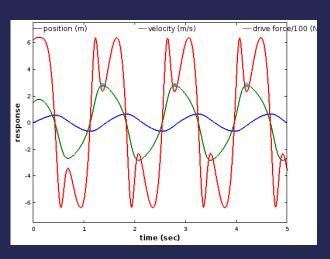
# ENGINEERING PROJECT PORTFOLIO

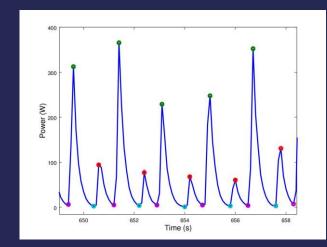
Dr. Scott J. Kennedy
Durham, NC

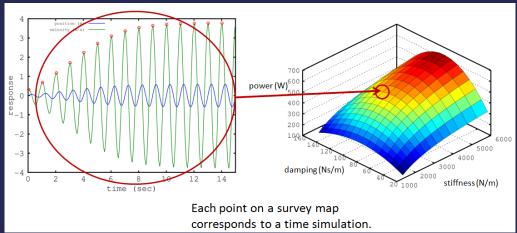
### HYDROPOWER STARTUP COMPANY



I served as the VP of Technology Development in the launching of a hydropower company. We developed an energy harvester for rivers that would not require dams or spinning turbine blades for regions that do not have access to large electrical grids. I helped write the proposals that won SBIR funding from the Office of Naval Research and the National Science Foundation. I wrote software to simulate and analyze the physics of the machines we considered and tested and designed a flow chamber that cost less than 1/20<sup>th</sup> of similarly-sized commercial systems.









## HYDROPOWER STARTUP COMPANY (CONT.)

We built many designs and increased power harvesting several orders of magnitude over the course of development. Maintaining an oscillation in a turbulent environment, harvesting as much as possible without stalling, over a wide range of flow rates which changes the power available and frequency of the periodic driving force, required mechanisms that enabled system dynamics that would evolve with the flow rate.



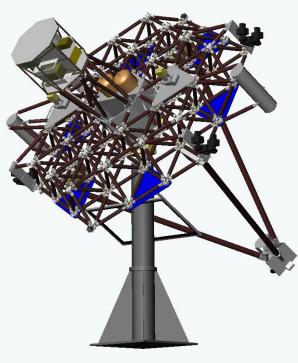


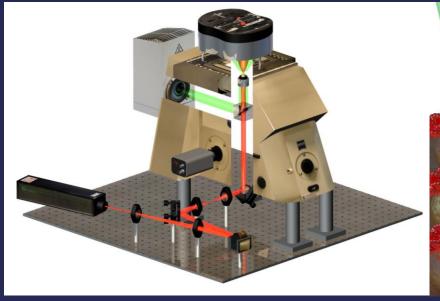


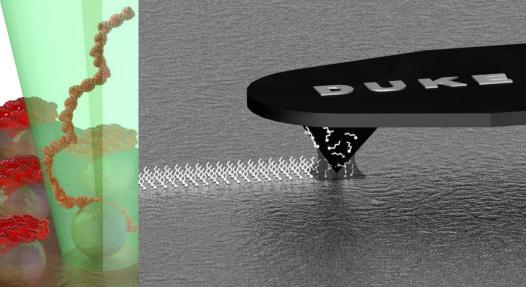
# SOLID MODELING

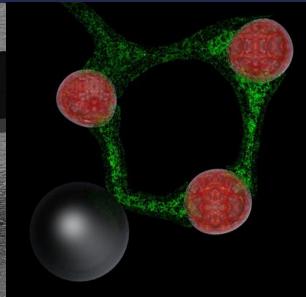
I learned to model in Solidworks when I created a mass model of a 30', 2500-part satellite dynamics test bed for the Air Force Research Lab – Space Vehicles Directorate. With a tape measure, a pair of calipers, and a hydraulic boom lift, I took the measurements needed to create a model that had a center of mass within 0.05" of the spherical air bearing center. Solid modeling has been a part of every position I have held since. I have designed prototype hardware and machine drawings for countless tests and created illustrations for presentations, proposals, patents, publications, and a textbook.







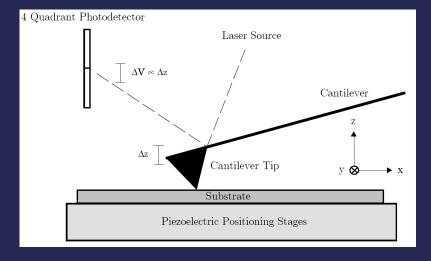




#### ATOMIC FORCE MICROSCOPY

Atomic force microscopy is a technique where a microscopic cantilever beam is used as a probe by sensing the bending of the beam by monitoring movement of a laser spot reflected off the end of the cantilever. If the bending stiffness of a beam can be calibrated, very small forces can be measured, for example, the forces associated with unzipping a strand of DNA.

My dissertation at Duke centered on finding an improved calibration method based on a model of the random thermal vibrations for probes in liquids for biological applications and other contributions to the field including signal processing recommendations that were published in a textbook and assistance with the development of an ISO calibration standard.





Micro-scale cantilever dimensions can be measured using an electron microscope.

| calibrate_0_40                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          | x                                                                                                                                               |
|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------|
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |                                                                                                                                                 |
| Measured Response F-S Interaction Model Step 1 - Load Data Select File  Step 2 - Known Inputs Cartilever Plan View Dimensions Length (µm) Width (µm) 100.5 19.33  Select Filid  C Air (generally not appicable)  F-S Interaction Model SHO Model  10 <sup>24</sup> 10 <sup>25</sup> 10 <sup>26</sup> 10 <sup>27</sup> Step 2 - Known Inputs  Cartilever Plan View Dimensions Length (µm) Width (µm) 100.5 19.33  Select Filid  F Air (generally not appicable) F Yelder  10 <sup>2</sup> 10 <sup>2</sup> 10 <sup>2</sup> Frequency (Hz) | CENTER FOR BIOLOGICALLY INSPIRED MATERIALS & MATERIAL SYSTEMS  Step 5 - Calibrate  Cantilever Stiffness (N/m) 0.377102  Selection Ratio 5.00003 |
| Step 3 - Initialize SHO Model  Natural Freq. (Hz) 4  Guality Factor DC Power  Step 4 - Initialize Fluid-Structure Interaction Model  Natural Freq. (Hz) 4  Mass Ratio Scale  4                                                                                                                                                                                                                                                                                                                                                          | > 27551<br>> 2.48097<br>> 8.15147e-026<br>> 6.15127e+007<br>> 2.84561e+006<br>> 0.813508                                                        |

I created this GUI in Matlab to allow a user to initialize parameters and then use my calibration algorithm.

## **ACOUSTICS & VIBRATIONS**



I have significant experience testing hardware to characterize noise and vibration issues in the automotive and aerospace industries. From left-to-right, pictured here there is a Minotaur fairing I conducted acoustic studies on, a welded truss used in a study on the damping imparted by cables, patent illustrations of a device that would damp rocket fairing panel vibrations, and a miniature rocket payload dummy and suspension that mimicked the dynamics of a full-scale system for the demonstration of a system that allowed shock isolation to motion on one axis while remaining stiff to rocking motion.



