# PROGRAMMING LANGUAGES: IMPERATIVE PROGRAM CONSTRUCTION 11. SEPARATION LOGIC I

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#### SEPARATION MATTERS

- Our reasoning so far is based on an important assumption: variables, having different names, are independent from each other.
- · With var a, b, for example, mutating a does not change the value of b.
- · Otherwise most of our reasoning would fail.

#### **REMARK: PROCEDURE CALLS**

· Problem with procedures with call-by-reference variables.

```
proc swap (ref x, y : Int) = x := x - y; y := x + y; x := y - x
```

- swap(a, b) should swap the values of a and b we have proved so before, haven't we?
- However, swap (a, a) sets a to 0.
- Extra care is needed to handle function/procedure calls, which we unfortunately won't cover in this course.

DYNAMIC MEMORY MANAGEMENT

#### DYNAMIC MEMORY MANAGEMENT

- Another source of possible violation is the heap memory model.
- Recall: variables declared are supposed to be located in *stacks*. (Also called a *store*).
- In the heap model, programmers can allocate blocks of memories in heaps.
- We can store addresses of heap cells in variables, lookup the content of a heap given the address, or deallocate a cell.

#### POINTER MANIPULATION

- · A pointer is a variable that stores a memory address.
- In our setting we let Addr = Int, and let nil be a unique address.
- p := cons(1, 2) allocate two consecutive heap cells, set their values to 1 and 2, and store the address of the first cell in p.
  - One has no control what the address will be, other than that it won't be nil.
- $x := {}^*e look$  up the value stored in the cell with address e, and copy the value to variable x.
- \*e := f let the value stored in cell with address e be updated to f.
- free e free the cell having address
- In the last three cases the address e must have been allocated.

#### **EXAMPLE**

program	store and heap
	$s: x = 3 \land y = 4; h: emp$
x := cons(1, 2)	$s: x = 34 \land y = 4$
	$h:34\mapsto 1,35\mapsto 2$
$y := {}^*X$	$s: x = 34 \land y = 1$
	$h:34\mapsto 1,35\mapsto 2$
*(x+1) := 3	$s: x = 34 \land y = 1$
	$h:34\mapsto 1,35\mapsto 3$
free $(x+1)$	$s: x = 34 \land y = 1$
	$h:34 \mapsto 1$

#### Notes:

- Apart from that cons does not return nil, the program cannot predict what address (e.g. 34) cons would return.
- Reading from, writing to, or deallocating an address that is not yet allocated aborts the program.
- We do not have an operator that gives you the address of variables in store (like & in C).

#### LINKED LISTS

- We abbreviate  $i \mapsto 1$  and  $i + 1 \mapsto 2$  to  $i \mapsto 1, 2$ .
- · Assume that we represent lists in heap by linked lists.
- E.g [1,2,3] is represented in the following heap, starting from address 34:

```
34 \mapsto 1,92 60 \mapsto 3, \text{nil} 92 \mapsto 2,60 .
```

• (We will present a more formal definition later.)

#### IN-PLACE LIST REVERSAL

• If the address *i* represents a list XS, after executing the following program, *i* points to **nil** and *j* represents the reverse of XS.

```
{ i represents XS }

j := nil

do i \neq nil \rightarrow k := *(i + 1)

*(i + 1) := j

j, i := i, k

od

{ j represents reverse\ XS }
```

- That is, the program reverts a linked list without using additional space.
- · Can we prove that it is correct?

#### IN-PLACE LIST REVERSAL

 Not that easy..! The loop only works if i and j do not share any nodes. The loop invariant would be something like:

```
i represents xs \land j represents ys \land ... i and j share only nil.
```

 Furthermore, we want to ensure that other data structure in the heap should remain unchanged. Assume that we have another linked-list k, we will need in the invariant:

```
    i represents xs ∧
    j represents ys ∧ ...
    i and j share only nil ∧
    k and (i union j) share only nil.
```

 We need to mention every pointer in the invariant. This does not scale well.

## SEPARATION LOGIC BASICS

#### SEPARATION LOGIC

- Separation logic: a logic for describing and reasoning about heaps, in which sections of heaps are separated by default
- Developed by people including Reynolds and O'Hearn in early 2000's.
- · Widely adopted by industry in around 2010's.

- Recall: assertions in Hoare logic are predicates on state space (values of variables in the store).
- Assertion in separation logic are predicates on the store and the heap.
- We will start with an informal description and give a more formal definition later.

#### STORE AND HEAP

- A store is a (partial) function from variable names to values:  $Store = Var \rightarrow Val$ , where  $Val = Int \cup Bool \cup ...$
- A heap is a (partial) function from addresses to integers:  $Heap = Int \rightarrow Int$  an address is also a Int.
- The domain of a function *f* is denoted *dom f*.
- We denote dom  $h_0 \cap dom \ h_1 = \emptyset$  by  $h_0 \perp h_1$ .
- Given functions  $h_0$  and  $h_1$  where  $h_0 \perp h_1$ , define

$$(h_0 \cdot h_1) x = h_0 x$$
 if  $x \in dom h_0$ ,  
=  $h_1 x$  if  $x \in dom h_1$ .

#### **SOME PRIMITIVES**

### Given a heap h,

- emp h holds if dom  $h = \emptyset$ .
  - emp says that nothing is allocated in the heap.
- $e \mapsto e'$  holds of h if  $dom h = \{e\}$  and h e = e'.
  - h is a singleton heap containing only e' in address e.
  - Note that both *e* and *e'* are expressions!
- P \* Q holds of h if  $h = h_0 \cdot h_1$  and  $P h_0$  and  $Q h_1$ .
  - That  $h_0 \cdot h_1$  being defined implies that  $h_0 \perp h_1$ .
  - h can be decomposed into two *disjoint* heap  $h_0$  and  $h_1$  such that p holds of  $h_0$  and q holds of  $h_1$ .

- True holds of any h, while False holds of no h.
- $e \mapsto e_0, e_1, ... e_n \equiv (e \mapsto e_0) * (e + 1 \mapsto e_1) * ... (e + n \mapsto e_n).$
- $e \mapsto \bot \equiv \langle \exists v :: e \mapsto v \rangle$ .
- $e \hookrightarrow e' \equiv (e \mapsto e') * True$ .
- separating implication  $p \rightarrow q$  will be introduced later.

#### THE TRUE STORY

- The presentation above was very simplified.
- In fact, all the predicates introduced above are predicate on store and heap, because we need the store to evaluate an expression.
- We will keep it simple for now. For a more precise account, see Reynolds.
- Keep in mind, for example, that  $x \mapsto 3$ , where x is a variable, actually means x is mapped to some a in the store, and a is mapped to a in the heap.
  - The predicate can be invalidated if either the value of x or the value stored in the heap changes.

#### **EXAMPLES**

- $x \mapsto 3, y$ .
- $(X \mapsto 3, y) * (y \mapsto 3, x)$ .
- $(x \mapsto 3, y) \land (y \mapsto 3, x)$ .
- $(x \hookrightarrow 3, y) \land (y \hookrightarrow 3, x)$ .

#### SEPARATING IMPLICATION

· Separating implication is defined by:

$$(P \twoheadrightarrow Q) h = \langle \forall h_0 : h_0 \perp h \wedge P h_0 : Q (h_0 \cdot h) \rangle$$
.

• That is,  $P ext{-*} Q$  holds of h if, given any  $h_0$  that is disjoint from h and satisfies P, we have  $h_0 \cdot h$  satisfies Q.

#### **EXAMPLE**

• Suppose P asserts various things, including  $x \mapsto 3, 4$ . Thus P holds of

$$s: x = a$$
  
 $h: a \mapsto 3, a + 1 \mapsto 4$ , rest of heap

•  $(x \mapsto 3, 4) - P$  holds of the following store and heap:

$$s: x = a$$
  
  $h: rest of heap$ 

•  $(x \mapsto 1, 2) * ((x \mapsto 3, 4) \twoheadrightarrow P)$  holds of the following store and heap:

$$s: x = a$$
  
 $h: a \mapsto 1, a + 1 \mapsto 2$ , rest of heap

#### **HEAP MUTATION - MOTIVATION**

· From the example above we notice that

$$\{(X \mapsto 1) * ((X \mapsto 3) \twoheadrightarrow P)\}$$
  
\* $X := 3$   
{ $P$ }

· To be slightly more general,

$$\{(X \mapsto \_) * ((X \mapsto 3) \twoheadrightarrow P)\}$$
  
\* $X := 3$   
{ $P$ }

· We will see a more general rule later.

## COMMANDS AND RULES

#### **RULE OF CONSTANCY**

 In logic systems, the following notation denotes "Q can be established by establishing P":

• In Hoare logic, the following "rule of constancy" holds:

$${P} S {Q}$$
$${P \wedge R} S {Q \wedge R}$$

where S does not mutate variables in R.

 It allows us to reason about programs in a more modular way.  However, rule of constancy does not hold for programs allowing dynamic memory management. The following does not hold, for example.

$$\frac{\{x \mapsto \bot\} *x := 4 \{x \mapsto 4\}}{\{x \mapsto \bot \land y \mapsto 3\} *x := 4 \{x \mapsto 4 \land y \mapsto 3\}}$$

• \*x := 4 does not mutate y. Yet the conclusion is invalidated when x = y.

#### FRAME RULE

• With the introduction of separating conjunction, we do have (for those *S* that do not mutate variables in *R*):

$$\frac{\{P\} S \{Q\}}{\{P*R\} S \{Q*R\}}$$

- The rule above is called the "frame rule". With it we can again reason about programs modularly.
- Wanting to have such rule is the very reason why separation logic was developed.

#### **COMMANDS**

- Now we discuss rules associated with each pointer manipulating command.
- Each command is associated with three types of rule: local, global (forward), and backward rules.

#### MUTATION

```
• Local: \{e \mapsto \_\} *e := e' \{e \mapsto e'\}.
• Global: \{(e \mapsto \_) * R\} *e := e' \{(e \mapsto e') * R\}.
• Backwards: \{(e \mapsto \_) * ((e \mapsto e') \multimap P)\} *e := e' \{P\}.
```

• The global rule is often the result of applying the frame rule to the local rule.

#### **DEALLOCATION**

```
• Local: \{e \mapsto \_\} free e \{emp\}.
```

- Global:  $\{(e \mapsto \_) * R\}$  free  $e \{R\}$ .
- For this case, the global rule is also a backwards rule.

#### ALLOCATION, NON-OVERWRITING

A simpler, *non-overwriting* case, where x does not occur free in e.

- Local:  $\{emp\} x := cons \ e \ \{x \mapsto e\},$
- Global:  $\{R\} x := \mathbf{cons} \ e \{(x \mapsto e) * R\}.$
- The backwards rule and the general case is much more complex — we will discuss them later.
- We have not yet discussed the rule for looking up (x := \*e)
   which turns out to be surprisingly complex. Discussion postponed.

#### **EXAMPLE**

The following code fragment tries to glue together adjacent cells, if possible.

```
\{(x \mapsto \_) * (y \mapsto \_)\}
if y = x + 1 \rightarrow skip
|x = y + 1 \rightarrow x := y
||x - y| > 1 \rightarrow free x; free y
x := cons (1, 2)
fi
\{x \mapsto \_, \_\}
```

#### ALLOCATION, GENERAL CASE

Local:

$$\{x = X \land emp\} x := cons \ e \{x \mapsto e[x \setminus X]\}$$
,

where X is distinct from x and does not occur free in e.

Global:

$$\{R\} x := \mathbf{cons} \ e \{\langle \exists x_0 :: (x \mapsto e[x \backslash x_0]) * R[x \backslash x_0] \rangle \}$$
,

where  $x_0$  is distinct from x and does not occur free in e and R.

· Backwards:

$$\{\langle \forall x_1 :: (x_1 \mapsto e) \twoheadrightarrow P[x \setminus x_1] \rangle\} x := \operatorname{cons} e\{P\}$$
,

where  $x_1$  is distinct from x and does not occur free in e and R

#### LOOKUP, NON-OVERWRITING

Provided that x does not occur free in e,

- Local:  $\{e \mapsto v\} x := *e \{x = v \land e \mapsto x\}.$
- · Global:

$$\left\{\left\langle \exists v :: \left(e \mapsto v\right) * R[x \backslash v]\right\rangle\right\} x := {^*\!e} \left\{\left(e \mapsto x\right) * R\right\} \ ,$$

where  $v \notin free \ e \cup (free \ R - \{x\})$ .

#### REMOVING ∃

• Note that *v* in the global rule can be *x*, which gives us this special case:

$$\{\langle \exists X :: (e \mapsto X) * R \rangle\} X := {}^*e \{(e \mapsto X) * R\} .$$

• That is,  $x := {}^*e$  can be used to remove an existential quantification — a common usage.

#### LOOKUP, GENERAL

Local:

$$\{x = x_0 \wedge e \mapsto v\} x := {^*e} \{x = v \wedge e[x \setminus x_0] \mapsto x\} ,$$

where x,  $x_0$ , v distinct.

· Global:

$$\{ \langle \exists v :: (e \mapsto v) * R[x_0 \setminus x] \rangle \}$$

$$x := *e$$

$$\{ \langle \exists x_0 :: (e[x \setminus x_0] \mapsto x) * R[v \setminus x] \rangle \} ,$$

where x,  $x_0$ , v distinct,  $x_0$  and v not free in e, x not free in R.

· Backwards:

$$\{ \langle \exists V :: (e \mapsto V) * ((e \mapsto V) - * P[X \setminus V]) \rangle \}$$

$$x := *e$$

$$\{P\}$$

· Backwards, in a shorter form:

#### LOOKUP — EXAMPLE

- To comprehend the global rule we see an example. Let y, x and respectively points to two adjacent nodes in a list.
- Performing x := \*(x + 1) points x to its *next* node.

```
 \{ \langle \exists v :: (y+1 \mapsto x) * (x+1 \mapsto v) * (v+1 \mapsto \mathsf{nil}) \rangle \} 
 x := *(x+1) 
 \{ \langle \exists x_0 :: (y+1 \mapsto x_0) * (x_0+1 \mapsto x) * (x+1 \mapsto \mathsf{nil}) \rangle \}
```

- In this example  $R = (y + 1 \mapsto x_0) * (v + 1 \mapsto \mathsf{nil})$ .
- Reynolds says that this global rule is the most commonly used among the three. I personlly prefer the backwards rule, with algebraic properties...

## \_\_\_\_\_

**ALGEBRAIC PROPERTIES** 

#### COMMUTATIVITY AND ASSOCIATIVITY

$$P * Q \equiv Q * P$$
  
 $(P * Q) * R \equiv P * (Q * R)$   
 $P * emp \equiv P$ 

#### **DISTRIBUTIVITY**

$$(P \lor Q) * R \equiv (P * R) \lor (Q * R)$$
  
 $(P \land Q) * R \Rightarrow (P * R) \land (Q * R)$ 

With x not free in Q,

$$\langle \exists X : R : P \rangle * Q \equiv \langle \exists X : R : P * Q \rangle$$
  
 $\langle \forall X : R : P \rangle * Q \Rightarrow \langle \forall X : R : P * Q \rangle$ 

#### MONOTONICITY AND CURRYING

· Monotonicity:

$$\frac{P \Rightarrow P' \qquad Q \Rightarrow Q'}{P * Q \Rightarrow P' * Q'}$$

· Currying and uncurrying:

$$((P*Q)\Rightarrow R)\equiv (P\Rightarrow (Q\twoheadrightarrow R))$$

#### Rules regarding $\mapsto$ and $\mapsto$

• 
$$(e_0 \mapsto h_0) \land (e_1 \mapsto h_1) \equiv$$
  
 $(e_0 \mapsto h_0) \land (e_0 = e_1) \land (h_0 = h_1)$   
•  $(e_0 \mapsto h_0) * (e_1 \mapsto h_1) \Rightarrow e_0 \neq e_1$   
•  $emp \equiv \langle \forall x :: \neg (x \mapsto \bot) \rangle$   
•  $(e \mapsto h) \land P \equiv$   
 $(e \mapsto h) * ((e \mapsto h) \multimap P)$ 

#### **PURITY**

- P is pure if P h implies P h' for all h and h'.
- P is independent from heaps.
- $(P_0 \wedge P_1) \Rightarrow (P_0 * P_1)$  if  $P_0$  or  $P_1$  is pure.
- $(P_0 * P_1) \Rightarrow (P_0 \wedge P_1)$  if  $P_0$  and  $P_1$  are pure.
- $(P \land Q) * R \equiv (P * R) \land Q$  if Q is pure.
- $(P \twoheadrightarrow Q) \Rightarrow (P \Rightarrow Q)$  if  $P_0$  is pure.
- $(P \Rightarrow Q) \Rightarrow (P \twoheadrightarrow Q)$  if  $P_0$  and  $P_1$  are pure.

#### STRICTLY EXACTNESS

- P is strictly exact if it uniquely determines the heap. That is P h and P h' implies h = h'.
- emp is strictly exact;  $e \mapsto h$  is strictly exact;  $e \hookrightarrow h$  is not.
- $(Q * True) \land P \Rightarrow Q * (Q \rightarrow P)$  if Q is strictly exact.
  - The other direction  $(\Leftarrow)$  holds for all Q. See below.

- There are other important classes of assertions: precise, intuitionistic, supported, etc., which we cannot cover here.
- See Reynolds for more information.

#### **DERIVED PROPERTIES**

- Some useful properties —
- $Q * (Q \rightarrow P) \Rightarrow (Q * True) \land P$ .
- $R \Rightarrow Q \twoheadrightarrow (Q * R)$ .