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ML- HW 5

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Q1) (a) 
$$\min_{\theta} \frac{1}{n} \sum_{i=1}^n \phi(y_i(\omega^T x_i + b)) + \lambda \|\omega\|^2$$

$$\phi(e) = \log(1 + e^{-t})$$

$$J = \min_{\theta} \frac{1}{n} \sum_{i=1}^n \log(1 + e^{-y_i(\omega^T x_i + b)}) + \lambda \|\omega\|^2$$

$$\frac{\partial J}{\partial \omega} \Rightarrow \frac{1}{n} \sum_{i=1}^n \frac{1}{1 + e^{-y_i(\omega^T x_i + b)}} \left[ -y_i x_i e^{-y_i(\omega^T x_i + b)} \right] + 2\lambda \omega$$

dividing the numerator and denominator

by  $e^{-y_i(\omega^T x_i + b)}$

We get,

$$\frac{\partial J}{\partial \omega} = \frac{1}{n} \sum_{i=1}^n \frac{-y_i x_i}{1 + e^{y_i(\omega^T x_i + b)}} + 2\lambda \omega$$

Similarly,

$$\frac{\partial J}{\partial b} = \frac{1}{n} \sum_{i=1}^n \frac{1}{1 + e^{-y_i(\omega^T x_i + b)}} \left[ -y_i e^{-y_i(\omega^T x_i + b)} \right] + 0$$

dividing numerator and denominator by  $e^{-y_i(\omega^T x_i + b)}$

We get,

$$\frac{\partial J}{\partial b} = \frac{1}{n} \sum_{i=1}^n \frac{-y_i}{1 + e^{y_i(\omega^T x_i + b)}}$$

Gradient descent update rule

$$\left. \begin{aligned} w^{k+1} &= w^k - \eta \frac{\partial J}{\partial w^k} \\ b^{k+1} &= b^k - \eta \frac{\partial J}{\partial b^k} \end{aligned} \right\} \text{ where } w^k, b^k \text{ indicate hyperparameters at } k^{\text{th}} \text{ iteration.}$$

$$\boxed{\begin{aligned} w^{k+1} &= w^k - \eta \left[ \frac{1}{n} \sum_{i=1}^n \frac{-y_i x_i}{1 + e^{y_i(w^k x_i + b^k)}} + 2\lambda w^k \right] \\ b^{k+1} &= b^k - \eta \left[ \frac{1}{n} \sum_{i=1}^n \frac{-y_i}{1 + e^{y_i(w^k x_i + b^k)}} \right] \end{aligned}}$$

→ This is  $(w^k)^T$

→ update rules =

$\mathcal{J}(b)$  In  $\mathcal{J}(a)$  we have got

$$\frac{\partial J}{\partial w} = \frac{1}{n} \sum_{i=1}^n \frac{-y_i x_i}{1 + e^{y_i(w^T x_i + b)}} + 2\lambda w$$

As the objective  $J$  is given to be convex, a unique global minimizer exists,  $(w^*, b^*)$ . And @ global minimizer

$$\underbrace{\frac{\partial J}{\partial w^*} = 0}_{\downarrow} \quad \frac{\partial J}{\partial b^*} = 0$$

We will just take  $\frac{\partial J}{\partial w^*} = 0$  and examine it.

$$\frac{\partial J}{\partial w^*} = 0 \Rightarrow \frac{1}{n} \sum_{i=1}^n \frac{-y_i x_i}{1 + e^{y_i(w^{*T} x_i + b^*)}} + 2\lambda w^* = 0$$

$$\Rightarrow 2\lambda w^* = +\frac{1}{n} \sum_{i=1}^n \frac{y_i x_i}{1 + e^{y_i(w^* T x_i + b^*)}}$$

$$\Rightarrow 2\lambda w^* = \frac{1}{n} X^T \begin{bmatrix} \frac{y_1}{1 + e^{y_1(w^* T x_1 + b^*)}} \\ \vdots \\ \frac{y_n}{1 + e^{y_n(w^* T x_n + b^*)}} \end{bmatrix}$$

where  $X^T = \begin{bmatrix} 1 & 1 & \dots & 1 \\ x_1 & x_2 & \dots & x_n \\ 1 & 1 & \dots & 1 \end{bmatrix}$

$$\Rightarrow w^* = X^T \underbrace{\begin{bmatrix} \frac{1}{2\lambda n} \\ \frac{y_1}{1 + e^{y_1(w^* T x_1 + b^*)}} \\ \vdots \\ \frac{y_n}{1 + e^{y_n(w^* T x_n + b^*)}} \end{bmatrix}}_{\alpha^*}$$

$$\therefore \boxed{w^* = X^T \alpha^*}$$

for some  $\alpha^*$

Q1 (c) (a)  $w^{\text{old}} = X^T \alpha^{\text{old}}$

We know from Q1 (a) update formula

$$w^{\text{new}} = w^{\text{old}} - \eta \left[ \frac{1}{n} \sum_{i=1}^n \frac{-y_i x_i}{1 + e^{y_i(w^{\text{old}} T x_i + b^{\text{old}})}} + 2\lambda w^{\text{old}} \right]$$

This is  $(w^{\text{old}})^T$

- (1)

Let us substitute  $w^{old} = X^T \alpha^{old}$  in eqn (1)

$$\cancel{X^T \alpha^{old}} \quad w^{new} = X^T \alpha^{old} - \eta \left[ \underbrace{\frac{1}{n} \sum \frac{-y_i x_i}{1 + e^{y_i (X^{oldT} x_i + b^{old})}}}_{\text{term}} + 2\lambda X^T \alpha^{old} \right] \quad (2)$$

Let us try to analyse this term

$$\Rightarrow \frac{1}{n} \sum_{i=1}^n \frac{-y_i x_i}{1 + e^{y_i (\alpha^{oldT} x_i + b^{old})}} \Rightarrow \frac{1}{n} X^T \begin{bmatrix} \frac{-y_1}{1 + e^{y_1 (\alpha^{oldT} x_1 + b^{old})}} \\ \vdots \\ \frac{-y_n}{1 + e^{y_n (\alpha^{oldT} x_n + b^{old})}} \end{bmatrix} \quad (3)$$

Substituting eqn (3) back in (2)

$$w^{new} = X^T \alpha^{old} - \eta \left[ \frac{1}{n} X^T \begin{bmatrix} \frac{-y_1}{1 + e^{y_1 (\alpha^{oldT} x_1 + b^{old})}} \\ \vdots \\ \frac{-y_n}{1 + e^{y_n (\alpha^{oldT} x_n + b^{old})}} \end{bmatrix} + 2\lambda X^T \alpha^{old} \right]$$

$$\Rightarrow w^{new} = X^T \left[ \alpha^{old} - \eta \left[ \frac{1}{n} \begin{bmatrix} \frac{-y_1}{1 + e^{y_1 (\alpha^{oldT} x_1 + b^{old})}} \\ \vdots \\ \frac{-y_n}{1 + e^{y_n (\alpha^{oldT} x_n + b^{old})}} \end{bmatrix} + 2\lambda \alpha^{old} \right] \right]$$

$\alpha^{new}$

$$\Rightarrow w^{new} = X^T \alpha^{new}$$

where

$$\alpha^{new} = \left[ \alpha^{old} - \eta \left[ \frac{1}{n} \begin{bmatrix} \frac{-y_1}{1 + e^{y_1 (\alpha^{oldT} x_1 + b^{old})}} \\ \vdots \\ \frac{-y_n}{1 + e^{y_n (\alpha^{oldT} x_n + b^{old})}} \end{bmatrix} + 2\lambda \alpha^{old} \right] \right] \rightarrow \text{update}$$

Bl (d) From Bl(c) we know that

$$\alpha^{\text{new}} = \alpha^{\text{old}} - \left[ \frac{1}{n} \begin{bmatrix} \frac{-y_1}{1 + e^{y_1(\alpha^{\text{old}T} x_1 + b^{\text{old}})}} \\ \vdots \\ \frac{-y_n}{1 + e^{y_n(\alpha^{\text{old}T} x_n + b^{\text{old}})}} \end{bmatrix} + 2\lambda \alpha^{\text{old}} \right] \quad - (1)$$

Let us just examine a general term in this vector

$$\Rightarrow \frac{-y_i}{1 + e^{y_i(\alpha^{\text{old}T} x_i + b^{\text{old}})}} \quad \text{we see that } x_i^T x_i \text{ is an inner product}$$

$$(ie) \quad x_i^T x_i = \begin{bmatrix} x_1^T x_i \\ x_2^T x_i \\ \vdots \\ x_n^T x_i \end{bmatrix} \quad - (2)$$

This inner product can be replaced by using a kernel.

$$x_i^T x_i = \begin{bmatrix} k(x_1, x_i) \\ k(x_2, x_i) \\ \vdots \\ k(x_n, x_i) \end{bmatrix} = K(x, x_i) \quad - (3)$$

am denoting this column vector as  $K(x, x_i)$



eq(3)

Now substituting the same  $n$  back in eqn (3)

We get  $\alpha^{\text{new}} = \alpha^{\text{old}} - \eta \left[ \frac{1}{n} \sum_{i=1, \dots, n} \frac{y_i}{1 + e^{y_i(\alpha^{\text{old}})^T K(X, x_i) + b^{\text{old}}}} \right] + 2\lambda \alpha^{\text{old}}$

also  $b^{\text{new}} = b^{\text{old}} - \eta \sum_{i=1}^n \frac{-y_i}{1 + e^{y_i(\alpha^{\text{old}})^T K(X, x_i) + b^{\text{old}}}}$

→ This is  $b^{\text{old}}$

Thus the update rule is kernelized.

We can set  $\alpha^{\text{old}}$  to zero vector to start with and keep updating  $\alpha^{\text{new}}, b^{\text{new}}$  till we end up with  $(\alpha^*, b^*)$ , then we know  $w^* = X^T \alpha^*$

Final classifier,

$$\eta(y=1|x) = \frac{1}{1 + e^{-(\alpha^*)^T K(X, x_i) + b^*)}}$$

✓  
This is the probability  
that class = 1,

and

$$\begin{cases} \eta(y=1|x) \geq \frac{1}{2} & \text{predict class} = 1 \\ \eta(y=1|x) < \frac{1}{2} & \text{predict class} = -1 \end{cases}$$

This is -1

## Kernel Logistic Regression

Q 1(e)

$$\text{Accuracy} = 0.796$$

$$\text{Error} \Rightarrow 1 - 0.796 \Rightarrow \underline{\underline{0.204}}$$

Q 2(a) Statistics  $X\text{-mean} = [0.50161345, 0.45612671, 0.3824407]$

$$X\text{std} = [0.24617303, 0.23615181, 0.23905821]$$

(1)

### • Resizing:

✓ Benefit — resizing is useful to have images with the same pixels in the data set

The raw dataset might contain different images with different dimensions

for example  $1000 \times 800$ ,  $200 \times 400$ , etc, but resizing helps us

to work with uniform dimensions through out dataset.

✓ Drawback: By doing resizing, some important features are interpolated,

and also, whenever we resize a smaller image, we would create a padding around, it which might mislead our classifier, if there are

several images with padding.

### • Normalizing:

✓ Benefit: Normalizing the pixel intensities, will help the convergence of the optimizer, there won't be much of ~~zig~~ zig-zagging during optimization. The ~~drawback~~ <sup>centered</sup> data will keep the gradients in control when we use backpropagation.

## Normalizing data

✓ Drawback - Normalizing data can sometimes lead to loss of information.

For example, Normalizing just preserves relative variations in data.

If we want to classify day and night images; normalizing our data will affect the classification performance as it only captures relative information.

Q2(a)

(2)

per-channel mean and standard deviation are used to scale our training data. Validation set is not a part of our training data. When we scale our training data using training per channel mean and per-channel standard deviation, it helps us center the data for training, but during validation and testing phase we should use the same scaling as the neural network that is trained is learnt for the information scaled this particular way. Hence, it does not make sense to use a different scaling metric for validation images.

Q2(b)

(1) Layer-1

Filter =  $5 \times 5$

Input channel = 3

Output channel = 16

No. of parameters =  $(5 \times 5 \times 3 + 1) \times 16$

← This is for bias

$$\boxed{= 1216} \quad \text{Convolution layer-1}$$

Layer-2

Filter =  $5 \times 5$

Input channel = 16

Output channels = 32

No. of parameters =  $(5 \times 5 \times 16 + 1) \times 32$

← Bias

$$\boxed{= 12832} \quad \text{Convolution layer-2}$$



### Layer-3

Filter =  $5 \times 5$

Input channel = 32

Output channel = 64

$$\begin{aligned} \text{No. of parameters} &= (5 \times 5 \times 32 + 1) \times 64 \\ &= \boxed{51264} - \text{convolution layer-3} \end{aligned}$$

### Layer-4

Filter =  $5 \times 5$

Input channel = 64

Output Channels = 128

$$\begin{aligned} \text{No. of parameters} &= (5 \times 5 \times 64 + 1) \times 128 \\ &= \boxed{204928} - \text{convolution layer-4} \end{aligned}$$

### Layer-5 (Fully connected)

Inputs =  $128 \times 2 \times 2$

Output = 64

$$\begin{aligned} \text{No. of parameters} &= (128 \times 2 \times 2 + 1) \times 64 \\ &= \boxed{32832} - \text{fully connected layer-5} \end{aligned}$$

### Layer-6 (Fully connected)

Inputs = 64

Outputs = 5

$$\begin{aligned} \text{No. of parameters} &= (64 + 1) \times 5 \\ &= \boxed{325} - \text{fully connected layer-6} \end{aligned}$$

$$\begin{aligned} \text{Total parameters} &= 1216 + \\ &12832 + \\ &51264 + \\ &204928 + \\ &32832 + \\ &325 \end{aligned}$$

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$$303397$$

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Q2(b) Q. One reason as to why we don't want to initialize our neural network to zero is because, when initialized with 0's then all the layers perform the same calculation, there won't be any symmetry breaking, the gradients computed take the learning no. where, This is the reason why we should initialize the network <sup>weights</sup> randomly.

Q2 (d) Final accuracies and losses

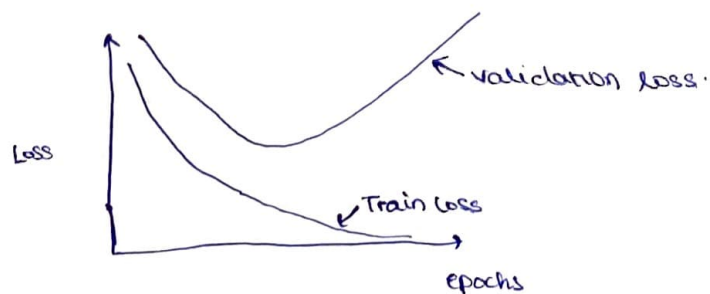
Validation loss:- 2.3131

Validation accuracy:- 0.4872

Train loss:- 0.007707

Train accuracy:- 1

(e) 1) The training loss keeps decreasing, and the validation loss drops at first and then starts increasing after a point.



As we keep on training the model our training loss would be going to zero, while our validation loss will shoot up to higher values.

This means we have done an overfit to our data.

Q2 (e) 2. We should always try to minimize Validation loss not the training loss.

Based on the plot, we should stop training our model after 2 epochs as after 2 epochs the validation loss starts increasing. We should not try to maximize training accuracy because it leads to overfitting for the data, and the model learnt, won't be a good generalization of the true nature of data.

~~Q2 (g)~~ Q2 (f) Final accuracies and losses:

Validation Loss:- 0.18

Validation accuracy = 0.935897

train loss: 0.11598

train accuracy: 0.956

Q2 (g) We can't use accuracy during an im balance dataset case because, it is not fully reflective of the <sup>correct</sup> classification for each class. Per-class accuracy metric makes more sense in this scenario to assess how good our model is.

## Q2(h) (Non-Weighted) Loss Imbalance dataset (5 epochs)

Validation loss: - 0.1246

Validation accuracy: - 0.9545

train loss: 0.03430

train accuracy: 0.99076

Per class accuracy :-  $\begin{bmatrix} \text{Cat} & \text{dog (+ve class)} \\ 1 & 0.5 \end{bmatrix}$

(dog +ve class)  $\left\{ \begin{array}{l} \text{precision} = 1 \\ \text{recall} = 0.5 \\ \text{F1-Score} = 0.66666 \end{array} \right.$

## Weighted Cross entropy loss Imbalance dataset (5 epochs)

Validation loss: - 0.12327

Validation accuracy: - 0.963636

train loss: - 0.047591

train accuracy: - 0.9857142

Per class accuracy: -  $\begin{bmatrix} \text{Cat} & \text{dog} \\ 0.98 & 0.8 \end{bmatrix}$

$\left. \begin{array}{l} \text{Precision} = 0.8 \\ \text{Recall} = 0.8 \\ \text{F1 Score} = 0.8 \end{array} \right\} \text{ (dog is +ve class)}$

The un-weighted model has more training accuracy and train loss, but as the dataset is imbalanced we can see it performs poorly on other metrics like F1 score, recall, & per-class accuracy. What was happening here is that the model was being overfit for the features of Cat as the examples are more in number.

In the weighted case, it can be observed that weighting dog class by a factor improved the performance of the model, this can be seen from metrics like F1 score, precision, recall. Here due to weight, the ~~less~~ model was able to distinguish features of dog from that of cat, though the examples are pretty less in number.