# aircraft

# Tight Rope v0.88

# $5 th\ March\ 2017$

# 1 ID Files

# 1.1 MissionIds

 ${\bf section}\ {\it MissionIds}\ {\bf parents}\ {\it scj\_prelude}, {\it MissionId}$ 

$$\label{lem:main_model} \begin{split} & \textit{MainMissionMID}: \textit{MissionID} \\ & \textit{TakeOffMissionMID}: \textit{MissionID} \\ & \textit{CruiseMissionMID}: \textit{MissionID} \\ & \textit{LandMissionMID}: \textit{MissionID} \end{split}$$

 $distinct \langle null Mission Id, Main Mission MID, Take Off Mission MID, Cruise Mission MID, Land Mission MID \rangle$ 

### 1.2 SchedulablesIds

 ${\bf section} \ Schedulable Ids \ {\bf parents} \ scj\_prelude, Schedulable Id$ 

 $\label{lem:main} MainMissionSequencerSID: SchedulableID\\ ACModeChanger2SID: SchedulableID\\ EnvironmentMonitorSID: SchedulableID\\ ControlHandlerSID: SchedulableID\\ FlightSensorsMonitorSID: SchedulableID\\ CommunicationsHandlerSID: SchedulableID\\ LandingGearHandlerSID: SchedulableID\\ TakeOffMonitorSID: SchedulableID\\ TakeOffFailureHandlerSID: SchedulableID\\ TakeOf$ 

 $Begin Landing Handler SID: Schedulable ID\\ Navigation Monitor SID: Schedulable ID\\ Ground Distance Monitor SID: Schedulable ID\\ Landing Gear Handler Land SID: Schedulable ID$ 

In strument Landing System Monitor SID: Schedulable ID

Safe Landing Handler SID: Schedulable ID

 $distinct \langle null Sequencer Id, null Schedulable Id, Main Mission Sequencer SID,$ 

 $A {\it CMode Changer 2SID}, {\it Environment Monitor SID},$ 

Control Handler SID, Flight Sensors Monitor SID,

Communications Handler SID, Landing Gear Handler SID,

TakeOffMonitorSID, TakeOffFailureHandlerSID,

BeginLanding Handler SID, Navigation Monitor SID,

Ground Distance Monitor SID, Landing Gear Handler Land SID,

InstrumentLandingSystemMonitorSID, SafeLandingHandlerSID

1.3	Non-Paradigm	<b>Objects</b>
-----	--------------	----------------

# 1.4 ThreadIds

 ${\bf section}\ ThreadIds\ {\bf parents}\ scj\_prelude, GlobalTypes$ 

 $Safe let TId: Thread ID \\ null Thread Id: Thread ID$ 

 $\overline{distinct\langle SafeletTId, nullThreadId\rangle}$ 

# 1.5 ObjectIds

### 2 Network

#### 2.1 Network Channel Sets

```
section NetworkChannels parents scj\_prelude, MissionId, MissionIds,
       Schedulable Id, Schedulable Ids, Mission Chan, Top Level Mission Sequencer FWChan,
       Framework Chan, Safelet Chan, Aperiodic Event Handler Chan, Managed Thread Chan,
       One Shot Event Handler Chan, Periodic Event Handler Chan, Mission Sequencer Meth Chan
channelset TerminateSync ==
       \{ schedulables\_terminated, schedulables\_stopped, get\_activeSchedulables \} 
channelset ControlTierSync ==
       \{ | start\_toplevel\_sequencer, done\_toplevel\_sequencer, done\_safeletFW | \}
channelset TierSync ==
       \{| start\_mission . MainMission, done\_mission . MainMission,
       done\_safeletFW, done\_toplevel\_sequencer }
{f channel set} \ {\it Mission Sync} ==
       \{|done\_safeletFW, done\_toplevel\_sequencer, register, \}
signal Termination Call, signal Termination Ret, activate\_schedulable, done\_schedulable,
cleanupSchedulableCall, cleanupSchedulableRet
channelset SchedulablesSync ==
       \{|activate\_schedulables, done\_safeletFW, done\_toplevel\_sequencer\}\}
channelset ClusterSync ==
       \{|done\_toplevel\_sequencer, done\_safeletFW|\}
channelset SafeltAppSync \cong
\{ getSequencerCall, getSequencerRet, initializeApplicationCall, initializeApplicationRet, end\_safelet\_app \} \}
channelset MissionSequencerAppSync ==
\{|getNextMissionCall, getNextMissionRet, end\_sequencer\_app|\}
channelset MissionAppSync ==
\{|initializeCall, register, initializeRet, cleanupMissionCall, cleanupMissionRet|\}
channelset AppSync ==
       \bigcup \{SafeltAppSync, MissionSequencerAppSync, MissionAppSync, \\
       MTAppSync, OSEHSync, APEHSync, PEHSync,
       \{|getSequencer, end\_mission\_app, end\_managedThread\_app, | end\_managed
       setCeilinqPriority, requestTerminationCall, requestTerminationRet, terminationPendinqCall,
       terminationPendingRet, handleAsyncEventCall, handleAsyncEventRet \} 
channelset ThreadSunc ==
       \{ raise\_thread\_priority, lower\_thread\_priority, isInterruptedCall, isInterruptedRet, get\_priorityLevel \} \}
channelset LockingSync ==
       \{ lockAcquired, startSyncMeth, endSyncMeth, waitCall, waitRet, notify, isInterruptedCall, isInterruptedRet, \} \}
       interruptedCall, interruptedRet, done\_toplevel\_sequencer, get\_priorityLevel
channelset Tier0Sync ==
       \{|done\_toplevel\_sequencer, done\_safeletFW,
       start\_mission \ . \ Take O\!f\!f\!Mission, done\_mission \ . \ Take O\!f\!f\!Mission,
       initializeRet. TakeOffMission, requestTermination. TakeOffMission. MainMissionSequencer,
       start_mission. CruiseMission, done_mission. CruiseMission,
       initializeRet. CruiseMission, requestTermination. CruiseMission. MainMissionSequencer,
       start_mission . LandMission, done_mission . LandMission,
       initializeRet. LandMission, requestTermination. LandMission. MainMissionSequencer
```

#### 2.2 MethodCallBinder

```
section MethodCallBindingChannels parents scj_prelude, GlobalTypes, FrameworkChan, MissionId, MissionIds,
         Schedulable Id, Schedulable Ids, Thread Ids
\mathbf{channel}\ binder\_setCabinPressureCall: \mathit{MissionID} \times \mathit{SchedulableID} \times \mathbb{P}\,\mathbb{A}
\mathbf{channel}\ binder\_setCabinPressureRet: MissionID \times SchedulableID
setCabinPressureLocs == \{MainMissionMID\}
setCabinPressureCallers == \{EnvironmentMonitorSID\}
channel binder\_setFuelRemainingCall: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
\mathbf{channel}\ binder\_setFuelRemainingRet: MissionID \times SchedulableID
setFuelRemainingLocs == \{MainMissionMID\}
setFuelRemainingCallers == \{EnvironmentMonitorSID\}
\mathbf{channel}\ binder\_getAltitudeCall: MissionID \times SchedulableID
channel binder\_getAltitudeRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getAltitudeLocs == \{MainMissionMID\}
getAltitudeCallers == \{NavigationMonitorSID, TakeOffMonitorSID, GroundDistanceMonitorSID, SafeLandingHandlerS, S
\mathbf{channel}\ binder\_setHeadingCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
{\bf channel}\ binder\_setHeadingRet: MissionID \times SchedulableID
setHeadingLocs == \{MainMissionMID\}
setHeadingCallers == \{FlightSensorsMonitorSID\}
{\bf channel}\ binder\_stowLandingGearCall: MissionID 	imes SchedulableID
\mathbf{channel}\ binder\_stowLandingGearRet: MissionID \times SchedulableID
stowLandingGearLocs == \{ TakeOffMissionMID, LandMissionMID \}
stowLandingGearCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
\mathbf{channel}\ binder\_takeOffAbortCall: MissionID \times SchedulableID
{\bf channel}\ binder\_takeOffAbortRet: MissionID \times SchedulableID
takeOffAbortLocs == \{ TakeOffMissionMID \}
takeOffAbortCallers == \{ TakeOffFailureHandlerSID \}
\mathbf{channel}\ binder\_setAltitudeCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
{\bf channel}\ binder\_setAltitudeRet: MissionID \times SchedulableID
```

 $setAltitudeLocs == \{MainMissionMID\}$ 

 $setAltitudeCallers == \{FlightSensorsMonitorSID\}$ 

```
channel binder\_qetHeadingCall: MissionID \times SchedulableID
channel binder\_getHeadingRet: MissionID \times SchedulableID \times \mathbb{P} \mathbb{A}
getHeadingLocs == \{MainMissionMID\}
getHeadingCallers == \{NavigationMonitorSID\}
\mathbf{channel}\ binder\_getAirSpeedCall: MissionID \times SchedulableID
\mathbf{channel}\ binder\_getAirSpeedRet: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
getAirSpeedLocs == \{MainMissionMID\}
getAirSpeedCallers == \{NavigationMonitorSID, TakeOffFailureHandlerSID\}
channel\ binder\_deployLandingGearCall: MissionID 	imes SchedulableID
channel binder\_deployLandingGearRet: MissionID \times SchedulableID
deployLandingGearLocs == \{ TakeOffMissionMID, LandMissionMID \}
deployLandingGearCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
channel binder\_setEmergencyOxygenCall: MissionID \times SchedulableID \times \mathbb{P} \, \mathbb{A}
channel binder\_setEmergencyOxygenRet: MissionID \times SchedulableID
setEmergencyOxygenLocs == \{MainMissionMID\}
setEmergencyOxygenCallers == \{EnvironmentMonitorSID\}
\mathbf{channel}\ binder\_setAirSpeedCall: MissionID \times SchedulableID \times \mathbb{P}\ \mathbb{A}
\mathbf{channel}\ binder\_setAirSpeedRet: MissionID \times SchedulableID
setAirSpeedLocs == \{MainMissionMID\}
setAirSpeedCallers == \{FlightSensorsMonitorSID\}
{\bf channel}\ binder\_isLandingGearDeployedCall: MissionID 	imes SchedulableID
channel binder\_isLandingGearDeployedRet: MissionID \times SchedulableID \times \mathbb{B}
isLandingGearDeployedLocs == \{ TakeOffMissionMID, LandMissionMID \}
isLandingGearDeployedCallers == \{LandingGearHandlerSID, LandingGearHandlerLandSID\}
channelset MethodCallBinderSync == \{ | done\_toplevel\_sequencer, \}
binder\_setCabinPressureCall, binder\_setCabinPressureRet,
binder\_setFuelRemainingCall, binder\_setFuelRemainingRet,
binder\_getAltitudeCall, binder\_getAltitudeRet,
binder_setHeadingCall, binder_setHeadingRet,
binder\_stowLandingGearCall, binder\_stowLandingGearRet,
binder\_takeOffAbortCall, binder\_takeOffAbortRet,
binder\_setAltitudeCall, binder\_setAltitudeRet,
binder\_getHeadingCall, binder\_getHeadingRet,
binder\_getAirSpeedCall, binder\_getAirSpeedRet,
binder\_deployLandingGearCall, binder\_deployLandingGearRet,
binder\_setEmergencyOxygenCall, binder\_setEmergencyOxygenRet,
binder\_setAirSpeedCall, binder\_setAirSpeedRet,
binder\_isLandingGearDeployedCall, binder\_isLandingGearDeployedRet
```

```
process Method Call Binder \stackrel{\frown}{=} begin
setCabinPressure\_MethodBinder \ \widehat{=}
              binder\_setCabinPressureCall? loc: (loc \in setCabinPressureLocs)? caller: (caller \in setCabinPressureCallers)? p1-
             setCabinPressureCall. loc. caller! p1 \longrightarrow
              setCabinPressureRet.loc.caller \longrightarrow
              binder\_setCabinPressureRet.\,loc.\,caller \longrightarrow
              setCabinPressure\_MethodBinder
setFuelRemaining\_MethodBinder \stackrel{\frown}{=}
              binder\_setFuelRemainingCall?loc:(loc \in setFuelRemainingLocs)?caller:(caller \in setFuelRemainingCallers)?p1
             setFuelRemainingCall.loc.caller!p1 \longrightarrow
             setFuelRemainingRet.loc.caller \longrightarrow
              binder\_setFuelRemainingRet.loc.caller \longrightarrow
              setFuelRemaining\_MethodBinder
getAltitude\_MethodBinder \stackrel{\frown}{=}
              binder\_getAltitudeCall? loc: (loc \in getAltitudeLocs)? caller: (caller \in getAltitudeCallers)—
              getAltitudeCall \:.\: loc \:.\: caller {\longrightarrow}
              getAltitudeRet.loc.caller?ret \longrightarrow
              binder\_getAltitudeRet \:.\: loc \:.\: caller \: !\: ret \longrightarrow
              getAltitude\_MethodBinder
setHeading\_MethodBinder \cong
              binder\_setHeadingCall?\ loc: (loc \in setHeadingLocs)?\ caller: (caller \in setHeadingCallers)?\ p1-setHeadingCallers)
              setHeadingCall.loc.caller!p1 \longrightarrow
              setHeadingRet.loc.caller \longrightarrow
              binder\_setHeadingRet. loc. caller \longrightarrow
              setHeading\_MethodBinder
stowLandingGear\_MethodBinder \stackrel{\frown}{=}
              binder\_stowLandingGearCall? loc:(loc \in stowLandingGearLocs)? caller:(caller \in stowLandingGearCallers)
              stowLandingGearCall.loc.caller \longrightarrow
              stowLandingGearRet.loc.caller \longrightarrow
              binder\_stowLandingGearRet.loc.caller \longrightarrow
              stowLandingGear\_MethodBinder
takeOffAbort\_MethodBinder \stackrel{\frown}{=}
              binder\_takeOffAbortCall?loc: (loc \in takeOffAbortLocs)? caller: (caller \in takeOffAbortCallers)
              takeOf\!fAbortCall\:.\:loc\:.\:caller {\longrightarrow}
              takeOffAbortRet.\,loc.\,caller {\longrightarrow}
              binder\_takeOffAbortRet. loc. caller \longrightarrow
              takeOffAbort\_MethodBinder
setAltitude\_MethodBinder \triangleq
              binder\_setAltitudeCall? loc: (loc \in setAltitudeLocs)? caller: (caller \in setAltitudeCallers)? p1-setAltitudeCallers)? p1-setAltitudeCallers? p1-setAltitudeCal
              setAltitudeCall . loc . caller ! p1 \longrightarrow
              setAltitudeRet . loc . caller \longrightarrow
              binder\_setAltitudeRet. loc. caller \longrightarrow
              setAltitude\_MethodBinder
```

section MethodCallBinder parents scj\_prelude, MissionId, MissionIds, SchedulableId, SchedulableIds, MethodCallBindingChannels

, Main Mission Meth Chan, Land Mission Meth Chan

```
getHeading\_MethodBinder \ \widehat{=}
       binder\_getHeadingCall?\ loc: (loc \in getHeadingLocs)?\ caller: (caller \in getHeadingCallers)
       getHeadingCall\:.\:loc\:.\:caller {\longrightarrow}
       getHeadingRet.\,loc.\,caller\,?\,ret {\longrightarrow}
       binder\_getHeadingRet.loc.caller!ret \longrightarrow
       getHeading\_MethodBinder
getAirSpeed\_MethodBinder \stackrel{\frown}{=}
       binder\_getAirSpeedCall? loc:(loc \in getAirSpeedLocs)? caller:(caller \in getAirSpeedCallers) \longrightarrow
       getAirSpeedCall . loc . caller \longrightarrow
       getAirSpeedRet . loc . caller ? ret \longrightarrow
       binder\_getAirSpeedRet.loc.caller!ret \longrightarrow
       getAirSpeed\_MethodBinder
deployLandingGear\_MethodBinder \stackrel{\frown}{=}
       binder\_deployLandingGearCall? loc:(loc \in deployLandingGearLocs)? caller:(caller \in deployLandingGearCallers)
       deployLandingGearCall. loc. caller \longrightarrow
       deployLandingGearRet. loc. caller \longrightarrow
       binder\_deployLandingGearRet. loc. caller \longrightarrow
       deployLandingGear\_MethodBinder
setEmergencyOxygen\_MethodBinder \triangleq
       binder\_setEmergencyOxygenCall? loc:(loc \in setEmergencyOxygenLocs)? caller:(caller \in setEmergencyOxygenCocs)?
       setEmergencyOxygenCall\:.\:loc\:.\:caller\:!\:p1 {\longrightarrow}
       setEmergencyOxygenRet . loc . caller \longrightarrow
       binder\_setEmergencyOxygenRet.loc.caller \longrightarrow
       setEmergencyOxygen\_MethodBinder
setAirSpeed\_MethodBinder \stackrel{\frown}{=}
       binder\_setAirSpeedCall?loc:(loc \in setAirSpeedLocs)?caller:(caller \in setAirSpeedCallers)?p1-
       setAirSpeedCall.loc.caller!p1 \longrightarrow
       setAirSpeedRet.loc.caller \longrightarrow
       binder\_setAirSpeedRet.loc.caller \longrightarrow
       setAirSpeed\_MethodBinder
isLandingGearDeployed\_MethodBinder \cong
       binder\_isLandingGearDeployedCall? loc:(loc \in isLandingGearDeployedLocs)? caller:(caller \in isLandingGearDeployedLocs)?
       is Landing Gear Deployed Call\:.\:loc\:.\:caller {\longrightarrow}
       is Landing Gear Deployed Ret \:.\: loc \:.\: caller \:?\: ret {\longrightarrow}
       binder\_isLandingGearDeployedRet. loc. caller! ret \longrightarrow
```

 $is Landing Gear Deployed\_Method Binder$ 

### $\textit{BinderActions} \ \widehat{=} \\$

```
| setCabinPressure_MethodBinder | | | setFuelRemaining_MethodBinder | | getAltitude_MethodBinder | | setHeading_MethodBinder | | setHeading_MethodBinder | | stowLandingGear_MethodBinder | | takeOffAbort_MethodBinder | | setAltitude_MethodBinder | | getHeading_MethodBinder | | getAirSpeed_MethodBinder | | deployLandingGear_MethodBinder | | setEmergencyOxygen_MethodBinder | | setAirSpeed_MethodBinder | | setAindingGearDeployed_MethodBinder | | setAindingGearDeployed_MethodBinder | | setAindingGearDeployed_MethodBinder | setAindin
```

 $\bullet \ \mathit{BinderActions} \ \triangle \ (\mathit{done\_toplevel\_sequencer} \longrightarrow \mathbf{Skip})$ 

# 2.3 Locking

 $\begin{array}{l} \textbf{section} \ \ NetworkLocking \ \textbf{parents} \ \ scj\_prelude, \ GlobalTypes, \ FrameworkChan, \ MissionId, \ MissionIds, \ ThreadIds, \ NetworkChannels, \ ObjectFW, \ ThreadFW, \ Priority \end{array}$ 

```
\begin{array}{l} \mathbf{process} \ Threads \ \widehat{=} \\ \mathbf{(Skip)} \\ \\ \mathbf{process} \ Objects \ \widehat{=} \\ \mathbf{(Skip)} \\ \\ \mathbf{process} \ Locking \ \widehat{=} \ (Threads \ \llbracket \ ThreadSync \ \rrbracket \ Objects) \ \triangle \ (done\_toplevel\_sequencer \longrightarrow \mathbf{Skip}) \end{array}
```

### 2.4 Program

```
section Program parents scj_prelude, MissionId, MissionIds,
       Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Mission FW,
       Safe let FW, Top Level Mission Sequencer FW, Network Channels, Managed Thread FW,
       Schedulable {\it Mission Sequencer FW}, Periodic {\it Event Handler FW}, One {\it Shot Event Hand
       AperiodicEventHandlerFW, ObjectFW, ThreadFW,
       ACSafeletApp, MainMissionSequencerApp, MainMissionApp, ACModeChanger2App, ControlHandlerApp,
       Communications Handler App, Environment Monitor App, Flight Sensors Monitor App
       , Take Off Mission App, Landing Gear Handler App, Take Off Failure Handler App,
       Take Off Monitor App, Cruise Mission App, Begin Landing Handler App, Navigation Monitor App
       , LandMissionApp, LandingGearHandlerLandApp, SafeLandingHandlerApp, GroundDistanceMonitorApp,
       InstrumentLandingSystemMonitorApp
process ControlTier =
   SafeletFW
           [ControlTierSync]
   TopLevel Mission Sequencer FW (Main Mission Sequencer)
process Tier0 =
   MissionFW(MainMissionID)
           [MissionSync]
        Schedulable Mission Sequencer FW(ACMode Changer 2ID)
               [SchedulablesSync]
        Aperiodic Event Handler FW (Control Handler ID, aperiodic, (time (10, 0), null Schedulable Id))
               [SchedulablesSync]
       Aperiodic Event Handler FW (Communications Handler ID, aperiodic, (NULL, nullSchedulable Id))
               [SchedulablesSync]
        PeriodicEventHandlerFW(EnvironmentMonitorID, (time (10,0), NULL, NULL, nullSchedulableId))
               [SchedulablesSync]
         PeriodicEventHandlerFW (FlightSensorsMonitorID, (time (10,0), NULL, NULL, nullSchedulableId))
process Tier1 =
    MissionFW(TakeOffMissionID)
           [MissionSync]
        Aperiodic Event Handler FW (Landing Gear Handler ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       Aperiodic Event Handler FW (Take Off Failure Handler ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       Periodic Event Handler FW (Take Off Monitor ID, (time (0,0), time (500,0), NULL, null Schedulable Id))
        [ClusterSync]
   MissionFW(CruiseMissionID)
           [MissionSync]
        AperiodicEventHandlerFW(BeginLandingHandlerID, aperiodic, (NULL, nullSchedulableId))
               [SchedulablesSync]
        Periodic Event Handler FW (Navigation Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id)
       [ClusterSync]
   MissionFW(LandMissionID)
           [MissionSync]
        Aperiodic Event Handler FW (Landing Gear Handler Land ID, aperiodic, (NULL, null Schedulable Id))
               [SchedulablesSync]
       AperiodicEventHandlerFW(SafeLandingHandlerID, aperiodic, (NULL, nullSchedulableId))
               [SchedulablesSync]
       Periodic Event Handler FW (Ground Distance Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id))
               [SchedulablesSync]
        Periodic Event Handler FW (Instrument Landing System Monitor ID, (time (0,0), time (10,0), NULL, null Schedulable Id))
```

```
\mathbf{process}\,\mathit{Framework}\,\,\widehat{=}\,
  ControlTier
      [\![\mathit{TierSync}]\!]
        [Tier0Sync]
\mathbf{process} Application \cong
  ACS a felet App
  Main Mission Sequencer App
 MainMissionApp
  ACModeChanger2App(MainMissionID)
  Control Handler App
  Communications Handler App
  EnvironmentMonitorApp(MainMissionID)
  FlightSensorsMonitorApp(MainMissionID)
  Take Off Mission App
  Landing Gear Handler App(Take Off Mission ID)
  Take Off Failure Handler App (Take Off Mission ID, 10.0)
  Take Off Monitor App(Take Off Mission ID, 10.0, landing Gear Handler ID)
  Cruise Mission App
  BeginLandingHandlerApp
  Navigation Monitor App
  LandMissionApp
  Landing Gear Handler Land App (Land Mission ID)
  SafeLandingHandlerApp(10.0)
  GroundDistanceMonitorApp(0.0)
 Instrument Landing System Monitor App (Land Mission ID) \\
```

# 3 Safelet

 $\textbf{section} \ ACS a felet App \ \textbf{parents} \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels Schedulable Ids, Safelet Chan, Method Channels Schedulable Ids, Safelet Channels Schedulable Ids, Safelet Chann$ 

```
\mathbf{process}\,\mathit{ACSafeletApp}\,\,\widehat{=}\,\,\mathbf{begin}
```

```
Initialize Application \ \widehat{=} \ \left( egin{array}{ll} initialize Application Call \longrightarrow \\ initialize Application Ret \longrightarrow \\ \mathbf{Skip} \end{array} \right)
```

 $\bullet \; (Methods) \; \triangle \; (end\_safelet\_app \longrightarrow \mathbf{Skip})$ 

# 4 Top Level Mission Sequencer

end

 $\begin{array}{c} \textit{State} \\ \textit{this}: \mathbf{ref} \ \textit{MainMissionSequencerClass} \\ \\ \hline \textit{State} \ \textit{State'} \\ \hline \textit{this'} = \mathbf{new} \ \textit{MainMissionSequencerClass}() \\ \\ \\ \textit{GetNextMission} \cong \mathbf{var} \ \textit{ret} : \textit{MissionID} \bullet \\ \textit{(getNextMissionCall . MainMissionSequencerSID} \longrightarrow \\ \textit{ret} := \textit{this . getNextMission}(); \\ \textit{getNextMissionRet . MainMissionSequencerSID} ! \ \textit{ret} \longrightarrow \\ \mathbf{Skip} \\ \\ \\ \textit{Methods} \cong \\ \textit{(GetNextMission)}; \ \textit{Methods} \\ \\ \bullet \ \textit{(Init ; Methods)} \triangle \ \textit{(end\_sequencer\_app . MainMissionSequencerSID} \longrightarrow \mathbf{Skip}) \\ \\ \end{array}$ 

 ${\bf section} \ Main Mission Sequencer Class \ {\bf parents} \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels, Mission Id, Mission Ids$ 

 $\mathbf{class}\,\mathit{MainMissionSequencerClass} \; \widehat{=} \; \mathbf{begin}$ 

```
\begin{array}{c} \textbf{state } \textit{State} \\ \textit{returnedMission} : \mathbb{B} \end{array}
```

 $\mathbf{state}\,\mathit{State}$ 

```
 \begin{array}{c} \mathbf{protected} \ \ qetNextMission \ \widehat{=} \\ \left( \begin{array}{c} \mathbf{if} \ (\neg \ returnedMission) \longrightarrow \\ \left( \begin{array}{c} returnedMission := \mathbf{True}; \\ ret := MainMissionMID \end{array} \right) \\ \left( \begin{array}{c} \neg \ (\neg \ returnedMission) \longrightarrow \\ \left( ret := nullMissionId \right) \end{array} \right) \\ \mathbf{fi} \end{array}
```

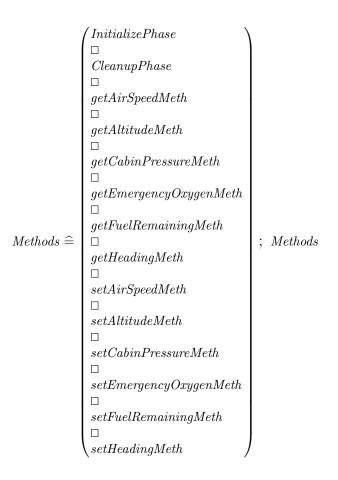
• Skip

### 5 Missions

#### 5.1 MainMission

```
section MainMissionApp parents scj_prelude, MissionId, MissionIds,
     Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Main Mission Meth Chan
, Main Mission Class, Method Call Binding Channels \\
process MainMissionApp \stackrel{\frown}{=} begin
   State .
    this: \mathbf{ref}\ Main Mission\ Class
{f state}\ State
  Init
   State'
    this' = \mathbf{new} \, MainMissionClass()
InitializePhase \stackrel{\frown}{=}
  'initializeCall . MainMissionMID \longrightarrow
  register! ACModeChanger2SID! MainMissionMID \longrightarrow
  register! EnvironmentMonitorSID! MainMissionMID \longrightarrow
  register! ControlHandlerSID! MainMissionMID \longrightarrow
  register! FlightSensorsMonitorSID! MainMissionMID-
  register \ ! \ Communications Handler SID \ ! \ Main Mission MID-
  initializeRet . MainMissionMID \longrightarrow
  Skip
CleanupPhase \stackrel{\frown}{=}
  clean up {\it MissionRet} : {\it MainMissionMID} \ ! \ {\bf True} -
  Skip
getAirSpeedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  'getAirSpeedCall . MainMissionMID ? caller-
  ret := this.getAirSpeed();
  getAirSpeedRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
getAltitudeMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  \ 'getAltitudeCall . MainMissionMID ? caller –
  ret := this.getAltitude();
  getAltitudeRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
getCabinPressureMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getCabinPressure();
  get Cabin Pressure Ret\ .\ Main Mission MID\ !\ ret
  Skip
```

```
getEmergencyOxygenMeth = \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getEmergencyOxygenCall. MainMissionMID-
  ret := this.getEmergencyOxygen();
  getEmergencyOxygenRet . MainMissionMID! ret
  Skip
getFuelRemainingMeth \cong \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  ret := this.getFuelRemaining();
  getFuelRemainingRet \ . \ MainMissionMID \ ! \ ret
getHeadingMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{P} \mathbb{A} \bullet
  getHeadingCall . MainMissionMID ? caller \longrightarrow
  ret := this.getHeading();
  getHeadingRet.\ MainMissionMID.\ caller\ !\ ret
  Skip
setAirSpeedMeth \stackrel{\frown}{=}
  \ 'setAirSpeedCall . MainMissionMID ? caller ? newAirSpeed .
  this.setAirSpeed(newAirSpeed);
  setAirSpeedRet . MainMissionMID . caller –
 Skip
setAltitudeMeth \triangleq
  \ 'set Altitude Call . Main Mission MID ? caller ? new Altitude-
  this.setAltitude(newAltitude);
  setAltitudeRet. MainMissionMID. caller \longrightarrow
  Skip
setCabinPressureMeth \ \widehat{=} \\
  \ 'set Cabin Pressure Call . Main Mission MID ? caller ? new Cabin Pressure -
  this.setCabinPressure(newCabinPressure);
  set Cabin Pressure Ret . Main Mission MID . caller –
  Skip
setEmergencyOxygenMeth \stackrel{\frown}{=}
  setEmergencyOxygenCall. MainMissionMID? caller? newEmergencyOxygen
  this.setEmergencyOxygen(newEmergencyOxygen);
  setEmergency OxygenRet\ .\ Main Mission MID\ .\ caller-
 Skip
setFuelRemainingMeth \stackrel{\frown}{=}
  this.setFuelRemaining(newFuelRemaining);
  setFuelRemainingRet. MainMissionMID. caller \longrightarrow
 Skip
setHeadingMeth \stackrel{\frown}{=}
  \'setHeadingCall . MainMissionMID ? caller ? newHeading-
  this.setHeading(newHeading);
  setHeadingRet . MainMissionMID . caller \longrightarrow
 Skip
```



 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end\_mission\_app} \; . \; \mathit{MainMissionMID} \longrightarrow \mathbf{Skip})$ 

 $\begin{array}{l} \textbf{section} \ \textit{MainMissionClass} \ \textbf{parents} \ \textit{scj\_prelude}, \textit{SchedulableId}, \textit{SchedulableIds}, \textit{SafeletChan}, \textit{MethodCallBindingChannels} \\ \end{array}$ 

```
class MainMissionClass = begin
```

```
{f state}\, State _
    cabinPressure : \mathbb{P} \mathbb{A}
    emergencyOxygen: \mathbb{P} \mathbb{A}
    fuelRemaining: \mathbb{P} \mathbb{A}
    altitude: \mathbb{P}\,\mathbb{A}
    airSpeed: \mathbb{P} \mathbb{A}
    heading: \mathbb{P}\,\mathbb{A}
\mathbf{state}\,\mathit{State}
   initial Init
    State'
public getAirSpeed \stackrel{\frown}{=}
(ret := airSpeed)
public getAltitude \stackrel{\frown}{=}
(ret := altitude)
public getCabinPressure =
(ret := cabinPressure)
public getEmergencyOxygen \stackrel{\frown}{=}
(ret := emergencyOxygen)
public getFuelRemaining =
(ret := fuelRemaining)
public getHeading =
(ret := heading)
public setAirSpeed \cong \mathbf{var} \ newAirSpeed : \mathbb{P} \mathbb{A} \bullet
(airSpeed := newAirSpeed)
public setAltitude \cong \mathbf{var} \ newAltitude : \mathbb{P} \mathbb{A} \bullet
(altitude := newAltitude)
public setCabinPressure \stackrel{\frown}{=} \mathbf{var} \ newCabinPressure : \mathbb{P} \mathbb{A} \bullet
(cabinPressure := newCabinPressure)
\mathbf{public}\ setEmergencyOxygen\ \widehat{=}\ \mathbf{var}\ newEmergencyOxygen: \mathbb{P}\,\mathbb{A}\,\bullet
(emergencyOxygen := newEmergencyOxygen)
```

```
\begin{array}{l} \mathbf{public} \ setFuelRemaining \ \widehat{=} \ \mathbf{var} \ newFuelRemaining : \mathbb{P} \ \mathbb{A} \ \bullet \\ \big( fuelRemaining := newFuelRemaining \big) \\ \\ \mathbf{public} \ setHeading \ \widehat{=} \ \mathbf{var} \ newHeading : \mathbb{P} \ \mathbb{A} \ \bullet \\ \big( heading := newHeading \big) \\ \end{array}
```

• Skip

# 5.2 Schedulables of MainMission

 $\begin{array}{l} \textbf{section} \ A C Mode Changer 2 App \ \textbf{parents} \ Top Level Mission S equencer Chan, \\ Mission Id, Mission Ids, Schedulable Id, Schedulable Ids, A C Mode Changer 2 Class, Method Call Binding Channels \\ \end{array}$ 

```
 \begin{aligned} & \textbf{process } ACModeChanger2App \; \widehat{=} \\ & controllingMission : MissionID \; \bullet \; \textbf{begin} \end{aligned}   \begin{aligned} & GetNextMission \; \widehat{=} \; \textbf{var} \; ret : MissionID \; \bullet \\ & \left( getNextMissionCall \; . \; ACModeChanger2SID \longrightarrow \right. \\ & ret := this \; . \; getNextMission(); \\ & getNextMissionRet \; . \; ACModeChanger2SID ! \; ret \longrightarrow \right. \\ & \textbf{Skip} \end{aligned}   \begin{aligned} & Methods \; \widehat{=} \\ & \left( GetNextMission \right); \; Methods \end{aligned}   \begin{aligned} & \bullet \; \left( Methods \right) \; \triangle \; \left( end\_sequencer\_app \; . \; ACModeChanger2SID \longrightarrow \textbf{Skip} \right) \end{aligned}   \end{aligned}   \end{aligned}   \begin{aligned} & \bullet \; \left( Methods \right) \; \triangle \; \left( end\_sequencer\_app \; . \; ACModeChanger2SID \longrightarrow \textbf{Skip} \right) \end{aligned}   \end{aligned}   \end{aligned}
```

 $\begin{array}{l} \textbf{section} \ A C Mode Changer 2 \ Class \ \textbf{parents} \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels, Mission Id, Mission Ids \end{array}$ 

 $\mathbf{class}\,\mathit{ACModeChanger2Class}\,\,\widehat{=}\,\,\mathbf{begin}$ 

```
egin{array}{c} \mathbf{state} \ \mathit{State} \ \mathit{modesLeft} : \mathbb{Z} \end{array}
```

 $\mathbf{state}\,\mathit{State}$ 

```
 \begin{array}{c} \textbf{initial } \textit{Init} \\ \textit{State'} \\ \hline \textit{modesLeft'} = 3 \end{array}
```

```
\begin{array}{l} \textbf{protected} \ \ getNextMission \ \widehat{=} \\ \left( \begin{array}{l} \textbf{if} \ (modesLeft = 3) \longrightarrow \\ & \left( \begin{array}{l} modesLeft := modesLeft - 1; \\ ret := TakeOffMissionMID \end{array} \right) \\ \left[ \begin{array}{l} \neg \ (modesLeft = 3) \longrightarrow \\ & \textbf{if} \ (modesLeft = 2) \longrightarrow \\ & \left( \begin{array}{l} modesLeft := modesLeft - 1; \\ ret := CruiseMissionMID \end{array} \right) \\ \left[ \begin{array}{l} \neg \ (modesLeft = 2) \longrightarrow \\ & \textbf{if} \ (modesLeft = 2) \longrightarrow \\ & \textbf{if} \ (modesLeft = 1) \longrightarrow \\ & \left( \begin{array}{l} modesLeft := modesLeft - 1; \\ ret := LandMissionMID \end{array} \right) \\ \left[ \begin{array}{l} \neg \ (modesLeft = 1) \longrightarrow \\ & (ret := nullMissionId) \end{array} \right) \\ \textbf{fi} \\ \textbf{fi} \\ \textbf{fi} \\ \textbf{fi} \end{array}
```

• Skip

# $\mathbf{process} \ \mathit{ControlHandlerApp} \ \widehat{=} \ \mathbf{begin}$

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; ControlHandlerSID \longrightarrow \\ \mathbf{Skip}; \\ handleAsyncEventRet \; . \; ControlHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
Methods = (handleAsyncEvent); Methods
```

 $\bullet \; (\mathit{Methods}) \; \triangle \; (\mathit{end\_aperiodic\_app} \; . \; \mathit{ControlHandlerSID} \longrightarrow \mathbf{Skip})$ 

# $\mathbf{process} \ \mathit{CommunicationsHandlerApp} \ \widehat{=} \ \mathbf{begin}$

```
\begin{array}{l} handleAsyncEvent \; \widehat{=} \\ \left( \begin{array}{l} handleAsyncEventCall \; . \; CommunicationsHandlerSID \longrightarrow \\ \mathbf{Skip}; \\ handleAsyncEventRet \; . \; CommunicationsHandlerSID \longrightarrow \\ \mathbf{Skip} \end{array} \right) \end{array}
```

```
Methods = (handleAsyncEvent); Methods
```

ullet (Methods)  $\triangle$  (end\_aperiodic\_app . CommunicationsHandlerSID  $\longrightarrow$  Skip)

 $\textbf{section} \ Environment Monitor App \ \textbf{parents} \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding, Main Mission Meth Chan$ 

```
\begin{aligned} & process \ Environment Monitor App \ \cong\\ & controlling Mission : Mission ID \bullet \mathbf{begin} \end{aligned} \\ & hand le A sync Event \ \cong\\ & \left( \begin{array}{l} hand le A sync Event \ \cong\\ & hand le A sync Event Call \ . \ Environment Monitor SID \longrightarrow\\ & binder\_set Cabin Pressure Call \ . \ controlling Mission \ . \ Environment Monitor SID \longrightarrow\\ & \mathbf{Skip};\\ & binder\_set Emergency O xygen Call \ . \ controlling Mission \ . \ Environment Monitor SID ! \ 0 \longrightarrow\\ & \mathbf{Skip};\\ & binder\_set Emergency O xygen Ret \ . \ controlling Mission \ . \ Environment Monitor SID ! \ 0 \longrightarrow\\ & \mathbf{Skip};\\ & binder\_set Fuel Remaining Call \ . \ controlling Mission \ . \ Environment Monitor SID ! \ 0 \longrightarrow\\ & \mathbf{Skip}\\ & \mathbf{Skip}\\ & \mathbf{Skip}\\ & \mathbf{Skip}\\ & \mathbf{Methods} \ \cong\\ & \left( hand le A sync Event Ret \ . \ Environment Monitor SID \longrightarrow\\ & \mathbf{Skip}\\ & \mathbf{Methods} \ \cong\\ & \left( hand le A sync Event \right); \ Methods \end{aligned}
```

 $\textbf{section} \ Flight Sensors Monitor App \ \textbf{parents} \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding, Main Mission Meth Chan$ 

```
process FlightSensorsMonitorApp \stackrel{\frown}{=}
               mainMission: MissionID \bullet \mathbf{begin}
         State_-
            controlling Mission: Main Mission\\
{f state}\ State
         Init
           State'
            controlling Mission' =
handleAsyncEvent =
       binder\_setAirSpeedCall\ .\ controlling Mission\ .\ FlightSensors Monitor SID\ !\ 0-lightSensors Monitor SID\ .\ 0-lightSen
               binder\_setAirSpeedRet.\ controllingMission.\ FlightSensorsMonitorSID---
               binder\_setAltitudeCall\:.\:controllingMission\:.\:FlightSensorsMonitorSID\:!\:0 \longrightarrow
               binder\_setAltitudeRet\ .\ controllingMission\ .\ FlightSensorsMonitorSID {\longrightarrow}
               binder\_setHeadingCall\ .\ controllingMission\ .\ FlightSensorsMonitorSID\ !\ 0-controllingMission\ .
               binder\_setHeadingRet.\ controllingMission.\ FlightSensorsMonitorSID-
        \dot{handle} A sync Event Ret. Flight Sensors Monitor SID \longrightarrow
       Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end\_periodic\_app} \; . \; \mathit{FlightSensorsMonitorSID} \longrightarrow \mathbf{Skip})
```

#### 5.3 TakeOffMission

```
section TakeOffMissionApp parents scj_prelude, MissionId, MissionIds,
           Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Take Off Mission Meth Chan
, \, Take Off Mission Class, \, Method Call Binding Channels \,
process TakeOffMissionApp \cong
           controlling Mission: Mission ID \bullet \mathbf{begin}
       State
         this: {f ref}\ Take Off Mission Class
\mathbf{state}\,\mathit{State}
       Init
         State'
         this' = \mathbf{new} \ TakeOffMissionClass()
InitializePhase \stackrel{\frown}{=}
      initializeCall. TakeOffMissionMID \longrightarrow
      register! LandingGearHandlerSID! TakeOffMissionMID \longrightarrow
      register \: ! \: TakeOffMonitorSID \: ! \: TakeOffMissionMID \longrightarrow
      register \ ! \ Take Off Failure Handler SID \ ! \ Take Off Mission MID - Take Off Mission
      initializeRet . TakeOffMissionMID \longrightarrow
     Skip
CleanupPhase = \mathbf{var} \, \mathbb{B} : ret \bullet
     (ret := (\neg this. abort))
      \stackrel{\textstyle \sim}{cleanup Mission Ret}. \stackrel{\textstyle \sim}{Take Off Mission MID} ! ret \longrightarrow
     Skip
takeOffAbortMeth \stackrel{\frown}{=}
     \ 'take Off Abort Call . Take Off Mission MID? caller-
      this. takeOffAbort();
      take {\it OffAbortRet}\;.\; Take {\it OffMissionMID}\;.\; caller
deployLandingGearMeth \stackrel{\frown}{=}
      deployLandingGearCall. TakeOffMissionMID? caller-
     this.\ deployLandingGear();
      deploy Landing Gear Ret.\ Take Off Mission MID\ .\ caller
     Skip
stowLandingGearMeth \stackrel{\frown}{=}
     \ 'stow Landing Gear Call . Take Off Mission MID ? caller-
      this.stowLandingGear();
      stowLandingGearRet.\ TakeOffMissionMID\ .\ caller
     Skip
```

```
is Landing Gear Deployed Meth \ensuremath{\widehat{=}} \mathbf{var} \ ret : \mathbb{B} \bullet \\ is Landing Gear Deployed Call \ . \ Take Off Mission MID \ ? \ caller \longrightarrow \\ ret := this \ . \ is Landing Gear Deployed (); \\ is Landing Gear Deployed Ret \ . \ Take Off Mission MID \ . \ caller \ ! \ ret \longrightarrow \\ \mathbf{Skip}
```

```
Methods \triangleq \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \\ \Box \\ takeOffAbortMeth \\ \Box \\ deployLandingGearMeth \\ \Box \\ stowLandingGearMeth \\ \Box \\ isLandingGearDeployedMeth \end{pmatrix}; Methods
```

 $\bullet \; (\mathit{Init} \; ; \; \mathit{Methods}) \; \triangle \; (\mathit{end\_mission\_app} \; . \; \mathit{TakeOffMissionMID} \longrightarrow \mathbf{Skip})$ 

 $\begin{array}{l} \textbf{section} \ \ Take Off Mission Class \ \ \textbf{parents} \ \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels \end{array}$ 

class  $TakeOffMissionClass \stackrel{\frown}{=} \mathbf{begin}$ 

```
\begin{array}{c} \textbf{state } SLATE = \\ SAFE\_AIRSPEED\_THRESHOLD: \mathbb{P} \, \mathbb{A} \\ TAKEOFF\_ALTITUDE: \mathbb{P} \, \mathbb{A} \\ abort: \mathbb{B} \\ landing Gear Deployed: \mathbb{B} \end{array}
```

 $\mathbf{state}\,\mathit{State}$ 

```
initial Init
State'
SAFE\_AIRSPEED\_THRESHOLD' = 10.0
TAKEOFF\_ALTITUDE' = 10.0
abort' = false
```

```
egin{align*} (abort := \mathbf{True}) \ & \mathbf{public} \ deployLandingGear \ \widehat{=} \ & (landingGearDeployed := \mathbf{True}) \ & \mathbf{public} \ stowLandingGear \ \widehat{=} \ & (landingGearDeployed := \mathbf{False}) \ & \mathbf{public} \ isLandingGearDeployed \ \widehat{=} \ & (ret := landingGearDeployed) \ & \end{aligned}
```

**public**  $takeOffAbort \stackrel{\frown}{=}$ 

• Skip

 $\quad \mathbf{end} \quad$ 

### 5.4 Schedulables of TakeOffMission

end

 ${\bf section} \ Landing Gear Handler App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Bindre, Take Off Mission Meth Chan$ 

```
process Landing Gear Handler App \cong
             mission: MissionID \bullet \mathbf{begin}
handle A sync Event =
      binder\_isLandingGearDeployedCall\ .\ mission\ .\ LandingGearHandlerSID {\longrightarrow}
              binder\_is Landing Gear Deployed Ret \ . \ mission \ . \ Landing Gear Handler SID \ ? \ is Landing Gear Deployed Ret \ . \ mission \ . \ Landing Gear Handler SID \ ? \ is Landing Gear Deployed Ret \ . \ mission \ . \ Landing Gear Handler SID \ ? \ is Landing Gear Deployed Ret \ . \ mission \ . \ Landing Gear Handler SID \ ? \ is Landing Gear Deployed \ . \ Market Market
             Skip; \operatorname{var} landing Gear Is Deployed : \mathbb{B} \bullet landing Gear Is Deployed := is Landing Gear Deployed;
             if landingGearIsDeployed \longrightarrow
                                  binder\_stowLandingGearCall . mission . LandingGearHandlerSID
                                  binder\_stowLandingGearRet\ .\ mission\ .\ LandingGearHandlerSID-learNet\ .
              \ 'binder\_deployLandingGearCall . mission . LandingGearHandlerSID -
                                  binder\_deployLandingGearRet..mission.LandingGearHandlerSID-\\
       handle A sync Event Ret \;.\; Landing Gear Handler SID {\longrightarrow}
      Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_aperiodic\_app . LandingGearHandlerSID \longrightarrow \mathbf{Skip})
```

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffFailureHandlerApp} \ \ \textbf{parents} \ \ \textit{AperiodicEventHandlerChan}, SchedulableId, SchedulableIds, MethodCallBing, MainMissionMethChan, TakeOffMissionMethChan \\ \end{array} \\$ 

```
process\ TakeOffFailureHandlerApp\ \widehat{=}
     mainMission: MissionID,
takeoffMission: MissionID,
threshold : \mathbb{P} \mathbb{A} \bullet \mathbf{begin}
handleAsyncEvent =
  'handle A sync Event Call . Take Off Failure Handler SID \longrightarrow
     binder\_getAirSpeedCall . mainMission . TakeOffFailureHandlerSID \longrightarrow
     binder\_getAirSpeedRet. mainMission. TakeOffFailureHandlerSID? getAirSpeed \longrightarrow
     Skip; var currentSpeed : \mathbb{P} \mathbb{A} \bullet currentSpeed := getAirSpeed;
     if(currentSpeed < threshold) \longrightarrow
             binder\_takeOffAbortCall. takeoffMission. TakeOffFailureHandlerSID \longrightarrow
             binder\_takeOffAbortRet. takeoffMission. TakeOffFailureHandlerSID \longrightarrow
             request Termination Call\ .\ take off Mission\ .\ Take Off Failure Handler SID \longrightarrow
             request Termination Ret.\ take off Mission.\ Take Off Failure Handler SID\ ?\ request Termination
             Skip
     [] \neg (\mathit{currentSpeed} < \mathit{threshold}) \longrightarrow
  handle A sync Event Ret. Take Off Failure Handler SID \longrightarrow
  Skip
Methods \mathrel{\widehat{=}}
(handleAsyncEvent); Methods
\bullet \ (\textit{Methods}) \ \triangle \ (\textit{end\_aperiodic\_app} \ . \ \textit{TakeOffFailureHandlerSID} \longrightarrow \mathbf{Skip})
```

 $\begin{array}{l} \textbf{section} \ \ \textit{TakeOffMonitorApp} \ \ \textbf{parents} \ \ \textit{PeriodicEventHandlerChan}, SchedulableId, SchedulableIds, MethodCallBindingChan, MainMissionMethChan \end{array}$ 

```
process TakeOffMonitorApp \cong
              main Mission: Mission ID,
takeOffMission: MissionID,
takeOffAltitude : \mathbb{P} \mathbb{A},
landingGear Handler: Schedulable ID ullet \mathbf{begin}
handleAsyncEvent \triangleq
      'handle A sync Event Call . Take Off Monitor SID \longrightarrow
               binder\_getAltitudeCall . mainMission . TakeOffMonitorSID \longrightarrow
               binder\_getAltitudeRet..mainMission..TakeOffMonitorSID?getAltitude {\longrightarrow}
              Skip; var altitude : \mathbb{P} \mathbb{A} \bullet altitude := getAltitude;
              if (altitude > takeOffAltitude) \longrightarrow
                                      release. landingGearHandler \longrightarrow
                                      request Termination Call\ .\ take Off Mission\ .\ Take Off Monitor SID \longrightarrow
                                      request Termination Ret.\ take Off Mission.\ Take Off Monitor SID\ ?\ request Termination - The Company of th
              [ \neg (altitude > takeOffAltitude) \longrightarrow \mathbf{Skip} ]
        \dot{handle} A sync Event Ret. Take Off Monitor SID \longrightarrow
      Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_periodic\_app . TakeOffMonitorSID \longrightarrow \mathbf{Skip})
```

end

0.4

### 5.5 CruiseMission

 $\begin{array}{l} \textbf{section} \ \ Cruise Mission App \ \textbf{parents} \ scj\_prelude, Mission Id, Mission Ids, \\ Schedulable Id, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Cruise Mission Meth Chan, \\ Method Call Binding Channels \end{array}$ 

```
 \begin{aligned} & \textbf{process } \textit{CruiseMissionApp} \; \widehat{=} \\ & \textit{controllingMission} : \textit{MissionID} \bullet \textbf{begin} \end{aligned} \\ & InitializePhase \; \widehat{=} \\ & \begin{pmatrix} initializeCall \; . \textit{CruiseMissionMID} \longrightarrow \\ register \; ! \; \textit{BeginLandingHandlerSID} \; ! \; \textit{CruiseMissionMID} \longrightarrow \\ register \; ! \; \textit{NavigationMonitorSID} \; ! \; \textit{CruiseMissionMID} \longrightarrow \\ initializeRet \; . \; \textit{CruiseMissionMID} \longrightarrow \\ \textbf{Skip} \end{pmatrix} \\ & CleanupPhase \; \widehat{=} \\ & \begin{pmatrix} cleanupMissionCall \; . \; \textit{CruiseMissionMID} \longrightarrow \\ cleanupMissionRet \; . \; \textit{CruiseMissionMID} \; ! \; \textbf{True} \longrightarrow \\ \textbf{Skip} \end{pmatrix} \\ & Methods \; \widehat{=} \; \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & CleanupPhase \end{pmatrix} ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \\ & \begin{pmatrix} InitializePhase \\ \Box \\ CleanupPhase \end{pmatrix} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \\ \end{pmatrix} \; ; \; \textit{Methods} \; ; \; \textit{Methods} \; ; \; \textit{Method
```

ullet (Methods)  $\triangle$  (end\_mission\_app . CruiseMissionMID  $\longrightarrow$  **Skip**)

# 5.6 Schedulables of CruiseMission

 ${\bf section} \ Begin Landing Handler App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binder Chan, Method Chan,$ 

```
 \begin{aligned} & \textbf{process } \textit{BeginLandingHandlerApp} \; \widehat{=} \\ & \textit{controllingMission} : \textit{MissionID} \; \bullet \; \textbf{begin} \end{aligned} \\ & \textit{handleAsyncEvent} \; \widehat{=} \\ & \begin{pmatrix} \textit{handleAsyncEventCall} \; . \; \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textit{frequestTerminationCall} \; . \; \textit{controllingMission} \; . \; \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textit{requestTerminationRet} \; . \; \textit{controllingMission} \; . \; \textit{BeginLandingHandlerSID} \; ? \; \textit{requestTermination} \longrightarrow \end{pmatrix} \; ; \\ & \textbf{Skip} \\ & \textit{handleAsyncEventRet} \; . \; \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textbf{Skip} \end{aligned} \\ & \textit{Methods} \; \widehat{=} \\ & \textit{(handleAsyncEvent)} \; ; \; \textit{Methods} \end{aligned} \\ & \bullet \; (\textit{Methods}) \; \triangle \; (\textit{end\_aperiodic\_app} \; . \; \textit{BeginLandingHandlerSID} \longrightarrow \\ & \textbf{Skip} ) \end{aligned}
```

 ${\bf section}\ \ Navigation Monitor App\ \ {\bf parents}\ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Binding Grant Mission Meth Chan$ 

```
\mathbf{process} \ Navigation Monitor App \ \widehat{=} 
              mainMission: MissionID \bullet \mathbf{begin}
handle A sync Event \triangleq
      \ 'handle A sync Event Call . Navigation Monitor SID {\longrightarrow}
              binder\_getHeadingCall\:.\:mainMission\:.\:NavigationMonitorSID \longrightarrow
              binder\_getHeadingRet..mainMission..NavigationMonitorSID~?~getHeading-particle for the contract of the contra
              Skip; var heading : \mathbb{P} \mathbb{A} \bullet heading := getHeading;
              binder\_getAirSpeedCall. mainMission. NavigationMonitorSID \longrightarrow
              binder\_getAirSpeedRet..mainMission..NavigationMonitorSID~?~getAirSpeed \longrightarrow
              Skip; \operatorname{var} airSpeed : \mathbb{P} \mathbb{A} \bullet airSpeed := getAirSpeed;
              binder\_getAltitudeCall. mainMission. NavigationMonitorSID \longrightarrow
             \mathbf{Skip}; \mathbf{var} altitude : \mathbb{P} \mathbb{A} \bullet altitude := getAltitude
        handle A sync Event Ret. Navigation Monitor SID \longrightarrow
      Skip
Methods =
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_periodic\_app . NavigationMonitorSID \longrightarrow \mathbf{Skip})
```

#### 5.7 LandMission

```
Schedulable Ids, Schedulable Ids, Mission Chan, Schedulable Meth Chan, Land Mission Meth Chan
, Land Mission Class, Method Call Binding Channels \\
process LandMissionApp \cong
     controlling Mission: Mission ID \bullet \mathbf{begin}
InitializePhase \stackrel{\frown}{=}
  'initializeCall . LandMissionMID \longrightarrow
  register! GroundDistanceMonitorSID! LandMissionMID \longrightarrow
   register! LandingGearHandlerLandSID! LandMissionMID \longrightarrow
  register! InstrumentLandingSystemMonitorSID! LandMissionMID \longrightarrow
  register! SafeLandingHandlerSID! LandMissionMID \longrightarrow
  initializeRet . LandMissionMID \longrightarrow
  Skip
CleanupPhase = \mathbf{var} \, \mathbb{B} : ret \bullet
  cleanup Mission Call . Land Mission MID \longrightarrow
   (ret := \mathbf{False})
   \`{c} leanup {\it Mission} {\it Ret} \; . \; Land {\it Mission} {\it MID} \; ! \; ret
deployLandingGearMeth \stackrel{\frown}{=}
  deploy Landing Gear Call . Land Mission MID? caller-
  this.\ deployLandingGear();
   deploy Landing Gear Ret\ .\ Land Mission MID\ .\ caller-
  Skip
stowLandingGearMeth \stackrel{\frown}{=}
  ^{'}stowLandingGearCall . LandMissionMID ? caller-
  this.stowLandingGear();
   stow Landing Gear Ret.\ Land Mission MID.\ caller-
  Skip
isLandingGearDeployedMeth \stackrel{\frown}{=} \mathbf{var} \ ret : \mathbb{B} \bullet
  is Landing Gear Deployed Call . Land Mission MID ? caller \longrightarrow
  ret := this.isLandingGearDeployed();
   is Landing Gear Deployed Ret . Land Mission MID . caller ! ret
                 Initialize Phase
                 CleanupPhase
Methods \stackrel{.}{=} \left[ \begin{array}{c} \Box \\ deployLandingGearMeth \end{array} \right]
                                                    ; Methods
```

ullet (Methods)  $\triangle$  (end\_mission\_app . LandMissionMID  $\longrightarrow$  **Skip**)

section LandMissionApp parents scj\_prelude, MissionId, MissionIds,

 $\begin{array}{l} \textbf{section} \ Land \textit{MissionClass} \ \textbf{parents} \ scj\_prelude, Schedulable Id, Schedulable Ids, Safelet Chan, Method Call Binding Channels \end{array}$ 

 $\mathbf{class}\,\mathit{LandMissionClass}\,\,\widehat{=}\,\,\mathbf{begin}$ 

```
\begin{array}{c} \textbf{state } State = \\ SAFE\_LANDING\_ALTITUDE : \mathbb{P} \, \mathbb{A} \\ ALTITUDE\_READING\_ON\_GROUND : \mathbb{P} \, \mathbb{A} \\ abort : \mathbb{B} \\ landingGearDeployed : \mathbb{B} \end{array}
```

 $\mathbf{state}\,\mathit{State}$ 

```
egin{align*} \left( landingGearDeployed := \mathbf{True} 
ight) \ & \mathbf{public} \ stowLandingGear \ \widehat{=} \ & \left( landingGearDeployed := \mathbf{False} 
ight) \ & \mathbf{public} \ isLandingGearDeployed \ \widehat{=} \ & \left( ret := landingGearDeployed 
ight) \end{aligned}
```

**public** deployLandingGear =

• Skip

### 5.8 Schedulables of LandMission

end

 ${\bf section} \ Landing Gear Handler Land App \ {\bf parents} \ Aperiodic Event Handler Chan, Schedulable Ids, Method Calley, Land Mission Meth Chan$ 

```
process Landing Gear Handler Land App \cong
                      mission: MissionID \bullet \mathbf{begin}
handle A sync Event =
           handle A sync Event Call. Landing Gear Handler Land SID \longrightarrow
                        binder\_isLandingGearDeployedCall\ .\ mission\ .\ LandingGearHandlerLandSID {\longrightarrow}
                       binder\_is Landing Gear Deployed Ret.\ mission.\ Landing Gear Handler Land SID?\ is Landing Gear Deployed
                      Skip; \operatorname{var} landing Gear Is Deployed : \mathbb{B} \bullet landing Gear Is Deployed := is Landing Gear Deployed;
                      if landingGearIsDeployed \longrightarrow
                                                        binder\_stowLandingGearCall . mission . LandingGearHandlerLandSID
                                                        binder\_stowLandingGearRet\ .\ mission\ .\ LandingGearHandlerLandSID-mission\ .\ LandingGearHandlerLandSID-
                       ^{'}binder\_deployLandingGearCall . mission . LandingGearHandlerLandSID -
                                                        binder\_deployLandingGearRet.\ mission.\ LandingGearHandlerLandSID-mission.\ LandingGearHandlerLandSI
            handle A sync Event Ret \;.\; Landing Gear Handler Land SID \longrightarrow
          Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
\bullet \ (Methods) \ \triangle \ (end\_aperiodic\_app \ . \ LandingGear Handler LandSID \longrightarrow \mathbf{Skip})
```

```
 \begin{aligned} & \textbf{process Safe Landing Handler App} \; \widehat{=} \\ & \textit{main Mission} : \textit{Mission ID}, \\ & \textit{threshold} : \mathbb{P} \, \mathbb{A} \, \bullet \, \textbf{begin} \\ \\ & \textit{handle Async Event} \; \widehat{=} \\ & \begin{pmatrix} \textit{handle Async Event Call} \; . \; \textit{Safe Landing Handler SID} \longrightarrow \\ & \textit{binder\_get Altitude Call} \; . \; \textit{main Mission} \; . \; \textit{Safe Landing Handler SID} \; \bigcirc \\ & \textit{binder\_get Altitude Ret} \; . \; \textit{main Mission} \; . \; \textit{Safe Landing Handler SID} \; ? \; \textit{get Altitude} \longrightarrow \\ & \textbf{Skip} \; ; \; \textbf{var} \; \textit{altitude} \; : \; \mathbb{P} \, \mathbb{A} \, \bullet \, \textit{altitude} \; : = \; \textit{get Altitude}; \\ & \textbf{if} \; (\textit{altitude} \; < \; \textit{threshold}) \; \longrightarrow \\ & \textbf{Skip} \; \\ & \textbf{fi} \; (\textit{altitude} \; < \; \textit{threshold}) \; \longrightarrow \\ & \textbf{Skip} \; \\ & \textbf{fi} \; \\ & \textit{handle Async Event Ret} \; . \; \textit{Safe Landing Handler SID} \longrightarrow \\ & \textbf{Skip} \; \\ & \textit{Methods} \; \widehat{=} \; \\ & \textit{(handle Async Event)} \; ; \; \textit{Methods} \; \end{aligned}
```

•  $(Methods) \triangle (end\_aperiodic\_app . SafeLandingHandlerSID \longrightarrow \mathbf{Skip})$ 

 ${\bf section} \ \ Ground Distance Monitor App \ \ {\bf parents} \ \ Periodic Event Handler Chan, Schedulable Id, Schedulable Ids, Method Call Birgon, Main Mission Meth Chan$ 

```
process GroundDistanceMonitorApp \cong
               mainMission: MissionID,
readingOnGround : \mathbb{P} \mathbb{A} \bullet \mathbf{begin}
handleAsyncEvent \triangleq
       'handle A sync Event Call. Ground Distance Monitor SID \longrightarrow
                binder\_getAltitudeCall . mainMission . GroundDistanceMonitorSID \longrightarrow
                binder\_getAltitudeRet \ . \ mainMission \ . \ GroundDistanceMonitorSID \ ? \ getAltitude \longrightarrow
                \mathbf{Skip}\;;\;\;\mathbf{var}\;\textit{distance}: \mathbb{P}\,\mathbb{A}\,\bullet\,\textit{distance}:=\;\textit{getAltitude};
               \mathbf{if} \ (\mathit{distance} = \mathit{readingOnGround}) \longrightarrow
                                       \'request Termination Call . main Mission . Ground Distance Monitor SID \longrightarrow
                                        request Termination Ret.\ main Mission.\ Ground Distance Monitor SID\ ?\ request Termination - The Control of the Control of
                              (distance = readingOnGround) \longrightarrow \mathbf{Skip}
         handle A sync Event Ret: Ground Distance Monitor SID {\longrightarrow}
       Skip
Methods \stackrel{\frown}{=}
(handleAsyncEvent); Methods
• (Methods) \triangle (end\_periodic\_app . GroundDistanceMonitorSID \longrightarrow \mathbf{Skip})
```

```
 \begin{aligned} \mathbf{process} & \textit{InstrumentLandingSystemMonitorApp} \ \widehat{=} \\ & \textit{mission} : \textit{MissionID} \bullet \mathbf{begin} \end{aligned} \\ handle & \textit{AsyncEvent} \ \widehat{=} \\ \begin{pmatrix} \textit{handleAsyncEventCall} \cdot \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ \mathbf{Skip}; \\ \textit{handleAsyncEventRet} \cdot \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \\ \mathbf{Skip} \end{aligned} \\ Methods \ \widehat{=} \\ \begin{pmatrix} \textit{handleAsyncEvent} \end{pmatrix}; \quad \textit{Methods} \end{aligned} \\ \bullet & (\textit{Methods}) \ \triangle & (\textit{end\_periodic\_app} \cdot \textit{InstrumentLandingSystemMonitorSID} \longrightarrow \mathbf{Skip}) \end{aligned} \\ \mathbf{end}
```