Article Presentation A Robot Application for Marine Vessel Inspection

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INTRODUCTION REENGINEERED INSPECTION PROCEDURE MINOAS INSPECTION PLATFORMS A VISION-BASED SOLUTION FOR DEFECT DETECTION SPATIAL CONTENT MANAGEMENT SYSTEM FOR ROBOT-AGE SYSTEM PERFORMANCE EVALUATION

INTRODUCTION







Overview
Traditional Inspection
MINOAS
Spatial Content Management System (SCMS)

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CONCLUSION AND EUTILIER PESSARCH

REENGINEERED INSPECTION PROCEDURE

System	Stage 1	Stage 2	Stage 3
Aerial platform	×		
Lightweight inspection system		×	
(crawler & localization device)			
Heavyweight inspection system			×
(crawler & NDT thickness			
measurement device)			
Defect detection system	×	×	
Spatial contents management system	×	×	×

Fast visual inspection
Visual close-up survey
Thickness measurement collection



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MINOAS Inspecton Platforms

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A VISION-BASED SOLUTION FOR DEFECT DETECTION

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SPATIAL CONTENT MANAGEMENT SYSTEM FOR ROBOT-ACQUIRED INSPECTION DATA

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SYSTEM PERFORMANCE EVALUATION

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CONCLUSION AND FUTURE RESEARCH

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