

10.13 Notes

Math 403/502

October 2022

1 Introduction

Calendar says week 10 is the next quiz. He is considering making it week 11.

Theorem: Let V be a finite dimensional and $L\epsilon(V, V)$. Then there is a basis of V in which T has a diagonal matrix if and only if, $E(T, \lambda_1)$ direct summed with all the other $E(T, \lambda_n)$ terms is equal to V where $\lambda_1, \dots, \lambda_n$ are distinct eigenvalues of T .

Proof: \rightarrow Suppose v_1, \dots, v_n is a basis of V and T is diagonal with respect to this basis. Then $T(v_j) = d_j v_j$ for all j . This means that the entries along the diagonal (d_j 's) are all eigenvalues and the v_j 's are all eigenvectors of T . Thus, each v_j lies in some eigenspace $E(T, d_j)$. Thus, the direct sum of the E 's mentioned above contains a spanning set so itself spans V .

\leftarrow Suppose $\lambda_1, \dots, \lambda_n$ are the eigenvalues of T and $E(T, \lambda_1)$ direct summed with all the other $E(T, \lambda_n)$ terms is equal to V . Then we can choose bases for each $E(T, \lambda_j)$ and combine these bases together to get a basis v_1, \dots, v_n consisting entirely of eigenvectors of T . Then with respect to this basis, $T v_j$ is always a multiple of v_j , so the matrix of T is diagonal. QED.

Recall we talked about invariant subspaces and how we might wish to breakdown V into several invariant subspaces on which T is very simple to understand. In the case of the theorem above we have succeeded fully, because $E(T, \lambda_j)$ is an invariant subspace and more strongly T is just scalar multiplication: $T(v) = \lambda_j v$ on that space! The net thing to worry about is what to do when this isn't satisfied and the $E(T, \lambda_j)$'s don't sum up to V ...

Corollary: If T is an operator on V and T has $n = \dim V$ distinct eigenvalues, then T has a basis in which it is diagonal.

Proof: Each $E(T, \lambda_j)$ contributes at least 1 dimension to the sum. With n summands, the sum is n -dimensions or all of V . QED.

Example: $T(x, y) = (x + y, y)$, T has matrix $\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$. We know that $\lambda = 1$

is the only eigenvalue! We find $v = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ is the only eigenvector (up to scalar multiple). $E(T, 1) = \text{span}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) \neq V$.

Example: Let $T(x, y, z) = (2x + y, 5y + 3z, 8z)$. T has matrix $\begin{bmatrix} 2 & 1 & 0 \\ 0 & 5 & 3 \\ 0 & 0 & 8 \end{bmatrix}$.

We know $\lambda_1 = 2, \lambda_2 = 5, \lambda_3 = 8$. We know it will be diagonalizable by corollary.

To do so: $E(T, 2) = \text{null} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 3 & 3 \\ 0 & 0 & 6 \end{bmatrix}$. Then we compute the null space of this

and get it to be $\begin{bmatrix} x \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ $x = \text{span} \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right)$. $E(T, 5) = \text{null} \begin{bmatrix} -3 & 1 & 0 \\ 0 & 0 & 3 \\ 0 & 0 & 3 \end{bmatrix}$. Then

we compute the null space of this and get it to be $\begin{bmatrix} 1/3y \\ y \\ 0 \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1 \\ 0 \end{bmatrix} y = \text{span}$

$\left(\begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} \right)$. $E(T, 8) = \text{null} \begin{bmatrix} -6 & 1 & 0 \\ 0 & -1 & 3 \\ 0 & 0 & 0 \end{bmatrix}$. Then we compute the null space of this

and get it to be $\begin{bmatrix} 1/6z \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \\ 6 \end{bmatrix} z = \text{span} \left(\begin{bmatrix} 1 \\ 6 \\ 6 \end{bmatrix} \right)$. So in basis $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 6 \\ 6 \end{bmatrix}, T$

has matrix $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 8 \end{bmatrix}$. What happens when things go wrong? When it isn't diagonalizable?

Example: $T = \begin{bmatrix} 2 & 3 & 4 \\ 0 & 5 & 1 \\ 0 & 0 & 5 \end{bmatrix}$. We know $\lambda_1 = 2, \lambda_2 = 5$ are the eigenvalues.

$E(T, 2) = \text{null} \begin{bmatrix} 0 & 3 & 4 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix} = \text{span} \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right)$. $E(T, 5) = \text{null} \begin{bmatrix} -3 & 3 & 4 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} = \text{span}$

$\left(\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right)$. So the direct sum of $E(T, 2)$ and $E(T, 5) \neq V$. Thankfully there is a

"generalized eigenvector" it lies in $\text{null} \begin{bmatrix} -3 & 3 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$. It further has the property

that $(T - 5I)v_3 = v_2$. It is $v_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

$\begin{bmatrix} -3 & 3 & 4 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} = v_2$. In the basis $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, T$ has matrix:

$\begin{bmatrix} 2 & 0 & 0 \\ 0 & 5 & 1 \\ 0 & 0 & 5 \end{bmatrix}$. Because of the equation above it is nearly diagonalizable.