

10.18

Math 403/503

October 2022

## 1 Generalized Eigenvectors

Our schedule is as follows: This is week 9 so it's the last week of material in this "unit". Next week is quiz week. This means on Tuesday we will have class and do a catch up/review. On Wednesday the take-home quiz will be released. There will be no class on Thursday. The quiz will be due Monday night.

Recall we have a goal of, given an operator  $T$ , decomposing  $V$  into invariant subspaces where  $T$  behaves quite simply. The best situation is when  $V = E(\lambda_1, T) + \dots + E(\lambda_m, T)$  where the terms are a direct sum. In this case  $T$  acts as a scalar on each of these subspaces and overall  $T$  acts as a diagonal matrix with respect to the basis of eigenvectors. But this is not always the case (more on this later... chapters 6 and 7). For now we will jump forward to chapter 8 where we show generalized eigenspaces fix this problem at least if we are over  $C$ .

Recall  $E(\lambda, T) = \text{null}(T - \lambda I)$ . We now define  $G(\lambda, T) =$  the union over  $j$  of the null space of  $[(T - \lambda I)^j]$ . This is called the generalized eigenspace of  $T$  corresponding to  $\lambda$ . Any  $v \in G(\lambda, T)$  other than 0 is called a generalized eigenvector of  $T$  corresponding to  $\lambda$ . Note  $E(\lambda, T)$  is a proper subspace of  $G(\lambda, T)$ .

**Lemma:**  $G(\lambda, T)$  is a subspace of  $V$  and it is  $T$  - invariant.

**Proof Sketch:** Note that  $\text{null}(T - \lambda I)$  is a proper subspace of  $\text{null}(T - \lambda I)^2$  which is a proper subspace of... this is because  $(T - \lambda I) = 0 \rightarrow (T - \lambda I)(T - \lambda I) = 0 \rightarrow \dots$  in this chain only at the most  $n$  of the proper subspace symbols can be proper inclusions, where  $n = \dim V$ . In fact it turns out the union over  $j$  going from 1 to infinity of the null space of  $(T - \lambda I)^j = \text{null}[(T - \lambda I)^n]$  so  $G(\lambda, T)$  is a subspace. For invariance assume  $(T - \lambda I)^2 v = 0$  we will show  $(T - \lambda I)^2 T v = 0$ .

$$\begin{aligned} & (T - \lambda I)^2 T v \\ &= (T^2 - 2\lambda T + \lambda^2 I) T v \\ &= (T^3 - 2\lambda T^2 + \lambda^2 T) v \\ &= T(T^2 - 2\lambda T + \lambda^2 I) v \\ &= T 0 \\ &= 0 \end{aligned}$$

The same goes for all powers. So  $\text{null}((T - \lambda I)^j)$  is  $T$ -invariant for any  $j$  for  $G(\lambda, T)$  is  $T$ -invariant.

$$\text{Example: } A = \begin{bmatrix} 2 & 3 & 4 \\ 0 & 5 & 1 \\ 0 & 0 & 5 \end{bmatrix}, E(2, T) = \text{null} \begin{bmatrix} 0 & 3 & 4 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix} = \dots \text{span} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$G(2, T) = ?$$

$$\text{null} \begin{bmatrix} 0 & 3 & 4 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 0 & 3 & 4 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix} = \text{null} \begin{bmatrix} 0 & 9 & 15 \\ 0 & 9 & 6 \\ 0 & 0 & 9 \end{bmatrix} = \dots \text{span} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$G(2, T) = E(2, T) = \text{span} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$E(5, T) = \text{null} \begin{bmatrix} -3 & 3 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \dots = \text{span} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$G(5, T) = ?$$

$$\text{null} \begin{bmatrix} -3 & 3 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} -3 & 3 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \text{null} \begin{bmatrix} 9 & -9 & -9 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \text{null} \begin{bmatrix} 1 & -1 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} y + \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} z = \text{span} \left( \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right)$$

What about  $\text{null}(A - SI)$ ?

$$\text{null} \begin{bmatrix} 9 & -9 & -9 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} -3 & 3 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \text{null} \begin{bmatrix} -27 & 27 & 27 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \text{span} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$G(5, T) = \text{span} \left( \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right). \text{ So } V = C^3 = \text{the direct sum of } E(2, T) \text{ and}$$

$E(5, T)$ . So we aim to prove that for any  $T$  over a finite dimensional vector space,  $V =$  the direct sum of  $G(\lambda_1, T) \dots G(\lambda_m, T)$  and furthermore show  $T$  has a very simple action on its  $G(\lambda_j, T)$ 's so this will complete the study of  $T$ .