



Dual-polarization phase shift processing with the Python ARM Radar Toolkit

The Python ARM Radar Toolkit

github.com/ARM-DOE/pyart



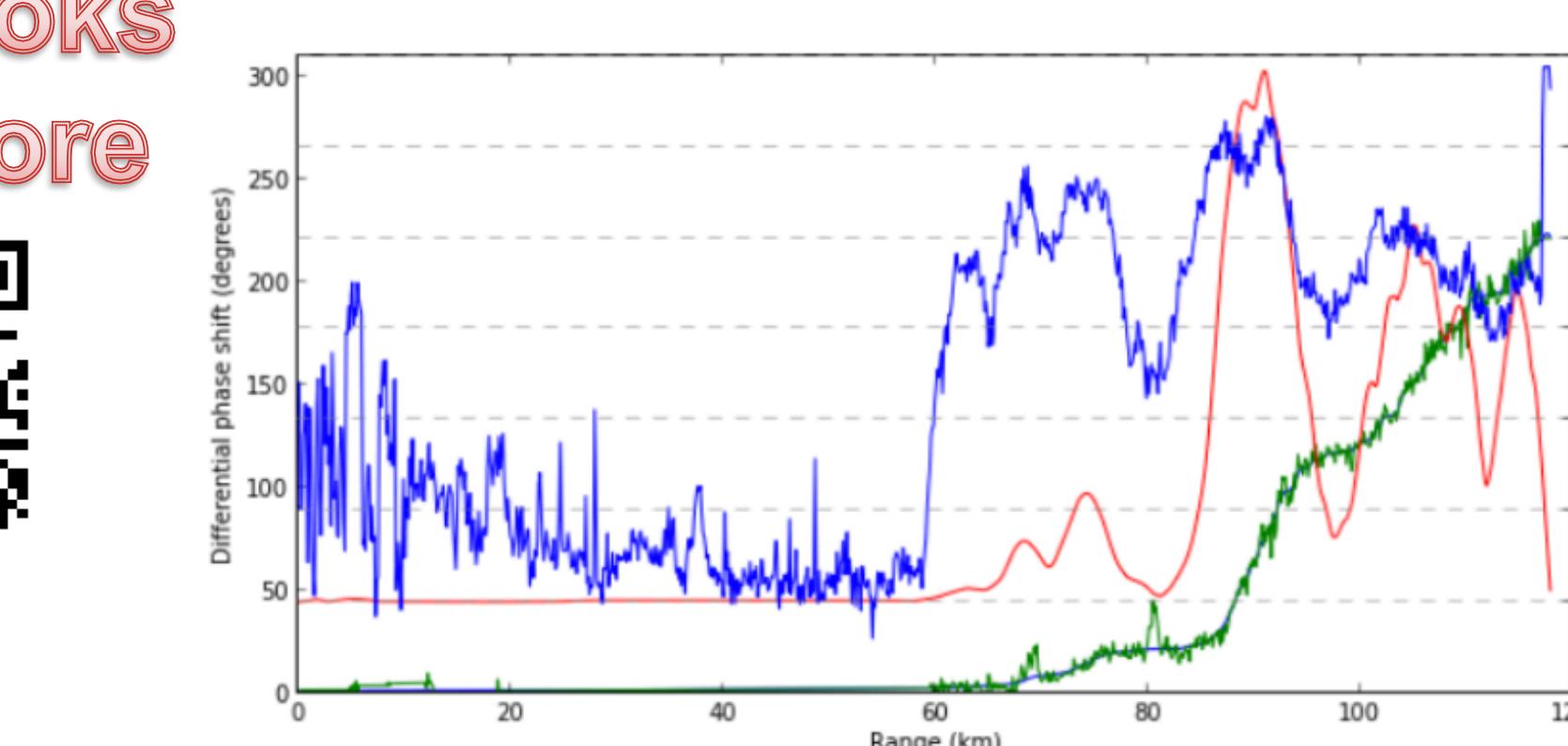
- Py-ART (Helmus and Collis 2016) uses a moderately complex data model which closely mirrors the CF-Radial community file format.
- It makes heavy use of Python dictionaries to form a self-describing radar object.
- Community codebase on GitHub, main fork is DoE maintained and moderated.

Specific Differential Phase, Why So Special?

- From a measurement perspective** Specific differential phase (K_{DP}) is the rate of change of phase lag between the horizontal and vertical polarized pulses.
- From a microphysical perspective** it is the phase lag between the propagating waves due to the anisotropy of the refractive index of the medium.
- It is a measure of RWC that is robust to calibration and liquid path attenuation.
- However, careful processing is required as K_{DP} is not measured, rather its integral, Ψ_{DP} which includes artifacts.

$$\Psi_{DP} = \Phi_{DP} + \delta + NBF$$

Notebooks
And more



Helmus, J.J. & Collis, S.M., (2016). The Python ARM Radar Toolkit (Py-ART), a Library for Working with Weather Radar Data in the Python Programming Language. Journal of Open Research Software. 4(1), p.e25. DOI: <http://doi.org/10.5334/jors.119>

Timothy J. Lang, David A. Ahijevych, Stephen W. Nesbit, Richard E. Carbone, Steven A. Rutledge, and Robert Cifelli, 2007: Radar-Observed Characteristics of Precipitating Systems during NAME 2004. J. Climate, 20, 1713–1733. doi: <http://dx.doi.org/10.1175/JCLI4082.1>

Maesaka, T., Iwanami, K. and Maki, M., 2012: "Non-negative KDP Estimation by Monotone Increasing PHIDP Assumption below Melting Layer". The Seventh European Conference on Radar in Meteorology and Hydrology.

Giangrande, S.E., McGraw, R., Lei, L., 2013. An Application of Linear Programming to Polarimetric Radar Differential Phase Processing. Journal of Atmospheric and Oceanic Technology 30, 1716–1729. doi:10.1175/JTECH-D-12-00147.1

Thurai, M., Huang, G.J., Bringi, V.N., Randue, W.L., Schönhuber, M., 2007. Drop Shapes, Model Comparisons, and Calculations of Polarimetric Radar Parameters in Rain. J. Atmos. Oceanic Technol. 24, 1019–1032. doi:10.1175/JTECH2051.1

Leinonen, J., High-level interface to T-matrix scattering calculations: architecture, capabilities and limitations, Opt. Express, vol. 22, issue 2, 1655-1660 (2014), doi: 10.1364/OE.22.001655.



CSU/Bringi:

Maesaka:

Giangrande LP:

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Timothy Lang³ and Kirk North⁴

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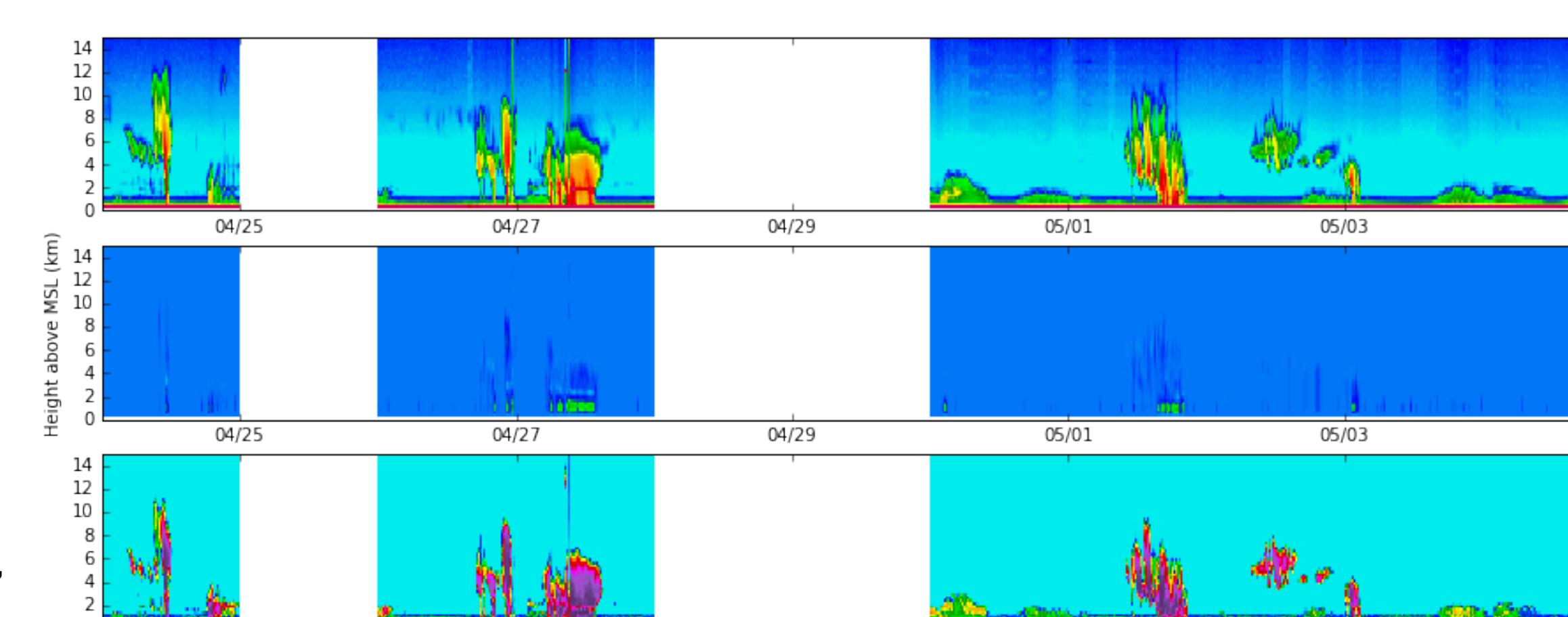
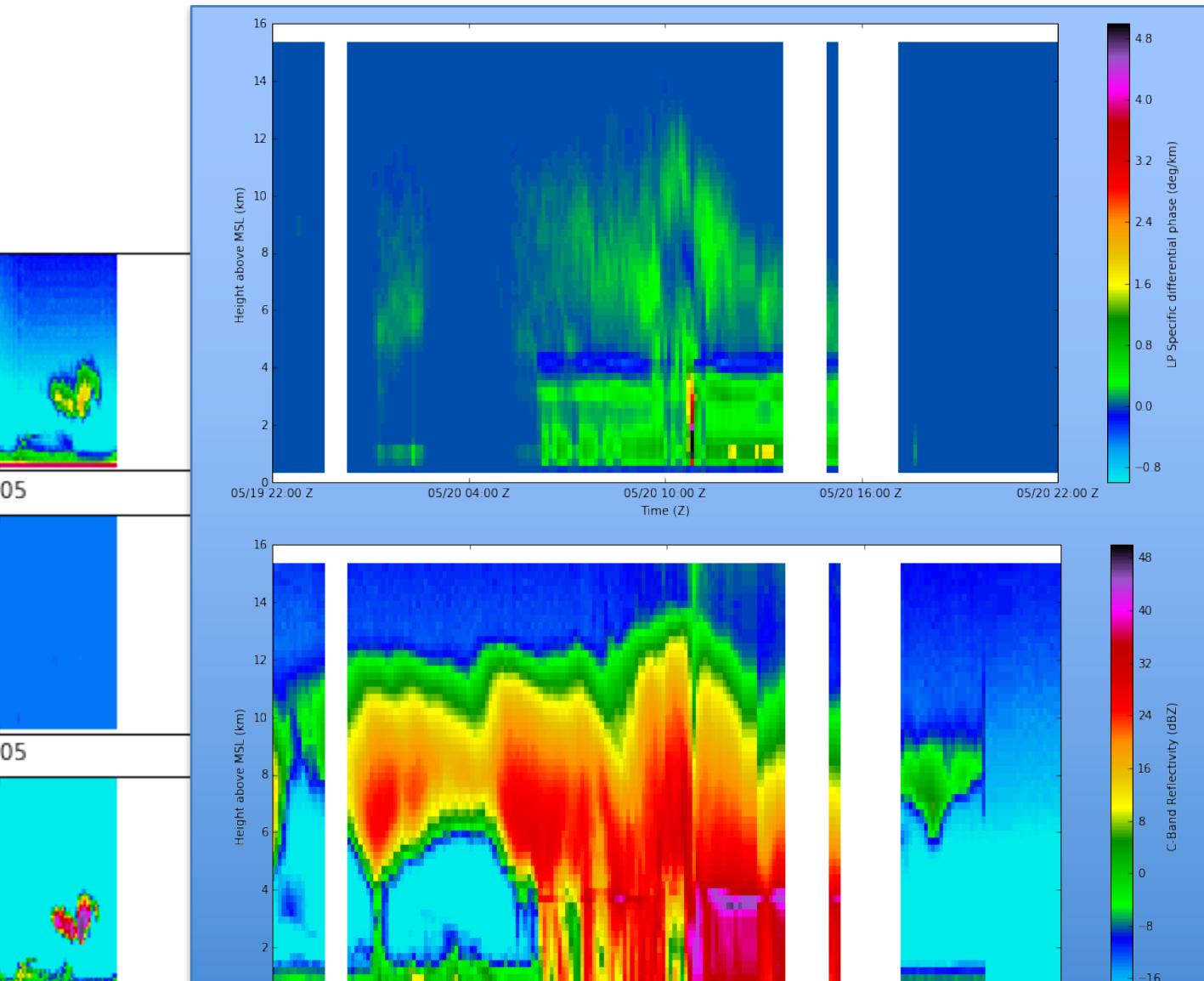
The Py-ART ecosystem has three Open Source K_{DP} retrieval techniques

One site for disdrometric measurements is never enough

Tests which were performed with “out of the box” configuration and result are initial.
The FIR Bringi technique is the quickest and easiest. Performs well at $K_{DP} > 0.5$.
The fully variational Maesaka technique works well but shows some stability issues.
The LP method is computationally costly and is difficult to install but shows great promise at low K_{DP}

- Lang et al 2007. Based on a finite impulse response filter applied to dif. phase. in a moving adjustable-length window.
- K_{DP} calculated using moving linear fit. Length based on Z_e
- Part of the CSU_RadarTools package.
- Big thanks to Brenda Dolan, Paul Hein and Brody Fuchs!
- Variational technique based on Maesaka (2012) which uses a cost function involving the square of the K_{DP} thus ensuring monotonicity.
- Cost function is minimized using a nonlinear conjugate gradient algorithm.
- Many options, comes default in Py-ART, easy to use.

- Uses Linear Programming to ensure monotonicity over a range of gates via an upwards bound, Giangrande et al (2013). Thanks to Scott for all his help!
- Uses reflectivity to force increase gradient.
- Originally used PyGLPK, now CyLP (20x improvement in speed). Involves poorly supported 3rd party dependencies.
- K_{DP} calculated from processed phase using a constant length sobel filter.

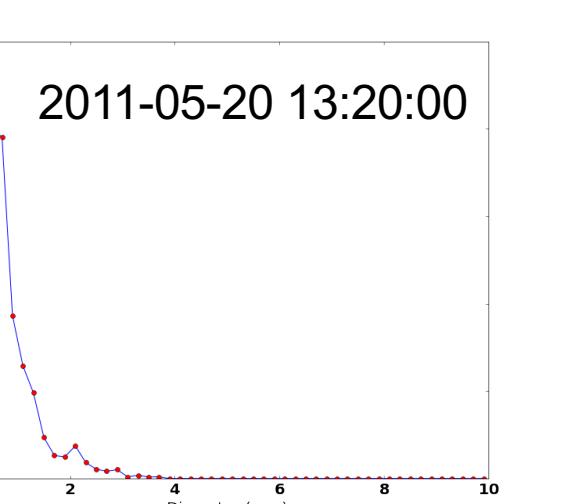
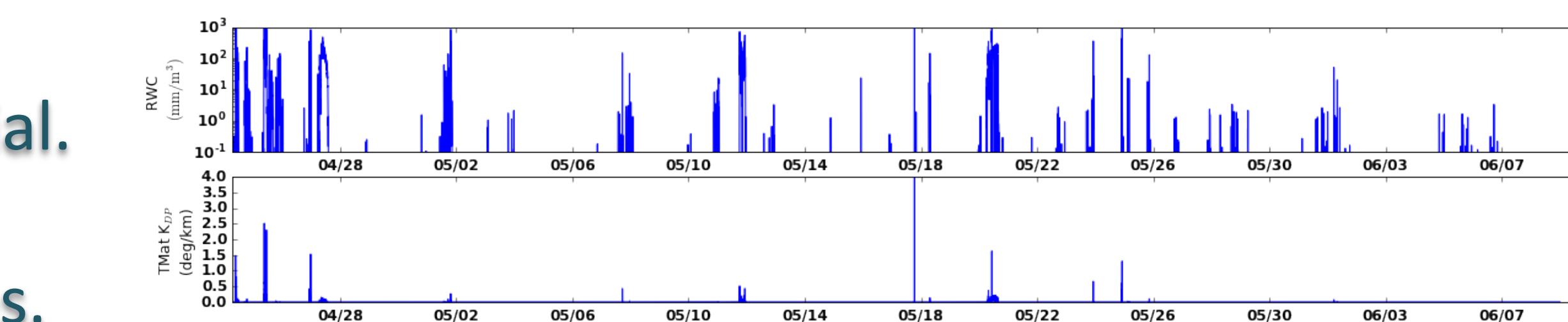


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T-Matrix

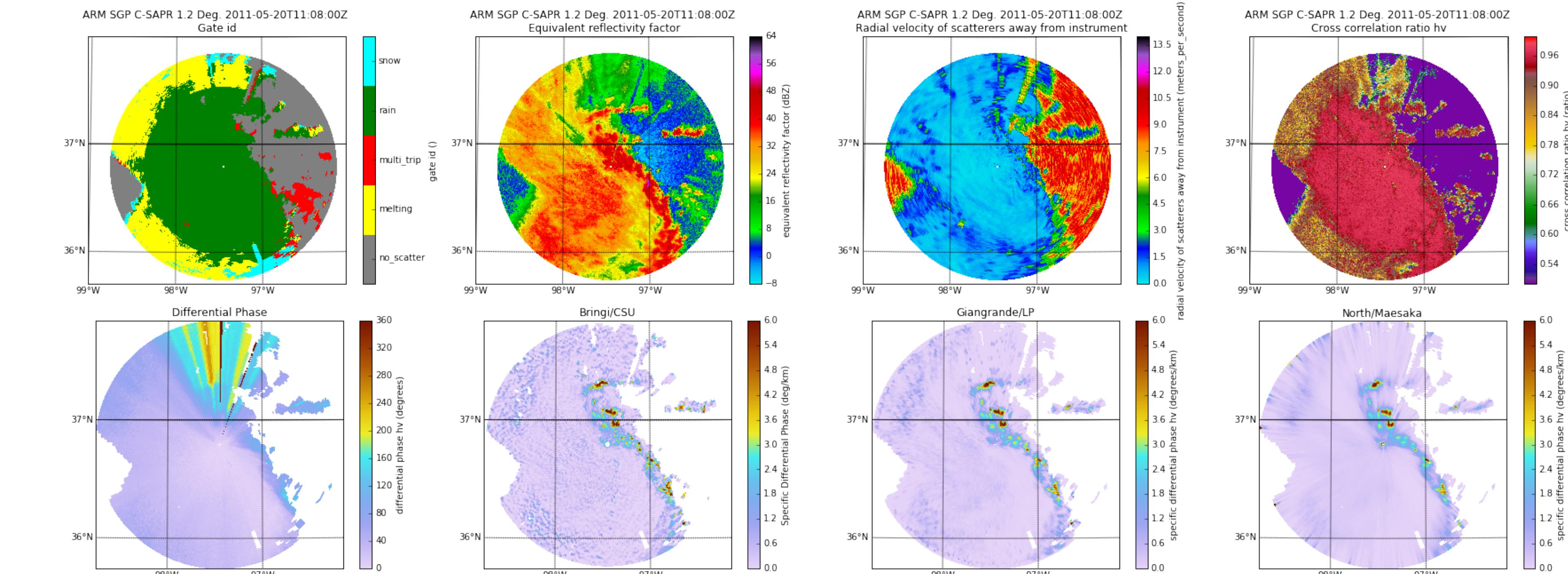


- Z_e K_{DP} A and Z_{DR} were calculated using PyTMatrix from 2DVD data collected during MC3E. Leinonen 2014.
- 72,000 DSDs used AR(D) from Thurai et al 2007



Processing

4218 volumes.. Only 221 matches



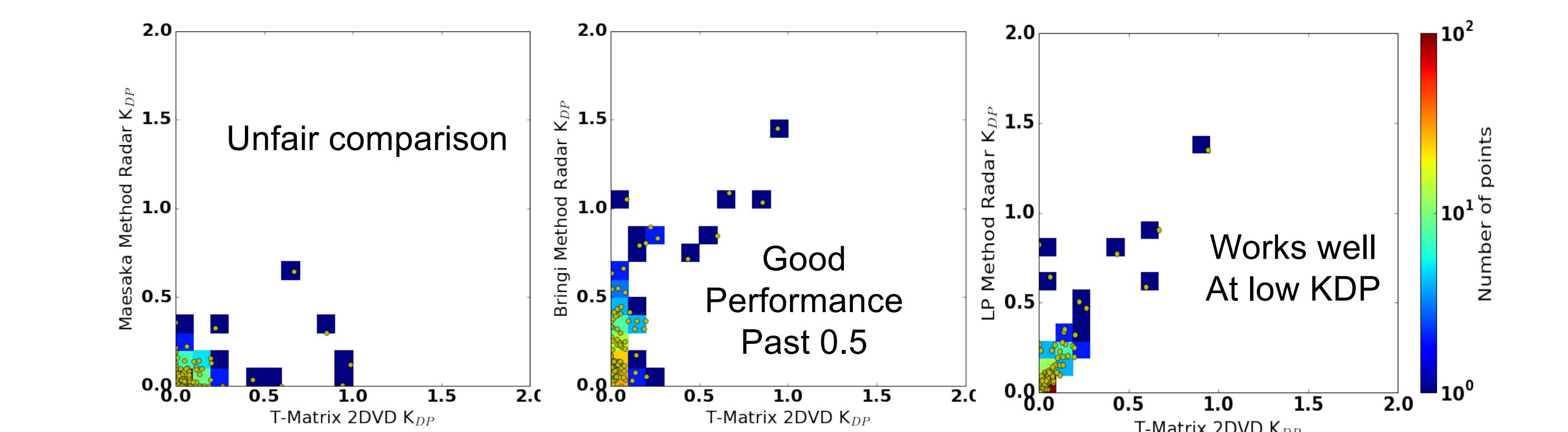
Future Work

Use 2DVD AR(D)
MORE Disdrometers! Use
NASA P2s.

Better configuration for
Maesaka.

Filter clutter for better
performance.

Very Initial Results



Special thanks to
Nitin Bharadwaj (PNNL) for engineering
the radars During MC3E and Mary-
Jane Bartholomew for the 2DVD