# aircraft

# Tight Rope v0.6

## 16th December 2015

# 1 ID Files

## 1.1 MissionIds

 ${\bf section}\ {\it MissionIds}\ {\bf parents}\ {\it scj\_prelude}, {\it MissionId}$ 

$$\label{lem:main_main} \begin{split} & \textit{MainMissionID}: \textit{MissionID} \\ & \textit{TakeOffMissionID}: \textit{MissionID} \\ & \textit{CruiseMissionID}: \textit{MissionID} \\ & \textit{LandMissionID}: \textit{MissionID} \end{split}$$

 $distinct \langle null Mission Id, Main Mission ID, Take Off Mission ID, Cruise Mission ID, Land Mission ID \rangle$ 

#### 1.2 SchedulablesIds

 ${f section}\ Schedulable Ids\ {f parents}\ scj\_prelude, Schedulable Id$ 

 $\begin{tabular}{ll} MainMissionSequencerID: SchedulableID\\ ACModeChangerID: SchedulableID\\ EnvironmentMonitorID: SchedulableID\\ ControlHandlerID: SchedulableID\\ FlightSensorsMonitorID: SchedulableID\\ CommunicationsHandlerID: SchedulableID\\ AperiodicSimulatorID: SchedulableID\\ \end{tabular}$ 

Landing Gear Handler Take Off ID: Schedulable ID

 $Take Off Monitor ID: Schedulable ID \\ Take Off Failure Handler ID: Schedulable ID \\ Begin Landing Handler ID: Schedulable ID \\ Navigation Monitor ID: Schedulable ID \\ Ground Distance Monitor ID: Schedulable ID \\ Landing Gear Handler Land ID: Schedulable ID \\$ 

Instrument Landing System Monitor ID: Schedulable ID

Safe Landing Handler ID: Schedulable ID

 $distinct \langle null Sequencer Id, null Schedulable Id, Main Mission Sequencer ID,$ 

ACModeChangerID, EnvironmentMonitorID,

ControlHandlerID, FlightSensorsMonitorID,

Communications Handler ID, Aperiodic Simulator ID,

 $Landing Gear Handler Take Of FID,\ Take Off Monitor ID,$ 

Take Off Failure Handler ID, Begin Landing Handler ID,

Navigation Monitor ID, Ground Distance Monitor ID,

Landing Gear Handler Land ID, Instrument Landing System Monitor ID,

 $SafeLandingHandlerID \rangle$ 

#### 1.3 ThreadIds

#### $section ThreadIds parents scj\_prelude, GlobalTypes$

 $Safe Landing Handler Thread ID: Thread ID \\ ACMode Changer Thread ID: Thread ID \\ Take Off Failure Handler Thread ID: Thread ID$ 

 $Instrument Landing System Monitor Thread ID:\ Thread ID$ 

 $Flight Sensors Monitor Thread ID: Thread ID \\ Take Off Monitor Thread ID: Thread ID \\ Aperiodic Simulator Thread ID: Thread ID \\ Landing Gear Handler Land Thread ID: Thread ID \\ Landing Gear Handler Take Off Thread ID: Thread ID \\ Landing Gear Handler Take Off Thread ID: Thread ID \\ Landing Gear Handler Take Off Thread ID: Thread ID \\ Landing Gear Handler Take Off Thread ID \\ Landing Gear Handler Thread ID \\ Landing Gear Handler$ 

 $\label{lem:control} Ground Distance Monitor Thread ID: Thread ID: Thread ID: Thread ID: Thread ID$ 

 $Communications Handler Thread ID: Thread ID\\ Begin Landing Handler Thread ID: Thread ID\\ Navigation Monitor Thread ID: Thread ID\\ Environment Monitor Thread ID: Thread ID$ 

 $distinct \langle SafeletThreadId, nullThreadId,$ 

Safe Landing Handler Thread ID, ACMode Changer Thread ID,

Take Off Failure Handler Thread ID, Instrument Landing System Monitor Thread ID,

FlightSensorsMonitorThreadID, TakeOffMonitorThreadID,

Aperiodic Simulator Thread ID, Landing Gear Handler Land Thread ID,

 $Landing Gear Handler Take Off Thread ID, \ Ground Distance Monitor Thread ID,$ 

ControlHandlerThreadID, CommunicationsHandlerThreadID,

BeginLandingHandlerThreadID, NavigationMonitorThreadID,

EnvironmentMonitorThreadID

### 1.4 ObjectIds

#### **section** ObjectIds **parents** scj\_prelude, GlobalTypes

ACSafeletObjectID: ObjectID
MainMissionObjectID: ObjectID
ACModeChangerObjectID: ObjectID
EnvironmentMonitorObjectID: ObjectID
ControlHandlerObjectID: ObjectID
FlightSensorsMonitorObjectID: ObjectID
CommunicationsHandlerObjectID: ObjectID
AperiodicSimulatorObjectID: ObjectID
TakeOffMissionObjectID: ObjectID

Landing Gear Handler Take Off Object ID: Object ID

TakeOffMonitorObjectID : ObjectID
TakeOffFailureHandlerObjectID : ObjectID
CruiseMissionObjectID : ObjectID
BeginLandingHandlerObjectID : ObjectID

 $Navigation Monitor Object ID:\ Object ID$ 

 $Land Mission Object ID:\ Object ID$ 

 $\label{lem:condition} Ground Distance Monitor Object ID: Object ID \\ Landing Gear Handler Land Object ID: Object ID \\$ 

In strument Landing System Monitor Object ID: Object ID

Safe Landing Handler Object ID: Object ID

 $\label{eq:control} distinct \langle ACSafelet Object ID, Main Mission Object ID, \\ ACMode Changer Object ID, Environment Monitor Object ID, \\ Control Handler Object ID, Flight Sensors Monitor Object ID, \\ Communications Handler Object ID, Aperiodic Simulator Object ID, \\ Take Off Mission Object ID, Landing Gear Handler Take Off Object ID, \\ Take Off Monitor Object ID, Take Off Failure Handler Object ID, \\ Cruise Mission Object ID, Begin Landing Handler Object ID, \\ Navigation Monitor Object ID, Land Mission Object ID, \\ Ground Distance Monitor Object ID, Landing Gear Handler Land Object ID, \\ Instrument Landing System Monitor Object ID, Safe Landing Handler Object ID) \\$ 

## 2 Network

```
section NetworkChannels parents scj_prelude, MissionId, MissionIds,
    Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Chan, Top Level Mission Sequencer FWChan,
    Framework Chan, Safelet Chan
channelset TerminateSync ==
    \{ schedulables\_terminated, schedulables\_stopped, get\_activeSchedulables \} 
channelset ControlTierSync ==
    \{ | start\_toplevel\_sequencer, done\_toplevel\_sequencer, done\_safeletFW \} 
channelset TierSync ==
    {| start_mission . MainMission , done_mission . MainMission ,
    done\_safeletFW, done\_toplevel\_sequencer }
channelset MissionSync ==
    \{|done\_safeletFW, done\_toplevel\_sequencer, register, \}
signal Termination Call, signal Termination Ret, activate\_schedulables, done\_schedulable,
cleanupSchedulableCall, cleanupSchedulableRet
channelset SchedulablesSync ==
    \{|activate\_schedulables, done\_safeletFW, done\_toplevel\_sequencer|\}
channelset ClusterSync ==
    { done\_toplevel\_sequencer, done\_safeletFW }
channelset AppSync ==
    \bigcup \{SafeltAppSync, MissionSequencerAppSync, MissionAppSync, \\
    MTAppSync, OSEHSync, APEHSync,
    {| getSequencer, end_mission_app, end_managedThread_app,
    set Ceiling Priority, request Termination Call, request Termination Ret, termination Pending Call,
    terminationPendingRet, handleAsyncEventCall, handleAsyncEventRet \}
channelset ThreadSync ==
    \{ raise\_thread\_priority, lower\_thread\_priority, isInterruptedCall, isInterruptedRet, get\_priorityLevel \} \}
channelset LockingSync ==
    \{ lockAcquired, startSyncMeth, endSyncMeth, waitCall, waitRet, notify, isInterruptedCall, isInterruptedRet, \} \}
    interruptedCall, interruptedRet, done\_toplevel\_sequencer, get\_priorityLevel
channelset Tier0Sync ==
    \{|done\_toplevel\_sequencer, done\_safeletFW,
    start_mission . TakeOffMission, done_mission . TakeOffMission,
    initializeRet. TakeOffMission, requestTermination. TakeOffMission. MainMissionSequencer,
    start_mission. CruiseMission, done_mission. CruiseMission,
    initializeRet. CruiseMission, requestTermination. CruiseMission. MainMissionSequencer,
    start_mission . LandMission, done_mission . LandMission,
    initializeRet . LandMission, requestTermination . LandMission . MainMissionSequencer
```

```
SchedulableId, SchedulableIds, MissionChan, SchedulableMethChan, MissionFW,
       SafeletFW, TopLevelMissionSequencerFW, NetworkChannels, ManagedThreadFW,
       Schedulable {\it Mission Sequencer FW}, Periodic {\it Event Handler FW}, One {\it Shot Event Hand
       AperiodicEventHandlerFW, ObjectFW, ThreadFW,
       ACSafeletApp, MainMissionSequencerApp, MainMissionApp, ACModeChangerApp, ControlHandlerApp,
       Communications Handler App, Environment Monitor App, Flight Sensors Monitor App,
       Aperiodic Simulator App, Take Off Mission App, Landing Gear Handler Take Off App, Take Off Failure Handler App,
       TakeOffMonitorApp, CruiseMissionApp, BeginLandingHandlerApp, NavigationMonitorApp
       , LandMissionApp, LandingGearHandlerLandApp, SafeLandingHandlerApp, GroundDistanceMonitorApp,
       InstrumentLandingSystemMonitorApp
process ControlTier \stackrel{\frown}{=}
   SafeletFW
           [ControlTierSync]
   TopLevelMissionSequencerFW(MainMissionSequencer)
process Tier0 =
   MissionFW(MainMissionID)
           [MissionSync]
        Schedulable Mission Sequencer FW(ACMode Changer ID)
              [SchedulablesSync]
           AperiodicEventHandlerFW(ControlHandlerID,(time(10,0),null))
                  [SchedulablesSync]
           Aperiodic Event Handler FW (Communications Handler ID, (NULL, null Schedulable Id))
              [SchedulablesSync]
           PeriodicEventHandlerFW (EnvironmentMonitorID, (time(10,0), NULL, NULL, nullSchedulableId))
                  [SchedulablesSync]
           PeriodicEventHandlerFW (FlightSensorsMonitorID, (time(10,0), NULL, NULL, nullSchedulableId))
                  [SchedulablesSync]
           PeriodicEventHandlerFW(AperiodicSimulatorID, (time(10,0), NULL, NULL, nullSchedulableId))
process Tier1 =
   MissionFW(TakeOffMissionID)
           [MissionSync]
           Aperiodic Event Handler FW (Landing Gear Handler Take Off ID, (NULL, null Schedulable Id))
                  [SchedulablesSync]
           Aperiodic Event Handler FW (Take Off Failure Handler ID, (NULL, null Schedulable Id))
              [SchedulablesSync]
        PeriodicEventHandlerFW(TakeOffMonitorID,(time(0,0),time(500,0),NULL,nullSchedulableId))
        [ClusterSync]
   MissionFW(CruiseMissionID)
           [MissionSync]
        Aperiodic Event Handler FW (Begin Landing Handler ID, (NULL, null Schedulable Id))
              [SchedulablesSync]
        Periodic Event Handler FW (Navigation Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
        [ClusterSync]
   MissionFW(LandMissionID)
           [MissionSync]
           Aperiodic Event Handler FW(Landing Gear Handler Land ID, (NULL, null Schedulable Id))
                  [SchedulablesSync]
           AperiodicEventHandlerFW(SafeLandingHandlerID, (NULL, nullSchedulableId))
              [SchedulablesSync]
           PeriodicEventHandlerFW(GroundDistanceMonitorID, (time(0,0), time(10,0), NULL, nullSchedulableId))
                  [SchedulablesSync]
           Periodic Event Handler FW (Instrument Landing System Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
```

section Program parents scj\_prelude, MissionId, MissionIds,

```
\mathbf{process} \, \mathit{Framework} \, \, \widehat{=} \,
  ControlTier
      [\![\mathit{TierSync}]\!]
        [\![\mathit{Tier}0\mathit{Sync}]\!]
\mathbf{process} Application \cong
  ACS a felet App
  Main Mission Sequencer App
  MainMissionApp
  ACModeChangerApp(MainMissionID)
  Control Handler App
  Communications Handler App
  EnvironmentMonitorApp(MainMissionID)
  FlightSensorsMonitorApp(MainMissionID)
  AperiodicSimulatorApp(controlHandlerID)
  Take Off Mission App
  Landing Gear Handler Take Off App (\ Take Off Mission ID)
  Take Off Failure Handler App (Main Mission, Take Off Mission ID,)
  TakeOffMonitorApp(MainMission, TakeOffMissionID, , landingGearHandlerID)
  Cruise Mission App
  BeginLandingHandlerApp(MainMission)
  NavigationMonitorApp(MainMission)
  Land Mission App
  LandingGear Handler LandApp(LandMission ID)
  SafeLandingHandlerApp(MainMission,)
  GroundDistanceMonitorApp(MainMission)
 InstrumentLandingSystemMonitorApp(LandMissionID)
```

#### $MethodCallBinder \stackrel{\frown}{=}$

```
setCabinPressure\_MethodBinder
setEmergencyOxygen\_MethodBinder
setFuelRemaining\_MethodBinder
setAirSpeed\_MethodBinder
setAltitude\_MethodBinder
setHeading\_MethodBinder
release\_MethodBinder
is Landing Gear Deployed\_Method Binder
stowLandingGear\_MethodBinder
deployLandingGear\_MethodBinder
getAltitude\_MethodBinder
release\_MethodBinder
request Termination\_Method Binder
getAirSpeed\_MethodBinder
abort\_MethodBinder
request Termination\_Method Binder
request Termination\_Method Binder
getHeading\_MethodBinder
getAirSpeed\_MethodBinder
getAltitude\_MethodBinder
getAltitude\_MethodBinder
request Termination\_Method Binder
is Landing Gear Deployed\_Method Binder
stowLandingGear\_MethodBinder
deployLandingGear\_MethodBinder
getAltitude\_MethodBinder
test\_MethodBinder
test\_MethodBinder
```

```
{\bf channel}\ binder\_setCabinPressureCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_setCabinPressureRet: MissionID \times SchedulableID \times
setCabinPressureLocs == \{controllingMission\}
setCabinPressureCallers == \{EnvironmentMonitorID\}
setCabinPressure\_MethodBinder \triangleq
                       binder\_setCabinPressureCall? loc:(loc \in setCabinPressureLocs)? caller:(caller \in setCabinPressureCallers)-
                       setCabinPressureCall.loc.caller \longrightarrow
                       setCabinPressureRet . loc . caller ? ret \longrightarrow
                       binder\_setCabinPressureRet.\,loc.\,caller\,!\,ret \longrightarrow
{\bf channel}\ binder\_setEmergencyOxygenCall: MissionID \times SchedulableID
\textbf{channel} \ binder\_setEmergencyOxygenRet: MissionID \times SchedulableID \times Sched
setEmergencyOxygenLocs == \{controllingMission\}
setEmergencyOxygenCallers == \{EnvironmentMonitorID\}
setEmergencyOxygen\_MethodBinder \triangleq
                       binder\_setEmergencyOxygenCall? loc:(loc \in setEmergencyOxygenLocs)? caller:(caller \in setEmergencyOxygenCocs)?
                      setEmergencyOxygenCall\:.\:loc\:.\:caller {\longrightarrow}
                       setEmergencyOxygenRet.loc.caller?ret \longrightarrow
                       binder\_setEmergencyOxygenRet.\,loc.\,caller\,!\,ret {\longrightarrow}
                      Skip
\mathbf{channel}\ binder\_setFuelRemainingCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_setFuelRemainingRet: MissionID \times SchedulableID \times Schedula
setFuelRemainingLocs == \{controllingMission\}
setFuelRemainingCallers == \{EnvironmentMonitorID\}
setFuelRemaining\_MethodBinder \stackrel{\frown}{=}
                       binder\_setFuelRemainingCall?loc:(loc \in setFuelRemainingLocs)?caller:(caller \in setFuelRemainingCallers) \longrightarrow
                      setFuelRemainingCall.loc.caller \longrightarrow
                       setFuelRemainingRet.loc.caller?ret \longrightarrow
                       binder\_setFuelRemainingRet.loc.caller!ret \longrightarrow
                       Skip
\mathbf{channel}\ binder\_setAirSpeedCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_setAirSpeedRet: MissionID \times SchedulableID \times
setAirSpeedLocs == \{controllingMission\}
setAirSpeedCallers == \{FlightSensorsMonitorID\}
setAirSpeed\_MethodBinder \stackrel{\frown}{=}
                       binder\_setAirSpeedCall? loc:(loc \in setAirSpeedLocs)? caller:(caller \in setAirSpeedCallers)-
                       setAirSpeedCall.loc.caller \longrightarrow
                      setAirSpeedRet.\,loc\,.\,caller\,?\,ret {\longrightarrow}
                       binder\_setAirSpeedRet . loc . caller ! ret \longrightarrow
                       Skip
```

```
{\bf channel}\ binder\_setAltitudeCall: MissionID 	imes SchedulableID
{\bf channel}\ binder\_setAltitudeRet: MissionID 	imes SchedulableID 	imes
setAltitudeLocs == \{controllingMission\}
setAltitudeCallers == \{FlightSensorsMonitorID\}
setAltitude\_MethodBinder \stackrel{\frown}{=}
                binder\_setAltitudeCall?loc: (loc \in setAltitudeLocs)?caller: (caller \in setAltitudeCallers)-
                setAltitudeCall.loc.caller \longrightarrow
               setAltitudeRet\:.\:loc\:.\:caller\:?\:ret {\longrightarrow}
                binder\_setAltitudeRet . loc . caller ! ret \longrightarrow
\mathbf{channel}\ binder\_setHeadingCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_setHeadingRet: MissionID \times SchedulableID \times
setHeadingLocs == \{controllingMission\}
setHeadingCallers == \{FlightSensorsMonitorID\}
setHeading\_MethodBinder \stackrel{\frown}{=}
                binder\_setHeadingCall? loc:(loc \in setHeadingLocs)? caller:(caller \in setHeadingCallers)—
                setHeadingCall.loc.caller \longrightarrow
                setHeadingRet . loc . caller ? ret \longrightarrow
                binder\_setHeadingRet . loc . caller ! ret \longrightarrow
               Skip
\mathbf{channel}\ binder\_releaseCall: MissionID \times SchedulableID
channel binder\_releaseRet: MissionID \times SchedulableID \times
releaseLocs == \{event, landingGearHandler\}
releaseCallers == \{AperiodicSimulatorID, TakeOffMonitorID\}
release\_MethodBinder \stackrel{\frown}{=}
               binder\_releaseCall?\ loc: (loc \in releaseLocs)?\ caller: (caller \in releaseCallers)
               releaseCall.loc.caller \longrightarrow
               releaseRet.loc.caller?ret \longrightarrow
                binder\_releaseRet.\,loc\,.\,caller\,!\,ret {\longrightarrow}
                Skip
\textbf{channel} \ binder\_isLandingGearDeployedCall: MissionID \times SchedulableID
\textbf{channel} \ binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times Sc
isLandingGearDeployedLocs == \{mission, mission\}
isLandingGearDeployedCallers == \{LandingGearHandlerTakeOffID, LandingGearHandlerLandID\}
isLandingGearDeployed\_MethodBinder \stackrel{\frown}{=}
                binder\_isLandingGearDeployedCall? loc:(loc \in isLandingGearDeployedLocs)? caller:(caller \in isLandingGearDeployedLocs)?
                isLandingGearDeployedCall.loc.caller \longrightarrow
                isLandingGearDeployedRet . loc . caller ? ret \longrightarrow
                binder\_isLandingGearDeployedRet. loc. caller! ret \longrightarrow
                Skip
```

```
{\bf channel}\ binder\_stowLandingGearCall: MissionID 	imes SchedulableID
\mathbf{channel}\ binder\_stowLandingGearRet: MissionID \times SchedulableID \times
stowLandingGearLocs == \{mission, mission\}
stowLandingGearCallers == \{LandingGearHandlerTakeOffID, LandingGearHandlerLandID\}
stowLandingGear\_MethodBinder \stackrel{\frown}{=}
             binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)-
             stowLandingGearCall. loc. caller \longrightarrow
             stowLandingGearRet . loc . caller ? ret \longrightarrow
             binder\_stowLandingGearRet.loc.caller!ret \longrightarrow
\mathbf{channel}\ binder\_deployLandingGearCall: MissionID \times SchedulableID
channel binder\_deployLandingGearRet: MissionID \times SchedulableID \times
deployLandingGearLocs == \{mission, mission\}
deployLandingGearCallers == \{LandingGearHandlerTakeOffID, LandingGearHandlerLandID\}
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
             binder\_deployLandingGearCall? loc:(loc \in deployLandingGearLocs)? caller:(caller \in deployLandingGearCallers)
             deployLandingGearCall. loc. caller \longrightarrow
             deployLandingGearRet. loc. caller? ret \longrightarrow
             binder\_deployLandingGearRet. loc. caller! ret \longrightarrow
            Skip
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAltitudeRet: \mathit{MissionID} \times \mathit{SchedulableID} \times
getAltitudeLocs == \{mainMission, mainMission, mainMissi
getAltitudeCallers == \{TakeOffMonitorID, NavigationMonitorID, GroundDistanceMonitorID, SafeLandingHandlerID\}
getAltitude\_MethodBinder \stackrel{\frown}{=}
             binder\_getAltitudeCall? loc: (loc \in getAltitudeLocs)? caller: (caller \in getAltitudeCallers)
             getAltitudeCall.loc.caller \longrightarrow
             getAltitudeRet . loc . caller ? ret \longrightarrow
             binder\_getAltitudeRet. loc. caller! ret \longrightarrow
             Skip
\mathbf{channel}\ binder\_releaseCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_releaseRet: MissionID \times SchedulableID \times
releaseLocs == \{landingGearHandler\}
releaseCallers == \{ TakeOffMonitorID \}
release\_MethodBinder \stackrel{\frown}{=}
             binder\_releaseCall?loc:(loc \in releaseLocs)?caller:(caller \in releaseCallers)
             releaseCall.loc.caller \longrightarrow
             releaseRet.loc.caller?ret \longrightarrow
             binder\_releaseRet.\,loc\,.\,caller\,!\,ret {\longrightarrow}
             Skip
```

```
{\bf channel}\ binder\_requestTerminationCall: MissionID 	imes SchedulableID
\mathbf{channel}\ binder\_request TerminationRet: MissionID \times SchedulableID \times
request Termination Locs == \{takeoff Mission, takeoff Mission, controlling Mission, main Mission\}
request Termination Callers == \{ Take Off Monitor ID, Take Off Failure Handler ID, Begin Landing Handler ID, Ground Distance Termination Callers Termination Callers
request Termination\_Method Binder \triangleq
                    binder\_requestTerminationCall? loc: (loc \in requestTerminationLocs)? caller: (caller \in requestTerminationCallers)
                    request Termination Call. loc. caller \longrightarrow
                    requestTerminationRet. loc. caller? ret \longrightarrow
                    binder\_requestTerminationRet.loc.caller!ret \longrightarrow
\mathbf{channel}\ binder\_getAirSpeedCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAirSpeedRet: MissionID \times SchedulableID \times
getAirSpeedLocs == \{mainMission, mainMission\}
getAirSpeedCallers == \{ TakeOffFailureHandlerID, NavigationMonitorID \}
getAirSpeed\_MethodBinder \stackrel{\frown}{=}
                    binder\_getAirSpeedCall? loc:(loc \in getAirSpeedLocs)? caller:(caller \in getAirSpeedCallers)—
                    getAirSpeedCall . loc . caller \longrightarrow
                    getAirSpeedRet.loc.caller?ret \longrightarrow
                    binder\_getAirSpeedRet.loc.caller!ret \longrightarrow
                  Skip
\mathbf{channel}\ binder\_abortCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_abortRet: \mathit{MissionID} \times \mathit{SchedulableID} \times
abortLocs == \{takeoffMission\}
abortCallers == \{ TakeOffFailureHandlerID \}
abort\_MethodBinder \stackrel{\frown}{=}
                    binder\_abortCall?\ loc: (loc \in abortLocs)?\ caller: (caller \in abortCallers)
                    abortCall.loc.caller \longrightarrow
                    abortRet.loc.caller?ret \longrightarrow
                    binder\_abortRet.loc.caller!ret \longrightarrow
                    Skip
\mathbf{channel}\ binder\_request Termination Call: Mission ID \times Schedulable ID
\mathbf{channel}\ binder\_requestTerminationRet: MissionID \times SchedulableID \times Interval + SchedulableID \times Int
requestTerminationLocs == \{takeoffMission, controllingMission, mainMission\}
request Termination Callers == \{ Take Off Failure Handler ID, Begin Landing Handler ID, Ground Distance Monitor ID \}
requestTermination\_MethodBinder \ \widehat{=}
                    binder\_requestTerminationCall? loc: (loc \in requestTerminationLocs)? caller: (caller \in requestTerminationCallers)
                    request Termination Call.loc.caller \longrightarrow
                    request Termination Ret. loc. caller? ret \longrightarrow
                    binder\_requestTerminationRet.loc.caller!ret \longrightarrow
```

Skip

```
\mathbf{channel}\ binder\_requestTerminationCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_request TerminationRet: MissionID \times SchedulableID \times
requestTerminationLocs == \{controllingMission, mainMission\}
requestTerminationCallers == \{BeginLandingHandlerID, GroundDistanceMonitorID\}
request Termination\_Method Binder \triangleq
       binder\_requestTerminationCall? loc: (loc \in requestTerminationLocs)? caller: (caller \in requestTerminationCallers)
       request Termination Call. loc. caller \longrightarrow
       request Termination Ret. loc. caller? ret \longrightarrow
       binder\_requestTerminationRet.loc.caller!ret \longrightarrow
\mathbf{channel}\ binder\_getHeadingCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getHeadingRet: MissionID \times SchedulableID \times
getHeadingLocs == \{mainMission\}
getHeadingCallers == \{NavigationMonitorID\}
qetHeading\_MethodBinder \stackrel{\frown}{=}
       binder\_getHeadingCall?loc: (loc \in getHeadingLocs)?caller: (caller \in getHeadingCallers) -
       getHeadingCall.loc.caller \longrightarrow
       getHeadingRet.loc.caller?ret \longrightarrow
       binder\_getHeadingRet.\,loc\,.\,caller\,!\,ret \longrightarrow
      Skip
\mathbf{channel}\ binder\_getAirSpeedCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAirSpeedRet: MissionID \times SchedulableID \times
getAirSpeedLocs == \{mainMission\}
getAirSpeedCallers == \{NavigationMonitorID\}
getAirSpeed\_MethodBinder \cong
       binder\_getAirSpeedCall? loc: (loc \in getAirSpeedLocs)? caller: (caller \in getAirSpeedCallers)
       getAirSpeedCall.loc.caller \longrightarrow
       getAirSpeedRet.loc.caller?ret \longrightarrow
       binder\_getAirSpeedRet.loc.caller!ret \longrightarrow
       Skip
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAltitudeRet: \mathit{MissionID} \times SchedulableID \times
getAltitudeLocs == \{mainMission, mainMission, mainMission\}
qetAltitudeCallers == \{NavigationMonitorID, GroundDistanceMonitorID, SafeLandingHandlerID\}
getAltitude\_MethodBinder \stackrel{\frown}{=}
       binder\_getAltitudeCall? loc: (loc \in getAltitudeLocs)? caller: (caller \in getAltitudeCallers)
       getAltitudeCall.loc.caller \longrightarrow
       getAltitudeRet\:.\:loc\:.\:caller\:?\:ret {\longrightarrow}
       binder\_getAltitudeRet \:.\: loc \:.\: caller \: !\: ret \longrightarrow
       Skip
```

```
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAltitudeRet: \mathit{MissionID} \times \mathit{SchedulableID} \times
getAltitudeLocs == \{mainMission, mainMission\}
getAltitudeCallers == \{GroundDistanceMonitorID, SafeLandingHandlerID\}
getAltitude\_MethodBinder \stackrel{\frown}{=}
                       binder\_getAltitudeCall?loc: (loc \in getAltitudeLocs)?caller: (caller \in getAltitudeCallers) \longrightarrow
                       getAltitudeCall.loc.caller \longrightarrow
                       getAltitudeRet\:.\:loc\:.\:caller\:?\:ret {\longrightarrow}
                       binder\_getAltitudeRet \:.\: loc \:.\: caller \: !\: ret \longrightarrow
{\bf channel}\ binder\_requestTerminationCall: MissionID 	imes SchedulableID
\mathbf{channel}\ binder\_requestTerminationRet: MissionID \times SchedulableID \times
requestTerminationLocs == \{mainMission\}
requestTerminationCallers == \{GroundDistanceMonitorID\}
reguestTermination\_MethodBinder \triangleq
                       binder\_requestTerminationCall? loc: (loc \in requestTerminationLocs)? caller: (caller \in requestTerminationCallers)
                       request Termination Call\:.\:loc\:.\:caller {\longrightarrow}
                       request Termination Ret. loc. caller? ret \longrightarrow
                       binder\_requestTerminationRet.loc.caller!ret \longrightarrow
                      Skip
\textbf{channel} \ binder\_isLanding Gear Deployed Call: Mission ID \times Schedulable ID
\mathbf{channel}\ binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times Sch
isLandingGearDeployedLocs == \{mission\}
isLandingGearDeployedCallers == \{LandingGearHandlerLandID\}
isLandingGearDeployed\_MethodBinder \stackrel{\frown}{=}
                       binder\_isLandingGearDeployedCall? loc:(loc \in isLandingGearDeployedLocs)? caller:(caller \in isLandingGearDeployedLocs)?
                      isLandingGearDeployedCall . loc . caller \longrightarrow
                       isLandingGearDeployedRet . loc . caller ? ret \longrightarrow
                       binder\_isLandingGearDeployedRet. loc. caller! ret \longrightarrow
                      Skip
\mathbf{channel}\ binder\_stowLandingGearCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_stowLandingGearRet: \mathit{MissionID} \times SchedulableID \times Schedu
stowLandingGearLocs == \{mission\}
stowLandingGearCallers == \{LandingGearHandlerLandID\}
stowLandingGear\_MethodBinder \ \widehat{=}
                       binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)
                       stowLandingGearCall.loc.caller \longrightarrow
                       stowLandingGearRet . loc . caller ? ret \longrightarrow
                       binder\_stowLandingGearRet.loc.caller!ret \longrightarrow
                       Skip
```

```
{\bf channel}\ binder\_deployLandingGearCall: MissionID 	imes SchedulableID
\mathbf{channel}\ binder\_deployLandingGearRet: \mathit{MissionID} \times \mathit{SchedulableID} \times
deployLandingGearLocs == \{mission\}
deployLandingGearCallers == \{LandingGearHandlerLandID\}
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
        binder\_deployLandingGearCall? loc:(loc \in deployLandingGearLocs)? caller:(caller \in deployLandingGearCallers)
        deployLandingGearCall\:.\:loc\:.\:caller {\longrightarrow}
        deployLandingGearRet.\,loc\,.\,caller\,?\,ret {\longrightarrow}
        binder\_deployLandingGearRet. loc. caller! ret \longrightarrow
        Skip
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAltitudeRet: \mathit{MissionID} \times SchedulableID \times
getAltitudeLocs == \{mainMission\}
getAltitudeCallers == \{SafeLandingHandlerID\}
qetAltitude\_MethodBinder \stackrel{\frown}{=}
       binder\_getAltitudeCall?\ loc: (loc \in getAltitudeLocs)?\ caller: (caller \in getAltitudeCallers)
       getAltitudeCall.loc.caller \longrightarrow
       getAltitudeRet\:.\:loc\:.\:caller\:?\:ret {\longrightarrow}
        binder\_getAltitudeRet \:.\: loc \:.\: caller \: !\: ret \longrightarrow
        Skip
channel binder\_testCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_testRet: MissionID \times SchedulableID \times
testLocs == \{testLoc\}
testCallers == \{testCaller\}
test\_MethodBinder \stackrel{\frown}{=}
       binder\_testCall?loc:(loc \in testLocs)?caller:(caller \in testCallers)-testCallers)
       testCall.loc.caller \longrightarrow
        testRet . loc . caller ? ret \longrightarrow
        binder\_testRet.\,loc.\,caller\,!\,ret {\longrightarrow}
\mathbf{channel}\ binder\_testCall: MissionID \times SchedulableID
channel binder\_testRet: MissionID \times SchedulableID \times
testLocs == \{testLoc\}
testCallers == \{testCaller\}
test\_MethodBinder \stackrel{\frown}{=}
       binder\_testCall?loc:(loc \in testLocs)?caller:(caller \in testCallers)
        testCall . loc . caller \longrightarrow
        testRet\:.\:loc\:.\:caller\:?\:ret {\longrightarrow}
        binder\_testRet.loc.caller!ret \longrightarrow
       Skip
```

 $Application B \ \widehat{=} \ Application \ \llbracket \ MethodCallBinderSync \ \rrbracket \ MethodCallBinder$ 

```
Threads \mathrel{\widehat{=}}
 ThreadFW(SafeLandingHandlerThreadID, 5)
 ThreadFW(ACModeChangerThreadID, 5)
 ThreadFW (TakeOffFailureHandlerThreadID, 5)
 ThreadFW (InstrumentLandingSystemMonitorThreadID, 5)
 ThreadFW(FlightSensorsMonitorThreadID, 5)
 ThreadFW (Take Off Monitor Thread ID, 5)
 ThreadFW(AperiodicSimulatorThreadID, 5)
 ThreadFW(LandingGear Handler LandThread ID, 5)
 ThreadFW(LandingGear Handler Take Off Thread ID, 5)
 ThreadFW(GroundDistanceMonitorThreadID, 5)
 ThreadFW(ControlHandlerThreadID, 5)
 ThreadFW ({\it Communications Handler Thread ID}, 5)
 ThreadFW(BeginLandingHandlerThreadID, 5)
 ThreadFW(NavigationMonitorThreadID, 5)
 ThreadFW(EnvironmentMonitorThreadID, 5)
```

```
Objects =
 ObjectFW(ACSafeletObjectID)
 ObjectFW(MainMissionObjectID)
 ObjectFW(ACModeChangerObjectID)
 ObjectFW(EnvironmentMonitorObjectID)
 ObjectFW(ControlHandlerObjectID)
 ObjectFW(FlightSensorsMonitorObjectID)
 ObjectFW(CommunicationsHandlerObjectID)
 ObjectFW (AperiodicSimulatorObjectID) \\
 ObjectFW(TakeOffMissionObjectID)
 ObjectFW(LandingGearHandlerTakeOffObjectID)
 ObjectFW(TakeOffMonitorObjectID)
 ObjectFW(TakeOffFailureHandlerObjectID)
 ObjectFW(CruiseMissionObjectID)
 ObjectFW(BeginLandingHandlerObjectID)
 ObjectFW(NavigationMonitorObjectID)
 ObjectFW(LandMissionObjectID)
 ObjectFW(GroundDistanceMonitorObjectID)
 ObjectFW(LandingGearHandlerLandObjectID)
 ObjectFW (InstrumentLandingSystemMonitorObjectID)
 ObjectFW(SafeLandingHandlerObjectID)
```

 $Locking \stackrel{\frown}{=} Threads \ [\![\ ThreadSync\ ]\!]\ Objects$ 

 $\mathbf{process} \ Program \ \widehat{=} \ (Framework \ \llbracket \ AppSync \ \rrbracket \ Application B) \ \llbracket \ LockingSync \ \rrbracket \ Locking B$ 

# 3 Safelet

 ${\bf section}\ ACS a felet App\ {\bf parents}\ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan$ 

```
\begin{aligned} &\mathbf{process}\,ACSafeletApp \,\widehat{=}\, \mathbf{begin} \\ &InitializeApplication \,\widehat{=} \\ &\left( initializeApplicationCall \,\longrightarrow \right) \\ &\left( initializeApplicationRet \,\longrightarrow \right) \\ &\mathbf{Skip} \end{aligned}
&GetSequencer \,\widehat{=} \\ &\left( getSequencerCall \,\longrightarrow \\ getSequencerRet \,!\, MainMissionSequencer \,\longrightarrow \\ &\mathbf{Skip} \end{aligned}
&Methods \,\widehat{=} \\ &\left( GetSequencer \\ \square \\ &InitializeApplication \right) \,;\,\, Methods
&\bullet \, (Methods) \,\triangle \, (end\_safelet\_app \,\longrightarrow \mathbf{Skip}) \end{aligned}
```

 $\quad \mathbf{end} \quad$ 

# 4 Top Level Mission Sequencer

 $\begin{array}{c} \textbf{section} \ \textit{MainMissionSequencerApp} \ \textbf{parents} \ \textit{TopLevelMissionSequencerChan}, \\ \textit{MissionIds}, \textit{MissionIds}, \textit{SchedulableId}, \textit{MainMissionSequencerClass} \end{array}$ 

 $process MainMissionSequencerApp \stackrel{\frown}{=} begin$ 

```
State = \\ this: \mathbf{ref}\ MainMissionSequencerClass}
\mathbf{state}\ State
-Init = \\ State' = \\ this' = \mathbf{new}\ MainMissionSequencerClass()
```

```
\begin{array}{l} \textit{Methods} \; \widehat{=} \\ \big( \, \textit{GetNextMission} \, \big) \; ; \; \; \textit{Methods} \end{array}
```

ullet (Init; Methods)  $\triangle$  (end\_sequencer\_app. MainMissionSequencer  $\longrightarrow$  **Skip**)

## $\mathbf{class}\,\mathit{MainMissionSequencerClass} \; \widehat{=} \; \mathbf{begin}$

```
\begin{array}{c} \textbf{state } \textit{State} \\ \textit{returnedMission} : \mathbb{B} \end{array} \textbf{state } \textit{State} \end{array}
```

```
__ initial Init ____
State'
returnedMission' = false
```

• Skip

 $\mathbf{end}$ 

#### 5 Missions

#### 5.1 MainMission

```
section MainMissionApp parents scj_prelude, MissionId, MissionIds,
            Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Main Mission Classian Classian Classian Change and Computer Change and Computer Change Chan
            , Main Mission Meth Chan
process MainMissionApp \stackrel{\frown}{=} begin
       State_{-}
         this: {f ref}\ Main Mission\ Class
\mathbf{state}\,\mathit{State}
      Init
         State'
         this' = \mathbf{new} \ MainMissionClass()
InitializePhase \stackrel{\frown}{=}
     'initializeCall . MainMission {\longrightarrow}
      register! ACModeChanger! MainMission \longrightarrow
      register \,!\, Environment Monitor \,!\, Main Mission-
      register \,! \, Control Handler \,! \, Main Mission {\longrightarrow}
      register \ ! \ Flight Sensors Monitor \ ! \ Main Mission --
      register \ ! \ Communications Handler \ ! \ Main Mission -
      register! AperiodicSimulator! MainMission \longrightarrow
      initializeRet \;.\; MainMission {\longrightarrow}
     Skip
CleanupPhase \stackrel{\frown}{=}
     clean up {\it MissionRet} : {\it MainMission!} \ {\bf True} -
     Skip
getAirSpeedMeth \cong \mathbf{var}\ ret : \mathbb{R} \bullet
     ^{'}getAirSpeedCall . MainMission-
     ret := this.getAirSpeed();
      getAirSpeedRet \ . \ MainMission \ ! \ ret
getAltitudeMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{R} \bullet
     'getAltitudeCall . MainMission —
     ret := this.getAltitude();
      getAltitudeRet\ .\ MainMission\ !\ ret
     Skip
getCabinPressureMeth \cong \mathbf{var} \ ret : \mathbb{R} \bullet
     ret := this.getCabinPressure();
      get Cabin Pressure Ret \ . \ Main Mission \ ! \ ret
     Skip
```

```
getEmergencyOxygenMeth \cong \mathbf{var}\ ret : \mathbb{R} \bullet
  getEmergencyOxygenCall. MainMission-
  ret := this.getEmergencyOxygen();
  getEmergencyOxygenRet.\ MainMission \ !\ ret
  Skip
getFuelRemainingMeth \cong \mathbf{var}\ ret : \mathbb{R} \bullet
  ret := this.getFuelRemaining();
  getFuelRemainingRet\ .\ MainMission\ !\ ret
getHeadingMeth = \mathbf{var} \ ret : \mathbb{R} \bullet
  getHeadingCall. MainMission \longrightarrow
  ret := this.getHeading();
  getHeadingRet . MainMission! ret
  Skip
setAirSpeedMeth \stackrel{\frown}{=}
  'setAirSpeedCall . MainMission ? airSpeed \longrightarrow
  this.setAirSpeed(airSpeed);
  setAirSpeedRet . MainMission
 Skip
setAltitudeMeth \triangleq
  \ 'set Altitude Call . Main Mission? altitude-
  this.setAltitude(altitude);
  setAltitudeRet . MainMission-
  Skip
setCabinPressureMeth \stackrel{\frown}{=}
  \ 'set Cabin Pressure Call . Main Mission? cabin Pressure-
  this.setCabinPressure(cabinPressure);
  set Cabin Pressure Ret . Main Mission —
  Skip
setEmergencyOxygenMeth \stackrel{\frown}{=}
  this.\ setEmergencyOxygen (emergencyOxygen);
  setEmergencyOxygenRet: MainMission {\longrightarrow}
 Skip
setFuelRemainingMeth \stackrel{\frown}{=}
  \ 'setFuelRemainingCall . MainMission? fuelRemaining-
  this.setFuelRemaining(fuelRemaining);
  setFuelRemainingRet. MainMission \longrightarrow
 Skip
setHeadingMeth \ \widehat{=}
  \'set Heading Call . Main Mission? heading-
  this.setHeading(heading);
  setHeadingRet. MainMission-
 Skip
```



ullet (Init; Methods)  $\triangle$  (end\_mission\_app. MainMission  $\longrightarrow$  **Skip**)

```
\mathbf{state}\,\mathit{State}\,.
    ALTITUDE\_READING\_ON\_GROUND: \mathbb{R}
    test: \mathbb{Z}
    cabinPressure: \mathbb{R}
    emergencyOxygen: \mathbb{R}
    fuelRemaining: \mathbb{R}
    altitude: \mathbb{R}
    airSpeed: \mathbb{R}
    heading: \mathbb{R}
\mathbf{state}\,\mathit{State}
   initial Init
    State'
    ALTITUDE\_READING\_ON\_GROUND' = 0.0
    test' = 0
public getAirSpeed \cong \mathbf{var}\ ret : \mathbb{R} \bullet
(ret := airSpeed)
public getAltitude \cong \mathbf{var}\ ret : \mathbb{R} \bullet
(ret := altitude)
\mathbf{public} \ getCabinPressure \ \widehat{=} \ \mathbf{var} \ ret : \mathbb{R} \bullet
(ret := cabinPressure)
\mathbf{public} \ getEmergencyOxygen \ \widehat{=} \ \mathbf{var} \ ret : \mathbb{R} \bullet
(ret := emergencyOxygen)
public getFuelRemaining \cong \mathbf{var} \ ret : \mathbb{R} \bullet
(ret := fuelRemaining)
public getHeading = \mathbf{var} \ ret : \mathbb{R} \bullet
(ret := heading)
public setAirSpeed =
(this.this.airSpeed := airSpeed)
public setAltitude \stackrel{\frown}{=}
(this.this.altitude := altitude)
public setCabinPressure \stackrel{\frown}{=}
(this.this.cabinPressure := cabinPressure)
\mathbf{public}\ setEmergencyOxygen\ \widehat{=}
(this.this.emergencyOxygen := emergencyOxygen)
```

```
\begin{array}{l} \textbf{public} \ setFuelRemaining} \ \widehat{=} \\ \big( \textit{this.this.fuelRemaining} := \textit{fuelRemaining} \big) \\ \\ \textbf{public} \ setHeading} \ \widehat{=} \\ \big( \textit{this.this.heading} := \textit{heading} \big) \end{array}
```

• Skip

 $\quad \mathbf{end} \quad$ 

## 5.2 Schedulables of MainMission

end

 $\begin{array}{c} \textbf{section} \ A C Mode Changer App \ \textbf{parents} \ Top Level Mission Sequencer Chan, \\ Mission Id, Mission Ids, Schedulable Id, A C Mode Changer Class \end{array}$ 

```
 \begin{aligned} \mathbf{process} & A C Mode Changer App \; \widehat{=} \\ & controlling Mission : Mission ID \; \bullet \; \mathbf{begin} \end{aligned}   \begin{aligned} & Get Next Mission \; \widehat{=} \; \mathbf{var} \; ret : Mission ID \; \bullet \\ & \left( \begin{array}{c} get Next Mission Call \; . \; A C Mode Changer \longrightarrow \\ ret \; := \; this \; . \; get Next Mission(); \\ & get Next Mission Ret \; . \; A C Mode Changer ! \; ret \longrightarrow \\ & \mathbf{Skip} \end{aligned}   \begin{aligned} & Methods \; \widehat{=} \\ & \left( \begin{array}{c} Get Next Mission \end{array} \right) \; ; \; Methods \end{aligned}   \begin{aligned} & \bullet \; \left( \begin{array}{c} Methods \; \widehat{=} \\ Get Next Mission \end{array} \right) \; ; \; Methods \end{aligned}   \end{aligned}   \end{aligned}   \begin{aligned} & \bullet \; \left( \begin{array}{c} Methods \; \widehat{=} \\ Get Next Mission \end{array} \right) \; ; \; Methods \end{aligned}
```

## $\mathbf{class}\,\mathit{ACModeChangerClass} \,\, \widehat{=}\,\, \mathbf{begin}$

```
\_ state State \_ controlling Mission: Main Mission modes Left: \mathbb{Z}
```

 $\mathbf{state}\,\mathit{State}$ 

```
protected getNextMission = var ret : MissionID \bullet
```

• Skip

```
\mathbf{process} \ \mathit{ControlHandlerApp} \ \widehat{=} \ \mathbf{begin}
```

```
\begin{array}{l} handler A sync Event \; \widehat{=} \\ \left( \begin{array}{l} handle A sync Event Call \; . \; Control Handler \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip} \end{array} \right) \; ; \\ handle A sync Event Ret \; . \; Control Handler \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
\begin{array}{l} \mathit{Methods} \mathrel{\widehat{=}} \\ (\mathit{handlerAsyncEvent}) \; ; \; \; \mathit{Methods} \end{array}
```

 $\bullet \; (Methods) \; \triangle \; (end\_aperiodic\_app \; . \; ControlHandler \longrightarrow \mathbf{Skip})$ 

 $\mathbf{process}\ Communications Handler App\ \widehat{=}\ \mathbf{begin}$ 

```
\begin{array}{l} handlerAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; CommunicationsHandler \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip} \end{array} \right); \\ handleAsyncEventRet \; . \; CommunicationsHandler \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

 $\begin{aligned} & \textit{Methods} \; \widehat{=} \\ & \left( \textit{handlerAsyncEvent} \right) \; ; \; \; \textit{Methods} \end{aligned}$ 

 $\bullet \; (Methods) \; \triangle \; (end\_aperiodic\_app \; . \; Communications Handler \longrightarrow \mathbf{Skip})$ 

 ${\bf section} \ Environment Monitor App \ {\bf parents} \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, \\ Main Mission Meth Chan$ 

```
\begin{array}{l} \textit{mainMission}: \textit{MissionID} \bullet \mathbf{begin} \\ \\ \textit{handlerAsyncEvent} \cong \\ \begin{pmatrix} \textit{handleAsyncEventCall} & \textit{EnvironmentMonitor} \longrightarrow \\ \mathbf{Skip}; \\ \textit{setCabinPressureCall} & \textit{controllingMission} & !0 \longrightarrow \\ \textit{setEmergencyOxygenCall} & \textit{controllingMission} & !0 \longrightarrow \\ \textit{setEmergencyOxygenRet} & \textit{controllingMission} & \cdots \longrightarrow \\ \mathbf{Skip}; \\ \textit{setEmergencyOxygenRet} & \textit{controllingMission} & \cdots \longrightarrow \\ \mathbf{Skip}; \\ \textit{setFuelRemainingCall} & \textit{controllingMission} & !0 \longrightarrow \\ \textit{setFuelRemainingRet} & \textit{controllingMission} & \cdots \longrightarrow \\ \mathbf{Skip} \\ \textit{handleAsyncEventRet} & \textit{EnvironmentMonitor} \longrightarrow \\ \mathbf{Skip} \\ \end{pmatrix} \\ \textit{Methods} \cong \\ \begin{pmatrix} \textit{handlerAsyncEvent} \end{pmatrix}; & \textit{Methods} \\ \end{cases}
```

ullet (Methods)  $\triangle$  (end\_periodic\_app . EnvironmentMonitor  $\longrightarrow$  **Skip**)

 $process EnvironmentMonitorApp \stackrel{\frown}{=}$ 

 $\mathbf{end}$ 

# $\mathbf{class}\, \textit{EnvironmentMonitorClass} \,\, \widehat{=} \,\, \mathbf{begin}$

$\_\_$ state $State$ $\_\_$ $controlling Mission$	n · Main Mission		
ControllingMission			
$\mathbf{state}\mathit{State}$			
initial Init			
State'			

• Skip

 $\mathbf{end}$ 

 ${\bf section} \ \ Flight Sensors Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Schedulable Ids$ 

```
\begin{array}{c} \mathbf{process} \ FlightSensorsMonitorApp \ \widehat{=} \\ mainMission : MissionID \ \bullet \ \mathbf{begin} \end{array}
```

```
\begin{array}{l} handler A sync Event \; \widehat{=} \\ \left( \begin{array}{l} handle A sync Event Call \; . \; Flight Sensors Monitor \longrightarrow \\ \left( \begin{array}{l} \mathbf{Skip}; \\ set A ir Speed Call \; . \; controlling Mission \; ! \; 0 \longrightarrow \\ set A ir Speed Ret \; . \; controlling Mission \longrightarrow \\ \mathbf{Skip}; \\ set A ltitude Call \; . \; controlling Mission \; ! \; 0 \longrightarrow \\ set A ltitude Ret \; . \; controlling Mission \longrightarrow \\ \mathbf{Skip}; \\ set Heading Call \; . \; controlling Mission \; ! \; 0 \longrightarrow \\ set Heading Ret \; . \; controlling Mission \longrightarrow \\ \mathbf{Skip} \\ handle A sync Event Ret \; . \; Flight Sensors Monitor \longrightarrow \\ \mathbf{Skip} \\ \end{array} \right)
```

```
Methods \cong (handlerAsyncEvent); Methods
```

ullet (Methods)  $\triangle$  (end\_periodic\_app . FlightSensorsMonitor  $\longrightarrow$  **Skip**)

# $\mathbf{class}\,\mathit{FlightSensorsMonitorClass}\,\,\widehat{=}\,\,\mathbf{begin}$

$\_$ state $State$ $\_$ $controllingMis$	sion: Main Mission		
${f state} State$			
initial Init State'			

• Skip

 $\mathbf{end}$ 

```
process AperiodicSimulatorApp \triangleq aperiodicEvent : SchedulableID • begin

handlerAsyncEvent \triangleq \binom{handleAsyncEventCall . AperiodicSimulator \longrightarrow}{\binom{\mathbf{Skip};}{releaseCall . event \longrightarrow}}; \binom{\mathbf{Skip};}{\mathbf{Skip}} handleAsyncEventRet . AperiodicSimulator \longrightarrow \binom{\mathbf{Skip};}{\mathbf{Skip}}

Methods \triangleq \binom{handlerAsyncEvent}{mandlerAsyncEvent}; Methods

• \binom{Methods}{mandle} \triangle (end_periodic_app . AperiodicSimulator \longrightarrow \mathbf{Skip})
```

# $\mathbf{class}\,\mathit{AperiodicSimulatorClass} \; \widehat{=} \; \mathbf{begin}$

state State			
event: Aperiodic	cEventHandler		
$\mathbf{state}\mathit{State}$			
$\_$ initial $Init$ $\_$			
State'			

 $\bullet$  Skip

 $\mathbf{end}$ 

#### 5.3 TakeOffMission

```
section TakeOffMissionApp parents scj_prelude, MissionId, MissionIds,
     Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Take Off Mission Class
     , \, Take Off Mission Meth Chan
process TakeOffMissionApp \cong
     controlling Mission: Mission ID \bullet \mathbf{begin}
   State
    this: {f ref}\ Take Off Mission Class
\mathbf{state}\,\mathit{State}
   Init
   State'
   this' = \mathbf{new} \ TakeOffMissionClass()
InitializePhase \stackrel{\frown}{=}
  initializeCall. TakeOffMission \longrightarrow
  register! Landing Gear Handler Take Off! Take Off Mission
  register! TakeOffMonitor! TakeOffMission \longrightarrow
  register! TakeOffFailureHandler! TakeOffMission \longrightarrow
  initializeRet \;.\; TakeOffMission {\longrightarrow}
  Skip
CleanupPhase \stackrel{\frown}{=}
  cleanupMissionRet . TakeOffMission! True \longrightarrow
  Skip
abortMeth \stackrel{\frown}{=}
  abortCall. TakeOffMission-
  this. abort();
  abortRet\ .\ Take Off Mission
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
  getControllingMissionCall. TakeOffMission \longrightarrow
  ret := this.getControllingMission();
  getControllingMissionRet \ . \ TakeOffMission \ ! \ ret
  Skip
setControllingMissionMeth =
  \ 'set Controlling Mission Call . Take Off Mission? controlling Mission-
  this.setControllingMission(controllingMission);
  setControllingMissionRet \;.\; TakeOffMission {\longrightarrow}
  Skip
```

```
clean UpMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  ret := this \cdot clean Up();
  clean UpRet . Take Off Mission! ret
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  \ 's tow Landing Gear Call . Take Off Mission -
  this.stowLandingGear();
  stow Landing Gear Ret.\ Take Off Mission
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  isLandingGearDeployedCall. TakeOffMission \longrightarrow
  ret := this.isLandingGearDeployed();
  is Landing Gear Deployed Ret.\ Take Off Mission\ !\ ret
 Skip
deployLandingGearSyncMeth =
  deployLandingGearCall. TakeOffMission? thread
    startSyncMeth. TakeOffMissionObject. thread—
    lockAcquired. TakeOffMissionObject. thread \longrightarrow
     (this.landingGearDeployed := true);
    \stackrel{.}{e}ndSyncMeth. TakeOffMissionObject. thread \longrightarrow
    deploy Landing Gear Ret.\ Take Off Mission\ .\ thread
    Skip
               Initialize Phase
               CleanupPhase
               abortMeth
               getControllingMissionMeth \\
Methods =
               set Controlling Mission Meth \\
                                                   : Methods
               clean\,UpMeth
               stow Landing Gear Meth \\
               is Landing Gear Deployed Meth
               deploy Landing Gear Sync Meth \\
```

• (Init; Methods)  $\triangle$  (end\_mission\_app. TakeOffMission  $\longrightarrow$  **Skip**)

#### class TakeOffMissionClass =begin

```
state State
    SAFE\_AIRSPEED\_THRESHOLD: \mathbb{R}
    TAKEOFF\_ALTITUDE: \mathbb{R}
    controlling Mission: Main Mission\\
    abort: \mathbb{B}
    landing Gear Deployed: \mathbb{B}
{f state}\ State
   initial Init
    State'
    SAFE\_AIRSPEED\_THRESHOLD' = 10.0
    TAKEOFF\_ALTITUDE' = 10.0
    abort' = false
public abort \stackrel{\frown}{=}
(this.abort := true)
public getControllingMission = \mathbf{var} \ ret : MissionID \bullet
(ret := controllingMission)
public setControllingMission  <math>\hat{=}
(this.this.controllingMission := controllingMission)
public clean Up \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
ret := (\neg abort = \mathbf{True})
public stowLandingGear \stackrel{\frown}{=}
(this.landingGearDeployed := false)
\mathbf{public}\ \mathit{isLandingGearDeployed}\ \widehat{=}\ \mathbf{var}\ \mathit{ret}: \mathbb{B}\ \bullet
(ret := landingGearDeployed = True)
```

• Skip

#### ${\bf section}\ \textit{TakeOffMissionMethChan}\ {\bf parents}\ \textit{scj\_prelude}, \textit{GlobalTypes}, \textit{MissionId}, \textit{SchedulableId}$

 $\begin{array}{l} \textbf{channel} \ abort Call: Schedulable ID \\ \textbf{channel} \ abort Ret: Schedulable ID \end{array}$ 

 ${\bf channel}\ get Controlling {\it Mission Call}\ : Schedulable {\it ID}$ 

 $\mathbf{channel}\ getControllingMissionRet: SchedulableID \times MissionID$ 

 $\textbf{channel} \ setControllingMissionCall: SchedulableID \times MissionID$ 

 ${\bf channel}\ set Controlling {\it MissionRet}: Schedulable {\it ID}$ 

 $\begin{array}{l} \textbf{channel} \ clean Up Call : Schedulable ID \\ \textbf{channel} \ clean Up Ret : Schedulable ID \times \mathbb{B} \end{array}$ 

 $\begin{array}{l} \textbf{channel} \ stow Landing Gear Call: Schedulable ID \\ \textbf{channel} \ stow Landing Gear Ret: Schedulable ID \\ \end{array}$ 

 $\begin{array}{l} \textbf{channel} \ is Landing Gear Deployed Call: Schedulable ID} \\ \textbf{channel} \ is Landing Gear Deployed Ret: Schedulable ID} \times \mathbb{B} \end{array}$ 

 $\label{lem:channel} \textbf{channel} \ deployLandingGearCall} : SchedulableID \times ThreadID \\ \textbf{channel} \ deployLandingGearRet : SchedulableID \times ThreadID \\$ 

#### 5.4 Schedulables of TakeOffMission

 ${\bf section}\ Landing Gear Handler Take Off App\ {\bf parents}\ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Schedulable Ids, Schedulable Ids, Schedulable Ids, Take Off Mission Meth Chan, Object Ids, Thread Ids$ 

```
process Landing Gear Handler Take Off App \cong
                mission: MissionID \bullet \mathbf{begin}
handlerAsyncEvent =
      'handle A sync Event Call . Landing Gear Handler Take Off \longrightarrow
               Skip;
               is Landing Gear Deployed Call\:.\:mission {\longrightarrow}
               isLandingGearDeployedRet. mission? isLandingGearDeployed \longrightarrow
               \mathbf{var}\ landing Gear Is Deployed: \mathbb{B} \bullet landing Gear Is Deployed:= is Landing Gear Deployed
              if landingGearIsDeployed = True \longrightarrow
                                    'stowLandingGearCall. mission \longrightarrow
                                     stow Landing Gear Ret\ .\ mission-
                                    Skip
               ^{'}deploy Landing Gear Call . mission . Landing Gear Handler Take Off Thread
                                     deploy Landing Gear Ret.\ mission.\ Landing Gear Handler Take Off Thread-points and the following Ge
                                    Skip
       handle A sync Event Ret \;. \; Landing Gear Handler Take Off \longrightarrow
      Skip
Methods \stackrel{\frown}{=}
(handlerAsyncEvent); Methods
ullet (Methods) \triangle (end_aperiodic_app . LandingGearHandlerTakeOff \longrightarrow Skip)
```

# $\mathbf{class}\,\mathit{LandingGearHandlerTakeOffClass} \; \widehat{=} \; \mathbf{begin}$

state State		
$mission: Take O\!f\!f\!Mission$		
${f state}\ State$		
initial Init		
State'		

• Skip

 ${\bf section} \ \ Take Off Failure Handler App\ \ {\bf parents}\ \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, \\ Main Mission Meth Chan, \ Take Off Mission Meth Chan$ 

```
process TakeOffFailureHandlerApp \cong
     mainMission: MissionID,
take off Mission: Mission ID,
threshold:Double \bullet \mathbf{begin}
handlerAsyncEvent =
 'handle A sync Event Call . Take Off Failure Handler \longrightarrow
    getAirSpeedRet. mainMission? getAirSpeed \longrightarrow
    \mathbf{var}\ currentSpeed : \mathbb{R} \bullet \ currentSpeed := \ getAirSpeed
    if (currentSpeed < threshold) \longrightarrow
           Skip;
            abortCall. takeoffMission \longrightarrow
            abortRet . takeoffMission \longrightarrow
            request Termination Call\ .\ take of fM is sion {\longrightarrow}
            request Termination Ret.\ take off Mission\ ?\ request Termination
    (Skip)
  handle A sync Event Ret \;.\; Take Off Failure Handler {\longrightarrow}
Methods \stackrel{\frown}{=}
(handlerAsyncEvent); Methods
```

ullet (Methods)  $\triangle$  (end\_aperiodic\_app . TakeOffFailureHandler  $\longrightarrow$  **Skip**)

# $\mathbf{class}\;\mathit{TakeOffFailureHandlerClass}\;\widehat{=}\;\mathbf{begin}$

$egin{array}{c} \mathbf{state} \ State \ State \ MainMission : MainMission \ takeoffMission : TakeOffMission \ threshold : \mathbb{R} \ \end{array}$		
state State		
initial Init		

• Skip

 $\begin{array}{c} \textbf{section} \ \ TakeOffMonitorApp \ \ \textbf{parents} \ \ PeriodicEventHandlerChan, SchedulableId, SchedulableIds}, \\ MainMissionMethChan \end{array}$ 

```
process TakeOffMonitorApp \stackrel{\frown}{=}
      mainMission: MissionID,
take Off Mission: Mission ID,
takeOffAltitude: \mathbb{R},
landingGear Handler: Schedulable ID ullet \mathbf{begin}
handlerAsyncEvent \stackrel{\frown}{=}
  handle A sync Event Call . Take Off Monitor \longrightarrow
     Skip:
     getAltitudeCall\:.\:mainMission {\longrightarrow}
     getAltitudeRet \ . \ mainMission \ ? \ getAltitude \longrightarrow
     \mathbf{var}\; altitude : \mathbb{R} \bullet altitude := \; getAltitude
     if (altitude > takeOffAltitude) \longrightarrow
             Skip;
             releaseCall . landingGearHandler \longrightarrow
             releaseRet\:.\:landingGearHandler\:?\:release {\longrightarrow}
             request Termination Call. take off Mission \longrightarrow
             request Termination Ret. take off Mission? request Termination
     fi;
     Skip
   handle A sync Event Ret. Take Off Monitor \longrightarrow
Methods \stackrel{\frown}{=}
(handlerAsyncEvent); Methods
• (Methods) \triangle (end\_periodic\_app . TakeOffMonitor \longrightarrow \mathbf{Skip})
```

# $\mathbf{class} \; \mathit{TakeOffMonitorClass} \; \widehat{=} \; \mathbf{begin}$

state State	
mainMission: MainMission	
take off Mission: Take Off Mission	
$takeOffAltitude: \mathbb{R}$	
landing Gear Handler: Aperiodic Event Handler	
${f state} State$	
State'	

• Skip

#### 5.5 CruiseMission

```
section CruiseMissionApp parents scj_prelude, MissionId, MissionIds,
                 Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Cruise Mission Class
                 , {\it Cruise Mission Meth Chan}
process CruiseMissionApp \cong
                   controlling Mission: Mission ID \bullet \mathbf{begin}
          State_{-}
             this: {f ref} \ Cruise Mission Class
\mathbf{state}\,\mathit{State}
          Init.
             State'
             this' = \mathbf{new} \ CruiseMissionClass()
InitializePhase \stackrel{\frown}{=}
        'initializeCall. CruiseMission \longrightarrow
        register \,!\, BeginLandingHandler \,!\, CruiseMission {\longrightarrow}
        register! NavigationMonitor! CruiseMission\longrightarrow
         initializeRet\:.\:CruiseMission {\longrightarrow}
        Skip
CleanupPhase \stackrel{\frown}{=}
       ' cleanupMissionCall . CruiseMission\longrightarrow
        {\it cleanup Mission Ret} : Cruise {\it Mission} \: ! \: \mathbf{True} \longrightarrow
     Skip
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
        getControllingMissionCall. CruiseMission \longrightarrow
        ret := this.getControllingMission();
        getControllingMissionRet \ . \ CruiseMission \ ! \ ret \longrightarrow
Methods \cong \left( egin{array}{c} InitializePhase & & & \\ \Box & & & \\ CleanupPhase & & \\ \Box & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & \\ & & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & &
```

end

• (Init; Methods)  $\triangle$  (end\_mission\_app. CruiseMission  $\longrightarrow$  Skip)

# $\mathbf{class}\ \mathit{CruiseMissionClass}\ \widehat{=}\ \mathbf{begin}$

$\_$ state $State$ $\_$ $controllingMis$	sion: Main Mission		
${f state} State$			
initial Init State'			

 $\begin{array}{l} \mathbf{public} \ \ getControllingMission \ \ \widehat{=} \ \mathbf{var} \ ret : MissionID \ \bullet \\ \left(ret := controllingMission \right) \end{array}$ 

• Skip

#### 5.6 Schedulables of CruiseMission

end

 ${\bf section}\ Begin Landing Handler App\ {\bf parents}\ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids$ 

```
 \begin{aligned} & \textbf{process } \textit{BeginLandingHandlerApp} \; \widehat{=} \\ & \textit{controllingMission} : \textit{MissionID} \; \bullet \; \mathbf{begin} \end{aligned} \\ & \textit{handlerAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{BeginLandingHandler} \longrightarrow \\ & \left( \begin{matrix} \mathbf{Skip}; \\ \textit{requestTerminationCall} \; . \; \textit{controllingMission} \longrightarrow \\ \textit{requestTerminationRet} \; . \; \textit{controllingMission} \; ? \; \textit{requestTermination} \longrightarrow \\ & \mathbf{Skip} \\ & \textit{handleAsyncEventRet} \; . \; \textit{BeginLandingHandler} \longrightarrow \\ & \mathbf{Skip} \\ \end{aligned} \right) \\ & \textit{Methods} \; \widehat{=} \\ & (\textit{handlerAsyncEvent}) \; ; \; \textit{Methods} \\ & \bullet \; (\textit{Methods}) \; \triangle \; (\textit{end\_aperiodic\_app} \; . \; \textit{BeginLandingHandler} \longrightarrow \\ & \mathbf{Skip} \\ \end{aligned}
```

# $\mathbf{class}\,\mathit{BeginLandingHandlerClass} \; \widehat{=} \; \mathbf{begin}$

${f state}$ $State$ ${f controlling Mission}: Mission$		
${f state} State$		
initial Init State'		

 $\bullet$  Skip

 ${\bf section}\ \ Navigation Monitor App\ \ {\bf parents}\ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Sched$ 

```
\begin{array}{l} \textit{mainMission}: \textit{MissionID} \bullet \mathbf{begin} \\ \\ \textit{handlerAsyncEvent} \cong \\ \begin{pmatrix} \textit{handleAsyncEventCall} : \textit{NavigationMonitor} \longrightarrow \\ \textit{getHeadingCall} : \textit{mainMission} \longrightarrow \\ \textit{getHeadingRet} : \textit{mainMission} ? \textit{getHeading} \longrightarrow \\ \\ \mathbf{var} \; \textit{heading} : \mathbb{R} \bullet \textit{heading} := \textit{getHeading} \\ \textit{getAirSpeedCall} : \textit{mainMission} \longrightarrow \\ \textit{getAirSpeedRet} : \textit{mainMission} ? \textit{getAirSpeed} \longrightarrow \\ \\ \mathbf{var} \; \textit{airSpeed} : \mathbb{R} \bullet \textit{airSpeed} := \textit{getAirSpeed} \\ \textit{getAltitudeCall} : \textit{mainMission} \longrightarrow \\ \textit{getAltitudeRet} : \textit{mainMission} ? \textit{getAltitude} \longrightarrow \\ \\ \mathbf{var} \; \textit{altitude} : \mathbb{R} \bullet \textit{altitude} := \textit{getAltitude} \\ \\ \mathbf{Skip} \\ \textit{handleAsyncEventRet} : \textit{NavigationMonitor} \longrightarrow \\ \\ \mathbf{Skip} \\ \end{pmatrix}
```

 $\begin{array}{l} \mathit{Methods} \; \widehat{=} \\ \big( \mathit{handlerAsyncEvent} \big) \; ; \; \; \mathit{Methods} \end{array}$ 

 $\mathbf{process} \ Navigation Monitor App \ \widehat{=} \$ 

ullet (Methods)  $\triangle$  (end\_periodic\_app . NavigationMonitor  $\longrightarrow$  **Skip**)

# $\mathbf{class}\,\mathit{NavigationMonitorClass} \; \widehat{=} \; \mathbf{begin}$

$\_$ state $State$ $\_$			
main Mission: Main Miss	ion		
$\mathbf{state}\mathit{State}$			
initial Init			
State'			

• Skip

#### 5.7 LandMission

```
section LandMissionApp parents scj_prelude, MissionId, MissionIds,
     Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Land Mission Class
     , Land Mission Meth Chan\\
\mathbf{process}\,\mathit{LandMissionApp}\,\,\widehat{=}\,\,
     controlling Mission: Mission ID \bullet \mathbf{begin}
   State
    this: \mathbf{ref}\ Land Mission Class
\mathbf{state}\,\mathit{State}
   Init
   State'
   this' = \mathbf{new} \ Land Mission Class()
InitializePhase \stackrel{\frown}{=}
  initializeCall . LandMission \longrightarrow
  register! GroundDistanceMonitor! LandMission \longrightarrow
  register! LandingGearHandlerLand! LandMission \longrightarrow
  register! InstrumentLandingSystemMonitor! LandMission-
  register! SafeLandingHandler! LandMission \longrightarrow
  initializeRet . LandMission \longrightarrow
  Skip
CleanupPhase \stackrel{\frown}{=}
  clean up {\it MissionRet}\:.\: Land {\it Mission!}\: {\bf True} -
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  \ 's tow Landing Gear Call . Land Mission-
  this.\ stowLandingGear();
  stow Landing Gear Ret\ .\ Land Mission
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  is Landing Gear Deployed Call . Land Mission-
  ret := this.isLandingGearDeployed();
  is Landing Gear Deployed Ret \ . \ Land Mission \ ! \ ret
  Skip
getControllingMissionMeth \stackrel{\frown}{=} \mathbf{var} \ ret : MissionID \bullet
  ret := this.getControllingMission();
  get Controlling Mission Ret \ . \ Land Mission \ ! \ ret
  Skip
```

```
abortMeth \stackrel{\frown}{=}
  abort Call\ .\ Land Mission-
  this.abort();
  abort Ret\ .\ Land Mission
  Skip
clean UpMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  ret := this.cleanUp();
  clean Up Ret\ .\ Land Mission\ !\ ret
deployLandingGearSyncMeth \stackrel{\frown}{=}
  startSyncMeth. LandMissionObject. thread \longrightarrow
    lockAcquired\;.\; LandMissionObject\;.\; thread {\longrightarrow}
    (this.landingGearDeployed := true);
    endSyncMeth.\ LandMissionObject.\ thread {\longrightarrow}
    deploy Landing Gear Ret\ .\ Land Mission\ .\ thread-
    Skip
               Initialize Phase \\
              CleanupPhase
              stow Landing Gear Meth \\
              is Landing Gear Deployed Meth
Methods \stackrel{\frown}{=}
                                                  ; Methods
               get Controlling Mission Meth \\
              abortMeth
              clean\,UpMeth
              deployLandingGearSyncMeth
```

ullet (Init; Methods)  $\triangle$  (end\_mission\_app.LandMission  $\longrightarrow$  **Skip**)

#### $\mathbf{class}\,\mathit{LandMissionClass} \,\, \widehat{=} \,\, \mathbf{begin}$

```
\_ state State \_ controlling Mission: Main Mission SAFE\_LANDING\_ALTITUDE: \mathbb{R} abort: \mathbb{B} landing Gear Deployed: \mathbb{B}
```

 $\mathbf{state}\,\mathit{State}$ 

```
State'
SAFE\_LANDING\_ALTITUDE' = 10.0
abort' = false
```

```
public stowLandingGear \hfrac{\text{$\hfrac{a}{l}$}}{lthis.landingGearDeployed := false}
public isLandingGearDeployed \hfrac{\text{$\hfrac{a}{l}$}}{lthis variet : \hfrac{\text{$\hfrac{a}{l}$}}{lthis variet : \hfrac{\text{$\hfrac{a}{l}$}}{lthis variet : \hfrac{\text{$\hfrac{a}{l}$}}{lthis variet : \hfrac{\text{$\hfrac{a}{l}$}{lthis variet : \hfrac{a}{l}}{lthis variet : \hfrac{a}{l}}{lth
```

• Skip

#### ${\bf section}\ Land {\it Mission Meth Chan}\ {\bf parents}\ scj\_prelude, {\it Global Types}, {\it Mission Id}, {\it Schedulable Id}$

 $\begin{array}{l} \textbf{channel} \ stowLandingGearCall} : SchedulableID \\ \textbf{channel} \ stowLandingGearRet} : SchedulableID \\ \end{array}$ 

**channel** isLandingGearDeployedCall: SchedulableID **channel**  $isLandingGearDeployedRet: SchedulableID <math>\times \mathbb{B}$ 

 ${\bf channel}\ get Controlling {\it Mission Call}: Schedulable ID$ 

 $\textbf{channel} \ getControllingMissionRet: SchedulableID \times MissionID$ 

 $\begin{array}{l} \textbf{channel} \ abort Call: Schedulable ID \\ \textbf{channel} \ abort Ret: Schedulable ID \end{array}$ 

 $\begin{tabular}{ll} {\bf channel} \ clean Up Call : Schedulable ID \\ {\bf channel} \ clean Up Ret : Schedulable ID \times \mathbb{B} \\ \end{tabular}$ 

 $\begin{cal}{c} {\bf channel}\ deployLandingGearCall: SchedulableID \times ThreadID \\ {\bf channel}\ deployLandingGearRet: SchedulableID \times ThreadID \\ \end{cal}$ 

#### 5.8 Schedulables of LandMission

 ${\bf section}\ \ Landing Gear Handler Land App\ \ {\bf parents}\ \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, \\ Land Mission Meth Chan, Object Ids, Thread Ids$ 

```
process Landing Gear Handler Land App \stackrel{\frown}{=}
                 mission: MissionID \bullet \mathbf{begin}
handlerAsyncEvent =
       'handle A sync Event Call . Landing Gear Handler Land \longrightarrow
                Skip;
                is Landing Gear Deployed Call\:.\:mission {\longrightarrow}
                isLandingGearDeployedRet. mission? isLandingGearDeployed \longrightarrow
                \mathbf{var}\ landing Gear Is Deployed: \mathbb{B} \bullet landing Gear Is Deployed:= is Landing Gear Deployed
               if landingGearIsDeployed = True \longrightarrow
                                      \ 'stow Landing Gear Call . mission-
                                       stow Landing Gear Ret\ .\ mission-
                                      Skip
                \c G deploy L and in g G ear C all \c G is in Sion \c G and in g G ear H and L and L H read-
                                       deploy Landing Gear Ret.\ mission.\ Landing Gear Handler Land Thread-polynomial Control of the Control of Co
                                      Skip
        handle A sync Event Ret \ . \ Landing Gear Handler Land \longrightarrow
      Skip
Methods \stackrel{\frown}{=}
(handlerAsyncEvent); Methods
\bullet \ (Methods) \ \triangle \ (end\_aperiodic\_app \ . \ LandingGearHandlerLand \longrightarrow \mathbf{Skip})
```

# $\mathbf{class}\,\mathit{Landing}\mathit{GearHandlerLandClass} \; \widehat{=} \; \mathbf{begin}$

$\_$ state $State \_$ $mission : LandMission$		
miission . Danamission		
$\mathbf{state}\mathit{State}$		
initial Init		
State'		

• Skip

 ${\bf section} \ \ Safe Landing Handler App \ \ {\bf parents} \ \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Schedulable Ids,$ 

```
 \begin{aligned} & \textbf{process } Safe Landing Handler App \; \widehat{=} \\ & \textit{main Mission} : \textit{Mission ID}, \\ & \textit{threshold} : \textit{Double} \bullet \textbf{begin} \end{aligned}   \begin{aligned} & \textit{handler Async Event} \; \widehat{=} \\ & \begin{pmatrix} \textit{handle Async Event Call} \; . \; Safe Landing Handler \longrightarrow \\ & \textit{get Altitude Call} \; . \; \textit{main Mission} \longrightarrow \\ & \textit{get Altitude Ret} \; . \; \textit{main Mission} \; ? \; \textit{get Altitude} \longrightarrow \\ & \textbf{var} \; \textit{altitude} \; : \; \mathbb{R} \bullet \; \textit{altitude} \; : = \; \textit{get Altitude} \\ & \textbf{if} \; (\textit{altitude} \; < \; \textit{threshold}) \longrightarrow \\ & & (\textbf{Skip}) \\ & \| \neg \; (\textit{altitude} \; < \; \textit{threshold}) \longrightarrow \\ & & (\textbf{Skip}) \\ & \textbf{fi} \\ & \textit{handle Async Event Ret} \; . \; \textit{Safe Landing Handler} \longrightarrow \\ & \textbf{Skip} \end{aligned}   \begin{aligned} & \textit{Methods} \; \widehat{=} \\ & (\textit{handler Async Event}) \; ; \; \textit{Methods} \end{aligned}
```

 $\bullet \ (Methods) \ \triangle \ (end\_aperiodic\_app \ . \ SafeLandingHandler \longrightarrow \mathbf{Skip})$ 

 $\quad \mathbf{end} \quad$ 

# $\mathbf{class}\,\mathit{SafeLandingHandlerClass} \; \widehat{=} \; \mathbf{begin}$

$state State $ $mainMission : Mai$ $threshold : \mathbb{R}$	in Mission		
${f state} State$			
initial Init			

 $\bullet$  Skip

 ${\bf section} \ \ Ground Distance Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Schedulable Id$ 

```
\begin{aligned} & \textit{mainMission} : \textit{MissionID} \bullet \mathbf{begin} \\ & \textit{handlerAsyncEvent} \subseteq \\ & \textit{(handleAsyncEventCall . GroundDistanceMonitor} \longrightarrow \\ & \mathbf{Skip}; \\ & \textit{getAltitudeCall . mainMission} \longrightarrow \\ & \textit{getAltitudeRet . mainMission} ? \textit{getAltitude} \longrightarrow \\ & \mathbf{var} \; distance : \mathbb{R} \bullet distance := \textit{getAltitude} \\ & \mathbf{if} \; (distance = \textit{readingOnGround}) \longrightarrow \\ & \mathbf{Skip}; \\ & \textit{requestTerminationCall . mainMission} \nearrow \textit{requestTermination} \longrightarrow \\ & \mathbf{Skip} \\ & \mathbb{I} \neg \; (distance = \textit{readingOnGround}) \longrightarrow \mathbf{Skip} \\ & \mathbf{fi} \; ; \\ & \mathbf{Skip} \\ & \textit{handleAsyncEventRet . GroundDistanceMonitor} \longrightarrow \end{aligned}
```

 $Methods \cong (handlerAsyncEvent); Methods$ 

**process**  $GroundDistanceMonitorApp \cong$ 

ullet (Methods)  $\triangle$  (end\_periodic\_app . GroundDistanceMonitor  $\longrightarrow$  **Skip**)

### $\mathbf{class} \ \mathit{GroundDistanceMonitorClass} \ \widehat{=} \ \mathbf{begin}$

${f state}$ $State$ ${f mainMission: Main.}$ ${f readingOnGround: } \mathbb{I}$		
${f state} State$		
initial Init State '		

 $\bullet$  Skip

```
 \begin{aligned} \mathbf{process} & \textit{InstrumentLandingSystemMonitorApp} \; \widehat{=} \\ & \textit{mission} : \textit{MissionID} \bullet \mathbf{begin} \end{aligned} \\ & \textit{handlerAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{InstrumentLandingSystemMonitor} \longrightarrow \\ & \left( \mathbf{Skip} \right) \; ; \\ & \textit{handleAsyncEventRet} \; . \; \textit{InstrumentLandingSystemMonitor} \longrightarrow \\ & \mathbf{Skip} \end{aligned} \\ & \textit{Methods} \; \widehat{=} \\ & \left( \textit{handlerAsyncEvent} \right) \; ; \; \textit{Methods} \end{aligned} \\ & \bullet \; \left( \textit{Methods} \right) \triangle \left( \textit{end\_periodic\_app} \; . \; \textit{InstrumentLandingSystemMonitor} \longrightarrow \mathbf{Skip} \right) \end{aligned} \\ & \mathbf{end}
```

# $\mathbf{class} \, \mathit{InstrumentLandingSystemMonitorClass} \, \, \widehat{=} \, \mathbf{begin} \,$

$\_$ <b>state</b> $State$ $\_$ $mission: LandMission$			
$\mathbf{state}\mathit{State}$			
initial Init			
State'			

• Skip