents scj_prelude, MissionId, MissionIds,
         Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Chan, Top Level Mission Sequencer FWChan, Top Level Mission Sequencer FWChan
         Framework Chan, Safelet Chan
channelset TerminateSync ==
         \{|schedulables\_terminated, schedulables\_stopped, get\_activeSchedulables|\}
channelset ControlTierSync ==
          \{ | start\_toplevel\_sequencer, done\_toplevel\_sequencer, done\_safeletFW | \}
channelset TierSync ==
         \{ | start\_mission., done\_mission., \}
         done\_safeletFW, done\_toplevel\_sequencer }
channelset MissionSync ==
          \{|done\_safeletFW, done\_toplevel\_sequencer, register, \}
signal Termination Call, signal Termination Ret, activate\_schedulables, done\_schedulable,
cleanupSchedulableCall, cleanupSchedulableRet
{\bf channelset} \ SchedulablesSync ==
         \{|activate\_schedulables, done\_safeletFW, done\_toplevel\_sequencer\}\}
{\bf channel set} \ {\it Cluster Sync} = =
          \{|done\_toplevel\_sequencer, done\_safeletFW|\}
channelset AppSync ==
         \bigcup \{SafeltAppSync, MissionSequencerAppSync, MissionAppSync, \}
         MTAppSync, OSEHSync, APEHSync,
         {| getSequencer, end_mission_app, end_managedThread_app,
         set Ceiling Priority, request Termination Call, request Termination Ret, termination Pending Call,
         terminationPendingRet, handleAsyncEventCall, handleAsyncEventRet \} 
channelset ObjectSync ==
         {| }
{f channelset} \ \mathit{ThreadSync} ==
         \{ | \}
{f channel set} \ {\it Locking Sync} ==
         \{ | lockAcquired, startSyncMeth, endSyncMeth, waitCall, waitRet, notify \}
```

```
 \begin{split} \textbf{channelset} \  \, \textit{Tier0Sync} == \\ & \{ | \  \, \textit{done\_toplevel\_sequencer}, \  \, \textit{done\_safeletFW}, \\ \textit{start\_mission., done\_mission.,} \\ & \  \, \textit{initializeRet., requestTermination..,} \\ \textit{start\_mission., done\_mission.,} \\ & \  \, \textit{initializeRet., requestTermination..,} \\ \textit{start\_mission., done\_mission.,} \\ & \  \, \textit{initializeRet., requestTermination...} \, \} \end{split}
```

```
section Program parents scj_prelude, MissionId, MissionIds,
         SchedulableId, SchedulableIds, MissionChan, SchedulableMethChan, MissionFW,
         Safe let FW, Top Level Mission Sequencer FW, Network Channels, Managed Thread FW,
         Schedulable Mission Sequencer FW, Periodic Event Handler FW, One Shot Event Handler FW,
         Aperiodic Event Handler FW, ACS a felet App, Main Mission Sequencer App,
          ObjectFW, ThreadFW,
                                                                       Main Mission App, A C Mode Changer App, Control Handler App, Communications Handler App, Communication Handler App, Communic
process ControlTier =
     SafeletFW
              [ControlTierSync]
     TopLevelMissionSequencerFW(MainMissionSequencer)
process Tier0 =
     MissionFW(MainMission)
              [MissionSync]
          Schedulable Mission Sequencer FW()
                   [SchedulablesSync]
               AperiodicEventHandlerFW()
                        [SchedulablesSync]
               Aperiodic Event Handler FW()
                   [SchedulablesSync]
               PeriodicEventHandlerFW()
                        [SchedulablesSync]
               PeriodicEventHandlerFW()
                        [SchedulablesSync]
               PeriodicEventHandlerFW()
process Tier1 =
     MissionFW (\mathit{TakeOffMission})
              [MissionSync]
               Aperiodic Event Handler FW()
                        [SchedulablesSync]
               Aperiodic Event Handler FW()
                   [SchedulablesSync]
          PeriodicEventHandlerFW()
           [ClusterSync]
     MissionFW(CruiseMission)
              [MissionSync]
          AperiodicEventHandlerFW()
                   [SchedulablesSync]
          PeriodicEventHandlerFW()
          [ClusterSync]
     MissionFW(LandMission)
              [MissionSync]
              AperiodicEventHandlerFW()
                        [SchedulablesSync]
               Aperiodic Event Handler FW()
                   [SchedulablesSync]
               PeriodicEventHandlerFW()
                        [\![SchedulablesSync]\!]
               PeriodicEventHandlerFW()
\mathbf{process} \, \mathit{Framework} \, \, \widehat{=} \,
     ControlTier
              [TierSync]
```

```
\mathbf{process} Application \cong
                 ACSafeletApp
                 MainMissionSequencerApp
                 Main Mission App (hijac.tools.tightrope.environments.Variable Env ullet 71c27ee8, hijac.tools.tightrope.environments.Variable Env ullet 71c27ee8, hijac.tools
                 ACModeChangerApp(MainMission)
                 Control Handler App
                 Communications Handler App
                 EnvironmentMonitorApp(MainMission)
                 FlightSensorsMonitorApp(MainMission)
                 Aperiodic Simulator App (Aperiodic Event Handler)
                 Take Off Mission App (hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Variable Env ullet 6e950 bcf, hijac. tools. tightrope. environments. Tightrope. environments. Tightrope. Environments. Tightrope. Environments. Tightrope. Environments. Tightrope. Environments. Tightrope. Tightrope. Environments. Tightrope. Tightrop
                 Landing Gear Handler Take Off App (Take Off Mission)
                 TakeOffFailureHandlerApp(TakeOffMission)
                 Take Off Monitor App (\ Take Off Mission, Aperiodic Event Handler)
                 Cruise Mission App(hijac.tools.tightrope.environments.Variable Env ullet 46 dff dc3, hijac.tools.tightrope.environments.Variable Env ullet 46 dff dc3, hijac.tools.tig
                 BeginLandingHandlerApp(Mission)
                 NavigationMonitorApp(CruiseMission)
                 Land Mission App (hijac.tools.tightrope.environments.Variable Env ullet 53dbe 163, hijac.tools.tightrope.environments.Variable Env ullet 1000 and 1000 a
                 LandingGear Handler LandApp(LandMission)
                 SafeLandingHandlerApp(LandMission)
                 GroundDistanceMonitorApp(LandMission)
```

InstrumentLandingSystemMonitorApp(LandMission)

```
Locking =
    ThreadFW(LandingGearHandlerLandThread, MinPriority)
       [ThreadSync]
    ThreadFW(SafeLandingHandlerThread, MinPriority)
       [ThreadSync]
    ThreadFW(GroundDistanceMonitorThread,MinPriority)
       [ThreadSync]
    ThreadFW(InstrumentLandingSystemMonitorThread, MinPriority)
   ObjectFW(ACSafeletObject)
       [ObjectSync]
   ObjectFW(MainMissionObject)
       [ObjectSync]
    ObjectFW(TakeOffMissionObject)
       [ObjectSync]
    ObjectFW(CruiseMissionObject)
       [ObjectSync]
    ObjectFW(LandMissionObject)
       [ObjectSync]
    ObjectFW(ACModeChangerObject)
       [ObjectSync]
    ObjectFW(EnvironmentMonitorObject)
       [ObjectSync]
    ObjectFW(ControlHandlerObject)
       [ObjectSync]
   ObjectFW(FlightSensorsMonitorObject)
       [ObjectSync]
    ObjectFW(CommunicationsHandlerObject)
        [ObjectSync]
    ObjectFW (AperiodicSimulatorObject) \\
       [ObjectSync]
    ObjectFW(LandingGearHandlerTakeOffObject)
       [ObjectSync]
    ObjectFW(TakeOffMonitorObject)
       [ObjectSync]
    ObjectFW(TakeOffFailureHandlerObject)
       [ObjectSync]
    ObjectFW(BeginLandingHandlerObject)
       [ObjectSync]
    ObjectFW(NavigationMonitorObject)
       [ObjectSync]
   ObjectFW(\bar{GroundDistanceMonitorObject)}
        [ObjectSync]
    ObjectFW(LandingGearHandlerLandObject)
       [ObjectSync]
    ObjectFW (InstrumentLandingSystemMonitorObject)
       [ObjectSync]
    ObjectFW(SafeLandingHandlerObject)
```

 $\mathbf{process} \ Program \ \widehat{=} \ Framework \ \llbracket \ AppSync \ \rrbracket \ Application \ \llbracket \ LockingSync \ \rrbracket \ Locking$

2 ID Files

2.1 MissionIds

section MissionIds parents scj_prelude, MissionId

MainMission: MissionID TakeOffMission: MissionID CruiseMission: MissionID LandMission: MissionID

 $distinct \langle null Mission Id, Main Mission, \ Take Off Mission, \ Cruise Mission, \ Land Mission \rangle$

2.2 SchedulablesIds

 $section Schedulable Ids parents scj_prelude, Schedulable Id$

 $\label{lem:main} MainMissionSequencer: SchedulableID \\ ACModeChanger: SchedulableID \\ EnvironmentMonitor: SchedulableID \\ ControlHandler: SchedulableID \\ FlightSensorsMonitor: SchedulableID \\ CommunicationsHandler: SchedulableID \\ AperiodicSimulator: SchedulableID \\ \end{tabular}$

Landing Gear Handler Take Off: Schedulable ID

TakeOffMonitor: SchedulableID
TakeOffFailureHandler: SchedulableID
BeginLandingHandler: SchedulableID
NavigationMonitor: SchedulableID
GroundDistanceMonitor: SchedulableID
LandingGearHandlerLand: SchedulableID

Instrument Landing System Monitor: Schedulable ID

Safe Landing Handler: Schedulable ID

 $distinct \langle null Sequencer Id, null Schedulable Id, ACMode Changer,$

EnvironmentMonitor,

ControlHandler,

FlightSensorsMonitor,

CommunicationsHandler,

AperiodicSimulator,

Landing Gear Handler Take Off,

Take Off Monitor,

Take Off Failure Handler,

BeginLandingHandler,

Navigation Monitor,

Ground Distance Monitor,

LandingGearHandlerLand,

Instrument Landing System Monitor,

 $SafeLandingHandler \rangle$

2.3 ThreadIds

 $section \ ThreadIds \ parents \ scj_prelude, \ GlobalTypes$

 $ACMode Changer Thread: Thread ID\\ Environment Monitor Thread: Thread ID\\ Control Handler Thread: Thread ID\\ Flight Sensors Monitor Thread: Thread ID\\ Communications Handler Thread: Thread ID\\ Aperiodic Simulator Thread: Thread ID\\$

 $Landing Gear Handler Take Off Thread:\ Thread ID$

Take Off Monitor Thread: Thread ID

TakeOffFailureHandlerThread: ThreadID
BeginLandingHandlerThread: ThreadID
NavigationMonitorThread: ThreadID
GroundDistanceMonitorThread: ThreadID
LandingGearHandlerLandThread: ThreadID

InstrumentLandingSystemMonitorThread: ThreadID

Safe Landing Handler Thread: Thread ID

 $distinct\langle SafeletThreadId, nullThreadId,$ ACModeChangerThread, EnvironmentMonitorThread, ControlHandlerThread, FlightSensorsMonitorThread, Communications Handler Thread, AperiodicSimulatorThread, Landing Gear Handler Take Off Thread, Take Off Monitor Thread, Take Off Failure Handler Thread, BeginLandingHandlerThread, Navigation Monitor Thread, Ground Distance Monitor Thread,Landing Gear Handler Land Thread, InstrumentLandingSystemMonitorThread, SafeLandingHandlerThread

2.4 ObjectIds

 ${\bf section}\ Object Ids\ {\bf parents}\ scj_prelude,\ Global Types$

ACSafeletObject: ObjectID
MainMissionObject: ObjectID
TakeOffMissionObject: ObjectID
CruiseMissionObject: ObjectID
LandMissionObject: ObjectID
ACModeChangerObject: ObjectID
EnvironmentMonitorObject: ObjectID
ControlHandlerObject: ObjectID
FlightSensorsMonitorObject: ObjectID
CommunicationsHandlerObject: ObjectID
AperiodicSimulatorObject: ObjectID
LandingGearHandlerTakeOffObject: ObjectID

TakeOffMonitorObject: ObjectID
TakeOffFailureHandlerObject: ObjectID
BeginLandingHandlerObject: ObjectID
NavigationMonitorObject: ObjectID
GroundDistanceMonitorObject: ObjectID
LandingGearHandlerLandObject: ObjectID

InstrumentLandingSystemMonitorObject:ObjectID

Safe Landing Handler Object: Object ID

 $distinct \langle ACSafeletObject,$ Main Mission Object,Take Off Mission Object,Cruise Mission Object,LandMissionObject, ACModeChangerObject, EnvironmentMonitorObject, ControlHandlerObject, FlightSensorsMonitorObject, Communications Handler Object,Aperiodic Simulator Object,Landing Gear Handler Take Off Object,TakeOffMonitorObject, Take Off Failure Handler Object,BeginLandingHandlerObject, NavigationMonitorObject, Ground Distance Monitor Object,Landing Gear Handler Land Object, In strument Landing System Monitor Object,SafeLandingHandlerObject

3 Safelet

```
{\bf section}\ ACS a felet App\ {\bf parents}\ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan
```

```
\mathbf{process}\,\mathit{ACSafeletApp}\,\,\widehat{=}\,\,\mathbf{begin}
```

 $\bullet \; (Methods) \; \triangle \; (end_safelet_app \longrightarrow \mathbf{Skip})$

 $\quad \mathbf{end} \quad$

Top Level Mission Sequencer 4

section MainMissionSequencerApp parents TopLevelMissionSequencerChan, MissionId, MissionIds, SchedulableId, MainMissionSequencerClass

 $process MainMissionSequencerApp \stackrel{\frown}{=} begin$

```
State_{-}
    this: {\bf ref}\ Main Mission Sequencer Class
{f state}\ State
   Init
    State'
    this' = \mathbf{new} \ Main Mission Sequencer Class()
GetNextMission \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
   \begin{array}{l} ret := this . \ getNextMission(); \\ getNextMissionRet . \ MainMissionSequencer ! \ ret \longrightarrow \\ \end{array} 
 \ Skip
Methods \stackrel{\frown}{=}
(GetNextMission); Methods
ullet (Init; Methods) \triangle (end_sequencer_app. MainMissionSequencer \longrightarrow Skip)
end
```

$\mathbf{class}\,\mathit{MainMissionSequencerClass} \; \widehat{=} \; \mathbf{begin}$

returned Mission' = false

• Skip

end

5 Missions

5.1 MainMission

```
section MainMissionApp parents sci_prelude, MissionId, MissionIds,
     Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Main Mission Class
                                                                                                             , Main Mission Meth Chan
process\ MainMissionApp\ \widehat{=}\ storageParameters: MissionID, storageParametersSchedulable: MissionID, aCModeChange
   State
    this: \mathbf{ref}\ Main Mission\ Class
\mathbf{state}\,\mathit{State}
   Init
   State '
   this' = \mathbf{new} \ Main Mission Class()
InitializePhase \stackrel{\frown}{=}
  initializeCall. MainMission \longrightarrow
  register ! ACModeChanger ! MainMission \longrightarrow
  register \,! \, Environment Monitor \,! \, Main Mission
  register! ControlHandler! MainMission \longrightarrow
  register! FlightSensorsMonitor! MainMission-
  register \ ! \ Communications Handler \ ! \ Main Mission -
  register! AperiodicSimulator! MainMission \longrightarrow
  initializeRet . MainMission \longrightarrow
  Skip
CleanupPhase \stackrel{\frown}{=}
  cleanupMissionCall. MainMission \longrightarrow
  cleanup {\it MissionRet} \ . \ Main {\it Mission!} \ {\bf True}
  Skip
getAirSpeedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : double \bullet
  ret := this.getAirSpeed();
  getAirSpeedRet . MainMission! ret
  Skip
getAltitudeMeth \stackrel{\frown}{=} \mathbf{var} \ ret : double \bullet
  ret := this.getAltitude();
  getAltitudeRet\ .\ MainMission\ !\ ret
  Skip
getCabinPressureMeth \stackrel{\frown}{=} \mathbf{var} \ ret : double \bullet
  ret := this.getCabinPressure();
  get Cabin Pressure Ret \ . \ Main Mission \ ! \ ret
  Skip
```

```
getEmergencyOxygenMeth = \mathbf{var} \ ret : double \bullet
  getEmergencyOxygenCall. MainMission \longrightarrow
  ret := this.getEmergencyOxygen();
  getEmergencyOxygenRet.\ MainMission \ !\ ret
  Skip
getFuelRemainingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : double \bullet
  ret := this.getFuelRemaining();
  getFuelRemainingRet\ .\ MainMission\ !\ ret
getHeadingMeth = \mathbf{var} \ ret : double \bullet
  getHeadingCall. MainMission \longrightarrow
  ret := this.getHeading();
  getHeadingRet . MainMission! ret
  Skip
setAirSpeedMeth \stackrel{\frown}{=}
  'setAirSpeedCall . MainMission? airSpeed—
  this.setAirSpeed(airSpeed);
  setAirSpeedRet . MainMission
 Skip
setAltitudeMeth \triangleq
  \ 'set Altitude Call . Main Mission? altitude-
  this.setAltitude(altitude);
  setAltitudeRet . MainMission-
  Skip
setCabinPressureMeth \stackrel{\frown}{=}
  set Cabin Pressure Call. Main Mission? cabin Pressure-
  this.setCabinPressure(cabinPressure);
  set Cabin Pressure Ret . Main Mission-
  Skip
setEmergencyOxygenMeth \stackrel{\frown}{=}
  this.\ setEmergencyOxygen (emergencyOxygen);
  setEmergencyOxygenRet: MainMission {\longrightarrow}
 Skip
setFuelRemainingMeth \stackrel{\frown}{=}
  \ 'setFuelRemainingCall . MainMission? fuelRemaining-
  this . setFuelRemaining(fuelRemaining);
  setFuelRemainingRet. MainMission \longrightarrow
 Skip
setHeadingMeth \ \widehat{=}
  \ 'set Heading Call . Main Mission? heading-
  this.setHeading(heading);
  setHeadingRet. MainMission-
 Skip
```



ullet (Init; Methods) \triangle (end_mission_app. MainMission \longrightarrow **Skip**)

${f class}\, {\it Main Mission Class} \ \widehat{=} \ {f begin}$

```
\mathbf{state}\,\mathit{State}\,.
    ALTITUDE\_READING\_ON\_GROUND: double
    cabin Pressure: double\\
    emergency Oxygen: double
   fuel Remaining: double
    altitude:double\\
    air Speed: double\\
    heading:double
\mathbf{state}\,\mathit{State}
   initial Init
    State'
    ALTITUDE\_READING\_ON\_GROUND' = 0.0
public getAirSpeed \cong \mathbf{var}\ ret : double \bullet
(ret := airSpeed)
public getAltitude \stackrel{\frown}{=} \mathbf{var} \ ret : double \bullet
(ret := altitude)
public getCabinPressure \stackrel{\frown}{=} \mathbf{var} \ ret : double \bullet
(ret := cabinPressure)
public getEmergencyOxygen \cong \mathbf{var}\ ret: double \bullet
(ret := emergencyOxygen)
\mathbf{public}\ \mathit{getFuelRemaining}\ \widehat{=}\ \mathbf{var}\ \mathit{ret}: \mathit{double}\ \bullet
(ret := fuelRemaining)
public getHeading = \mathbf{var} \ ret : double \bullet
(ret := heading)
public setAirSpeed =
(this.this.airSpeed := airSpeed)
public setAltitude \stackrel{\frown}{=}
(this.this.altitude := altitude)
public setCabinPressure =
(this.this.cabinPressure := cabinPressure)
public setEmergencyOxygen   =
(this.this.emergencyOxygen := emergencyOxygen)
```

```
\begin{array}{l} \textbf{public} \ setFuelRemaining} \ \widehat{=} \\ \big( \textit{this.this.fuelRemaining} := \textit{fuelRemaining} \big) \\ \\ \textbf{public} \ setHeading} \ \widehat{=} \\ \big( \textit{this.this.heading} := \textit{heading} \big) \end{array}
```

• Skip

 $\quad \mathbf{end} \quad$

$section \ Main Mission Meth Chan \ parents \ scj_prelude, \ Global Types, \ Mission Id, \ Schedulable Id$

 ${\bf channel}\ getAirSpeedCall: MissionID$

 $\textbf{channel} \ getAirSpeedRet: \textit{MissionID} \times double$

 ${\bf channel}\ getAltitudeCall: MissionID$

channel $getAltitudeRet: MissionID \times double$

 ${\bf channel}\ get Cabin Pressure Call: Mission ID$

 $\mathbf{channel} \ getCabinPressureRet: \mathit{MissionID} \times \mathit{double}$

 ${\bf channel}\ getEmergency Oxygen Call: Mission ID$

channel $getEmergencyOxygenRet: MissionID \times double$

 ${\bf channel}\ getFuelRemainingCall: MissionID$

 $\textbf{channel} \ getFuelRemainingRet: \textit{MissionID} \times \textit{double}$

 ${\bf channel}\ get Heading Call: Mission ID$

 $\textbf{channel} \ getHeadingRet: \textit{MissionID} \times \textit{double}$

 $\textbf{channel} \ setAirSpeedCall: MissionID \times double$

 ${\bf channel}\, setAirSpeedRet: MissionID$

 $\textbf{channel} \ setAltitudeCall: MissionID \times double$

 ${\bf channel}\ set Altitude Ret: Mission ID$

 $\mathbf{channel}\, setCabinPressureCall: \mathit{MissionID} \times \mathit{double}$

 ${\bf channel}\ set Cabin Pressure Ret: Mission ID$

channel $setEmergencyOxygenCall: MissionID \times double$

 $channel\ setEmergencyOxygenRet: MissionID$

 $\textbf{channel} \ setFuelRemainingCall} : \textit{MissionID} \times \textit{double}$

 ${\bf channel}\ setFuelRemainingRet: MissionID$

 $\textbf{channel} \ setHeadingCall: MissionID \times double$

 ${\bf channel}\ set Heading Ret: Mission ID$

5.2 Schedulables of

```
 \begin{array}{c} \textbf{section} \ A CMode Changer App \ \textbf{parents} \ Top Level Mission Sequencer Chan, \\ Mission Id, Mission Ids, Schedulable Id \end{array}
```

 $\mathbf{process}\ A\mathit{CModeChangerApp}\ \widehat{=}\ \mathit{controllingMission}: \mathit{MissionID}\ ullet\ \mathbf{begin}$

```
State_{-}
   modesLeft: \mathbb{Z}
   {\bf ref}\ current Mode Class: Mode Class
   {\bf ref}\ launch Mode Class: Mode Class
   {\bf ref}\ cruise Mode Class: Mode Class
   {\bf ref}\ land Mode Class: Mode Class
{f state}\ State
  Init
   State'
   modesLeft' = 3
   \mathbf{ref}\ current Mode Class' = \mathbf{new}\ Mode Class()
   \mathbf{ref}\ launchModeClass' = \mathbf{new}\ ModeClass()
   \mathbf{ref}\ cruiseModeClass' = \mathbf{new}\ ModeClass()
   \mathbf{ref}\ landModeClass' = \mathbf{new}\ ModeClass()
GetNextMission = \mathbf{var} \ ret : MissionID \bullet
  ret := this.getNextMission();
  getNextMissionRet.\ ACMode Changer \ !\ ret-
 Skip
change To Meth \stackrel{\frown}{=}
  \ 'change To Call . ACMode Changer ? new Mode-
  (this.currentMode := newMode);
  change To Ret \ . \ ACMode Changer \longrightarrow
  Skip
```

```
getNextMissionCall . ACModeChanger-
    'if (modesLeft = 3) \longrightarrow
          modesLeft := modesLeft - 1;
          ret := TakeOffMission
    if (modesLeft = 2) \longrightarrow
          modesLeft := modesLeft - 1;
         \ \ ret := CruiseMission
    if (modesLeft = 1) \longrightarrow
          modesLeft := modesLeft - 1;
          ret := Land Mission
    [] \neg (modesLeft = 1) \longrightarrow
         (ret := nullMissionId)
    fi
    fi
  getNextMissionRet . ACModeChanger! ret-
  Skip
advanceModeSyncMeth \stackrel{\frown}{=}
  advanceModeCall. ACModeChanger? thread \longrightarrow
    startSyncMeth . ACModeChangerObject . thread-
    lockAcquired. ACModeChangerObject. thread \longrightarrow
      Skip;
      \mathbf{if} \ (modesLeft=3) \longrightarrow
            modesLeft := modesLeft - 1;
            (change To(launch Mode))
      \mathbf{if} \ (\mathit{modesLeft} = 2) \longrightarrow
            modesLeft := modesLeft - 1;
            change To(cruise Mode)
       [] \neg (modesLeft = 2) \longrightarrow
          if (modesLeft = 1) \longrightarrow
            modesLeft := modesLeft - 1;
            (change To(land Mode))
      (change To(\mathbf{null}))
      fi
      \mathbf{fi}
    end Sync Meth.\ ACMode\ Changer\ Object.\ thread-
    advance Mode Ret . ACMode Changer . thread –
    Skip
Methods =
  GetNextMission
  change To Meth
                             ; Methods
  getNextMissionMeth
  advance Mode Sync Meth \\
```

 $getNextMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet$

• (Init; Methods) \triangle (end_sequencer_app. ACModeChanger \longrightarrow Skip)

 $\quad \text{end} \quad$

$\mathbf{class}\,\mathit{ACModeChangerClass} \,\, \widehat{=}\,\, \mathbf{begin}$

```
 \begin{array}{l} \circ \ \mathbf{sync} \ advanceMode \ \widehat{=} \\ \\ \left(\begin{matrix} \vdots \\ \mathbf{if} \ (modesLeft = 3) \longrightarrow \\ & \left(\begin{matrix} modesLeft := modesLeft - 1; \\ changeTo(launchMode) \end{matrix}\right) \end{matrix} \\ \left[\begin{matrix} \neg \ (modesLeft = 3) \longrightarrow \\ & \mathbf{if} \ (modesLeft = 2) \longrightarrow \\ & \left(\begin{matrix} modesLeft := modesLeft - 1; \\ changeTo(cruiseMode) \end{matrix}\right) \end{matrix} \\ \left[\begin{matrix} \neg \ (modesLeft = 2) \longrightarrow \\ & \mathbf{if} \ (modesLeft = 2) \longrightarrow \\ & \mathbf{if} \ (modesLeft = 1) \longrightarrow \\ & \left(\begin{matrix} modesLeft := modesLeft - 1; \\ changeTo(landMode) \end{matrix}\right) \end{matrix} \\ \left[\begin{matrix} \neg \ (modesLeft = 1) \longrightarrow \\ & \left(\begin{matrix} changeTo(\mathbf{null}) \end{matrix}\right) \end{matrix} \right] \\ \mathbf{fi} \\ \mathbf{fi} \\ \mathbf{fi} \\ \mathbf{fi} \end{matrix}
```

• Skip

${\bf section}\ A CMode Changer Meth Chan\ {\bf parents}\ scj_prelude,\ Global Types,\ Mission Id,\ Schedulable Id$

 $\begin{tabular}{ll} {\bf channel} \ change To Call: Schedulable ID \times \\ {\bf channel} \ change To Ret: Schedulable ID \\ \end{tabular}$

 ${\bf channel}\ getNextMissionCall: SchedulableID$

 $\textbf{channel} \ \textit{getNextMissionRet} : Schedulable ID \times \textit{MissionID}$

 $\begin{calce} {\bf channel} \ advance Mode Call: Schedulable ID \times Thread ID \\ {\bf channel} \ advance Mode Ret: Schedulable ID \times Thread ID \\ \end{calce}$

 $\mathbf{class}\; Control Handler Class\; \widehat{=}\; \mathbf{begin}$

• Skip

 ${\bf section}\ \ Control Handler Meth Chan\ \ {\bf parents}\ \ scj_prelude,\ Global Types,\ Mission Id,\ Schedulable Id$

 $\mathbf{class}\ Communications Handler Class\ \widehat{=}\ \mathbf{begin}$

• Skip



 $\mathbf{class}\,\textit{EnvironmentMonitorClass} \,\, \widehat{=}\,\, \mathbf{begin}$

• Skip

 $\mathbf{class}\,\mathit{FlightSensorsMonitorClass}\,\,\widehat{=}\,\,\mathbf{begin}$

• Skip

 ${\bf class}\, Aperiodic Simulator Class \ \widehat{=}\ {\bf begin}$

• Skip

5.3 TakeOffMission

```
{\bf section}\ \ Take Off Mission App\ \ {\bf parents}\ \ scj\_prelude, Mission Id, Mission Ids,
           Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Take Off Mission Class
                                                                                                                                                                                                                                                                   , Take Off Mission Meth Collins Coll
process\ TakeOffMissionApp \cong storageParametersSchedulable: MissionID, landingGearHandler: MissionID, takeOffMorger
      State_{\perp}
        this: {f ref}\ Take Off Mission Class
{f state}\ State
      Init
        State'
        this' = \mathbf{new} \; TakeOffMissionClass()
InitializePhase \stackrel{\frown}{=}
     'initializeCall . TakeOffMission \longrightarrow
      register! LandingGearHandlerTakeOff! TakeOffMission-
      register! TakeOffMonitor! TakeOffMission \longrightarrow
      register \ ! \ Take Off Failure Handler \ ! \ Take Off Mission -
      initializeRet . TakeOffMission \longrightarrow
     Skip
CleanupPhase =
     cleanup {\it MissionRet} : Take {\it OffMission!} {\bf True} -
abortMeth \stackrel{\frown}{=}
     this.\ abort();\\ abortRet.\ Take Off Mission
     Skip
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
     getControllingMissionCall. TakeOffMission \longrightarrow
     ret := this.getControllingMission();
      getControllingMissionRet \ . \ TakeOffMission \ ! \ ret
setControllingMissionMeth \triangleq
     this.\ set Controlling Mission (controlling Mission);
      setControllingMissionRet . TakeOffMission \longrightarrow
     Skip
clean UpMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
     \ 'clean Up Call . Take Off Mission-
      ret := this \cdot clean Up();
      clean \textit{UpRet} . \textit{TakeOffMission} ! \textit{ret} \cdot
     Skip
```

```
stowLandingGearMeth \stackrel{\frown}{=}
  stowLandingGearCall. TakeOffMission-
  this.stowLandingGear();
  stowLandingGearRet . TakeOffMission
  Skip
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  \ 'is Landing Gear Deployed Call . Take Off Mission -
  ret := this.isLandingGearDeployed();
  is Landing Gear Deployed Ret \;.\; Take O\!f\!f\!Mission \;!\; ret
deployLandingGearSyncMeth \stackrel{\frown}{=}
  startSyncMeth. TakeOffMissionObject. thread-
    lockAcquired. TakeOffMissionObject. thread \longrightarrow
    (this.landingGearDeployed := true);
    \stackrel{\cdot}{end} SyncMeth \;.\; Take Off Mission Object \;.\; thread \longrightarrow
    deploy Landing Gear Ret.\ Take Off Mission\ .\ thread-
    Skip
               Initialize Phase \\
               CleanupPhase
               abortMeth
               getControllingMissionMeth
Methods \stackrel{\frown}{=}
               set Controlling {\it Mission Meth}
                                                   ; Methods
               clean\,UpMeth
               stowLandingGearMeth \\
               is Landing Gear Deployed Meth
               deploy Landing Gear Sync Meth \\
```

 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end_mission_app} \; . \; \mathit{TakeOffMission} \longrightarrow \mathbf{Skip})$

class TakeOffMissionClass =begin

```
State'
SAFE\_AIRSPEED\_THRESHOLD' = 10.0
TAKEOFF\_ALTITUDE' = 10.0
abort' = false
```

```
\begin{array}{l} \mathbf{public} \ abort \ \stackrel{\frown}{=} \\ \big(this.\ abort := true\big) \\ \\ \mathbf{public} \ getControllingMission \ \stackrel{\frown}{=} \ \mathbf{var} \ ret : MissionID \ \bullet \\ \big(ret := controllingMission\big) \\ \\ \mathbf{public} \ setControllingMission \ \stackrel{\frown}{=} \\ \big(this.\ this.\ controllingMission := controllingMission\big) \\ \\ \mathbf{public} \ cleanUp \ \stackrel{\frown}{=} \ \mathbf{var} \ ret : \mathbb{B} \ \bullet \\ \Big(\mathbf{Skip}; \\ ret := (\neg \ abort = \mathbf{True}) \Big) \\ \\ \mathbf{public} \ stowLandingGear \ \stackrel{\frown}{=} \\ \big(this.\ landingGearDeployed \ \stackrel{\frown}{=} \ \mathbf{var} \ ret : \mathbb{B} \ \bullet \\ \big(ret := landingGearDeployed \ \stackrel{\frown}{=} \ \mathbf{var} \ ret : \mathbb{B} \ \bullet \\ \big(ret := landingGearDeployed \ = \mathbf{True}\big) \\ \end{array}
```

• Skip

end

${\bf section}\ \textit{TakeOffMissionMethChan}\ {\bf parents}\ \textit{scj_prelude}, \textit{GlobalTypes}, \textit{MissionId}, \textit{SchedulableId}$

 $\begin{array}{l} \textbf{channel} \ abortCall: MissionID \\ \textbf{channel} \ abortRet: MissionID \end{array}$

 ${\bf channel}\ getControlling Mission Call: Mission ID$

 $\mathbf{channel}\ getControllingMissionRet: MissionID \times MissionID$

 $\mathbf{channel}\ setControllingMissionCall: MissionID \times MissionID$

 ${\bf channel}\ set Controlling {\it Mission Ret}\ : {\it Mission ID}$

 $\begin{array}{l} \textbf{channel} \ clean Up Call: Mission ID \\ \textbf{channel} \ clean Up Ret: Mission ID \times \mathbb{B} \end{array}$

 $\begin{array}{l} \textbf{channel} \ stowLandingGearCall: MissionID} \\ \textbf{channel} \ stowLandingGearRet: MissionID} \end{array}$

 $\begin{tabular}{l} {\bf channel} \ is Landing Gear Deployed Call: Mission ID \\ {\bf channel} \ is Landing Gear Deployed Ret: Mission ID \times \mathbb{B} \\ \end{tabular}$

 $\begin{cal}{c} {\bf channel} \ deployLandingGearCall: MissionID \times ThreadID \\ {\bf channel} \ deployLandingGearRet: MissionID \times ThreadID \\ \end{cal}$

5.4 Schedulables of

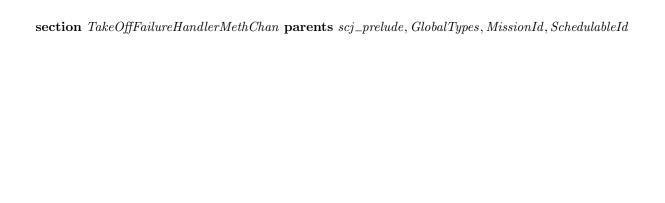
 $\mathbf{class}\,\mathit{LandingGearHandlerTakeOffClass} \; \widehat{=} \; \mathbf{begin}$

• Skip



 $\mathbf{class}\;\mathit{TakeOffFailureHandlerClass}\;\widehat{=}\;\mathbf{begin}$

• Skip



 $\textbf{class} \; \textit{TakeOffMonitorClass} \; \widehat{=} \; \textbf{begin}$

• Skip

5.5 CruiseMission

section CruiseMissionApp parents scj_prelude, MissionId, MissionIds, Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Cruise Mission Class, Cruise Mission Meth Char $\mathbf{process}$ $CruiseMissionApp \cong storageParametersSchedulable: MissionID, beginLandingHandler: MissionID, navigationMathematical formula of the process of$ $State_{-}$ $this: {f ref}\ Cruise Mission Class$ ${f state}\ State$ Init. State' $this' = \mathbf{new} \ CruiseMissionClass()$ $InitializePhase \stackrel{\frown}{=}$ 'initializeCall . $CruiseMission \longrightarrow$ $register \,!\, BeginLanding Handler \,!\, Cruise Mission {\longrightarrow}$ $register \,!\, Navigation Monitor \,!\, Cruise Mission {\longrightarrow}$ initializeRet . $CruiseMission \longrightarrow$ Skip CleanupPhase = $\begin{picture}(cleanupMissionCall\ .\ CruiseMission \longrightarrow \ cleanupMissionRet\ .\ CruiseMission\ !\ {\bf True} \longrightarrow \end{picture}$ Skip $getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet$ ret := this.getControllingMission(); $get Controlling Mission Ret.\ Cruise Mission\ !\ ret Methods \cong egin{pmatrix} InitializePhase & & & & \\ \Box & & & & \\ CleanupPhase & & & \\ \Box & & & \\ getControllingMissionMeth \end{pmatrix}$

 \mathbf{end}

 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end_mission_app} \; . \; \mathit{CruiseMission} \longrightarrow \mathbf{Skip})$

 $\mathbf{class}\ \mathit{CruiseMissionClass}\ \widehat{=}\ \mathbf{begin}$

 $\begin{array}{l} \mathbf{public} \ \ getControllingMission \ \ \widehat{=} \ \mathbf{var} \ ret : MissionID \ \bullet \\ \left(ret := controllingMission \right) \end{array}$

• Skip

 $\quad \mathbf{end} \quad$

${\bf section} \ \ Cruise Mission Meth Chan \ \ {\bf parents} \ \ scj_prelude, \ Global Types, Mission Id, Schedulable Id$

 $\begin{tabular}{l} {\bf channel} \ getControllingMissionCall: MissionID \\ {\bf channel} \ getControllingMissionRet: MissionID \times MissionID \\ \end{tabular}$

5.6 Schedulables of

 $\mathbf{class}\,\mathit{BeginLandingHandlerClass} \; \widehat{=} \; \mathbf{begin}$

• Skip



 ${\bf class}\, {\it Navigation Monitor Class} \ \widehat{=} \ {\bf begin}$

• Skip

5.7 LandMission

section LandMissionApp parents scj_prelude, MissionId, MissionIds,

```
Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Land Mission Class
                                                                                                                                                                                                                                                                             , Land Mission Meth Chan
{\bf process}\ Land {\it MissionApp}\ \widehat{=}\ storage Parameters Schedulable: {\it MissionID}, {\it groundDistanceMonitor}: {\it MissionID}, {\it landingHamiltonian} {\it MissionID}, {\it landingHamiltonian} {\it landingHamiltonian} {\it MissionID}, {\it landingHamiltonian} {\it landingHamiltonian}
       State
         this: \mathbf{ref}\ Land Mission Class
state State
       Init
         State'
         this' = \mathbf{new} \ Land Mission Class()
InitializePhase \stackrel{\frown}{=}
     'initializeCall . LandMission \longrightarrow
     register! GroundDistanceMonitor! LandMission \longrightarrow
      register \,! \, Landing Gear Handler Land \,! \, Land Mission {\longrightarrow}
      register \,!\, Instrument Landing System Monitor \,!\, Land Mission-
      register \,! \, Safe Landing Handler \,! \, Land Mission {\longrightarrow}
      initializeRet . LandMission \longrightarrow
     Skip
CleanupPhase \stackrel{\frown}{=}
     clean up {\it MissionRet} \;. \; Land {\it Mission!} \; {\bf True} -
    Skip
stowLandingGearMeth \stackrel{\frown}{=}
     's tow Landing Gear Call . Land Mission -
      this.stowLandingGear();
      stow Landing Gear Ret\ .\ Land Mission
    Skip
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
     is Landing Gear Deployed Call . Land Mission \longrightarrow
     ret := this.isLandingGearDeployed();
      is Landing Gear Deployed Ret \ . \ Land Mission \ ! \ ret
     Skip
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
     ret := this . getControllingMission();
      getControlling Mission Ret \mathrel{.} Land Mission \mathrel{!} ret
    Skip
abortMeth \stackrel{\frown}{=}
     \'abort Call . Land Mission-
      abort Ret\ .\ Land Mission-
      Skip
```

```
\begin{array}{c} clean UpMeth \; \widehat{=}\; \mathbf{var}\; ret : \mathbb{B}\; \bullet \\ \\ clean UpCall \; . \; Land Mission \longrightarrow \\ ret \; := \; this \; . \; clean Up(); \\ clean UpRet \; . \; Land Mission \, ! \; ret \longrightarrow \\ \mathbf{Skip} \\ \\ \\ deploy Landing Gear Sync Meth \; \widehat{=} \\ \\ deploy Landing Gear Call \; . \; Land Mission \, ? \; thread \longrightarrow \\ \\ \left( \; start Sync Meth \; . \; Land Mission Object \; . \; thread \longrightarrow \\ lock Acquired \; . \; Land Mission Object \; . \; thread \longrightarrow \\ \\ \left( \; this \; . \; landing Gear Deployed \; := \; true \; \right) \; ; \\ end Sync Meth \; . \; Land Mission Object \; . \; thread \longrightarrow \\ \\ deploy Landing Gear Ret \; . \; Land Mission \; . \; thread \longrightarrow \\ \\ \mathbf{Skip} \\ \\ \\ \end{array} \right)
```

```
Methods \triangleq \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ stowLandingGearMeth \\ \Box \\ isLandingGearDeployedMeth \\ \Box \\ getControllingMissionMeth \\ \Box \\ abortMeth \\ \Box \\ cleanUpMeth \\ \Box \\ deployLandingGearSyncMeth \end{pmatrix}; Methods
```

• (Init; Methods) \triangle (end_mission_app.LandMission \longrightarrow Skip)

end

$\mathbf{class}\,\mathit{LandMissionClass} \,\, \widehat{=} \,\, \mathbf{begin}$

```
{f state}\ State
    SAFE\_LANDING\_ALTITUDE: double
    abort: \mathbb{B}
    landing Gear Deployed: \mathbb{B}
\mathbf{state}\,\mathit{State}
   initial Init
    State'
    SAFE\_LANDING\_ALTITUDE' = 10.0
    abort'=\mathit{false}
public stowLandingGear \stackrel{\frown}{=}
(this.landingGearDeployed := false)
\mathbf{public} \ \mathit{isLandingGearDeployed} \ \widehat{=} \ \mathbf{var} \ \mathit{ret} : \mathbb{B} \bullet
(ret := landingGearDeployed = True)
\mathbf{public}\ \mathit{getControllingMission}\ \widehat{=}\ \mathbf{var}\ \mathit{ret}: \mathit{MissionID}\ \bullet
(ret := controllingMission)
public abort \stackrel{\frown}{=}
(this.abort := true)
public clean Up \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
```

• Skip

end

${\bf section}\ Land {\it Mission Meth Chan}\ {\bf parents}\ scj_prelude, {\it Global Types}, {\it Mission Id}, {\it Schedulable Id}$

 $\begin{array}{l} \textbf{channel} \ stowLandingGearCall: MissionID} \\ \textbf{channel} \ stowLandingGearRet: MissionID} \end{array}$

 $\begin{array}{l} \textbf{channel} \ is Landing Gear Deployed Call: Mission ID \\ \textbf{channel} \ is Landing Gear Deployed Ret: Mission ID \times \mathbb{B} \end{array}$

 ${\bf channel}\ getControlling Mission Call: Mission ID$

 $\mathbf{channel} \ getControllingMissionRet: MissionID \times MissionID$

 $\begin{array}{l} \textbf{channel} \ abort Call: Mission ID \\ \textbf{channel} \ abort Ret: Mission ID \end{array}$

 $\begin{array}{l} \textbf{channel} \ clean Up Call : \textit{MissionID} \\ \textbf{channel} \ clean Up Ret : \textit{MissionID} \times \mathbb{B} \end{array}$

 $\begin{cal}{c} {\bf channel} \ deployLandingGearCall: MissionID \times ThreadID \\ {\bf channel} \ deployLandingGearRet: MissionID \times ThreadID \\ \end{cal}$

5.8 Schedulables of

 $\mathbf{class}\,\mathit{Landing}\mathit{GearHandlerLandClass} \; \widehat{=} \; \mathbf{begin}$

• Skip



 $\mathbf{class}\,\mathit{SafeLandingHandlerClass} \; \widehat{=} \; \mathbf{begin}$

• Skip

 ${\bf section}\ Safe Landing Handler Meth Chan\ {\bf parents}\ scj_prelude, Global Types, Mission Id, Schedulable Id$

 $\mathbf{class} \ \mathit{GroundDistanceMonitorClass} \ \widehat{=} \ \mathbf{begin}$

• Skip

 $\mathbf{class} \, \mathit{InstrumentLandingSystemMonitorClass} \, \, \widehat{=} \, \mathbf{begin} \,$

• Skip