# Programming Languages: Imperative Program Construction 8. Case Studies

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# 1 Faster Division

## **Quotient and Remainder**

· Recall the problem:

$$\begin{array}{l} \mathbf{con}\ A,B: Int\ \{0\leqslant A\land 0< B\}\\ \mathbf{var}\ q,r: Int\\ ?\\ \{A=q\times B+r\land 0\leqslant r< B\} \end{array}.$$

- Recall: recognising the postcondition as a conjunction, we use  $A=q\times B+r\wedge 0\leqslant r$  as the invariant and  $\neg \ (r< B)$  as the guard.
- The program we came up with:

$$\begin{array}{l} q,r:=0,A\\ \{A=q\times B+r\wedge 0\leqslant r,bnd:r\}\\ \mathbf{do}\ B\leqslant r\rightarrow q:=q+1\\ \qquad \qquad r:=r-B\\ \mathbf{od}\\ \{A=q\times B+r\wedge 0\leqslant r< B\} \end{array}.$$

- In each iteration of the loop, r is decreased by B.
- We can probably get a quicker program by decreasing r by ...  $2 \times B$ , when possible.
- What about decreasing r by  $4 \times B$ ,  $8 \times B$ ,... etc?

## 1.1 Division in $O(\log B)$ Time

Strategy...

$$\begin{array}{l} \mathbf{con}\ A,B:Int\ \{0\leqslant A\land 0< B\}\\ \mathbf{var}\ q,r,b,k:Int\\ \dots\\ \{0\leqslant k\land b=2^k\times B\land A< b\}\\ \dots\\ \{A=q\times b+r\land 0\leqslant r< b\land\\ 0\leqslant k\land b=2^k\times B,bnd:b\}\\ \mathbf{do}\ b\neq B\rightarrow \dots \mathbf{od}\\ \{A=q\times B+r\land 0\leqslant r< B\} \end{array}$$

## Generating $2^k \times B$

• It is easy to satisfy  $b = 2^k \times B \land A < b$ .

$$\begin{array}{l} b,k:=B,0\\ \mathbf{do}\ b\leqslant A\to b, k:=b\times 2, k+1\ \mathbf{od}\\ \{0\leqslant k\wedge b=2^k\times B\wedge A< b\} \end{array}$$

- What are the loop invariant and the bound?
- Initialisation for the next loop easily follows:

$$\begin{cases} 0 \leqslant k \wedge b = 2^k \times B \wedge A < b \} \\ q, r := 0, A \\ \{ A = q \times b + r \wedge 0 \leqslant r < b \wedge \\ 0 \leqslant k \wedge b = 2^k \times B \}$$

## Decreasing b

• What needs to be done before we decrement  $\boldsymbol{b}$  by half?

$$(A = q \times b + r \wedge 0 \leqslant r < b)[b \setminus b / 2]$$
  
$$\equiv (A = q \times (b / 2) + r \wedge 0 \leqslant r < b / 2)$$

• We can restore the invariant by  $q:=q\times 2...$ 

$$\begin{array}{l} (A = q \times (b \ / \ 2) + r \wedge 0 \leqslant r < b \ / \ 2)[q \setminus q \times 2] \\ \equiv A = (q \times 2) \times (b \ / \ 2) + r \wedge 0 \leqslant r < b \ / \ 2 \\ \Leftarrow A = q \times b + r \wedge 0 \leqslant r < b \ / \ 2 \wedge b = 2^k \times B \end{array}$$

- only if we already have r < b / 2!
- · That gives us one guarded command:

$$r < b / 2 \rightarrow q, b, k := q \times 2, b / 2, k - 1$$

## Decreasing b — The Other Case

- What about the case when  $b / 2 \le r < b$ ?
- · The task is to find a substitution such that

$$(A = q \times (b/2) + r \wedge 0 \leqslant r < b/2)[? \setminus ?]$$
  
$$\Leftarrow A = q \times b + r \wedge b/2 \leqslant r < b \wedge b = 2^k \times B$$

• Comparing  $0 \le r < b/2$  and  $b/2 \le r < b$ , one might want to try a substitution containing  $[r \setminus r - b / 2]$ .

$$(0 \leqslant r < b / 2)[r \backslash r - b / 2]$$

$$\equiv 0 \leqslant r - b / 2 < b / 2$$

$$\Leftarrow b / 2 \leqslant r < b \wedge b = 2^k \times B .$$

• Consider the former half of the expression:

$$(A = q \times (b/2) + r)[r \setminus r - b/2] \equiv A = q \times (b/2) + r - b/2 \equiv A = (q-1) \times (b/2) + r.$$

- Applying  $[q \setminus q \times 2 + 1]$  gives us back  $A = q \times b + r$ .
- Therefore, another guarded command:

$$b/2 \le r \to q, b, k, r := q \times 2 + 1, b/2, k - 1, r - b/2$$

## The Program

$$\begin{array}{l} \mathbf{con}\ A,B: Int\ \{0\leqslant A\land 0 < B\} \\ \mathbf{var}\ q,r,b,k: Int \\ b,k:=B,0 \\ \mathbf{do}\ b\leqslant A\to b,k:=b\times 2,k+1\ \mathbf{od} \\ \{0\leqslant k\land b=2^k\times B\land A < b\} \\ q,r:=0,A \\ \{A=q\times b+r\land 0\leqslant r< b\land \\ 0\leqslant k\land b=2^k\times B,bnd:b\} \\ \mathbf{do}\ b\neq B\to \\ \mathbf{if}\ r< b\ /\ 2\to q,b,k:=q\times 2,b\ /\ 2,k-1 \\ |\ b\ /\ 2\leqslant r\to q,b,k,r:=q\times 2+1,b\ /\ 2,k-1,r-b\ /\ 2 \\ \mathbf{fi} \\ \mathbf{od} \\ \{A=q\times B+r\land 0\leqslant r< B\} \end{array}$$

## 1.2 Alternative Programs

### **Existential Quantification**

- The variable *k* is used in the proofs, but not needed for computing the output.
- One can remove k and use existential quantification in the assertions instead.

$$\begin{array}{l} \mathbf{con}\ A,B: Int\ \{0\leqslant A\land 0< B\} \\ \mathbf{var}\ q,r,b: Int \\ b:=B \\ \mathbf{do}\ b\leqslant A\to b:=b\times 2\ \mathbf{od} \\ \{\langle \exists k: 0\leqslant k: b=2^k\times B\rangle \land A< b\} \\ q,r:=0,A \\ \{A=q\times b+r\land 0\leqslant r< b\land \\ \langle \exists k: 0\leqslant k: b=2^k\times B\rangle, bnd: b\} \\ \mathbf{do}\ b\neq B\to \\ \mathbf{if}\ r< b\ /\ 2\to q, b:=q\times 2, b\ /\ 2 \\ |\ b\ /\ 2\leqslant r\to q, b, r:=q\times 2+1, b\ /\ 2, \\ r-b\ /\ 2 \\ \mathbf{fi} \\ \mathbf{od} \\ \{A=q\times B+r\land 0\leqslant r< B\} \end{array}$$

- The variable k is called a "ghost variable" in Kaldewaij [Kal90].
- We can introduce k and remove it later. Or we can deal with existential quantification in the proofs.
   Which style do you prefer?

#### **Alternative Program**

Kaldewaij [Kal90] presented the following alternative. Do you prefer this program?

con 
$$A, B : Int \{0 \le A \land 0 < B\}$$
  
var  $q, r, b, k : Int$   
 $b := B$   
do  $b \le A \to b, k := b \times 2, k + 1$  od  
 $q, r := 0, A$   
do  $b \ne B \to$   
 $q, b, k := q \times 2, b / 2, k - 1$   
if  $r < b \to skip$   
 $|b \le r \to q, r := q + 1, r - b$   
fi  
od  
 $\{A = q \times B + r \land 0 \le r < B\}$ 

- The program has the advantage that we do not need to have  $b \ / \ 2$  in the guards.
- Note what the first assignment establishes:

$$\begin{cases} A = q \times b + r \wedge 0 \leqslant r < b \wedge \\ 0 \leqslant k \wedge b = 2^k \times B \wedge b \neq B \end{cases}$$
 
$$q, b, k := q \times 2, b / 2, k - 1$$
 
$$\{ A = q \times b + r \wedge 0 \leqslant r < 2 \times b \wedge \\ 0 \leqslant k \wedge b = 2^k \times B \}$$

#### A Historical Note

 The correctness of the if in the loop was actually a key example in Dahl [DDH72], one of the earliest book on structured programming:

$$\begin{cases} 0 \leqslant r < b \} \\ b := b \ / \ 2 \\ \textbf{if} \ \ r < b \ \rightarrow skip \\ \mid \ b \leqslant r \rightarrow r := r - b \\ \textbf{fi} \\ \{0 \leqslant r < b \} \\ \end{cases}$$

- Now we can prove its correctness by routine symbolic manipulation.
- In Dahl [DDH72], Dijkstra needed about one page of textual proof. It shows how much symbolic reasoning has advanced since then.

# 2 Binary Search Revisited

## **Binary Search**

- Given a sorted array of N numbers and a key, either locate the position where the key resides in the array, or report that the key does not present in the array, in  $O(\log N)$  time.
- A possible spec:

```
\begin{array}{l} \textbf{con } N,K:Int \; \{0 < N\} \\ \textbf{con } F: \textbf{array} \; [0..N) \; \textbf{of } Int \; \{F \; ascending\} \\ \textbf{var } l,r:Int \\ bsearch \\ \{F[l] = K \vee ...\} \end{array}.
```

# 2.1 The van Gasteren-Feijen Approach

- Van Gasteren and Feijen [vGF95] pointed a surprising fact: binary search does not apply only to sorted lists!
- In fact, they believe that comparing binary search to searching for a word in a dictionary is a major educational blunder.
- Their binary search: let  $\Phi$  be a predicate on two integers with some additional constraints to be given later:

```
 \begin{array}{l} \textbf{con} \ M, N: Int \ \{M < N \land \Phi \ M \ N \land ...\} \\ \textbf{var} \ l, r: Int \\ bsearch \\ \{M \leqslant l < N \land \Phi \ l \ (l+1)\} \end{array} .
```

#### **Invariant and Bound**

- Invariant:  $\Phi \ l \ r \wedge M \leqslant l < r \leqslant N,$  loop guard:  $l+1 \neq r.$
- Initialisation: l, r := M, N.
- Bound: r-l.
- For any m such that l < m < r, we have r m < r l and m l < r l. Therefore both l := m and r := m decrease the bound.

#### **Constructing the Loop Body**

• For l := m we calculate.

$$\begin{array}{l} (\Phi \ l \ r \wedge M \leqslant l < r \leqslant N \ |)[l \backslash m] \\ \equiv \Phi \ l \ m \wedge M \leqslant m < r \leqslant N \\ \Leftarrow \Phi \ l \ m \wedge M \leqslant l < m < r \leqslant N \end{array} .$$

- That l < m < r is our assumption. The leftover  $\Phi \ l \ m$  gives rise to a guarded command:  $\Phi \ l \ m \rightarrow l := m$ .
- The case with r := m is similar.

#### The Program Skeleton

$$\begin{cases} M < N \land \Phi \ M \ N \rbrace \\ l, r := M, N \\ \{ \Phi \ l \ r \land M \leqslant l < r \leqslant N, bnd : r - l \} \end{cases}$$
 
$$\begin{aligned} \text{do } l + 1 \neq r \rightarrow \\ \{ \dots \land l + 2 \leqslant r \} \\ m := \text{anything s.t. } l < m < r \\ \{ \dots \land l < m < r \} \end{cases}$$
 
$$\begin{aligned} \text{if } \Phi \ m \ r \rightarrow l := m \\ | \ \Phi \ l \ m \rightarrow r := m \end{aligned}$$
 
$$\begin{aligned} \text{fi} \end{aligned}$$
 
$$\end{aligned}$$
 
$$\begin{aligned} \text{od} \\ \{ M \leqslant l < N \land \Phi \ i \ (i+1) \} \end{aligned}$$

Note:  $m:=(l+r)\ /\ 2$  is a valid choice, thanks to the precondition that  $l+2\leqslant r.$ 

#### Constraints on $\Phi$

- But we need the if to be total.
- Therefore we demand a constrant on  $\Phi$ :

$$\Phi \ l \ r \Rightarrow \Phi \ l \ m \lor \Phi \ m \ r$$
, if  $l < m < r$ . (1)

• Some  $\Phi$  satisfying (1) (for F of appropriate type):

$$\begin{split} & - \Phi \ l \ r = F[l] \neq F[r], \\ & - \Phi \ l \ r = F[l] < F[r], \\ & - \Phi \ l \ r = F[l] \leqslant A \wedge A \leqslant F[r], \\ & - \Phi \ l \ r = F[l] \times F[r] \leqslant 0, \\ & - \Phi \ l \ r = F[l] \vee F[r], \\ & - \Phi \ l \ r = \neg \ (Q \ l) \wedge Q \ r. \end{split}$$

• Van Gasteren and Feijen believe that  $\Phi$  l  $r=F[l] \neq F[r]$  is a better example when explaining binary search.

# 2.2 Searching for a Key

- The case  $\Phi$  l  $r = \neg$   $(Q \ l) \land Q \ r$  is worth special attention.
- Choose Q i = K < F[i] for some K.
- Therefore  $\Phi$  l  $r = F[l] \leqslant K < F[r]$ .
- · That constitutes the binary search we wanted!
- The postcondition:  $M \leqslant l < N \land F[l] \leqslant K < F[l+1]$ .
- Note that we do not yet need F to be sorted!
- The algorithm gives you some l such that  $F[l] \leq K < F[l+1]$ . If there are more than one such l, one is returned non-deterministically.

#### Sortedness

- That F is sorted comes in when we need to establish that there is at most one l satisfying the postcondition.
- That is, either F[l] = K, or  $\neg \langle \exists i : M \leqslant i < N : F[i] = K \rangle$ .

#### The Program... Or A Part Of It

- Let  $\Phi$  l  $r = F[l] \leqslant K < F[r]$ .
- Processing the array fragment *F* [*a* . . *b*]:

$$\begin{array}{l} l, r := a, b \\ \{\Phi \ l \ r \wedge a \leqslant l < r \leqslant b, bnd : r - l\} \\ \mathbf{do} \ l + 1 \neq r \to \\ m := (l + r) \, / \, 2 \\ \mathbf{if} \ F[m] \leqslant K \to l := m \\ \mid K < F[m] \to r := m \\ \mathbf{fi} \\ \mathbf{od} \\ \{a \leqslant l < b \wedge F[l] \leqslant K < F[l + 1]\} \end{array}$$

- Note that F[a] and F[b] are never accessed.
- · This program is not yet complete....

#### Initialisation

- But wait.. to apply the algorithm to the entire array, we need the precondition  $\Phi$  0 N, that is  $F[0] \leqslant K < F[N]$ . Is that true? (We don't even have F[N].)
- One can rule out cases when the precondition do not hold (and also deal with empty array). E.g.

```
\begin{array}{l} \textbf{if } 0 = N \rightarrow present := False \\ \mid 0 < N \rightarrow \\ \textbf{if } K < F[0] \rightarrow present := False \\ \mid F[N-1] = K \rightarrow present, l := True, N-1 \\ \mid F[0] \leqslant K < F[N-1] \rightarrow \\ a, b := 0, N-1 \\ program \ above \\ p := f \ l = K \\ \textbf{fi} \\ \textbf{fi} \end{array}
```

## **Pseudo Elements**

- But there is a better way... introduce two pseudo elements!
- Let  $F[-1] = -\infty$  and  $F[N] = \infty$ .
- Initially,  $\Phi$  0 N is satisfied.
- In the code, F[-1] and F[N] are never accessed. Therefore we do not actually have to represent them!
- We need to be careful interpreting the result, once the main loop terminates, however.

#### The Program (1)

```
Let \Phi \ l \ r = F[l] \leqslant K < F[r].

con N, K : Int \ \{0 \leqslant N\}

con F : \mathbf{array} \ [0..N) of Int \ \{F \ ascending \land F[-1] = -\infty \land F[N] = \infty\}

var l, r : Int

var p : Bool

l, r := -1, N

\{\Phi \ l \ r \land -1 \leqslant l < r \leqslant N, bnd : r - l\}

do l + 1 \neq r \rightarrow

m := (l + r) / 2

if F[m] \leqslant K \rightarrow l := m

l \ K < F[m] \rightarrow r := m

fi

od

\{-1 \leqslant l < N \land F[l] \leqslant K < F[l + 1]\}
```

#### The Program (2)

$$\begin{aligned} & \{ 0 \leqslant l < N \wedge F[l] \leqslant K < F[l+1] \} \\ & \mathbf{if} - 1 = l \rightarrow p := False \\ & | \ 0 \leqslant l \quad \rightarrow p := F[l] = K \\ & \mathbf{fi} \\ & \{ p = \langle \exists i : 0 \leqslant i < N : F[i] = K \rangle \wedge \\ & p \Rightarrow F[l] = K \} \end{aligned}$$

#### **Alternative Program**

- Kaldewaij [Kal90, Sec. 6.3] derived an alternative program that introduces only  $F[N]=\infty$  (but not  $F[-1]=-\infty$ ), while requiring the array to be nonempty.
- The main loop is the same. It is only post-loop interpretation that is different.

# 2.3 Searching with Premature Return

#### A More Common Program

- Recall that Bentley [Ben86, pp. 35-36] proposed using binary search as an exercise.
- Bentley's solution can be rephrased below:

```
\begin{array}{l} l,r,p:=0,N-1,False\\ \mathbf{do}\ l\leqslant r\rightarrow\\ m:=\left(l+r\right)/2\\ \mathbf{if}\ F[m]< K\rightarrow l:=m+1\\ \mid\ F[m]=k\rightarrow p:=True;break\\ \mid\ K< F[m]\rightarrow r:=m-1\\ \mathbf{fi}\\ \mathbf{od} \end{array}
```

#### A More Common Program

I'd like to derive it, but

- it is harder to formally deal with break.
  - Still, Bentley employed a semi-formal reasoning using a loop invariant to argue for the correctness of the program.
- To relate the test F[m] < K to l := m+1 we have to bring in the fact that F is sorted earlier.

#### Comparison

- The two programs do not solve exactly the same problem (e.g. when there are multiple Ks in F).
- Is the second program quicker because it assigns l and r to m+1 and m-1 rather than m?
  - l := m+1 because F[m] is covered in another case:
  - r:=m-1 because a range is represented differently.
- Is it quicker to perform an extra test to return early?
  - When K is not in F, the test is wasted.
  - Rolfe [Rol97] claimed that single comparison is quicker in average.
  - Knuth [Knu97, Exercise 23, Section 6.2.1]: single comparison needs  $17.5 \lg N + 17$  instructions, double comparison needs  $18 \lg N 16$  instructions.

# References

- [Ben86] J. L. Bentley. *Programming Pearls*. Addison-Wesley, 1986.
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