

Continuous L2 approximation

Wednesday, October 23, 2024 9:46 AM

Class 25: October 23, 2024

Recall: Last time, we discussed a general way to frame a discrete approximation problem: Given n data points (x_i, y_i) , can we find a model $p(x) = a_0 \phi_0(x) + a_1 \phi_1(x) + \dots + a_m \phi_m(x)$ such that it minimizes some norm $\|p(x) - y\|$? We then discussed the case where the norm being minimized is the euclidean norm (2-norm). We called this "Discrete Least Squares".

$$\text{Min } q(a) = \text{Min Sum}_{\{i=0\}^n} (p(x_i) - y_i)^2 = \text{Min } \|M a - y\|_2^2$$

We then realized that the function $q(a) = \|M a - y\|_2^2$ being minimized is a concave up quadratic. We can write its formula using inner products and matrix-vector algebra as:

$$q(a) = a^T G a - 2b^T a + c$$

With $G = (M^T)M$ the SPS Grammian matrix, $b = M^T y$ and $c = y^T y$ (constant). If M has L columns (trivial nullspace), then G is SPD and invertible, and q has a unique minimizer at the one value of a such that:

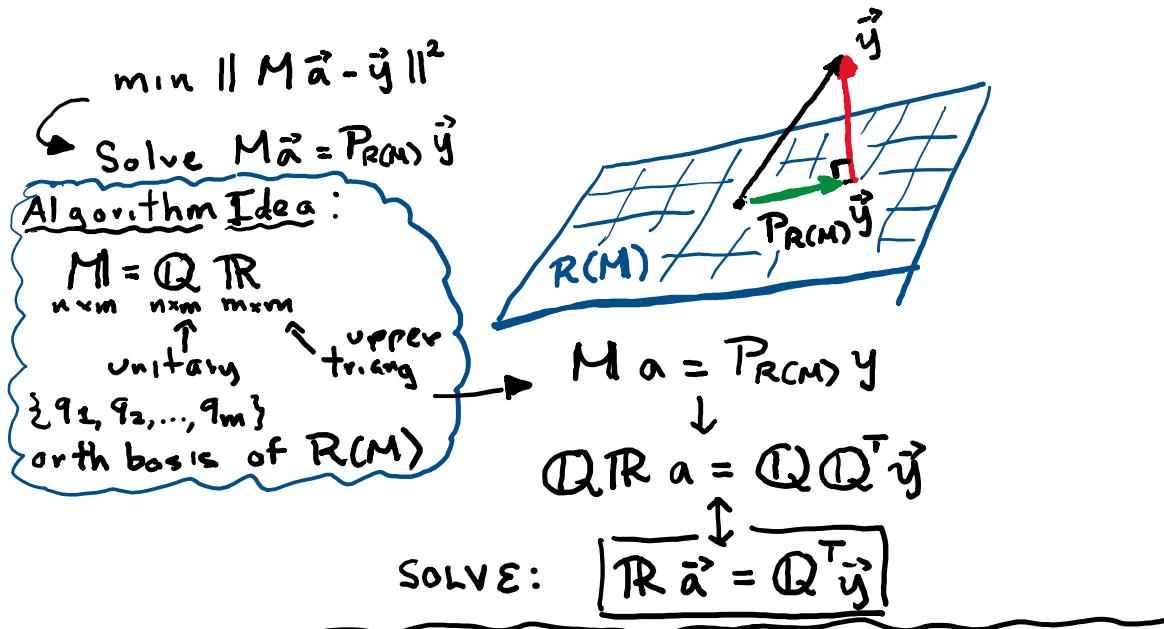
$$\begin{aligned} \text{Grad } q(a) &= 2(Ga - b) = 0 \\ Ga &= b \\ (M^T)M a &= (M^T) y \end{aligned}$$

We called this linear system the "Normal Equations", and its solution a_{LS} is the vector of coefficients of our model of best fit (in the LS sense), $p = M^* a_{\text{LS}}$.

Finally, we mentioned that even if G is invertible, it will sometimes be very ill-conditioned (e.g. polynomial model using monomial basis). So, stabler methods to solve this problem involve some factorization of M instead of solving $Ga=b$.

Today, I will briefly explain one of these methods, show a demo, and then we will move on to another problem of function approximation: continuous L2 approximation.

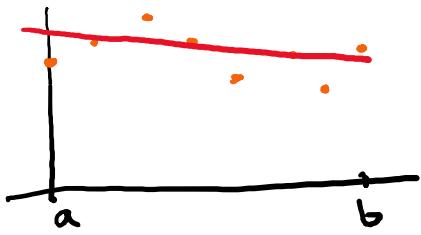
Recall this interpretation of DLS:



Generalizations:

- Weighted LS: $\min \sum_{i=0}^{n-1} w_i (p(x_i) - y_i)^2$
- Regularized LS: $\min \{ \|p - y\|^2 + \underbrace{\lambda \|P_a\|}_\text{penalty} \}$
 - Ridge regression / Shrinkage
 - Tikhonov
 - LASSO

CONTINUOUS FUNCTION APPROX:



DISCRETE APPROX ✓

HOW? FORM $\vec{p} = p(x_i)$,
Find coeffs a_0, \dots, a_m to
minimize $\|\vec{p} - \vec{y}\|$.



CONT. APPROX ?

$$\min \|\vec{p} - \vec{f}\|$$

What does $\|\vec{f}\|$ mean?

$f \in C[a, b]$,

$$\|\vec{f}\|_2 = \left(\int_a^b f(x)^2 dx \right)^{1/2} \rightarrow L^2 \text{ norm.}$$

space
 $L^2([a, b])$

$$\langle f, g \rangle = \int_a^b f(x)g(x) dx \quad \text{inner product sp.}$$

(Hilbert).

- Find \vec{a} such that $\|\vec{f} - \vec{p}\|^2$ is minimized.

$$\|\vec{f}\|_{\omega, 2} = \left(\int_a^b f(x)^2 \omega(x) dx \right)^{1/2} \quad (\omega(x) \geq 0, \text{ integrable.})$$

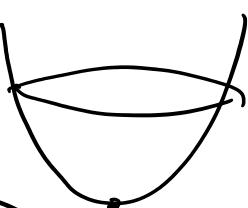
$$\langle f, g \rangle_{\omega} = \int_a^b f(x)g(x) \omega(x) dx \quad \text{Hilbert sp.}$$

$$\|\vec{f}\|_{\infty} = \sup_{x \in [a, b]} \{ |f(x)| \} \rightarrow \underline{\text{max}} \quad L^{\infty}$$

$$\|\vec{f}\|_p = \left(\int_a^b |f(x)|^p dx \right)^{1/p} \quad L^p$$

L^2 :

$$q(\vec{a}) = \int_a^b \left(\sum_{j=0}^{m-1} a_j x^j - f(x) \right)^2 dx$$



$$= \left\langle \sum_{i=0}^{m-1} a_i x^i - f, \sum_{j=0}^{m-1} a_j x^j - f \right\rangle$$

$$q(\vec{a}) = \vec{a}^T \mathbf{G} \vec{a} - 2 \vec{b}^T \vec{a} + c \quad | \quad \text{DISC}$$

$\sim b$

$-$

$$q(\vec{a}) = \vec{a}^T G \vec{a} - 2 \vec{b}' \vec{a} + c$$

$$G(i,j) = \langle x^i, x^j \rangle = \int_a^b x^{i+j} dx \quad | \quad \text{DISC}$$

$$b(i) = \langle x^i, f \rangle = \int_a^b x^i f(x) dx \quad | \quad M_{(i,i)}^T M_{(:,j)}$$

$$c = \langle f, f \rangle = \int_a^b f(x)^2 dx \quad | \quad M_{(i,i)}^T y$$

$$y^T y$$

Powers of x (poly approx) \rightarrow Hilbert mat.

$\{1, x, x^2, x^3, \dots, x^{m-1}\} \rightarrow$ LI but poorly cond.

$$G(i,j) = \langle \phi_i, \phi_j \rangle$$

$\langle \phi_i, \phi_j \rangle = 0$ if $i \neq j$ ORTHOGONAL

and $\langle \phi_i, \phi_i \rangle = 1$ — ORTHONORMAL.

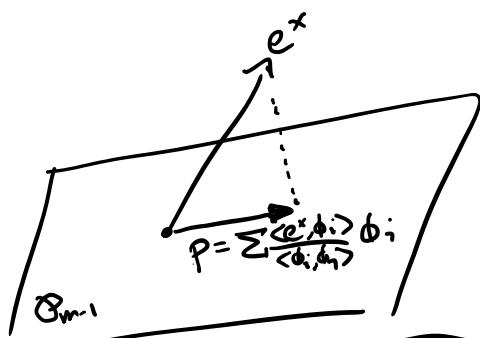
ORTHOGONAL BASIS $\{\phi_0, \phi_1, \dots, \phi_{m-1}\}$

$$G a = b$$

$$\begin{bmatrix} \langle \phi_0, \phi_0 \rangle & 0 & 0 & \dots & 0 \\ 0 & \langle \phi_1, \phi_1 \rangle & 0 & \dots & 0 \\ \vdots & 0 & \langle \phi_2, \phi_2 \rangle & \ddots & 0 \\ \vdots & \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \dots & \dots & \langle \phi_{m-1}, \phi_{m-1} \rangle \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_{m-1} \end{bmatrix} = \begin{bmatrix} \langle f, \phi_0 \rangle \\ \langle f, \phi_1 \rangle \\ \vdots \\ \langle f, \phi_{m-1} \rangle \end{bmatrix}$$

$$a_j = \frac{\langle f, \phi_j \rangle}{\langle \phi_j, \phi_j \rangle}$$

$$P(x) = \sum_{j=0}^{m-1} \frac{\langle f, \phi_j \rangle}{\langle \phi_j, \phi_j \rangle} \phi_j(x)$$



$$a_j = \frac{\int_a^b f(x) \phi_j(x) dx}{\int_a^b \phi_j(x)^2 dx}$$

$$\text{ERROR } \|f - P\|^2 = \sum_{j=m}^{\infty} \left(\frac{\langle f, \phi_j \rangle}{\langle \phi_j, \phi_j \rangle} \right)^2$$

$$\text{ERROR } \|f - p\| = \sum_{j=m}^n \left(\frac{\langle f, \phi_j \rangle}{\langle \phi_j, \phi_j \rangle} \right)$$

Polynomial approx, $[-1, 1]$, $\omega(x) \equiv 1$

Find orthogonal basis of polynomials
 $\{P_0(x), P_1(x), P_2(x), \dots\} \rightarrow \boxed{\text{LEGENDRE}}$

spans the same as

$$\{1, x, x^2, x^3, \dots\}$$

GRAM-SCHMIDT:

$$P_0(x) = 1$$

$$P_1(x) = x - \frac{\langle x, 1 \rangle}{\langle 1, 1 \rangle} \cdot 1$$

$$= x - \left(\frac{\int_{-1}^1 x dx}{\int_{-1}^1 1 dx} \right) 1 = \textcircled{x}$$

$$P_2(x) = x^2 - \underbrace{\frac{\langle x^2, x \rangle}{\langle x, x \rangle}}_{\begin{array}{l} \int_{-1}^1 x^3 dx \\ \hline \int_{-1}^1 x^2 dx \end{array}} x - \frac{\langle x^2, 1 \rangle}{\langle 1, 1 \rangle} 1$$

$$\left[\begin{array}{l} \int_{-1}^1 x^2 dx \\ \hline \int_{-1}^1 1 dx \end{array} \right] \rightarrow (2/3)/2$$

$$\boxed{P_2(x) = x^2 - \frac{1}{3}}$$

$$P_3(x) = x^3 - \frac{\langle x^3, x^2 - \frac{1}{3} \rangle}{\langle x^2 - \frac{1}{3}, x^2 - \frac{1}{3} \rangle} \left(x^2 - \frac{1}{3} \right) - \frac{\langle x^3, x \rangle}{\langle x, x \rangle} x - \frac{\langle x^3, 1 \rangle}{\langle 1, 1 \rangle} 1.$$