

Protocol Verification

A Brief Introduction to Model Checking and Temporal Logic

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Motivation

Protocol Verification?



Examples of protocols



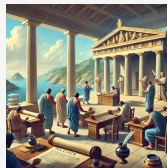
Distributed systems (e.g. paxos)



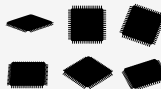
Examples of protocols



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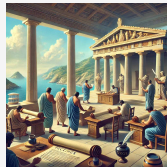


Hardware (e.g. cache coherence)



Examples of protocols

- ❖ Distributed systems (e.g. paxos)



- ❖ Hardware (e.g. cache coherence)



- ❖ Cryptographic protocols (e.g. TLS)



Examples of properties

✚ Fairness

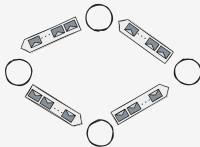


Examples of properties

✚ Fairness



✚ Deadlock-freedom

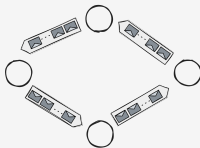


Examples of properties

✚ Fairness



✚ Deadlock-freedom



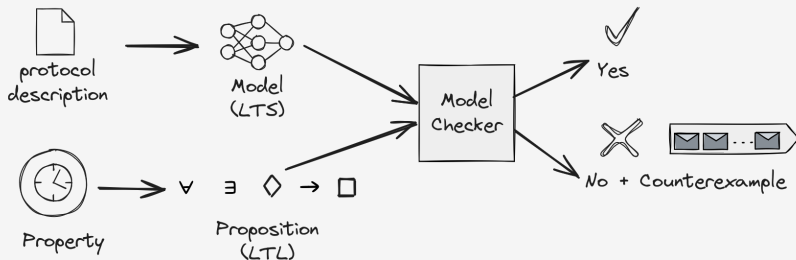
✚ Safety



Protocol Verification



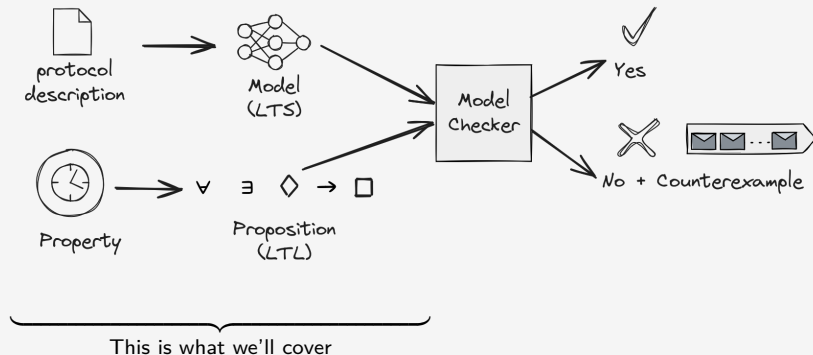
What this course is about



Protocol Verification



What this course is about



What you *will* (hopefully) know
by the end

- ❖ Labeled transition systems (LTS)
- ❖ Modeling languages (promela)
- ❖ (Propositional) Linear Temporal Logic (LTL)
- ❖ Examples!

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- ❖ Labeled transition systems (LTS)
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- ❖ (Propositional) Linear Temporal Logic (LTL)
- ❖ Examples!

What you will *not* (necessarily) know by the end

- ❖ Other logics (e.g. CTL*, μ calculus)
- ❖ How model checking works internally (decision procedures)

Modelling Protocols

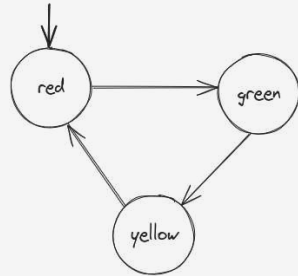
Definition (Labeled Transition Systems)

A labeled transition system is a tuple of the form $(S, \text{Act}, \rightarrow, S_0, \text{AP}, L)$, where S is a set of states, $S_0 \subseteq S$ a subset of initial states, Act is a set (of actions), $\rightarrow \subseteq \text{Act} \times S \times S$ is a (transition) relation, AP is a set (of atomic propositions) and $L : S \rightarrow \text{Pow}(\text{AP})$ is a (labeling) function.

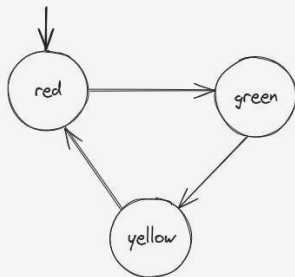
Example: Traffic Light



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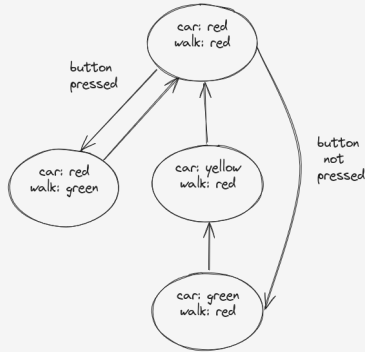


Example: Traffic Light

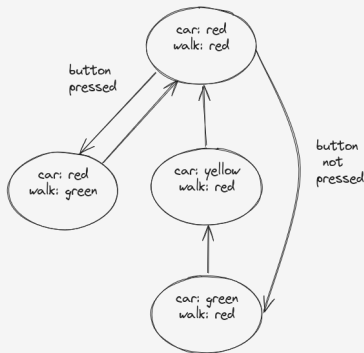


- ❖ $S = \{\text{red}, \text{green}, \text{yellow}\}, S_0 = \text{red}$
- ❖ $\text{Act} = \{*\}$
- ❖ $\rightarrow = \{(*, \text{red}, \text{green}), (*, \text{green}, \text{yellow}), (*, \text{yellow}, \text{red})\}$
- ❖ $\text{AP} = L = \emptyset.$

Two Traffic Lights



Two Traffic Lights



- ❖ $Act = \{\epsilon, \text{button pressed}, \text{no button pressed}\}$
- ❖ $AP = \{\text{Pedestrians can go}, \text{Cars can go}\}$
- ❖ $L = \text{cars: red, walk: green} \mapsto \{\text{Pedestrians can go}\}, \dots$

Interleaving



Two traffic lights \leftrightarrow One LTS

Two traffic lights \leftrightarrow One LTS

Definition (Interleaving)

Let $TS_i = (S_i, \text{Act}_i, \rightarrow_i, S_{0,i}, \text{AP}_i, L_i)$, $i = 1, 2$ be two transition systems. We define the transition system $TS_1 \parallel TS_2 := (S_1 \times S_2, \text{Act}_1 \times \text{Act}_2, \rightarrow, S_{0,1} \times S_{0,2}, \text{AP}_1 \cup \text{AP}_2, L_1 \times L_2)$, where $L_1 \times L_2 : S_1 \times S_2 \rightarrow \text{Pow}(\text{AP}_1 \cup \text{AP}_2)$ is defined as $(L_1 \times L_2)(s_1, s_2) = L_1(s_1) \cup L_2(s_2)$ and \rightarrow is defined by

$$\frac{s_1 \xrightarrow{\alpha}_1 s'_1}{(s_1, s_2) \xrightarrow{\alpha} (s'_1, s_2)} \quad \frac{s_2 \xrightarrow{\alpha}_2 s'_2}{(s_1, s_2) \xrightarrow{\alpha} (s_1, s'_2)} .$$

We call this construction the *interleaving* of TS_1 and TS_2 .

Two traffic lights \leftrightarrow One LTS

Definition (Interleaving)

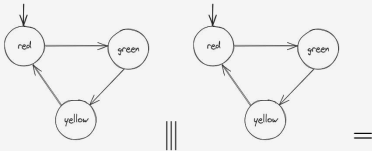
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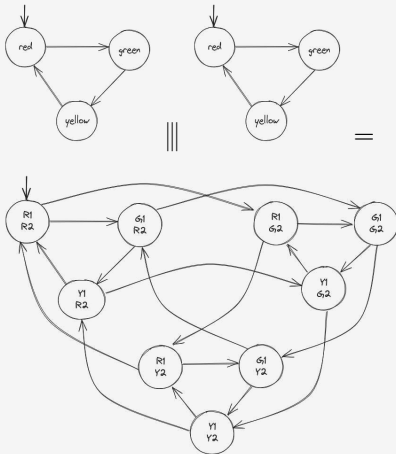
We call this construction the *interleaving* of TS_1 and TS_2 .

Note that this means the two TS are *independent*

Example: Intearleaving



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Definition (Handshake)

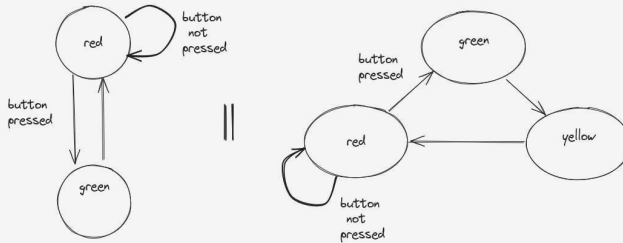
Let $TS_i = (S_i, \text{Act}_i, \rightarrow_i, S_{0,i}, \text{AP}_i, L_i)$, $i = 1, 2$ be two transition systems and $H \subseteq \text{Act}_1 \cap \text{Act}_2$. We define the transition system $TS_1 \parallel_H TS_2 := (S_1 \times S_2, \text{Act}_1 \times \text{Act}_2, \rightarrow, S_{0,1} \times S_{0,2}, \text{AP}_1 \cup \text{AP}_2, L_1 \times L_2)$, where \rightarrow is defined by:

$$\frac{s_1 \xrightarrow{\alpha}_1 s'_1 \quad \alpha \notin H}{(s_1, s_2) \xrightarrow{\alpha} (s'_1, s_2)} \quad \frac{s_2 \xrightarrow{\alpha}_2 s'_2 \quad \alpha \notin H}{(s_1, s_2) \xrightarrow{\alpha} (s_1, s'_2)}$$

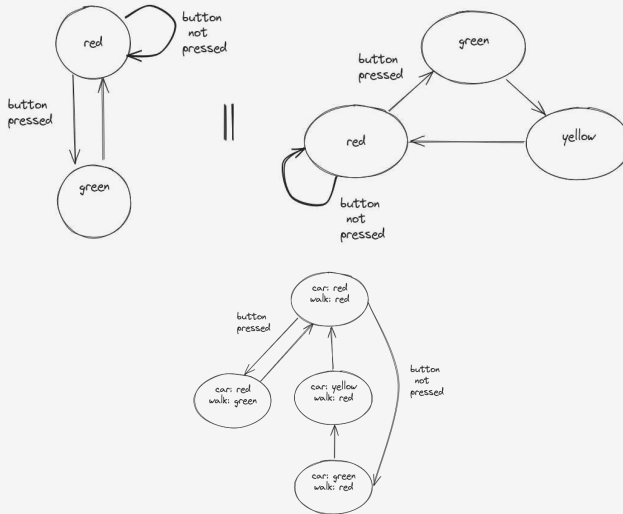
$$\frac{s_1 \xrightarrow{\alpha}_1 s'_1 \quad s_2 \xrightarrow{\alpha}_2 s'_2 \quad \alpha \in H}{(s_1, s_2) \xrightarrow{\alpha} (s'_1, s'_2)}$$

We call this the *parallel composition with handshake* H . When $H = \text{Act}_1 \cap \text{Act}_2$, we omit H .

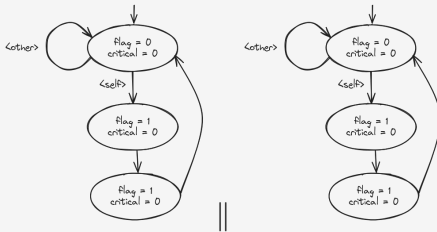
Two Traffic Lights, revisited



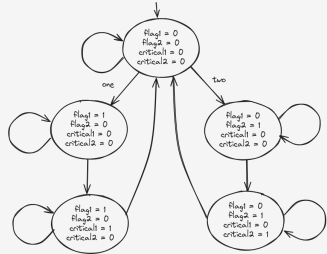
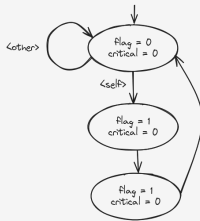
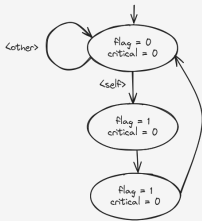
Two Traffic Lights, revisited



Concurrency: Message Passing



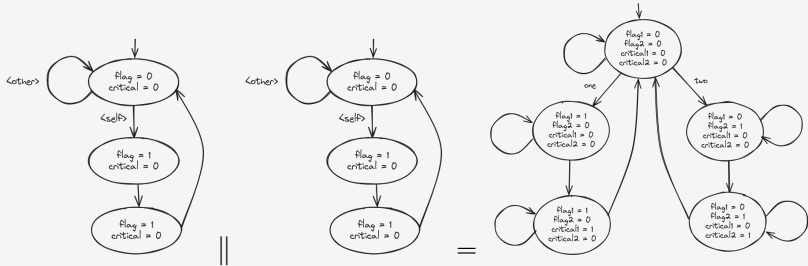
Concurrency: Message Passing



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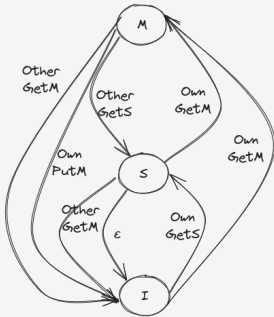
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Concurrency: Message Passing

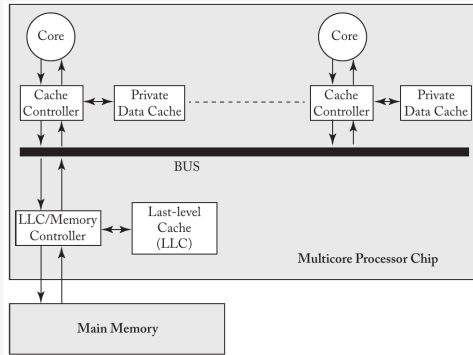
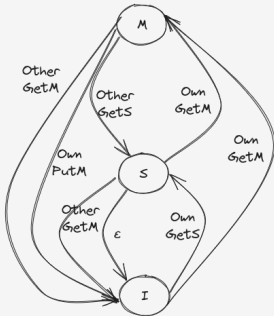


Assumption: atomicity of read-modify-writes here. Reasonable?

MSI Cache Coherency Protocol



MSI Cache Coherency Protocol



Source: Nagarajan, Vijay, et al. A primer on memory consistency and cache coherence. Springer Nature, 2020.

State Graph



✚ TS \neq Graphs

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- ❖ Visualization (graphs): very useful!

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Definition (Predecessors/Successors)

Let $TS = (S, \text{Act}, \rightarrow, S_0, \text{AP}, L)$ be a transition system. For $s \in S, \alpha \in \text{Act}$, we define

$\text{Post}(s, \alpha) := \{s' \in S \mid s \xrightarrow{\alpha} s'\}$, $\text{Post}(s) := \bigcup_{\alpha \in \text{Act}} \text{Post}(s, \alpha)$ as the successors of s , and similarly Pre for the predecessors.

- ❖ $TS \neq \text{Graphs}$
- ❖ Visualization (graphs): very useful!

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Definition (State Graph)

Let $TS = (S, \text{Act}, \rightarrow, S_0, \text{AP}, L)$ be a transition system. We call the directed graph $G(TS) = (S, E)$ the state graph of TS , where $E = \{s, s' \in S \times S \mid s \in S, s' \in \text{Post}(s)\}$

Definition (Path fragments)

Let $TS = (S, \text{Act}, \rightarrow, S_0, \text{AP}, L)$ be a transition system. A sequence $\pi = \pi_0\pi_1\pi_2 \dots \in (S)_{\mathbb{N}}$ is called a *path fragment* if $\pi_{i+1} \in \text{Post}(\pi_i) \forall i \in \mathbb{N}$. It is called *finite* if it is a finite sequence $(\pi_i)_{i=0}^N$ instead.

For a path fragment π , we denote the i -th element by $\pi[i]$ and similarly the sub-sequence $(\pi_k)_{k=i}^j$ by $\pi[i..j]$

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Sequences of transitions = path fragments through the state graph

Definition (Initial path fragment)

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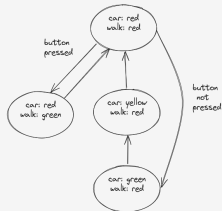
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Definition (Path)

A path fragment π is called a *path* if it is initial and maximal.

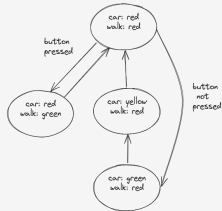
Example: Paths in Traffic Light



A Typical Traffic Light in the UK?



Example: Paths in Traffic Light



A Typical Traffic Light in the UK?



Non-example



Finite vs Infinite Paths

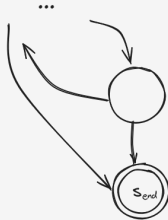


finite path fragments can be extended to infinite ones, but...

Finite vs Infinite Paths



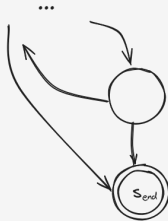
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Finite vs Infinite Paths



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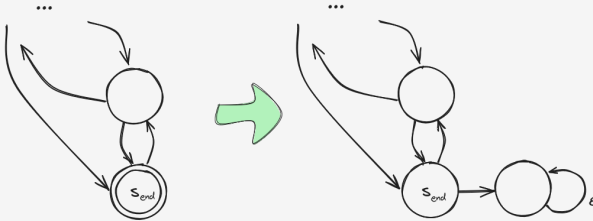


$$\text{Post}(s) = \emptyset$$

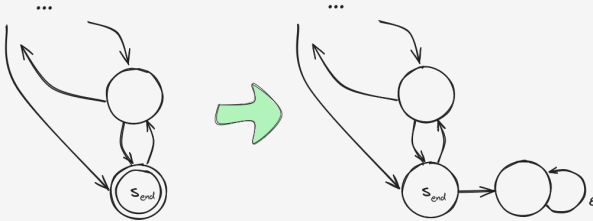
End States



Modeling end states with infinite paths



Modeling end states with infinite paths



Assumption

For the rest of this course we assume no end states s with $\text{Post}(s) = \emptyset$.