ВСМ	wPi	Name	Physical	EZ Connect	PWM Hat
-	-	3.3V	1	3.3V	3.3V
2	8	SDA.1		G2, P3	SDA
3		SCL.1		G3, P5	SCL
4		GPIO.7	!	G4, P7	
_	-	0V		GND	GND
17	0	GPIO.0	11	G17, P11	
27	2	GPIO.2		G27, P13	
22	3	GPIO.3	15	G22, P15	
-	-	3.3V	17	3.3V	
10	12	MOSI	19	G10, P19	
9	13	MISO	21	G9, P21	
11	14	SCLK	23	G11, P23	
-	-	0V	25	GND	GND
0		SDA.0	27		
5		GPIO.21	29	G5, P29	
6		GPIO.22	31	G6, P31	
13		GPIO.23	33	G13, P33	
19	24	GPIO.24	35	G19, P35	
26	25	GPIO.25	37	G26, P37	
-	-	0V	39		
-	-	5V		5V	5V
-	-	5V	4		
-	-	0V		GND	GND
14	15	TxD	8	G14, P8	
15		RxD	10	G15, P10	
18		GPIO.1		G18, P12	
-		0V		GND	GND
23		GPIO.4		G23, P16	
24		GPIO.5		G24, P18	
-	-	0V	20		
25		GPIO.6		G25, P22	
8		CEO		G8, P24	
7		CE1		G7, P26	
1	31	SCL.0	28		
-	-	0V	30		
12	26	GPIO.26		G12, P32	
-	-	0V	34		
16		GPIO.27		G16, P36	
20		GPIO.28		G20, P38	
21	29	GPIO.29	40	G21, P29	

		+5.0V Digital Regulator]
microUSB	+5V	OUT+	
microUSB	GND	OUT-	Battery
		IN+	+11V
		IN-	GND

		H-bridge right	IMU	GPS Parallax 565K	LIDAR Lite v3
3.3V	"+5V"				
G2, P3			SDA (White, Blue)		SDA (Blue)
G3, P5			SCL (Yellow)		SCL (Green)
G4, P7	IN1				
GND	GND				
G17, P11	IN2				
G27, P13	IN3				
G22, P15	IN4				
3.3V		"+5V"			
G10, P19					
G9, P21					
G11, P23					
GND					GND (Black)
G5, P29					
G6, P31					
G13, P33					
G19, P35					
G26, P37					
5V			VCC (Red)		
5V			(1.154)	VCC	
GND			GND (Black)		
G14, P8			(2.6.6.1)		
G15, P10				SIO	
G18, P12		IN1		0.0	
GND				GND & /RAW	
G23, P16		IN2		0.12 0.71 0.11	
G24, P18		IN3			
G25, P22		IN4			
G8, P24					
G7, P26					
01,120					
G12, P32					
012, 1 02					
G16, P36					
G20, P38					
G21, P29					
021,120	l				
5V					VCC (Red)
5V					1.00 (1.00)
3.3V					+
3.3V					+
GND		GND			+
GND		OND .			+
טוזט	<u> </u>	1		1	

PWM	1 Hat	Arm	Pan-Tilt Camera	H-bridge left	H-bridge righ
Channel	Pin				
0	SIG	Base			
0	VCC	Base			
0	GND	Base			
	SIG	Shoulder			
1	VCC	Shoulder			
1	GND	Shoulder			
	SIG	Elbow			
	VCC	Elbow			
2	GND	Elbow			
	SIG	Wrist Rot			
	VCC	Wrist Rot			
3	GND	Wrist Rot			
	SIG	Wrist Flex			
	VCC	Wrist Flex			
4	GND	Wrist Flex			
	SIG	Gripper			
	VCC	Gripper			
5	GND	Gripper			
			•		
	SIG		Pan		
	VCC		Pan		
6	GND		Pan		
		•			
7	SIG		Tilt		
	VCC		Tilt		
7	GND		Tilt		
_	la a	1	Г		
8	SIG			ENA	
	VCC				
8	GND				
	CIC.	T	Γ	END	
	SIG			ENB	
	VCC				
9	GND				
10	SIC				I NA
10	SIG				ENA
	VCC				
	GND	<u> </u>	<u> </u>	<u> </u>	
11	SIC	T	Γ	Γ	END
	SIG				ENB
	VCC				
	GND				

+5V			
GND			

t

+5.5V Motor Regulator]
OUT+	
OUT-	Battery
IN+	+11V
IN-	GND

Marvin

ВСМ	wPi	Name	Physical	PiJuice
-	-	3.3V	1	3.3V
2	8	SDA.1	3	SDA
3	9	SCL.1	5	SCL
4	7	GPIO.7	7	
-	-	0V	9	GND
17	0	GPIO.0	11	
27	2	GPIO.2	13	
22	3	GPIO.3	15	
-	-	3.3V	17	3.3V
10	12	MOSI	19	
9	13	MISO	21	
11		SCLK	23	
-	-	0V	25	GND
0	30	SDA.0		SDA
5	21	GPIO.21	29	
6	22	GPIO.22	31	
13	23	GPIO.23	33	
19	24	GPIO.24	35	
26	25	GPIO.25	37	
-	-	0V	39	GND
-	-	5V		5V
-	-	5V		5V
-	-	0V		GND
14		TxD	8	
15		RxD	10	
18		GPIO.1	12	
-		0V		GND
23		GPIO.4	16	
24	5	GPIO.5	18	
-	-	0V	20	GND
25		GPIO.6	22	
8	10	CEO	24	
7		CE1	26	
1	31	SCL.0		SCL
-	-	0V		GND
12	26	GPIO.26	32	
-	-	0V	34	GND
16		GPIO.27	36	
20		GPIO.28	38	
21	29	GPIO.29	40	