

Continuous L2 approximation

Wednesday, October 23, 2024 9:46 AM

Class 25: October 23, 2024

Recall: Last time, we discussed a general way to frame a discrete approximation problem: Given n data points (x_i, y_i) , can we find a model $p(x) = a_0 \phi_0(x) + a_1 \phi_1(x) + \dots + a_m \phi_m(x)$ such that it minimizes some norm $\|p(x) - y\|$? We then discussed the case where the norm being minimized is the euclidean norm (2-norm). We called this "Discrete Least Squares":

$$\min q(a) = \min \sum_{i=0}^{n-1} (p(x_i) - y_i)^2 = \min \|M a - y\|_2^2$$

We then realized that the function $q(a) = \|M a - y\|_2^2$ being minimized is a concave up quadratic. We can write its formula using inner products and matrix-vector algebra as:

$$q(a) = a^T G a - 2b^T a + c$$

With $G = (M^T)^* M$ the SPS Gramian matrix, $b = M^T y$ and $c = y^T y$ (constant). If M has L columns (trivial nullspace), then G is SPD and invertible, and q has a unique minimizer at the one value of a such that:

$$\begin{aligned} \text{Grad } q(a) &= 2(G a - b) = 0 \\ G a &= b \\ (M^T)^* M a &= (M^T)^* y \end{aligned}$$

We called this linear system the "Normal Equations", and its solution a_{LS} is the vector of coefficients of our model of best fit (in the LS sense), $p = M^* a_{LS}$.

Finally, we mentioned that even if G is invertible, it will sometimes be very ill-conditioned (e.g. polynomial model using monomial basis). So, stabler methods to solve this problem involve some factorization of M instead of solving $G a = b$.

Today, I will briefly explain one of these methods, show a demo, and then we will move on to another problem of function approximation: continuous L2 approximation.

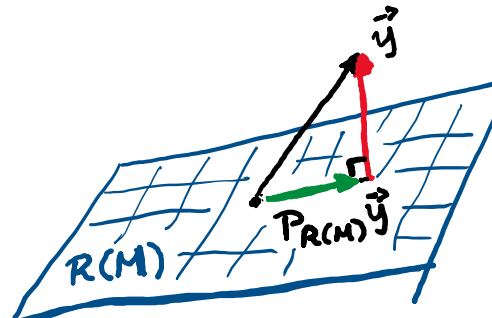
Recall this interpretation of DHS:

$\min \|M \vec{a} - \vec{y}\|^2$

→ Solve $M \vec{a} = \text{Proj}_{R(M)} \vec{y}$

Algorithm Idea:

$M = Q R$
 $n \times m \quad n \times m \quad m \times m$
 $\uparrow \quad \uparrow$
 unitary upper
 $\{q_1, q_2, \dots, q_m\}$ triang
 orth basis of $R(M)$

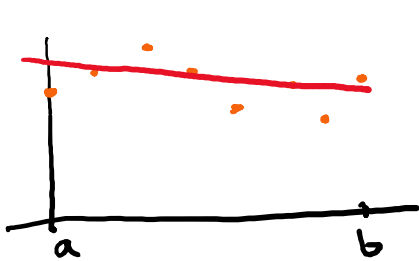


$M a = \text{Proj}_{R(M)} y$
 \downarrow
 $Q R a = Q Q^T y$
 \updownarrow
 SOLVE: $R \vec{a} = Q^T \vec{y}$

Generalizations: (FOR MORE, FINAL PROJECTS!)

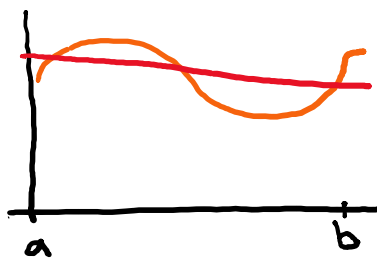
- Weighted LS: $\min \sum_{i=0}^{n-1} \omega_i (p(x_i) - y_i)^2$
- Regularized LS: $\min \{ \|p - y\|^2 + \underbrace{\lambda \|P a\|}_{\text{penalty}} \}$
 - Ridge regression / Shrinkage
 - Tikhonov
 - LASSO

CONTINUOUS FUNCTION APPROX:



DISCRETE APPROX ✓

HOW? FORM $\vec{p} = p(x_i)$,
Find coeffs a_0, \dots, a_m to
minimize $\|\vec{p} - \vec{y}\|$.



CONT. APPROX ?

$$\min \|p - f\|$$

What does $\|f\|$ mean?

$$f \in C[a, b],$$

$$\|f\|_2 = \left(\int_a^b f(x)^2 dx \right)^{1/2} \rightarrow L^2 \text{ norm.}$$

space
 $L^2([a, b])$

$$\langle f, g \rangle = \int_a^b f(x)g(x) dx$$

inner product sp.
(Hilbert).

- Find \vec{a} such that $\|f - p\|^2$ is minimized.

$$\|f\|_{w,2} = \left(\int_a^b f(x)^2 w(x) dx \right)^{1/2} \quad (w(x) \geq 0, \text{ integrable.})$$

$$\langle f, g \rangle_w = \int_a^b f(x)g(x) w(x) dx \quad \text{Hilbert sp.}$$

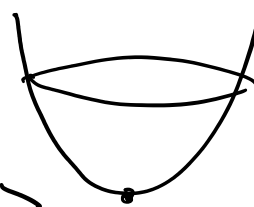
- $\|f\|_\infty = \sup_{x \in [a, b]} \{ |f(x)| \} \rightarrow \text{"minimax"} L^\infty$

- $\|f\|_p = \left(\int_a^b f(x)^p dx \right)^{1/p} L^p$

L^2 :

$$q(\vec{a}) = \int_a^b \left(\sum_{j=0}^{m-1} a_j x^j - f(x) \right)^2 dx$$

$$= \left\langle \sum_{i=0}^{m-1} a_i x^i - f, \sum_{j=0}^{m-1} a_j x^j - f \right\rangle$$



$$q(\vec{a}) = \underset{a, b}{a^T G a} - 2 \underset{b}{b^T a} + c$$

DISC
|
-

$$q(\vec{a}) = \mathbf{a}^T \mathbf{G} \mathbf{a} - 2 \mathbf{b}^T \mathbf{a} + c$$

DISC

$$G(i, j) = \langle x^i, x^j \rangle = \int_a^b x^{i+j} dx$$

$$M(i, i)^T M(i, j)$$

$$b(i) = \langle x^i, f \rangle = \int_a^b x^i f(x) dx$$

$$M(i, i)^T y$$

$$c = \langle f, f \rangle = \int_a^b f(x)^2 dx$$

$$y^T y$$

Powers of x (poly approx) \rightarrow Hilbert met.

$\{1, x, x^2, x^3, \dots, x^{m-1}\} \rightarrow$ LI but poorly cond.

$$G(i, j) = \langle \phi_i, \phi_j \rangle$$

$\langle \phi_i, \phi_j \rangle = 0$ if $i \neq j$ ORTHOGONAL

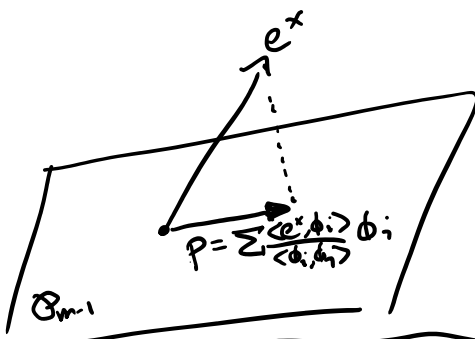
and $\langle \phi_i, \phi_i \rangle = 1$ — ORTHONORMAL.

ORTHOGONAL BASIS $\{\phi_0, \phi_1, \dots, \phi_{m-1}\}$

$$\mathbf{G} \mathbf{a} = \mathbf{b} \quad \begin{bmatrix} \langle \phi_0, \phi_0 \rangle & 0 & 0 & \dots & 0 \\ 0 & \langle \phi_1, \phi_1 \rangle & 0 & \dots & 0 \\ \vdots & 0 & \langle \phi_2, \phi_2 \rangle & \dots & 0 \\ 0 & 0 & \vdots & \ddots & \langle \phi_{m-1}, \phi_{m-1} \rangle \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_{m-1} \end{bmatrix} = \begin{bmatrix} \langle f, \phi_0 \rangle \\ \langle f, \phi_1 \rangle \\ \vdots \\ \langle f, \phi_{m-1} \rangle \end{bmatrix}$$

$$a_j = \frac{\langle f, \phi_j \rangle}{\langle \phi_j, \phi_j \rangle}, \quad p(x) = \sum_{j=0}^{m-1} \frac{\langle f, \phi_j \rangle}{\langle \phi_j, \phi_j \rangle} \phi_j(x)$$

$$a_j = \frac{\int_a^b f(x) \phi_j(x) dx}{\int_a^b \phi_j(x)^2 dx}$$



$$\text{ERROR } \|f - p\|^2 = \sum_{j=m}^{\infty} \left(\frac{\langle f, \phi_j \rangle}{\langle \phi_j, \phi_j \rangle} \right)^2$$

$$\text{ERROR } \|f - p\|^2 = \sum_{j=m}^n \left(\frac{\langle f, \phi_j \rangle}{\langle \phi_j, \phi_j \rangle} \right)$$

Polynomial approx, $[-1, 1]$, $w(x) \equiv 1$

Find orthogonal basis of polynomials
 $\{P_0(x), P_1(x), P_2(x), \dots\}$ \rightarrow LEGENDRE

spans the same as
 $\{1, x, x^2, x^3, \dots\}$

GRAM-SCHMIDT:

$$P_0(x) = 1$$

$$P_1(x) = x - \frac{\langle x, 1 \rangle}{\langle 1, 1 \rangle} \cdot 1$$

$$= x - \left(\frac{\int_{-1}^1 x \, dx}{\int_{-1}^1 1 \, dx} \right) 1 = \textcircled{x}$$

$$P_2(x) = x^2 - \frac{\langle x^2, x \rangle}{\langle x, x \rangle} x - \frac{\langle x^2, 1 \rangle}{\langle 1, 1 \rangle} 1$$

$$\frac{\int_{-1}^1 x^3 \, dx}{\int_{-1}^1 x^2 \, dx}$$

$$\left[\frac{\int_{-1}^1 x^2 \, dx}{\int_{-1}^1 1 \, dx} \right]$$

$$\boxed{P_2(x) = x^2 - \frac{1}{3}}$$

$$\rightarrow (2/3)/2$$

$$P_3(x) = x^3 - \frac{\langle x^3, x^2 - 1/3 \rangle}{\langle x^2 - 1/3, x^2 - 1/3 \rangle} (x^2 - 1/3) - \frac{\langle x^3, x \rangle}{\langle x, x \rangle} x - \frac{\langle x^3, 1 \rangle}{\langle 1, 1 \rangle} 1$$